```
Al record.py - C:/Users/DELL/Al record.py (3.11.9)
                                                                                   IDLE Shell 3.11.9
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class BlocksWorld:
                                                                                      Python 3.11.9 (tags/v3.11.9:de54cf5, Apr 2 2024, 10:12:12) [MSC v.1938 64]
    def init (self):
                                                                                      bit (AMD64)] on win32
        self.state = {
                                                                                      Type "help", "copyright", "credits" or "license()" for more information.
            "A": "B",
                                                                                  >>>
            "B": "table",
                                                                                      = RESTART: C:/Users/DELL/AI record.py
            "C": "table"
                                                                                      Initial State: {'A': 'B', 'B': 'table', 'C': 'table'}
        self.goal = {
                                                                                      Moving B from table to C
            "A": "B",
            "B": "C",
                                                                                      Final Goal State Reached: {'A': 'B', 'B': 'C', 'C': 'table'}
            "C": "table"
                                                                                  >>>
    def is goal state(self):
        return self.state == self.goal
    def move(self, block, destination):
        if block in self.state and self.state[block] != destination:
            print(f"Moving {block} from {self.state[block]} to {destination}")
            self.state[block] = destination
    def plan moves(self):
        print("\nInitial State:", self.state)
        while not self.is goal state():
            for block, target in self.goal.items():
                if self.state[block] != target:
                     self.move(block, target)
        print("\nFinal Goal State Reached:", self.state)
bw = BlocksWorld()
bw.plan moves()
```