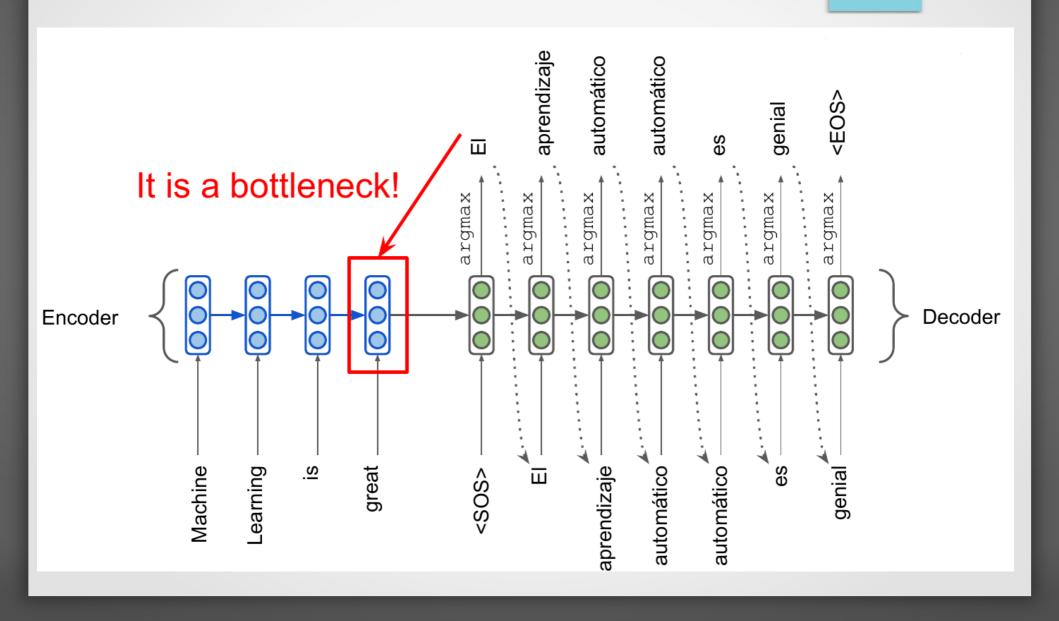
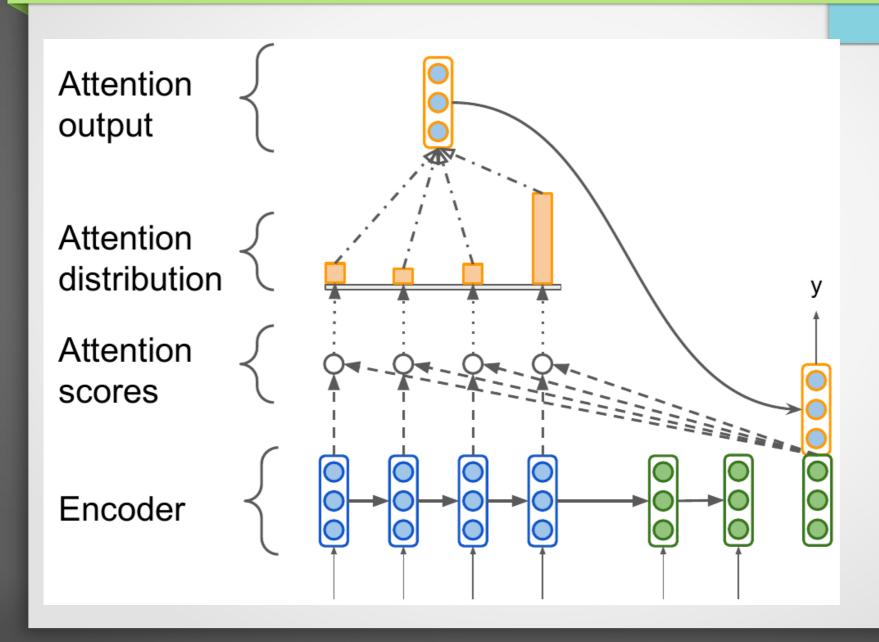
# Модель Transformer и механизм внимания Self-Attention

Евгений Борисов

# SEQ2SEQ NMT



# SEQ2SEQ NMT with ATTENTION

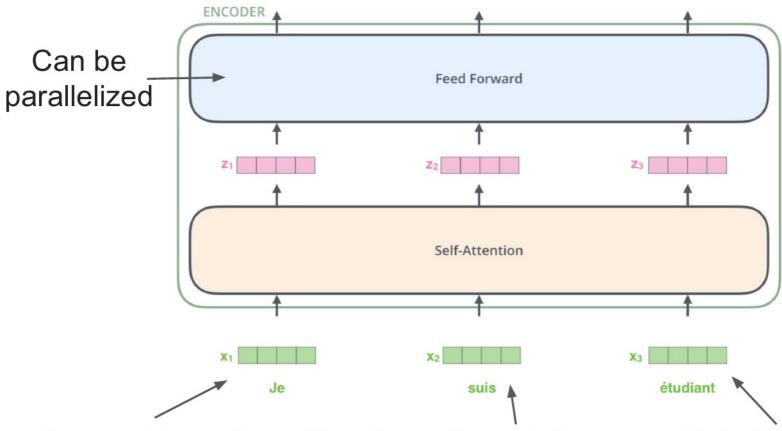


Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, Illia Polosukhin

Attention Is All You Need, 2017

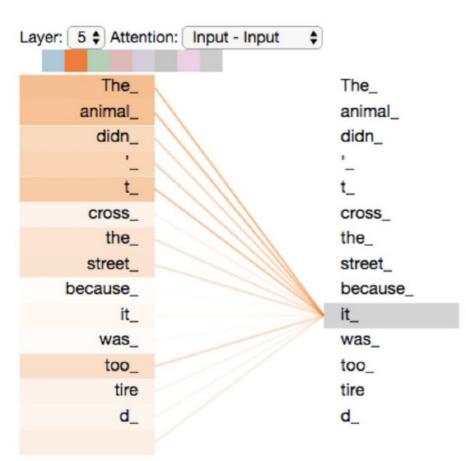
# The Transformer OUTPUT am a student **ENCODERS DECODERS** INPUT étudiant suis

#### The Encoder Side



the word in each position flows through its own path in the encoder 18

#### Self-Attention at a High Level



**Self-Attention** 

query - откуда смотрим (из какого слова)

key - куда смотрим (на какое слово)

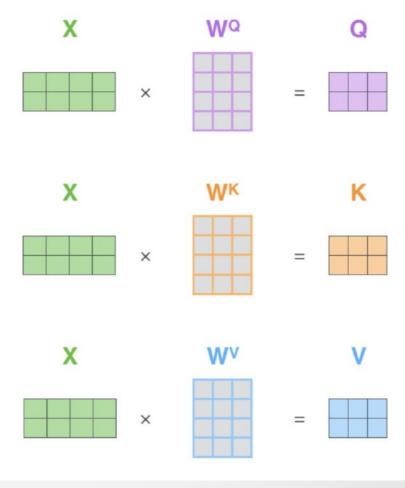
value - смысл (условно) слова

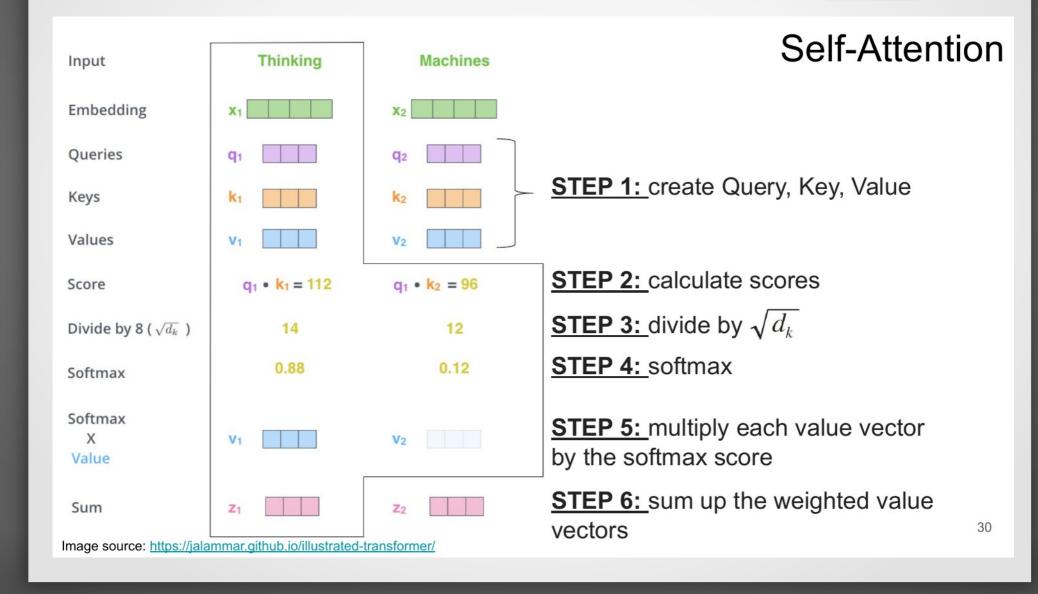
#### Self-Attention: detailed explanation **Thinking Machines** Input **Embedding** WQ Queries WK Keys WV Values 24 Image source: https://jalammar.github.io/illustrated-transformer/

#### Self-Attention: Matrix Calculation

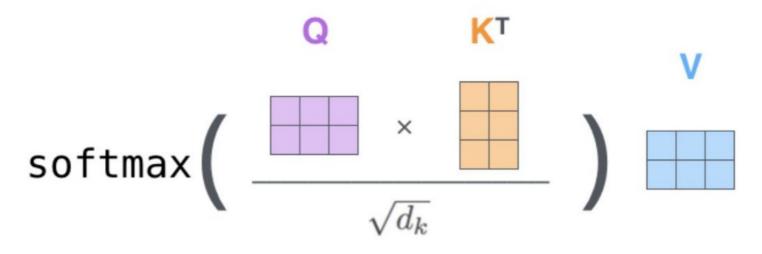
Pack embeddings into matrix **X** 

Multiply **X** by weight matrices we've trained (**Wk**, **Wq**, **Wv**)



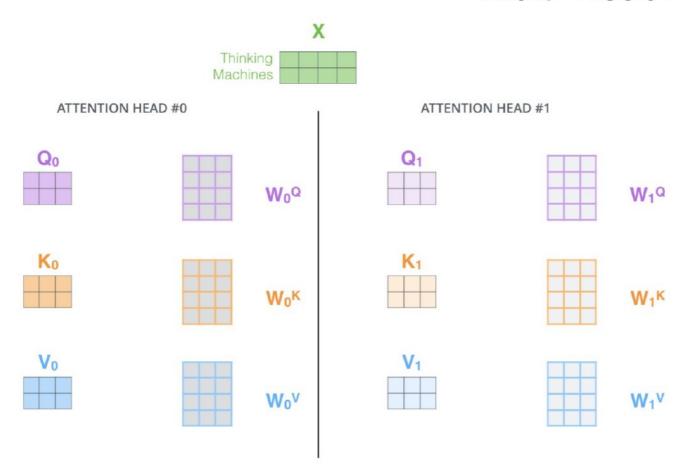


#### Self-Attention: Matrix Calculation

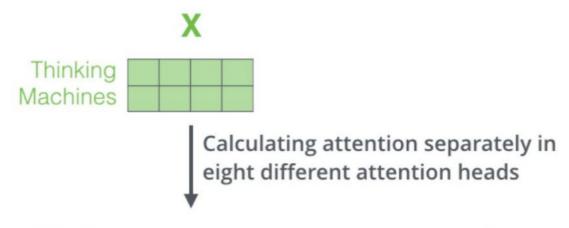


каждая голова MHSA ищет свои связи между словами

#### Multi-Head Attention



#### **Multi-Head Attention**



ATTENTION HEAD #0

Z<sub>0</sub>

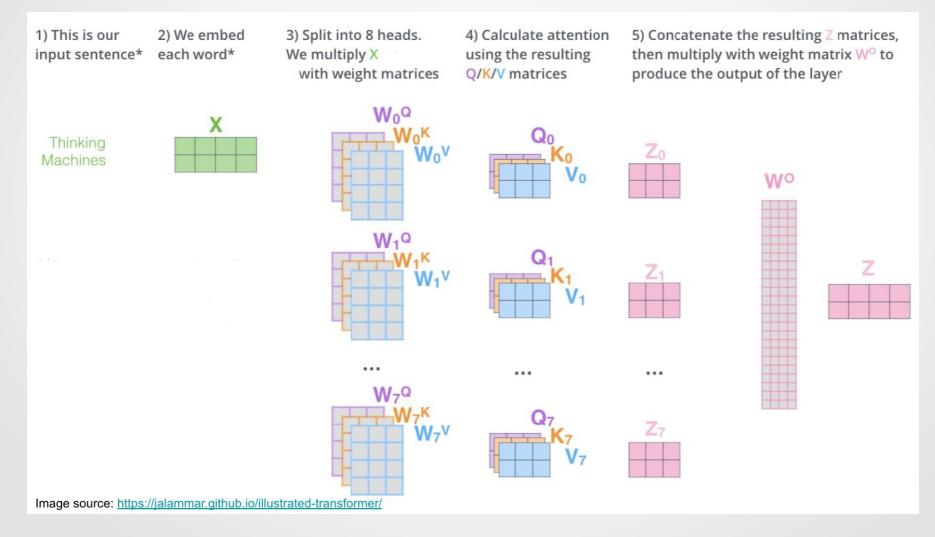
ATTENTION HEAD #1

Z<sub>1</sub>

ATTENTION HEAD #7

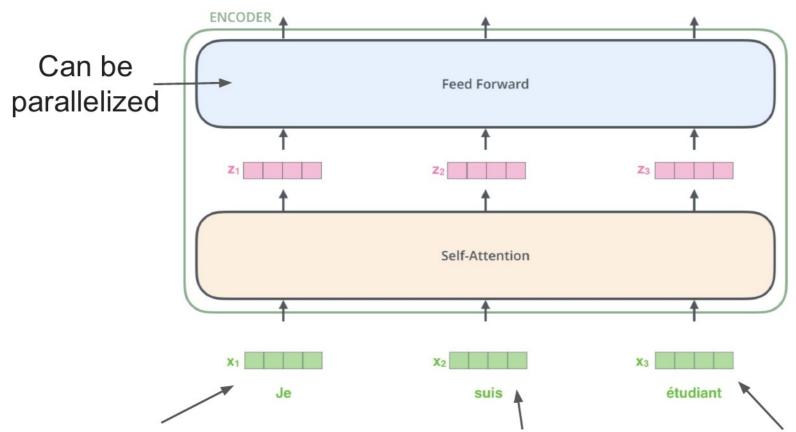


можно сделать так, чтобы размерность входа и выхода MHSE была одинаковая



Positional Encoding

#### The Encoder Side

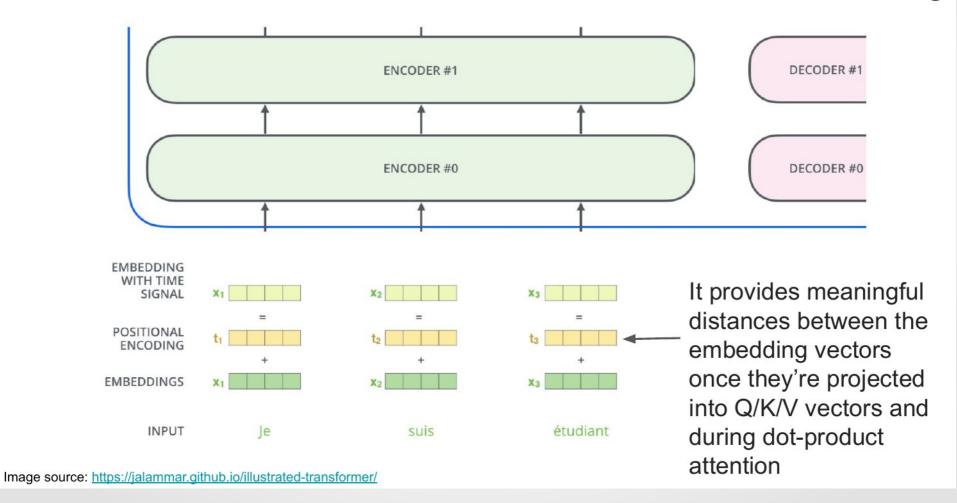


the word in each position flows through its own path in the encoder 46

Необходимо обозначить позицию слова выполняя условия

- уникальность для каждого слова
- не зависит от длинны предложения
- детерминирован (не стохастический)

#### Positional Encoding



#### Positional Encoding: why sin and cos?

$$\vec{p_t}^{(i)} = f(t)^{(i)} = \begin{cases} \sin(\omega_k t), & \text{if } i = 2k \\ \cos(\omega_k t), & \text{if } i = 2k + 1 \end{cases}$$
 
$$\omega_k = \frac{1}{10000^{2k/d}} \qquad \vec{p_t} = \begin{bmatrix} \sin(\omega_1 . t) \\ \cos(\omega_1 . t) \\ \sin(\omega_2 . t) \\ \cos(\omega_2 . t) \\ \vdots \\ \sin(\omega_{d/2} . t) \\ \cos(\omega_{d/2} . t) \\ \cos(\omega_{d/2} . t) \end{bmatrix}$$
 t stays for position in the original sequence k is the index of the element in the positional vector

$$\omega_k = \frac{1}{10000^{2k/d}}$$

$$\sin(\omega_1.t)$$
 $\cos(\omega_1.t)$ 
 $\sin(\omega_2.t)$ 
 $\cos(\omega_2.t)$ 
 $\vdots$ 
 $\sin(\omega_{d/2}.t)$ 
 $\cos(\omega_{d/2}.t)$ 

Image source: https://kazemnejad.com/blog/transformer\_architecture\_positional\_encoding/

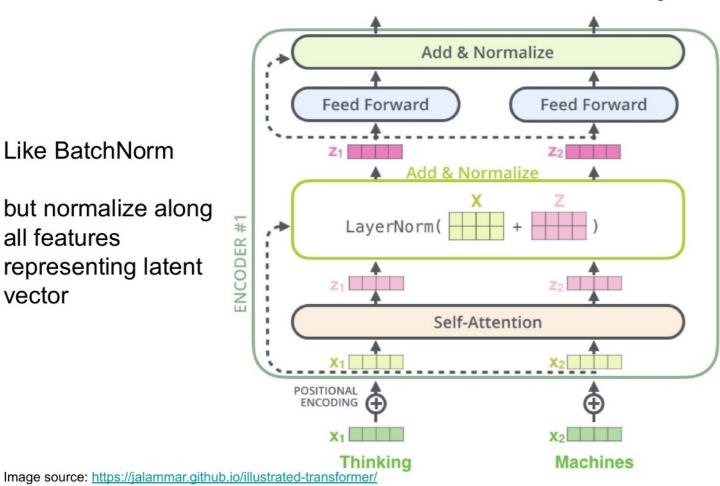
#### Layer Normalization

More info:

**Layer Normalization** 

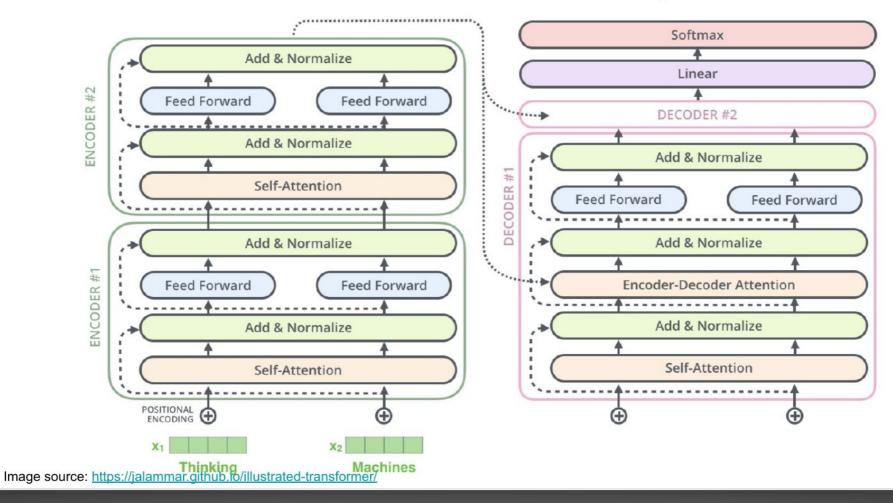
Like BatchNorm

but normalize along all features representing latent vector



можно сделать так, чтобы размерность входа и выхода MHSE была одинаковая и состыковать несколько Encoder

#### Layer Normalization



# Transformer: литература

git clone <a href="https://github.com/mechanoid5/ml\_nlp.git">https://github.com/mechanoid5/ml\_nlp.git</a>

Евгений Борисов Неросетевой транслятор текстов. Использование рекуррентных нейронных сетей для создания систем машинного перевода и чатботов.

http://mechanoid.su/ml-chatbot.html

Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, Illia Polosukhin Attention Is All You Need

https://arxiv.org/abs/1706.03762

Радослав Нейчев Прикладное машинное обучение. 4. Self-Attention. Transformer overview.

https://www.youtube.com/watch?v=UETKUIIYE6g&list=PL4\_hYwCyhAvY7k32D65q3xJVo8X8dc3Ye&index=5