

# 承認書

## FOR APPROVAL

客戶名稱

Customer:

松山湖材料實驗室

機種

Product:

客戶料號

Part No.:

客戶確認回覆:  
Customer Approval Status:

簽核:  
Signature:

合格 PASSED

拒收 REJECTED

### 昇威資料 SOUNDWELL'S INFORMATION

機種類別

ENCODER

Product:

品號

EC110201M2D-HA1-466

Part No.:

規格

Specification: 15P6-KV135A050-N1 (送货单标签只写流水号)

樣辦批號

Samples lot No.:

22171909286G

圖號

Drawing No.:

C-EC11XX-0051

摘要

Note:

| 承辦<br>Prepared By   | 校對<br>Proofed By  | 審核<br>Checked By   | 營業部<br>Sales Department |
|---|---|--|-------------------------|
| <br>19-09-20<br>李苗 | <br>19-09-20<br>歐陽昌雄 | <br>19-09-20<br>蘇朝暉 | 梁炳輝                     |

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The First Potentiometers Manufacturer in South Eastern Asia Certified By ISO9000  
ISO14001 TS16949認證企業

ISO14001 TS16949 Approved Company



香港公司: 昇威電子元件有限公司

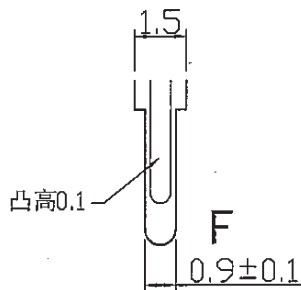
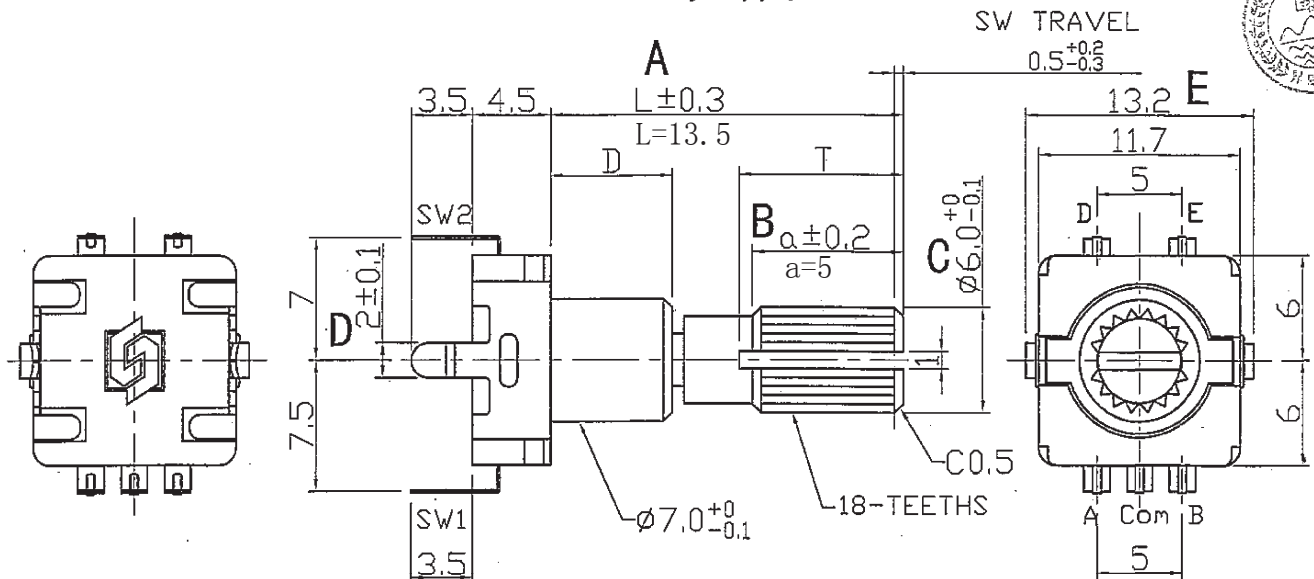
SOUNDWELL ELECTRONIC COMPONENTS CO., LTD  
香港九龍觀塘開源道六十四號源成中心十一樓五室  
Room 5, 11/F., Yen Sheng Centre,  
64 Hoi Yuen Road, Kwun Tong, Kowloon, Hong Kong  
TEL: (00852) 27966770 (12 Lines) FAX: (00852) 27530400  
E-mail: sw@soundwell-cn.com  
Website: www.soundwell-cn.com

大陸工廠: 廣東昇威電子製品有限公司

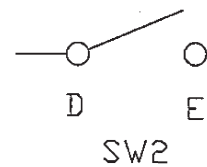
SOUNDWELL ELECTRONIC PRODUCTS (GUANG DONG) CO., LTD  
東莞市塘廈鎮鳳凰崗昇威工業園  
Soundwell Industrial Park, Feng Huang Gang, Tang  
Xia Town, Dong Guang City  
TEL: (0769) 38833333/86856888 FAX: (0769) 87930111/87930222



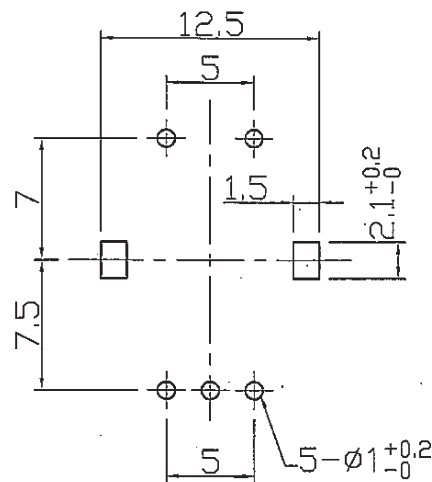
# 文件发行章



TERMINAL DETAIL (4:1)



|   |      |   |
|---|------|---|
| X | D    | X |
| M | 5.0  | 2 |
| N | 7.0  | 6 |
| A | 10.0 |   |



P.C.B. MOUNTING DETAIL

注：1、重点管控尺寸A~F。

|       |                  |                             |                  |                             |                                  |
|-------|------------------|-----------------------------|------------------|-----------------------------|----------------------------------|
| 01    |                  |                             | 03               |                             |                                  |
| 00    | ORIGINAL DRAWING | 11.10.15                    | 02               |                             |                                  |
| ISSU. | REVISION         | DATE                        | ISSU.            | <b>SOUNDWELL ELECTRONIC</b> |                                  |
|       |                  | TOL. UNLESS OTHERWISE SPEC. |                  |                             |                                  |
| DSGD. | CHKD.            | APPD.                       | BASIC DIMENSIONS | TOL.                        | TITLE: 编码器                       |
|       |                  |                             | L ≤ 10           | ± 0.3                       | MODEL: EC110201XXD-HA1-KVXXXAXXX |
|       |                  |                             | 10 < L           | ± 0.5                       |                                  |
|       |                  |                             | 100 ≤ L          | ± 0.8                       | DRAWING NO: C-EC11XX-0051        |
|       |                  |                             | ANGLE            | ± 5°                        | NO:                              |
|       | SCALE            |                             |                  |                             |                                  |
|       | UNIT             | mm                          |                  |                             |                                  |

# EC1102 SERIES SPECIFICATION

## EC1102 系列规格书

1/5P

### 1、General 一般事项

#### 1-1、Scope 适用规格

This specification applies to 11mm size low-profile thin rotary encoder (incremental type) for microscopic current circuits, used in electronic equipment.

本规格书为11mm小型回转式编码器（增量型），适用于电子设备内微小电子电路。

#### 1-2、Standard atmospheric conditions标准状态

Unless otherwise specified ,the standard range of atmospheric conditions for making measurements and test is as following limits:

除另有规定外，测量应在以下状态下进行：

Ambient temperature温度：15°C to 35°C

Relative humidity相对湿度：25% to 85%

Air pressure气压：86kPa to 106kPa

#### 1-3、Operating temperature range

使用温度范围：-40°C to 85°C

#### 1-4、Storage temperature range

保存温度范围：-40°C to 85°C

### 2、Construction 构造

#### 2-1 Dimensions 尺寸

Refer to attached drawing 见所附成品图

### 3、Rating 额定值

#### 3-1、Rated voltage 额定电压: DC 5V

#### 3-2、Maximum operating current (resistive load)最大额定电流（阻抗负载）

Each lead 各相导线：0.5mA (Max 10mA; Min 0.5mA)

Common lead 公共导线：1mA (Max 10mA; Min 0.5mA)

### 4、Application Notes 使用上的事项

4-1. Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation . If any remainder left after packing is opened, please store it with proper moistureproofing, gasproofing etc.

避免储藏于高温,潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余产品需储藏于防潮防毒的环境下.

4-2. The encoder pulses count method should be designed with taking operating speed ,sampling time and design software into cosideration.

编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去.

4-3. With this products ,detent positon will always be aligned with A-OFF or ON phase. Therefore make the A phase of the microcom-puter the reference at the soft ware design stage.

此产品在定位点状态时A相波形是处于OFF或ON状态,因此在设计软体时请留意此现象.

4-4. At design of the pulse count process. Using the C/R filter circuit is Recommended.

在设计时要考虑到杂讯,须使用C/R滤波电路.

4-5. Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.

本产品请勿碰触到水,可能会导致输出波形的异常.

4-6. When encoder are used, the speed is suitable for controlling with 360°/s. The highest speed will lead that IC doesn't obtain signal.

Mean while,the slide contact in the inside of product can be divorced form in order to be poor conatct.


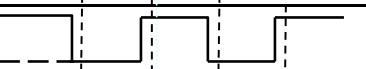


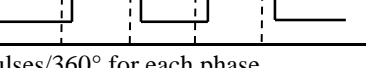
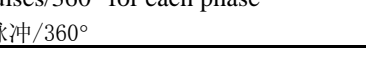


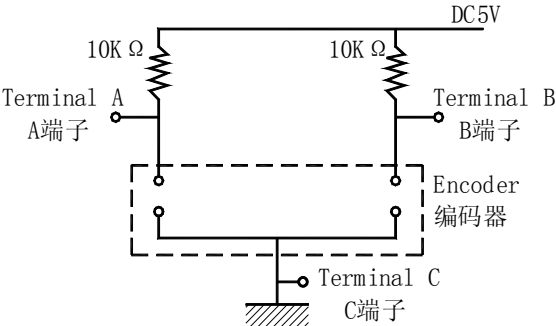
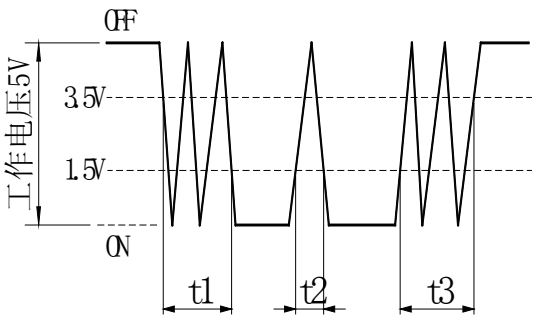
在使用编码品时速度宜控制在360°/s 内，转速过快会导致IC抓取不到信号及产品内部的接触刷会瞬间脱离产生接触不良。

# EC1102 SERIES SPECIFICATION

## EC1102 系列规格书

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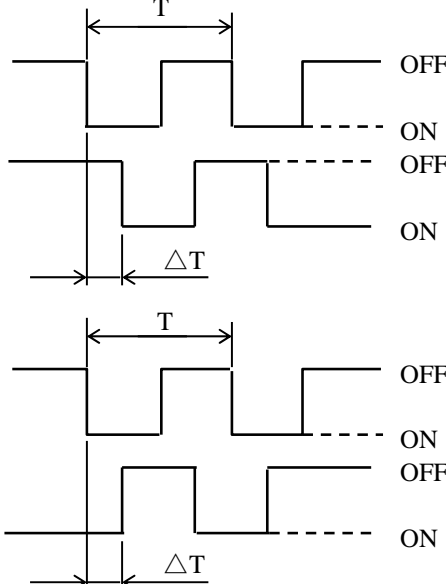
### 5、ELECTRICAL CHARACTERISTICS 电气性能

| ITEM<br>项 目                                 | CONDITIONS<br>条 件   |                               | SPECIFICATIONS<br>规 格   |
|---|---|-------------------------------|---|
| 5-1、Output signal<br>format<br>输出信号         | Note: Output signal is 1 pulse per 2 detents. And terminal A-C is pulse ON or OFF at detent position. No specified output of terminal B-C at detent position.<br>注意事项：输出信号方式是2个定位1个脉冲。在定位点位置时A-C端子处于ON或OFF状态，而B-C端子间不作特定要求。   |                               | 2 Phase-different signals (signal A, signal B)<br>Details shown in 〈fig.1〉 (The broken line shows detent position.)<br>A、B两信号输出相位差,输出波形详见(图1)。虚线表示带卡点装置的卡点处位置。                        |
|   | Shaft rotational direction<br>轴回转方向   | Signal<br>信号                  | Output (fig.1)<br>输出波形 (图1)   |
|   | C.W.<br>顺时针方向   | A(Terminal A-C)<br>A( A-C端子间) | OFF <br>ON      |
|   |   | B(Terminal B-C)<br>B( B-C端子间) | OFF <br>ON      |
|   | C.C.W<br>逆时针方向  | A(Terminal A-C)<br>A( A-C端子间) | OFF <br>ON     |
|   |   | B(Terminal B-C)<br>B( B-C端子间) | OFF <br>ON  |
| 5-2、Resolution<br>分解能力                      | Number of pulses in 360° rotation.<br>回转360°的输出脉冲数。   |                               | 15 pulses/360° for each phase<br>15个脉冲/360°   |
| 5-3、Switching<br>characteristics<br>开关特性    | Measurement shall be made under the condition as follows.<br>1)Shaft rotational speed : 360°/s<br>2)Test circuit : (fig.2)<br>下(图2)所示回路,轴以360°/s的速度回转测定。<br><div style="display: flex; justify-content: space-around; align-items: flex-start;"> <div style="text-align: center;"> <p>fig.2</p>  </div> <div style="text-align: center;"> <p>〈fig.3〉图3</p>  </div> </div> <p>(Note) Code-OFF area :The area which the voltage is 3.5V or more.<br/>           Code-ON area :The area which the voltage is 1.5V or less.<br/>           (注) 编码器OFF指输出电压3.5V以上的状态。<br/>           编码器ON指输出电压1.5V以下的状态。</p> |                               |   |
| 5-3-1、Chattering<br>振荡                      | Specified by the signal's passage time from 1.5V to 3.5V of each switching position (code OFF~ON or ON~OFF) (Fig.3)<br>编码从OFF → ON 或 ON → OFF时,输出1.5V~3.5V通过的时间应符合规定。(图3)   |                               | On the case within detent, B signal will be irregular oscillation.带卡点时,在卡点位置上的B信号振荡无规定。<br>$t_1, t_3 \leq 3 \text{ ms}$   |
| 5-3-2、Sliding noise<br>(Bounce)<br>滑动杂音(突跳) | Specified by the time of voltage change exceed 1.5V in code-ON area.<br>When the bounce has code-ON time less than 1mS between chattering (t1 or t3).the voltage change shall be regarded as a part of chattering. When the code-ON time between 2 bounces is less than 1mS.they are regarded as 1 linked bounce.<br>编码ON部分的1.5V以上的电压变动时间在振荡t1,t3之间会产生1毫秒以上1.5V以下的ON部分.另外,如果各突跳间1.5V以下的范围在1毫秒以上时,则判定为另一个突跳。   |                               | $t_2 \leq 2 \text{ ms}$   |

# EC1102 SERIES SPECIFICATION

## EC1102系列规格书

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| 5、ELECTRICAL CHARACTERISTICS电气性能             |   |   |
|--|---|---|
| ITEM<br>项 目                                  | CONDITIONS<br>条 件   | SPECIFICATIONS<br>规 格   |
| 5-3-3、Sliding noise<br>滑动噪音                  | The voltage change in code - OFF area.<br>编码OFF部分的电压变动。   | 3.5V Min<br>3.5V 以上   |
| 5-4、Phase difference<br>相位差                  | <p>Measurement shall be made under the condition which the shaft is rotated in <math>360^{\circ}\cdot S^{-1}</math> (constant speed).以<math>360^{\circ}/s</math>的速度测量。<br/>(Fig.4)图4</p> <p>C W<br/>顺时针方向</p> <p>A信号(A~C间)<br/>Signal A</p> <p>B信号(B~C间)<br/>Signal B</p> <p>C C W<br/>逆时针方向</p> <p>A信号(A~C间)<br/>Signal A</p> <p>B信号(B~C间)<br/>Signal B</p>  | <p><math>\Delta T \geq 6 \text{ ms}</math></p> <p>In(fig.4) 见图4</p>   |
| 5-5、Insulation resistance<br>绝缘电阻            | Measurement shall be made under the condition which a voltage of 250V DC 1min is applied between individual terminals and bushing.<br>在端子和安装板间施加电压 250V DC 1分钟。   | Between individual terminals and bushing<br>100 MΩ Min<br>端子安装板间电阻100 MΩ以上。   |
| 5-6、Dielectric strength<br>耐电压               | A voltage of 300V AC shall be applied for 1 minute between individual terminals and bushing.<br>在端子和安装板间施加 AC 300V电压1分钟。  | Without arcing or breakdown.<br>不得有绝缘破坏。  |
| 6、Mechanical characteristics 机械性能            |   |   |
| 6-1、Total rotational angle<br>全回转角度          |   | 360°(Endless)<br>360°(无止挡点)   |
| 6-2、Detent Torque<br>定位点力矩                   | Only suitable for C.C. equipment.<br>只适用于附卡点装置  | $6 \pm 3 \text{ mNm}$ ( $60 \pm 30 \text{ gf.cm}$ )   |
| 6-3、Number and position of detent<br>定位点数及位置 | Only suitable for C.C. equipment.<br>只适用于附卡点装置  | 30 detents(Step angle: $12^{\circ} \pm 3^{\circ}$ )<br>30点定位 (间隔角度 $12^{\circ} \pm 3^{\circ}$ )   |
| 6-4、Push-pull strength of shaft<br>轴推拉强度     | Pull static load of 100 N(10 kgf) for 20s and push static load of 100 N (10 Kgf)for 10s shall be applied to the shaft in the axial direction .<br>(After soldering of the PC board)<br>在轴端, 沿轴向施加100 N(10 kgf)的静负荷力拉力20秒钟和施加100 N (10 Kgf)推力10秒钟(焊锡固定在PCB上)。  | Without damage or excessive play in shaft . No excessive abnormality in rotational feeling.And electrical characteristics shaft be satisfied.<br>轴无破损, 旋转、电气性能无异常。  |
| 6-5、Terminal strength<br>端子强度                | A static load of 3N(0.31kgf) shall be applied to the tip of terminals for 10 s in any direction.<br>端子前端的任意方向施加3N(0.31kgf)的静负荷力10秒钟。  | Without excessive play in terminal or poor contact.<br>端子不得有明显松动及接触不良。  |
| 6-6、Shaft wobble<br>轴摆动                      | A momentary load of 2N(200 gf) shall be applied at the point 2mm from the tip of the shaft in a direction perpendicular to the axis of shaft.<br>在轴前端2mm处,沿径向瞬间施加2N (200 gf)的力。<br>L:Distance between mounting surface and measuring point on the shaft.  | <p>Bushing length      Wobble</p> <p>轴套长 (mm)      摆动 (mmp-p less)</p> <p><input checked="" type="checkbox"/> 5      0.3*L/20</p> <p><input type="checkbox"/> 7      0.25*L/20</p> <p><input type="checkbox"/> 10以上      0.2*L/20</p> |

# EC1102 SERIES SPECIFICATION

## EC1102 系列规格书

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| 6、Mechanical characteristics 机械性能               |  |  |
|---|--|--|
| ITEM<br>项 目                                     | CONDITIONS<br>条 件  | SPECIFICATIONS<br>规 格  |
| 6-7、Side thrust strength of shaft<br>轴的垂直押引强度   | A load of 20N(2.04Kgf) shall be applied at the point 5mm from the tip of the shaft in a direction perpendicular to the axis of shaft for 10 s.<br>在轴前端5 mm处加20 N(2.04 Kgf)的静负荷力10 s.   | Without excessive play of bending in shaft. No mechanical abnormally.<br>轴不得有明显松动及接触不良.  |
| 6-8、Shaft play in rotational wobble<br>轴的回转方向摆动 | Testing by angle board.<br>用角度板测定.   | 2° Max<br>2° 以下  |
| 6-9、Shaft play in axial direction<br>轴向间隙       | The pull / push load of 0.5N(51gf) shall be imposed on the shaft.<br>在轴上施加0.5N(51gf)的推力或拉力.  | 0.2 mm Max.<br>0.2 mm以下.   |
| 7、Endurance characteristics 耐久性能                |  |  |
| 7-1、Rotational life<br>回转寿命                     | The shaft of encoder shall be rotated to 30,000 cycles at a speed of 600~800 cycles/H without electrical load,after which measurements shall be made.<br>在无负荷条件下轴以600~800周/小时速度回转 30,000 周。<br>1 cycle: rotate 360° CCW rotate 360° CW<br>1周指顺时针转360°逆时针转360°。   | Chattering t1,t3≤5ms Bounce t2≤3ms<br>振荡: t1,t3≤5ms; 突跳: t2≤3ms<br>Detent torque:Relative to the previously specified value 50%.<br>定位力矩: 为原始规格值的50%<br>Shaft wobble should be within 150% of the specifications.<br>轴摆动为原始规格值的150%以内<br>Shaft play in rotational wobble:4° Max.<br>轴的回转方向摆动: 4°以内 |
| 7-2、Damp heat<br>耐湿性                            | The encoder shall be stored at temprature of 40±2°C with relative humidity of 90% to 95% for 240±10H in a thermostatic chamber .And the encoder shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.<br>温度40±2°C,湿度90~95%的恒温恒湿槽中放置240±10小时后,在常温、常湿中放置1.5小时后测试.  | SW Contact resistance:200 mΩ max.<br>Encoder characteristics item:<br>5-1、5-5、5-6、6-2  |
| 7-3、Dry heat<br>耐热性                             | The encoder shall be stored at a temperature of 80±3°C for 240±10H in a thermostatic chamber.And then the encoder shall be subjected to standard atmospheric conditions for 1.5H .After witch measurement shall be made.温度80±3°C的恒温箱中放置240±10小时,常温、常湿放置1.5小时后测试.   | Push switch characteristics item:<br>1-2-3、1-2-4、1-3-2、1-3-3<br>The same as the initial specifications.<br>开关接触阻抗小于200 mΩ。<br>编码器特性项目: 5-1、5-5、5-6、6-2   |
| 7-4、Cold<br>低温特性                                | The encoder shall be stored at a temperature of -40±3°C for 240±10H in a thermostatic chamber.And then the encoder shall be subjected to standard atmospheric conditions for 1.5H .After witch measurement shall be made .温度-40±3°C的恒温箱中放置240±10小时,常温、常湿放置1.5小时后测试.  | 按压开关特性项目: 1-2-3、1-2-4、1-3-2、1-3-3应同原规格值相同。   |
| 7-5、Solder ability<br>焊锡性                       | The terminals shall be immersed into solder bath at 260°C±5°C for 3s±1s in the same manner as para.<br>端子在260°C±5°C温度的焊锡槽内浸锡3秒±1秒。   | A new uniform coating of solder shall cover 75% minimum of the surface being immersed.<br>浸渍面须有75%以上焊锡附着   |
| 7-6、Resistance to Soldering heat<br>耐焊接热        | Manual soldering手工焊接<br>Bit temperature of soldering iron: 350°C less than<br>Application time of soldering iron: within 3s<br>温度350°C以下, 时间3秒以内。<br>Dip soldering槽焊<br>Printed wiring board : copper clad laminate board with thickness of 1.6mm.<br>使用基板: t=1.6mm的覆铜板。<br>Preheating : 1、Surface temperature of board: 100°C or less.<br>2、Preheating time : within 1 min.<br>预热: 基板表面温度100°C以下, 时间1分钟以内。<br>Soldering : Solder temperature : 260±5°C or less<br>Immersion time :within 3 s<br>焊接: 温度260±5°C或以下, 时间3秒以内。 | Electrical characteristics shall be satisfied<br>No mechanical abnormality.<br>不得有绝缘体的破损、变形、接触无异常。   |



# EC1102 SERIES SPECIFICATION

## EC1102 系列规格书

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### Push switch portion 推动开关部分

Note: The following specification is only suitable for the one type with switch construction of EC11 encoder series.

注：以下规格只适用于此EC11编码器系列带开关结构。

1-1、Rated capacity (Resistance load ): DC 5V 10 mA (1 mA Min)

额定容量（电阻负荷）：DC 5V 10 mA (1 mA 以上)

### 1-2 Electrical characteristics 电气性能

| ITEM<br>项 目                      | CONDITIONS<br>条 件  | SPECIFICATIONS<br>规 格   |
|----------------------------------|--|---|
| 1-2-1、Contact resistance接触电阻     | Voltage step-down test at DC 5V 1mA<br>用DC 5V 1mA 电压降下法测定.   | 100 m $\Omega$ Max<br>100 m $\Omega$ 以下   |
| 1-2-2、Bouncing<br>振荡             | Shaft shall be rotated at 1 cycles/S (OFF-ON-OFF)<br>以1秒钟1往返（OFF-ON-OFF）回转运转   | 10 ms Max<br>10 ms 以下   |
| 1-2-3、Insulation resistance绝缘电阻  | Measurement shall be made under the condition which a voltage 250V DC 1min $\pm$ 5S is applied between individual terminals and tracked<br>在端子与安装板间施加电压DC 250V 1分钟 $\pm$ 5秒。 | Between individual terminals and bracket<br>100 M $\Omega$ Min.<br>在端子安装板间100 M $\Omega$ 以上 |
| 1-2-4 Dielectric strength<br>耐电压 | A voltage of 250V AC /min or 300 V AC /2S( leak current 1mA) be applied between individual terminals and bracket.在端子与安装板间施加AC 250V 1分钟或AC 300V 2秒钟（漏电流1mA）                   | Without arcing or breakdown.<br>不得有绝缘损坏。  |

### 1-3 Mechanical characteristics 机械性能

|  |  |   |
|--|--|---|
| 1-3-1、Switch circuit and number of pulse<br>开关电路、接点数 |  | Single pole and single throw (push on)<br>单极单投（推ON） |
| 1-3-2、Travel of switch开关移动量                          |  | 0.5 $^{+0.2}_{-0.3}$ mm                             |
| 1-3-3、Operating force of switch开关作动力                 |  | 5 $\pm$ 3 N (500 $\pm$ 300gf)                       |

### 1-4 Endurance characteristics 耐久性能

|                             |   |  |
|-----------------------------|---|--|
| Push operating life<br>寿命特性 | The encoder's shall be pushed to 20,000 cycles at a speed of 1800 $\pm$ 300/H without electrical load.(shaft push load: 1 kgf Max.)<br>在无负荷条件下,对轴以每小时1800 $\pm$ 300次的速度推动20,000次,（轴按压力1 kgf以下）. | Contact resistance : 200m $\Omega$ max.<br>Specification in clause 1-2-2~4,1-3-1~2 shall be satisfied.<br>Operating force:Before test 50%.<br>接触电阻 : 200m $\Omega$ 以下.<br>1-2-2~4,1-3-1~2 满足初期规格.<br>开关动作为寿命前的50%. |
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