



Operating Systems

Lecture 17

S

Arturo Gangwar to Everyone 7:15 PM

```
Hello Sir , How are you doing??  
void RecordingReminder ()  
if (Recording == false)  
{  
    recording == true ;  
}  
else  
{  
    ignore this remainder ;  
}
```

Collapse All ^

😊 2

😂 8



understand the requirements to solve the

problem.

→ mutual exclusion

→ Progress

→ Bounded waiting.

A large, semi-transparent watermark of the "GO CLASSES" logo is centered on the slide. The logo consists of a large, stylized 'G' with horizontal lines through it, followed by the words "GO CLASSES" in a large, bold, black font.



Critical-Section Problem Solution

A solution to the critical-section problem must satisfy the following three requirements:

1. **Mutual exclusion.** If process P_i is executing in its critical section, then no other processes can be executing in their critical sections.
2. **Progress.** If no process is executing in its critical section and some processes wish to enter their critical sections, then only those processes that are not executing in their remainder sections can participate in deciding which will enter its critical section next, and this selection cannot be postponed indefinitely.
3. **Bounded waiting.** There exists a bound, or limit, on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted.

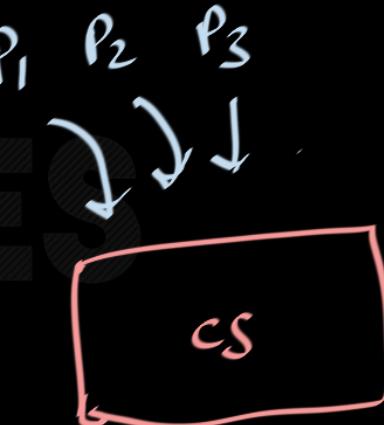
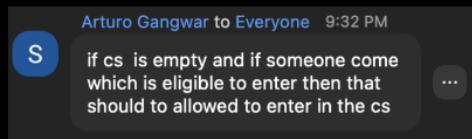
Source: Galvin



Progress. If no process is executing in its critical section and some processes wish to enter their critical sections, then only those processes that are not executing in their remainder sections can participate in deciding which will enter its critical section next, and this selection cannot be postponed indefinitely.

↳ multiple

- Progress : there should be some Progress in critical section
- if p_1 wants to enter in CS, and no one else wants to enter in CS then p_1 should get entered.
 - if multiple process wants to enter then AT LEAST one should get enter (in other words no deadlock)



Progress. If no process is executing in its critical section and some processes wish to enter their critical sections, then only those processes that are not executing in their remainder sections can participate in deciding which will enter its critical section next, and this selection cannot be postponed indefinitely.



Progress. If no process is executing in its critical section and some processes wish to enter their critical sections, then only those processes that are not executing in their remainder sections can participate in deciding which will enter its critical section next, and this selection cannot be postponed indefinitely.



Only P_2, P_3 decides who will go in cs next.
 $(P_1$ won't)



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Remainder section

→ i don't want p_i to re enter immediately

to CS while others are waiting.

→ if others are not waiting then i should
allow to re enter immediately. } S

Bounded waiting. There exists a bound, or limit, on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted.

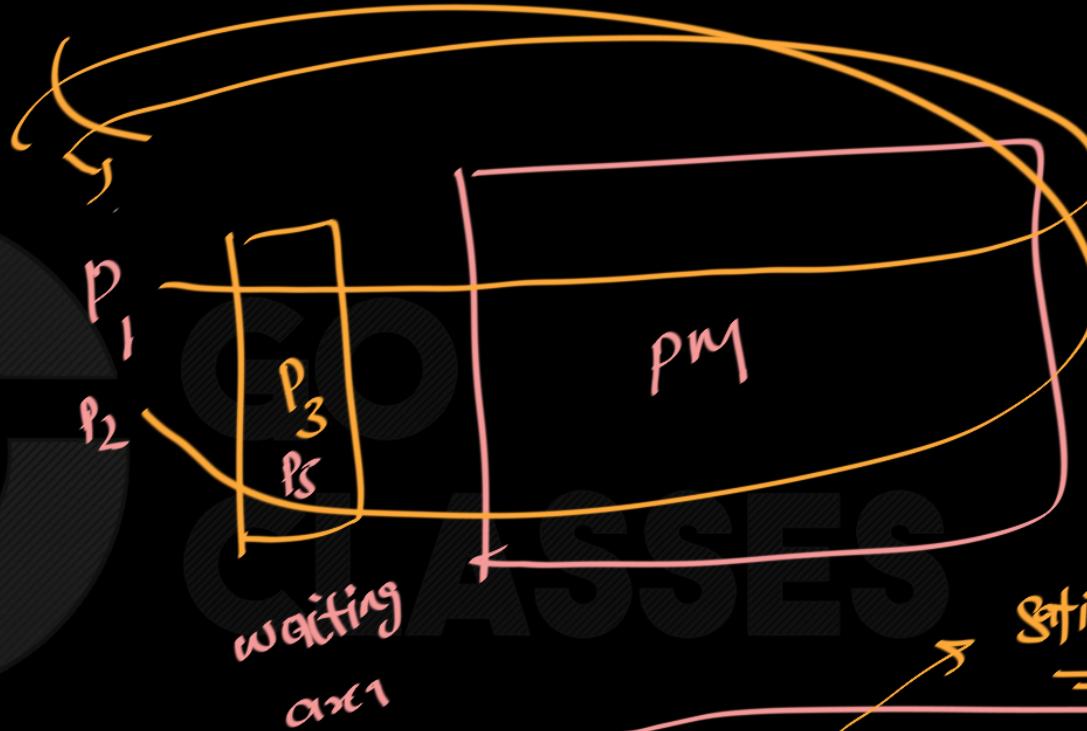
→ it is in the waiting area

1 process \Rightarrow final



P_3

n processes



P_1

P_2

P_3

P_4

waiting
area

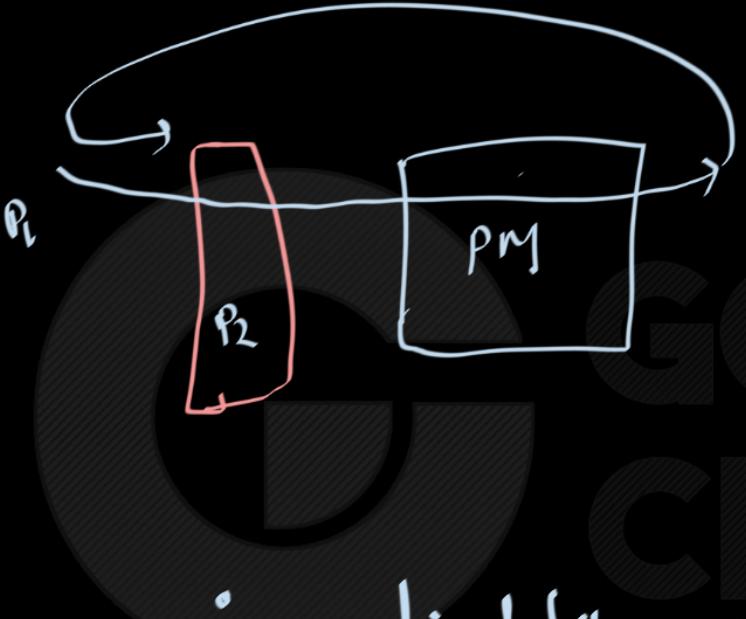
PM

satisfy B10



P_i

after 5 processes



⇒ Re-enter immediately won't be the issue to
BW if we are giving a guarantee on the
no. of times it can re-enter immediately (or sequentially)

in layman terms

- 1) ME : allow at most one
- 2) Progress: allow at least one
- 3) BW : Re-enter immediately is not possible
(you can reenter but there should be a bound)



That's ok,

but how to solve questions ?

{ V executions satisfied then it is acceptable solution

ME, Progress, and BW is

we want to come up with some set of rules
that covers all possibilities.



How to check these three in questions ?

1. Mutual exclusion

2. Progress (== absence of deadlock)

3. Bounded waiting (== fairness)



1. Mutual exclusion

- a. One process in critical section, another process tries to enter → Show that second process will block in entry code
- b. Two (or more) processes are in the entry code → Show that at most one will enter critical section

2. Progress (== absence of deadlock)

- a. No process in critical section, P1 arrives → P1 enters
- b. Two (or more) processes are in the entry code → Show that at least one will enter critical section

3. Bounded waiting (== fairness)

One process in critical section, another process is waiting to enter → show that if first process exits the critical section and attempts to re-enter, show that waiting process will be get in



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1. Mutual exclusion

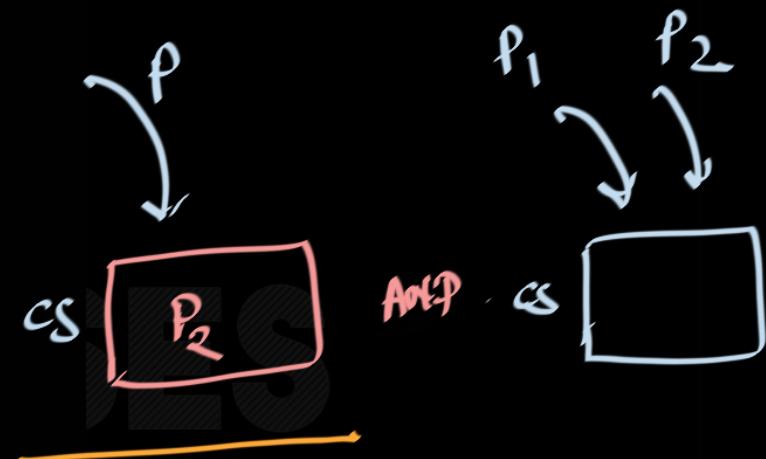
- One process in critical section, another process tries to enter → Show that second process will block in entry code
- Two (or more) processes are in the entry code → Show that at most one will enter critical section

2. Progress (== absence of deadlock)

- No process in critical section, P1 arrives → P1 enters
- Two (or more) processes are in the entry code → Show that at least one will enter critical section

3. Bounded waiting (== fairness)

One process in critical section, another process is waiting to enter → show that if first process exits the critical section and attempts to re-enter, show that waiting process will be get in





Implementation: First try (remember . . .)

Shared variables:

```
int count=0;  
int busy=0;
```

Thread 1:

```
while(busy);  
busy=1;  
count++;  
busy=0;
```

Thread 2:

```
while(busy);  
busy=1;  
count++;  
busy=0;
```



Operating Systems

Implementation: First try (remember ...)

Shared variables:

```
int count=0;  
int busy=0;
```

Thread 1:

```
while(busy);  
busy=1;  
count++; P1  
busy=0;
```

busy = 0;

initial setup

Thread 2:

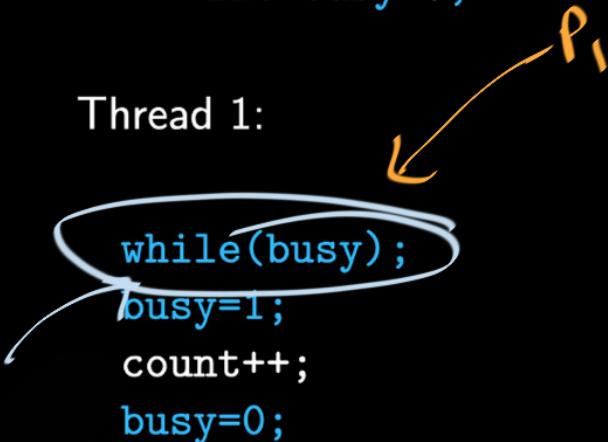
```
while(busy); P2  
busy=1;  
count++;  
busy=0;
```

for BWD

Shared variables:

```
int count=0;
int busy=0;
```

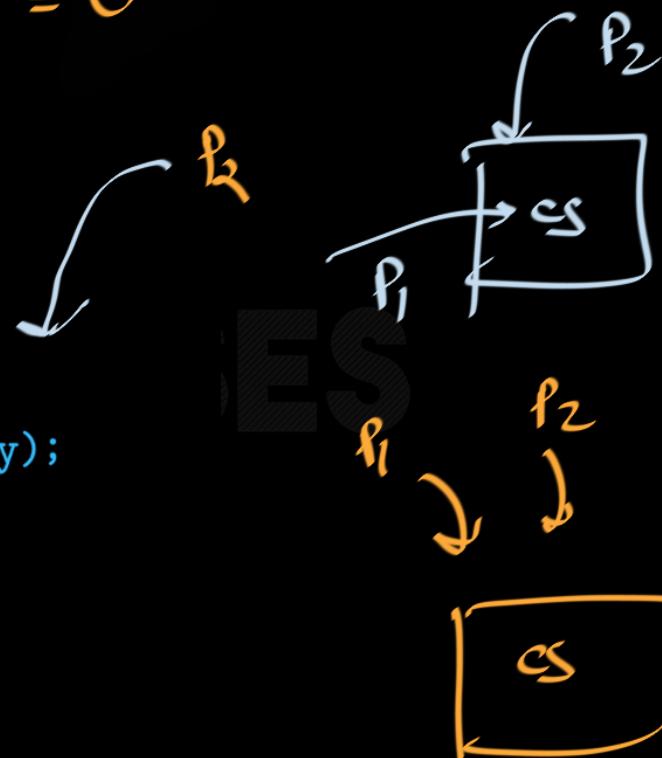
Thread 1:



Thread 2:

```
while(busy);
busy=1;
count++;
busy=0;
```

$busy = 0$



Shared variables:

```
int count=0;
int busy=0;
```

Thread 1:

```
while(busy);
busy=1;
count++;
busy=0;
```

inferred

Thread 2:

```
while(busy);
busy=1;
count++;
busy=0;
```

$busy = \cancel{P_1}^0$

ASSES

since P_1 can re-enter hence Bw is not satisfied

Shared variables:

```
int count=0;
int busy=0;
```

Thread 1:

```
while(busy);
busy=1;
count++;
busy=0;
```

Thread 2:

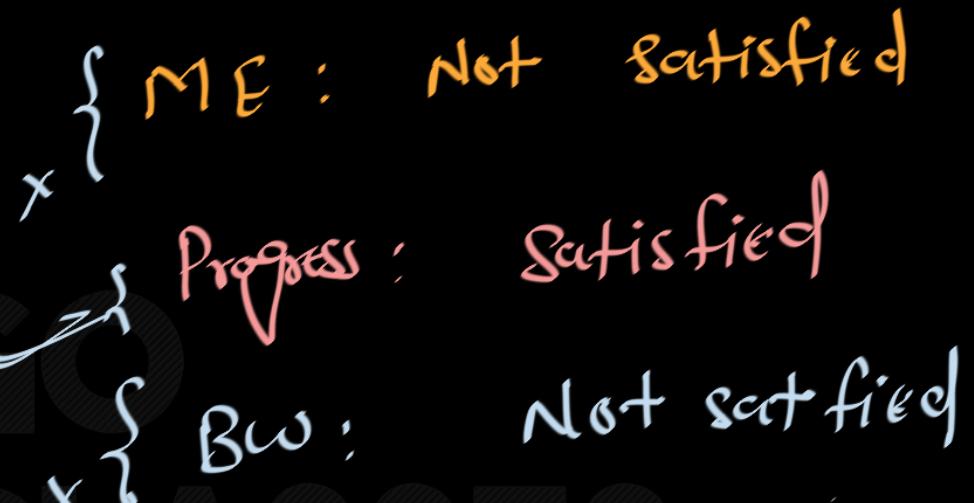
```
while(busy);
busy=1;
count++;
busy=0;
```

2. Progress (== absence of deadlock)

- No process in critical section, P1 arrives \rightarrow P1 enters
- Two (or more) processes are in the entry code \rightarrow Show that at least one will enter critical section

3. Bounded waiting (== fairness)

One process in critical section, another process is waiting to enter \rightarrow show that if first process exits the critical section and attempts to re-enter, show that waiting process will be get in

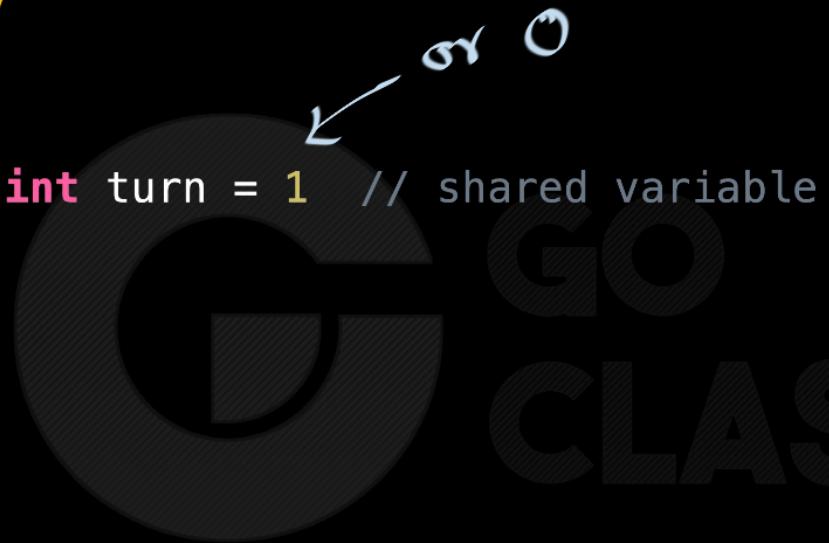


if busy is initialised to 1 then progress is also not satisfied



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Another Try



Code for Process 0

```
while (turn!=0);  
CS  
turn = 1;
```

Code for Process 1

```
want[0] = True;  
while (want[1]);  
CS  
want[0] = False;
```



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Another Try

Code for Process 0

```
while (turn!=0);  
CS  
turn = 1;
```

int turn = 1 // shared variable

initial Setup

$P_0 \xrightarrow{\text{CS}} P_1 \xrightarrow{\text{turn} = 0;}$

BW ✓

Code for Process 1

```
while (turn!=1);  
CS  
turn = 0;
```

$P_1 \xrightarrow{\text{turn} = 0;} P_0$

ME ✓
Progress ✗



Another Try

Called as Strict Alteration

Code for Process 0

```
int turn = 1 // shared variable  
  
while (turn!=0);  
  
CS  
  
turn = 1;
```

int turn = 1 // shared variable

Code for Process 1

```
want[0] = True;  
while (want[1]);  
  
CS  
  
want[0] = False;
```

- Mutual exclusion – satisfied
- Progress – not satisfied

BW





Yet Another Try...

```
int want[2] = {False, False}; // shared variable
```

Code for Process 0

```
want[0] = True;  
while (want[1]);
```

CS

```
want[0] = False;
```

Code for Process 1

```
want[1] = True;  
while (want[0]);
```

CS

```
want[1] = False;
```



Yet Another Try...

1

```
int want[2] = {False, False}; // shared variable
```

Code for Process 0

```
want[0] = True;  
while (want[1]);
```

CS

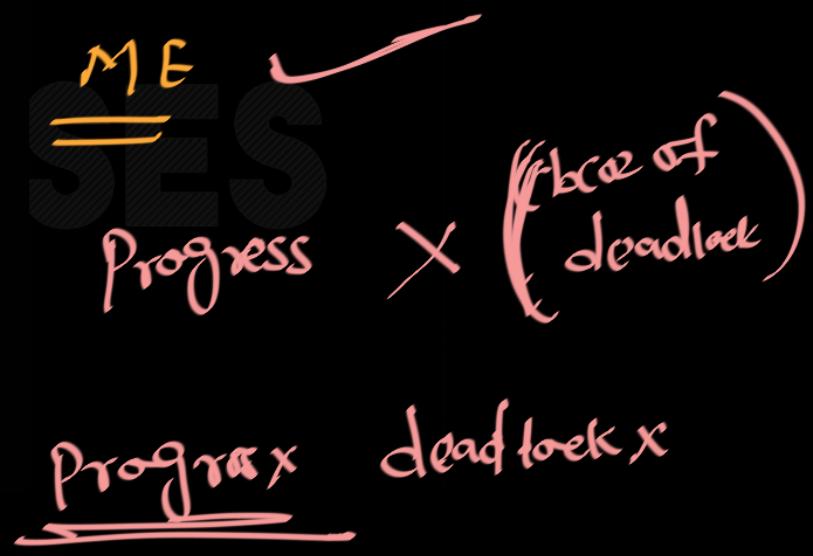
```
want[0] = False;
```

Code for Process 1

```
want[1] = True;  
while (want[0]);
```

CS

```
want[1] = False;
```



initial Setup for Bw

int want[2] = {False, False};

Code for Process 0

```
want[0] = True;
while (want[1]);
```

CS
P₀

```
want[0] = False;
```

T T

Code for Process 1

```
want[1] = True;
while (want[0]);
```

CS

```
want[1] = False;
```

P₀ ask P₁
to leave CS and
re-enter in CS

Since P₀ can not re-enter
hence Bw is satisfied

3. Bounded waiting (== fairness)

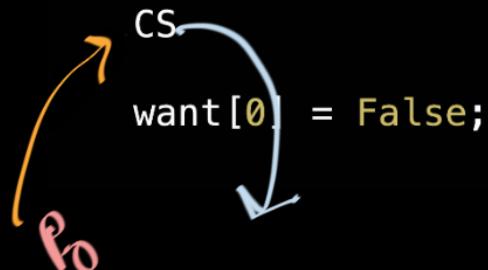
One process in critical section, another process is waiting to enter → show that if first process exits the critical section and attempts to re-enter, show that waiting process will be get in

Common Mistake.

```
int want[2] = {False, False}; // shared variable
```

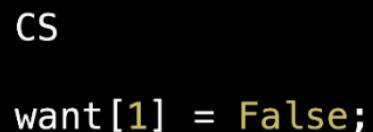
Code for Process 0

```
want[0] = True;  
while (want[1]);
```



Code for Process 1

```
want[1] = True;  
while (want[0]);
```



↓ wrong

But Not Satisfied

$\leftarrow \overbrace{p_1}$

Students forget
to make p_1 in wait
area

if progress is not then then there

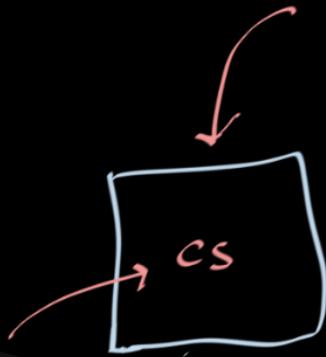
could be two possible reasons

- 1) single interested process was not allowed
- 2) there was a deadlock (ex: strict alt)
(example - Yet another try)

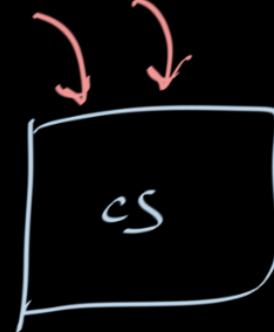
• deadlock is just one of the reason for progress to not happen.



ME



AND

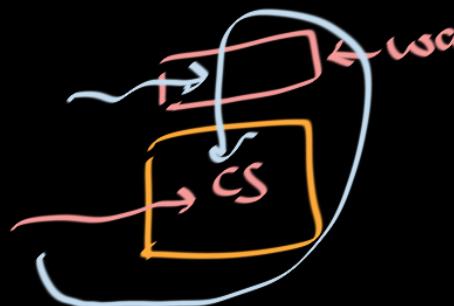


Progress



AND

Bw



n entry



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```
int want[2] = {False, False}; // shared variable
```

Code for Process 0

```
want[0] = True;  
while (want[1]);  
  
CS  
  
want[0] = False;
```

Code for Process 1

```
want[1] = True;  
while (want[0]);  
  
CS  
  
want[1] = False;
```

This does enforce Mutual Exclusion.

But now both processes can set flag to true, then loop for ever waiting for the other.

This is deadlock

- Mutual exclusion – satisfied
- Progress – not satisfied

BW → satisfied





Question: 1

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13,211 views



35

Consider the methods used by processes P_1 and P_2 for accessing their critical sections whenever needed, as given below. The initial values of shared boolean variables $S1$ and $S2$ are randomly assigned.



Method used by P_1	Method used by P_2
while ($S1 == S2$); Critical Section $S1 = S2$;	while ($S1 != S2$); Critical Section $S2 = \text{not}(S1)$;

Which one of the following statements describes the properties achieved?

- A. Mutual exclusion but not progress
- B. Progress but not mutual exclusion
- C. Neither mutual exclusion nor progress
- D. Both mutual exclusion and progress



Question:

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13,211 views



35



Consider the methods used by processes P_1 and P_2 for accessing their critical sections whenever needed, as given below. The initial values of shared boolean variables $S1$ and $S2$ are randomly assigned.

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- C. Neither mutual exclusion nor progress
- D. Both mutual exclusion and progress

;S

ME ✓

Prog X

Bw ✓

Method used by P1	Method used by P2
while ($S_1 == S_2$);	while ($S_1 != S_2$);
Critical Section	Critical Section
$S_1 = S_2$;	$S_2 = \text{not}(S_1)$;

M E ✓

P R O G P Y ✗

B W ✓

both conditions can't be true or false at same time.



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Best
answer

Answer is (A). In this mutual exclusion is satisfied, only one process can access the critical section at particular time but here progress will not be satisfied because suppose when $S1 = 1$ and $S2 = 0$ and process $P1$ is not interested to enter into critical section but $P2$ wants to enter critical section. $P2$ is not able to enter critical section in this as only when $P1$ finishes execution, then only $P2$ can enter (then only $S1 = S2$ condition be satisfied).

Progress will not be satisfied when any process which is not interested to enter into the critical section will not allow other interested process to enter into the critical section. When $P1$ wants to enter the critical section it might need to wait till $P2$ enters and leaves the critical section (or vice versa) which might never happen and hence progress condition is violated.

answered Oct 29, 2014 • edited Jun 21, 2021 by Lakshman Patel RJIT

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neha pawar



Question: 2



Two processes, P_1 and P_2 , need to access a critical section of code. Consider the following synchronization construct used by the processes:

44



```
/* P1 */
while (true) {
    wants1 = true;
    while (wants2 == true);
    /* Critical Section */
    wants1 = false;
}
/* Remainder section */
```

```
/* P2 */
while (true) {
    wants2 = true;
    while (wants1 ==
           true);
    /* Critical
       Section */
    wants2=false;
}
/* Remainder section
   */
```

Here, $wants1$ and $wants2$ are shared variables, which are initialized to false.

Which one of the following statements is TRUE about the construct?

- A. It does not ensure mutual exclusion.
- B. It does not ensure bounded waiting.
- C. It requires that processes enter the critical section in strict alteration.
- D. It does not prevent deadlocks, but ensures mutual exclusion.

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SES



Question:



Two processes, P_1 and P_2 , need to access a critical section of code. Consider the following synchronization construct used by the processes:

44



```
/* P1 */
while (true) {
    wants1 = true;
    while (wants2 == true);
    /* Critical Section */
    wants1 = false;
}
/* Remainder section */
```

```
/* P2 */
while (true) {
    wants2 = true;
    while (wants1 ==
           true);
    /* Critical
       Section */
    wants2=false;
}
/* Remainder section
   */
```

Here, $wants1$ and $wants2$ are shared variables, which are initialized to false.

Which one of the following statements is TRUE about the construct?

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- B. It does not ensure bounded waiting.
- C. It requires that processes enter the critical section in strict alteration.
- D. It does not prevent deadlocks, but ensures mutual exclusion.

GATE CSE 2007 | Question: 58

ME ✓
Progress X
SES
BW ✓

```
wants1 = true;  
while (wants2 == true);  
/* Critical Section */  
wants1 = false;
```

wants1 = $\frac{F}{T}$ wants2 = $\frac{F}{T}$

```
wants2 = true;  
while (wants1 == true);  
/* Critical Section */  
wants2=false;
```

ME - ✓
Progress - ✗
BW - ✓



Operating Systems



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Best answer

P_1 can do $wants1 = \text{true}$ and then P_2 can do $wants2 = \text{true}$. Now, both P_1 and P_2 will be waiting in the while loop indefinitely without any progress of the system - deadlock.

When P_1 is entering critical section it is guaranteed that $wants1 = \text{true}$ ($wants2$ can be either true or false). So, this ensures P_2 won't be entering the critical section at the same time. In the same way, when P_2 is in critical section, P_1 won't be able to enter critical section. So, mutual exclusion condition satisfied.

So, **D** is the correct choice.

Suppose P_1 first enters critical section. Now suppose P_2 comes and waits for CS by making $wants2 = \text{true}$. Now, P_1 cannot get access to CS before P_2 gets and similarly if P_1 is in wait, P_2 cannot continue more than once getting access to CS. Thus, there is a bound (of 1) on the number of times another process gets access to CS after a process requests access to it and hence bounded waiting condition is satisfied.

<https://cs.stackexchange.com/questions/63730/how-to-satisfy-bounded-waiting-in-case-of-deadlock>

answered Apr 12, 2015 • edited Jun 26, 2018 by Milicevic3306

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Pip Box Delete with Reason Wrong Useful

Arjun



Question: 3

GATE CSE 1988 | Question: 10iib

9
↑
↓

Given below is solution for the critical section problem of two processes P_0 and P_1 sharing the following variables:

```
var flag :array [0..1] of boolean; (initially false)
turn: 0 .. 1;
```

The program below is for process P_i ($i = 0$ or 1) where process P_j ($j = 1$ or 0) being the other one.

```
repeat
    flag[i]:= true;
    while turn != i
    do begin
        while (flag[j]);
        turn:=i;
    end
    critical section
    flag[i]:=false;
until false
```

$$\text{flag}[i] = \{ f, \bar{f} \}$$

iSES

Determine if the above solution is correct. If it is incorrect, demonstrate with an example how it violates the conditions.

$$\text{flag}[i] = \{ F, f \}$$

P₁

P₀

repeat

```
    flag[0]:= true;
    while turn != 0
    do begin
        while (flag[1]);
        turn:=1;
    end
```

critical section

```
    flag[0]:=false;
```

until false

repeat

```
    flag[1]:= true;
    while turn != 1
    do begin
        while (flag[0]);
        turn:=0;
    end
```

critical section

```
    flag[1]:=false;
```

until false

try with both turn , if one initialisation says no
to some property then NO to that property.



the above solution for the critical section isn't correct because it **satisfies Mutual exclusion and Progress** but it **violates the bounded waiting**.

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Here is a sample run



```
suppose turn =j initially;
```

Best answer

P_i runs its first statement then P_j runs its first statement then P_i run 2, 3, 4 statement, It will block on statement 4

Now P_j start executing its statements goes to critical section and then $\text{flag}[j] = \text{false}$

Now suppose P_j comes again immediately after execution then it will again execute its critical section and then $\text{flag}[j] = \text{false}$

Now if P_j is coming continuously then process P_i will suffer starvation.

the correct implementation ([for Bounded waiting](#)) is, at the exit section we have to update the turn variable at the exit section.

```
repeat
    flag[i]:= true;
    while turn != i
    do begin
        while flag [j] do skip
        turn:=i;
    end
    critical section
    flag[i]:=false;
    turn=j;
until false
```

ASSES

in



Question:



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Two processes X and Y need to access a critical section. Consider the following synchronization construct used by both the processes

Process X	Process Y
<pre>/* other code for process X */ while (true) { varP = true; while (varQ == true) { /* Critical Section */ varP = false; } } /* other code for process X */</pre>	<pre>/* other code for process Y */ while (true) { varQ = true; while (varP == true) { /* Critical Section */ varQ = false; } } /* other code for process Y */</pre>

Here varP and varQ are shared variables and both are initialized to false. Which one of the following statements is true?

- A. The proposed solution prevents deadlock but fails to guarantee mutual exclusion
- B. The proposed solution guarantees mutual exclusion but fails to prevent deadlock
- C. The proposed solution guarantees mutual exclusion and prevents deadlock
- D. The proposed solution fails to prevent deadlock and fails to guarantee mutual exclusion

GATE CSE 2015 Set 3 | Question: 10

SSES



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Answer is (A).





Question:

GATE CSE 2016 Set 2 | Question: 48



Consider the following two-process synchronization solution.

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PROCESS 0	Process 1
Entry: loop while ($\text{turn} == 1$); (critical section) Exit: $\text{turn} = 1$;	Entry: loop while ($\text{turn} == 0$); (critical section) Exit $\text{turn} = 0$;



The shared variable turn is initialized to zero. Which one of the following is TRUE?

- A. This is a correct two- process synchronization solution.
- B. This solution violates mutual exclusion requirement.
- C. This solution violates progress requirement.
- D. This solution violates bounded wait requirement.



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Best answer

There is strict alternation i.e. after completion of process 0 if it wants to start again. It will have to wait until process 1 gives the lock.

This violates progress requirement which is, that no other process outside critical section can stop any other interested process from entering the critical section.
Hence the answer is that it violates the progress requirement.

The given solution does not violate bounded waiting requirement.

Bounded waiting is : There exists a bound, or limit, on the number of times other processes are allowed to enter their critical sections after a process has made request to enter its critical section and before that request is granted.

Here there are only two processes and when process 0 enters CS, next entry is reserved for process 1 and vice-versa (strict alteration). So, bounded waiting condition is satisfied here.

Correct Answer: C



Question

Consider two processes P_0 and P_1 .

Code for Process P_0

```
while (x==0);  
x=0;  
  
CS
```

Code for Process P_1

```
while (x==1);  
x=1;  
  
CS
```

Proposed solution satisfy which one of the following ?

Mutual exclusion

Progress

Bounded waiting



Question

Consider two processes P_0 and P_1 .

Code for Process P_0

```
while (x==0);  
x=0;  
  
CS
```

Code for Process P_1

```
while (x==1);  
x=1;  
  
CS
```

Proposed solution satisfy which one of the following ?

Mutual exclusion

Progress

Bounded waiting



Question

Consider two processes P_0 and P_1 .

Code for Process P_0

```
x2 = 0;  
while (x1 != 1);
```

```
CS  
x2 = 1;
```

Code for Process P_1

```
x1 = 0;  
while (x2 != 1);
```

```
CS  
x1 = 1;
```

Proposed solution satisfy which one of the following ?

Mutual exclusion

Progress

Bounded waiting



Question

Consider two processes P_0 and P_1 .

Code for Process P_0

```
x2 = 0;  
while (x1 != 1);
```

```
CS  
x2 = 1;
```

Code for Process P_1

```
x1 = 0;  
while (x2 != 1);
```

```
CS  
x1 = 1;
```

Proposed solution satisfy which one of the following ?

Mutual exclusion

Progress

Bounded waiting



Peterson's Solution



Peterson's Solution

ME
Program
BW

Code for Process 0

```
want[0] = True;  
favored = 1;  
while (want[1] && favored ==1);
```

CS

```
want[0] = False;
```

```
// shared variables  
int want[2] = {False, False};  
int favored = 0;
```

Code for Process 1

```
want[1] = True;  
favored = 0;  
while (want[0] && favored ==0);
```

CS

```
want[1] = False;
```



Operating Systems

```
int turn;
boolean flag[2];

do {

    flag[i] = true;
    turn = j;
    while (flag[j] && turn == j);

    critical section

    flag[i] = false;

    remainder section

} while (true);
```

ASSES

Figure 5.2 The structure of process P_i in Peterson's solution.

Hard ware

Solⁿ

= 40 mins

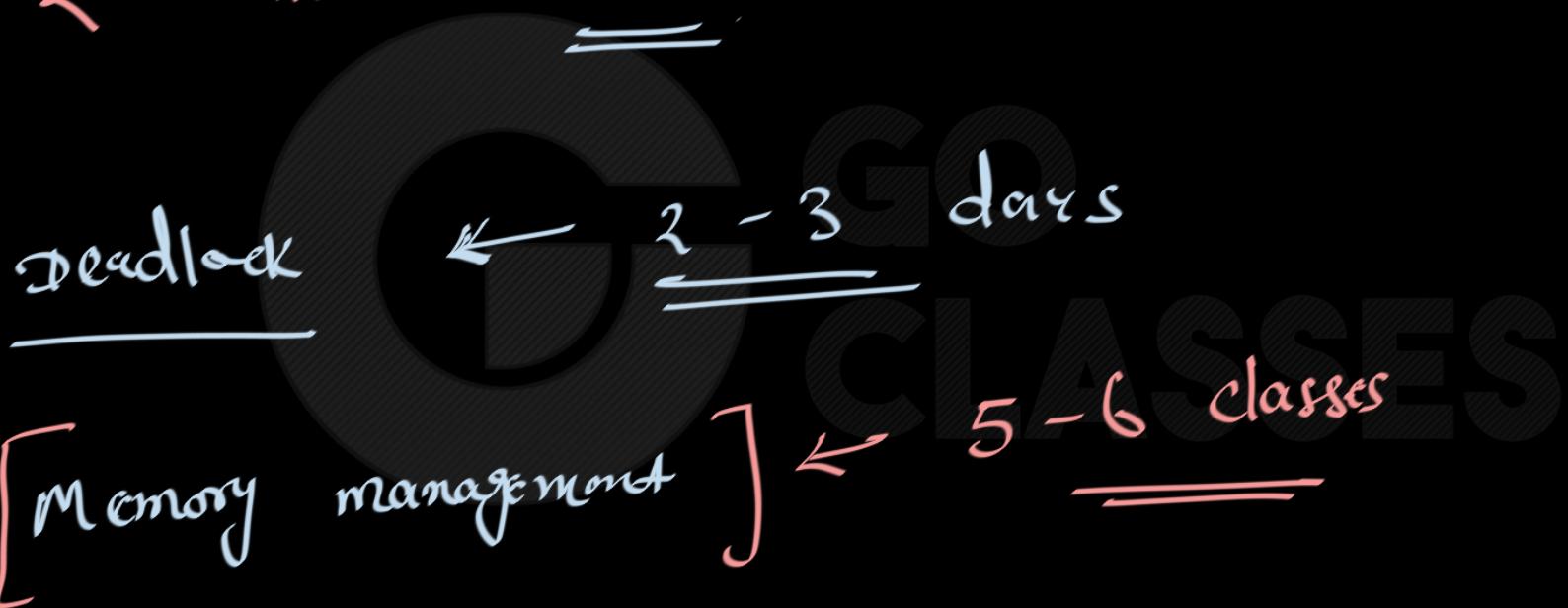
Semaphores

Why we need semaphores

How to implement it

advantages of semaphores (if any)

2 more days for Synchronisation



file system ← 2-3 days