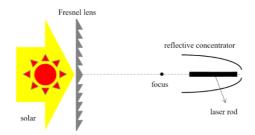


Ray Tracing Simulation of optically pumped Laser Crystals

Masters Project
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June 13, 2021



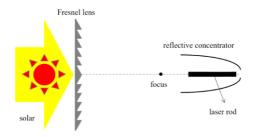




Problems to solve:

- Build a framework for physically accurate raytracing
- 2. Calculate absorbed power
- 3. Optimize mirror shape

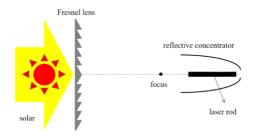




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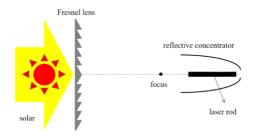




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Outline

Ray Tracing Basics

Scene Tracing

Sampling Techniques

Reflection and Refraction

Calculating Absorbed Power

Outlook for Masters Thesis



Ray Tracing Basics





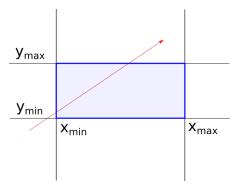
Parametrization

All points along a ray are described as follows:

$$r(t) = o + t \cdot d$$

Testing intersections against primitives involves solving for the parameter t.

Example: Axis aligned box intersection





Parametrization contd.

Solution:

```
float tx1 = (xmin - ray.origin.x) / ray.direction.x;
      float tx2 = (xmax - ray.origin.x) / ray.direction.x;
3
      float tmin = min(tx1, tx2):
4
      float tmax = max(tx1, tx2);
      float ty1 = (ymin - ray.origin.y) / ray.direction.y;
7
      float ty2 = (ymax - ray.origin.y) / ray.direction.y;
9
      tmin = max(tmin, glm::min(ty1, ty2));
10
      tmax = min(tmax, glm::max(ty1, ty2));
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```

Other primitives in 2D can be lines, cricles, etc. Or in 3D triangles, quads, spheres, etc.

All objects in a scene need to be built with a collection of such primitives.



Scene Tracing





Scene Tracing

If a ray hits an object new rays are genertated according to its type of surface (reflection, refraction).

These new rays are traced again through the scene.

⇒ Recurse until a desired "depth".

An object is intersected if one of its primitives is hit.

⇒ Need to check each primitive of every object in the scene.

Runtime of a scene tracing step with N objects with M primitives each:

$$O(N*M)$$



Hierarchical Bounding Volumes

Performance optimization:

Runtime of a scene tracing step with N objects with M primitives each and 5 recursive subdivisions:

$$O(N*(5*4+M/4^5)) = O(N*M/1024)$$



Hierarchical Bounding Volumes

Performance optimization:

- 1. Preprocessing: Attach a bounding box around each object and recursively subdivide.

Runtime of a scene tracing step with N objects with M primitives each and 5 recursive subdivisions:

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Hierarchical Bounding Volumes

Performance optimization:

- 1. Preprocessing: Attach a bounding box around each object and recursively subdivide.
- 2. Tracing: Check if ray hits bounding box. If yes recursively check its subdivisions.

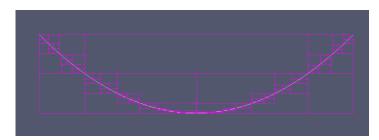
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Mirror

Mirror consists of 2D line segments arranged by a 1D shape function (parabolic for testing purposes).

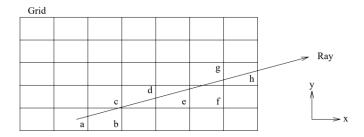




Crystal

The laser crystal is a 2D Box with an internal grid structure and grid tracing algorithm.

Rays need to be traced through cells in order¹ because of the absorbed energy calculation.



¹ A Fast Voxel Traversal Algorithm for Ray Tracing, John Amanatides, Andrew Woo, University of Toronto



Sampling Techniques

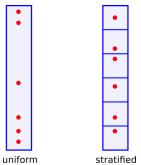




Generating Rays and Random Sampling

The goal is to randomly generate a cone of rays originating in the focus of the fresnel lense.

Uniformly sample the opening angle around a direction vector.



→ Not ideal in this case (big gaps between rays)

Better: Stratified Uniform Sampling



In reality sunlight consists of unpolarized light with a specific frequency spectrum. Thus the rays need to carry information about their power, frequency and polarity.

> Need mechanism to generate random samples x according to a given distribution density function p(x) (gauss, poisson, sun spectrum, etc.)

Inversion Method:



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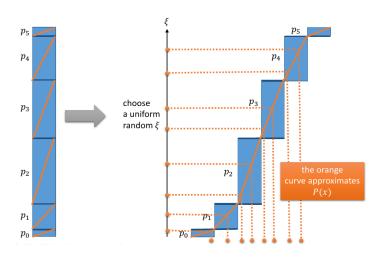
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- 2. Uniformly sample $\xi \in [0,1]$ and figure out in which interval it lies.
- 3. Interpolate linearly within the interval and return resulting x value.



Inversion Method contd.





Reflection and Refraction





Reflection

A ray is reflected by creating a new ray with the origin at the intersection point and the direction determined by the incident angle.

$$\theta_1 = \theta_2$$

where θ_1 is the incident angle and θ_2 is the reflection angle.

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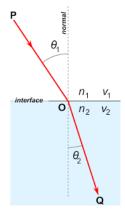


Refraction

Refraction is modelled accurately by Snells' law:

$$n_1\sin(\theta_1)=n_2\sin(\theta_2)$$

where n_1 , n_2 are the indices of refraction.





Fresnel Laws

The transmitted and reflected power can be calculated with the transmission- and reflection rates given by Fresnel's laws.

These are dependent on the orientation of the polarization of the incident ray (perpendicular or parallel) to the surface:

$$egin{aligned} R_{\perp} &= rac{\sin^2(heta_1 - heta_2)}{\sin^2(heta_1 + heta_2)} \ R_{\parallel} &= rac{ an^2(heta_1 - heta_2)}{ an^2(heta_1 + heta_2)} \ T_{\perp} &= 1 - R_{\perp} \end{aligned}$$



Fresnel Laws contd.

For now unpolarized light is assumed and only one refraction takes place so the total rates are:

$$R_{total} = rac{R_{\perp} + R_{\parallel}}{2}$$

$$T_{total} = \frac{T_{\perp} + T_{\parallel}}{2}$$

This will be changed in the future since in reality absorption in the crystal also depends on polarization.



Calculating Absorbed Power





Calculating Absorbed Power

The remaining power of a ray passing through the crystal is calculated by:

$$I_{out} = I_{in} \cdot e^{-\alpha d}$$

where α is the absorption coefficient d is the distance travelled through a cell. Thus the absorbed power is:

$$I_{abs} = I_{in} - I_{out}$$

In reality the α is frequency dependent but this is not implemented yet.

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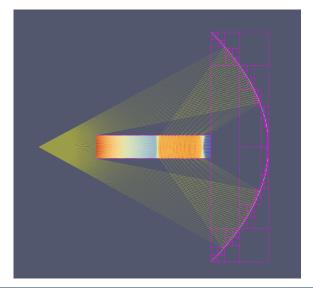


Outlook for Masters Thesis





Results







- 1. Implement custom distribution sampling
- Use frequency and polarity in raytracing/absorption
- 3. Make step to 3D or correct 2D values for 3D usage (transversal rays cannot be modelled).
- Optimize mirror shape using freeform shape functions
- Model the Fresnel lense and divergent sunlight



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Todo:

- Implement custom distribution sampling
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- 4. Optimize mirror shape using freeform shape functions

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5. Model the Fresnel lense and divergent sunlight

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Thanks for listening.

Any questions/suggestions?



References





References I

- [1] A. W. John Amanatides, A Fast Voxel Traversal Algorithm for Ray Tracing. [Online]. Available: https://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.42.3443&rep=rep1&type=pdf.
- [2] M. Stamminger, *Global Illumination SS21*. 2021. [Online]. Available: https://www.studon.fau.de/crs3792557.html.