

CNOT-dihedral circuits

Another class of circuits which can be **efficiently represented** and **optimally** (in some cases) synthesized are **CNOT-dihedral circuits**

Def'n (CNOT-dihedral)

CNOT-dihedral circuits of order n are those over $\{X, CNOT, R_n = R_2^{(\pi/n)}\}$

Fact

$\{X, R_n\}$ generate the dihedral group of order n , D_n

Fact

CNOT and X together generate the **affine** permutations

$$(A, \vec{b}) \in GA(n, \mathbb{Z}_2) \cong GL(n, \mathbb{Z}_2) \times \mathbb{Z}_2^n$$

$$(A, \vec{b}) \vec{x} = A\vec{x} + \vec{b}$$

$$\text{E.g. } X|xy\rangle = |x\oplus y\rangle = |(I, 1)x\rangle$$

Intuitively then, CNOT-dihedral circuits compute an affine on basis states, together with a **phase** which is a sum of phases on affine combinations of basis states

E.g.  sends $|xy\rangle$ $\xrightarrow{\text{CNOT}}$ $|x\rangle|x\oplus y\rangle$
 \xrightarrow{T} $w^{x\oplus y}|x\rangle|x\oplus y\rangle$

 sends $|x\rangle$ \xrightarrow{X} $|x\oplus 1\rangle$
 \xrightarrow{T} $w^{x\oplus 1}|x\oplus 1\rangle$

Def'n

Given $\vec{x}, \vec{y} \in \mathbb{Z}_2^n$, $X_{\vec{y}}(\vec{x}) = \vec{x} \cdot \vec{y} = x_1 y_1 \oplus \dots \oplus x_n y_n$

Representation of (NOT-dihedral groups)

Prop (phase polynomial representation)

Let C be a circuit over $\{X, \text{CNOT}, R_m\}$. Then

$$[C]: |\vec{x}\rangle \mapsto e^{2\pi i/m P(\vec{x})} |A\vec{x} + \vec{b}\rangle$$

where $A \in \text{AGL}(n, \mathbb{Z}_2)$, and $P: \mathbb{Z}_2^n \rightarrow \mathbb{Z}_m$ can be written as

$$P(\vec{x}) = \sum_{\vec{y}} a_{\vec{y}} X_{\vec{y}}(\vec{x}), \quad a_{\vec{y}} \in \mathbb{Z}_m$$

We call P a **phase polynomial** and (P, A, \vec{b}) a **phase polynomial representation** of C

Pf.

By induction on the gates of g . Let

$$[C]: |\vec{x}\rangle \mapsto e^{2\pi i/m P(\vec{x})} |A\vec{x} + \vec{b}\rangle$$

$$\begin{aligned} \text{Then } [X_i \cdot C]|\vec{x}\rangle &\mapsto e^{2\pi i/m P(\vec{x})} (X_i |A\vec{x} + \vec{b}\rangle) \\ &\mapsto e^{2\pi i/m P(\vec{x})} |A\vec{x} + (\vec{b} + \vec{e}_i)\rangle \end{aligned}$$

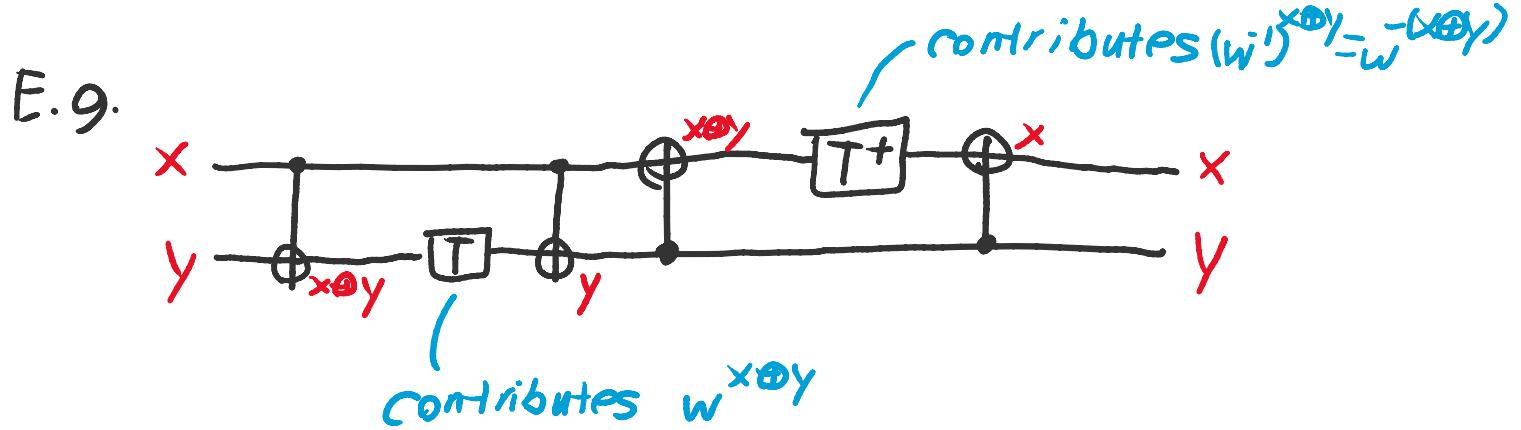
$$\begin{aligned} [\alpha_{ij} \cdot C]|\vec{x}\rangle &\mapsto e^{2\pi i/m P(\vec{x})} ((X_{ij} |A\vec{x} + \vec{b}\rangle) \\ &\mapsto e^{2\pi i/m P(\vec{x})} |E_{ij} A\vec{x} + E_{ij} \vec{b}\rangle \end{aligned}$$

$$\begin{aligned} [(R_k)_i \cdot C]|\vec{x}\rangle &\mapsto e^{2\pi i/m P(\vec{x})} ((R_k)_i |A\vec{x} + \vec{b}\rangle) \\ &\mapsto e^{2\pi i/m P(\vec{x})} e^{2\pi i/m (A_i \vec{x} \oplus b_i)} |A\vec{x} + \vec{b}\rangle \\ &\mapsto e^{2\pi i/m (P(\vec{x}) + (-1)^{b_i} X_{A_i}(\vec{x}) + b_i)} |A\vec{x} + \vec{b}\rangle \end{aligned}$$

Note that $(-1)^{b_i} X_{A_i}(\vec{x}) + b_i$ is itself a phase polynomial

Annotated Circuits

We can find a Phase polynomial representation by **annotating the states of qubits** (in the comp. basis)



Hence,

$$|x\rangle|y\rangle \xrightarrow{\text{Circuit}} w^{x \oplus y} w^{-(x \oplus y)} |x\rangle|y\rangle = |x\rangle|y\rangle$$

Prop.

Given a circuit C over $\{X, \text{CNOT}, R_n\}$, a phase polynomial representation of C can be computed in time and space **linear** in the volume of C ,

$$|C| = (\text{num qubits of } C) \cdot (\text{num gates of } C)$$

We call the bitstrings $\vec{y} \in \mathbb{Z}_2^n$ where $y_i \neq 0$ the **Support** of a phase polynomial P , denoted **Supp(P)**. While phase polynomials are **NOT unique**, P.Q.

$$\sum_{\vec{y}} x_{\vec{y}}(\vec{x}) \equiv 0 \pmod{8} \quad \forall \vec{x}$$

The **canonical** phase polynomial of C , obtained by annotating the circuit and collecting the phases satisfies

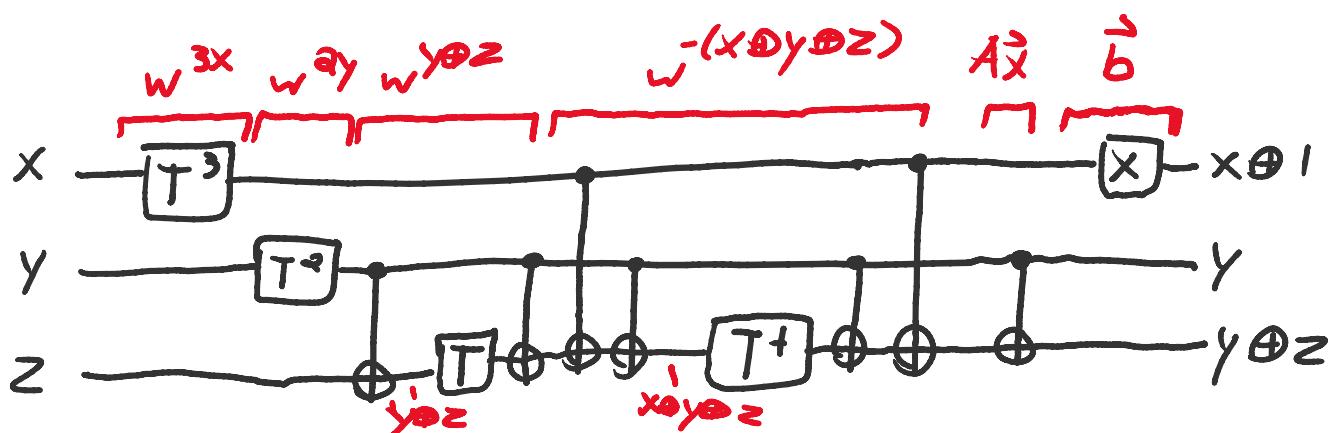
$$|\text{Supp}(P)| \leq \# R_n \text{ gates in } C$$

Synthesis of (NOT-dihedral ops)

Intuitively, a phase polynomial representation (P, A, \vec{b}) corresponds to a sequence of **phase rotations** on **parities** of \vec{x} , followed by a final **Affine permutation**, so we can easily synthesize such a circuit.

E.g.
 Let $U: |xyz\rangle \mapsto e^{i\pi/8} |w\rangle^{3x+2y+(y\oplus z)-(x\otimes y\otimes z)} |(x\oplus y)(y\oplus z)\rangle$

We can implement U over $\{\text{CNOT}, X, T = R_8\}$ as so:



Prop

Let $P(\vec{x}) = \sum_y \alpha_y x_y(\vec{x})$, $\alpha_y \in \mathbb{Z}_n$ and $(A, \vec{b}) \in GA(m, \mathbb{Z}_2)$.

Then $U: |\vec{x}\rangle \mapsto e^{i\pi/2m P(\vec{x})} |A\vec{x} + \vec{b}\rangle$ can be synthesized over $\{\text{CNOT}, X, R_n\}$ in time polynomial in n and with $|\text{supp}(P)| R_n^k$ gates, $k \in \mathbb{Z}_n$.

Note:

If $m=2^8$, i.e. $R_n=T$, then only **even** power of T is a Clifford gate, and any **odd** power means only 1 T gate to implement, since $T^{2k+1} = T \cdot T^{2k}$

$$\text{Hence, } T\text{-count} = |\text{supp}(P \bmod 2)|$$

Synthesizing the Toffoli gate

Recall that $\text{Toffoli} = \overline{\text{CCZ}}$, where CCZ is the CCZ gate defined by

$$\text{CCZ}: |xyz\rangle \mapsto (-1)^{xyz} |xyz\rangle$$

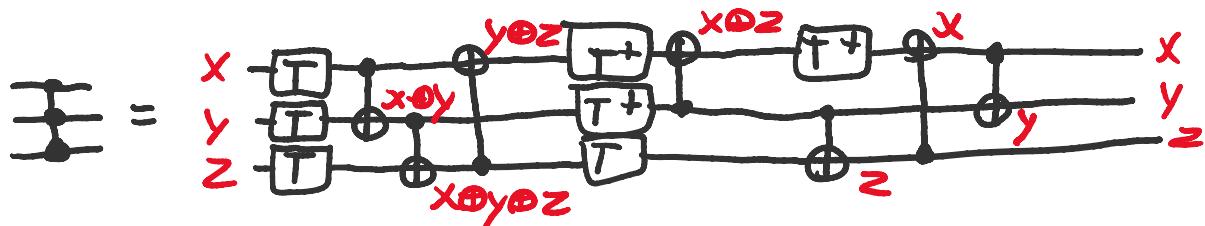
Taking the Fourier expansion* of $f(x,y,z) = xyz$ gives us

$$f(x,y,z) = \frac{1}{4} [x + y + z - (x \oplus y) - (x \oplus z) - (y \oplus z) + (x \oplus y \oplus z)]$$

↑ ↑ ↑ ↑ ↑ ↑ ↑

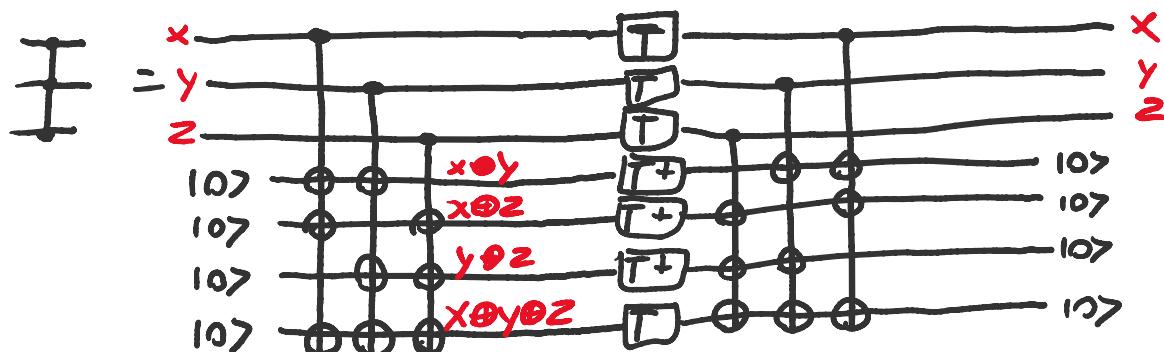
this is a phase polynomial over $\sqrt{-1} = w = e^{\pi i/4}$

We can synthesize an explicit circuit for CCZ by preparing each parity and applying either a $w = e^{\pi i/4}$ or $w^{-1} = e^{\pi i/4}$ rotation (T or T^+).



(T-depth 1 CCZ)

Alternatively, we can synthesize the CCZ (and hence Toffoli gate) in T-depth 1 by using an ancilla to "hold" each parity at once



*Fourier expansion: given $f: \mathbb{Z}_2^n \rightarrow \mathbb{R}$, an expression of f as $f(\vec{x}) = \sum_{\vec{y}} \hat{f}(\vec{y}) X_{\vec{y}}(\vec{x})$

The phase polynomial method

We now have the ingredients for a **phase gate reducing algorithm**, by re-synthesizing CNOT-diagonal circuits. In particular, note

- ① The phase polynomial representation (P, A, \vec{b}) of C can be computed efficiently
- ② $|supp(P)| \leq H$ phase gates in C
- ③ The phase polynomial representation (P, A, \vec{b}) can be synthesized efficiently with $|supp(P)|$ phase gates

(phase gate, e.g. T gate, optimization for {CNOT, X, R_m})

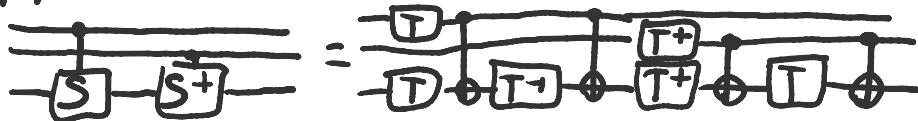
$$C \xrightarrow{\text{annotate}} (P, A, \vec{b}) \xrightarrow{\text{synthesize}} C'$$

$$R_m\text{-count}(C') \leq R_m\text{-count}(C)$$

profit :)

(Example)

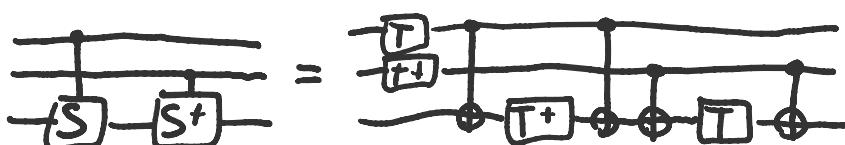
Suppose we want to optimize the circuit:



We start by computing the phase polynomial representation:

$$\begin{aligned} |xyz\rangle &\mapsto_w^{x \cdot z - (x \otimes z)} -y \cdot z + (y \otimes z) |xyz\rangle \\ &\mapsto_w^{x - (x \otimes z)} -y + (y \otimes z) |xyz\rangle \end{aligned}$$

Re-Synthesizing we get a circuit with **$4 < 6$ T gates**



Phase polynomial synthesis problems

More generally, we can ask what is the best circuit for (P, A, \tilde{B}) in some cost metric?

Synthesizing an optimal circuit for (P, A, \tilde{B}) is known as a phase polynomial synthesis problem.

metric	result
R_m -depth	poly-time via Matroid partitioning ($t\text{-par}$)
R_m -count	Equivalent to min-distance decoding for $RM^{\pm}(n, n - \lfloor \log_2(m) \rfloor - 1)$ (hard!)
$CNOT$ -count	NP-hard in restricted cases asymptotically optimal heuristic (Gray-Synth)

Note: $\lfloor \log_2(m) \rfloor$ is the 2-adic valuation of m
(highest power of 2 that divides m)

(Upper & lower bounds on Solutions)

metric	lower bound	upper bound
R_m -depth	$O(1)$ (with ancillas)	$O(1)$ (with ancillas)
R_m -count	Covering radius of $RM^{\pm}(n, n - \lfloor \log_2(m) \rfloor - 1)$	$O\left(\frac{n^{\lfloor \log_2(m) \rfloor - 1}}{\lfloor \log_2(m) \rfloor !}\right)/O(n^2)$ for T-count
$CNOT$ -count	$O(n^2)$ (from gray code)	$O(n^2)$ (from gray code)

CNOT-minimal synthesis

Problem:

Given a phase polynomial representation (P, A, b) ,
synthesize with minimal CNOT-count

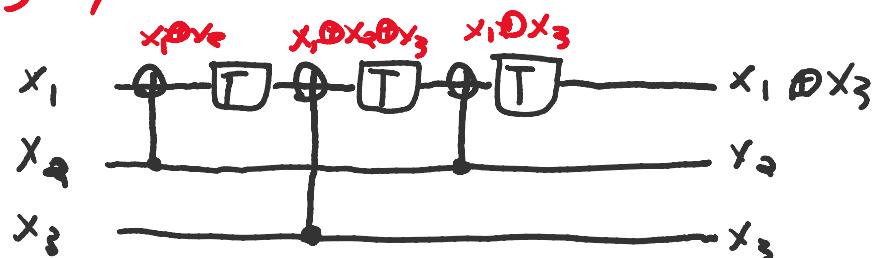
Key idea:

We need to construct a tour of $x_3(\vec{x})$ for each
 $\vec{y} \in \text{Supp}\{P\}$ with the minimal CNOT-count

Ex.

Let $P(x_1, x_2, x_3) = x_1 \oplus x_2 + x_1 \oplus x_3 + x_1 \oplus x_2 \oplus x_3$

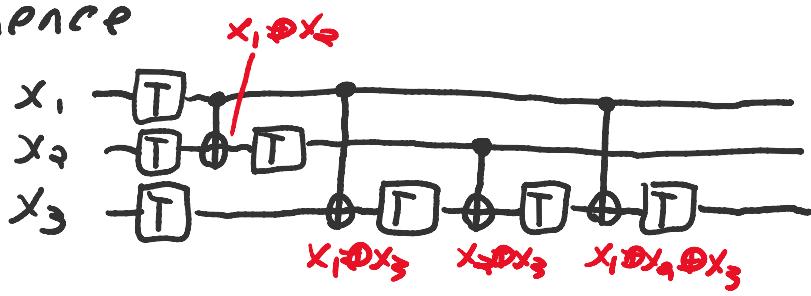
Since $\text{Supp}\{P\} \cong \mathbb{Z}_2^2$, we can construct a minimal tour using the gray cone.



Ex.

Let $P(x_1, x_2, x_3) = x_1 + x_2 + x_3 + x_1 \oplus x_2 + x_1 \oplus x_3 + x_2 \oplus x_3 + x_1 \oplus x_2 \oplus x_3$

Now $\text{Supp}\{P\} = \mathbb{Z}_2^3 \setminus \{0\}$. Any tour of $\text{Supp}\{P\}$ hence requires at least $2^3 - 1$ CNOT gates. An optimal circuit is hence



Prop

Any set $X \cong \mathbb{Z}_2^k$ can be enumerated optimally with $|X \setminus Y|$ CNOT gates where $Y \subseteq \mathbb{Z}_2^n$ is the set of inputs (toured)

Gray-Synth

Basic idea

Attempt to decompose

$$S = \text{Supp } \{P\} = X_1 \cup X_2 \cup \dots \cup X_m$$

where each $X_i \approx \mathbb{Z}_2^k$ for some k .

We do this by recursively selecting some qubit i which maximizes either the 0 or 1 co-factor,

$$i = \arg \max_i \max_{x \in \{0,1\}^k} |\{y \in S \mid y_i = x\}|$$

Algorithm, queue

1. $C := []$, $Q := [(S, I, \epsilon)]$
2. While $Q \neq []$
3. $(S, I, \epsilon) = Q.pop$
4. if $S = \emptyset$, then we're done
5. if $S = \{\bar{y}\}$, then
6. for each j s.t. $\bar{y}_j = 1$
 $C := [CNOT_{ij}] ++ C$
7. for all remaining \bar{y}' , set $\bar{y}' := E_{ij}\bar{y}'$
8. Else
9. $j = \arg \max_{i \in I} \max_{x \in \{0,1\}^k} |\{y \in S \mid y_i = x\}|$
10. $S_0 := \{\bar{y} \in S \mid y_j = 0\}$, $S_1 := \{\bar{y} \in S \mid y_j = 1\}$
11. $Q := [(S_0, I \setminus \{j\}, i \vee j), (S_1, I \setminus \{j\}, i \vee j)] ++ Q$
($i \vee j = j$ if $i = \epsilon$, ; otherwise)

Example

Suppose we wish to Synthesize the phase polynomial

$$f(x) = \frac{1}{8} [x_2 \oplus x_3 + x_1 + x_1 \otimes x_4 + x_1 \otimes x_2 \otimes x_3 + x_1 \otimes x_2 \otimes x_4 + x_1 \otimes x_3]$$

We can visualize Gray-Synth as operating on a matrix with columns corresponding to each parity:

$$\begin{matrix} & & & x_1 \otimes x_2 \otimes x_3 \\ x_2 \otimes x_3 & x_1 \otimes x_4 & / & x_1 \otimes x_2 \\ \begin{matrix} 0 & 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{matrix} & & & x_1 \otimes x_4 \\ & & & x_1 \otimes x_4 \otimes x_3 \end{matrix}$$

We first partition into S_0 & S_1 , by the first row

$$S_0 \rightarrow \begin{matrix} 0 & 1 & -1 & -1 & 1 & 1 & - \\ 1 & 0 & 0 & 1 & 1 & 1 & - \\ 0 & 0 & 1 & 0 & 0 & 0 & \leftarrow S_1 \\ 0 & 0 & 1 & 0 & 1 & 0 & \end{matrix}$$

To compute the only parity in S_0 , $x_2 \otimes x_3$, we perform a CNOT between 3 & 2, then update the matrix

$$\begin{matrix} x_1 & \xrightarrow{\quad} & x_1 \\ x_2 & \xrightarrow{\text{CNOT}} & x_2 \otimes x_3 \\ x_3 & \xrightarrow{\quad} & x_3 \\ x_4 & \xrightarrow{\quad} & x_4 \end{matrix} \quad \begin{matrix} 0 & 1 & 1 & -1 & 1 & 1 & - \\ 1 & 0 & 0 & 1 & 1 & 1 & - \\ 0 & 0 & 0 & 0 & 1 & 1 & - \\ 0 & 0 & 1 & 0 & 1 & 0 & - \end{matrix}$$

We're done with S_0 now, so we pop it off the queue and continue with the remaining, selecting row 2 to construct the next set of co-factors

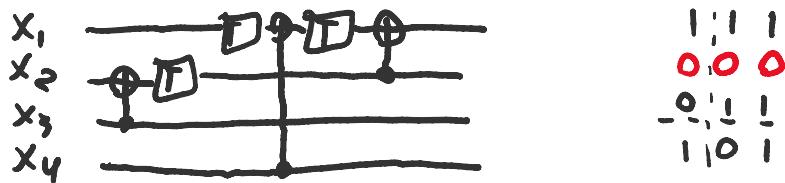
$$S_0 \rightarrow \begin{matrix} 1 & 1 & 1 & 1 & 1 & 1 & - \\ 0 & 0 & 1 & -1 & 1 & -1 & - \\ 0 & 0 & 0 & 1 & 0 & 1 & - \\ 1 & 0 & 1 & 0 & 1 & 0 & \leftarrow S_1 \end{matrix}$$

The first parity of S_0 is already "computed", so we only need to perform a CNOT between row 4 & row 1:

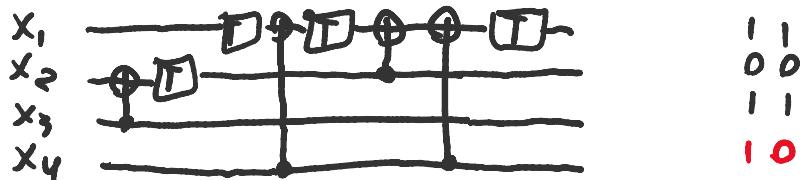
$$\begin{matrix} x_1 & \xrightarrow{\quad} & \square & \square & \square & \square \\ x_2 & \xrightarrow{\text{CNOT}} & \square & \square & \square & \square \\ x_3 & \xrightarrow{\quad} & \square & \square & \square & \square \\ x_4 & \xrightarrow{\quad} & \square & \square & \square & \square \end{matrix} \quad \begin{matrix} 1 & 1 & 1 & 1 & 1 & 1 & - \\ 0 & 0 & 1 & -1 & 1 & -1 & - \\ 0 & 0 & 0 & 1 & 1 & 1 & - \\ 0 & 0 & 1 & 0 & 1 & 1 & - \end{matrix}$$

Example cont.

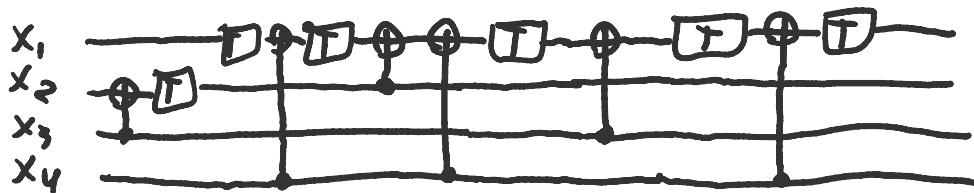
Continuing on with S_1 , we zero out the second row with $CNOT_{2,1}$, then partition on row 3



Next we $CNOT_{4,1}$ and move on to S_1



At this point we perform $CNOT_{3,1}$, and then divide into co-factors S_0 & S_1 , which require 0 & 1 $CNOT_{n \text{ loop}}$

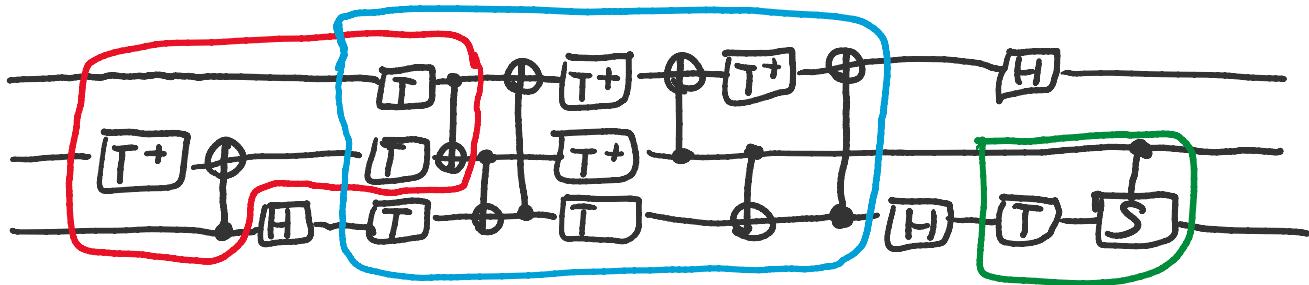


Choice of subcircuits

Even with **optimal** re-synthesis, different partitionings of a circuit may result in different costs.

E.g.

Consider the below circuit. There are **3 maximal CNOT-dihedral sub-circuits**: 1, 2, & 3



Since 1 and 2 overlap, the order of re-synthesis matters — re-synthesizing 1 first may remove the gates in the intersection, but associating those gates with 2 instead could have led to better optimization.

One option is to mark gates in the intersection and try to find a **global optimum** over a set of synthesis problems. We're still just *sweeping the floors on the Titanic* though because the optimization fails to take into account the **whole circuit**. As in classical compilers, the best optimizations are **whole program optimizations** typically using static analysis to make it tractable.

Clifford+T representations

To represent a **whole program** over $\{H, CNOT, T\}$ using phase polynomials, we can note that

$$H: |x\rangle \mapsto \frac{1}{\sqrt{2}} \sum_{x' \in \mathbb{Z}_2} (-1)^{xx'} |x'\rangle$$

$$\text{In particular, } \frac{1}{\sqrt{2}} \sum_{x' \in \mathbb{Z}_2} (-1)^{xx'} |x'\rangle = \frac{|0\rangle + (-1)^x |1\rangle}{\sqrt{2}}$$
$$= |+\rangle \text{ if } x=0, |-\rangle \text{ if } x=1$$

Noting that $(-1)^{xx'} = e^{i(x+x' - (x \otimes x'))}$, we almost have a **phase polynomial representation**, but with one extra variable (x') which is summed over (+ norm. factor)

Prop.

Any circuit C over $\{H, CNOT, R_n\}$ can be written as

$$\textcircled{1} \quad [C]: |\vec{x}\rangle \mapsto \frac{1}{\sqrt{2}^k} \sum_{\vec{x}' \in \mathbb{Z}_2^k} e^{i \pi \sum_m P(\vec{x}, \vec{x}') A(\vec{x}, \vec{x}') + \vec{b}} |A(\vec{x}, \vec{x}') + \vec{b}\rangle$$

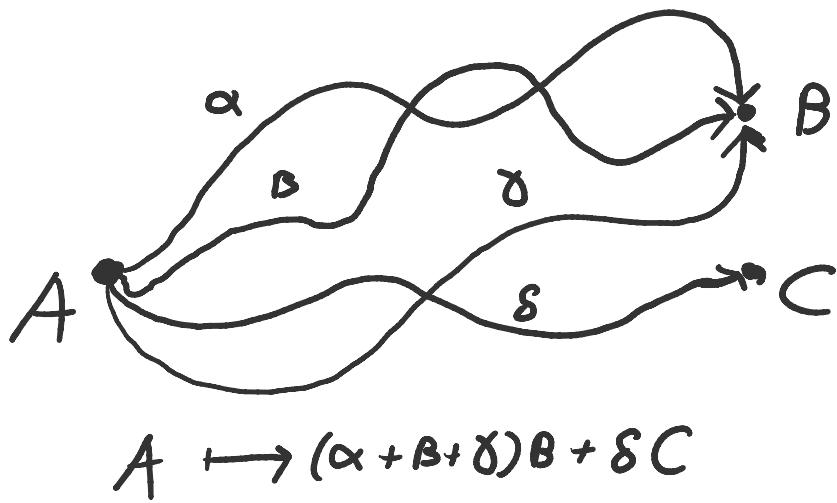
for some phase polynomial P and $A \in M_{n \times n+k}(\mathbb{Z}_2)$

(Sum-over-paths)

The representation $\textcircled{1}$ is known as the (circuit) **sum-over-paths**. The summed variables x_i' are called **path variables** and can be thought of as identifying the branch taken (in superposition) at some **Hadamard gate**. The sum-over-paths corresponds to Feynman's **path integral formulation** of quantum mechanics.

The Feynman path integral

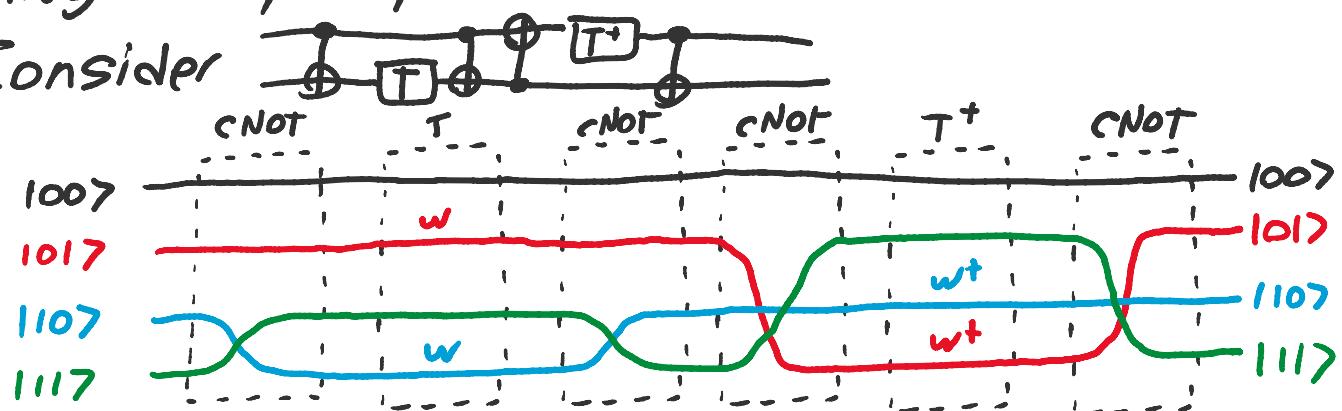
In Feynman's path integral formulation of QM, the evolution of a particle or system is viewed as the sum/integral over the different (classical) paths/evolutions it takes in superposition.



E.g.

We can analyze the evolution of circuits in the path integral style by tracking the evolution of an input basis state

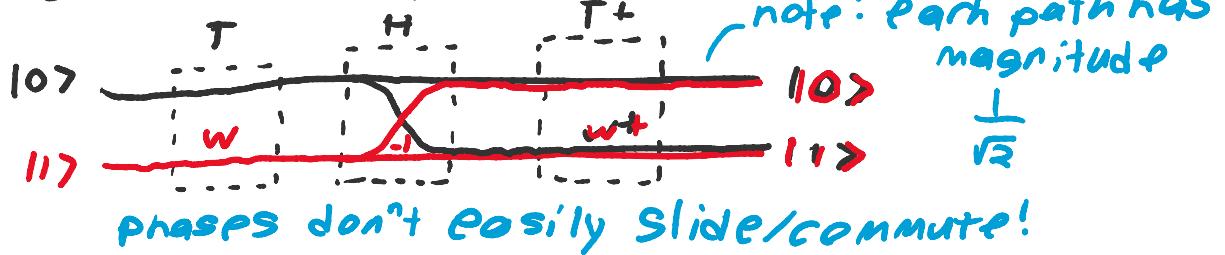
Consider



Each path ends in the state it started, and the red (10) and blue (10) paths both pick up a phase of $w \cdot w^* = 1$, so the overall effect of the circuit is nothing.

E.g.

Hadamard gates correspond to branching paths



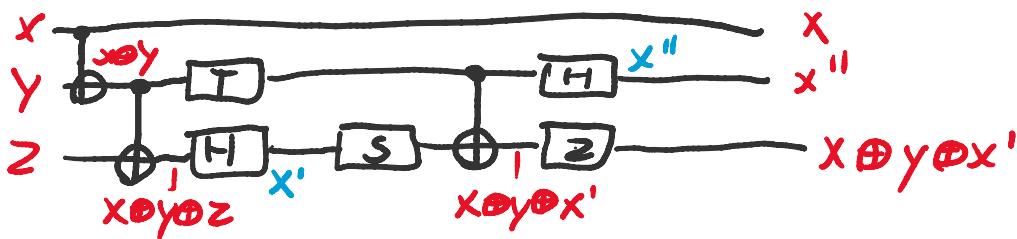
Annotated circuits

As with phase polynomial representations, the sum-over-paths can be determined by annotating

E.g.

Annotating ① basis state transformations, and ② branches,

the sum-over-paths representation of the following circuit can be read out by collecting the phase terms and summing over all branches:



$$\text{SOP form: } |xyz\rangle \mapsto \frac{1}{2} \sum_{x', x''} w^{P(x,y,z,x',x'')} |xx''(x \oplus y \oplus x')\rangle$$

$$\begin{aligned} P(x,y,z,x',x'') &= x \oplus y + 4x'(x \oplus y \oplus z) + 2x' + 4(x \oplus y \oplus x') + 4|x''(x \oplus y) \\ &= x \oplus y + 2x' + 2(x \oplus y \oplus z) + 6(x' \oplus x \oplus y \oplus z) + 2x'' \\ &\quad 4x + 4y + 4x' + 2x'' + 2(x \oplus y) + 6(x'' \oplus x \oplus y) \\ &= x \oplus y + 2(x \oplus y \oplus z) + 6(x' \oplus x \oplus y \oplus z) + 4(x + 4y) \\ &\quad + 2x'' + 2(x \oplus y) + 6(x'' \oplus x \oplus y) \end{aligned}$$

This is tedious! Computers are much better

Prop.

The sum-over-paths representation of a Clifford+T circuit C can be computed in $\text{poly}(|C|)$ time & space

Sum-over-paths re-synthesis

Synthesizing a circuit from a sum-over-paths is generically hard (at least coNP-hard)

Ex.

Consider a sum-over-paths with k distinct variables $\{x_i\}$ and phases only of the form $(-1)^{x_i x_j} = (-1)^{x_i + x_j - (x_i \oplus x_j)}$. We can draw the phase polynomial as a graph where a phase of $(-1)^{x_i x_j}$ means an edge between x_i & x_j .

$$\begin{array}{c} x_1 \xrightarrow{x_4} \\ / \quad \diagup \\ x_2 \quad x_3 \end{array} \rightarrow (-1)^{x_1 x_2 + x_1 x_3 + x_1 x_4 + x_2 x_4}$$

We can implement phases by either

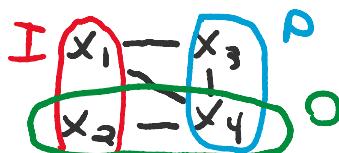
$$CZ: |x_i\rangle |x_j\rangle \mapsto (-1)^{x_i x_j} |x_i\rangle |x_j\rangle, \text{ or}$$

$$H: |x_i\rangle \mapsto \frac{1}{\sqrt{2}} \sum_{x_j} (-1)^{x_i x_j} |x_j\rangle$$

Since H "consumes" an x_i , given subsets (I, P, O) of $\{x_i\}$ corr. to inputs, path variables, and outputs, synthesizing a circuit over $\{H, CZ\} \equiv \{H, CZ, S\}$ amounts to finding an assignment $V(x_j) = x_i$ for all $x_j \in P$ s.t.

1. $V(x_j) = x_i \Rightarrow (x_i, x_j) \in E$
2. $V(x_j) = x_i = V(x_k) \Rightarrow x_j = x_k$
3. $V(\{x_i\}) \cap O = \emptyset$
4. $V(x_j) = x_i \Rightarrow x_i < x_j$ is a partial order

These constraints are unsatisfiable for the graph



But it can be satisfied by applying a linear transform first
 $x_q \rightarrow x_1 \oplus x_2$, i.e. $x_1 \xrightarrow{x_1 \oplus x_2} x_1 \oplus x_2$

Where do we go from here?

Classical program optimization also runs into inherent problems of tractability (or even uncomputability...). To solve this problem, they use static program analysis to prove properties which allow a compiler to safely perform an optimization.

Our final (lecture) topic will be the phase folding optimization which uses the sum-over-paths model to prove two phase gates can be merged into one.