

Gaussian Integration

Gaussian Integration is based on the concept that the accuracy of numerical integration can be improved by choosing the sampling point wisely rather than on the basis of equal spacing. For example consider the following figure.

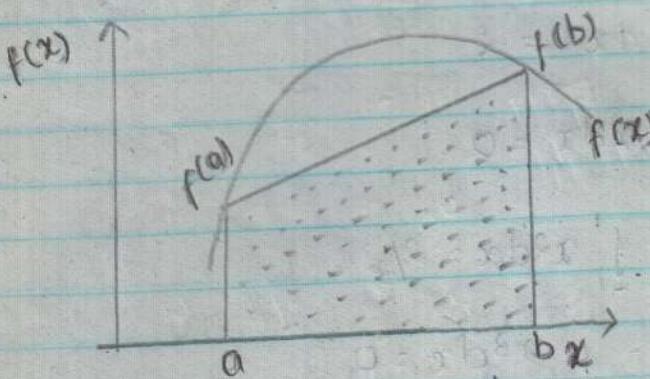


fig1: Trapezoidal rule

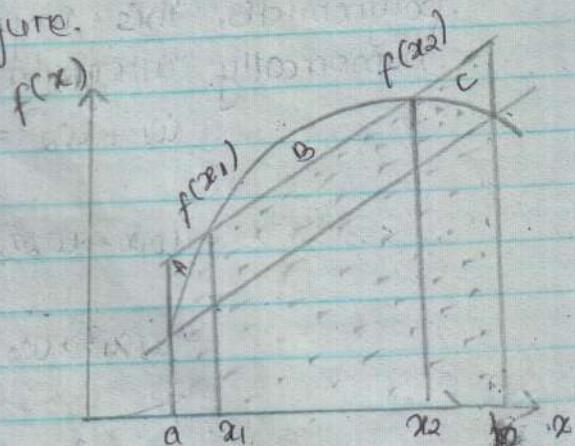


fig2: Gaussian rule

In figure 1 for trapezoidal rule the end point of integral lies in the function curve, whereas in figure 2 the straight line has been moved up such that area $B = A + C$. In this case the function values at the end points are not used in computation whereas the function values $f(x_1)$ & $f(x_2)$ are used to compute the shaded area. Here, the problem is to compute the values of x_1 & x_2 given the values of a & b & choose appropriate weights (w_1 & w_2).

Hence the method of implementing the strategy of finding appropriate values of x_i & w_i & obtaining the integral of $f(x)$ is called gaussian integration or quadrature.

Gaussian Integration assumes the approximation of the form,

$$I_g = \int_{-1}^1 f(x) dx \approx \sum_{i=1}^n w_i f(x_i) \quad \dots \quad (1)$$

This eqn contains n unknowns to be determined. These unknowns can be determined using the condition

given in above eqn ①

let us find a Gaussian quadrature formula for $n=2$. In this case we need to find the values of w_1, w_2, x_1 & x_2 . Also, let us assume that the integral will be exact upto cubic polynomials. This implies that the function $1, x_1, x_2^2, x_2^3$ can be numerically integrated to obtain exact result.

$$w_1 + w_2 = \int_{-1}^1 dx = 2$$

$$w_1 x_1 + w_2 x_2 \int_{-1}^1 x dx = 0$$

$$w_1 x_1^2 + w_2 x_2^2 = \int_{-1}^1 x^2 dx = 2/3$$

$$w_1 x_1^3 + w_2 x_2^3 = \int_{-1}^1 x^3 dx = 0$$

Solving those simultaneous eqn, we obtain,

$$w_1 = w_2 = 1$$

$$x_1 = -1/\sqrt{3}$$

$$x_2 = 1/\sqrt{3}$$

thus we have gaussian quadrature formula for $n=2$ as,

$$\int_{-1}^1 f(x) dx = f\left[-\frac{1}{\sqrt{3}}\right] + f\left[\frac{1}{\sqrt{3}}\right]$$

This formula gives correct values for integral of $f(x)$ in the range $(-1, 1)$ for any function upto 3rd order. This eqn is known as Gauss legendre formula.

Q) Compute $\int_{-1}^1 e^x dx$ using two point gauss legendre formula.
Soln,

We know that, for two point

$$x_1 = -1/\sqrt{3}$$

$$x_2 = 1/\sqrt{3}$$

then $f(x_1) = e^{-\frac{1}{153}} = 0.96138$
 $f(x_2) = e^{\frac{1}{153}} = 1.078181.$

Then we know

$$\int_a^b f(x) dx = f(x_1) + f(x_2)$$

$$= 0.96138 + 1.078181$$

$$= \underline{\underline{2.0394269}}$$

{ for $n=8$.

$$\begin{array}{cccc} q & = & 1 & 2 & 3 \\ w_1 & = & 0.55656 & 0.88889 & 0.555566 \\ w_2 & = & -0.7746 & 0.0000 & 0.7746. \end{array}$$

Romberg Integration Formula

This method can oftenly used to improve the approximate results obtained by the finite difference method. We consider the definite integral

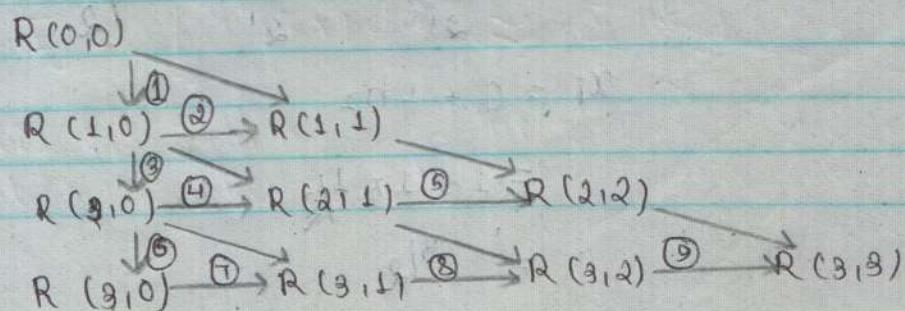
$$I = \int_a^b f(x) dx$$

and evaluate it by trapezoidal rule with different sub intervals as shown below.

let us consider a Romberg integration formula.

$$R_{j,j} = \frac{4^j R_{j,j-1} - R_{j-1,j-1}}{4^{j-1}} \quad \dots \quad (1)$$

when this equation is expanded it will form a lower diagonal matrix where the elements of matrix R are completed Row by Row In The Order Indicated In The Figure Below.



Elements in the 1st column represent trapezoidal rule at $h, h/2, h/4$ etc
They can be evaluated recursively as follows,

$$h = (b-a)$$

$$R(0,0) = \frac{h}{2} (f(a) + f(b))$$

$$R(p,0) = \frac{R(p-1,0)}{2} + h^p \sum_{k=1}^{2^{p-1}} f(x_{2k-1}) \quad \text{for } p=1,2,\dots$$

$$\text{where } h^p = \frac{b-a}{2^p}$$

$$x_k = a + kh^p$$

Q) Compute Romberg estimate $R_{2,2}$ for $\int_0^2 \frac{1}{x} dx$

Soln,

$$a = 0, b = 1$$

$$h = 1$$

$$h = b-a = 1$$

$$\text{Then } f(a) = f(0) = 1/0 \rightarrow \infty$$

$$f(b) = f(1) = 1/1 = 1$$

So,

$$R(0,0) = \frac{h}{2} [f(a) + f(b)]$$

$$= \frac{1}{2} [1 + 0.5]$$

$$= \frac{3}{4}$$

f) $R(1,0) = \frac{R(0,0)}{2} + h_1 \sum_{k=1}^1 f(x_1)$

$$\text{So, } h_1 = \frac{b-a}{2^1} = \frac{1-0}{2^1} = \frac{1}{2}$$

$$x_1 = a + 1 \cdot h_1$$

$$= 0 + 1 \times \frac{1}{2}$$

$$= \frac{3}{2}$$

etc

$$f(x_1) = f(3/2) = 2/3$$

So we have

$$R(L,0) = \frac{R(0,0)}{2} + h_L \sum_{k=1}^L f(x_k)$$
$$= \left(\frac{3}{4}\right)/2 + \frac{1}{2} \times \frac{2}{3}$$

$$= \frac{3}{8} + \frac{1}{3}$$

$$= \frac{17}{24}$$

Solution of Ordinary Differential Equation.

mathematical models for different laws in scientific work are often expressed in terms of not only certain system parameters, but also in terms of their derivatives. Such mathematical models which use differential calculus to express relationship between variables are known as differential variables.

For example

① law of cooling

Newton's law of cooling.

$$\frac{dT(t)}{dt} = K [T_s - T(t)] \quad \dots \dots \dots \textcircled{1}$$

where T_s = temp^r of surrounding

$T(t)$ = temp^r of liquid at time t

K = constant of proportionality

Radioactive decay

The radioactive decay of an element is given by,

$$\frac{dm}{dt} + km = 0 \quad \dots \dots \dots \textcircled{2}$$

where,

m = mass

t = time

k = constant rate of decay.

Simple harmonic motion

$$\frac{md^2y}{dt^2} + a \frac{dy}{dt} + ky = 0 \quad \dots \dots \dots \textcircled{3}$$

where

y = displacement

m = mass

dy/dt^2 = acceleration

dy/dt = velocity of moving particle

If there is only one independent variable, the eqn is called an ordinary differential equation.

Example, above eqn ① ② ③

If there is two or more independent variables, the derivatives will be partial: therefore the eqn is called partial differential equation.

Example, Heat flow in a rectangular plate is given by,

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y) \quad \text{--- ④}$$

where $u(x, y)$ denotes the temperature at point (x, y) & $f(x, y)$ = heat source.

Order of differential eqn.

The order of differential equation is the highest derivative that appears in the eqn. For example,

$$\frac{dT(t)}{dt} = \kappa(T_s - T(t)) \quad \text{--- first ordered.}$$

$$m \frac{d^2y}{dt^2} + a \frac{dy}{dt} + by = 0 \quad \text{--- second ordered.}$$

A first ordered eqn can be expressed on the form $\frac{dy}{dx} = f(x)$. A second ordered eqn can be expressed on the form $\frac{d^2y}{dx^2} = y'' = f(x, y, y')$.

where y'' = Second derivative,
 y' = First derivative.

Higher order eqⁿ can be reduced to a set of first ordered equations by suitable transformation. For example,

$y'' = f(x, y, y')$ can be equivalently represented by,

$$u' = f(x, y, y') \text{ where } y' = u.$$

Degree of equation

The degree of a differential eqⁿ is the power of the highest order derivative. For example,

$$xy'' + y^2y' = 2y + 3 \rightarrow \text{first degree (second order)}$$

$$(y''')^2 + 5y' = 0 \rightarrow \text{Second degree (third order)}$$

Initial value problem.

It is well known that a differential eqⁿ of n^{th} order will have n arbitrary constants in its general solution. In order to compute the numerical soln of such an eqⁿ we therefore need n conditions. Problems in which all the initial conditions are specified at the initial point only are called initial value problems.

On the other hand, in problems involving second & higher order differential eq's we may prescribe the conditions at two points or more. Such problems are called boundary value problems.

Consider the soln $y = ae^x$ to the eq¹ $y' = y$

If we are given the value of y for some x , the constant a can be determined.

Suppose $y = 1$ at $x = 0$ then,

$$y(0) = ae^0 = 1$$

$$\therefore a = 1$$

$$y(x) = y(x_0) + y'(x_0)(x-x_0) + \frac{y''(x_0)(x-x_0)^2}{2!}$$

& the particular soln is

$$y = e^x.$$

If the order of equation is n we will have to obtain n constants & therefore we need n conditions, in order to obtain a unique soln.

Taylor

Taylor series method

A function $y(x)$ is extended about a point $x=x_0$ using Taylor's theorem of expansion as,

$$\begin{aligned} y(x) = & y(x_0) + \frac{y'(x_0)}{1!}(x-x_0) + \frac{y''(x_0)}{2!}(x-x_0)^2 \\ & + \frac{y'''(x_0)}{3!}(x-x_0)^3 + \dots + \frac{y^n(x_0)}{n!}(x-x_0)^n \end{aligned} \quad (1)$$

where,

$y^{(n)}(x_0)$ = n th derivative of $y(x)$ evaluated at $x=x_0$.

The value of y can be obtained if we know the value of its derivatives. This implies that if we are given the eqn

$$y' = f(x, y) \quad (2)$$

We must then repeatedly differentiate $f(x, y)$ empirically with respect to x and evaluate them at x_0 .

Example:

$$\text{If } \frac{dy}{dx} = y' = f(x, y) \text{ then,}$$

$$y'' = \frac{d}{dx} \left[\frac{dy}{dx} \right] = \frac{d}{dx} [f(x, y)]$$

$$= \frac{d}{dx} [f(x, y)] + \frac{\partial}{\partial y} [f(x, y)] \cdot \frac{dy}{dx}$$

$$(x=x_0)$$

$$y(x) = y(x_0) + y'(x_0)(x-x_0) + \frac{y''(x_0)(x-x_0)^2}{2!}$$

$$\begin{aligned} y(x) = & y(x_0) + \\ & \frac{y'(x_0)}{1!}(x-x_0) + \frac{y''(x_0)}{2!}(x-x_0)^2 \end{aligned}$$

$$= \frac{df}{dx} + \frac{df}{dy} \cdot f$$

$$= f_x + f_y \cdot f \quad \text{where}$$

$f = \text{function } \Rightarrow f(x,y)$, f_x & f_y denote
the partial derivatives of the
function $f(x,y)$ with respect to
 x & y respectively.

Similarly we can obtain

$$y''' \sim f_{xx} + 2f_x f_{xy} + f^2 f_{yy} + f_x f_{yy} + f_y f_y^2$$

let us illustrate with example.

consider the eqn.

$$y' = x^2 + y^2$$

under the condition,

$$y(0) = 1 \text{ where } x = 0.$$

Given,

$$y' = x^2 + y^2$$

$$y'' = \frac{d}{dx} (x^2 + y^2)$$

$$= \frac{d}{dx} (x^2 + y^2) + \frac{d}{dy} (x^2 + y^2) \frac{dy}{dx}$$

$$= 2x + 2y \cdot y'$$

$$y''' = 2 + 2y'y'' + 2(y')^2$$

at $x=0$, $y(0)=1$. & therefore

$$y'(0) = 1$$

$$y''(0) = 2$$

$$y'''(0) = 8$$

Finally substituting the values, Taylor series become

$$y(x) = 1 + x + x^2 + \frac{8}{3!} x^3 + \dots \quad (8)$$

The number of terms to be used depends on the accuracy of the soln needed.

Q1 Use the Taylor method to solve the eqn,

$$y' = x^2 + y^2 \text{ for } x = 0.25 \text{ & } x = 0.5$$

given $y(0) = 1$

Soln

We have,

given eqn (8)

$$y' = x^2 + y^2$$

The Taylor series for above eqn (8),

$$y(x) = 1 + x + x^2 + \frac{8}{3!} x^3 + \dots$$

Now for $x = 0.25$

$$y[0.25] = 1 + 0.25 + (0.25)^2 + \frac{8}{3!} (0.25)^3$$

$$= 1.025 + 0.0625 + 1.33 \times 0.015625$$

$$= 1.0875 + 0.02078125$$

$$= 1.108311$$

& for $x = 0.5$,

$$y[0.5] = 1 + 0.5 + 0.5^2 + \frac{8}{3!} (0.5)^3$$

$$= 1.5 + 0.25 + 1.33 \times 0.125$$

$$= 1.75 + 0.16625$$

$$= 1.9162511$$

One major problem with Taylor series method is the evaluation of higher order derivative. This method is therefore generally impractical from a computational point of view. The error in Taylor method is in the order of $(x-x_0)^n$. If $|f'(x-x_0)|$ is large the error can also become large, therefore the result is often found unsatisfactory.

Picard's method:

Consider the first ordered eqn $\frac{dy}{dx} = f(x, y) \dots \textcircled{1}$
 It is necessary to find that particular soln of eqn $\textcircled{1}$ which assumes the value y_0 when $x = x_0$. Integrating eqn $\textcircled{1}$ between limits we get:

$$\int_{y_0}^y dy = \int_{x_0}^x f(x, y) dx$$

$$\text{or, } y - y_0 = \int_{x_0}^x f(x, y) dx$$

$$\therefore y = y_0 + \int_{x_0}^x f(x, y) dx \dots \textcircled{2}$$

This is an integral eqn equivalent to eqn $\textcircled{1}$, for it contains the unknown y under the integral sign.

As a first approximation y_1 to the soln, we put $y=y_0$ in $f(x, y)$ & integrate eqn $\textcircled{2}$, giving

$$y_1 = y_0 + \int_{x_0}^x f(x, y_0) dx$$

For a second approximation y_2 we put $y=y_1$ in $f(x, y)$ & integrate eqn $\textcircled{2}$ giving,

$$y_2 = y_0 + \int_{x_0}^{x_1} f(x_1, y_1) dx$$

Similarly 3rd approximation is given by

$$y_3 = y_0 + \int_{x_0}^{x_2} f(x_2, y_2) dx$$

continuing this process we obtain y_4, y_5, \dots, y_n

g

$$y_n = y_0 + \int_{x_0}^x f(x_n, y_{n-1}) dx$$

Hence this method gives a sequence of approximations y_1, y_2, \dots, y_n each giving a better result than preceding one.

- Q. Using peccard's process of successive approximation, obtain a solution upto 5th approximation of the equation $\frac{dy}{dx} = y+x$ such that $y=1$ when $x=0$

soin,

we have,

$$y = 1 + \int_0^x (y+x) dx$$

for the first approximation, put $y=1$ in $y+x$
then,

$$y_1 = 1 + \int_0^x (1+x) dx$$

$$= 1 + \left[x + \frac{x^2}{2} \right]_0^x$$

$$= 1 + x + \frac{x^2}{2}$$

for the second approximation put

$$y_1 = 1 + x + \frac{x^2}{2}$$

Then

$$y_2 = 1 + \int_0^x \left(1 + x + \frac{x^2}{2} + x\right) dx$$

$$= 1 + x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^2}{2}$$

$$= 1 + x + x^2 + \frac{x^3}{6}$$

for third approximation put $y = 1 + x + x^2 + \frac{x^3}{6}$

Then, $y_3 = 1 + \int_0^x \left(1 + x + x^2 + \frac{x^3}{6} + x\right) dx$

$$= 1 + \int_0^x \left(1 + 2x + x^2 + \frac{x^3}{6}\right) dx$$

$$= 1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{24}$$

for the fourth approximation put $y = 1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{24}$

Then,

$$y_4 = 1 + \int_0^x \left(1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{24} + x\right) dx$$

$$= 1 + \int_0^x \left(1 + 2x + x^2 + \frac{x^3}{3} + \frac{x^4}{24}\right) dx$$

$$= 1 + x + x^2 + \frac{x^3}{3} + \frac{x^4}{12} + \frac{x^5}{120}$$

for 5th approximation put $y = 1 + x + x^2 + x^3/3 + x^4/12 + x^5/120$ we get
 $y_5 = 1 + \int_0^x (1 + x + x^2 + x^3/3 + x^4/12 + x^5/120 + x) dx$
 $= 1 + x + x^2 + x^3/3 + x^4/12 + x^5/60 + x^6/720.$

Q. Solve the following eqn by Picard's method

① $y'(x) = x^2 + y^2, y(0) = 0$

② $y'(x) = xe^y, y(0) = 0$

To estimate $y(0.1), y(0.2)$ & $y(1)$.

soln.

Given:

$$y'(x) = x^2 + y^2$$

$$y_0 = 0, x_0 = 0$$

then:

$$\begin{aligned} y_1 &= y_0 + \int_0^x (x^2 + y_0^2) dx \\ &= 0 + \left[x^3 - \frac{x^3}{3} + xy^2 \right]_0^x \\ &= \frac{x^3}{3} + xy^2 \end{aligned}$$

$$\begin{aligned} y_2 &= y_0 + \int_0^x (x^2 + y_1^2) dx \\ &= 0 + \int_0^x \left(x^2 + \left(\frac{x^3}{3} + xy^2 \right)^2 \right) dx \\ &= 0 + \int_0^x \left(x^2 + \frac{x^6}{9} + \frac{2x^4y^2}{3} + x^2y^4 \right) dx \end{aligned}$$

$$= 0 + \left[\frac{x^3}{3} + \frac{x^7}{63} + \frac{2x^5y^2}{15} + \frac{x^3y^4}{3} \right]_0^x$$

$$= \frac{x^3}{3} + \frac{x^7}{63} + \frac{2x^5y^2}{15} + \frac{x^3y^4}{3}$$

Since Picard's method involves actual integration, sometimes it may not be possible to carry out the integration. Also this method is not convenient for computer based soln. Like Taylor series this is also semi numerical method.

Euler's method:

It is the simplest one step method & has a limited application because of its low accuracy.

Consider the first two terms of the expansion of Taylor series,

$$y(x) = y(x_0) + y'(x_0)(x-x_0) \quad \text{durch -2} \quad (1)$$

from the differential eqn,

$$y'(x) = f(x, y) \text{ with } y(x_0) = y_0$$

Then we have

$$y'(x_0) = f(x_0, y_0)$$

and therefore i

$$y(x) = y(x_0) + (x - x_0) f(x_0, y_0)$$

Then the value of $y(x)$ at $x = x_0$, is given by

$$y(x_1) = y(x_0) + (x_1 - x_0) f_1(x_0, y_0)$$

Let $h = x_1 - x_0$, then,

$$y_1 = y_0 + h f(x_0, y_0)$$

Similarly, y_x at point $x = x_2$ is given by

$$y_2 = y_1 + h f(x_1, y_1)$$

In general we obtain a recursive relation,

$$y_{i+1} = y_i + h f(x_i, y_i)$$

This formula is known as Euler's method, and can be used recursively to evaluate y_1, y_2, y_3, \dots of $\frac{dy}{dx}$.

of $y(x_1), y(x_2), y(x_3)$... etc. starting from the initial condition $y_0 = y(x_0)$.

Here a new value of y is estimated using the previous value of y as the initial condition. Note that the term $h f(x_i, y_i)$ represents the incremental value of y & $f(x_i, y_i)$ is the slope of $y(x)$ at point (x_i, y_i) i.e. the new value is obtained by extrapolating linearly over the step size h using the slope at its previous value. i.e.

$$\text{new value} = \text{old value} + \text{stepsize} * \text{slope}$$

This is illustrated in the figure below.

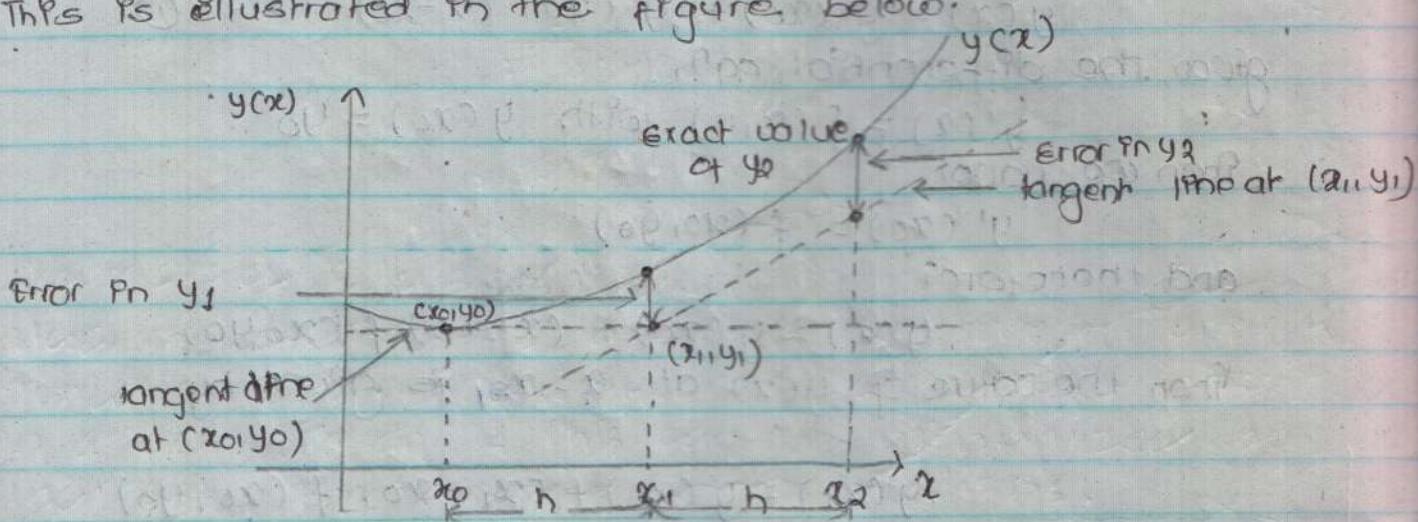


Fig - Illustration of Euler's method for two steps.

Q1 Given the equation $dy/dx = 3x^2 + 1$ with $y(1) = 2$ estimate $y(2)$ by Euler's method using

$$\textcircled{1} \quad h = 0.5$$

$$\textcircled{2} \quad h = 0.25.$$

Soln

We have

$$h = 0.5$$

& the given condition is

$$y(1) = 2$$

$$x_0 = 1$$

$$y_0 = 2$$

$$f(x) = 3x^2 + 1$$

Now,

$$y(1+0.5) = y_0 + hf(x_0, y_0)$$

$$\text{or } y(1.5) = 2 + 0.5 \times (3 \times 1^2 + 1)$$

$$= 2 + 0.5 \times 4$$

$$= 2 + 2$$

~~$$= 4$$~~

Again,

$$y(1.5+0.5) = y_{1.5} + 0.5 \times f(x_{1.5}, y_{1.5})$$

$$= 4 + 0.5 \times (3 \times 1.5^2 + 1)$$

$$= 7.0875$$

$$\text{for } h = 0.25$$

$$y(1) = 2$$

$$x_0 = 1$$

$$y_0 = 2$$

$$f(x) = 3x^2 + 1$$

Now,

$$y(1+0.25) = y_0 + hf(x_0, y_0)$$

$$= 2 + 0.25 \times 4$$

$$= 3$$

Again,

$$y(1.25+0.25) = y_{1.25} + 0.25 \times f(x_{1.25}, y_{1.25})$$

$$= 3 + 0.25 \times (5.625)$$

$$= 4.0421875$$

$$\begin{aligned} CA &\rightarrow 23 \\ NM &\rightarrow 20 \\ DOM &\rightarrow 14 \end{aligned}$$

Now,

$$y(1.05 + 0.25) = y_{1.05} + hf(x_{1.05}, y_{1.05})$$

$$= 40421875 + 0.25 \times 7075$$

$$= 60359375 //$$

Again

$$y(1.075 + 0.25) = y_{1.075} + hf(x_{1.075}, y_{1.075})$$

$$= 60359375 + 0.25 \times 1001875$$

$$= 8090625 //$$

Accuracy of Euler's method.

- ↳ Here, the accuracy is affected by roundoff error & truncation error. Roundoff error is always present in a computation & this can be minimized by increasing the precision of calculations.
- ↳ The major cause of loss of accuracy is truncation error because of the use of truncated Taylor series.
- ↳ Also, the total truncation error in any iteration step will consist of two components.
 - ① The propagated truncation error
 - ② The truncation error introduced by the step itself
- ↳ The truncation introduced by the step itself is known as local truncation error & the sum of propagated error & the local error is called the global truncation error.

Recall the Taylor series expansion used in Euler's method for estimating the values of y_{P+1} as,

$$y_{P+1} = y_P + y'_P h + \frac{y''_P}{2!} h^2 + \frac{y'''_P}{3!} h^3 + \dots$$

Since only the first two terms are used in Euler's Formula, The local truncation error is given by,

$$E_{t,P+1} = \frac{y''_P}{2!} h^2 + \frac{y'''_P}{3!} h^3 + \frac{y^{(4)}_P}{4!} h^4 + \dots$$

If the step size h is very small, the higher order terms can be neglected & therefore

$$E_{t,P+1} = \frac{y''_P}{2!} h^2$$

This shows that the local truncation error of Euler's method is of the order h^2 . If the final estimation requires n steps, the total (global) truncation error at the target point say b will be,

$$\begin{aligned} |E_{tg}| &= \sum_{i=1}^n c_i h^2 = (c_1 + c_2 + c_3 + \dots + c_n) h^2 \\ &= nch^2 \text{ where } c = \frac{c_1 + c_2 + \dots + c_n}{n} \end{aligned}$$

$$\text{Since } n = \frac{b - x_0}{h}$$

$$|E_{tg}| = \frac{(b - x_0) ch^2}{h}$$

$$= (b - x_0) ch.$$

Q. Compute the error in the previous example when $h=0.05$

Given,

$$\text{Step 1, } x_0 = 1 \quad y_0 = 2$$

$$+ \quad y_1 = y(1.05) = 4$$

$$E_{L1} = \frac{y_0''}{2} h^2 + \frac{y_0'''}{6} h^3$$

$$= \frac{6x}{2} (0.05)^2 + \frac{(6) \cdot (0.05)^3}{6}$$

$$= \frac{6 \cdot 1}{2} (0.05)^2 + 0.05^3$$

$$= 0.75 + 0.0125$$

Heun's method.

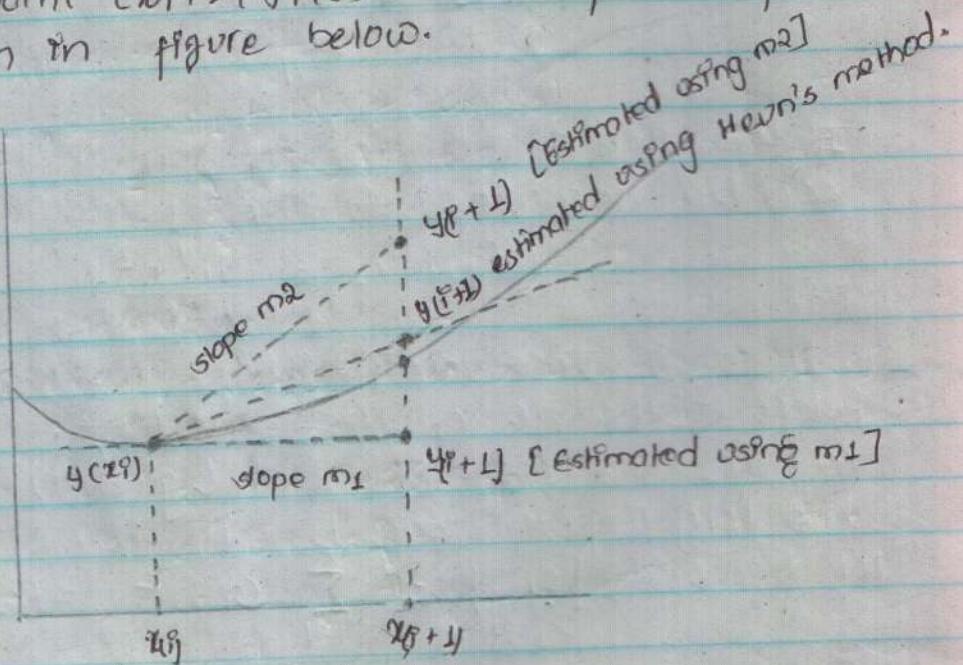
It is the improvement to Euler's method, so it is also called modified Euler's method.

In Euler's method the slope at the beginning of the interval is used to extrapolate y_i to y_{i+1} . Thus

$$y_{i+1} = y_i + m_1 * h$$

where m_1 is the slope at (x_i, y_i)

In Heun's method, we use the line which is parallel to the tangent at point (x_{i+1}, y_{i+1}) to extrapolate from y_i to y_{i+1} as shown in figure below.



P.E.

$$y_{i+1} = y_i + m_2 * h$$

where m_2 = slope at point (x_{i+1}, y_{i+1})

The next step is to use a line whose slope is the average of the slopes at the end points of the interval then,

$$y_{i+1} = y_i + \frac{m_1 + m_2}{2} * h. \quad \dots \textcircled{1}$$

This gives better approximation to y_{i+1} . This approach is known as Heun's method.

Formula for implementing Heun's method is constructed as follows,
given me eqⁿ,

$$y'(x) = f[x_i, y]$$

we obtain m_1, m_2

$$m_1 = y'(x_i^0) = f(x_i^0, y_i^0) \quad y_{i+1}^0 = y_i^0 + h f(x_i^0, y_i^0)$$

$$m_2 = y'(x_{i+1}^0) = f(x_{i+1}^0, y_{i+1}^0)$$

and therefore

$$m = \frac{m_1 + m_2}{2} = \frac{f(x_i^0, y_i^0) + f(x_{i+1}^0, y_{i+1}^0)}{2}$$

so,

eqⁿ ① becomes

$$y_{i+1}^0 = y_i^0 + \frac{h}{2} [f(x_i^0, y_i^0) + f(x_{i+1}^0, y_{i+1}^0)] \quad \text{--- (2)}$$

Note that the term y_{i+1}^0 of RHS of me eqⁿ is predicted using Euler's formula as,

$$y_{i+1}^0 = y_i^0 + h f(x_i^0, y_i^0). \quad \text{--- (3)}$$

Then Heun's formula becomes,

$$y_{i+1}^0 = y_i^0 + \frac{h}{2} [f(x_i^0, y_i^0) + f(x_{i+1}^0, y_{i+1}^0)] \quad \text{--- (4)}$$

This is an improved version of Euler's method also called one step predictor, corrector method. Hence substituting eqⁿ ③ in eqⁿ ④ we get,

$$y_{i+1}^0 = y_i^0 + \frac{h}{2} [f(x_i^0, y_i^0) + f(x_{i+1}^0, y_i^0 + h f(x_i^0, y_i^0))]$$

Q1 Given the equation $y'(x) = 2y/x$ with $y(1) = 2$ estimate $y(2)$ using
 ① Euler's method.
 ② Heun's method using $h = 0.25$ & compare the result with exact answer.

Soln,

Given,

$$y'(x) = 2y/x = f(x, y)$$

$$x_0 = 1, y_0 = 2, h = 0.25$$

① Using Euler's method.

$$\begin{aligned} y(1+0.25) &= y_0 + 0.25 f(x_0, y_0) \\ &= 2 + 0.25 \times 4 \\ &= 3 \end{aligned}$$

$$y(1.25+0.25) = y_{1.25} + 0.25 f(x_{1.25}, y_{1.25})$$

$$\begin{aligned} &= 3 + 0.25 \times 4.8 \\ &= 3 + 1.2 \\ &= 3.5 \end{aligned}$$

$$y(1.5+0.25) = y_{1.5} + 0.25 f(x_{1.5}, y_{1.5})$$

$$\begin{aligned} &= 4.2 + 0.25 \times 5.6 \\ &= 4.2 + 1.4 \\ &= 5.6 \end{aligned}$$

$$\begin{aligned} y(1.75+0.25) &= y_{1.75} + 0.25 f(x_{1.75}, y_{1.75}) \\ &= 5.6 + 0.25 \times 6.4 \\ &= 5.6 + 1.6 \\ &= 7.2 \end{aligned}$$

(ii) Using Heun's method,

$$y(1+0.25) = y_1 + \frac{0.25}{2} [4 \rightarrow 3]$$
$$= 2 + 0.125 \times 7$$
$$= 2.875$$

(i) Using Heun's method,

$$m_1 = f(x_0, y_0) = 4$$
$$y(1+0.25) = y_0 + hm$$
$$= 2 + 0.25 \times 4$$
$$= 3$$
$$m_2 = f(x_1, y_e)$$
$$= \frac{2 \times 3}{1+0.25}$$
$$= 4.8$$

then,

$$y(1+0.25) = y_0 + \frac{h}{2} (m_1 + m_2)$$
$$= 2 + \frac{0.25}{2} (4 + 4.8)$$
$$= 3.11$$

Again,

$$m_1 = f(x_{1+0.25}, y_{1+0.25})$$
$$= 4.9611$$

$$y_e(1+0.5) = y_{1+0.25} + hm$$
$$= \cancel{3.1} + 0.25 \times 4.96$$
$$= 4.3411$$

$$m_2 = f(x_{1.025}, y^e)$$

$$= \frac{2 \times 4.34}{1.05}$$

$$= 50.7871$$

Again, then

$$m_1 = f(x_{1.05}, y_{1.05})$$

$$y_{1.05} = y_{1.025} + \frac{h}{2} (m_1 + m_2)$$

$$= 30.1 + \frac{0.25}{2} (40.96 + 50.787)$$

$$= 40.4434$$

Again,

$$m_1 = f(x_{1.05}, y_{1.05})$$

$$= \frac{2 \times 40.4434}{1.05}$$

$$= 50.921$$

$$y_e(1.075) = y_{1.05} + hm$$

$$= 40.4434 + 0.25 \times 5.92$$

$$= 50.9234$$

$$m_2 = f(x_2, y^e)$$

$$= \frac{2 \times 50.9234}{1.075}$$

$$= 6.7696 //$$

$$y(1.75) = y_{10.5} + \frac{h}{2} (m_1 + m_2)$$

$$= 4.04434 + \frac{0.25}{2} (5.92 + 6.7696)$$

$$= 6.0296 //$$

Again

$$m_1 = f(x_{1.75}, y_{10.5}) - 0.25 \times 4$$

$$= 2 \times 6.0296$$

$$= 6.89 //$$

$$y_e(2.0) = y_{10.5} + hm$$

$$= 6.0296 + 0.25 \times 6.89$$

$$= 7.07521 //$$

$$m_2 = f(x_{1.75}, y_e)$$

$$= \frac{2 \times 7.07521}{2}$$

$$= 7.07521 //$$

Then

$$y(2) = y_{10.5} + \frac{h}{2} (m_1 + m_2)$$

$$= 6.0296 + \frac{0.25}{2} (6.89 + 7.07521)$$

$$= 7.086 //$$

Runge-Kutta method.

This method refers to the family of one step method used for the solution of initial value problems. They are all based on the general form of the extrapolation equation,

$$y_{p+1} = y_p + \text{slope} \times \text{interval size.}$$

$$= y_p + mh.$$

where m = slope weighted averages of the slopes at various points in the interval h . h = interval size

Runge-Kutta (RK) methods are known by their order. For instance an RK method is called the r -order Runge-Kutta method when slopes at r -points are used to construct the weighted average slope m . Euler's method uses only one slope at (x_p, y_p) to estimate y_{p+1} . And therefore Euler's method is the first order Runge-Kutta method. Similarly Heun's method is a 2nd order Runge-Kutta method because it employs slopes at two end points of the interval.

From Euler's & Heun's method it is seen that higher the order better would be the accuracy of estimates.

It is clear from above discussion that it is possible to construct RK method of different orders. However, the commonly used one is the 4th order method. Although there are different versions of 4th order RK method, the most popular method is, the classical 4th order RK method, which is given below,

$$m_1 = f(x_p, y_p)$$

$$m_2 = f\left[x_p + \frac{h}{2}, y_p + \frac{m_1 h}{2}\right]$$

$$m_3 = f(x_i + h/2, y_i + m_2 h/2)$$

$$m_4 = f(x_i + h, y_i + m_3 h)$$

$$y_{i+1} = y_i + \frac{(m_1 + 2m_2 + 2m_3 + m_4) * h}{6}$$

Q11 Use the classical RK method to estimate $y(0.4)$ when
 $y'(x) = x^2 + y^2$ with $y(0) = 0$. Assume $h = 0.2$

Soln, $y(0.4)$ when $h = 0.1$

Given $y'(x) = x^2 + y^2 = f(x, y)$
 $y_0 = 0, x_0 = 0$
 $h = 0.2$

Then iteration 1,

$$\begin{aligned}m_1 &= f(x_0, y_0) \\&= 0^2 + 0^2 \\&= 0\end{aligned}$$

$$\begin{aligned}m_2 &= f(x_i + h/2, y_i + \frac{m_1 h}{2}) \\&= f(0.1, 0) \\&= 0.1^2 + 0^2 \\&= 0.01\end{aligned}$$

$$m_3 = f(x_i + h/2, y_i + m_2 h/2)$$

$$= f(0 + 0.1, 0 + 0.01 \times 0.02/2)$$

$$= f(0.1, 0.001)$$

$$= 0.01,$$

$$m_4 = f(x_i + h, y_i + m_3 h)$$

$$= f(0 + 0.2, 0 + 0.01 \times 0.2)$$

$$= f(0.2, 0.002)$$

$$= 0.04$$

Then,

$$y_{0.2} = y_0 + \frac{(m_1 + 2m_2 + 2m_3 + m_4) \times h}{6}$$

$$= 0 + \frac{(0 + 2 \times 0.01 + 2 \times 0.01 + 0.04) \times 0.2}{6}$$

$$= 0.00871$$

$$= 0.00267$$

for 2nd iteration, we have,

$$m_1 = f(x_{0.2}, y_{0.2})$$

$$= 0.2^2 + 0.00267^2$$

$$= 0.0411$$

$$m_2 = f(x_{0.2} + h/2, y_{0.2} + m_1 h/2)$$

$$= f[0.2 + 0.01 + 0.00267 + 0.04 \times 0.01]$$

$$= f(0.26, 0.00307)$$

$$= 0.26^2 + 0.00307^2$$

$$= 0.090041$$

$$m_3 = f(x_{0.2} + h/2, y_{0.2} + m_2 h/2)$$

$$= f(0.2 + 0.1, 0.00267 + 0.09004 \times 0.1)$$

$$= f(0.3, 0.01167)$$

$$= 0.42 + 0.01167$$

$$= 0.09014$$

$$m_4 = f(x_{0.2} + h, y_{0.2} + m_3 h)$$

$$= f(0.2 + 0.2, 0.00267 + 0.09014 \times 0.2)$$

$$= f(0.4, 0.0207)$$

$$= 0.42 + 0.0207$$

$$= 0.16043$$

Now,

$$y(0.4) = y_{0.2} + \frac{(m_1 + 2m_2 + 2m_3 + m_4)}{6} \times h$$

$$= 0.00267 + \left(\frac{0.04 + 2 \times 0.09004 + 2 \times 0.09014 + 0.16043}{6} \right) \times 0.2$$

$$= 0.00267 + 0.09352 \times 0.2$$

$$= 0.02137$$

Soln.

$$\text{Given } f(x,y) = x^2 + y^2$$

$$x_0 = 0, y_0 = 0, h = 0.1 \quad h/2 = 0.05$$

Then in first iteration,

$$m_1 = f(x_0, y_0)$$

$$= 0^2 + 0^2$$

$$= 0 //$$

$$m_2 = f(x_i + h/2, y_i + m_1 h/2)$$

$$= f(0 + 0.05, 0 + 0 \times 0.05)$$

$$= f(0.05, 0)$$

$$= 0.05^2 + 0^2$$

$$= 0.0025 //$$

$$m_3 = f(x_i + h/2, y_i + m_2 h/2)$$

$$= f(0 + 0.05, 0 + 0.0025 \times 0.05)$$

$$= f(0.05, 0.000125)$$

$$= 0.05^2 + 0.000125^2$$

$$= 0.0025 //$$

$$m_4 = f(x_i + h, y_i + m_3 h)$$

$$= f(0.1, 0.0025 \times 0.1)$$

$$= f(0.1, 0.00025)$$

$$= 0.1^2 + 0.00025^2$$

$$\approx 0.01$$

Then,

$$y_{0.1} = y_0 + \frac{(m_1 + 2m_2 + 2m_3 + m_4) * h}{6}$$

$$= 0 + [0 + 2 \times 0.0025 + 2 \times 0.00025 + 0.01] * 0.1$$

$$= 0.000833 //$$

for 2nd iteration we have

$$x_i^0 = 0 \cdot 1, y_i^0 = 0 \cdot 000333$$

$$\text{Then, } m_1 = f(0 \cdot 1, 0 \cdot 000333) \\ = 0 \cdot 01_{11}$$

$$m_2 = f(x_i^0 + h/2, y_i^0 + m_1 * h/2) \\ = f(0 \cdot 15, 0 \cdot 000833) \\ = 0 \cdot 023_{11}$$

$$m_3 = f(x_i^0 + h/2, y_i^0 + m_2 * h/2) \\ = f(0 \cdot 15, 0 \cdot 001483) \\ = 0 \cdot 023_{11}$$

$$m_4 = f(x_i^0 + h, y_i^0 + m_3 * h) \\ = f(0 \cdot 2, 0 \cdot 002688) \\ = 0 \cdot 04_{11}$$

Then,

$$y_{0 \cdot 2} = y_i^0 + \frac{(m_1 + 2m_2 + 2m_3 + m_4) * h}{6} \\ = 0 \cdot 000333 + \frac{(0 \cdot 01 + 2 \times 0 \cdot 023 + 2 \times 0 \cdot 023 + 0 \cdot 04) \times 0 \cdot 1}{6} \\ = 0 \cdot 002699667$$

For 3rd iteration we have

$$x_i^0 = 0 \cdot 2, y_i^0 = 0 \cdot 002699667,$$

Then,

$$m_1 = f(0 \cdot 2, 0 \cdot 002699667) \\ = 0 \cdot 04_{11}$$

$$m_2 = f(x_i^0 + h/2, y_i^0 + m_1 * h/2) \\ = f(0 \cdot 21, 0 \cdot 003099667) \\ = 0 \cdot 0441_{11}$$

$$\begin{aligned}
 m_3 &= f(x_i + h/2, y_i + m_2 \times h/2) \\
 &= f(0.21, 0.00314) \\
 &= 0.00441
 \end{aligned}$$

$$\begin{aligned}
 m_4 &= f(x_i + h, y_i + m_3 \times h) \\
 &= f(0.3, 0.0071) \\
 &= 0.00911
 \end{aligned}$$

$$\begin{aligned}
 \text{Then, } y_{0.3} &= y_i + \frac{(m_1 + 2m_2 + 2m_3 + m_4) \times h}{6} \\
 &= 0.004911
 \end{aligned}$$

Now for fourth iteration we have

$$x_i = 0.3, y_i = 0.0049$$

Then,

$$\begin{aligned}
 m_1 &= f(x_i, y_i) \\
 &= 0.00911
 \end{aligned}$$

$$\begin{aligned}
 m_2 &= f(x_i + h/2, y_i + m_1 \times h/2) \\
 &= 0.009611
 \end{aligned}$$

$$\begin{aligned}
 m_3 &= f(x_i + h/2, y_i + m_2 \times h/2) \\
 &= 0.009611
 \end{aligned}$$

$$\begin{aligned}
 m_4 &= f(x_i + h, y_i + m_3 \times h) \\
 &= 0.0116
 \end{aligned}$$

Then,

$$\begin{aligned}
 y_{0.4} &= y_i + \frac{(m_1 + 2m_2 + 2m_3 + m_4) \times h}{6} \\
 &= 0.0049 + 0.0109667 \\
 &= 0.0154666711
 \end{aligned}$$

System of Differential Equations

mathematical model or many application problems
a system of 1st order differential eqn which may be
represented as follows,

$$\frac{dy_1}{dx} = f_1(x, y_1, y_2, \dots, y_m) \quad y_1(x_0) = y_{10}$$

$$\frac{dy_2}{dx} = f_2(x, y_1, y_2, \dots, y_m) \quad y_2(x_0) = y_{20}$$

$$\vdots$$

$$\frac{dy_m}{dx} = f_m(x, y_1, y_2, \dots, y_m) \quad y_m(x_0) = y_{m0}$$

These eqns can be solved by any of the method
studied before for $y_1(x), y_2(x), \dots, y_m(x)$ over the
interval $[a, b]$. At each stage, all the equations are
solved before proceeding to the next stage. For examp
If $h = 0.5$ & $a = x_0 = 0$ then we must evaluate $y_{10.5},$
 $y_{20.5}, \dots, y_{m0.5}$ before proceeding to the next
stage $h = 1.$

Let us consider a system of two equations
for the purpose of illustration.

$$y_1'(x) = f_1(x, y_1, y_2), \quad y_1(x_0) = y_{10}$$

$$y_2'(x) = f_2(x, y_1, y_2), \quad y_2(x_0) = y_{20}$$

If we use Heun's method, The 1st stage
would involve the following calculations.

$$m_1(1) = f_1(x_0, y_{10}, y_{20})$$

$$m_2(2) = f_2(x_0, y_{10}, y_{20})$$

$$m_2(1) = f_1 [x_0 + h, y_{10} + h m_1(1), y_{20} + h m_1(2)]$$

$$m_2(2) = f_2 [x_0 + h, y_{10} + h m_1(1), y_{20} + h m_1(2)]$$

Note:

$$m(1) = \frac{m_1(1) + m_2(1)}{2}$$

$$m(2) = \frac{m_1(2) + m_2(2)}{2}$$

$$y_1(x_1) = y_1(20) = y_{10} + m(1)h \\ = y_{10} + m(1)h$$

$$y_2(x_1) = y_2(1) = y_{20} + m(2)h$$

The next stage uses $y_1(1)$ & $y_2(1)$ as initial values of y_1 & y_2 by following similar procedure, $y_1(2)$ & $y_2(2)$ can be obtained.

- B. Given the equation $\frac{dy_1}{dx} = x + y_1 + y_2, y_1(0) = 1$
 $\frac{dy_2}{dx} = 1 + y_1 + y_2, y_2(0) = -1$
 estimate the values of $y_1(0.2)$ & $y_2(0.1)$ using Heun's method.

Soln,

$$\text{Given } x_0 = 0, y_{10} = 1$$

$$y_{20} = -1$$

Then, initial condition & method gives

$$\begin{aligned} m_1(1) &= f_1(x_0, y_{10}, y_{20}) \\ &= f(0, 1, -1) \\ &= 0 \end{aligned}$$

$$\begin{aligned}m_1(2) &= f_2(x_0, y_{10}, y_{20}) \\&= f_2(0, 1, -1) \\&= 1_{11}\end{aligned}$$

$$\begin{aligned}m_2(2) &= f_1(x_0 + h, y_{10} + hm_1(1), y_{20} + hm_1(2)) \\&= f_1(0 + 0 \cdot 1, 1 + 0 \cdot 1 \times 0 + (-1) + 0 \cdot 1 \times 1) \\&= f_1(0 \cdot 1, 1, -0 \cdot 9) \\&= 0 \cdot 2_{11}\end{aligned}$$

$$\begin{aligned}m_2(2) &= f_2(x_0 + h, y_{10} + hm_1(1), y_{20} + hm_1(2)) \\&= f_2(0 + 0 \cdot 1, 1 + 0 \cdot 1 \times 0 + -1 + 0 \cdot 1 \times 1) \\&= f_2(0 \cdot 1, 1, -0 \cdot 9) \\&= 1 \cdot 1_{11}\end{aligned}$$

Now,

$$\begin{aligned}m(1) &= \frac{m_1(1) + m_2(1)}{2} \\&= \frac{0 + 0 \cdot 2}{2}\end{aligned}$$

$$= 0 \cdot 1$$

$$\begin{aligned}m(2) &= \frac{m_1(2) + m_2(2)}{2} \\&= \frac{1 + 1 \cdot 1}{2} \\&= 1 \cdot 05_{11}\end{aligned}$$

Then,

$$\begin{aligned}y_1(x_1) &= y_{10} + m(1)h \\&= y_{10} + m(1)h \\&= 1 + 0 \cdot 1 \times 0 \cdot 1 \\&= 1 \cdot 01_{11}\end{aligned}$$

$$\begin{aligned}y_2(x_1) &= y_{20} + m(2)h \\&= -1 + 1.08 \times 0.1 \\&= -0.895\end{aligned}$$

Higher order difference equation.

Higher order difference equation.
 It is in the form $\frac{d^m y}{dx^m} = f(x, y, \frac{dy}{dx}, \frac{d^2y}{dx^2}, \dots)$

with m initial conditions given as,

$$y(x_0) = a_1$$

$$y'(x_0) = 0_2$$

$$y^{m+1}(x_0) = 0_m$$

We replace eqn ① by a system of 1st order equations as follows.

Let us denote $y = y_1$, $\frac{dy}{dx} = y_2$, $\frac{d^2y}{dx^2} = y_3$,

$$\frac{d^{m-1}y}{dx^{m-1}} = y_m$$

phon.

$$\frac{dy_1}{dx} = y_2, \quad y_1(x_0) \approx y_{10} = q_1$$

$$\frac{dy_2}{dx} = y_3, \quad y_2(x_0) = y_{20} = q_2$$

$$\frac{dy_{m-1}}{dx} = y_m, \quad y_{m-1}(x_0) = y_{m-1,0} = q_{m-1}$$

$$\frac{dy_m}{dx} = f(x, y_1, y_2, \dots, y_m)$$

$$\frac{d^2y}{dx^2}$$

Q Solve the following eq'n for $y(0.2)$ $\frac{d^2y}{dx^2} + \frac{2}{dx} dy - 3y = 6x$

given $y(0) = 0$, $y'(0) = 1$

Soln,

$$\frac{d^2y}{dx^2} = 6x + 3y - \frac{2}{dx} dy$$

$$y = y_1, \quad \frac{dy}{dx} = y_2$$

$$\text{then } \frac{dy_1}{dx} = y_2, \quad y_{10} = 0$$

$$\frac{dy_2}{dx} = 6x + 3y - 2y_2, \quad y_{20} = 1$$

let $h = 0.2$,

$$m_1(1) = y_{20} = 1$$

$$\begin{aligned} m_1(2) &= 6x_0 + 3y_{10} - 2y_{20} \\ &= 6 \cdot 0 + 3 \times 0 - 2 \times 1 \\ &= -2 \end{aligned}$$

$$\begin{aligned} m_2(1) &= y_{20} + hm_1(2) \\ &= 1 + 0.2 \times -2 \\ &= 0.6 \end{aligned}$$

$$\begin{aligned} m_2(2) &= 6x_0 f(0.2, 0.2, 0.6) \\ &= 0.6 \end{aligned}$$

$m_1(0.2)$
 $(x_0 + h, y_0 + hm_1(1))$
 $, y_{20} + hm_2(2)$

Then,

$$m(1) = \frac{m_1(1) + m_2(2)}{2}$$

$$= \frac{1 + 0.6}{2}$$

$$= 0.8$$

$$= 0.8$$

$$m(2) = \frac{m_2(2) + m_2(2)}{2}$$

$$= \frac{-2+0.6}{2}$$

$$= -0.71$$

Boundary value problems.

It is seen previously that to solve m order differential equation, we require m conditions to be specified when all m conditions were specified at one point, $x = x_0$, and, therefore, we called this problem as an initial value problem.

It is not always necessary to specify a condition at one point of the independent variable. They may be specified at different points in the interval (a, b) and, therefore, such problems are called boundary value problems.

In solving initial value problem, we move in steps from the given initial value of x to the point where soln. is required.

In case of boundary value problem we seek solutions at specified points within the domain of given boundaries. For instance,

$$\frac{d^2y}{dx^2} = f(x, y, y') , \quad y(a) = y_a, \quad y(b) = y_b$$

We are interested in finding the value of y in the range $a \leq x \leq b$. There are two popular methods available for solving the boundary value problem.

(a) shooting method.

(b) finite difference method.

(a) shooting method.

In this method, the given boundary value problem is first transformed to an initial value problem, then this initial value problem is solved by Taylor series method or Runge Kutta method etc. finally the given boundary value problem is solved.

consider the equation:

$$y' = f(x, y, y')$$

$$y(a) = A, \quad y(b) = B$$

by letting $y' = z$ we obtain the following set of two eq's.

$$y' = z$$

$$z' = f(x, y, z)$$

In order to solve this set as an initial value problem we need two condition at $x=a$. We have one condition i.e. $y(a) = A$

and, therefore, required another condition for z at $x=a$. let us assume that,

$$z(a) = m_1,$$

where m_1 is a guess.

Note that m_1 represents the slope.

$$y'(x) \text{ at } x=a$$

Thus the problem is reduced to a system two first order equations, with the initial conditions

$$y' = z \quad y(a) = A$$

$$\cancel{z} = f(x, y, z) \quad z(a) = m_1 (= y'(a)) \dots \textcircled{1}$$

The above can $\textcircled{1}$ can be solved for y , and z using any one step method, using step of h , until the solution at $x=b$ is reached.

let the estimated value of $y(x)$ at $x=b$ be

B₁. If B₁ = B then we have obtained the required soln.

If B₁ ≠ B, then we obtain the soln with another guess say

Z(a) = m₂. let the new estimate of $y(x)$ at $x=b$ be B₂.

If B₂ ≠ B, then the process may be continued until we obtain the correct estimate of $y(b)$.

However The procedure can be accelerated by using an improved guess Z(a), after the

estimates of B_1 & B_2 are obtained.

Let us assume that $y(a) = m_3$ leads to the value of $y(b) = B$. If we assume that the value of m and B are linearly related then, $\frac{m_3 - m_2}{B - B_2} = \frac{m_2 - B_1}{B_2 - B_1}$

$$\begin{aligned} \text{So } m_3 &= m_2 + \frac{B - B_2}{B_2 - B_1} \times m_2 - m_1 \\ &= m_2 - \frac{B_2 - B}{B_2 - B_1} \times m_2 - m_1 \quad \dots \text{(2)} \end{aligned}$$

Now (with $y(a) = m_3$) we can again obtain the soln

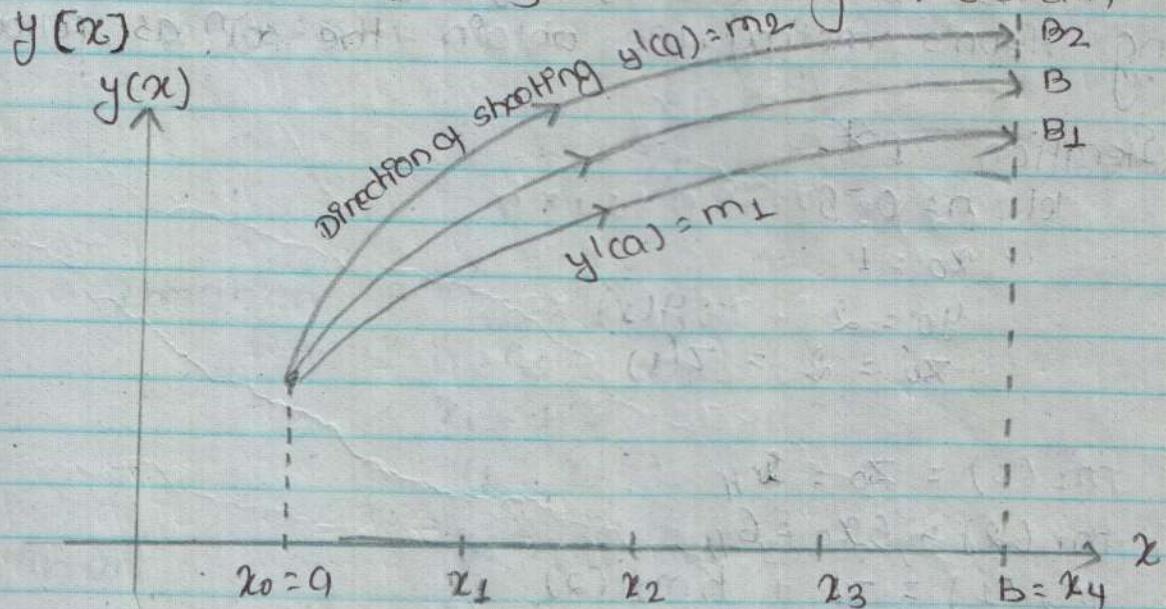
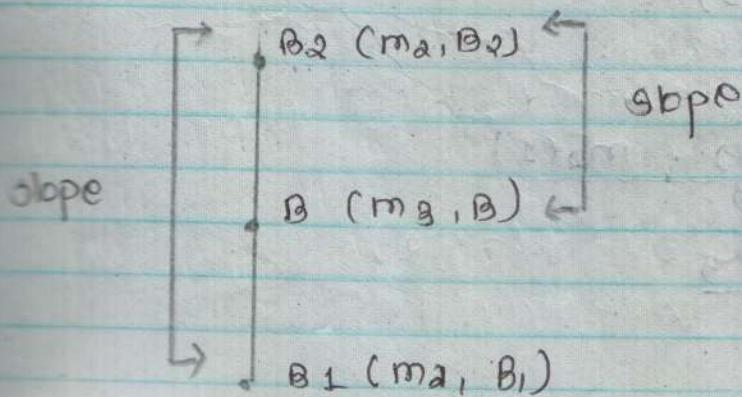


fig: Illustration of shooting method.



(0.75) 3.25

Q1 using shooting method solve the equation $\frac{d^2y}{dx^2} = 6x$
 $y(1) = 2$ $y(2) = 9$

Soln,

By transformation we obtain the following,

$$f_1 = \frac{dy}{dx} = z, \quad y(1) = 2$$

$$f_2 = \frac{dz}{dx} = 6x$$

Let us assume that $z(1) = y'(1) = 2 (= m_1)$
Applying Heun's method we obtain the soln as following,

Iteration 1st.

$$\text{let } h = 0.5$$

$$x_0 = 1$$

$$y_0 = 2 = y(1)$$

$$z_0 = 2 = z(1)$$

$$m_1(1) = z_0 = 2$$

$$m_1(2) = 6x_0 = 6$$

$$m_2(1) = z_0 + hm_1(2)$$

$$= 2 + 0.5 * 6$$

$$= 5$$

$$m_2(2) = 6(x_0 + h)$$

$$= 6(1 + 0.5)$$

$$= 9$$

$$m(1) = \frac{m_1(1) + m_2(1)}{2}$$

$$= \frac{2 + 5}{2}$$

$$= 3.5$$

$$\begin{aligned}
 m(2) &= \frac{m_1(2) + m_2(2)}{2} \\
 &= \frac{6+9}{2} \\
 &= 7.5,
 \end{aligned}$$

Now,

$$\begin{aligned}
 y(1.5) &= y_0 + m_1 * h \\
 &= 2 + 3.05 * 0.5 \\
 &= 3.075 = y_1
 \end{aligned}$$

$$\begin{aligned}
 z(1.5) &= z(1) + m_2 * h \\
 &= 8 + 7.05 * 0.5 \\
 &= 5.075 = z_1
 \end{aligned}$$

Iteration 2nd:

$$h = 0.5$$

$$x_1 = 1.05$$

$$y_1 = 3.075$$

$$z_1 = 5.075$$

Then

$$m_1(1) = z_1 = 5.075$$

$$m_1(2) = 6x_1 = 6 \times 1.05 \approx 9$$

$$\begin{aligned}
 m_2(1) &= z_1 + hm_1(2) \\
 &= 5.075 + 0.5 \times 9 \\
 &= 10.25
 \end{aligned}$$

$$m_2(2) = 6(x_1 + h)$$

$$\begin{aligned}
 &= 6(1.05 + 0.5) \\
 &= 12
 \end{aligned}$$

Now,

$$m(1) = \frac{m_1(1) + m_2(1)}{2}$$

$$= \frac{50.75 + 10.25}{2}$$

$$= 81$$

$$m(2) = \frac{m_1(2) + m_2(2)}{2}$$

$$= \frac{9 + 12}{2}$$

$$= 10.5$$

Now,

$$y(2) = y_1 + m(1) \times h$$

$$= 90.75 + 8 \times 0.5$$

$$= 90.75$$

$$z(2) = z_1 + m(2) \times h$$

$$= 50.75 + 100.5 \times 0.5$$

$$= 111$$

This gives $B_1 = 90.75$ which is less than $B = 9$
Now, let us assume,

$$z(1) = y'(1) = 4 (= m_2)$$

Applying Heun's method we obtain the soln as
following:

Iteration 1st,

$$\text{let } h = 0.5, x_0 = 1, y_0 = 2, z_0 = 4$$

then,

$$m_1(1) = z_0 = 4$$

$$m_2(1) = 6x_0 = 6 \times 1 = 6$$

$$\begin{aligned} m_2(1) &= z_0 + hm_1(1) \\ &= 4 + 0.5 \times 6 \\ &= 7.5 \end{aligned}$$

$$\begin{aligned} m_2(2) &= 6(x_0 + h) \\ &= 6(1 + 0.5) \\ &= 9 \end{aligned}$$

$$\begin{aligned} \text{Then } m_1 &= \frac{m_1(1) + m_2(1)}{2} \\ &= \frac{4 + 7.5}{2} \\ &= 5.75 \end{aligned}$$

$$\begin{aligned} m_2 &= \frac{m_2(1) + m_2(2)}{2} \\ &= \frac{6 + 9}{2} \\ &= 7.5 \end{aligned}$$

Now

$$\begin{aligned} y(1.05) &= y_0 + m_1(1) \times h \\ &= 2 + 5.75 \times 0.5 \\ &= 4.75 \end{aligned}$$

$$\begin{aligned} z(1.05) &= z_0 + m_2(2) \times h \\ &= 4 + 7.5 \times 0.5 \\ &= 7.75 \end{aligned}$$

Iteration 2nd.

$$h = 0.5, x_1 = 10s, y_1 = 4075, z_1 = 7075$$

then

$$m_1(1) = z_1 = 7075$$

$$m_1(2) = 6x_1 = 6 \times 10s \\ = 9$$

$$m_2(1) = zg + hm_1(2) \\ = 7075 + 0.5 \times 9 \\ = 12025$$

$$m_2(2) = 6(xg + h) \\ = 6(10s + 0.5) \\ = 1211$$

then

$$m(1) = \frac{m_1(1) + m_2(1)}{2} \\ = \frac{7075 + 12025}{2} \\ = 10$$

$$m(2) = \frac{m_1(2) + m_2(2)}{2} \\ = \frac{9 + 1211}{2} \\ = 10.5$$

then

$$y(1.25) = y_1 + m(1)h \\ = 4075 + 10 \times 0.5 \\ = 4075$$

$$\begin{aligned} \text{Now we have, } B_1 &= 7.075 & m_1 &= 9 \\ B_2 &= 9.075 & m_2 &= 4 \\ B &= 9 \end{aligned}$$

then

$$\begin{aligned} m_3 &= m_2 + \frac{B - B_2}{B_2 - B_1} * m_2 - m_1 \\ &= 4 + \frac{9 - 9.075}{9.075 - 7.075} (4 - 2) \\ &= 4 + \left(\frac{-0.075}{2} \right) \times 2 \\ &= 4 + (-0.0375) \times 2 \\ &= 3.925 \parallel \end{aligned}$$

Now,

Iteration 3rd

$$h = 0.05 \quad x_0 = 1 \quad y_0 = 2, z_0 = 3.925$$

then,

$$m_1(1) = z_0 = 3.925$$

$$m_1(2) = 6x_0 = 6 \times 1 = 6$$

$$m_2(1) = z_0 + hm_1(2)$$

$$= 3.925 + 0.05 \times 6$$

$$= 6.025 \parallel$$

$$m_2(2) = 6(x_0 + h)$$

$$= 6(1 + 0.05)$$

$$= 6.3 \parallel$$

Then

$$m(1) = \frac{m_1(1) + m_2(1)}{2}$$

$$= \frac{3.2S + 6.2S}{2}$$

$$= 4.75$$

$$m(2) = \frac{m_1(2) + m_2(2)}{2}$$

$$= \frac{6 + 9}{2}$$

$$= 7.5$$

Now,

$$y(x) = y_0 + m(1)h$$
$$= 2 + 4.75 \times 0.5$$

$$= 4.75$$

&

$$z(x) = z_0 + m(2) \times h$$

$$= 3.2S + 7.5 \times 0.5$$

$$= 7.75$$

Algorithm for shooting method.

1. Convert the given problem into an initial value problem.
2. Initialize the variables including two guesses of the initial slope.
3. Solve the equations with these guesses using either a one step or a multi step method.
4. Interpolate from these results to find an improved value of the slope obtained.
5. Repeat the process until a specified accuracy in the final function value is obtained (or until a limit to the number of iteration is reached).

Eigenvalue & Eigenvector Problem.

Boundary value problems such as study of vibrating systems, structure analysis, electric circuit system analysis, reduce to a system of eqn of the form

$$Ax = \lambda x \quad \dots \dots \dots \quad (1)$$

such problems are called eigenvalue problem.

The solⁿ vector x corresponding to eigen values λ are called eigenvectors.

We need to find the value of λ and vector x which satisfies the eqn (1). We have two simple methods available to solve this type of problem:

(i) Polynomial method.

(ii) Power method.

Power method

It is a 'single value' method used for determine the 'dominant' eigen value of a matrix. It is an iterative method implemented using an initial starting vector x. It is implemented as,

$$Y = AX \quad \text{--- (2)}$$

$$X = \frac{1}{K} Y \quad \text{--- (3)}$$

The new value of X obtained from eqn (3) is used in eqn (2) to obtain a new value of Y , and the process is repeated until the desired level of accuracy is obtained.

The parameter K is known as the scaling factor & is the element of Y with the largest magnitude.

Let us assume that the eigen values are

$$|\lambda_1| > |\lambda_2| \geq \dots \geq |\lambda_n|$$

and the corresponding eigen vectors

$$v_1, v_2, \dots, v_n$$

after repetitive application of eqn (2) & (3)

the vector X converges to v_1 and K converges

to λ_1 .

Q) Find the largest eigen value & its corresponding eigen vector v_1 of the matrix

$$\begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

Using power method.

SOL,

let us assume the starting vector as

$$x = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Initial eqn (2) & (3) are repeatedly used as follows,

Iteration ①

$$y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix},$$

Now,

$$\begin{aligned} x &\approx \frac{1}{k} y \\ &= \frac{1}{2} \times \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 1 \\ \frac{1}{2} \\ 0 \end{bmatrix} \end{aligned}$$

Iteration ②

$$y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0.5 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 2.5 \\ 0 \end{bmatrix}$$

$$\begin{aligned} x &\approx \frac{1}{k} y \\ &= \frac{1}{2.5} \begin{bmatrix} 2 \\ 2.5 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0.8 \\ 1 \\ 0 \end{bmatrix} \end{aligned}$$

Iteration ③

$$Y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0.8 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2.8 \\ 2.6 \\ 0 \end{bmatrix}$$

$$\therefore x = \frac{1}{2.8} \begin{bmatrix} 2.8 \\ 2.6 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0.93 \\ 0 \end{bmatrix}$$

Iteration ④

$$Y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0.93 \\ 0 \end{bmatrix} = \begin{bmatrix} 2.86 \\ 2.93 \\ 0 \end{bmatrix}$$

$$\therefore x = \frac{1}{2.93} \begin{bmatrix} 2.86 \\ 2.93 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0.98 \\ 1 \\ 0 \end{bmatrix}$$

Iteration ⑤

$$Y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0.98 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2.98 \\ 2.96 \\ 0 \end{bmatrix}$$

$$x = \frac{1}{2.98} \begin{bmatrix} 2.98 \\ 2.96 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0.99 \\ 0 \end{bmatrix}$$

Iteration ⑥

$$y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0.99 \\ 0 \end{bmatrix} = \begin{bmatrix} 2.98 \\ 2.99 \\ 0 \end{bmatrix}$$

f

$$x = \frac{1}{2.99} \begin{bmatrix} 2.98 \\ 2.99 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Iteration ⑦

$$y = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 0 \end{bmatrix}$$

$$f(x) = \frac{1}{3} \times \begin{bmatrix} 3 \\ 3 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

The final answer shows that $\lambda_1 = 3$ (element with largest magnitude) & the corresponding eigen vector is the last x

$$\text{P}_1 e^{\lambda_1} x_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Solution of Partial Differential Equation.

It is a differential eq'n involving more than one independent variable. Mathematical model of many physical phenomena in applied science & engineering fall into a category of systems known as partial differential Equations.

For example,

- (i) Study of displacement of vibrating string.
- (ii) Heat flow problem.
- (iii) Fluid flow analysis.

most of these problems can be formulated as 2nd order partial differential eq'n's (with the highest order of derivative being the 2nd).

If we represent the dependent variable as f , & the two independent variables as x & y , then we will have three possible 2nd order partial derivatives,

$$\frac{d^2f}{dx^2}, \frac{d^2f}{dxdy}, \frac{d^2f}{dy^2}$$

In addition to two first order partial derivatives,

$$\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}$$

we can write a 2nd order eq'n involving two independent variables in general form

$$a \frac{d^2f}{dx^2} + b \frac{d^2f}{dxdy} + c \frac{d^2f}{dy^2} = p(x, y, f, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}) \quad (1)$$

where a, b & c may be constants or functions of x & y . Depending on the value of these coefficients there are three types of eq'n's.

$$b^2 - 4ac < 0 \quad (\text{elliptic curve})$$

$$b^2 - 4ac = 0 \quad (\text{parabolic curve})$$

$$b^2 - 4ac > 0 \quad (\text{hyperbolic curve})$$

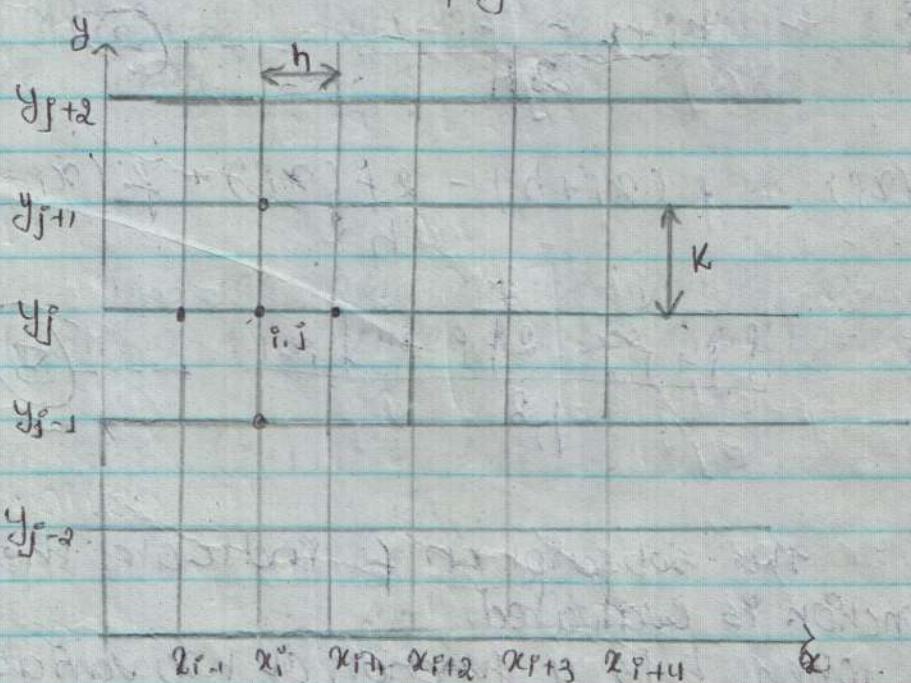
Since the application of analytical method becomes more complex, we seek the help of numerical technique to solve partial differential equation.

There are two types of numerical technique,

- ✓ ① finite difference method
- ② finite element method

Deriving difference equation

While deriving difference eqn, we will discuss two dimensional problems only, consider a two dimensional solution domain as shown in figure below.



(Refer fig - Two-dimensional finite difference grid.)

Here, the domain is split into regular rectangular grids of width h & height k . The pivotal value at the point of intersection (known as grid point or node) are denoted by $f_{i,j}$ which is a function of two space variables x & y .

In finite difference method, we write the difference eqn corresponding to each "grid point" & where derivative is required) using function values at the surrounding grid points. Solving these eqns simultaneously gives values for the function at each grid points.

If the function $f(x)$ has a continuous 4th derivative then its 1st & 2nd derivatives are given by the following central difference approximation-

$$f'(x_i^0) = \frac{f(x_{i+1}^0) - f(x_{i-1}^0)}{2h}$$

$$\text{or, } f'_i^0 = \frac{f_{i+1}^0 - f_{i-1}^0}{2h} \quad \dots \textcircled{2}$$

$$f''(x_i^0) = \frac{f(x_{i+1}^0) - 2f(x_i^0) + f(x_{i-1}^0)}{h^2}$$

$$\text{or, } f''_i^0 = \frac{f_{i+1}^0 - 2f_i^0 + f_{i-1}^0}{h^2} \quad \dots \textcircled{3}$$

The subscript on f indicates the n value where the function is evaluated,

when f is a function of two variables x, y , the partial derivative of f with respect to x (or y) are the ordinary derivative of f with respect to x (or y) when y (or x) does not change.

We use eqn $\textcircled{2}$ & $\textcircled{3}$ in x direction to determine derivatives with respect to x & in y direction to determine derivatives with respect to y . Thus we have,

$$\frac{\partial f(x_i, y_j)}{\partial x} = f_n(x_i, y_j) - \frac{f(x_{i+1}, y_j) - f(x_{i-1}, y_j)}{2h}$$

$$\frac{\partial f(x_i, y_j)}{\partial y} = f_y(x_i, y_j) = \frac{f(x_i, y_{j+1}) - f(x_i, y_{j-1})}{2h}$$

$$\frac{\partial^2 f(x_i, y_j)}{\partial x^2} = f_{xx}(x_i, y_j) = \frac{f(x_{i+1}, y_j) - 2f(x_i, y_j) + f(x_{i-1}, y_j)}{h^2}$$

f.

$$\frac{\partial^2 f(x_i, y_j)}{\partial y^2} = f_{yy}(x_i, y_j) = \frac{f(x_i, y_{j+1}) - 2f(x_i, y_j) + f(x_i, y_{j-1})}{h^2}$$

$$\frac{\partial^2 f(x_i, y_j)}{\partial x \partial y} = f_{xy}(x_i, y_j) = \frac{f(x_{i+1}, y_{j+1}) - f(x_{i+1}, y_{j-1}) - f(x_{i-1}, y_{j+1}) + f(x_{i-1}, y_{j-1})}{4h^2}$$

It is convenient to use double subscript i, j on f to indicate x & y values. Then the above eqn becomes,

$$f_{x, ij} = \frac{f_{i+1, j} - f_{i-1, j}}{2h} \dots \dots \dots \quad (4)$$

$$f_{y, ij} = \frac{f_{i, j+1} - f_{i, j-1}}{2h} \dots \dots \dots \quad (5)$$

$$f_{xx, ij} = \frac{f_{i+1, j} - 2f_{i, j} + f_{i-1, j}}{h^2} \dots \dots \dots \quad (6)$$

$$f_{yy, ij} = \frac{f_{i, j+1} - 2f_{i, j} + f_{i, j-1}}{h^2} \dots \dots \dots \quad (7)$$

$$f_{xy, ij} = \frac{f_{i+1, j+1} - f_{i+1, j-1} + f_{i-1, j+1} + f_{i-1, j-1}}{4h^2} \dots \dots \dots \quad (8)$$

We will use those above formula to construct various types of differential equations.

Elliptic Equations:

The two most commonly used elliptic eqⁿs are,

- (a) Laplace's Equation.
- (b) Poisson's equation.

(1) Laplace's Equation

The equation

$$a \frac{\partial^2 f}{\partial x^2} + b \frac{\partial^2 f}{\partial y^2} + c \frac{\partial^2 f}{\partial z^2} = f(x, y, z, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}),$$

when,

$$a=1, b=0 + c=1 \text{ and,}$$

$f(x, y, z, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}) = 0$ becomes.

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 0 = \nabla^2 f \quad \dots \quad (1)$$

The operator $\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$ is called the

Laplacian operator; and the eqⁿ (1) is called Laplace equation. (Sometimes it may be written in place of f). To solve Laplace equation on a region in xy plane we divide the region as shown in the above figure. (ODE)

Let us consider the portion of the region near (x_i^*, y_j^*) . We have to approximate

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 0$$

replacing the 2nd order derivatives by their finite difference equivalence (from eqn 8 + 7) at the point (x_i^o, y_j) , we obtain

$$\nabla^2 f_{ij} = \frac{f_{i+1,j} - 2f_{ij} + f_{i-1,j}}{h^2} + \frac{f_{i,j+1} - 2f_{ij} + f_{i,j-1}}{h^2} = 0$$

let us assume $h=1$ for simplicity,
we get,

$$\nabla^2 f_{ij} = \frac{1}{h^2} (f_{i+1,j} + f_{i-1,j} + 4f_{ij} + f_{i,j+1} + f_{i,j-1}) = 0 \quad \text{(10.)}$$

Note that eqn (10) contains four neighbouring points around the central points (x_i^o, y_j) (on all four sides) as shown in the figure below,

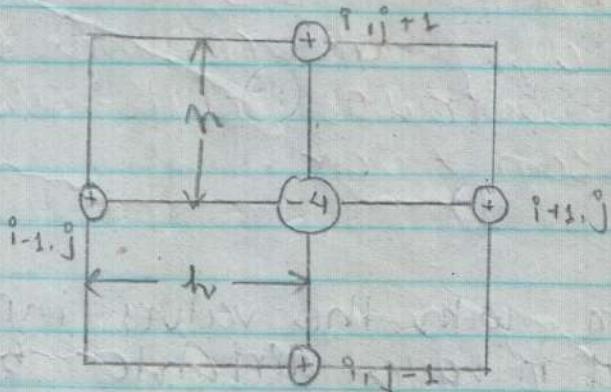


Fig - Grid for laplace equation.

The relationship of pivotal values are represented

$$\nabla^2 f_{ij} = \frac{1}{h^2} \left\{ 1 \quad -4 \quad 1 \right\} f_{ij} = 0 \quad \text{(11)}$$

from eqn ⑩ we can show that, the function value at the grid point (x_i, y_j) is the average of the values at the four adjoining points, i.e,

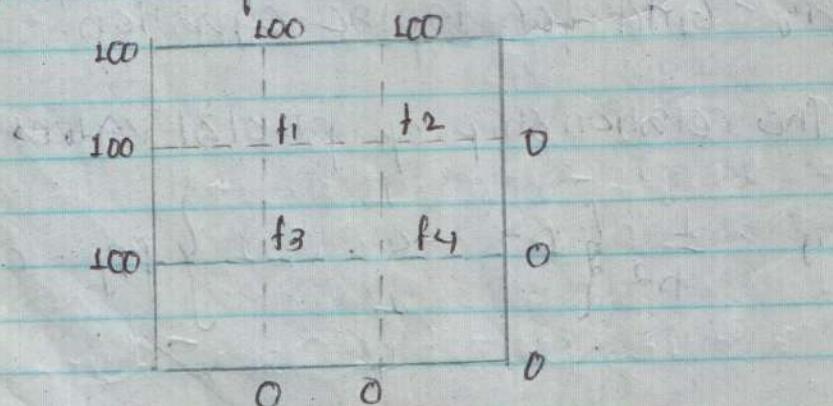
$$f_{ij} = \frac{1}{4} (f_{i+1,j} + f_{i-1,j} + f_{i,j+1} + f_{i,j-1}) \quad (12)$$

To evaluate numerically the soln of replace eqn at the grid points, we can apply eqn ⑫ at the grid points where f_{ij} is required. Thus obtaining a system of linear eqn in the pivotal values f_{ij} . The system of linear eqn may be solved using other direct method or iterative methods.

- Q. Consider a steel plate of size 15cm \times 15cm. If the two sides are held at 100°C & other two sides are held at 0°C , what are the steady state temperature at interior points, assuming a grid size of 5 cm \times 5cm.

2017

A problem with the values known on each boundary is said to have Dirichlet boundary condition. The problem is illustrated as follows.



The system of eqⁿ is as follows,

at point 1 (f_1)

$$f_2 + f_3 - 4f_1 + 100 + 100 = 0$$

at point 2 (f_2)

$$f_1 + f_3 - 4f_2 + 100 + 0 = 0$$

$f_1 = 15$
 $f_2 = 50$
 $f_3 = 50$
 $f_4 = 8$

at point 3 (f_3)

$$f_1 + f_4 - 4f_3 + 100 + 0 = 0$$

at point 4 (f_4)

$$f_2 + f_3 - 4f_4 + 0 + 0 = 0$$

Note,

By symmetry we can say that $f_2 = f_3$ so
the system of eqⁿ reduced to,

$$\begin{aligned} f_2 + f_2 - 4f_1 + 200 &= 0 \\ \text{i.e. } 2f_2 - 4f_1 + 200 &= 0 \end{aligned}$$

f_1

Poisson's Equation:-

The equation

$$a \frac{\partial^2 f}{\partial x^2} + b \frac{\partial^2 f}{\partial y^2} + c \frac{\partial^2 f}{\partial z^2} = F(x, y, z, f, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z})$$

when $a=1$

$b=0$

$$c=1 \text{ & } F(x, y, f, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}) = g(x, y)$$

becomes,

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = g(x, y)$$

or,

$$\nabla^2 f = g(x, y) \quad \dots \quad (13)$$

then thus eqⁿ (13) is called poisson's eqⁿ.

using the notation

$$g_{i,j} = g(x_i, y_j)$$

using eqⁿ (6) + (7) at point (x_i, y_j) we obtain,

$$f_{i+1,j} + f_{i-1,j} + f_{i,j+1} + f_{i,j-1} - 4f_{i,j} = h^2 g_{i,j} \quad \dots \quad (14)$$

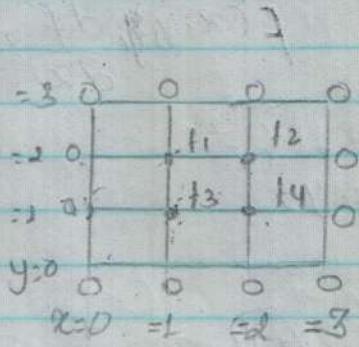
By applying the replacement formula to each grid point, in the domain of consideration, we will get a system of linear equations of $f_{i,j}$.

These equations may be solved either by any of the elimination method or by any iterative method as done in solving laplace eqⁿ.

Q solve the poisson's Eqⁿ

$\nabla^2 f = 2x^2y^2$ over the square domain
 $0 \leq x \leq 2$ & $0 \leq y \leq 1$ with $f = 0$ on the boundary
 $f \approx h = 1$.

Soln / the domain is divided into squares of 1 unit size as illustrated below.



at point 1 (f_1)

$$0 + 0 + f_2 + f_3 - 4f_1 = 12 \cdot 2x^2y^2$$

$$\text{or } f_1 + f_3 - 4f_1 = 2 \cdot 1 \cdot 2^2$$

$$\text{or } f_1 + f_3 - 4f_1 = 8$$

at point 2 (f_2)

$$\text{or } 0 + 0 + f_1 + f_4 - 4f_2 = 12 \cdot 2x^2y^2$$

$$\text{or } f_1 + f_4 - 4f_2 = 2 \cdot 2^2 \cdot 2^2$$

$$\text{or, } f_1 + f_4 - 4f_2 = 32$$

at point 3 (f_3)

$$0 + 0 + f_1 + f_4 - 4f_3 = 12 \cdot 2x^2y^2$$

$$\text{or, } f_1 + f_4 - 4f_3 = 1 \cdot 2 \cdot 1 \cdot 1$$

$$\text{or } f_1 + f_4 - 4f_3 = 2$$

at point f₄,

$$0 + 0 + f_2 + f_3 - 4f_4 = 2x^2y^2$$

$$\text{or } f_2 + f_3 - 4f_4 = 2 \cdot 2^2 \cdot 1$$

$$\text{or } f_2 + f_3 - 4f_4 = 8_{11}$$

$$\begin{aligned}f_1 &= -2\frac{1}{4} \\f_2 &= -4\frac{3}{4} \\f_3 &= -1\frac{3}{4} \\f_4 &= -2\frac{1}{4}\end{aligned}$$