Assignment # 6: Problem Set 4, Problem 1 - Due 2/13/2013

y(n)

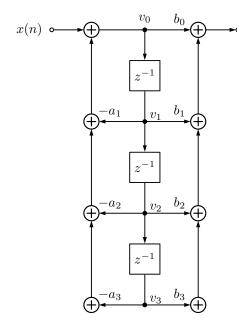


Figure 1: Shown to the left is the design of an "IIR direct form type II filter," described in Chapter 5 of the text. Design a program for the TMS 32C5x DSP, discussed in class, to implement this filter, using the format of the class examples. Data sample x(n) is to be read from an input port, and filter output y(n) is to be sent to an output port, as in the "Low Pass Filter" example in the class slides. The values a1, a2, a3, b0, b1, b2, b3 are constants, stored in program memory. Variables v0, v1, v2, v3 are to be stored in data memory. You may assume that all values are in the "proper format" to use for this calculation, as shown in the examples on the class slides. Submit the source program (typed or hand written). On the submitted program, show how you have the variables arranged and stored in memory.

$PS4_1.s$

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Brian Arnberg
       Problem Set #4 - Problem 1
       IIR direct form type II filter
  ; ;
         TMS 32C5x DSP
  ;;
    y(n) = b3*v3 + b2*v2 + b1*v1 + b0*v0
       v0 = x(n) - a3*v3 - a2*v2 - a1*v1
  ; ;
                  B3 = b3
                           B0 = b0
       A3 = -a3
       A2 = -a2
                  B2 = b2
       A1 = -a1
                  B1 = b1
13
         IN X0, PA0
                          read x(n) from PAO, set as XO
         ZAP
                          clear A and P
         ADD X0
                          A = A + X0
         MAC A3, v3
                          -a3*v3
         MAC A2, v2
                          -a2*v2
         MAC A1, v1
                          -a1*v1
         APAC
                          A = A + P
20
         SACH v0
                          save LSB to V0
21
         ZAP
22
                          clear A and P
         MAC B3, v3
                          b3*v3
23
         MACD B2, v2
                          +b2*v2, move v2 to v3
24
25
         MACD B1, v1
                          +b1*v1, move v1 to v2
                          +b0*v0, move v0 to v1
         MACD B0, v0
26
         APAC
                          A=A+P
27
         SACH Yn
                          save LSB
29
         OUT Yn, PA1
                          write y(n) to PA1
  31
32
33
      Program Memory
                          Data Memory
34
       A3 = -a3
                           X0
35
       A2 = -a2
                           V0
                                (low)
36
       A1 = -a1
                           V1
37
  ;;
       B0 = b0
                           V2
38
       B1 =
             b1
                           V3
39
                                (high)
  ; ;
       B2 =
             b2
40
  ;;
41
       B3 = b3
```