

**EN 001203 Artificial Neural Networks**

**E002: Numerical Programming and Optimization**

**Faculty of Engineering, Khon Kaen University**

Submission: <https://autolab.en.kku.ac.th>

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- \* Submit an answer to a question with a file with `txt` extension. E.g., an answer for Q1 should be submitted in a text file “Q1.txt”
  - \* Submit a program to a (programming) problem with a file with a proper extension. E.g., a python program for P2 should be named “P2.py”
  - \* All answers and programs must be packaged together in a tar file.
  - \* Each question or problem is worth 60 points. There are 5 problems, thus 300 points are counted as a total score for this exercise.
  - \* Floating-point numbers are graded using tolerance 0.001.
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“If we are facing in the right direction,  
all we have to do is keep on walking.”

-- Joseph Goldstein

**P1. Dot product.** Write function `sop` with interface `sop(w, u)`, where `w` and `u` are supposed to be Numpy arrays. The function returns a sum of products of both arguments. That is, the `sop` function returns  $\sum_{i=0}^d w_i \cdot x_i$ , when  $w_0, \dots, w_d$  are elements of `w` and  $x_0, \dots, x_d$  are elements of `x`.

[Hint: it is easier with Numpy dot.]

Given the function is called as follows

```
import numpy as np
from P1 import sop

if __name__ == "__main__":

    x = np.array([1, 2, 3, 4])
    w = np.array([-1, 1, 0, 2])
    print("w dot x =", sop(w, x))
```

output example will look like:

```
w dot x = 9
```

You may use a starter code below.

Starter code:

```
"""
P1. Online averaging.
Student name: Tenaciti Kurios
"""

import numpy as np

def sop(w, x):
    # WRITE YOUR CODE HERE
    return 0

if __name__ == "__main__":
    # Test your code sufficiently!
    d = np.array([1, 2, 3, 4])
    v = np.array([-1, 0, 1, 2])

    print("dot product =", sop(d, v))
```

**P2. Loss and gradient.** Given a loss function  $g(u) = \frac{1}{1+\exp(-8u)} - \frac{1}{1+\exp(-u)}$ , write a loss function with interface `loss(u)` and its gradient function with interface `grad(u)`.

[Hint: you need a chain rule of derivative; recall the quotient rule of derivative.]

Given the functions are called as follows

```
import numpy as np

from P2 import loss, grad

if __name__ == "__main__":
    us = np.linspace(-1, 0, num=5)
    print(us)
    print(loss(us))
    print(grad(us))
```

output example may look like:

```
[ -1.    -0.75 -0.5  -0.25  0.   ]
[ -0.26860607 -0.31834868 -0.35955446 -0.31862058  0.    ]
[ -0.19393003 -0.19816292 -0.09370206  0.5938146  1.75  ]
```

**P3. Minimization with Gradient Descend.** Given the problem formulation:

$$\min_u g(u)$$

where  $g(u) = \frac{1}{1+\exp(-8u)} - \frac{1}{1+\exp(-u)}$ , write a function with interface `gmin(u0, lr, N)` to find the minimizer  $u^*$  using gradient descend algorithm. The function takes in values of an initial value of the control variable as `u0`, step size `lr` and a number of iterations `N`. The function returns a value of the minimizer found in the process.

[Hint: test it out, check the optimizing progress, play around and test it with various sets of arguments; students are encouraged to use visualization to gain understanding as much as possible.]

Given the functions are called as follows

```
from P3 import gmin

if __name__ == "__main__":
    ux = gmin(u0=0, lr=0.2, N=10)
    print(ux)
```

output example may look like:

```
-0.430047280075
```

**P4. Maximization with Gradient Descend.** Given the problem formulation:

$$\max_u g(u)$$

where  $g(u) = 2 + 3u - u^2$ , write a function with interface `gmax(u0, lr, N)` to find the maximizer  $u^*$  using gradient descend algorithm. The function takes in values of an initial value of the control variable as `u0`, step size `lr` and a number of iterations `N`. The function returns a value of the maximizer found in the process.

[Hint: it is MAXIMIZATION! students are encouraged to use visualization to gain understanding as much as possible.]

Given the functions are called as follows

```
from P4 import gmax

if __name__ == "__main__":
    ux = gmax(u0=0, lr=0.2, N=10)
    print(ux)
```

output example may look like:

```
1.4909300736
```

**P5. Two-Dimensional Problem with Gradient Descend.** Given the problem formulation:

$$\min_{\vec{u}} g(\vec{u})$$

where  $\vec{u} = [u_1, u_2]$  and  $g(\vec{u}) = u_1^2 + 1.5u_1u_2 - 16u_1 + 2u_2^2 - 35u_2$ , write a function with interface `g2min(u0, lr, N)` to find the minimizer using gradient descend algorithm. The function takes in values of an initial value of the control variable `u0` as a numpy array of shape (2,1), step size `lr` and a number of iterations `N`. The function returns a value of the minimizer found in the process.

[Hint: always check the progress with losses over iteration steps.]

Given the functions are called as follows

```
import numpy as np
from P5 import g2min

if __name__ == "__main__":
    u0= np.array([[0],[0]])
    ux = g2min(u0, lr=0.1, N=50)
    print("u*=", ux)
```

output example may look like:

```
u*= [[ 2.00301865]
      [ 7.99838447]]
```