

# 注: 1、重点管控尺寸A~F。

01					03			•	
00	ORIGINAL	DRAWING		11. 10. 15	02		-		_
. ISSU.	REVI	SION	,	DATE	. ISSU.	SUL SULIDWELL ELECTRON		TDONLO	
SOUNDWELL		TOL. UNLESS OTHERWISE SPEC.		SOUNDWELL ELECTRONIC			RUNIU		
/ M	2011-10-22.	2011-10-24	BASIC DIMENSIONS		TOL.	TITLE: 编码器			
H V	WU TIAN JING	HUNG KAM PU	Ľ≈	€10 ·	± 0.3	MODEL:	OOOTUUD III		
DSGD.	CHKD.	APPD.	10	<l .<="" td=""><td>± 0.5</td><td colspan="2">EC110201XXD-HA1-KVXXXAXXX</td><td>LAXXX .</td></l>	± 0.5	EC110201XXD-HA1-KVXXXAXXX		LAXXX .	
$\oplus \in$	SCALE		100≤L		± 0.8	DRAWING NO: C-EC11XX-0	051		
	UNIT	mm	AN	GLE.	±5°		C-ECIIAA-0	.AA UUUI	NO:

### **EC1102 SERIES SPECIFICATION**

## EC1102 系列规格书

1/5P

#### 1、General 一般事项

1-1、Scope 适用规格

This specification applies to 11mm size low-profile thin rotary encoder (incremental type) for microscopic current circuits, used in electronic equipment.

本规格书为11mm小型回转式编码器(增量型),适用于电子设备内微小电子电路。

1-2、Standard atmospheric conditions标准状态

Unless otherwise specified ,the standard range of atmospheric conditions for making measurements and test is as following limits: 除另有规定外,测量应在以下状态下进行:

Ambient temperature温度: 15°C to 35°C

Relative humidity相对湿度: 25% to 85%

Air pressure气压 : 86kPa to 106kPa

1-3. Operating temperature range

使用温度范围 : -40℃ to 85℃

1-4. Storage temperature range

保存温度范围 : -40°C to 85°C

#### 2、Construction 构造

2-1 Dimensions 尺寸

Refer to attached drawing 见所附成品图

### 3、 Rating 额定值

- 3-1、Rated voltage 额定电压: DC 5V
- 3-2、Maximum operating current (resistive load)最大额定电流(阻抗负载)

Each lead 各相导线

: 0.5mA(Max 10mA; Min 0.5mA)

Common lead 公共导线: 1mA (Max 10mA; Min 0.5mA)

#### 4、Application Notes 使用上的事项

4-1. Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened, please store it with proper moisture proofing, gasproofing etc.

避免储藏于高温,潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余产品需储藏于防潮防毒的 环境下.

4-2. The encoder pulses count method should be designed with taking operating speed ,sampling time and design software into cosideration.

编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去.

4-3. With this products ,detent position will always be aligned with A-OFF or ON phase. Therefore make the A phase of the microcomputer the reference at the soft ware design stage.

此产品在定位点状态时A相波形是处于OFF或ON状态,因此在设计软体时请留意此现象.

4-4. At design of the pulse count process. Using the C/R filter circuit is Recommended.

在设计时要考虑到杂讯,须使用C/R滤波电路.

4-5. Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.

本产品请勿碰触到水,可能会导致输出波形的异常.

4-6. When encoder are used, the speed is suitable for controlling with 360°/s. The highest speed will lead that IC doesn't obtain signal.

Mean while, the slide contact in the inside of product can be divorced form in order to be poor conatct.

在使用编码品时速度宜控制在360°/s 内,转速过快会导致IC抓取不到信号及产品内部的接触刷会瞬间脱离产生接触不良。

### **EC1102 SERIES SPECIFICATION**

EC1102 系列规格书

ECTIVE 系列规格书 2/3F						
5、ELECTRICAL CHARACTERISTICS电气性能						
ITEM	CONDIT 条		SPECIFICATIONS			
项 目		1 <del>11</del> per 2 detents. And terminal A-C is pulse	规格 2 Phase-different signals			
		No specified output of termial B-C	(signal A, signal B)			
	at detent position.	Details shown in \langle fig.1 \rangle (The broken				
		个定位1个脉冲。在定位点位置时	line shows detent position .)			
1	A-C端子处于ON或OFF状态,	而B-C端子间不作特定要求。	A、B两信号输出相位差,输出波形详			
			细见(图1)。虚线表示带卡点装置的卡			
			点处位置。			
5-1 Output signal	Shaft rotational direction	Signal	Output 〈fig.1〉			
format	轴回转方向	信号	输出波形 (图1)			
输出信号	111111111111	A(Terminal A-C)	OFF			
1111 III III J	C.W.	A(A-C端子间)	ON —			
	顺时针方向	B(Terminal B-C)	OFF			
	102 to 1 A 1 to 1 A 1 A	B(B-C端子间)	ON ———			
		A(Terminal A-C)	OFF			
	C.C.W	A(A-C端子间)	ON _			
	逆时针方向	B(Terminal B-C)	OFF			
	<b>型的针刀</b> 的					
5-2、Resolution	Number of pulses in 360° rota	B(B-C端子间)	0N 15 pulses/360° for each phase			
分解能力	回转360°的输出脉冲数。	MOII o	15 pulses/300 for each phase 15个脉冲/360°			
/J /htt 86/J	Measurement shall be made un	der the condition as follows.	10   ///// 7 000			
	1)Shaft rotational speed: 360°/s					
	2)Test circuit: (fig.2)					
	下(图2)所示回路,轴以360°/s的速度回转测定。 〈fig.3〉图3					
		DC 5 V	Œ			
	fig.2 10K Ω <b>≥</b>	10K Ω	- <del></del>			
5.0 0 1.11	Terminal A	Terminal B 16 35	v\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\			
5-3 Switching characteristics	A端子 •	Terminal B AS 出 35 B端子 田				
开关特性	[	Encoder 15	v			
カ <b>大付</b> 性 		♀   编码器 ⊢				
	L	<del></del> -	ON V			
		Terminal C	t1 t2 t3			
		/////////////////////////////////////				
		rea which the voltage is 3.5V or more.				
	Code-ON area: The area which the voltage is 1.5V or less.					
	(注)编码器OFF指输出电压					
	编码器ON指输出电压	1.5V以下的状念。 ge time from 1.5V to 3.5V of each	On the case within detent, B signal will			
5-3-1 Chattering	switching position (code OFF-	_	be irregular oscillation.带卡点时,在卡点			
振荡		N → OFF时,输出1.5V~3.5V通过	位置上的B信号振荡无规定。			
#W 154	的时间应符合规定。(图3)		t1,t3 ≤ 3 ms			
	Specified by the time of voltage cl	hange exceed 1.5V in code-ON area.				
		ne less than 1mS between chattering				
5-3-2. Sliding noise		all be regarded as a part of chatteri-				
(Bounce)	ng. When the code-ON time be	$t2 \leqslant 2 \text{ ms}$				
滑动杂音(突跳)	are regarded as 1 linked bounce. 编码ON部分的1.5V以上的电压变动时间在振荡t1,t3之间会产生					
		·. 另外, 如果各突跳间1. 5V以下的范				
	围在1毫秒以上时,则判定为另					
	<u> </u>		l .			

## EC1102 SERIES SPECIFICATION EC1102系列规格书

5、	ELECTRICA	AL CHARACTERISTICS电气性能			
	ITEM	CONDITIONS	SPECIFICATIONS		
	项 目	条 件	规 格 规 格		
5-3-3	Sliding noise	The voltage change in code - OFF area.	3.5V Min		
	滑动噪音	编码OFF部分的电压变动。  Measurement shall be made under the condition which the shaft is	3.5V 以上		
5-4、	Phase difference 相位差	rotated in 360°·S <sup>-1</sup> (constant speed).以360°/s的速度测量。 (Fig.4)图4  C W  顺时针方向  A信号(A~C间)  Signal A  B信号(B~C间)  Signal B	△T≥6 ms In(fig.4) 见图4		
5-5	Insulation	Measurement shall be made under the condition which a voltage of	Between individual terminals and bushing		
ll .	resistance	250V DC 1min is applied between individual terminals and bushing.	100 MΩ Min		
ll .	绝缘电阻	在端子和安装板间施加电压 250V DC 1分钟。	端子安装板间电阻100 MΩ以上。		
	Dielectric	A voltage of 300V AC shall be applied for 1 minute between individua	Without arcing or breakdown.		
	strength	terminals and bushing.	不得有绝缘破坏。		
	耐电压	在端子和安装板间施加 AC 300V电压1分钟。			
<b>6.</b> I	Mechanical c	haracteristics 机械性能			
6-1、	Total ratational		360°(Endless)		
angl	le 全回转角度		360°(无止挡点)		
6-2、	Detent Torque	Only suitable for C.C, equipment.	6± 3 mNm (60±30 gf.cm)		
5	定位点力矩	只适用于附卡点装置	-		
6-3、	Number and	Only suitable for C.C, equipment.	30 detents(Step angle:12°±3°)		
pos	ition of detent	只适用于附卡点装置	30点定位(间隔角度 12°±3°)		
定位	立点数及位置				
		Pull static load of 100 N(10 kgf) for 20s and push static load of 100 N	Without damage or excessive play in sh-		
6-4、	Push-pull stren-	(10 Kgf)for 10s shall be applied to the shaft in the axial direction.	aft . No excessive abnormality in rotatio-		
	gth of shaft	(After soldering of the PC board)	nal feeling.And electrical characteristics		
4	油推拉强度	  在轴端,沿轴向施加100 N(10 kgf)的静负荷力拉力20秒钟和施加			
1	ロ 4 PP 4 ユー 4 土 1 人	100 N (10 Kgf)推力10秒钟(焊锡固定在PCB上)。	轴无破损,旋转、电气性能无异常。		
	TD : 1				
6-5	Terminal				
	strength	10 s in any direction. 豐子並豐的任意主向強加2N/0 211-60的數色基本10秒钟	poor contact. 学子不但有明显松和及接触不自		
	端子强度	端子前端的任意方向施加3N(0.31kgf)的静负荷力10秒钟.	端子不得有明显松动及接触不良。		
6-6、	Shaft wobble	A momentary load of 2N(200 gf) shall be applied at the point	Bushing length Wobble		
	轴摆动	2mm from the tip of the shaft in a direction perpendicular to the axis of shaft. 在轴前端2mm处,沿径向瞬间施加2N (200 gf)的力.	轴套长 (mm) 摆动 (mmp-p less) □ 5 0.3*L/20		
		上:Distance between mounting surface and measuring point on	$\square$ 5 0. 3*L/20 $\square$ 7 0. 25*L/20		
		the shaft.	□ 10以上 0.2*L/20		

### EC1102 SERIES SPECIFICATION EC1102 系列规格书

( Machaniaal a	ECIIU2 系列规格书	4/5P
TTEM	haracteristics 机械性能 CONDITIONS	SPECIFICATIONS
项 目	条 件	规 格
	A load of 20N(2.04Kgf) shall be applied at the point 5mm from the tip	
ngth of shaft	of the shaft in a direction perpendicular to the axis of shaft for 10 s.	shaft. No mechanical abnormally.
轴的垂直押引强度	在轴前端5 mm处加20 N(2.04 Kgf)的静负荷力10 s.	新福代. No inechanical abilofinally.
描的垂直狎り强度 6-8、Shaft play in	在相前網5 mm处加20 N(2.04 Kgf)的群页间为10 8. Testing by angle board.	2° Max
rotational wobble	用角度板测定.	2°以下
	用反似例足。	
<u>轴的回转方向摆动</u> 6-9、Shaft play in	The pull / push load of 0.5N(51gf) shall be imposed on the shaft.	0.2 mm Max.
axial direction	在轴上施加0.5N(51gf)的推力或拉力.	0.2 mm以下.
ll .	在抽工爬加O.31V(31g1)印1)性/J.5X1亚/J.	0.2 mm & P.
轴向间隙 7 Fndurance ch	ı garacteristics耐久性能	
75 Endurance ch	The shaft of encoder shall be rotated to 30,000 cycles at a speed of	Chattering t1,t3≤5ms Bounce t2≤3ms
7-1 Rotational life	600~800 cycles/H without electrical load, after which measurements	振荡: t1,t3≤5ms; 突跳: t2≤3ms
回转寿命	shall be made.	Detent torque:Relative to the previously
■ 四粒石印 ■	在无负荷条件下轴以600~800周/小时速度回转30,000周。	specified value 50%.
	1 cycle: rotate 360° CCW rotate 360° CW	定位力矩: 为原始规格值的50%
	1周指顺时针转360°逆时针转360°。	Shaft wobble should be within 150% of
	17月11日小公中3 45 200 (20年3 年) 45 200 (3	the specifications.
		轴摆动为原始规格值的150%以内
		Shaft play in rotational wobble:4° Max.
		轴的回转方向摆动: 4°以内
	The encoder shall be stored at temprature of 40±2°C with relative hu-	和的四次分间送物: 4 6/19
	midity of 90% to 95% for 240±10H in a thermostatic chamber .And	
7-2. Damp heat	the encoder shall be subjected to standard atmospheric conditions	
耐湿性	for 1.5H, After which measurements shall be made.	SW Contact resistance:200 mΩ max.
	温度40±2°C,湿度90~95%的恒温恒湿槽中放置240±10小时后,在	Encoder characteristics item:
	常温、常湿中放置1.5小时后测试.	5-1 \ 5-5 \ 5-6 \ 6-2
		Push switch characteristics item:
7-3 Dry heat	in a thermostatic chamber. And then the encoder shall be subjected to	1-2-3、1-2-4、1-3-2、1-3-3
耐热性	standard atmospheric conditions for 1.5H .After witch measurement	The same as the initial specifications.
	shall be made.温度80±3°C的恒温箱中放置240±10小时,常温、常	开关接触阻抗小于200 mΩ。
	湿放置1.5小时后测试.	编码器特性项目: 5-1、5-5、5-6、6-2
	The encoder shall be stored at a temperature of -40±3°C for 240±10H	按压开关特性项目: 1-2-3、1-2-4、1-3-2
7-4、Cold	in a thermostatic chamber. And then the encoder shall be subjected to	、1-3-3应同原规格值相同。
低温特性	standard atmospheric conditions for 1.5H .After witch measurement	, , , , , , , , , , , , , , , , , , , ,
	shall be made .温度-40±3°C的恒温箱中放置240±10小时,常温、	
	常湿放置1.5小时后测试。	
7-5 Solder ability	The terminals shall be immersed into solder bath at 260°C±5°C for	A new uniform coating of solder shall
焊锡性	3s±1s in the same manner as para.	cover 75% minimum of the surface being
	端子在260℃±5℃温度的焊锡槽内浸锡3秒±1秒。	immersed.
		浸渍面须有75%以上焊锡附着
	Manual soldering手工焊接	
	Bit temperature of soldering iron: 350°C less than	
	Application time of soldering iron: within 3s	
	温度350°C以下,时间3秒以内。	
	Dip soldering槽焊	
7-6 Resistance to	Printed wiring board: copper clad laminate board with	Electrical characteristics shall be satisfied
Soldering heat	thickness of 1.6mm.	No mechanical abnormality.
耐焊接热	使用基板: t=1.6mm的覆铜板。	不得有绝缘体的破损、变形、接触无异
M1 1/L1X 1/1	Preheating: 1、Surface temperature of board: 100°C or less.	常。
	2. Preheating time: within 1 min.	114 0
	预热: 基板表面温度100℃以下,时间1分钟以内。	
	Soldering: Solder temperature: 260±5°C or less	
	Immersion time: within 3 s	
	焊接: 温度260±5℃或以下,时间3秒以内。	

### EC1102 SERIES SPECIFICATION EC1102 系列规格书

#### Push switch portion 推动开关部分 Note: The following specification is only suitable for the one type with switch construction of EC11 encoder series. 注:以下规格只适用于此EC11编码器系列带开关结构。 1-1 Rated capacity (Resistance load ): DC 5V 10 mA (1 mA Min) 额定容量(电阻负荷): DC 5V 10 mA (1 mA 以上) 1-2 Electrical characteristics电气性能 **ITEM CONDITIONS SPECIFICATIONS** 项目 条件 规格 1-2-1 Contact resist-Voltage step-down test at DC 5V 1mA $100 \text{ m} \Omega \text{ Max}$ ance接触电阻 用DC 5V 1mA 电压降下法测定. 100 mΩ 以下 1-2-2 Bouncing Shaft shall be rotated at 1 cycles/S (OFF-ON-OFF) 10 ms Max 以1秒钟1往返(OFF-ON-OFF) 回转运转 振荡 10 ms 以下 1-2-3. Insulation res-Measurement shall be made under the condition which a voltage 250V Between individual terminals and bracket istance绝缘电阻 $100 \text{ M}\Omega \text{ Min.}$ DC 1min±5S is applied between individual terminals and tracked 在端子安装板间100 MΩ以上 在端子与安装板间施加电压DC 250V 1分钟±5秒。 1-2-4 Dielectric A voltage of 250V AC /min or 300 V AC /2S( leak current 1mA) be ap Without arcing or breakdown. strength plied between individual terminals and bracket.在端子与安装板间 不得有绝缘损坏。 施加AC 250V 1分钟或AC 300V 2秒钟(漏电流1mA) 耐电压 1-3 Mechanical characteristics机械性能 1-3-1 Switch circuit Single pole and single throw (push on) 单极单投(推ON) and number of pulse 开关电路、接点数 1-3-2 Travel of $0.5^{+0.2}_{-0.3}$ mm switch开关移动量 1-3-3 Operating force $5\pm3 \text{ N} \quad (500\pm300 \text{gf})$ of switch开关作动力 1-4 Endurance characteristics耐久性能 Contact resistance : $200 \text{m}\Omega$ max. Push operating life The encoder's shall be pushed to 20,000 cycles at a speed of 1800±300/H without electrical load.(shaft push load: 1 kgf Max.) Specification in clause 1-2-2~4.1-3-1~2 寿命特性 在无负荷条件下,对轴以每小时1800±300次的速度推动20,000次, shall be satisfied. (轴按压力1 kgf以下). Operating force:Before test 50%. 接触电阻:200mΩ以下. 1-2-2~4,1-3-1~2 满足初期规格. 开关动作力为寿命前的50%. 文控编号: EC-编制时间 版本号: 00 SOUNDWELL ELECTRONIC 2014-2-12 SOUNDWELL 变更记事: 变更时间 DSGD.主办 CHKD.审查 APPD. 核准 TITLE 标题: 技术部 技术部 技术部 ENCODER 编码器 19-09-20 19-09-20 19-09-20 EC1102-HA1-15P6正信号 欧阳昌雄 苏朝晖 李苗 DOCUMENT No.文号: