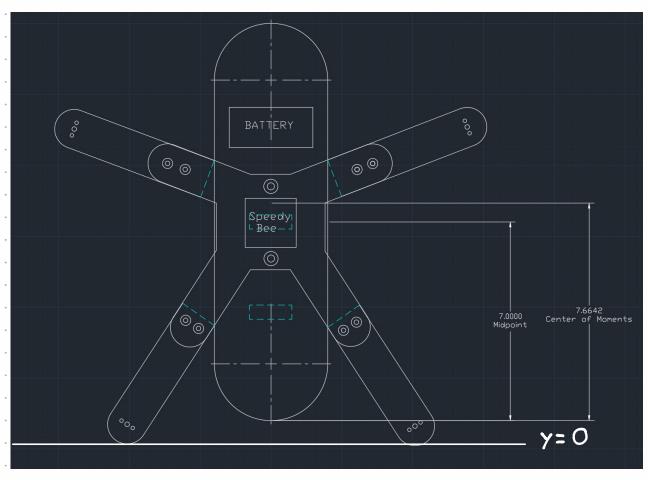
Centroid:

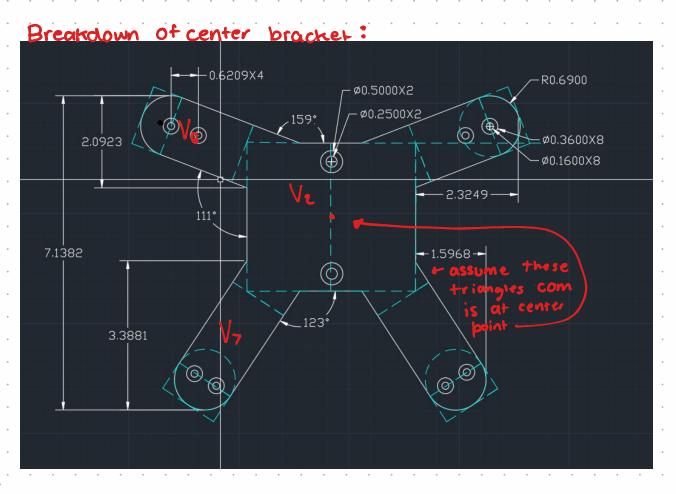
Names and dimensions from dwg file in media folder: units: inches this is an approximation that doesn't take into account the holes and treats the arms as rectangles.



Body: $V_1 = 10.4.0.5 + \pi(2)^2 \cdot 0.5 = 26.3 \text{ in}^3$

position: y= 7.88 in

Battery: V_3 : 2.95·1.42·2.2 = 9.22 in³ position: 11.2 in Speedy bee: V_4 : 1.73·18·0.31 = 0.97 in³ position: 7.88 in motor: V_5 = $TI(1.38/2)^2 \cdot 0.72 = 1.08 in³ position: 11.2 in$



Center bracket:

 V_2 : 3.83.36.0.25 + (0.66.1.02 + 0.38.0.58 + 1.14×0.44 + 0.94×0.36) 0.25 = 3.65 in³ position: 7.88in V_6 = 2×2.43.1.38.0.25 = 1.68in³ position: 9.77In V_7 = 2×2.89×1.38×0.25 = 1.99in³ position: 4.74 in

Arm 1: 1.38.5.7.0.25 = 1.97 in position: 10.34 in Arm 2: 5.29.1.38.0.25 = 1.83in position: 2.34 in

centroid = $\frac{\text{ZV-pos}}{\text{ZV}} = \frac{26.3 \cdot 7.88 + 9.22 \times 11.2 + 0.97 \times 7.88 + 1.08 \times 11.2 + 3.65 \times 7.88}{+ 1.68 \times 9.77 + 1.99 \times 4.74 + 1.97 \times 10.34 + 1.83 \times 2.34}$

centroid: y = 8.41 in