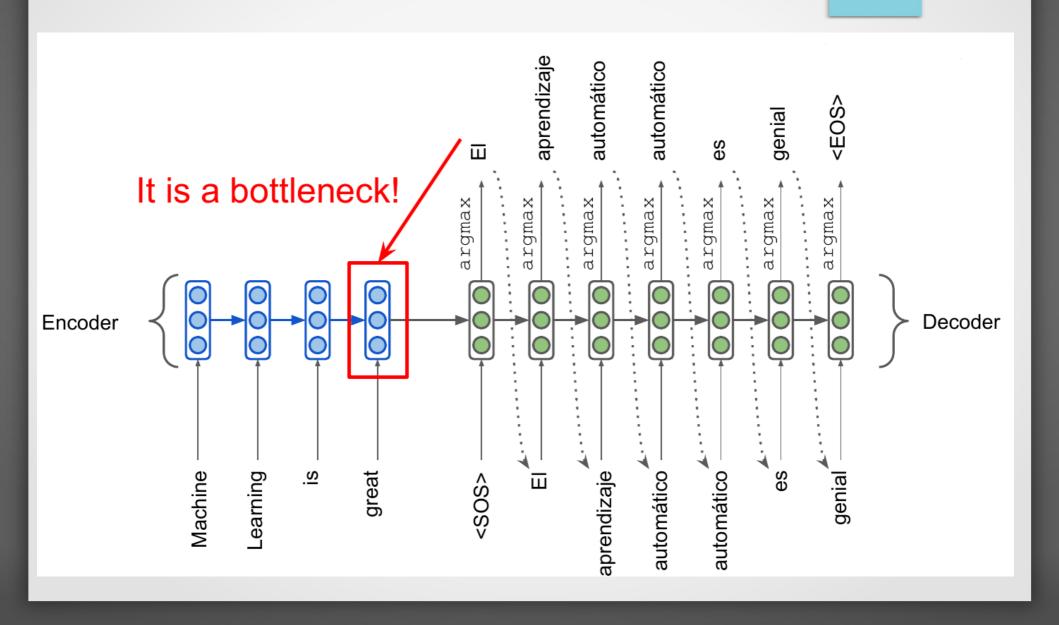
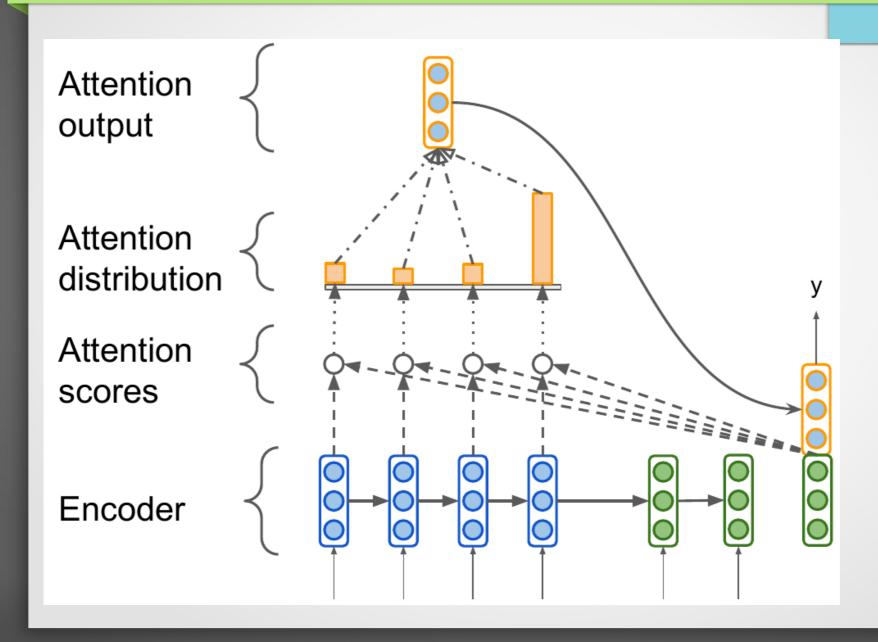
Модель Transformer и механизм внимания Self-Attention

Евгений Борисов

SEQ2SEQ NMT

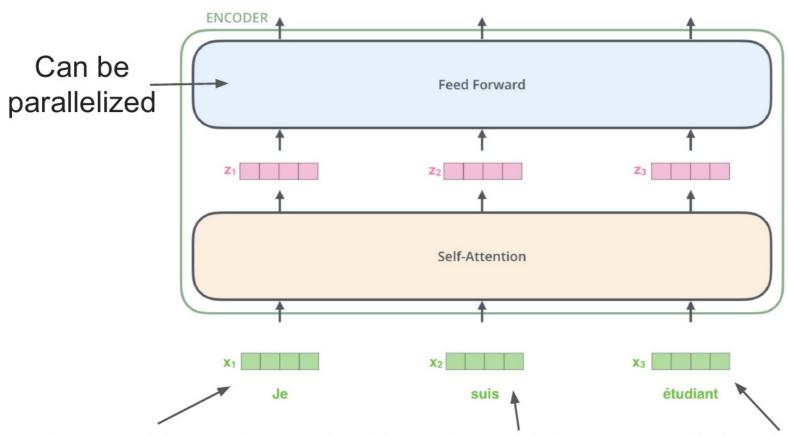


SEQ2SEQ NMT with ATTENTION



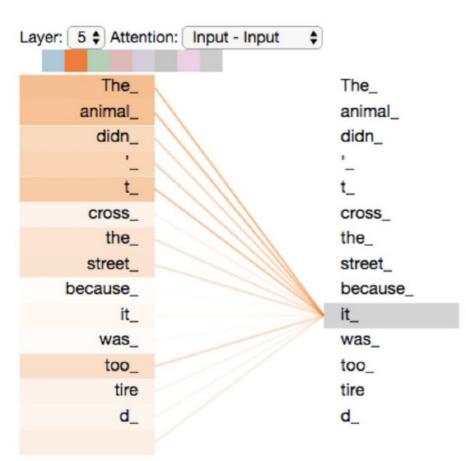
The Transformer OUTPUT am a student **ENCODERS DECODERS** étudiant INPUT

The Encoder Side



the word in each position flows through its own path in the encoder 18

Self-Attention at a High Level



Self-Attention

query - откуда смотрим (из какого слова)

key - куда смотрим (на какое слово)

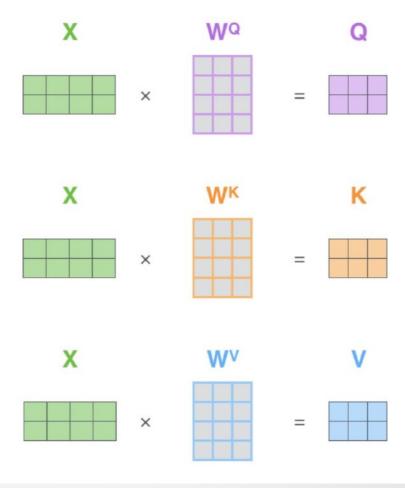
value - смысл (условно) слова

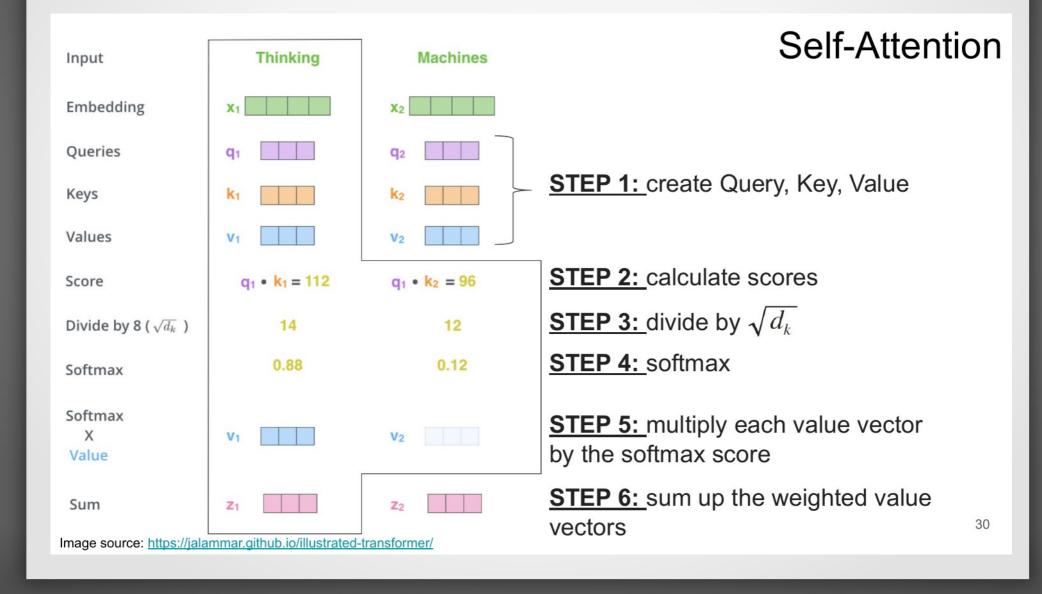
Self-Attention: detailed explanation **Thinking Machines** Input **Embedding** WQ Queries WK Keys W٧ Values 24 Image source: https://jalammar.github.io/illustrated-transformer/

Self-Attention: Matrix Calculation

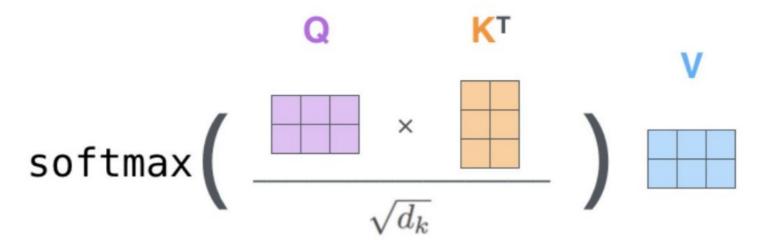
Pack embeddings into matrix **X**

Multiply **X** by weight matrices we've trained (**Wk**, **Wq**, **Wv**)



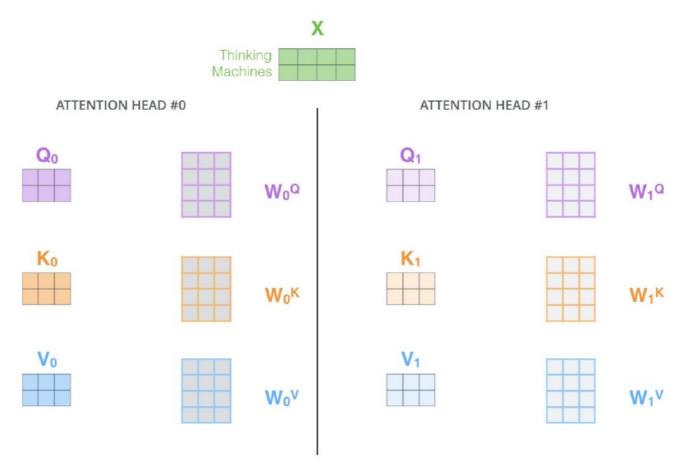


Self-Attention: Matrix Calculation

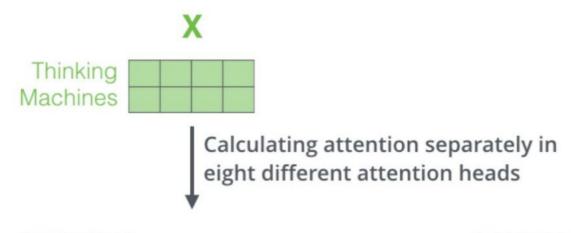


каждая голова MHSA ищет свои связи между словами

Multi-Head Attention



Multi-Head Attention



ATTENTION HEAD #0

Z₀



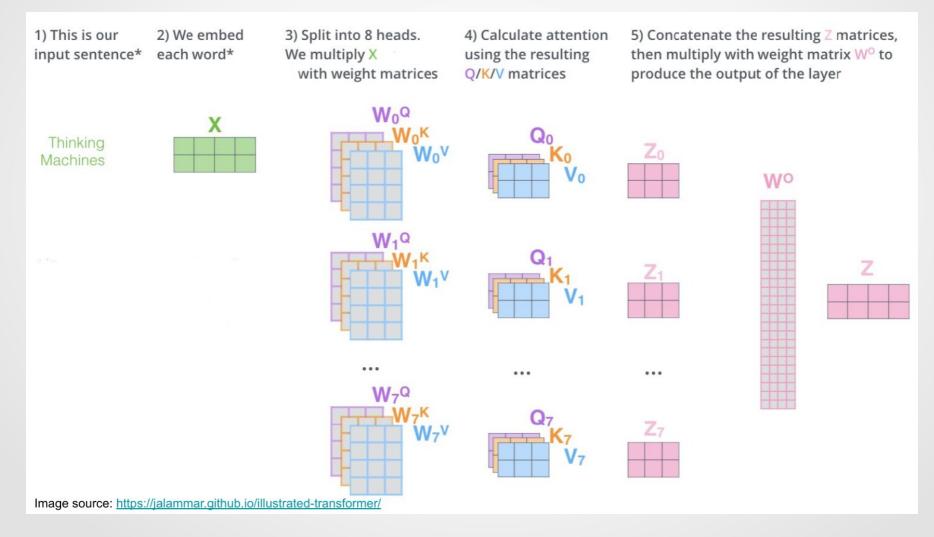
ATTENTION HEAD #1

Z₁

ATTENTION HEAD #7

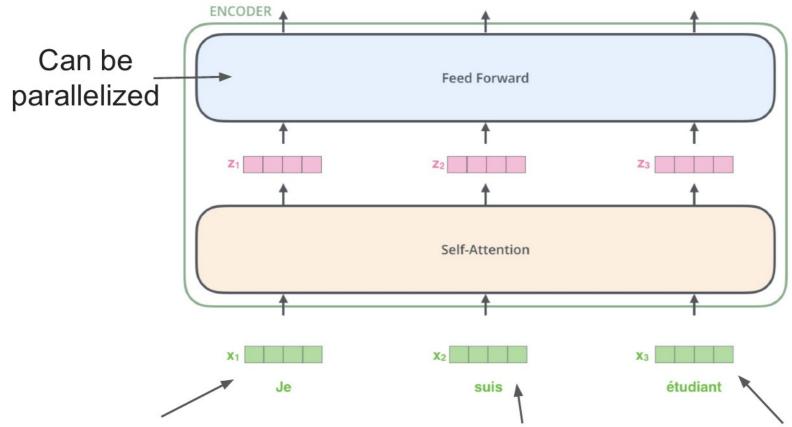


можно сделать так, чтобы размерность входа и выхода MHSE была одинаковая



Positional Encoding

The Encoder Side

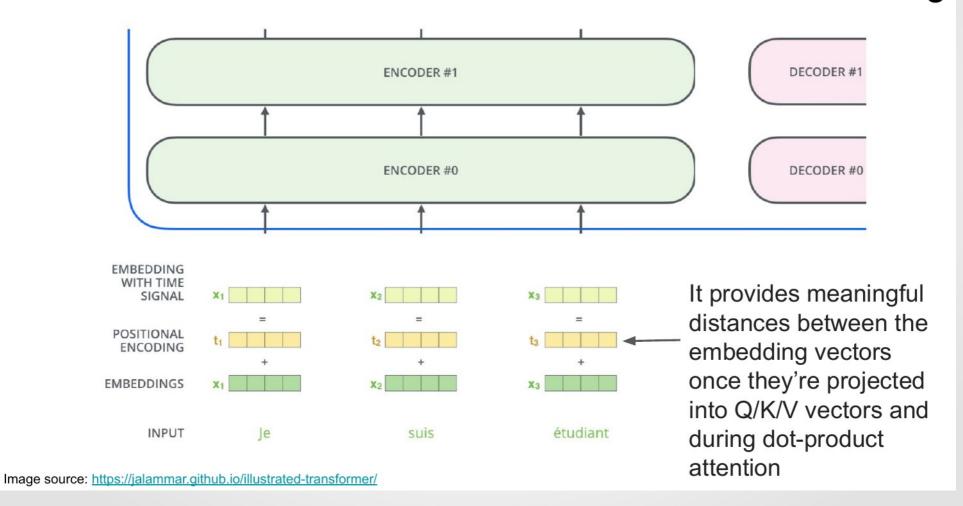


the word in each position flows through its own path in the encoder 46

Необходимо обозначить позицию слова выполняя условия

- уникальность для каждого слова
- не зависит от длинны предложения
- детерминирован (не стохастический)

Positional Encoding



Positional Encoding: why sin and cos?

$$\vec{p_t}^{(i)} = f(t)^{(i)} = \begin{cases} \sin(\omega_k t), & \text{if } i = 2k \\ \cos(\omega_k t), & \text{if } i = 2k + 1 \end{cases}$$

$$\omega_k = \frac{1}{10000^{2k/d}} \qquad \vec{p_t} = \begin{bmatrix} \sin(\omega_1 . t) \\ \cos(\omega_1 . t) \\ \sin(\omega_2 . t) \\ \cos(\omega_2 . t) \\ \vdots \\ \sin(\omega_{d/2} . t) \\ \cos(\omega_{d/2} . t) \\ \cos(\omega_{d/2} . t) \end{bmatrix}_{d \times 1}$$
 t stays for position in the original sequence k is the index of the element in the positional vector

$$\omega_k = \frac{1}{10000^{2k/d}}$$

$$\begin{bmatrix} \sin(\omega_1.t) \\ \cos(\omega_1.t) \end{bmatrix}$$

$$\sin(\omega_2.t) \\ \cos(\omega_2.t)$$

$$\vdots$$

$$\sin(\omega_{d/2}.t) \\ \cos(\omega_{d/2}.t)$$

Image source: https://kazemnejad.com/blog/transformer_architecture_positional_encoding/

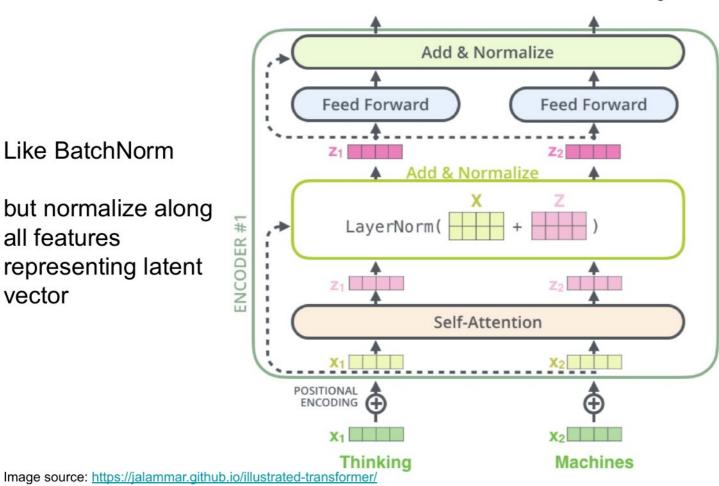
Layer Normalization

More info:

Layer Normalization

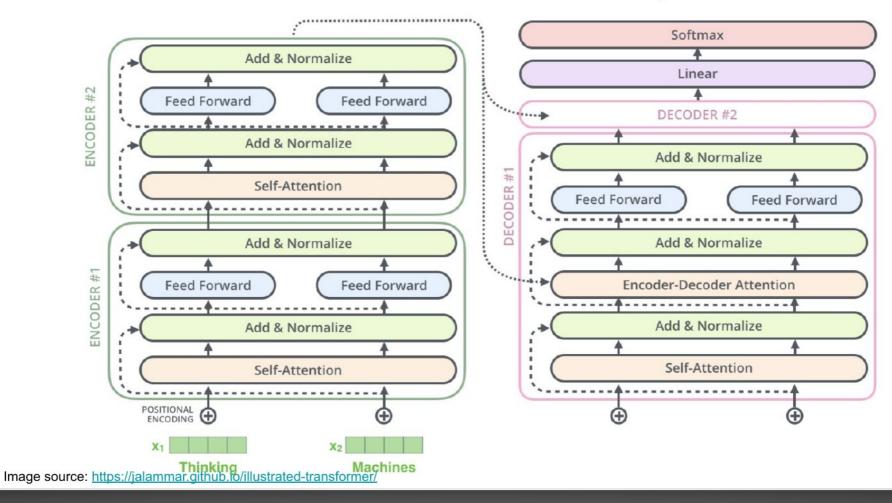
Like BatchNorm

but normalize along all features representing latent vector



можно сделать так, чтобы размерность входа и выхода MHSE была одинаковая и состыковать несколько Encoder

Layer Normalization



SEQ2SEQ NMT: литература

git clone https://github.com/mechanoid5/ml_nlp.git

Евгений Борисов Неросетевой транслятор текстов. Использование рекуррентных нейронных сетей для создания систем машинного перевода и чатботов.

http://mechanoid.su/ml-chatbot.html

Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, Illia Polosukhin Attention Is All You Need

https://arxiv.org/abs/1706.03762

Радослав Нейчев Прикладное машинное обучение. 4. Self-Attention. Transformer overview.

https://www.youtube.com/watch?v=UETKUIIYE6g&list=PL4_hYwCyhAvY7k32D65q3xJVo8X8dc3Ye&index=5