I will talk about my thesis:
 "Simulation of Simple Evolutionary System"

2. Part I

- 3. I will give background, and computations involving our model in the simulations we did.
 - Then I will address these four questions, and make concluding remarks.
- 4. Population is a collection of length ℓ binary strings
 - Population can be represented by a vector p; the jth component is the proportion of string j in the population.
 - \mathcal{R} is the set of length ℓ binary strings and operations under \mathcal{R} are bitwise modulo 2 operations.
- 5. Crossover and mutation operators are defined using the bitwise operations in \mathcal{R} .
 - Crossover exchanges bits in parents u and v using crossover mask to produce children u' and v' using the rule $u' = um + v\bar{m}, v' = u\bar{m} + vm$
 - χ_m is probability of using crossover mask m

•

- Mutation flips bits in x using mutation mask m.
- μ_m is probability of using mutation mask m
- 6. This flowchart illustrates finite population genetic algorithm
 - Start from random initial population p.
 - Randomly select parents u and v
 - Crossover u and v to produce u' and v' according to randomly chosen crossover mask

- Keep one of u', v' and mutate using randomly chosen mutation mask to produce gamete g
- Repeat to form next generation $\tau(p)$
- 7. In Random Heuristic Search,
 - Given population p, τ is transition rule that maps p to the next generation p' where p and p' both belong to population space Λ_N . N is population size.
 - Finite population evolution forms Markov chain
 - However, τ is stochastic function of crossover and mutation and $\tau(p)$ can not be predicted with certainty
- In infinite population model, population is modeled by vector p where p belongs to population space Λ.
 - \mathcal{G} is a function that maps p to the next generation p' where jth component is proportion of string j occurs in the next generation.
 - The sequence shows evolution of p under infinite population model.
 - The variance is expectation of square of distance between finite population and infinite population.
- 9. This is our model setup for diploid population.
 - We consider diploid genome α with genome length 1.
 - Population is modeled by vector q
 - q_{α} is prevalence of diploid α
 - $t_{\alpha}(g)$ is transmission function which is probability of gamete g being produced from parent α
 - q' is next generation
- 10. Diploids can be determined in terms of haploid distributions.
 - Haploids can be determined in terms of diploid distributions.

 And evolution equation can be expressed in terms of haploid distributions as

$$m{p}_{\gamma_0}' \, = \, \sum_{lpha_0,\,lpha_1} m{p}_{lpha_0} \, m{p}_{lpha_1} \, t_{\langlelpha_0,\,lpha_1
angle}(\gamma_0)$$

- ullet In the matrix form, evolution equation can be expressed as $m{p}_g' = m{p}^T M_g \, m{p}$
- Where M(g) is mixing matrix
- 11. This slide shows computation of crossover and mutation distributions, and transmission function
 - Transmission function is computed with this expression
 - There are 3 sum terms in it, which is expensive to compute
- 12. W is walsh matrix
 - \hat{A} is walsh transform of matrix A, and \hat{w} is walsh transform of column vector w.
 - Mixing matrix is given by the expression

$$\widehat{M}_{u,v} = 2^{\ell-1} \left[uv = \mathbf{0} \right] \widehat{\boldsymbol{\mu}}_u \widehat{\boldsymbol{\mu}}_v \sum_{k \in \overline{u+v} \mathcal{R}} \boldsymbol{\chi}_{k+u} + \boldsymbol{\chi}_{k+v}$$

• This is evolution eqn in Walsh basis

$$\widehat{\boldsymbol{p}}_g' = 2^{\ell/2} \sum_{i \in g\mathcal{R}} \widehat{\boldsymbol{p}}_i \, \widehat{\boldsymbol{p}}_{i+g} \, \widehat{M}_{i,i+g}$$

- 13. Now if we compare evolution eqn in Walsh basis to what we had before, we got rid of matrix multiplication to compute next generation.
 - We don't need to refer to 2^{ℓ} mixing matrices either, only one mixing matrix is required in walsh basis computation.
 - Calculating each mixing matrix in previous eqn required 3 sum terms, which is reduced to 1 sum term in walsh basis.
 - Consider l = 14, 2^{14} mixing matrices would require 32 TB of memory, while one mixing matrix would require only 2 GB of memory

- We think that is great optimization in resource
- 14. With naive computation as shown in equation (1), there would be $2^l \cdot 2^l$ multiplication terms to be computed
 - where f is finite population and q is infinite population
 - We simplify it as shown in eqn (2) where it needs only 2^l + cardinal value of S_f terms
 - S_f is set of diploids that are in finite populations
 - Writing code to compute in the Walsh basis, and running simulations
 using the Walsh basis is a significant part of my thesis. It represents
 the "Efficient" in the thesis title "Efficient Simulation of a Simple
 Evolutionary System".

15. Part II

- Our first question concerns about convergence of finite population to infinite population.
 - Chebyshev's inequality, Jensen's inequality and geometric point of view, all, suggest the distance might decrease as $1/\sqrt{N}$
 - But all of 3 implications are from inequalities. The distance might decrease much smaller than $1/\sqrt{N}$.
 - \bullet We investigate if the distance in fact decreases like $1/\sqrt{N}$ in practice.
- 17. We ran some simulations with $\chi=0.1$ and $\mu=0.001$ for different values of l
 - These graphs show the results in logarithmic scale.
 - (point to axis) d is the distance, (point to axis) N is population size, (point to axis) n is number of generations
 - Data shows as population size increases, distance decreases and converge to infinite population
 - Graphs show flat surface so we model the data by linear equation

- 18. Regression shows slope m is nearly equal to -0.5
 - This proves distance does decrease as $1/\sqrt{N}$
- 19. $1/\sqrt{N}$ was theoretical upper bound but our simulaion shows it is really very good bound and the distance decreases as $1/\sqrt{N}$.
- 20. Our 2nd question concerns about oscillation in finite populations.
- 21. The infinite population sequence p, $\mathcal{G}(p)$, $\mathcal{G}^2(p)$, \cdots may converge to a point, and we call that point a fixed point, we also call it limit.
 - But under certain conditions, the sequence converges to a periodic orbit between two fixed points, say p* and q*
- 22. And the conditions are: For some g

$$-1 = \sum_{j} (-1)^{g^{T} j} \boldsymbol{\mu}_{j}$$
$$1 = \sum_{k \in \bar{g}\mathcal{R}} \boldsymbol{\chi}_{k+g} + \boldsymbol{\chi}_{k}$$

- 1st one is for mutation distribution and 2nd one is for crossover distribution
- We try to answer our 2nd question through simulations; that is do finite populations exhibit oscillations from random intial populations when infinite populations oscillate?
- 23. Akin, Hasting, Wright, Bidwell and Agapie have studied oscillations in the past.
- 24. Akin considers continuous time model, we consider discrete time model
 - Hastings' study is limited to two bits length, includes only crossover, but no mutation
 - Wright and Bidwell compute a specific fitness function and a specific initial population for randomly generated mutation and crossover distributions in an attempt to find cyclic behavior

- Wright and Agapie use dynamic mutation that depends upon where population is in the population space while we use static mutation
- 25. Simulations were run for both haploid and diploid populations
 - To visualize oscillations, distance to fixed points (p*, q*) are plotted
- 26. These are the results for haploid and diploid population of length 8
 - top row shows results for haploid, bottom row for diploids
 - Population size is in increasing order in columns
 - As population size increases, oscillation approaches the behavior exhibited by infinite population
 - We observe more randomness in diploids than in haploids for same string length and population size.
- Graphs show the results for haploid and diploid population of length
 - We observe that increase in 1 degrades oscillation (particularly in diploids)
- 28. So our answer to the 2nd question is
 - Finite populations exhibit approximate oscillation when infinite populations oscillate
- 29. Question 3 concerns the robustness of finite population oscillation under mutation-violation
- 30. We introduce violation ϵ as following
 - This means no periodic orbits for finite population
 - ullet The modification in μ makes the Markov chain regular
 - This means no periodic orbits for infinite population
 - We study if finite population can exhibit approximate oscillations in that case

- 31. Simulations were run for different values of ϵ .
 - Distance of population to limits p and q without violation are plotted
- 32. These figures show results for haploid population behavior of string length 8
 - Graphs are arranged in rows for increasing ϵ and columns for increasing population size
 - Graphs show convergence of finite population behavior to infinite population behavior as population increases
 - Results show oscillating behavior of population for smaller values of epsilon that diminishes with time.
 - As value of ϵ grows, oscillation diminishes
 - Oscillation dies out for infinite population.
 - Even though finite population also appears to be dying out, since Markov chain is regular, finite population will oscillate infinitely often (for $\epsilon = 0.1$).
- Graphs show results for diploid population behavior of string length12
 - We observed oscillation also degrades as string length increases. It
 is seen in both haploid and diploid cases, but particularly noticeable
 in diploids.
- **34**. Our conclusions from this simulation are
 - Finite populations exhibit approximate oscillation even if Markov chain is regular when violation is small
 - If violation becomes larger, finite population oscillation decreases
 - As string length increases, oscillation degrades
- 35. Our previous question concerns with the robustness of finite population oscillation under mutation-violation, our next question also

concerns with the robustness of finite population but under crossoverviolation

- 36. We introduce violation ϵ in crossover distribution
 - Crossover-violation means no periodic orbit exists for infinite population
 - We investigate if finite population can exhibit approximate oscillations in this case
- 37. Simulations were run for different values of ϵ
 - Distances of population to limits p and q without violation are plotted
- Graphs show results for haploid population behavior of string length
 - Results show similar behavior to that of violation in mutation case
- Graphs show results for diploid population behavior of string length
 12
 - However, we noticed that rate of damping of amplitudes of oscillation is slower than in mutation violation
 - And, we see more randomness in population behavior than in mutation violation, especially for diploid case
- 40. Conclusions from experiment on violation in crossover are
 - Finite populations exhibit approximate oscillation if violation is small
 - If violation becomes larger, finite population oscillation decreases
- 41. Overall conclusions from this research are
 - Vose's haploid model makes computation efficient in diploid case by reducing to haploid case
 - Distance between finite population and infinite population can decrease like $1/\sqrt{N}$

- \bullet When infinite populations oscillate, finite populations exhibit approximate oscillation
- $\bullet\,$ Finite populations exhibit approximate oscillation for small mutation-violation
- Finite populations exhibit approximate oscillation for small crossover-violation