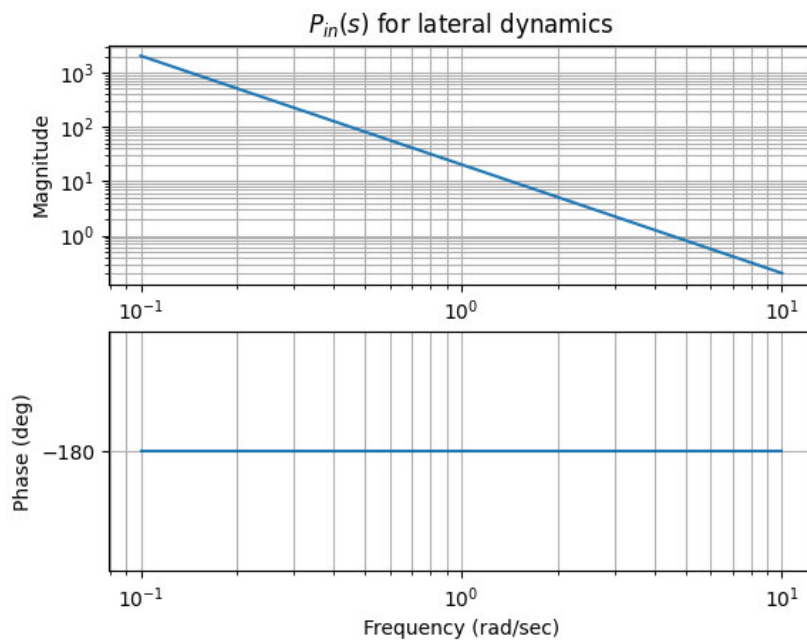
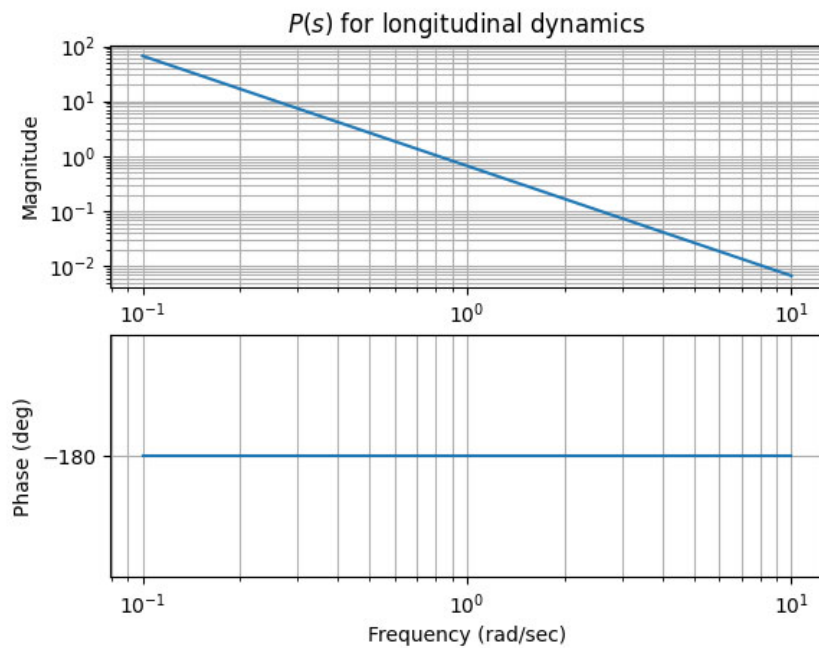
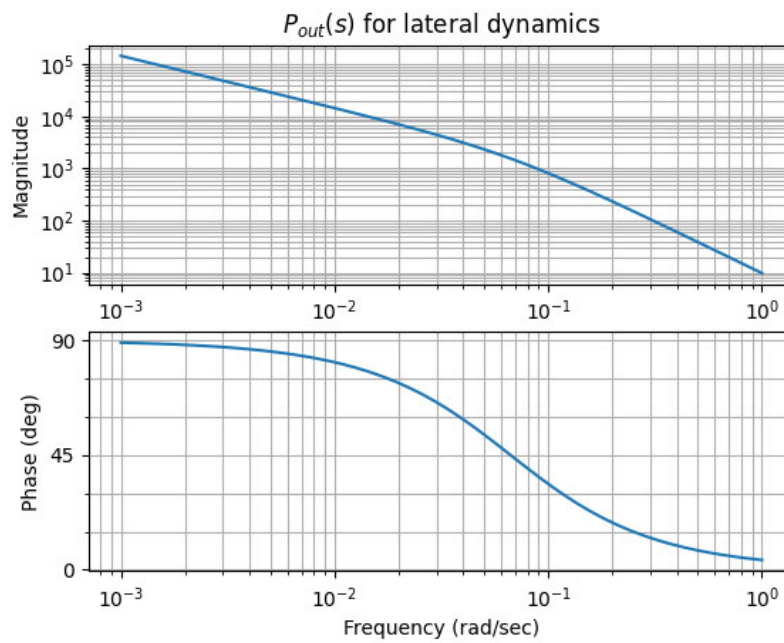


Assignment 11 - F.15 and F.16

F.15

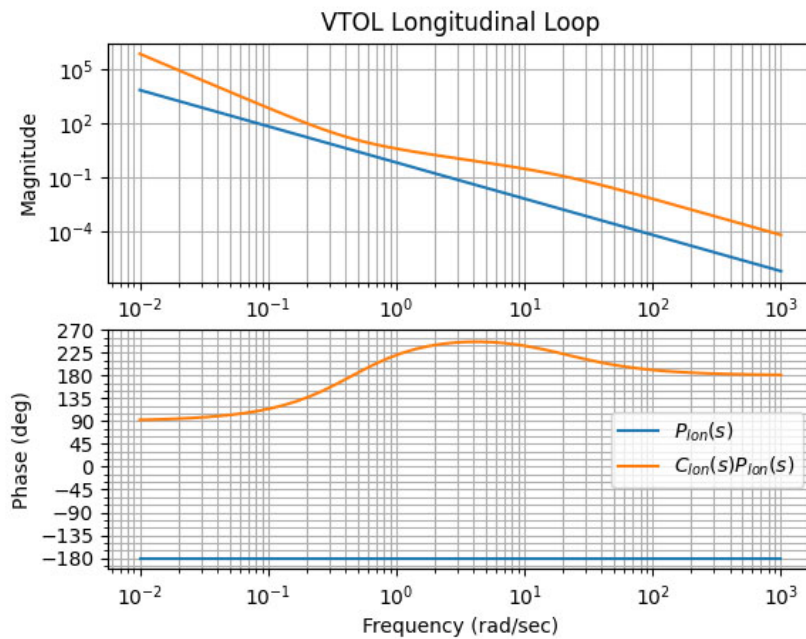
compare plots below to your sketches
(see code on learning suite)





F.16 (see code on learning suite)
using the following gains gives the bode plots
below:

```
sigma: 0.05  
kp_z: -0.147  
ki_z: 0.0  
kd_z: -0.213  
kp_h: 4.218  
ki_z: 1.0  
kd_h: 4.779  
kp_th: 7.099  
kd_th: 1.064
```



a) from code \Rightarrow

$$C_{lon} P_{lon} = \frac{3.327s^2 + 2.845s + 0.667}{s^3(0.05s + 1)}$$

so $l = 3$ \dot{z}

$$e_{ss} = \lim_{s \rightarrow 0} \frac{1}{s^3 + \bar{C}\bar{P}} \cdot s^{3-k}$$

for a parabolic input, $k=2 \Rightarrow$

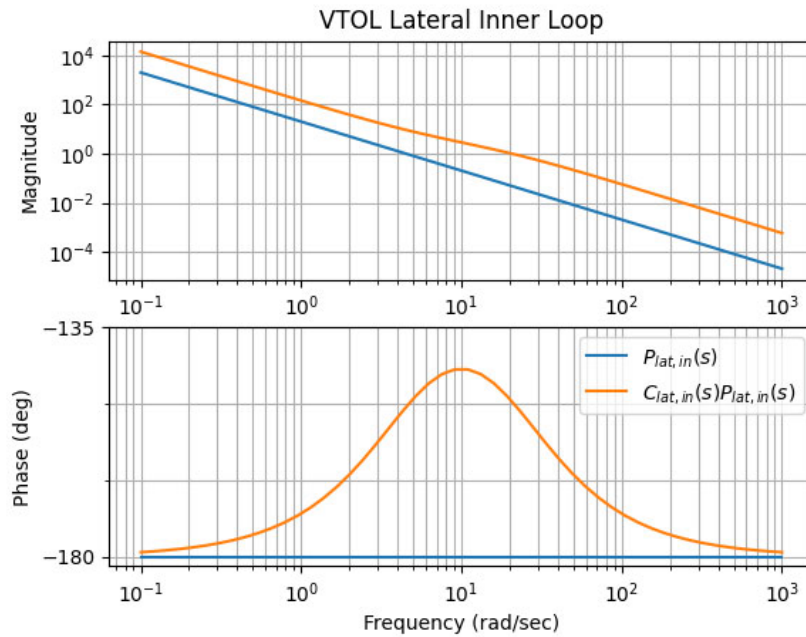
there fore

$$e_{ss} = 0$$

b) % error = $\gamma_n \cdot 100 \Rightarrow$

$$\gamma_n = M_{C_{lon}P_{lon}}(\omega_{no}) = 0.0615 \Rightarrow$$

$$\% \text{ error} = 6.15\%$$



c) % of $D_{in} = \gamma_{din} \cdot 100 \Rightarrow$

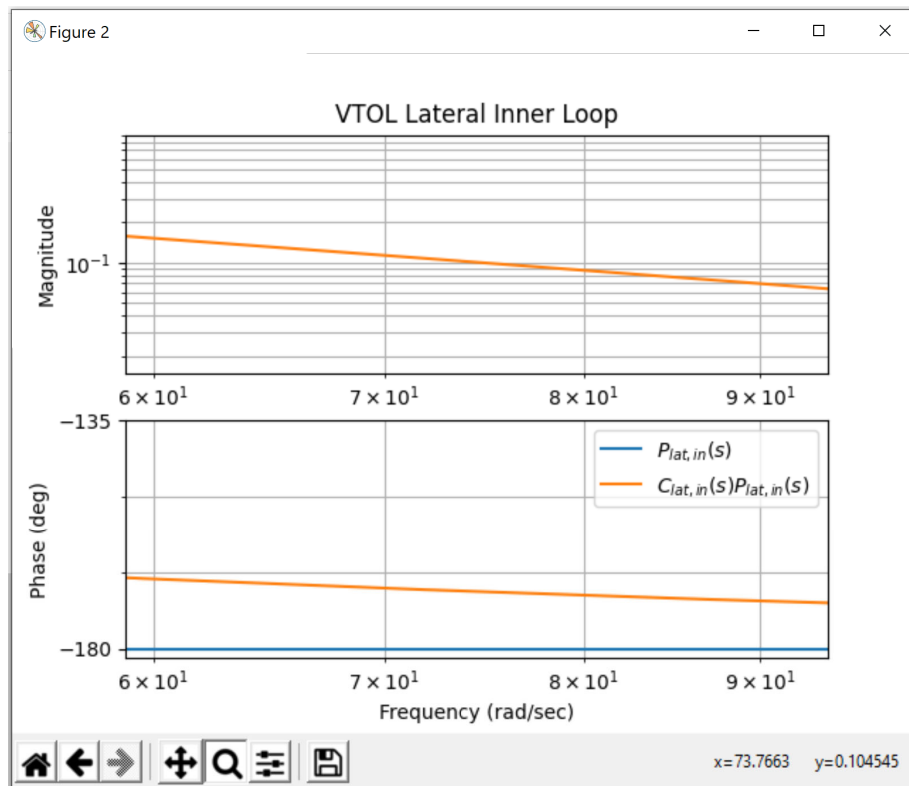
$$\gamma_{din} = \frac{M_{P_{in}}(\omega_{din})}{M_{C_{in}P_{in}}(\omega_{din})} = 0.131 \Rightarrow$$

$\% \text{ error} = 13.1\%$

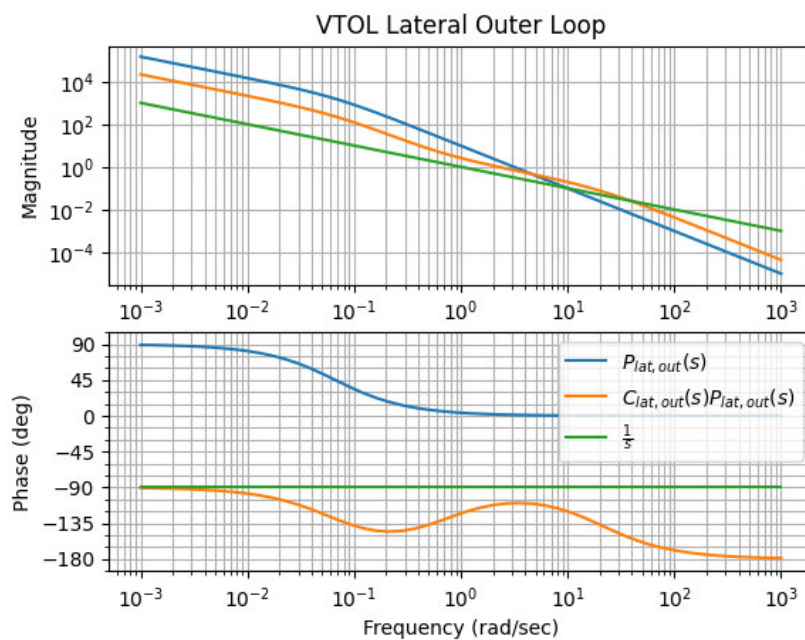
d) assume that $|N| \approx 1 \text{ degree} \Rightarrow$
 $|e| = 0.1 \leq \gamma_n |1 \text{ degree}| \Rightarrow$

(if you chose differently, that's fine)

$$\gamma_n = 0.1, \text{ where does } M_{CP}(\omega_{no}) = \gamma_n = 0.1 ?$$



this plot shows it is at about
 $\omega_{no} = 73 \text{ rad/s}$



$$e) \quad \% \text{ error tracking} = \gamma_r \cdot 100 \Rightarrow$$

$$\gamma_r = \frac{1}{M_{\text{cont}} P_{\text{out}}(\omega_r)} = 0.00824$$

$$\% \text{ error} = 0.824\%$$

$$f) \quad \% \text{ error from } P_{\text{out}} = \gamma_{\text{dout}} \cdot 100 \Rightarrow$$

$$\gamma_{\text{dout}} = \frac{1}{M_{\text{cont}} P_{\text{out}}(\omega_{\text{dout}})} = 0.000467 \Rightarrow$$

$$\% \text{ error} = 0.0467\%$$