D0020E, Projekt i datateknik, Lp2-3, H22

Group 12

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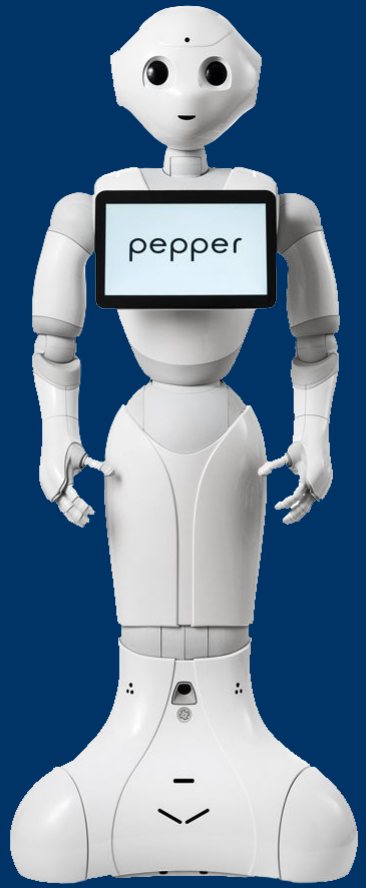
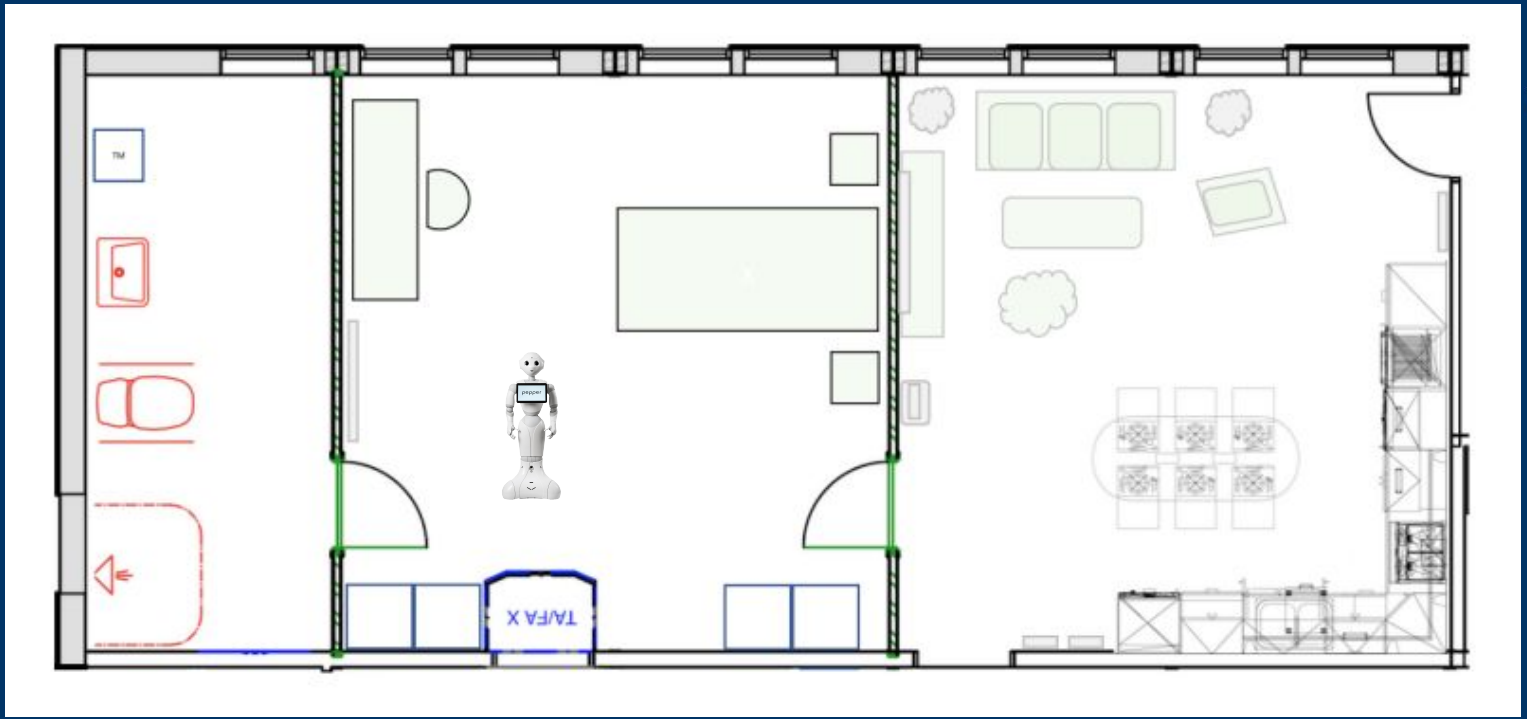


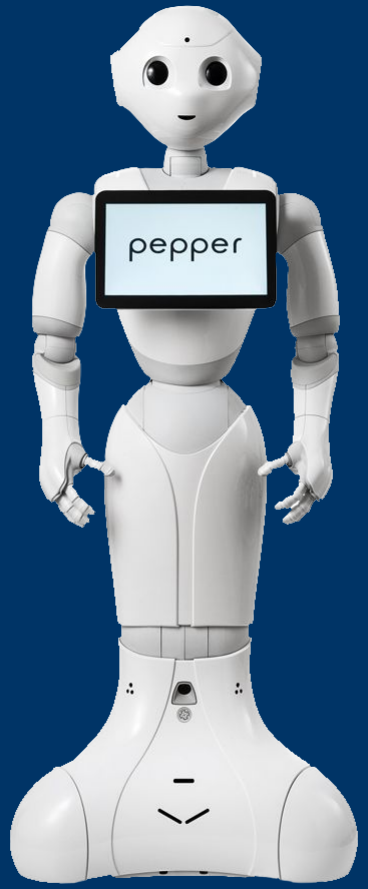
Introduktion

- Pepper
  - Är en sociala “humanoid” robot
  - Optimerad för mänskliga interaktion genom
    - konversation
    - tablet
- Syfte
  - Kombinera Pepper med ett UWB-positioneringssystem med hjälp av Widefind kommunikation
- Målgrupp och användning
  - Vård-och omsorg
    - Större målgrupp Äldreomsorg



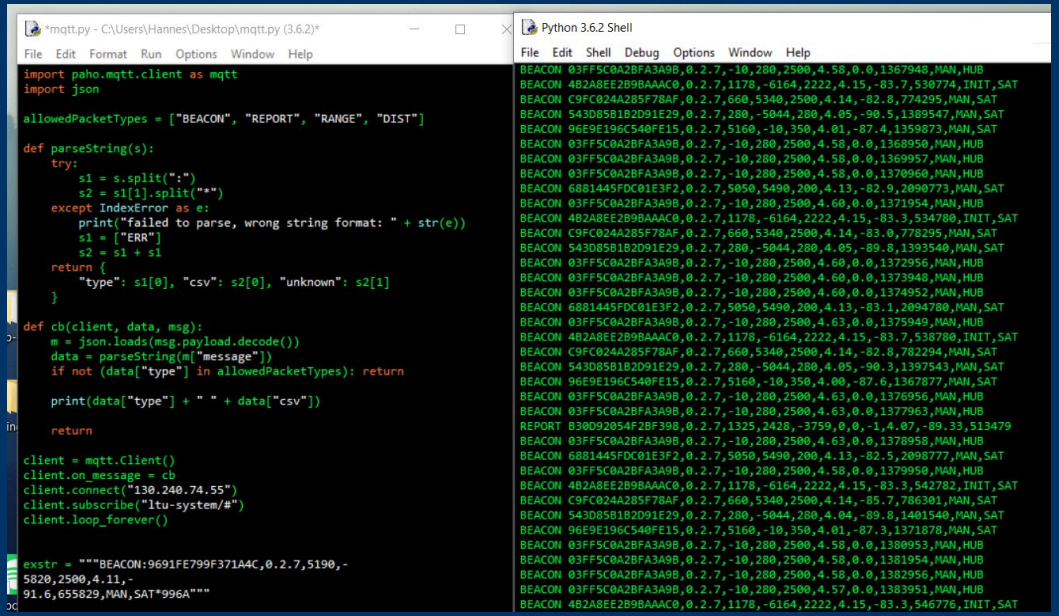
Figur 1: Layout of the the Human Health and Activity Laboratory

Figur 1 tagen från *"Niklas exjobb rapport - Automated Control of a Telepresence Robot using UWB Positioning"*

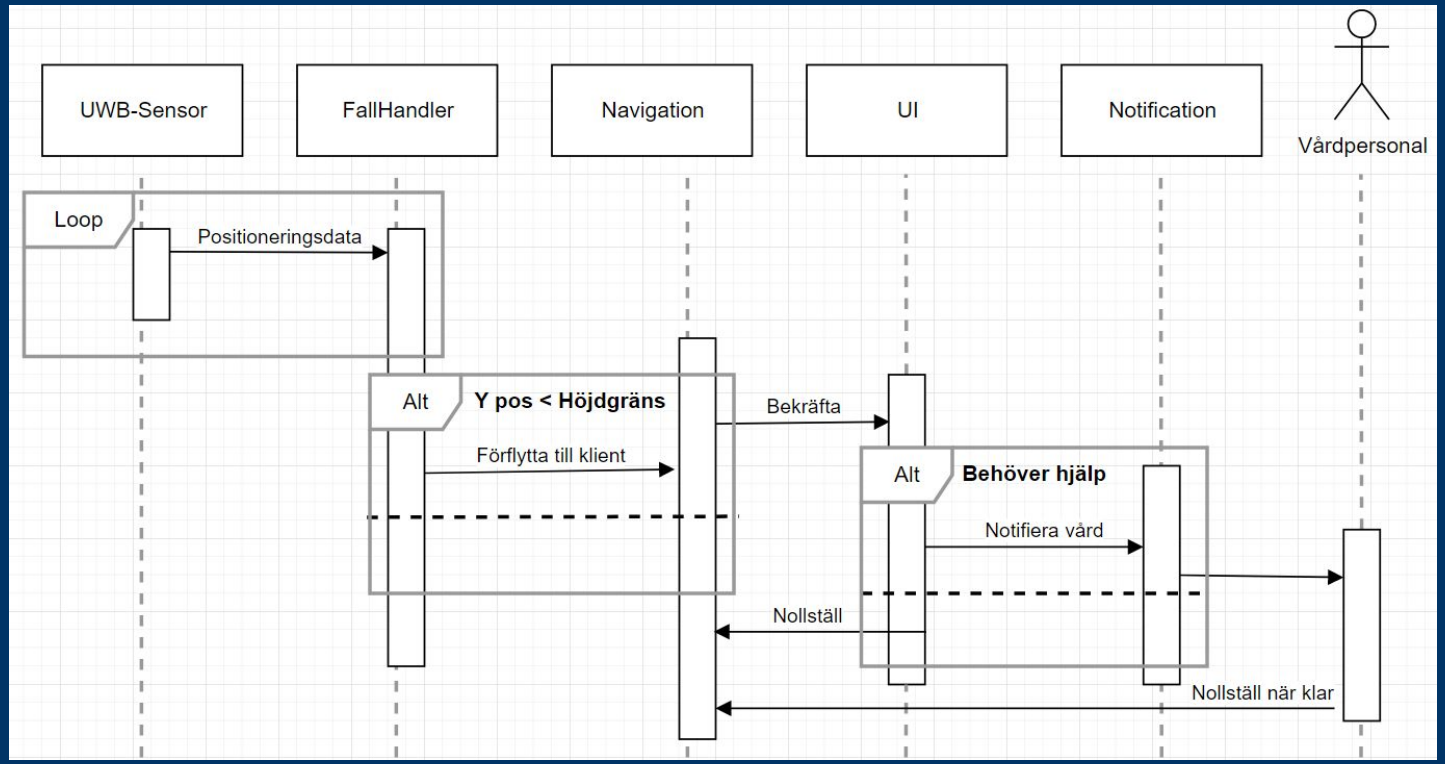


UWB

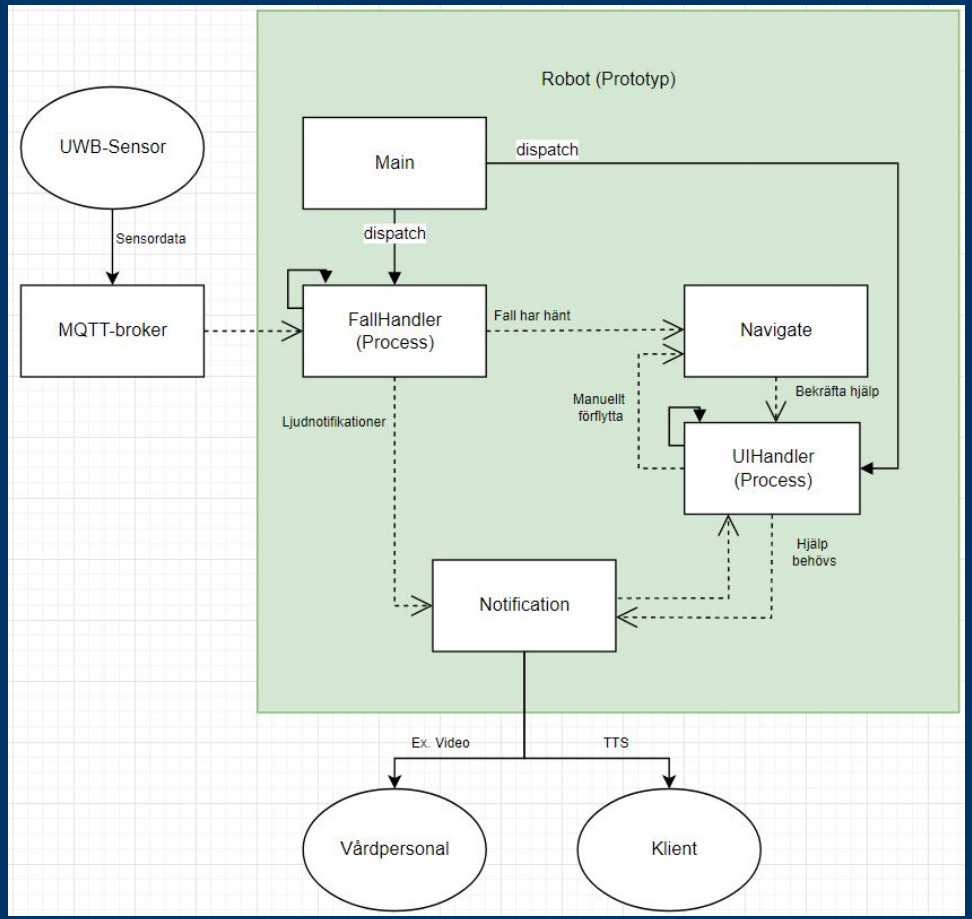
- UWB- Ultra wideband
  - Korta pulser över brett frekvensspektrum (>500MHz)
  - Funkar som ett positionssystem med hög noggrannhet
- Några användningsområden
  - Real-tids positionering
  - Dataöverföring



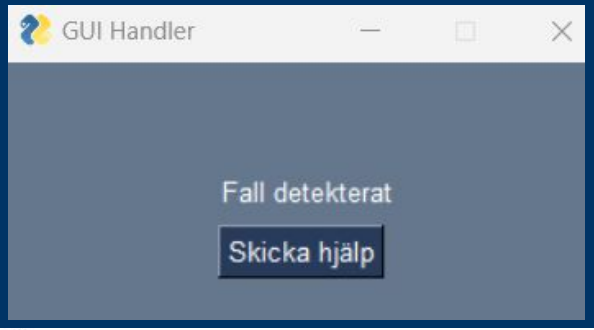
Dynamisk design: sekvens

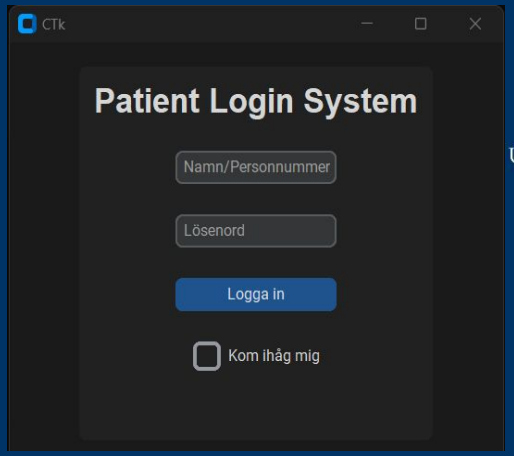


Statisk design: UML



GUI - Prototyp samt koncept design





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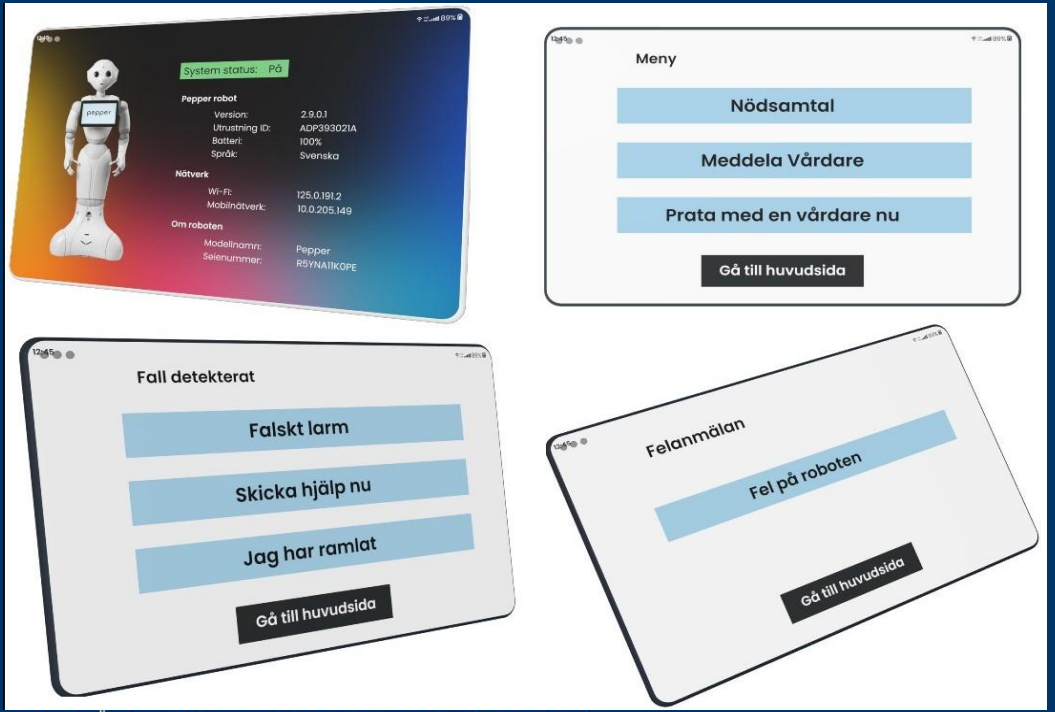

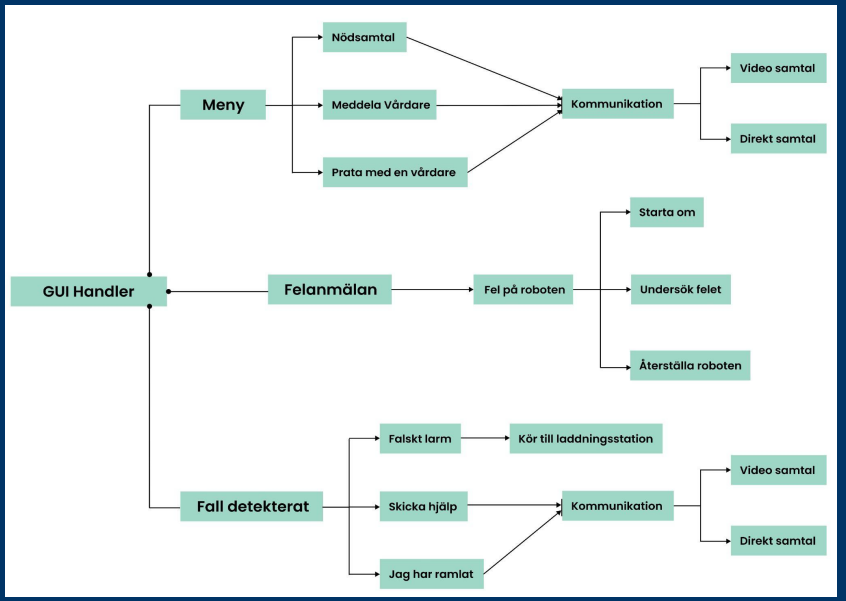

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Kostnader & Övriga frågor

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Källor

- Figur 1 tagen från *“Niklas exjobb rapport - Automated Control of a Telepresence Robot using UWB Positioning”*
- Ultra-wideband https://en.wikipedia.org/wiki/Ultra-wideband
- Pepper officielt sida- https://www.aldebaran.com/en/pepper
- Niklas exjobb rapport - *https://staff.www.ltu.se/~unicorn/h2al/DBv3-WideFind/Niklas_exjobb_rapport_update.pdf*