	Q1	
NAME :	Q2	
SID :	Q3	
SECTION:	Q4	
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Table No.:



# **COLLEGE OF ENGINEERING PUTRAJAYA CAMPUS** TEST 2 **SEMESTER 1, 2021/2022**

PROGRAMME : Bachelor of Electrical & Electronics Engineering (Honours) /

Bachelor of Electrical Power Engineering (Honours)

SUBJECT CODE : EEEB363/EEEB3024 SUBJECT : Digital Signal Processing : 29th December 2021

DATE

: 2.5 hours **DURATION** 

#### **INSTRUCTIONS TO CANDIDATES:**

- 1. This paper contains FOUR (4) questions.
- 2. Answer all questions.

### DO NOT OPEN THE QUESTION PAPER UNTIL YOU ARE TOLD TO DO SO

THIS QUESTION PAPER CONSISTS OF FIVE (5) PRINTED PAGES **INCLUDING THIS COVER PAGE** 

#### **QUESTION 1 [20 MARKS]**

- (a) A causal finite impulse response filter is given as  $h_1[n] = \{1, 2, 2, 1\}; 0 \le n \le 3$ .
  - (i) Write  $h_1[n]$  as a function of delayed unit impulses,  $\delta[n]$ . Then determine its z-transform,  $H_1(z)$ .

[3 marks]

(ii) Sketch the poles of  $H_1(z)$  on a z-plane.

[3 marks]

(iii) Describe the stability and causality of the finite impulse response filter above based on its region of convergence (ROC).

[2 marks]

(b) A digital filter transfer function is given by

$$H_2(z) = \frac{z^2 + z - 2}{z^2 + 0.9z + 0.18}$$

(i) Sketch the poles of  $H_2(z)$  on another z-plane.

[3 marks]

(ii) Determine the various possible ROC for  $H_2(z)$ .

[3 marks]

(c) A digital filter transfer function is given by

$$H_3(z) = \frac{1}{1 - 0.6 e^{-j\frac{\pi}{2}} z^{-1}} + \frac{1}{1 - 0.6 e^{j\frac{\pi}{2}} z^{-1}}$$

(i) Sketch the poles of  $H_3(z)$  on another z-plane.

[3 marks]

(ii) If the system  $H_3(z)$  is stable and causal, determine the impulse response  $h_3[n]$ .

[3 marks]

## **QUESTION 2 [30 MARKS]**

(a) A linear time-invariant (LTI) discrete-time system is described in **Figure 1**.

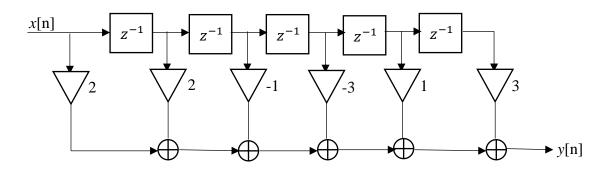


Figure 1: Linear Time Invariant (LTI) discrete-time system

(i) Analyze the block diagram in **Figure 1** and develop the relation between output, y[n] and input, x[n].

[3 marks]

(ii) Determine the impulse response, h[n], of above LTI discrete-time system.

[5 marks]

(iii) Determine **AND** explain the linearity and causality condition of h[n].

[4 marks]

(iv) Determine the group delay value of h[n].

[3 marks]

(b) A typical transmission channel is characterized by a causal transfer function, H(z).

$$H(z) = \frac{(0.5z - 2)(4z + 12)(2z - 3)}{(z - 0.1)(z + 0.3)(z + 0.2)}$$

(i) Determine all poles **AND** zeros value of H(z).

[3 marks]

(ii) Classify H(z) as a minimum, maximum or mixed phase system. In your own words, discuss on the choice of phase class.

[4 marks]

(iii) Represent H(z) as a minimum phase function,  $H_{min}(z)$  in cascade with all pass phase function,  $H_{ap}(z)$ .

[8 marks]

#### **QUESTION 3 [25 MARKS]**

Consider the cascade of two causal first order and second order linear time-invariant (LTI) discrete time system shown in **Figure 2**.

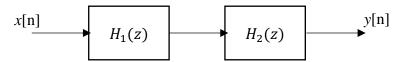


Figure 2: First order and second order LTI-DT system

where,

$$H_1(z) = \frac{2 - 0.2z^{-1}}{1 + 0.1z^{-1}} \text{ and } H_2(z) = \frac{(1 + 2z^{-1})(1 + z^{-1})}{(1 + 0.3z^{-1})(1 - 0.1z^{-1})}$$

(a) Determine the transfer function of the overall cascade system,  $H(z) = H_1(z) \times H_2(z)$ .

[3 marks]

(b) Develop the realization of the overall system, H(z) in Direct Form I **AND** Direct Form II.

[12 marks]

(c) In your own words, describe the differences between Direct Form I and Direct Form II.

[4 marks]

(d) Develop the cascade form realization of H(z) with the least number of coefficients in the structure.

[6 marks]

#### **QUESTION 4 [25 MARKS]**

- (a) When selecting digital filters for an application, compare between finite impulse response (FIR) and infinite impulse response (IIR) filters as below:
  - (i) Discuss the differences between FIR and IIR based on their phase response and the number of coefficients.

[2 marks]

(ii) What needs to be done in the design steps to narrow the transition bandwidth in FIR and IIR filters respectively? Please explain.

[2 marks]

(b) Somebody hacked your Discord server and now all voice chats have some audio noise at a specific frequency. You recorded the noise and managed to identify the noise frequencies by analyzing its frequency spectrum. Following your findings, a digital filter is proposed to attenuate the noise, with a sampling frequency of 2000Hz and the following specifications:

$$0.90 \le |H(e^{j\omega})|^2 \le 1.00; |f| \le 600Hz$$
  
 $|H(e^{j\omega})|^2 \le 0.10; |f| \ge 800Hz$ 

(i) According to the specifications mentioned above, sketch the expected graph / tolerance diagram of its squared magnitude response  $|H(e^{i\omega})|^2$  versus normalized angular frequency  $\omega$ . Carefully label the gains, passband edge frequency, stopband edge frequency, passband and stopband frequency ranges.

[6 marks]

(ii) Design a Butterworth infinite impulse response (IIR) filter using the above specifications.

[15 marks]