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03. Implement Dijkstra's algorithm to-find Suitable path i.e., shortest path for a given topology.

emport sys

class Graph:

def -init - (self, vertices):

Self. v = vertices

Self. graph = [[o for column in

range (vertices)] for row in

range (vertices)]

def printSolution (self, dist):

print ("Vextex It Distance from
Source Vertex")

-fox node in range (self, v):

print (node, "It", print &

dist[node])

Page No.
Date

def minDistance (self, dist, spiset):
min = sys. maxsize

-fox v in range (self.v):

if dist[v] < min and sptSet[v]=

False:

min = dut[v]
min index = v

return min index

def dijkstra (self, soc):

dist = [sys.maxsize] \* self.v

dist [soc] = 0

spt Set = [False] \* self.v

for cout in range (self.v):

u=self.minDistance (dist, sptset) sptset[u] = Tove

=for v in range (self.v):

if self.graph[u][v] >0 and

sptSet[v] == False and dist[v] > dist[u]+

## SULF-graph will telf-graph

sulf, printsolution (dut)

9 = Graph (9)

9.9xaph = [ [0,4,0,0,0,0,0,8,0], [4,0,8,0,0,0,0,11,0] [0,8,0,7,0,4,0,0,2] [0,0,7,0,9,14,0,0,0] [0,0,4,14,10,0,2,0,0] [0,0,4,14,10,0,2,0,0] [0,0,0,0,0,0,2,0,1,6] [8,11,0,0,0,0,0,1,0,7] [0,0,2,0,0,0,0,6,7,0]

g. dijkstra(o)