(s, a)

(n)=1 = +(n)=1+e-4 -1/1+e+002689

92=3332

a2=0.43

olj = s(1 - sali)

DAns 9939615082

$$J = (y - a(2))^{2}$$
 $W = -1$ $a(2) = y = -1$
 $J(n) = \frac{1}{1 + \sigma n}$ $a(0) = 1$ $\alpha = 0.1$

$$\frac{\partial J}{\partial a_2} = 2(y - a(2))(-1) = -2(y - a_2)$$

$$\frac{\partial J}{\partial \omega_1} = \frac{\partial J}{\partial a_2} \cdot \frac{\partial a_2}{\partial \omega_1}$$

$$w'_1 = w_1 - \frac{\partial J}{\partial \omega_1}$$

$$a_2$$

$$\omega_{1}^{2} = \omega_{2} - \frac{\partial \omega_{1}}{\partial \omega_{2}}$$

$$\omega_{1}^{2} = 0.98611$$

$$a(0)$$
 w $a(0)$ w

$$\frac{101^{2}-0.018}{101} = -1.018$$

$$\frac{101^{2}-0.018}{101} = 0.18$$

$$\frac{1+(-1)=0}{101} = 0.18$$

Ankitha Kulkarni 3) And Anketha Kulkarni (2) Ans 9939615082 @ Y= (x, Vx2) 1 (~x31 x4), X; E {0,1} XXX (X XOR Y) @ Y= x, @x2 x: € {0, 1} XIXX2 XOR funct

(St. a1)

(3) Ans $0 = \{VS, VL\}$ VS & M L VL 9939615082 $A_1 = \begin{bmatrix} 0.7 & 0.3 \\ 0.3 & 0.7 \end{bmatrix}$ $B_1 = \begin{bmatrix} 0.1 & 0.2 & 0.2 & 0.2 & 0.3 \\ 0.2 & 0.1 & 0.4 & 0.1 & 0.2 \end{bmatrix}$ $B_2 = \begin{bmatrix} 0.5 & 0.5 \\ 0.5 & 0.5 \end{bmatrix}$ $B_2 = \begin{bmatrix} 0.1 & 0.1 & 0.1 & 0.6 \\ 0.5 & 0.1 & 0.1 & 0.1 & 0.2 \end{bmatrix}$ BY Deducing $P(x_1/0) \approx P(x_2/0)$ by $P(0/x_1)$, $P(0/x_2)$ using

He Deducing P(x1/0)& P(x2/0) by P(0/x1), P(0/x2) using Note = Tiche (Olvs)) xo(c)=0.03 = 0.03 X0(H)= 0.14 40(H)=0.35 «((c)= [«(()a(+ √(H)aH)) «, (c)=[«o(c)act « (H)aH) = 0.0189 6,0(vy) = 0.114 $x_1(H) = [x_{olc})a_{cH} + x_{olh}$ W/(H)=0.038 L'HH) by (du) P(0/2)=0.152 =0.0214

P(0/x,)=x,(c)+x,(H)

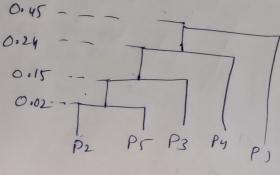
= 0.0403

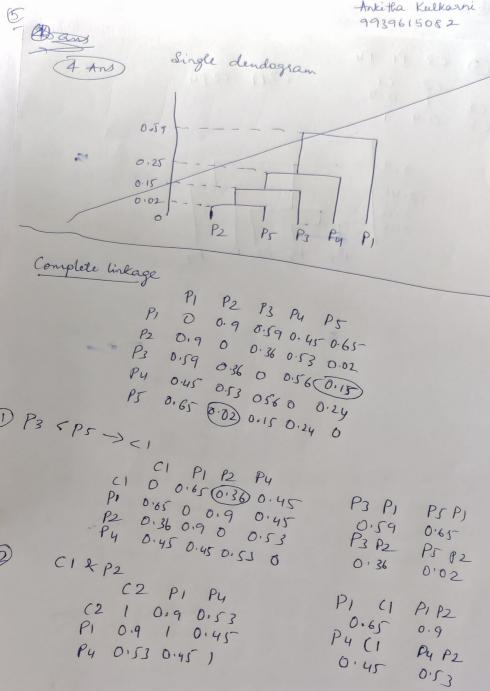
Comp P(0/x,) & P(0/x2) x2 the HMM in (b) would be
more likely to Co. 1. (1)

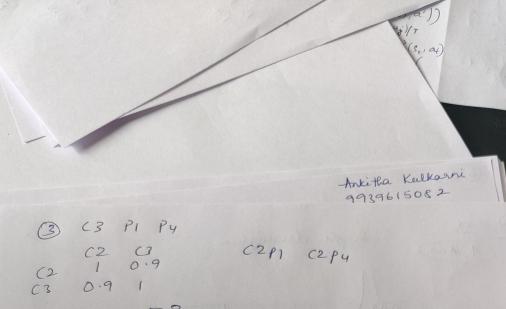
more likely to caude (VS, VI)

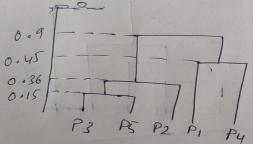
Port [0.08 x 0.3 + 0.14x 6.7) x 0.2 -0.0214

Ankitha Kulkarni 1 Aas Single lintage
PI P2 P2 P4 P Antitla Kultaeni P2 P3 P4 P5 9939615081 (P1, P2) = 0.10 7 P1 P2 P3 P4 P5 P1 0 P2 0.9 0 P3 0.59 0.36 0 P4 0.45 0.53 0.56 0 PS 0.65 0.02 0.15 0.24 0 (P2. Ps) cluster PI PZPS Py Py P, 0 P2 P5 0.65 0 (P2, P5), P3 P3 0.59 0.15 0 Py 0,45 0,24 0.56 0 P1 (P2 P5 P3) Py PI P2 PJ P3 P4 P, 0 2 PS P3 0.59 0 P2 P5 P3 P4 0.45 0 Py 0.45 0.24 0 0.45



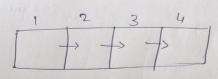








5 Ans



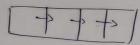
Ankitha Kulkarni 9939615082

Optimal policy is to move sight cell 1-4
For cell 1,

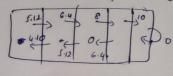
$$P_1 =$$
 Fimmediale + $V = 9i$
= 0 + 0.8 (0+0+10)
= 8

$$Q_2 = rinnediate + V = 9;$$

= 0 + 0.8(0 + 10)
= 8



We should start a way from leftwork to right most only and last state of is updated then we comptele walks again from left to right and pass & update the and state. Since the action to right is of max of value, coptimal of values stabilize to



5.12 > 6.4 -> 8 -> 10 -> 0