I will talk about my thesis:
 "Simulation of Simple Evolutionary System"

## 2. Part I

- 3. I will give background, and computations involving our model in the simulations we did.
  - Then I will address these four questions, and make concluding remarks.
- 4. Population is a collection of length  $\ell$  binary strings
  - Population can be represented by a vector; the *j*th component is the proportion of string j in the population.
  - $\mathcal{R}$  is the set of length  $\ell$  binary strings and operations under  $\mathcal{R}$  are bitwise modulo 2 operations.
- 5. Crossover and mutation operators are defined using the bitwise operations in  $\mathcal{R}$ .
  - Crossover exchanges bits in parents u and v using crossover mask to produce children u' and v' using the rule  $u' = um + v\bar{m}, v' = u\bar{m} + vm$
  - $\chi_m$  is probability of using crossover mask m

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- Mutation flips bits in x using mutation mask m.
- $\mu_m$  is probability of using mutation mask m
- 6. This flowchart illustrates finite population genetic algorithm
  - Start from random initial population p.
  - Randomly select parents u and v
  - Crossover u and v to produce u' and v' according to randomly chosen crossover mask

- Keep one of u', v' and mutate using randomly chosen mutation mask to produce gamete g
- Repeat to form next generation  $\tau(p)$
- 7. In Random Heuristic Search,
  - Given population p,  $\tau$  is transition rule that maps p to the next generation p' where p and p' both belong to population space  $\Lambda_N$ . N is population size.
  - Finite population evolution forms Markov chain
  - However,  $\tau$  is stochastic function of crossover and mutation and  $\tau(p)$  can not be predicted with certainty
- In infinite population model, population is modeled by vector p where p belongs to population space Λ.
  - $\mathcal{G}$  is a function that maps p to the next generation p' where jth component is proportion of string j occurs in the next generation.
  - The sequence shows evolution of p under infinite population model.
  - The variance is expectation of square of distance between finite population and infinite population.
- 9. This is our model setup for diploid population.
  - We consider diploid genome  $\alpha$  with genome length 1.
  - Population is modeled by vector q
  - $q_{\alpha}$  is prevalence of diploid  $\alpha$
  - $t_{\alpha}(g)$  is transmission function which is probability of gamete g being produced from parent  $\alpha$
  - q' is next generation
- 10. Diploids can be determined in terms of haploid distributions.
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 And evolution equation can be expressed in terms of haploid distributions as

$$m{p}_{\gamma_0}' \, = \, \sum_{lpha_0,\,lpha_1} m{p}_{lpha_0} \, m{p}_{lpha_1} \, t_{\langlelpha_0,\,lpha_1
angle}(\gamma_0)$$

- ullet In the matrix form, evolution equation can be expressed as  $m{p}_g' = m{p}^T M_g \, m{p}$
- Where M(g) is mixing matrix
- 11. This slide shows computation of crossover and mutation distributions, and transmission function
  - Transmission function is computed with this expression
  - There are 3 sum terms in it, which is expensive to compute
- 12. W is walsh matrix
  - $\hat{A}$  is walsh transform of matrix A, and  $\hat{w}$  is walsh transform of column vector w.
  - Mixing matrix is given by the expression

$$\widehat{M}_{u,v} = 2^{\ell-1} \left[ uv = \mathbf{0} \right] \widehat{\boldsymbol{\mu}}_u \widehat{\boldsymbol{\mu}}_v \sum_{k \in \overline{u+v} \mathcal{R}} \boldsymbol{\chi}_{k+u} + \boldsymbol{\chi}_{k+v}$$

• This is evolution eqn in Walsh basis

$$\widehat{\boldsymbol{p}}_g' = 2^{\ell/2} \sum_{i \in g\mathcal{R}} \widehat{\boldsymbol{p}}_i \, \widehat{\boldsymbol{p}}_{i+g} \, \widehat{M}_{i,i+g}$$

- 13. Now if we compare evolution eqn in Walsh basis to what we had before, we got rid of matrix multiplication to compute next generation.
  - We don't need to refer to  $2^{\ell}$  mixing matrices either, only one mixing matrix is required in walsh basis computation.
  - Calculating each mixing matrix in previous eqn required 3 sum terms, which is reduced to 1 sum term in walsh basis.
  - Consider l = 14,  $2^{14}$  mixing matrices would require 32 TB of memory, while one mixing matrix would require only 2 GB of memory

- We think that is great optimization in resource
- 14. With naive computation as shown in equation (1), there would be  $2^l \cdot 2^l$  multiplication terms to be computed
  - where f is finite population and q is infinite population
  - We simplify it as shown in eqn (2) where it needs only  $2^l$  + cardinal value of  $S_f$  terms
  - $S_f$  is set of diploids that are in finite populations
- 15. Writing code to compute in the Walsh basis, and running simulations using the Walsh basis is a significant part of my thesis. It represents the "Efficient" in the thesis title "Efficient Simulation of a Simple Evolutionary System".

16.

- 17. Our first question concerns about convergence of finite population to infinite population.
  - Chebyshev's inequality, Jensen's inequality and geometric point of view, all, suggest the distance might decrease as  $1/\sqrt{N}$
  - But all of 3 implications are from inequalities. The distance might decrease much smaller than  $1/\sqrt{N}$ .
  - $\bullet$  We investigate if the distance in fact decreases like  $1/\sqrt{N}$  in practice.
- - These graphs show the results in logarithmic scale.
  - (point to axis) d is the distance, (point to axis) N is population size,
     (point to axis) n is number of generations
  - Data shows as population size increases, distance decreases and converge to infinite population
  - Graphs show flat surface so we model the data by linear equation

- 19. Regression shows slope m is nearly equal to -0.5
  - This proves distance does decrease as  $1/\sqrt{N}$
- 20.  $1/\sqrt{N}$  was theoretical upper bound but our simulaion shows it is really very good bound and the distance decreases as  $1/\sqrt{N}$ .
- 21. Our 2nd question concerns about oscillation in finite populations.
- 22. The infinite population sequence p,  $\mathcal{G}(p)$ ,  $\mathcal{G}^2(p)$ ,  $\cdots$  may converge to a point, and we call that point a fixed point, we also call it limit.
  - But under certain conditions, the sequence converges to a periodic orbit between two fixed points, say p\* and q\*
- 23. And the conditions are: For some g

$$-1 = \sum_{j} (-1)^{g^{T} j} \boldsymbol{\mu}_{j}$$
$$1 = \sum_{k \in \bar{g}\mathcal{R}} \boldsymbol{\chi}_{k+g} + \boldsymbol{\chi}_{k}$$

- 1st one is for mutation distribution and 2nd one is for crossover distribution
- We try to answer our 2nd question through simulations; that is do finite populations exhibit oscillations from random intial populations when infinite populations oscillate?
- 24. Akin, Hasting, Wright, Bidwell and Agapie have studied oscillations in the past.
- 25. Akin considers continuous time model, we consider discrete time model
  - Hastings' study is limited to two bits length, includes only crossover, but no mutation
  - Wright and Bidwell compute a specific fitness function and a specific initial population for randomly generated mutation and crossover distributions in an attempt to find cyclic behavior

- Wright and Agapie use dynamic mutation that depends upon where population is in the population space while we use static mutation
- 26. Simulations were run for both haploid and diploid populations
  - To visualize oscillations, distance to fixed points  $(p^*, q^*)$  are plotted
- 27. These are the results for haploid and diploid population of length 8
  - top row shows results for haploid, bottom row for diploids
  - Population size is in increasing order in columns
  - As population size increases, oscillation approaches the behavior exhibited by infinite population
  - We observe more randomness in diploids than in haploids for same string length and population size.
- 28. Graphs show the results for haploid and diploid population of length 12
  - We observe that increase in 1 degrades oscillation (particularly in diploids)
- 29. So our answer to the 2nd question is
  - Finite populations exhibit approximate oscillation when infinite populations oscillate
- 30. Question 3 concerns the robustness of finite population oscillation under mutation-violation
- 31. We introduce violation  $\epsilon$  as following
  - This means no periodic orbits for finite population
  - ullet The modification in  $\mu$  makes the Markov chain regular
  - This means no periodic orbits for infinite population
  - We study if finite population can exhibit approximate oscillations in that case

- 32. Simulations were run for different values of  $\epsilon$ .
  - Distance of population to limits p and q without violation are plotted
- 33. These figures show results for haploid population behavior of string length 8
  - Graphs are arranged in rows for increasing  $\epsilon$  and columns for increasing population size
  - Graphs show convergence of finite population behavior to infinite population behavior as population increases
  - Results show oscillating behavior of population for smaller values of epsilon that diminishes with time.
  - As value of  $\epsilon$  grows, oscillation diminishes
  - Oscillation dies out for infinite population.
  - Even though finite population also appears to be dying out, since Markov chain is regular, finite population will oscillate infinitely often (for  $\epsilon = 0.1$ ).
- Graphs show results for diploid population behavior of string length
   12
  - We observed oscillation also degrades as string length increases. It
    is seen in both haploid and diploid cases, but particularly noticeable
    in diploids.
- 35. Our conclusions from this simulation are
  - Finite populations exhibit approximate oscillation even if Markov chain is regular when violation is small
  - If violation becomes larger, finite population oscillation decreases
  - As string length increases, oscillation degrades
- 36. Our previous question concerns with the robustness of finite population oscillation under mutation-violation, our next question also

concerns with the robustness of finite population but under crossoverviolation

- 37. We introduce violation  $\epsilon$  in crossover distribution
  - Crossover-violation means no periodic orbit exists for infinite population
  - We investigate if finite population can exhibit approximate oscillations in this case
- 38. Simulations were run for different values of  $\epsilon$ 
  - Distances of population to limits p and q without violation are plotted
- Graphs show results for haploid population behavior of string length
  - Results show similar behavior to that of violation in mutation case
- 40. Graphs show results for diploid population behavior of string length 12
  - However, we noticed that rate of damping of amplitudes of oscillation is slower than in mutation violation
  - And, we see more randomness in population behavior than in mutation violation, especially for diploid case
- 41. Conclusions from experiment on violation in crossover are
  - Finite populations exhibit approximate oscillation if violation is small
  - If violation becomes larger, finite population oscillation decreases
- 42. Overall conclusions from this research are
  - Vose's haploid model makes computation efficient in diploid case by reducing to haploid case
  - Distance between finite population and infinite population can decrease like  $1/\sqrt{N}$

- $\bullet$  When infinite populations oscillate, finite populations exhibit approximate oscillation
- $\bullet\,$  Finite populations exhibit approximate oscillation for small mutation-violation
- Finite populations exhibit approximate oscillation for small crossover-violation