

Inputs:  $K_i=25.1$  (Ns/m),  $K_p=37.7$  (Ns/m), Gain=1.0, Model=Anti-Sway  
Outputs:  $\theta_{\text{Max}}=4.53^\circ$ ,  $V_p \text{ Max}=0.5$  m/s,  $V_t \text{ Max}=0.5$  m/s

