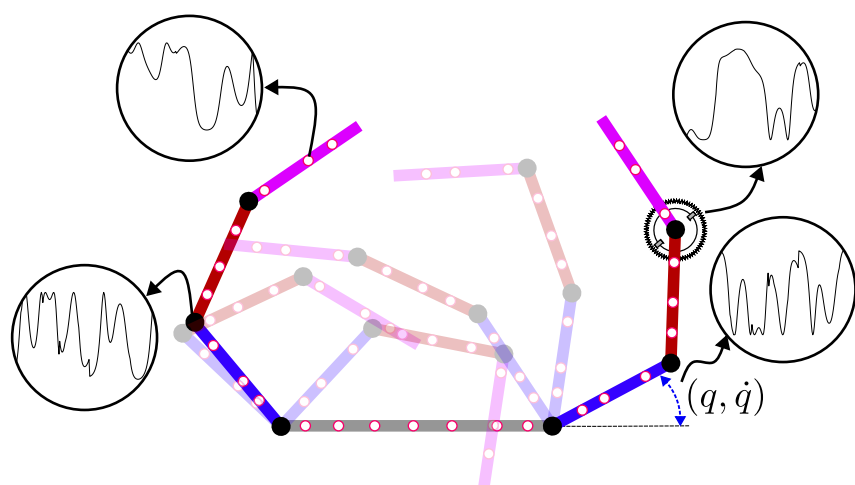
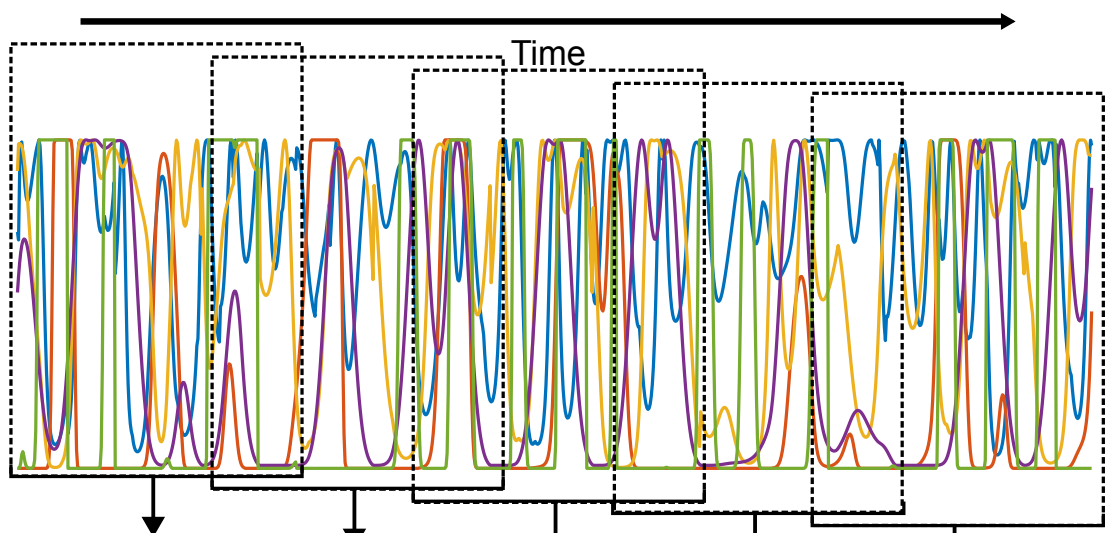


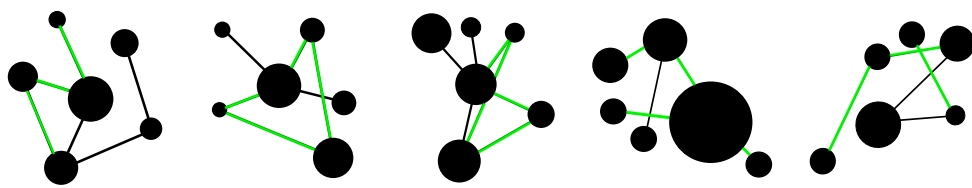
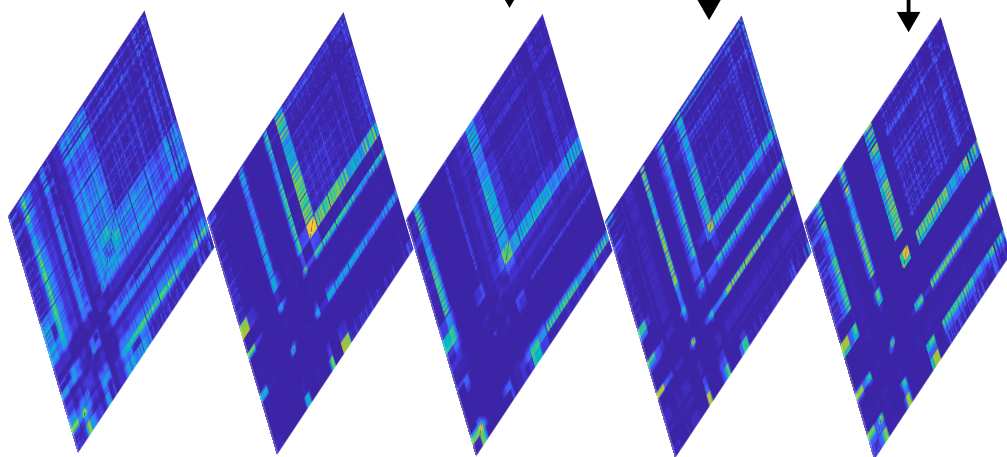
Robot
performing
motor babbling



Somatosensory
signals
time series



Instantaneous
mutual information
matrices



Different relationships
at different times