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## Question 1a

$$t_1 := \frac{(V_0 - V_E)}{a}$$

$$t_1 := \frac{V_0 - V_E}{a} \tag{1}$$

$$V_b(t) := V_b\theta + V_pc(t)$$

$$V b := t \mapsto V b\theta + V pc(t)$$
 (3)

$$t_2(t) := \frac{V_b(t)}{q} + t - \frac{V_\theta}{q}$$

$$t_2 := t \mapsto \frac{V_- b(t)}{a} + t - \frac{V_- \theta}{a} \tag{4}$$

$$x(t) := \frac{m}{2} \cdot t^2 + u_pc\theta \cdot t + x_0$$

$$x := t \mapsto \frac{1}{2} \cdot m \cdot t^2 + u pc\theta \cdot t + x \theta$$
 (5)

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$$V\_{\theta\_func} := t\_{f} \mapsto solve \left( x_{(}t\_{f}) = \left( \frac{V\_{\theta}}{2} - \frac{V\_{E}}{2} \right) \cdot t\_{1} + V\_{E} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \right) \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{2}(t\_{f}) - t\_{1}) - \frac{a \cdot t\_{f}^{2}}{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{f}) - t\_{f}^{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{f}) - t\_{f}^{2} \cdot t\_{1} + V\_{\theta} \cdot (t\_{f}) - t\_{f}^{2} \cdot t\_{f}^{2$$

>  $V_0\_val\_out(t\_f) := piecewise(V_0\_func(t\_f)[2] > 42100, V_0\_func(t\_f)[2], V_0\_func(t\_f)[2] \le 42100, 42100)$ 

$$V\_0\_val\_out := t\_f \mapsto \begin{cases} V\_0\_func_(t\_f)_2 & 42100 < V\_0\_func_(t\_f)_2 \\ 42100 & V\_0\_func_(t\_f)_2 \le 42100 \end{cases}$$
(8)

 $V_0_{val\_back(t\_f)} := piecewise(V_0_{func(t\_f)}[2] > 42100, V_0_{func(t\_f)}[2], V_0_{func(t\_f)}[2] \le 65800, 65800)$ 

$$V\_0\_val\_back := t\_f \mapsto \begin{cases} V\_0\_func_(t\_f)_2 & 42100 < V\_0\_func_(t\_f)_2 \\ 65800 & V\_0\_func_(t\_f)_2 \le 65800 \end{cases} \tag{9}$$

 $V_0_val(1e5\cdot yr_sec)$ 

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V_0_val(100000. yr_sec)
                                                         (10)
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> V_0 func(t_f)[2]

t_f a m t_f V_E V_b u_pc0

\frac{v_b u_pc0}{2} + \frac{v_b u_pc0}{2}
                                                                                                                                                                    (11)
        -\frac{1}{2}(a^2 t_f^2 - m^2 t_f^2 + 2 V_E a t_f + 2 V_E m t_f + 2 V_b 0 a t_f
       -2 \ V\_b0 \ m \ t\_f - 2 \ u\_pc0 \ t\_f \ a - 2 \ m \ t\_f \ u\_pc0 - V\_E^2 + 2 \ V\_E \ V\_b0 + 2 \ V\_E \ u\_pc0 - V\_b0^2 - 2 \ V\_b0 \ u\_pc0 - 4 \ x\_0 \ a - u\_pc0^2)^{1/2}
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## **Rocket Equations**

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Question 1b
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Question to

$$V_{-max}(t,f,m\_mir\_m\_tot) := \operatorname{sqrt}\left(\left(\left(m\_mir\_m\_tot * \frac{(1+R)}{2} * L\_star\right) / (2 * \operatorname{Pi} * c * \operatorname{rho})\right) * (1$$

$$/r_{-}0) + V_{-}b(t_{-}f);$$

$$V_{-max} := (t_{-}f,m\_mir\_m\_tot) \mapsto \sqrt{\frac{m\_mir\_m\_tot \cdot \left(\frac{1}{2} + \frac{2}{2}\right) \cdot L\_star}{2 \cdot \pi \cdot c \cdot \rho \cdot r\_\theta}} + V_{-}b(t_{-}f)$$

$$V_{-max}(t_{-}f,m\_mir\_m\_tot) = V_{-}max(t_{-}f,m\_mir\_m\_tot) + m \cdot t\_{-}f + V_{-}b\theta + u\_{-}pc\theta$$

$$V_{-}max(t_{-}f,m\_mir\_m\_tot) := \operatorname{solve}\left(t\_{-}f = \frac{X(t\_f)}{V\_max(t\_f,m\_mir\_m\_tot)}, t\_{-}f\right) | 1$$

$$final\_time\_sail(m\_mir\_m\_tot) \mapsto \operatorname{solve}\left(t\_{-}f = \frac{X(t\_f)}{V\_max(t\_f,m\_mir\_m\_tot)}, t\_{-}f\right) | 1$$

$$final\_time\_sail(mr)$$

$$V_{-}max(t\_f,m\_mir\_m\_tot) = V_{-}max(t\_f,m\_mir\_m\_tot) + V_{-}f\right) | 1$$

$$V_{-}max(t\_f,m\_mir\_m\_tot) + V_{-}f\right) | 1$$

$$V_{-}max(t\_f,m\_m\_tot) + V_{-}f\right) | 1$$

$$V_{-}max(t\_f,m\_tot) + V_{-}f\right) | 1$$

$$V_{-}max$$