## Antialiasing

Foley – 3.17 (Chapter 3)

### What is Antialiasing?

#### Aliasing

- Approximating a continuous entity with discrete samples
- Jagging / staircasing effect
- Result of an all-or-nothing approach to scan conversion
  - Each pixel is either colored or left unchanged

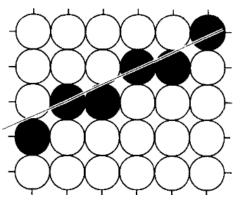


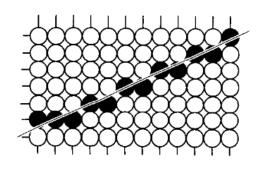
#### Antialiasing

 The application of techniques that reduce or eliminate aliasing

#### Antialiasing Techniques

- Increase Screen Resolution
  - Costly
    - Only diminishes, does not solve
    - Higher memory
    - More time for scan-conversion





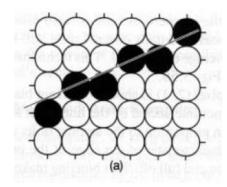
(a) res. W X H

(b) res. 2W X 2H

- Area Sampling
  - Unweighted Area Sampling
  - Weighted Area Sampling

#### Basic Idea:

- Horizontal or vertical line passes through one pixel per row or column
- Lines at other angles go through multiple pixels per row or column



 A line is considered as a rectangle of a desired thickness covering a portion of the grid

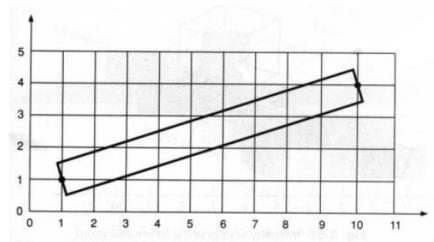


Figure 3.55 Line of nonzero width from point (1,1) to point (10,4).

#### Basic Idea:

 Pixels on the grid overlapped by the rectangle are colored to an appropriate intensity.

General rule: A line contributes to each pixel's intensity an amount proportional to the percentage of the pixel's tile it covers.

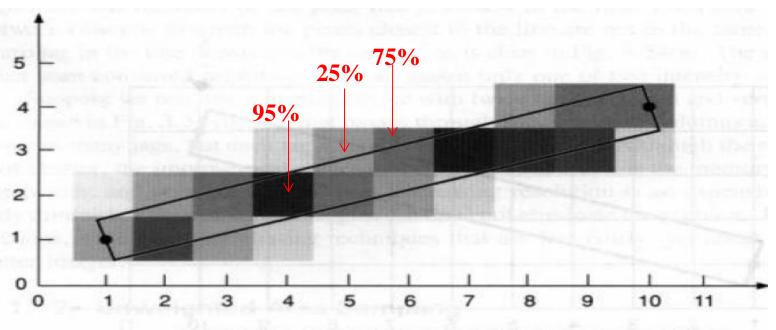
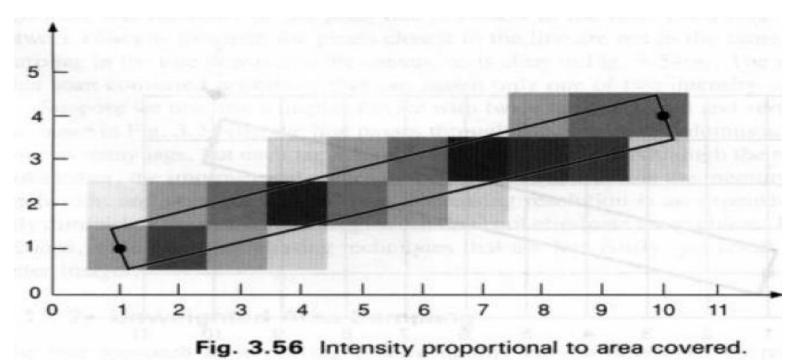


Fig. 3.56 Intensity proportional to area covered.



Intensity of pixel centered at (x,y):

 $I_{x,y} = I_{max}$ . dA. Weight

dA = area overlap for pixel at (x,y)

Weight = 1 for unweighted area sampling

#### Properties:

- 1. The intensity decreases with decreased area overlap.
- 2. Primitive cannot influence the intensity at a pixel if the primitive does not intersect it.
- 3. Equal areas contribute equal intensity, regardless of **distance from pixel center to area**.

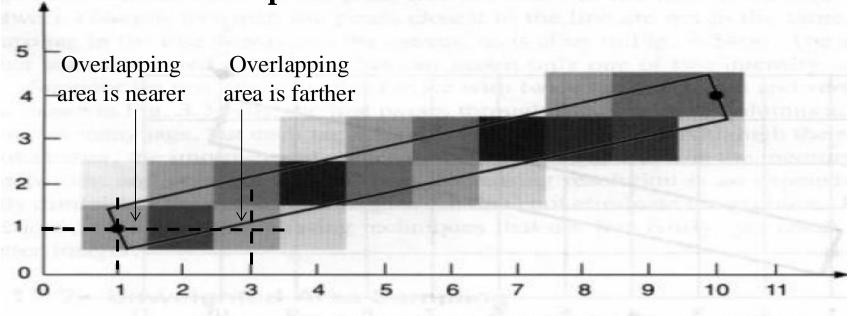


Fig. 3.56 Intensity proportional to area covered.

- Weighting Function
  - Uniform weight for equal overlapping area

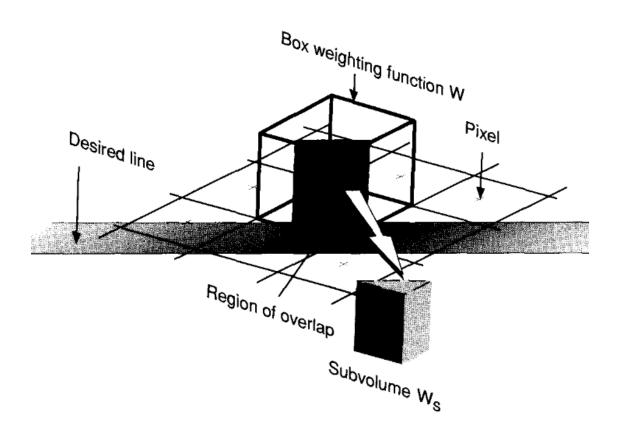


Fig. 3.57 Box filter for square pixel.

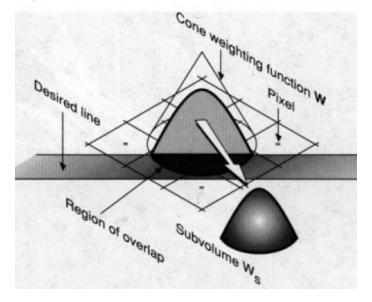
#### Properties:

- First and second properties are unchanged
- Property 3 has been modified as:
  - Equal areas contribute unequally: A small area closer to the pixel center has greater influence than does one at a greater distance.

• Remember, the intesity for unweighted area sampling Intensity of pixel centered at (x,y)

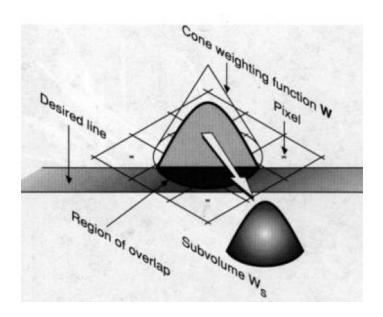
$$I_{x,y} = I_{max}$$
 . dA . Weight

Now, we need to construct a
 weighting function that gives
 less weight to area further
 away from pixel center than
 it does to equal but closer one.

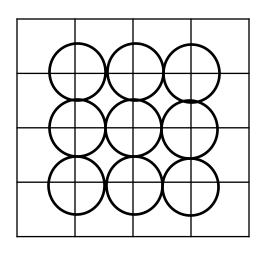


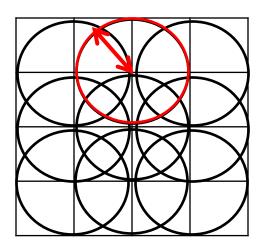
- So weighting must be a decreasing function of distance.
- A circular cone is an example of such a function.

- To obtain such weighting, pixels are considered as circles.
- Each pixel is considered to have a conical volume.
- Intensity at pixel (x,y)
  - $-I_{x,y} = I_{max} \cdot W_s$
  - where W<sub>s</sub> is the sub volume of cone

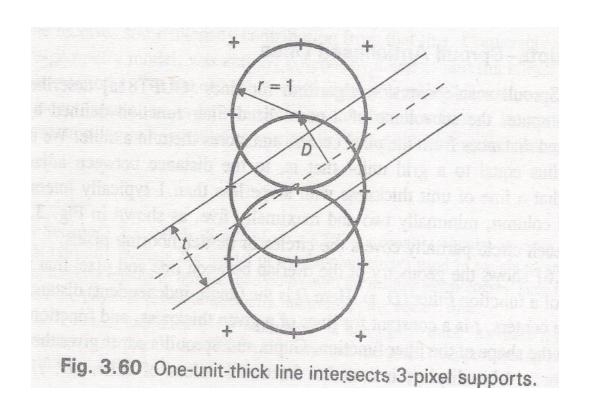


- Each circular pixel has radius of **1 unit** so the pixels will be overlapping
  - Ensures that no area in the grid is left uncovered by the pixels



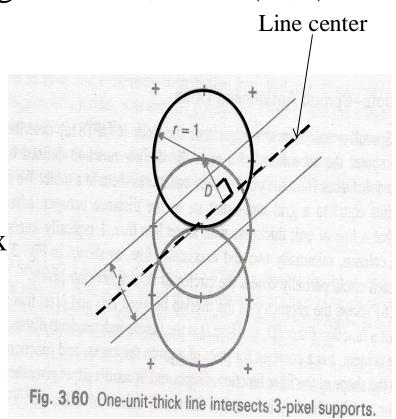


- Each line intersects more than one pixel
  - Usually three pixels



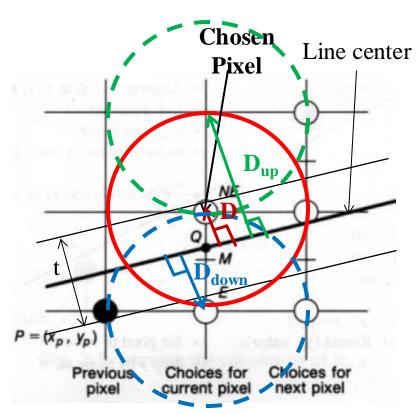
## Gupta-Sproull Weighting Function

- Uses Gupta-Sproull weighting function, Filter(D, t)
  - D = Perpendicular distance between pixel center and the line center
  - t = Constant for a line of given thickness
  - A table takes distance D as index and provides corresponding
     Filter(D, t) value i.e. Intensity.



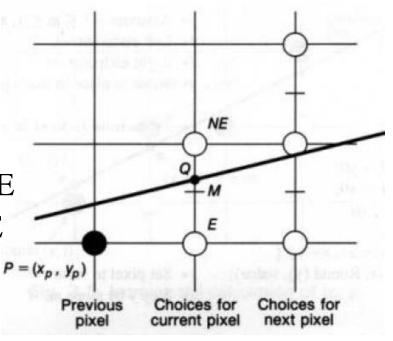
#### Gupta-Sproull Antialiased Lines

- Modifies the midpoint line algorithm for scan converting lines
- The decision variable d is used as before to choose between E and NE
- Then Distance D between the chosen pixel to the line is computed
- Using D, distances between its two vertical neighbors and the line:
   D<sub>up</sub>, and D<sub>down</sub> are computed
- If the slope > 1, distances between its two vertical neighbors and the line:  $D_{right}$ , and  $D_{left}$  are computed
- Then intensity of chosen pixel and its two vertical neighbors are set, on the basis of the distances from these pixels to the line, using Filter(D, t)



### Midpoint Line Algorithm - Recap

- Initially we are at  $P(x_p, y_p)$
- Choose between **NE** and **E**
- Midpoint M is  $(x_p+1, y_p+1/2)$
- M lies on which side of the line?
  - M is on the line  $\rightarrow$  any pixel NE/E
  - M is below the line  $\rightarrow$  choose NE
  - M is above the line  $\rightarrow$  choose E
- Find the equation of the line f(x,y)
  - f(x,y) = ax + by + ca = dy; b = -dx; c = dx.B (B is the y-intercept)
  - Let,  $d = f(M) = f(x_p+1, y_p+1/2)$
  - -d = 0 → M is on the line d > 0 → M is below the line d < 0 → M is above the line



#### Midpoint Line Algorithm - Recap

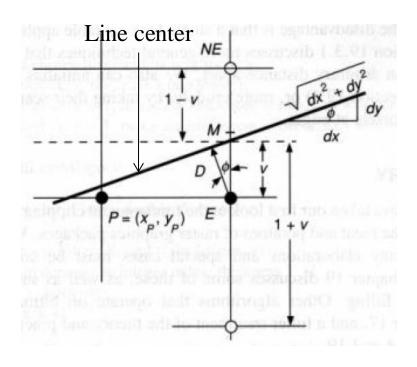
- Initial value of decision variable d<sub>start</sub>
- Start point  $(x_0, y_0)$

• 
$$d_{start} = f(x_o+1, y_o+1/2)$$
  
=  $f(x_o, y_o) + dy - dx/2$   
=  $dy - dx/2$ 

Here the fraction in dx/2 can be avoided by considering f(x,y) = 2(ax+by+c)

## Gupta-Sproull: Calculation of D and v

- The decision variable d is used as before to choose between E and NE
  - D = perpendicular distance between chosen pixel (E) and line center
  - -v = Vertical distance between chosen pixel (E) and line center



#### Calculation of D

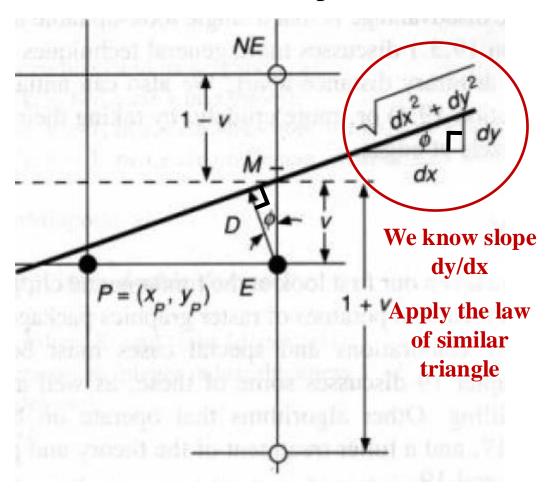
• For E,

- D = perpendicular distance between chosen pixel (E) and the

line center

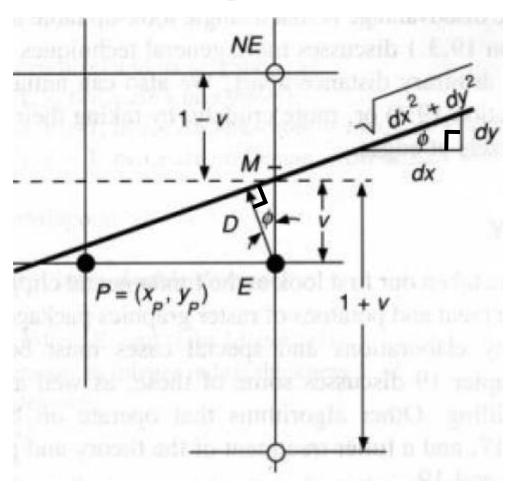
$$D = v \cos \phi$$

$$= \frac{v dx}{\sqrt{dx^2 + dy^2}}$$



#### Calculation of v

- For E,
  - -v = vertical distance between chosen pixel (E) and line center
    - +ve if line center passes above the chosen pixel
    - -ve if line center passes below the chosen pixel
    - consider the absolute value

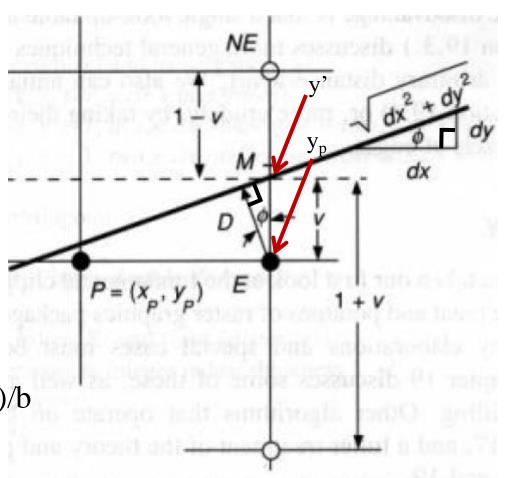


#### Calculation of v

- v = vertical distance between chosen pixel (E) and line center
   vertical distance = subtraction of y of E from y of the intersecting point
- Go from  $P = (x_p, y_p)$ to  $E = (x_p+1, y_p)$
- v = y of line at  $x_p+1$ • y of E at  $x_p+1$ =  $y'-y_p$
- How to get y'?
  - Equation of Line,ax+by+c=0

$$=> y = -(ax+c)/b$$

- So, y'=- $(a(x_p+1)+c)/b$ 



#### Calculation of v

• From  $v = y' - y_p$  we can derive,  $vdx = a(x_p+1) + by_p + c$ For avoiding fraction,

$$2vdx = 2(a(x_p+1) + by_p + c)$$

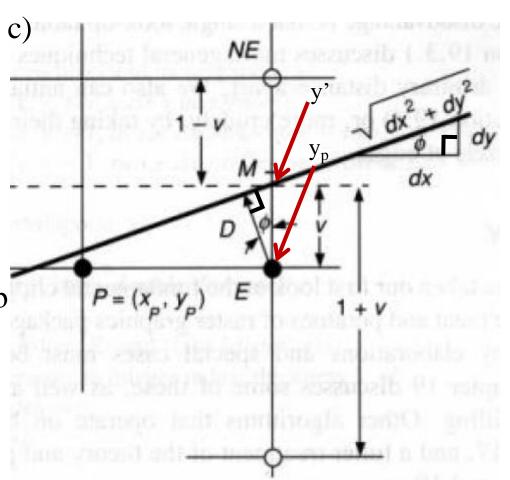
$$2vdx = f(x_p+1,y_p)$$
Present In terms of
$$M = d_{old} = f(x_p+1,y_p+1/2)$$

$$2vdx = 2(a(x_p+1) + b(y_p+1/2) + c) - b$$

$$2vdx = f(x_p+1,y_p+1/2) - b$$

$$= d - b = d + dx$$

$$vdx = \frac{d + dx}{2}$$



# Calculation of D<sub>up</sub>, D<sub>down</sub>

$$vdx = \frac{d + dx}{2}$$

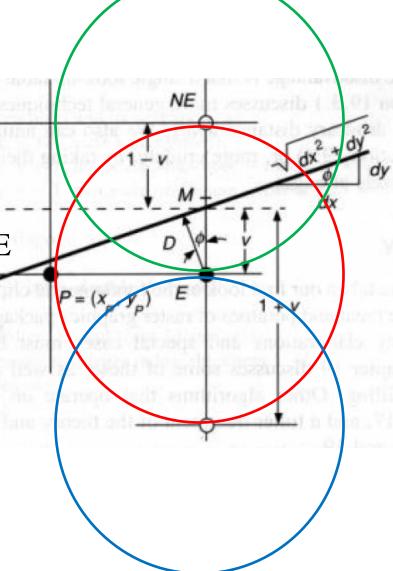
$$D = \frac{vdx}{\sqrt{dx^2 + dy^2}} = \frac{dx + d}{2\sqrt{dx^2 + dy^2}}$$

So we have D, and v for selected pixel E

Now, find D for upper and lower pixels

$$D_{up} = \frac{2(1-v)dx}{2\sqrt{dx^2 + dy^2}} = \frac{2dx - 2vdx}{2\sqrt{dx^2 + dy^2}}$$

$$D_{down} = \frac{2(1+v)dx}{2\sqrt{dx^2 + dy^2}} = \frac{2dx + 2vdx}{2\sqrt{dx^2 + dy^2}}$$



#### Calculation of D and v

• For NE,  

$$2vdx = f(x_p+1,y_p+1)$$

$$= 2(a(x_p+1) + b(y_p+1) + c)$$

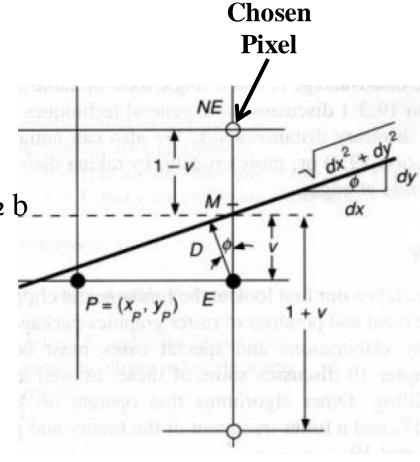
$$vdx = a(x_p+1) + b(y_p+1) + c$$

$$= (a(x_p+1) + b(y_p+1/2) + c) + \frac{1}{2}b$$

$$= f(x_p+1,y_p+1/2)/2 + \frac{1}{2}b$$

$$= d/2 + b/2 = (d+b)/2$$

$$D = \frac{vdx}{\sqrt{dx^2 + dy^2}} = \frac{d - dx}{2\sqrt{dx^2 + dy^2}}$$



Also find the values of D for The pixel above NE and The pixel below NE

#### Gupta-Sproull Algorithm

- Modification of Midpoint line algorithm
- Pseudocode: Figure 3.62 of textbook if d < 0 then begin {Choose *E*} two v dx := d + dx; d := d + incrE;x := x + 1end else {Choose NE} begin two v dx := d - dx; d := d + incrNE: x := x + 1;y := y + 1end; IntensifyPixel (x, y, two v dx \* invDenom);IntensifyPixel  $(x, y + 1, two_dx_invDenom - two_v_dx * invDenom);$ IntensifyPixel  $(x, y - 1, two_dx_invDenom + two_v_dx * invDenom)$

Thank you ©