



COLLEGE OF ENGINEERING
NUCLEAR ENGINEERING & RADIOLOGICAL SCIENCES
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Lecture 20

Mesh and Mesh Libraries

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NERS 590-004



Outline

- Geometry and Mesh
- Mesh Formats and Libraries
- Meshing Tools
- CUBIT Tutorial
 - <https://caen.engin.umich.edu/connect/windows-remote-desktop/>



Why should I care about mesh?

- In engineering we typically have a governing equation that comes from physics.
 - These equations are most often some form of partial differential equation
- Being engineers we care about things out in the “real world”
 - To solve our governing equations on real world representations numerically, we need some kind of representation of the real world thing.
- The discretization of PDE's usually involves discretizing in space.
 - As you can imagine discretization schemes for various equations are fairly similar
- Hard to solve a PDE without a mesh!
- Don't reinvent the wheel!



Today's Learning Objectives

- Understand differences of “geometry” and “mesh”
- Types of discretization methods for PDE's
- Become familiar with what libraries are out there
 - And how they relate to one another
- Become aware of what tools are available
 - Often these are the “front end” of the meshing library.
- Tutorial for basics of using CUBIT



Geometry and Mesh



Modeling and Simulation of Physical Processes

- Define the physical problem.
- Create a mathematical (PDE) model
 - Systems of PDEs, ODEs, algebraic equations.
 - Define initial and or boundary conditions to get a well-posed problem.
- Create a Discrete (Numerical) model
 - Discretize the domain -> generate the grid -> obtain discrete model
 - Solve the discrete system
- Analyze errors in the discrete system
 - Consistency, stability and convergence analysis.



Fundamental Concepts

Geometry

- Description of the real-world physical problem
 - Sizes/dimensions of physical objects in space
 - AND the description of the materials occupying that space
- The geometry in the simulation is often an approximation of the real world.

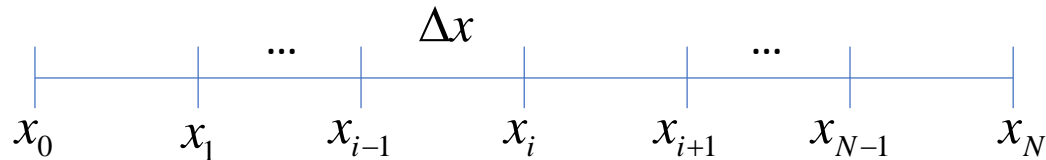
Mesh

- Discretized phase-space for dependent variable
 - Most commonly refers physical space
 - But, can also be applicable to other variables: speed, energy, time, etc.
- Type of mesh depends on the numerical method(s) used.
- Mesh & numerical method contain additional approximations

Geometry is *discretized* to produce a mesh

Types of Spatial Discretizations: Finite Difference

- From a spatial domain, represent solution at discrete points



- Expressions can be derived from Taylor expansions about a point.
 - Discarded terms represent local truncation error.

$$f(x_i + \Delta x) = f(x_i) + \frac{df(x_i)}{dx} \frac{\Delta x}{1!} + \frac{d^2 f(x_i)}{dx^2} \frac{\Delta x^2}{2!} \dots$$

- Derivatives represented as:

- Forward $\frac{df(x_i)}{dx} \approx \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i}$

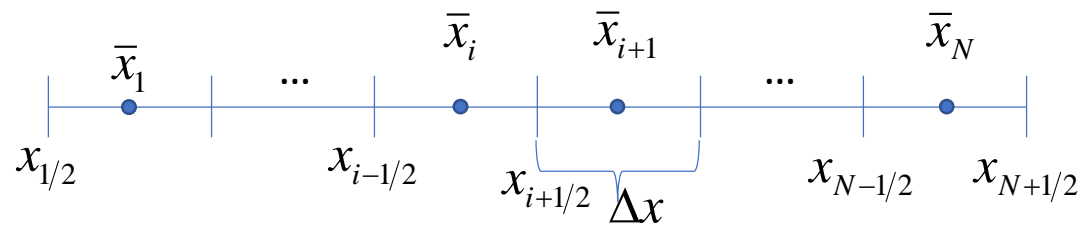
- Backward $\frac{df(x_i)}{dx} \approx \frac{f(x_i) - f(x_{i-1})}{x_i - x_{i-1}}$

- Central $\frac{df(x_i)}{dx} \approx \frac{f(x_{i+1}) - f(x_{i-1}))}{2(x_{i+1} - x_{i-1})}$

- Resulting mesh are typically structured grids
 - Rectangular, triangular, etc.

Types of Spatial Discretizations: Finite Volume

- From a spatial domain, represent solution in discrete control volumes
- Also typically applied to equations where the divergence theorem can be applied:



$$\int \nabla \cdot f(\vec{r}) dV = \oint \vec{n} \cdot f(\vec{r}) dS$$

- Makes use of conservation law for an integral over a finite volume

$$\bar{x}_i = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} f(x) dx$$

- Resulting mesh may be arbitrary
- Methods typically require computing “fluxes” through surfaces between volumes

Types of Spatial Discretizations: Finite Element

- Solve “weak” formulations of equations

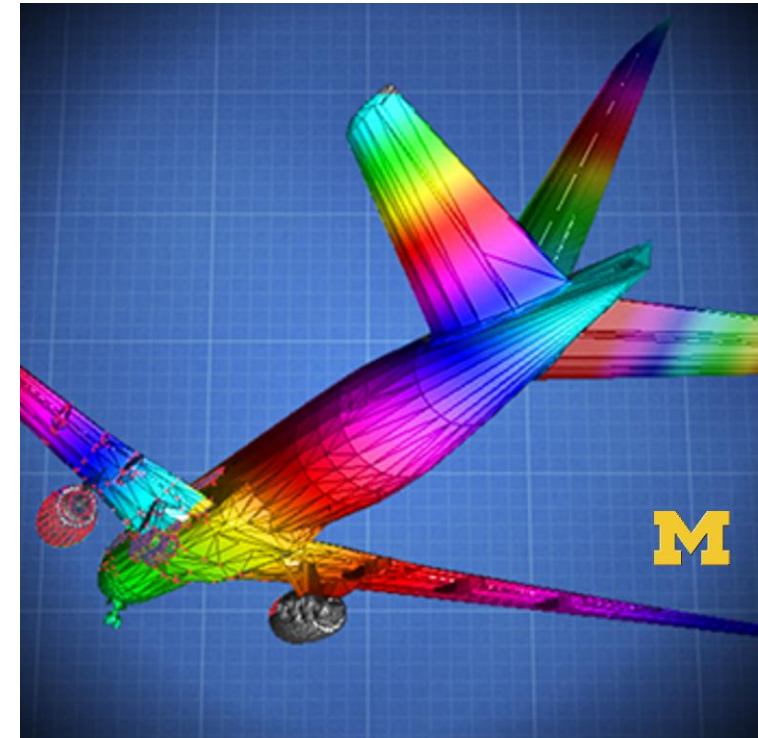
$$\frac{d^2 f}{dx^2} = q(x) \Rightarrow \int \frac{d^2 f}{dx^2} \xi(x) dx = \int q(x) \xi(x) dx$$

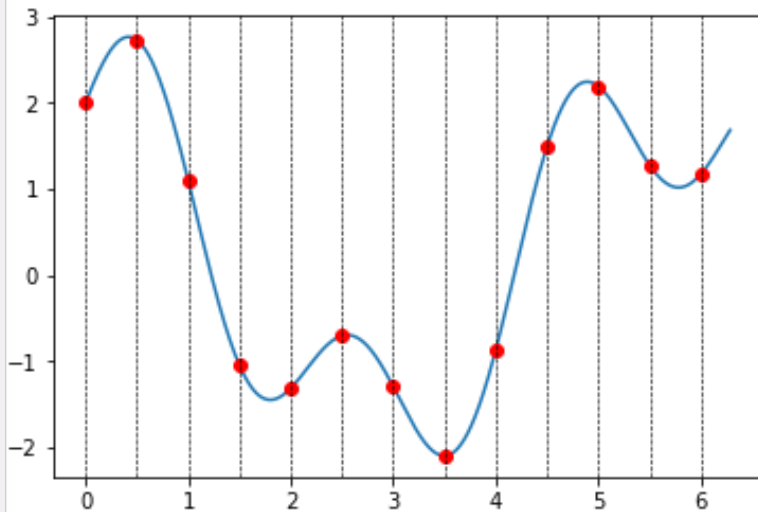
$$\int \frac{d^2 f}{dx^2} \xi(x) dx \Rightarrow - \int \frac{df}{dx} \frac{d\xi}{dx}(x) dx \equiv -\phi(f, \xi)$$

Multi-dimensional

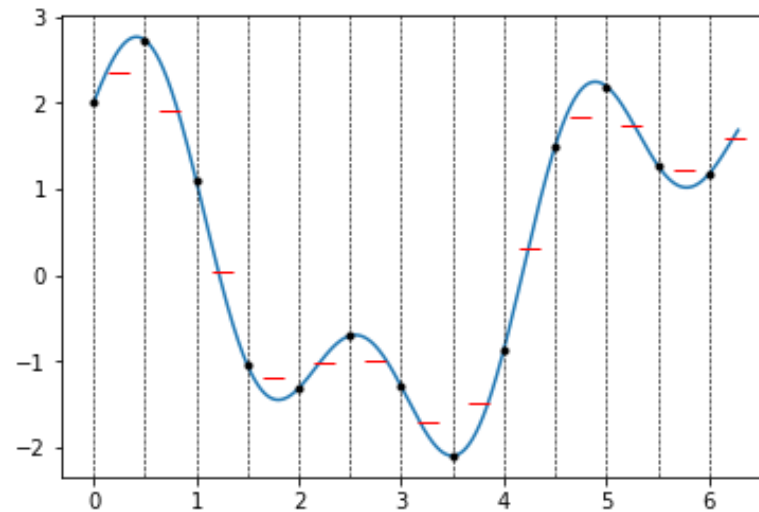
$$\nabla^2 f(\vec{r}) = q(\vec{r}) \Rightarrow -\phi(f, \xi) \equiv \int_{\Omega} \nabla f(\vec{r}) \cdot \nabla \xi(\vec{r}) dS$$

- Use “basis” (or “trial”) functions to represent “shape” of solution in a discrete spatial cell.
- Very widely used in structural analysis

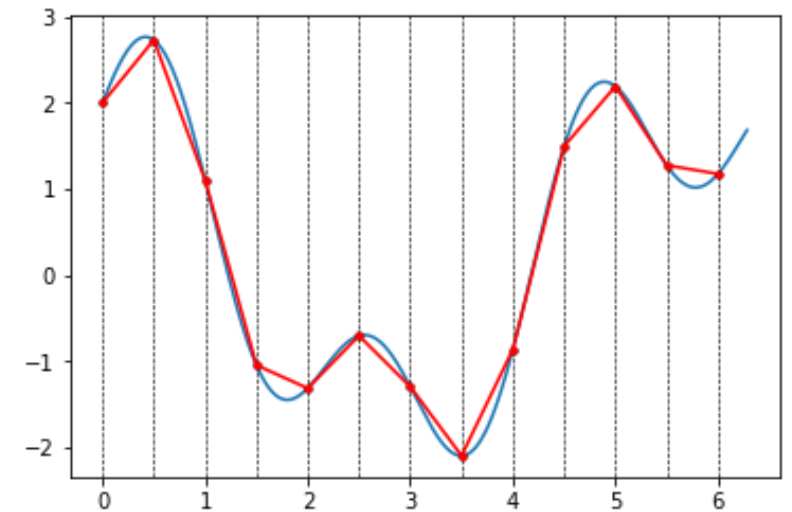




finite difference



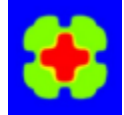
finite volume



finite element.

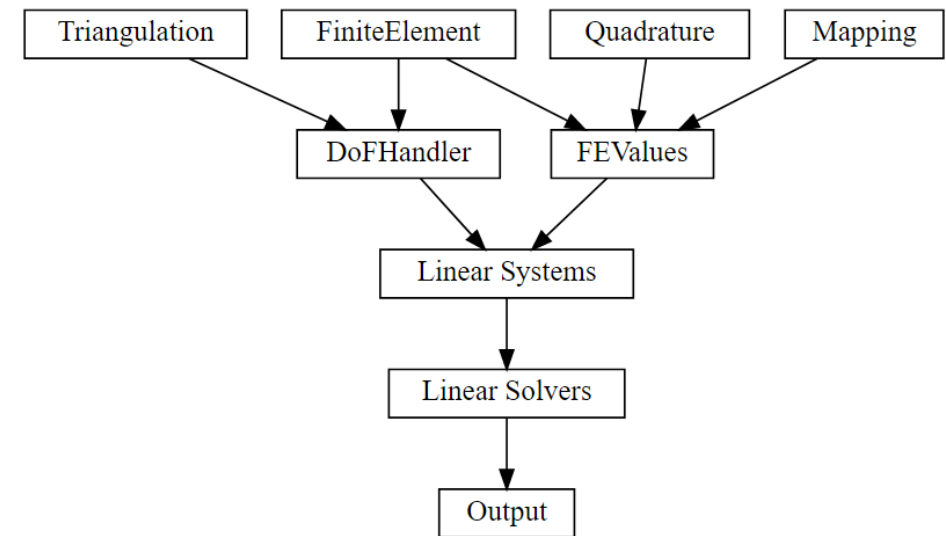


Mesh Formats and Libraries



deal.II (<https://www.dealii.org/>)

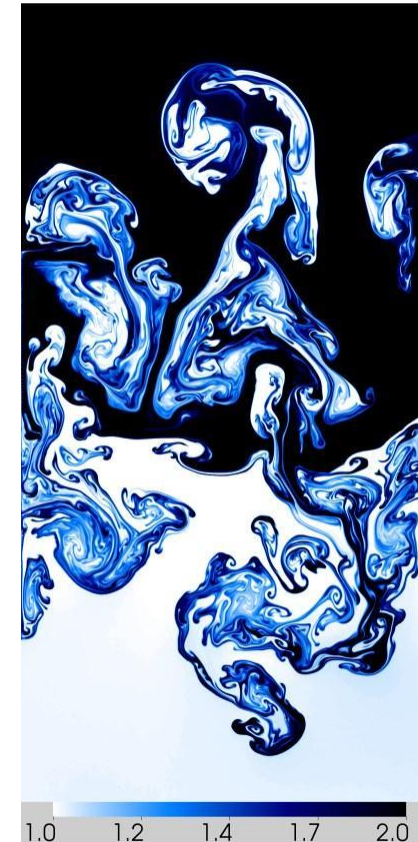
- **Differential Equations Analysis Library**
 - (about 20 years old)
- Open source C++ FEA library.
- Interfaces to PETSc or Trilinos solvers
- Excellent translation support
 - Can process inputs from
 abaqus, unv, ucd, vtk, tecplot, netcdf
 CAD/IGES (OpenCASCADE)
- Lots well structured tutorials and videos



deal.II Architecture

MFEM (<https://mfem.org/>)

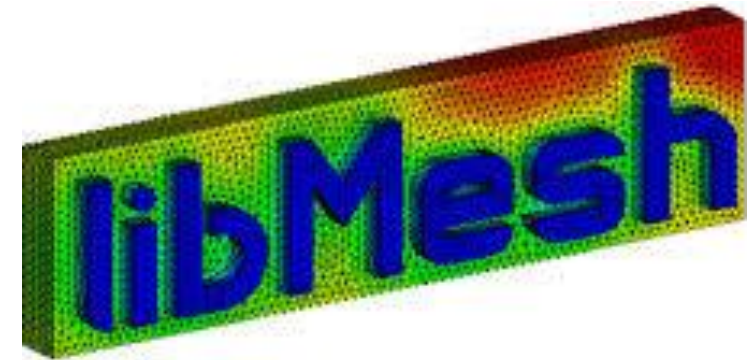
- Modular Finite Element Methods
 - about 10 years old developed by DOE
- Designed for highly parallel computations
- Another C++ Library
- Interfaces to PETSc or HYPRE solvers
- Good translation support
 - Can process inputs from
 vtk, Gmsh, CUBIT (NetCDF)
- Good Tutorials
 - Lots of complex examples (miniapps)



Multi-mode Rayleigh-Taylor instability simulation using 4th order mixed elements in the MFEM-based [BLAST](#) shock hydrodynamics code. Visualization with [VisIt](#).

libMesh (<http://libmesh.github.io/>)

- Another C++ FEA library.
- Provide support for adaptive mesh refinement (AMR) computations in parallel while allowing a research scientist to focus on the physics they are modeling.
- Interfaces to PETSc or Trilinos solvers
- Good translation support

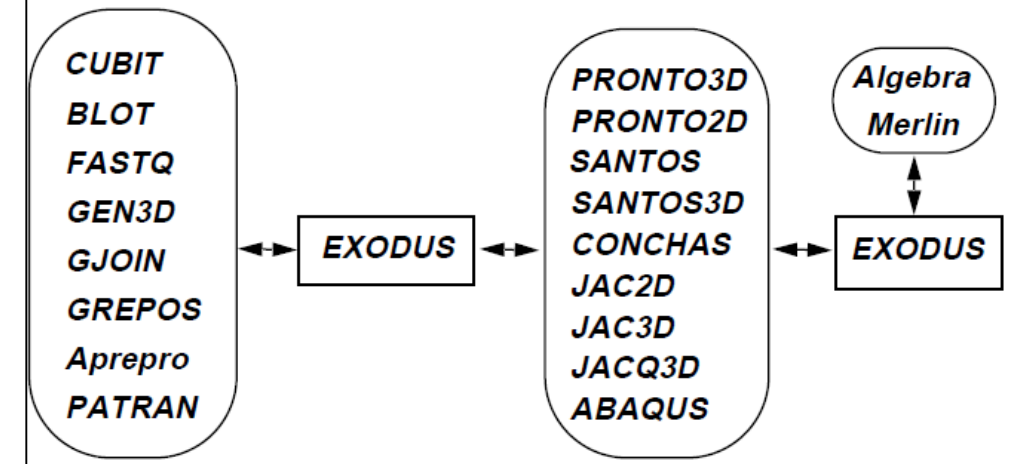


SEACAS/EXODUS

<https://gsjaardema.github.io/seacas/html/index.html>

- The Sandia Engineering Analysis Code Access System (SEACAS) is a suite of preprocessing, postprocessing, translation, and utility applications supporting finite element analysis software using the Exodus database file format.
 - Specifically for using Exodus II
 - Specifically for finite element analysis
- API supports C/C++ and Fortran

FIGURE 2. Expanded Modular View of SEACAS

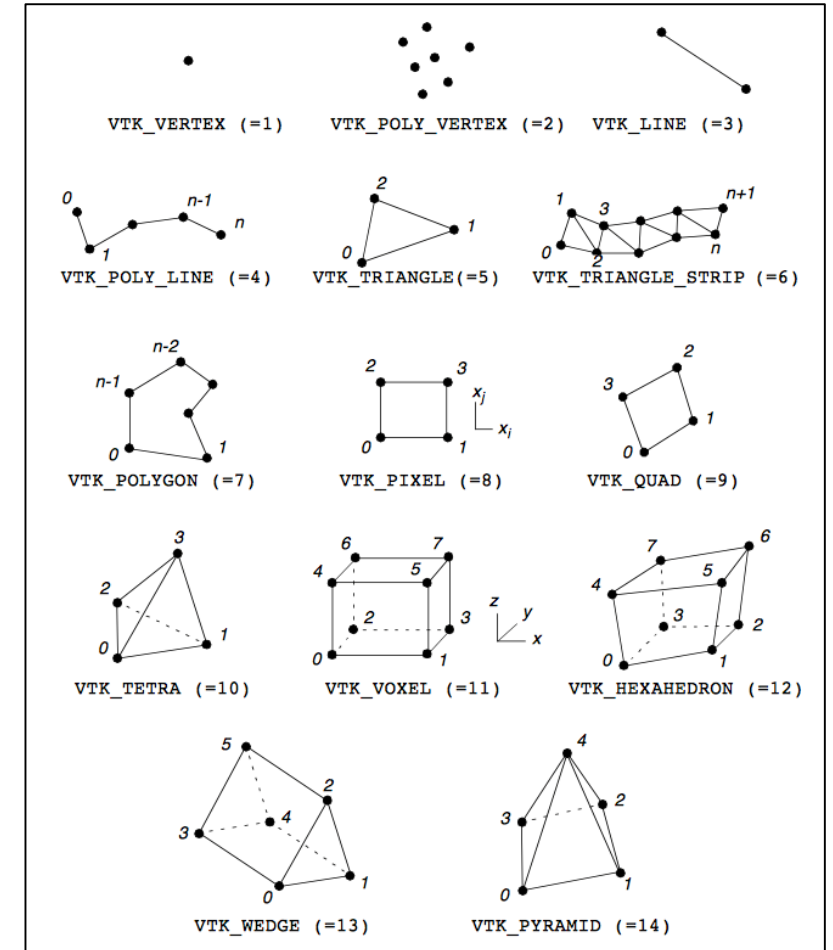




Visualization ToolKit

(www.vtk.org)

- Open source C++ library developed by Kitware (the Cmake people).
- Primarily a library for visualization
 - However core data model is very similar to mesh
 - Furthermore, previously discussed visualization tools that visualize work with the aforementioned mesh libraries
 - Consequently, there are several tools available that now how to go from VTK to a mesh or vice-versa.
- Does not presume discretization of type of numerical scheme

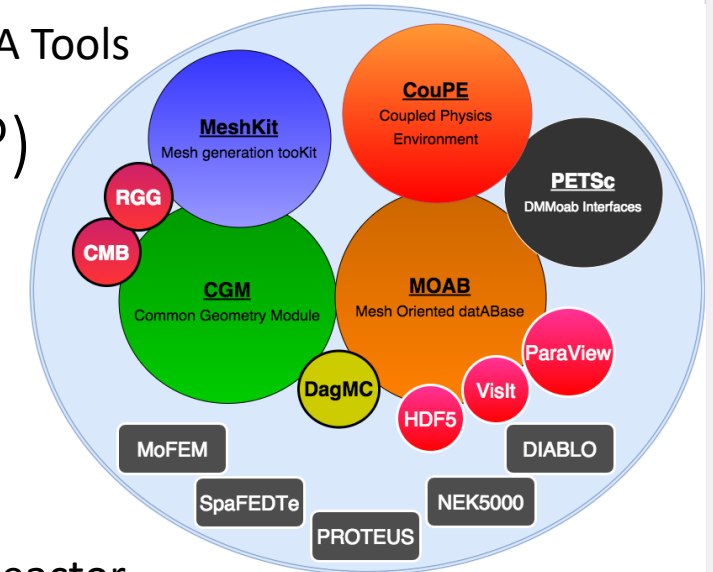


VTK primitives

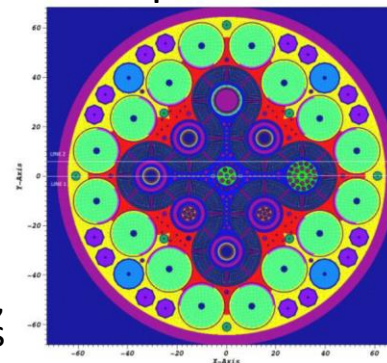
SIGMA Tools (sigma.mcs.anl.gov—deprecated?)

- Scalable Interfaces for Geometry and Mesh based Applications
 - SIGMA provides interfaces and tools to access geometry data, create high quality unstructured meshes along with unified data-structures to load and manipulate parallel computational meshes for various applications to enable efficient physics solver implementations.
 - All libraries implemented in C++ and Python interfaces are provided.
- MeshKit – Provides meshing algorithms
- CGM – Common Geometry Model
 - Provides geometry functionality to other applications and mesh libraries. Includes some features not in solid modeling engines like decomposition tools
- MOAB – Mesh Oriented dAtaBase
 - library for representing unstructured and structured mesh, and field data on a mesh. Includes “Zoo” of finite elements
 - Facilitates solution transfer

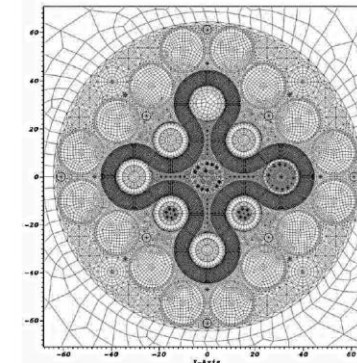
SIGMA Tools



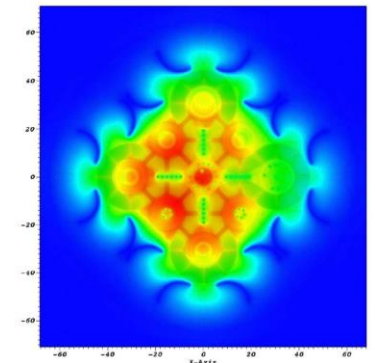
Example: Advanced Test Reactor



Geometry/BC Setup



Generate unstructured mesh
and link with solvers



Check-point/Analyze/Visualize



Which one is best for me?

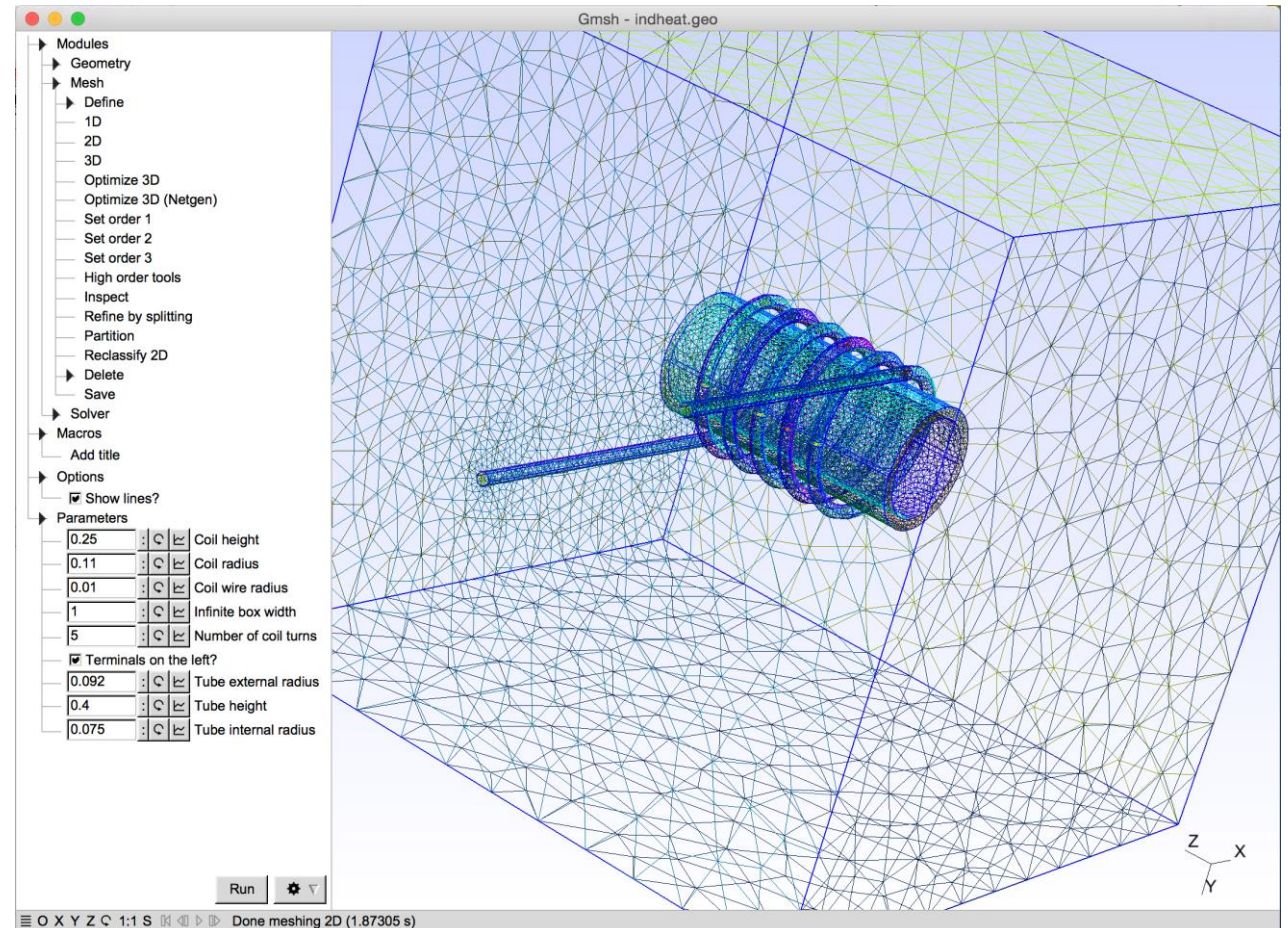
- People seem to love writing open source finite element libraries
- If your group is already using one, go with it.
 - Unless...
- If starting new things to consider
 - What language am I programming in and does the library have an API to this language?
 - Is the API sufficient for my needs?
 - Do I find the API intuitive and/or easy to use?
 - Is there good tool support for pre- and post- processing?
 - Interoperability with commercial tools



Meshing Tools

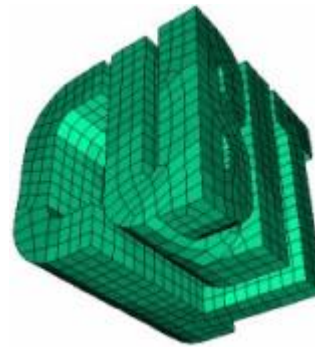
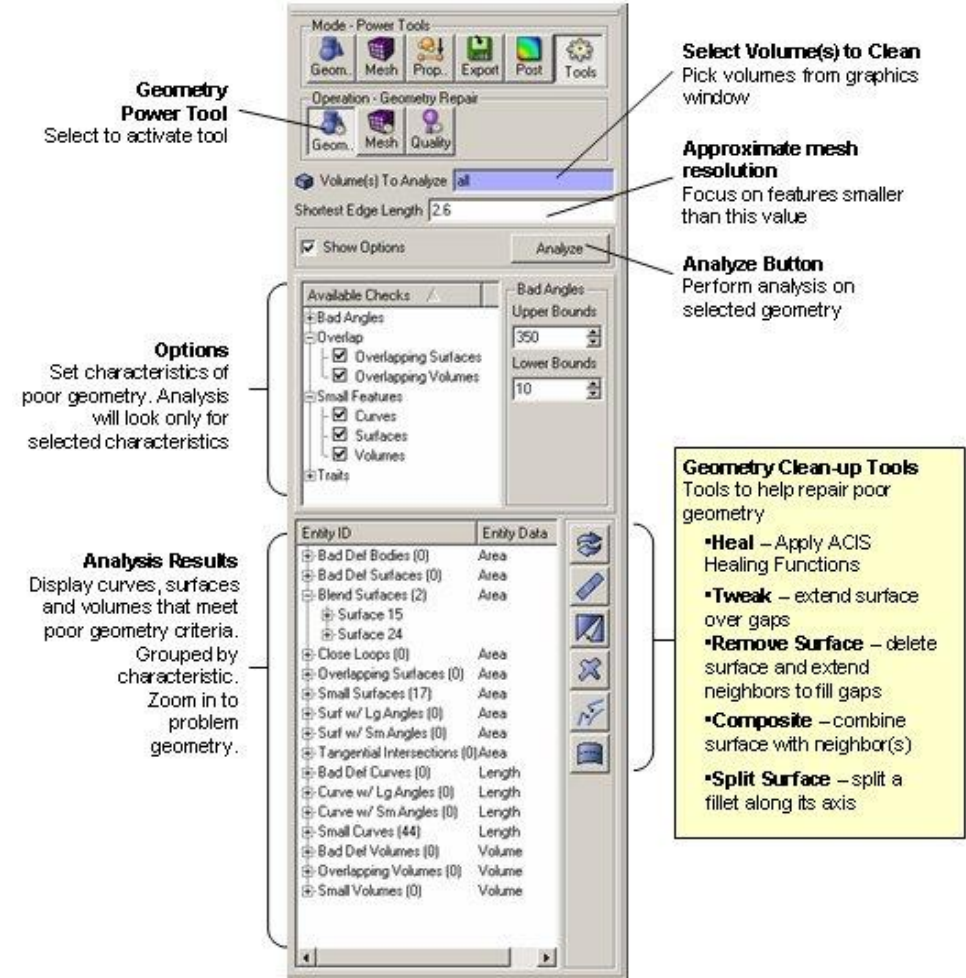
Gmsh (<http://gmsh.info/>)

- Open Source GUI
 - Has good support in previously mentioned libraries
- Capabilities
 - Built-in CAD engine (geometry)
 - Post-processing
 - Generating extruded, or repetitive meshes
 - Interface to external solvers via sockets (TCP/IP)
- Some drawbacks
 - Limited functionality in scripting and GUI



CUBIT (cubit.sandia.gov)

- CUBIT is a full-featured software toolkit for robust generation of two- and three-dimensional finite element meshes (grids) and geometry preparation.
 - Pretty much the only DOE sponsored open source meshing GUI.

Geometry Power Tool
 Select to activate tool

Select Volume(s) to Clean
 Pick volumes from graphics window

Approximate mesh resolution
 Focus on features smaller than this value

Analyze Button
 Perform analysis on selected geometry

Options
 Set characteristics of poor geometry. Analysis will look only for selected characteristics

Analysis Results
 Display curves, surfaces and volumes that meet poor geometry criteria. Grouped by characteristic. Zoom in to problem geometry.

Geometry Clean-up Tools
 Tools to help repair poor geometry

- **Heal** – Apply ACIS Healing Functions
- **Tweak** – extend surface over gaps
- **Remove Surface** – delete surface and extend neighbors to fill gaps
- **Composite** – combine surface with neighbor(s)
- **Split Surface** – split a fillet along its axis



CUBIT Tutorial

“Hold on to your butts...”

- Arnold

https://cubit.sandia.gov/public/15.1/help_manual/WebHelp/step_by_step_tutorials/gui/overview.htm

