



COLLEGE OF ENGINEERING  
NUCLEAR ENGINEERING & RADIOLOGICAL SCIENCES  
UNIVERSITY OF MICHIGAN

# Lecture 22

# Testing, Verification, Validation

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NERS 590-004



# Outline

- Motivation
- Review of Testing
- Definitions
- Code Verification
- Solution Verification
- Validation & Prediction



## Why should I care about V&V?

- How do you know someone else's code is correct?
- How does someone else know your code is correct?
- Correct in what sense?
  - Does it do what its supposed to?
  - Does it represent reality?
- How can we develop tests that are meaningfully providing evidence of verification and validation?



## Today's Learning Objectives

- Understand difference of Verification and Validation
- Understand testing strategies for verification and validation testing



## Further Reading

- Oberkamp, W., & Roy, C. (2010). *Verification and Validation in Scientific Computing*. Cambridge: Cambridge University Press.  
doi:10.1017/CBO9780511760396
  - This book is 665 pages!
- <https://doi.org/10.1017/CBO9780511760396>
- <https://search.lib.umich.edu/catalog/record/015554090>
- Specifically, chapters: 2, 5, 6, 7, 12



# Ross's Taxonomy of Testing



# A Taxonomy of Testing

- Testing is the backbone of software quality assurance (SQA).
- Types of testing
  - *Unit Testing* – Test individual units of program *in isolation*
    - Should run very fast: < 1 second (a couple seconds is ok)
  - *Integral Testing* – Testing program components together
    - Should run fast: < 1 minute (a couple minutes is ok)
  - *Regression Testing* – Test whole program for changes in program output
    - Should run fast: < 1 minute (a couple minutes is ok)
  - *Verification Testing* – Test that you are “doing things right”
    - Can happen at unit or integral or regression level. Comparison analytic solutions or manufactured solutions.
  - *Validation Testing* – Whole program testing “doing the right thing”; simulating reality, comparison to experiment.
    - May be long running: minutes to hours
  - *Memory Testing* – Expensive testing that does detailed memory simulations to detect errors (valgrind)
  - *Coverage Testing* – Figure out how much of your source code is actually covered by testing
  - *Portability Testing* – test on different platforms and with different compilers
- Other types of testing exist





## Testing Layers

Correctness Testing

### Nightly Testing

Secondary Tested (ST)

CATEGORIES [BASIC CONTINUOUS NIGHTLY]

(includes all testing\*)

### Post-Push CI Testing

Secondary Tested (ST)

CATEGORIES [BASIC CONTINUOUS]

(includes more regression testing)

### Pre-Push CI Testing

Primary Tested (PT)

CATEGORIES [BASIC]

(unit tests & some regression tests)

\*Additional Categories:  
Heavy or Weekly

Coverage Testing

Memory (Valgrind) Testing





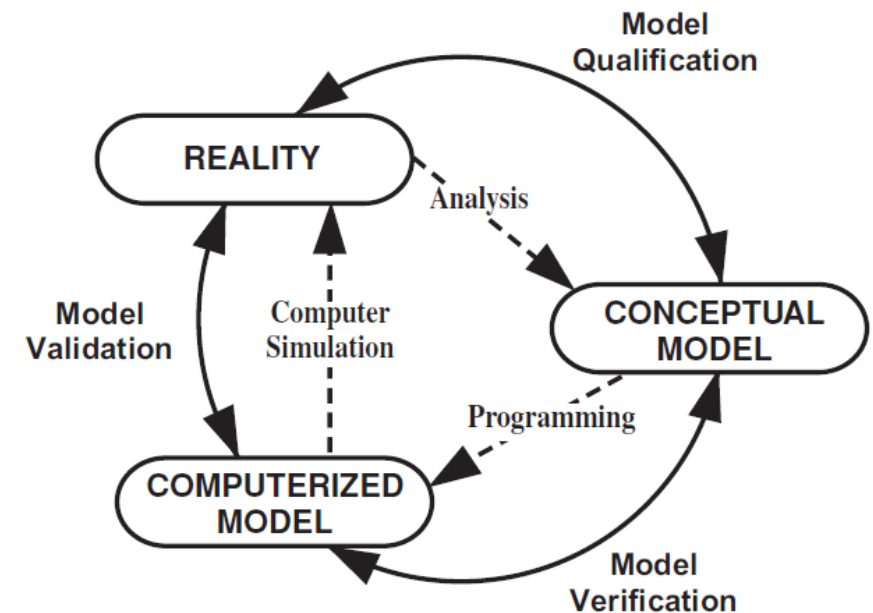


# Terminology

What is V&V?

# Early Definitions of Verification and Validation

- *Model verification*: substantiation that a computerized model represents a conceptual model **within specified limits of accuracy**.
- *Model validation*: substantiation that a computerized model within its domain of applicability possesses a **satisfactory range of accuracy** consistent with the **intended application** of the model.





## Other Definitions

### IEEE

- *Verification*: the process of evaluating the products of a software development phase to provide assurance that they meet the requirements defined for them by the previous phase.
- *Validation*: the process of testing a computer program and evaluating the results to ensure compliance with specific requirements.

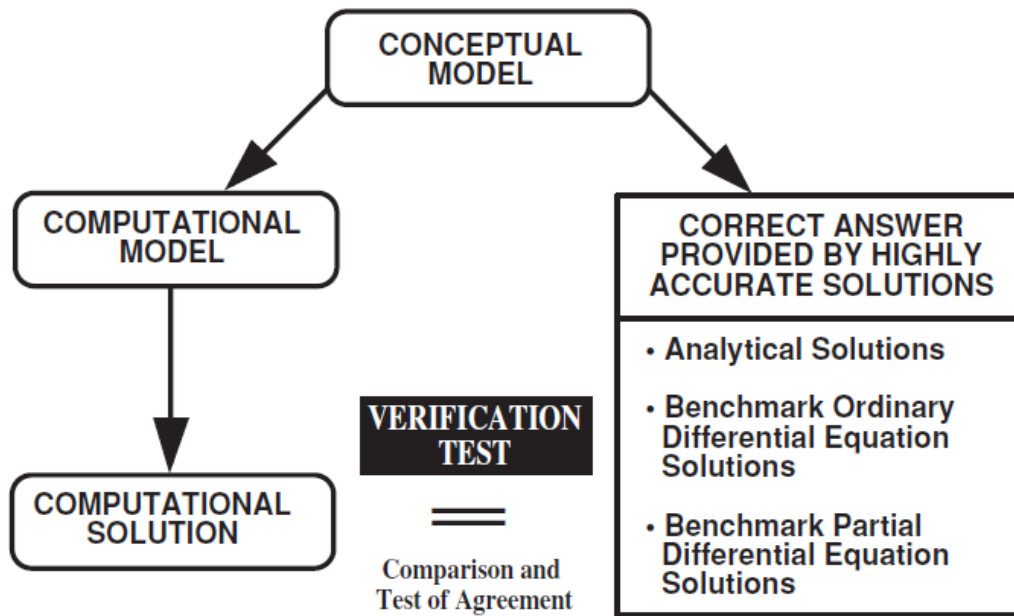
### Department of Defense

- *Verification*: the process of determining that a model implementation **accurately represents the developer's conceptual** description of the model.
- *Validation*: the process of determining the degree to which a model is an **accurate representation of the real world** from the **perspective of the intended uses** of the model.

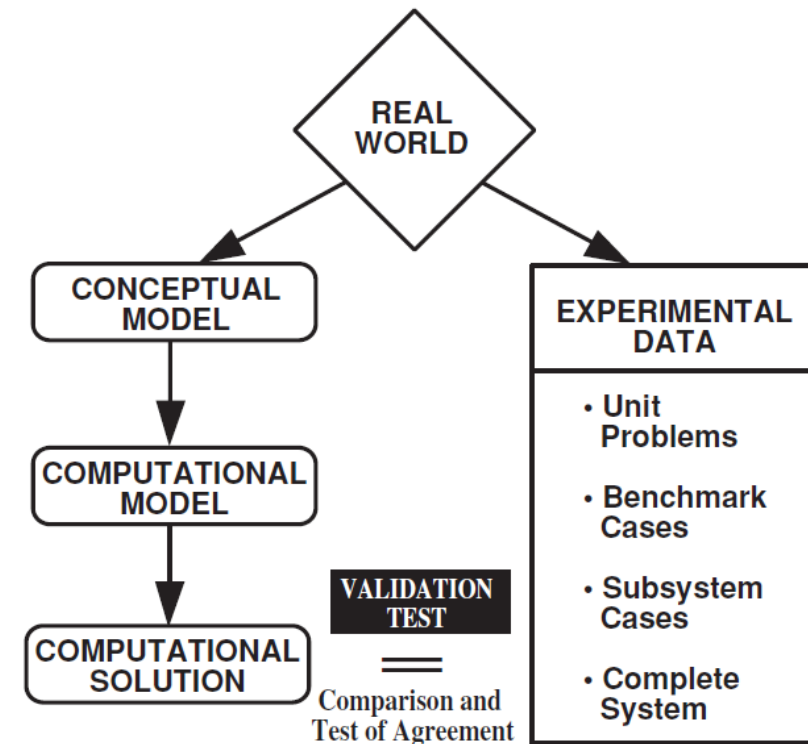


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## Verification

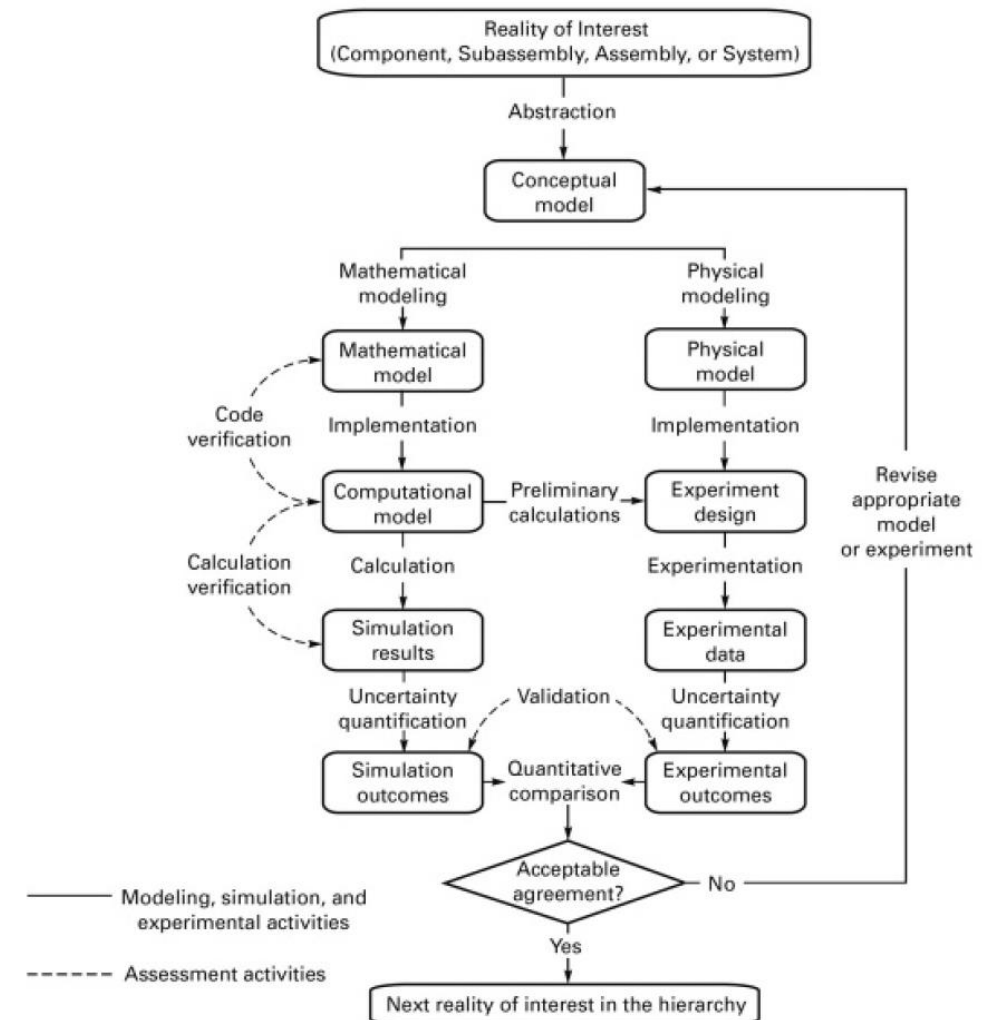


## Validation



# ASME

- *Code verification*: the process of determining that the numerical algorithms are correctly implemented in the computer code and of identifying errors in the software.
- *Solution verification*: the process of determining the **correctness of the input data**, the numerical accuracy of the solution obtained, and the **correctness of the output data** for a particular simulation.





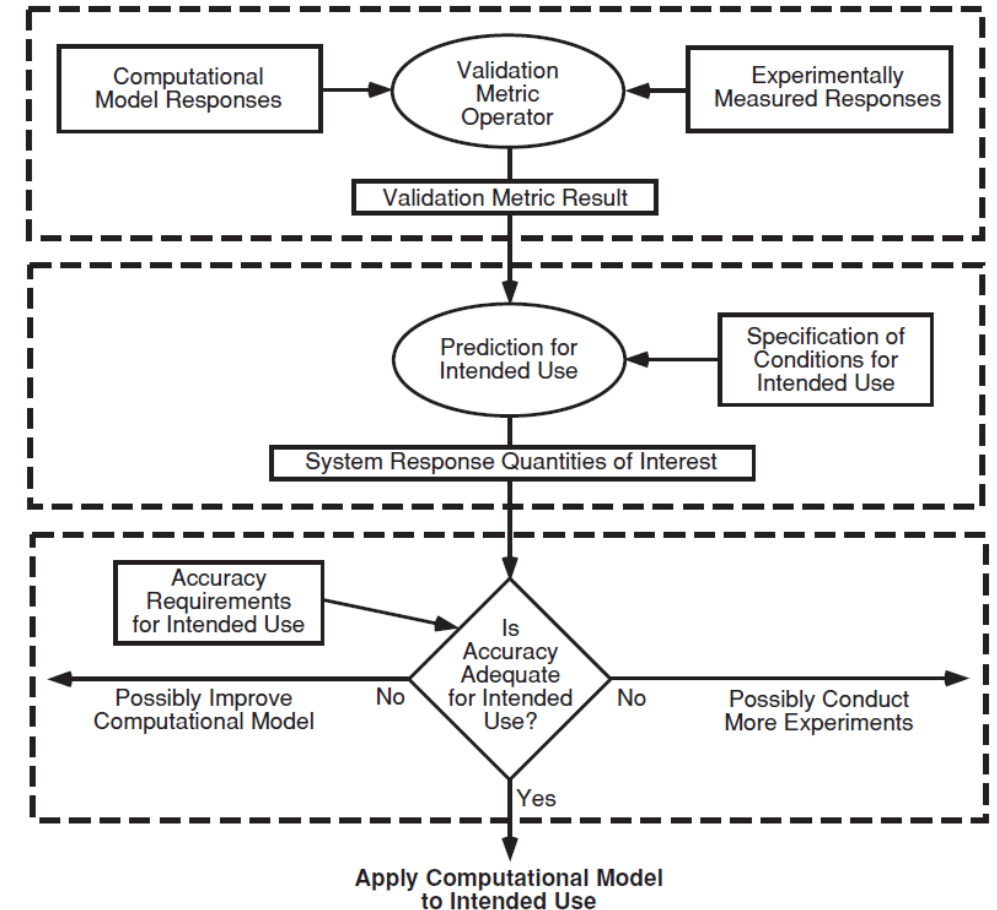
# Aspects of Validation

- Quantification of the accuracy of the computational model results by comparing the computed system response quantities (SRQs) of interest with experimentally measured SRQs
- Use of the computational model to make predictions, in the sense of interpolation or extrapolation of the model, for conditions corresponding to the model's domain of intended use.
- Determination of whether the estimated accuracy of the computational model results satisfies the accuracy requirements specified for the SRQs of interest.

## 1 Assessment of Model Accuracy by Comparison with Experimental Data

## 2 Interpolation or Extrapolation of the Model to the Intended Use

## 3 Decision of Model Adequacy for Intended Use





# Code Verification

How do you prove that your program is a faithful representation of the original mathematical model?





## Selection of Criteria/Metrics

- Choosing the solution is a natural, but has practical issues.
  - Need a good reference solution or exact solution
  - Mapping of the numerical solution to the reference can be burdensome
  - Considering the full solution may be overwhelming w.r.t the amount data
- Solution: Norms!
  - L1 norms are good for problems where discontinuities or singularities might exist. Typically applied for discretization errors.
  - L2 norms also commonly used for discretization errors.
  - L-infinity will be the most sensitive
- Additionally consider, quantities of interest for the application

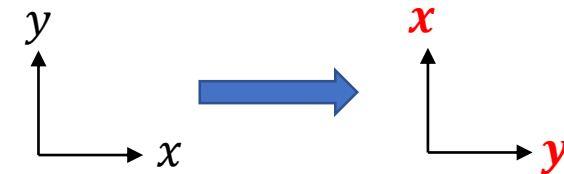
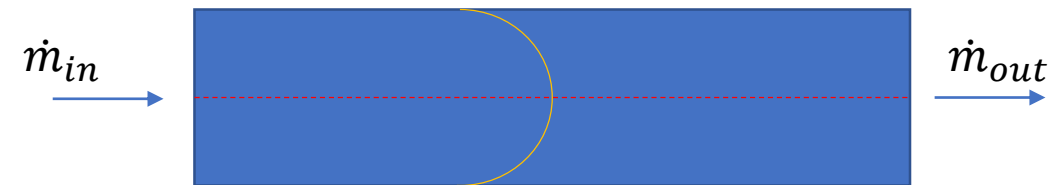


# Types of Code Verification Tests

- Simple Tests
- Code-to-Code Verification
- Discretization Error Quantification
- Convergence Tests
- Order-of-Accuracy Tests

# Simple Test Example

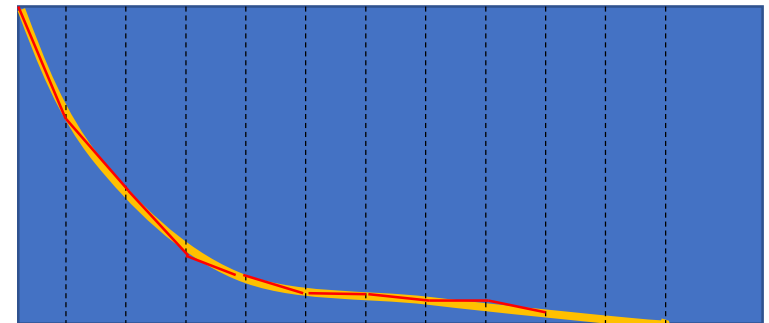
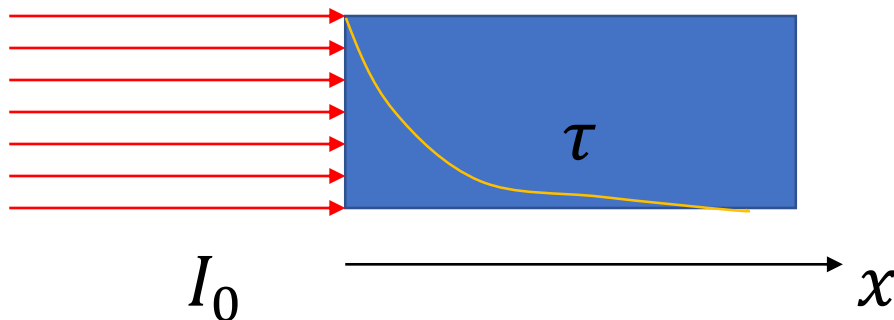
- Symmetry
  - Define a problem with geometry and boundary conditions symmetric about a plane
  - Can also look at periodic problems
- Rotational Invariance
  - Similar to the above except change coordinates
- Conservation (perform global integration)
  - of energy in heat transfer
  - of mass or momentum in fluid flow



$$\dot{m}_{in} = \dot{m}_{out}$$

## Discretization Error Tests

- Compare the numerical solution to an exact solution
- Quantitative assessment of code output using a single mesh
- Example: beam attenuation



$$I(x) = I_0 \exp(-\tau x)$$

# Convergence Tests

## Mesh Refinement

- Essentially testing the fundamental theorem of calculus
- As you refine your discretization does the error reduce towards zero?

$$\frac{df(x)}{dx} = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

## Iterative Methods

- Fixed point method (lecture 7)

$$x^{(\ell+1)} = \mathbf{F}x^{(\ell)} + \mathbf{c}$$

- Has a rate of convergence  $\rho(\mathbf{F})$  the spectral radius.
- Does your implementation behave like:

$$\frac{\|\epsilon^{(\ell+1)}\|}{\|\epsilon^{(\ell)}\|} \approx \rho(\mathbf{F}) = \lim_{\ell \rightarrow \infty} \frac{\|\epsilon^{(\ell+1)}\|}{\|\epsilon^{(\ell)}\|}$$

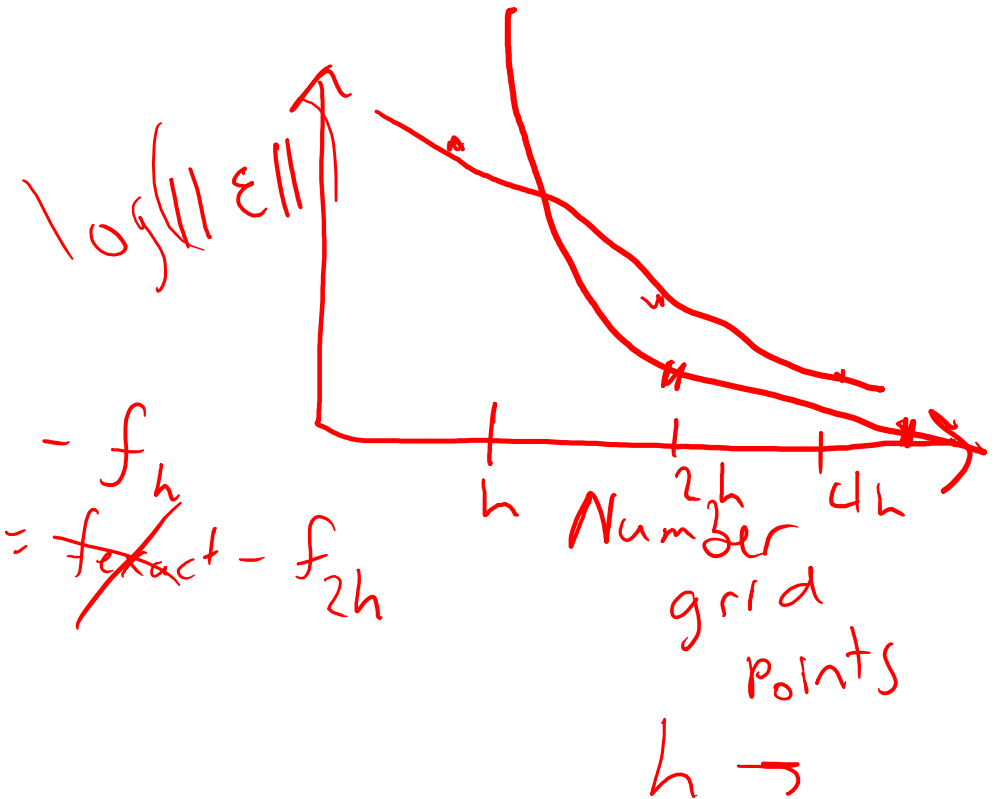
## Order-of-Accuracy Tests

- Run two calculations (or a series) with a uniform grid refinement factor, typically 2

- Error in solution on grid  $h$  is  $\epsilon_h = f_{\text{exact}} - f_h$
- Error in solution on refined grid  $2h$  is  $\epsilon_{2h} = f_{\text{exact}} - f_{2h}$

- Computing Observed Order of Accuracy

$$\hat{p} = \frac{\ln\left(\frac{\epsilon_{2h}}{\epsilon_h}\right)}{\ln(2)}$$



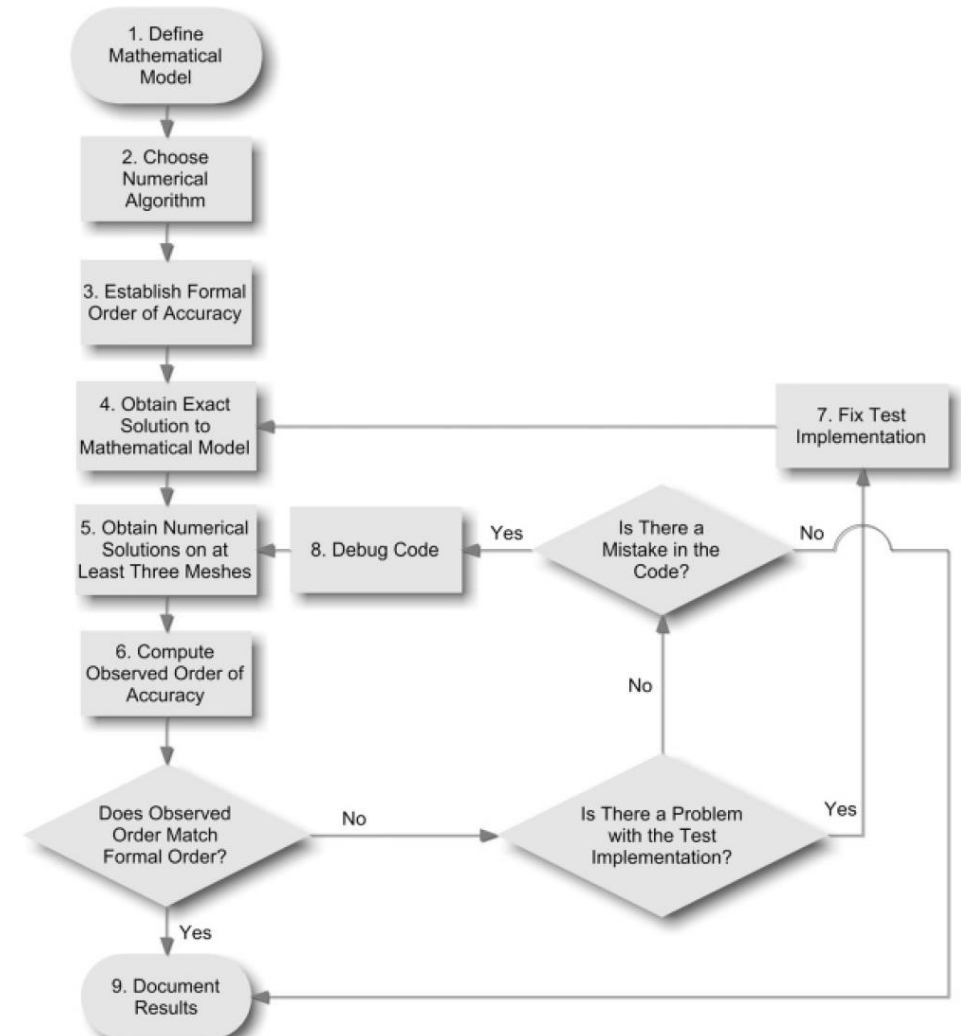
# Formal Order of Accuracy

- Establish formal order of accuracy
  - Example: Finite Difference

$$f(x_i + \Delta x) = f(x_i) + \frac{df(x_i)}{dx} \frac{\Delta x}{1!} + \frac{d^2f(x_i)}{dx^2} \frac{\Delta x^2}{2!} + \dots$$

$$\frac{df(x_i)}{dx} \approx \frac{f(x_i + \Delta x) - f(x_i)}{\Delta x} + \mathcal{O}(\Delta x^2)$$

- Does your observed order of accuracy agree with theory?







# Solution Verification

Is the given numerical approximation of a mathematical model sufficiently accurate for its intended use?



# Elements of Solution Verification

- Verification of Input Data
  - Examples: boundary conditions, coefficients, geometry approximations
- Verification of Post-Processing Tools
  - Examples: Excel Charts—how do you show pointwise data?
- Numerical error estimation
  - Examples: round-off, statistical sampling, iterative error, discretization error



## How to estimate numerical errors

condition of matrix

$$K(A_n) \rightarrow 10^7 \rightarrow 10^{-10}$$

$$K(A_{2n}) \rightarrow 10^8 \rightarrow 10^{-9}$$

$$K(A_{128n}) \rightarrow 10^{16} \rightarrow \text{1 digit of accuracy}$$

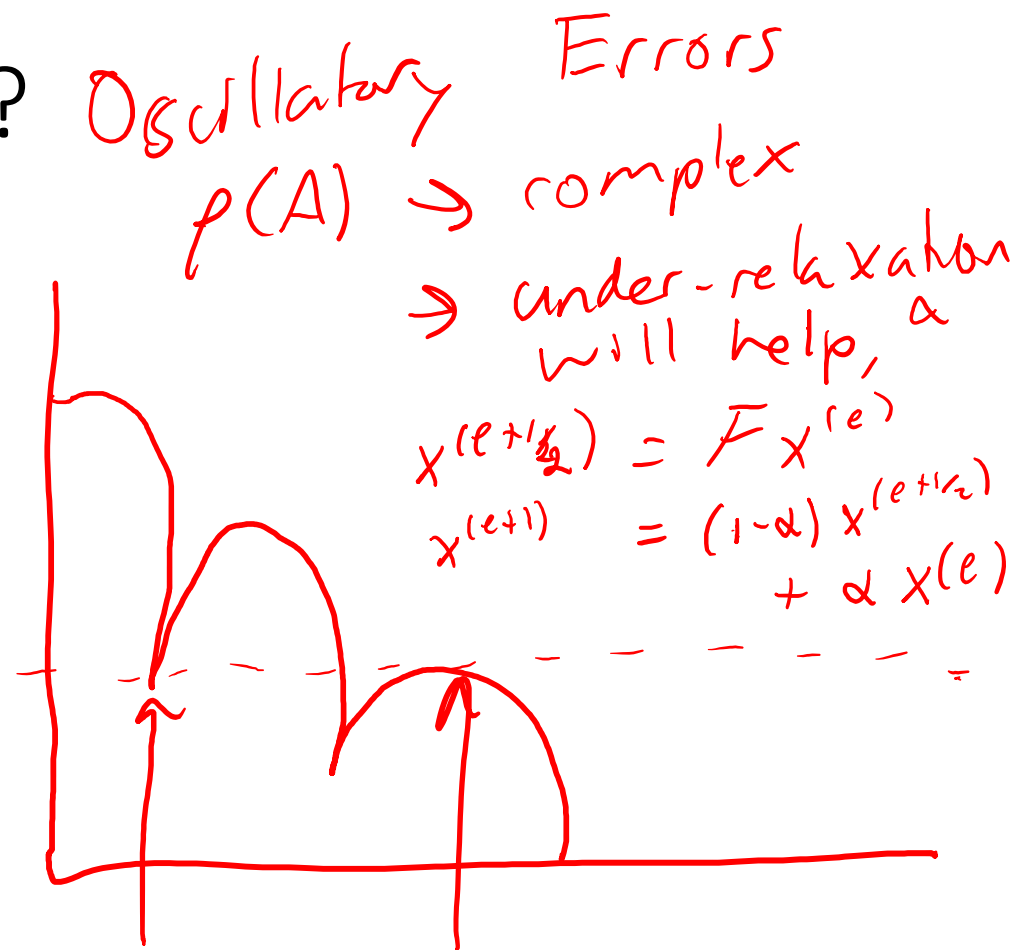
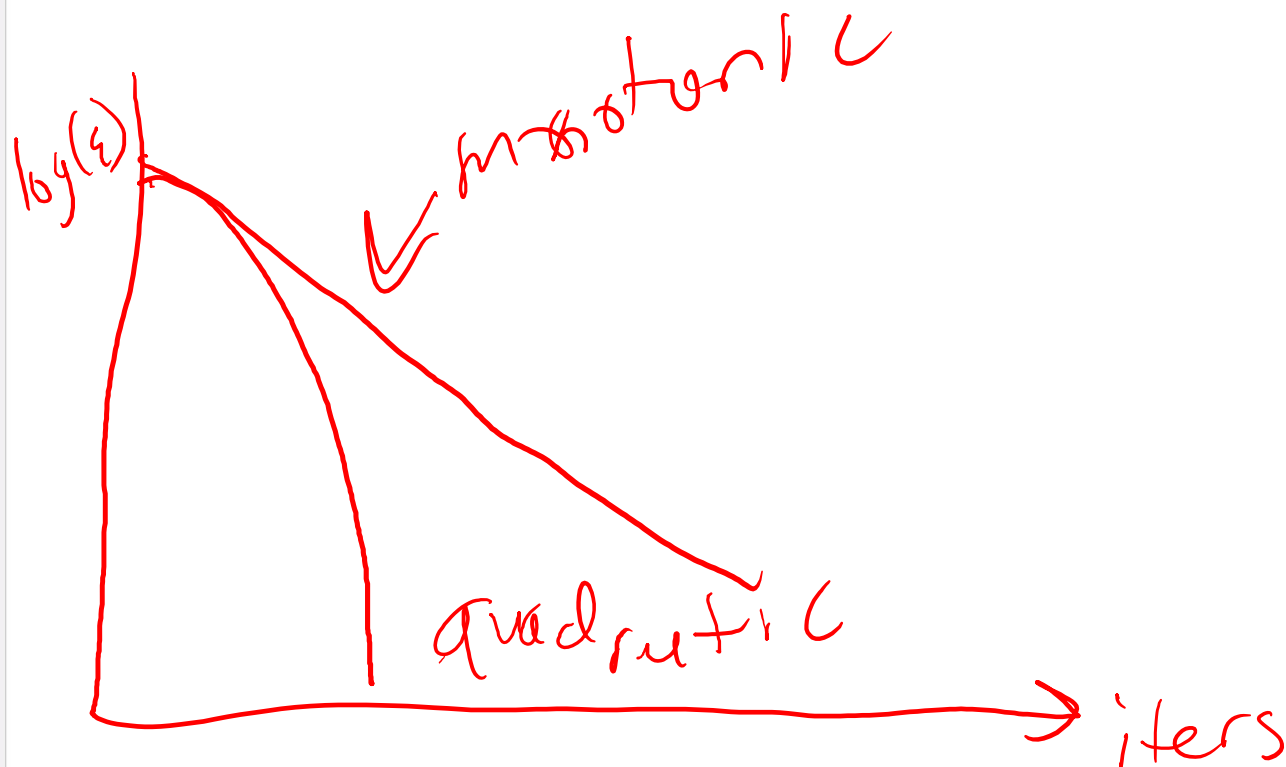
F.P. Round off

$\epsilon \rightarrow$  smallest representable floating point number

double Precision  $\approx 10^{-17}$

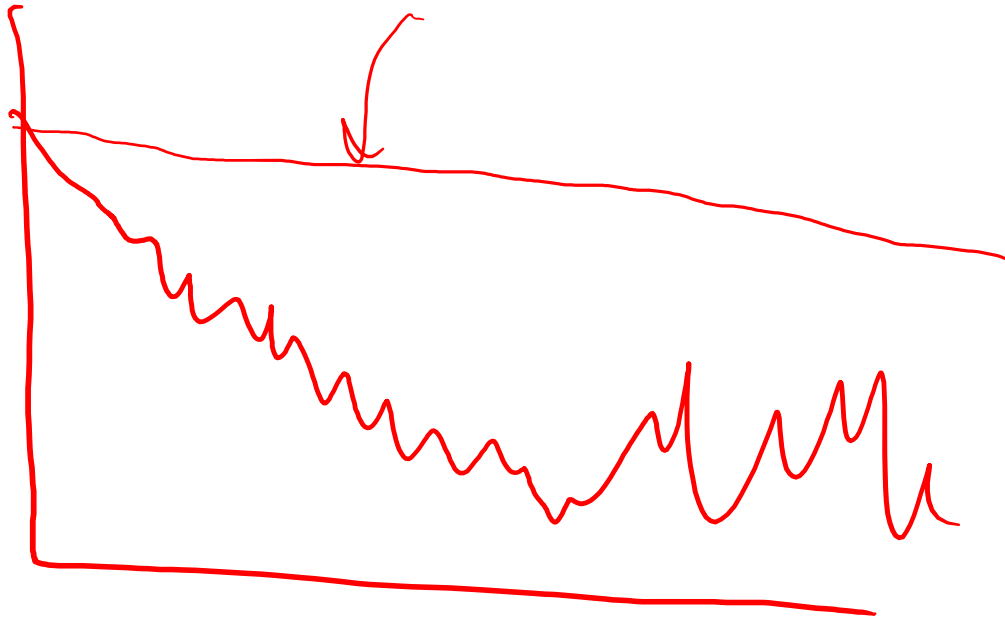
Round off  $\approx K \times \epsilon$

# How to show iterative errors?





## How to show iterative errors?



$$\epsilon_{crit} > |x^{(e+1)} - x^{(e)}|$$