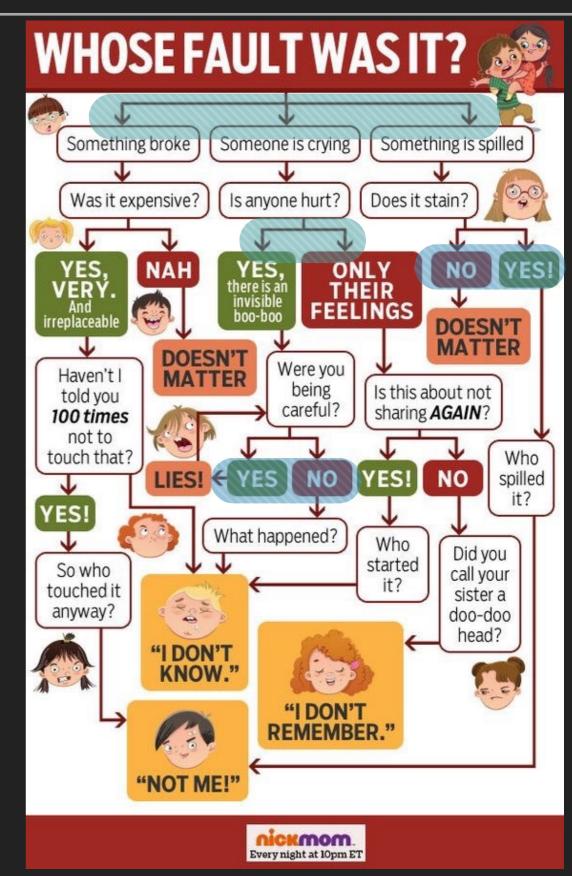
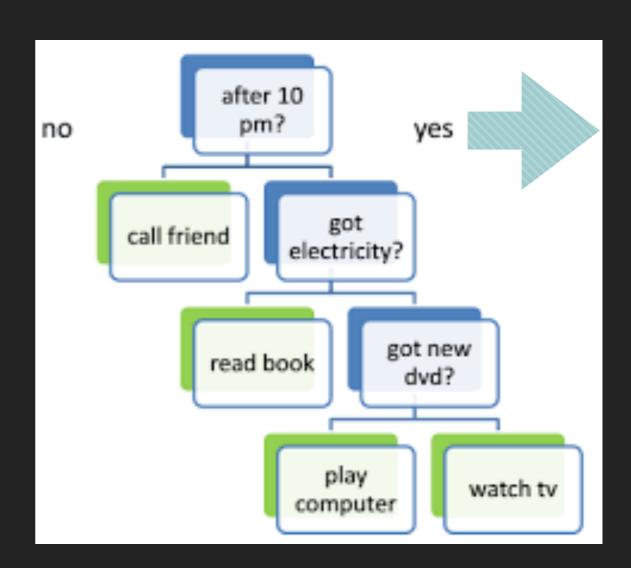
Pre-defined paths



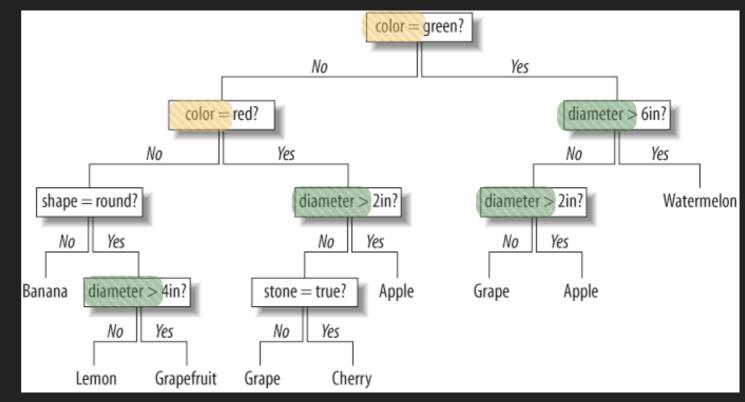
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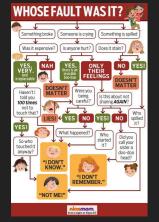
- Pre-defined paths
- Algorithms

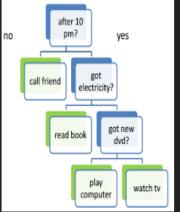




- Pre-defined paths
- Algorithms
- Identification

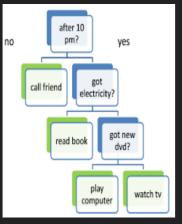


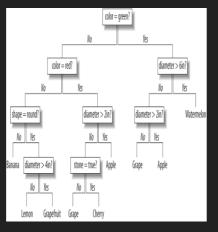


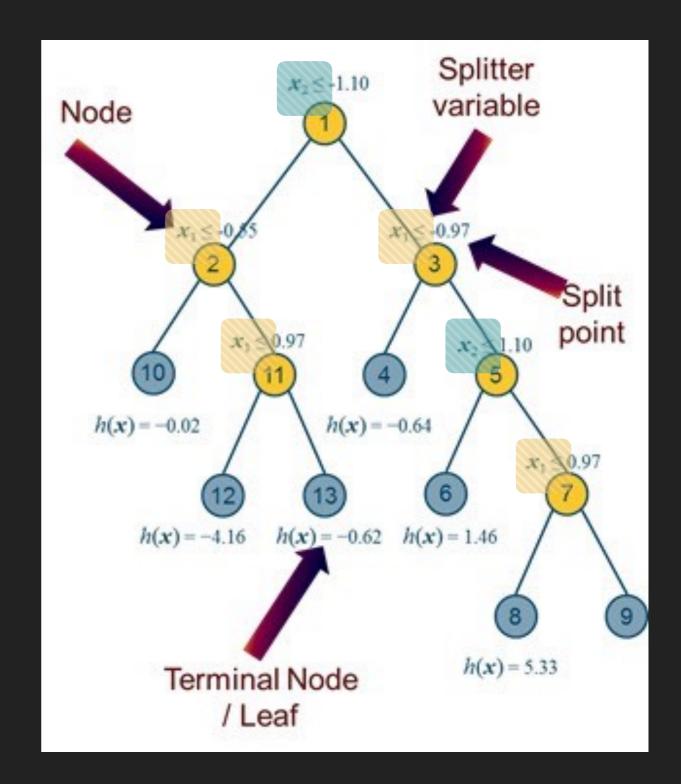


- Pre-defined paths
- Algorithms
- Identification
- Modelling









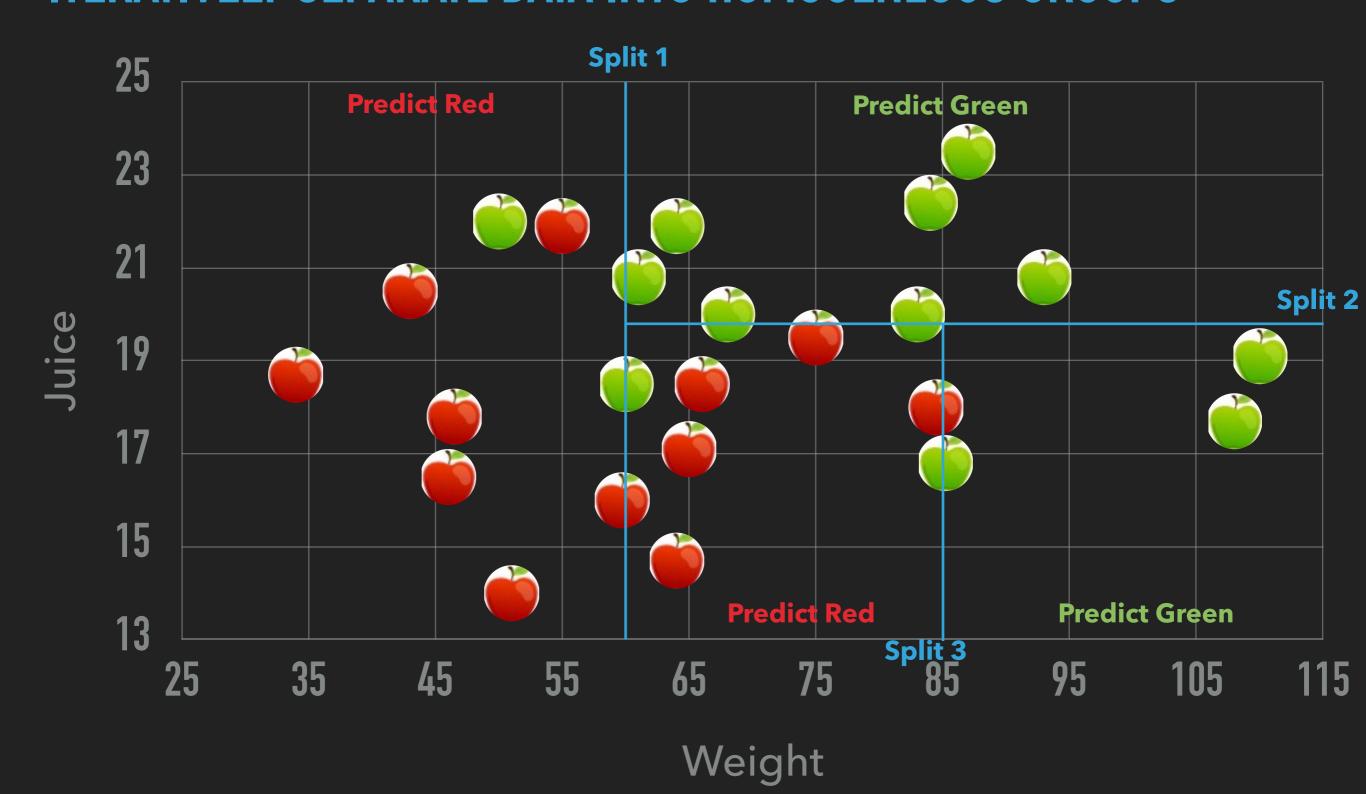
#### **BUILDING DECISION TREES**

- The idea is to: Iteratively separate data into homogeneous groups
  - Split data by category or range, one feature at a time
  - Into groups as pure as possible
  - repeating the process until a certain stop condition is reached

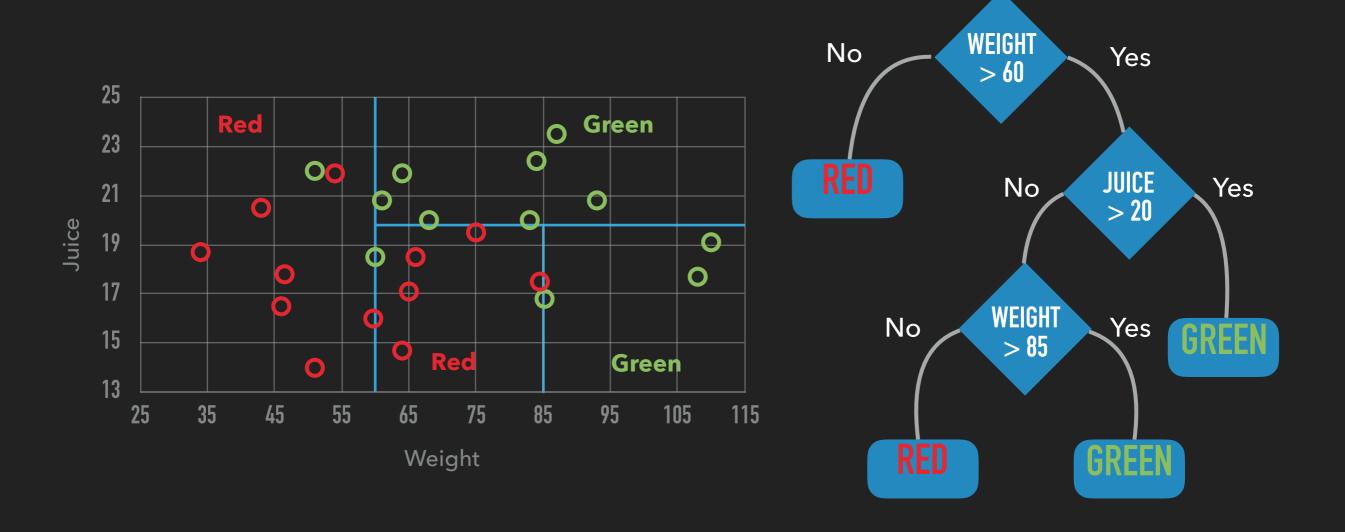




### ITERATIVELY SEPARATE DATA INTO HOMOGENEOUS GROUPS



## MAPPING THE DECISION TREE



#### **GREEDY DECISION TREE LEARNING**

- 1. Start with an **empty** tree
- Select a <u>feature</u> to split the data (Look for the feature that gives the <u>smallest classification</u> <u>error</u>)
- 3. For **each split** of the tree
  - If reached <u>stop condition</u> (purity, # elements, depth) then make predictions
  - 2. Otherwise go to 2. and continue recursively on this **split**