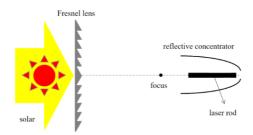


Ray Tracing Simulation of optically pumped Laser Crystals

Master's Thesis
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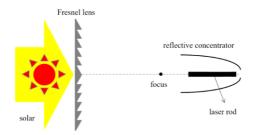






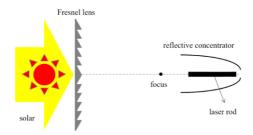
- Build a framework for physically accurate raytracing
- Calculate absorbed power
- 3. Optimize mirror shape





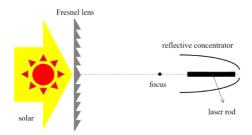
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Outline

Optics

Ray Tracing

Optimization

Results



Optics





Reflection

A ray is reflected by creating a new ray with the origin at the intersection point and the direction determined by the incident angle.

$$\theta_1 = \theta_2$$

where θ_1 is the incident angle and θ_2 is the reflection angle.

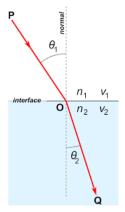


Refraction

Refraction is modelled accurately by Snells' law:

$$n_1\sin(\theta_1)=n_2\sin(\theta_2)$$

where n_1 , n_2 are the indices of refraction.





Fresnel Laws

The transmitted and reflected power can be calculated with the transmission- and reflection rates given by Fresnel's laws.

These are dependent on the orientation of the polarization of the incident ray (perpendicular or parallel) to the surface:

$$egin{aligned} R_{\perp} &= rac{\sin^2(heta_1 - heta_2)}{\sin^2(heta_1 + heta_2)} \ R_{\parallel} &= rac{ an^2(heta_1 - heta_2)}{ an^2(heta_1 + heta_2)} \ T_{\perp} &= 1 - R_{\perp} \ \end{aligned}$$



Fresnel Laws contd.

For now unpolarized light is assumed and only one refraction takes place so the total rates are:

$$R_{total} = rac{R_{\perp} + R_{\parallel}}{2}$$

$$T_{total} = rac{T_{\perp} + T_{\parallel}}{2}$$



Sellmeier Equation

Dependency of the refractive index on the wavelength of light is modelled using the Sellmeier equation.

$$n^2(\lambda) = 1 + \sum_i \frac{B_i \lambda^2}{\lambda^2 - C_i}$$

Here the B_i and C_i are empirically determined coefficients.



Ray Tracing



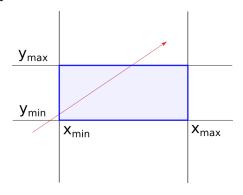


Parametrization

All points along a ray are described as follows:

$$r(t) = o + t \cdot d$$

Testing intersections against primitives involves solving for the parameter *t*. **Example:** Axis aligned box intersection





Parametrization contd.

Solution:

```
float tx1 = (xmin - ray.origin.x) / ray.direction.x;
      float tx2 = (xmax - ray.origin.x) / ray.direction.x;
3
      float tmin = min(tx1, tx2):
4
      float tmax = max(tx1, tx2);
      float ty1 = (ymin - ray.origin.y) / ray.direction.y;
7
      float ty2 = (ymax - ray.origin.y) / ray.direction.y;
9
      tmin = max(tmin, glm::min(ty1, ty2));
10
      tmax = min(tmax, glm::max(ty1, ty2));
11
```

Other primitives in 2D can be lines, cricles, etc. Or in 3D triangles, quads, spheres, etc.

All objects in a scene need to be built with a collection of such primitives.



Scene Tracing

If a ray hits an object new rays are genertated according to its type of surface (reflection, refraction).

These new rays are traced again through the scene.

⇒ Recurse until a desired "depth".

An object is intersected if one of its primitives is hit.

⇒ Need to check each primitive of every object in the scene.

Runtime of a scene tracing step with N objects with M primitives each:

$$O(N*M)$$



Hierarchical Bounding Volumes

Performance optimization:

Runtime of a scene tracing step with N objects with M primitives each and 5 recursive subdivisions:

$$O(N*(5*4+M/4^5)) = O(N*M/1024)$$



Hierarchical Bounding Volumes

Performance optimization:

- 1. Preprocessing: Attach a bounding box around each object and recursively subdivide.

Runtime of a scene tracing step with N objects with M primitives each and 5 recursive subdivisions:

$$O(N*(5*4+M/4^5)) = O(N*M/1024)$$



Hierarchical Bounding Volumes

Performance optimization:

- 1. Preprocessing: Attach a bounding box around each object and recursively subdivide.
- 2. Tracing: Check if ray hits bounding box. If yes recursively check its subdivisions.

Runtime of a scene tracing step with N objects with M primitives each and 5 recursive subdivisions:

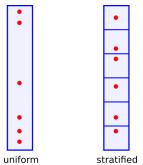
$$O(N*(5*4+M/4^5)) = O(N*M/1024)$$



Generating Rays and Random Sampling

The goal is to randomly generate a cone of rays originating in the focus of the fresnel lense.

Uniformly sample the opening angle around a direction vector.



⇒ Not ideal in this case (big gaps between rays)

Better: Stratified Uniform Sampling



In reality sunlight consists of unpolarized light with a specific frequency spectrum. Thus the rays need to carry information about their power, frequency and polarity.

> Need mechanism to generate random samples x according to a given distribution density function p(x) (gauss, poisson, sun spectrum, etc.)

Inversion Method:

Frequencies and polarisations of rays are not implemented as of yet.



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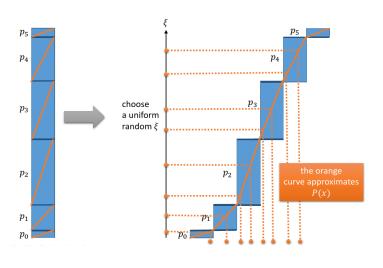
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- 1. Integrate(sum up) the distribution p(x) in uniform steps x and save the value for each step resulting in P(x).
- 2. Uniformly sample $\xi \in [0,1]$ and figure out in which interval it lies.
- 3. Interpolate linearly within the interval and return resulting x value.

Frequencies and polarisations of rays are not implemented as of yet.



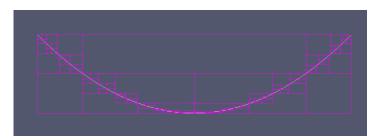
Inversion Method contd.





Mirror

Mirror consists of 2D line segments arranged by a 1D shape function (parabolic for testing purposes).

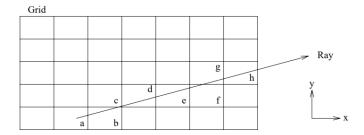




Crystal

The laser crystal is a 2D Box with an internal grid structure and grid tracing algorithm.

Rays need to be traced through cells in order¹ because of the absorbed energy calculation.



¹ A Fast Voxel Traversal Algorithm for Ray Tracing, John Amanatides, Andrew Woo, University of Toronto



Calculating Absorbed Power

The remaining power of a ray passing through the crystal is calculated by the Lambert law of absorption:

$$I_{out} = I_{in} \cdot e^{-\alpha d}$$

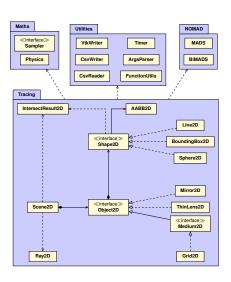
where α is the absorption coefficient d is the distance travelled through a cell. Thus the absorbed power is:

$$I_{abs} = I_{in} - I_{out}$$

In reality the α is frequency dependent but this is not implemented yet.



Framework Overview





Optimization



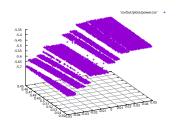


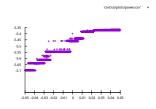
Problem

Goal: Optimize both total absorbed power and variance across the crystal

- ⇒ Should result in a better and more powerful beam (verification in ASLD)
- \Rightarrow Need an algorithm to handle two objective functions at the same time (biobjective optimization)

Additional problem: noisy and nonsmooth objective functions!





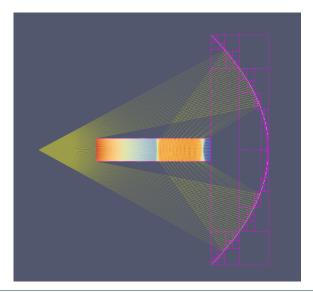


Results





Results





Outlook



Thanks for listening.

Any questions/suggestions?



References





References I

- [1] A. W. John Amanatides, A Fast Voxel Traversal Algorithm for Ray Tracing. [Online]. Available: https://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.42.3443&rep=rep1&type=pdf.
- [2] M. Stamminger, *Global Illumination SS21*. 2021. [Online]. Available: https://www.studon.fau.de/crs3792557.html.