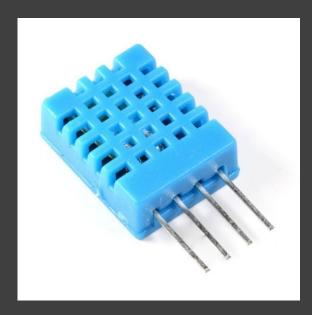
# Data Acquisition System Project Weather station

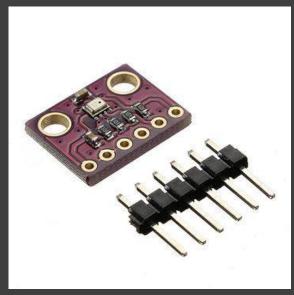
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## Components: input sensors

• Temperature and humidity sensor DHT11

• Pressure and temperature sensor BMP280





## Components: outputs

• Serial monitor

• 8x8 LED matrix

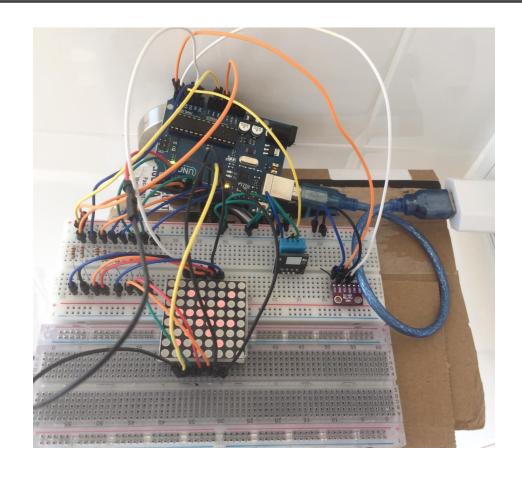




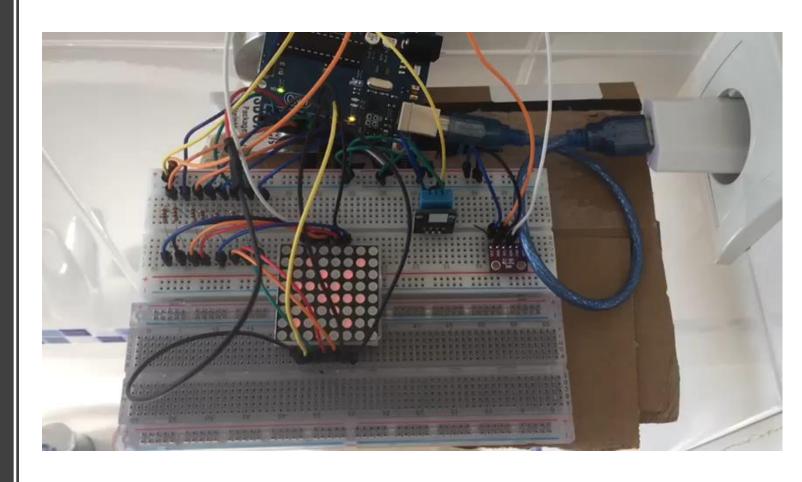
## Time schedule

## Implementation of the circuit

PIN	goes to	
2	>	*1st column
3	>	*5th row
4	>	3nd column
5	>	4th row
6	>	*7th row
7	>	*6th row
8	>	3rd row
9	>	*4th column
10	>	1st row
11	>	6th column
12	>	*7th column
13	>	2nd row
A0	>	1
A1	>	*2nd column
A2	>	5th column
А3	>	DHT
A4	>	SCL (BMP)
A5	>	SDA(BMP)



Implementation of the circuit



## Model used

The model used to predict the weather is based on humidity(H) and change in pressure(P).

H>65 % and  $\Delta$ P> 200 hPa in the last 3 h

probable bad weather in the following 24 hours

H<65 % regardless the P

probable good weather

## Humidity

## To do:

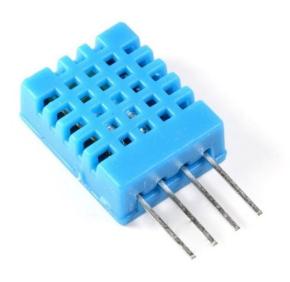
- Code the acquisition
- Test the data acquires

## <u>Time schedule</u>:

• 2 hours needed

## <u>Problem</u>:

none



```
#define DHT11_PIN 17

dht DHT;

int chk = DHT.read11(DHT11_PIN);

Serial.print(F("Humidity: "));
Serial.print(DHT.humidity);
Serial.println(" %");
```

## Pressure and Temperature

#### <u>To do</u>:

- Code the acquisition
- Test the data acquires

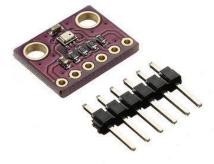
#### Time schedule:

• 7 hours

#### <u>Problems</u>:

- It's possible to acquire data only every 2 seconds
- A timer interrupts has been coded in order to get the right acquisition ratio without compromising the other functionality in the loop function
- Total time needed: 10 hours

```
#include <Adafruit_Sensor.h>
#include <Adafruit_BMP280.h>
Adafruit_BMP280 bmp;
void setup(){
  cli(); //stop interrupts
   //set timer0 interrupt at 62Hz
  TCCR0A = 0;// set entire TCCR0A register to 0
  TCCR0B = 0;// same for TCCR0B
  TCNT0 = 0;//initialize counter value to 0
  // set compare match register for 62hz increments
  OCR0A = 252;// = (16*10^6) / (2000*64) - 1 (must be <256)
  // turn on CTC mode
  TCCR0A = (1 << WGM01);
  TCCR0B |= (1 << CS12) | (1 << CS10);
  // enable timer compare interrupt
  TIMSK0 = (1 << OCIE0A);
ISR(TIMER0_COMPA_vect){
 inc0 = inc0 + 1;
  if (inc0 == 248)
    flagPrint = 1;
    inc0 = 0;
if(flagPrint == 1){
    Serial.print(F("Temperature: "));
    Serial.print(bmp.readTemperature());
    Serial.println(" °C ");
    Serial.print(F("Pressure: "));
    Serial.print(bmp.readPressure());
    Serial.println(" Pa ");
```



## Output devices

#### <u>To do</u>:

- Code the LED matrix
- Code the serial communications

#### <u>Time schedule</u>:

• 5 hours

#### Problems:

- Too many pins requested from the matrix in the board: two pins have been gained making the matrix a 7x7 LED matrix. Fillers number(99) have been used in code in order to keep the same scheme of coding of an 8x8 LED matrix
- It needs a very short time of refresh: time interrupts have been used for the other commands in the loop in order not to waste time in the loop providing the fastest refresh possible to the matrix
- Time needed: 7 hours



```
#define MatrixVector 65
 #define Ncolrow 8
 #define Npin 17
 int pins[Npin]= { 99, 5, 4, 3, 2, 99, 15, 16, 99, 13, 12, 11, 10, 9, 8, 7, 6};
 int cols[Ncolrow] = {pins[13], pins[10], pins[15], pins[9], pins[4], pins[16], pins[6], pins[1
 int rows[Ncolrow] = {pins[8], pins[7], pins[3], pins[14], pins[2], pins[12], pins[11], pins[5]
 int vect[MatrixVector];
int carSun [MatrixVector] = { ...
int carCloud [MatrixVector] = { // cloud matrix...
 void setup(){
      for (int i = 1; i <= (Npin-1); i++){ // I'm defining at output all the ports in the array
       pinMode(pins[i], OUTPUT);}
  for (int i = 1; i <= Ncolrow; i++) {// I'm switching off all the pin</pre>
     digitalWrite(cols[i - 1], LOW);
     digitalWrite(rows[i - 1], LOW);} }
  void loop(){
      for (r1 = 1; r1 <= Ncolrow; r1 ++){
     for (c1 = 1; c1 <= Ncolrow; c1 ++){
       if (vect [(r1-1)*Ncolrow + c1] == 1){ // BYTE = 1 (led to switch on)
           digitalWrite (rows [r1-1], HIGH); // active row (anod)
           digitalWrite (cols [c1-1], LOW);} // disactive (catod) and switch on the led on the
        digitalWrite (rows [r1-1], LOW); // disable the row (anod)
        digitalWrite (cols [c1-1], HIGH); // enable the column (catod) and switch off the led
```

## Model of prediction

### To do:

- Write down the model
- Code it

#### Time schedule:

• 2 hours

#### Problems:

- being sure that the code responds in the right way at each iteration taking in account also the previous output (ex. Previous output=bad weather, at the next iteration the difference in pressure is not satisfied any more but this doesn't mean that the weather is going to be good)
- 4 hours

```
(flagMemory == 1)
 hum = DHT.humidity;
 press[add] = bmp.readPressure();
  if (add >= 3)
   if (hum >= HumEdge)
          if ((press[add-3]-press[add]) >= PresDiffEdge || flagBadW == 1 )
            flagMatrix = 1;
            flagBadW = 1;
            }else
              flagMatrix = 0;
              flagBadW = 0;
 if (add == 71)
      add = 0;
      }else
        add = add + 1;
flagMemory = 0;
```

## Test of the system

## To do:

- test the system in different humidity and pressure situation
- Test the efficiency of the output

### Time schedule:

• 9 hours

### Problems:

- Time and different atmospheric situation are necessary to make a real test of the project: different humidity situations have been got artificially while the pressure is much more difficult to be handled with
- Time requested : 48 hours

## Possible improvement

Code the EEPROM memory in order to save the parameters that can be useful for other analysis:

- Problem: it's possible to save just integers and number smaller the 255
- Possible solution : use a union and save the number in different byte
- Cons: comparation for the estimation of the weather more tricky

Implement a real time clock in order to keep count of the time in which the board is switched off:

- Problem: it's needed a welder to prepare the hardware to use
- Cons: even with a real time clock, if the board has been switched off for a long time comparing the pressure data in the memory with the new ones doesn't make any sense: the board has to start to work as in the case of first use