

# Ch 3.3: Complex Roots of Characteristic Equation

- Recall our discussion of the equation

$$ay'' + by' + cy = 0$$

where  $a$ ,  $b$  and  $c$  are constants.

- Assuming an exponential soln leads to characteristic equation:

$$y(t) = e^{rt} \Rightarrow ar^2 + br + c = 0$$

- Quadratic formula (or factoring) yields two solutions,  $r_1$  and  $r_2$ :

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

- If  $b^2 - 4ac < 0$ , then complex roots:  $r_1 = \lambda + i\mu$  and  $r_2 = \lambda - i\mu$

Thus

$$y_1(t) = e^{(\lambda + i\mu)t}, \quad y_2(t) = e^{(\lambda - i\mu)t}$$

# Euler's Formula; Complex Valued Solutions

- Substituting  $it$  into Taylor series for  $e^t$ , we obtain **Euler's formula**:

$$e^{it} = \sum_{n=0}^{\infty} \frac{(it)^n}{n!} = \sum_{n=0}^{\infty} \frac{(-1)^n t^{2n}}{(2n)!} + i \sum_{n=1}^{\infty} \frac{(-1)^{n-1} t^{2n-1}}{(2n-1)!} = \cos t + i \sin t$$

- Generalizing Euler's formula, we obtain

$$e^{i\mu t} = \cos \mu t + i \sin \mu t$$

- Then

$$e^{(\lambda+i\mu)t} = e^{\lambda t} e^{i\mu t} = e^{\lambda t} [\cos \mu t + i \sin \mu t] = e^{\lambda t} \cos \mu t + i e^{\lambda t} \sin \mu t$$

- Therefore

$$y_1(t) = e^{(\lambda+i\mu)t} = e^{\lambda t} \cos \mu t + i e^{\lambda t} \sin \mu t$$

$$y_2(t) = e^{(\lambda-i\mu)t} = e^{\lambda t} \cos \mu t - i e^{\lambda t} \sin \mu t$$

## Real Valued Solutions

- Our two solutions thus far are complex-valued functions:

$$y_1(t) = e^{\lambda t} \cos \mu t + ie^{\lambda t} \sin \mu t$$

$$y_2(t) = e^{\lambda t} \cos \mu t - ie^{\lambda t} \sin \mu t$$

- We would prefer to have real-valued solutions, since our differential equation has real coefficients.
- To achieve this, recall that linear combinations of solutions are themselves solutions:

$$y_1(t) + y_2(t) = 2e^{\lambda t} \cos \mu t$$

$$y_1(t) - y_2(t) = 2ie^{\lambda t} \sin \mu t$$

- Ignoring constants, we obtain the two solutions

$$y_3(t) = e^{\lambda t} \cos \mu t, \quad y_4(t) = e^{\lambda t} \sin \mu t$$

# Real Valued Solutions: The Wronskian

- Thus we have the following real-valued functions:

$$y_3(t) = e^{\lambda t} \cos \mu t, \quad y_4(t) = e^{\lambda t} \sin \mu t$$

- Checking the Wronskian, we obtain

$$\begin{aligned} W &= \begin{vmatrix} e^{\lambda t} \cos \mu t & e^{\lambda t} \sin \mu t \\ e^{\lambda t} (\lambda \cos \mu t - \mu \sin \mu t) & e^{\lambda t} (\lambda \sin \mu t + \mu \cos \mu t) \end{vmatrix} \\ &= \mu e^{2\lambda t} \neq 0 \end{aligned}$$

- Thus  $y_3$  and  $y_4$  form a fundamental solution set for our ODE, and the general solution can be expressed as

$$y(t) = c_1 e^{\lambda t} \cos \mu t + c_2 e^{\lambda t} \sin \mu t$$

## Example 1 (1 of 2)

- Consider the differential equation

$$y'' + y' + 9.25y = 0$$

- For an exponential solution, the characteristic equation is

$$y(t) = e^{rt} \Rightarrow r^2 + r + 9.25 = 0 \Rightarrow r = \frac{-1 + \sqrt{1 - 37}}{2} = \frac{-1 \pm 6i}{2} = -\frac{1}{2} \pm 3i$$

- Therefore, separating the real and imaginary components,

$$\lambda = -\frac{1}{2}, \mu = 3$$

and thus the general solution is

$$y(t) = c_1 e^{-t/2} \cos(3t) + c_2 e^{-t/2} \sin(3t) = e^{-t/2} (c_1 \cos(3t) + c_2 \sin(3t))$$

## Example 1 (2 of 2)

- Using the general solution just determined

$$y(t) = e^{-t/2} \{c_1 \cos(3t) + c_2 \sin(3t)\}$$

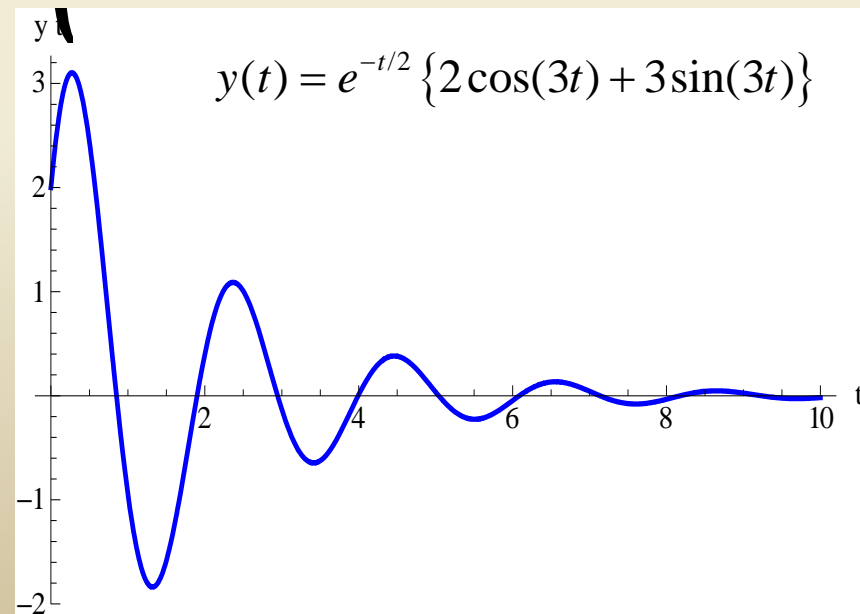
- We can determine the particular solution that satisfies the initial conditions  $y(0) = 2$  and  $y'(0) = 8$

$$\left. \begin{aligned} \text{So } y(0) &= c_1 = 2 \\ y'(0) &= -\frac{1}{2}c_1 + 3c_2 = 8 \end{aligned} \right\} \Rightarrow c_1 = 2, c_2 = 3$$

- Thus the solution of this IVP is

$$y(t) = e^{-t/2} \{2 \cos(3t) + 3 \sin(3t)\}$$

- The solution is a decaying oscillation

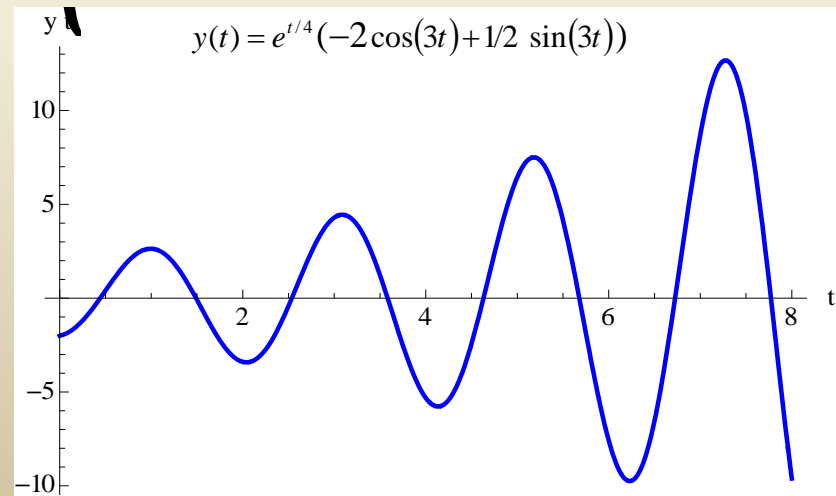


## Example 2

- Consider the initial value problem

$$16y'' - 8y' + 145y = 0, \quad y(0) = -2, \quad y'(0) = 1$$

- Then  $y(t) = e^{rt} \Rightarrow 16r^2 - 8r + 145 = 0 \Leftrightarrow r = \frac{1}{4} \pm 3i$
- Thus the general solution is  $y(t) = c_1 e^{t/4} \cos(3t) + c_2 e^{t/4} \sin(3t)$
- And 
$$\left. \begin{aligned} y(0) &= c_1 = -2 \\ y'(0) &= -\frac{1}{4}c_1 + 3c_2 = 1 \end{aligned} \right\} \Rightarrow c_1 = -2, c_2 = \frac{1}{2}$$
- The solution of the IVP is 
$$y(t) = -2e^{t/4} \cos(3t) + \frac{1}{2}e^{t/4} \sin(3t)$$
- The solution displays a growing oscillation



## Example 3

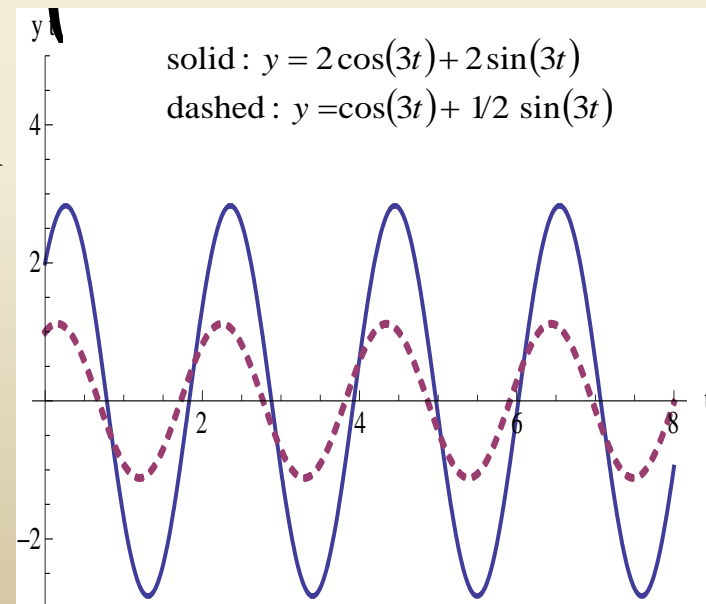
- Consider the equation

$$y'' + 9y = 0$$

- Then  $y(t) = e^{rt} \Rightarrow r^2 + 9 = 0 \Leftrightarrow r = \pm 3i$
- Therefore  $\lambda = 0, \mu = 3$
- and thus the general solution is

$$y(t) = c_1 \cos(3t) + c_2 \sin(3t)$$

- Because  $\lambda = 0$ , there is no exponential factor in the solution, so the amplitude of each oscillation remains constant. The figure shows the graph of two typical solutions





## Ch 3.4: Repeated Roots; Reduction of Order

- Recall our 2<sup>nd</sup> order linear homogeneous ODE

$$ay'' + by' + cy = 0$$

- where  $a$ ,  $b$  and  $c$  are constants.
- Assuming an exponential solution leads to characteristic equation:

$$y(t) = e^{rt} \Rightarrow ar^2 + br + c = 0$$

- Quadratic formula (or factoring) yields two solutions,  $r_1$  and  $r_2$ :

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

- When  $b^2 - 4ac = 0$ ,  $r_1 = r_2 = -b/(2a)$ , since method only gives one solution:

$$y_1(t) = ce^{-bt/(2a)}$$

## Second Solution: Multiplying Factor $v(t)$

- We know that

$$y_1(t) \text{ a solution} \Rightarrow y_2(t) = cy_1(t) \text{ a solution}$$

- Since  $y_1$  and  $y_2$  are linearly dependent, we generalize this approach and multiply by a function  $v$ , and determine conditions for which  $y_2$  is a solution:

$$y_1(t) = e^{-bt/(2a)} \text{ a solution} \Rightarrow \text{try } y_2(t) = v(t)e^{-bt/(2a)}$$

- Then

$$y_2(t) = v(t)e^{-bt/(2a)}$$

$$y_2'(t) = v'(t)e^{-bt/(2a)} - \frac{b}{2a}v(t)e^{-bt/(2a)}$$

$$y_2''(t) = v''(t)e^{-bt/(2a)} - \frac{b}{2a}v'(t)e^{-bt/(2a)} - \frac{b}{2a}v'(t)e^{-bt/(2a)} + \frac{b^2}{4a^2}v(t)e^{-bt/(2a)}$$

$$ay'' + by' + cy = 0$$

## Finding Multiplying Factor $v(t)$

- Substituting derivatives into ODE, we seek a formula for  $v$ :

$$e^{-bt/(2a)} \left\{ a \left[ v''(t) - \frac{b}{a} v'(t) + \frac{b^2}{4a^2} v(t) \right] + b \left[ v'(t) - \frac{b}{2a} v(t) \right] + cv(t) \right\} = 0$$

$$av''(t) - bv'(t) + \frac{b^2}{4a} v(t) + bv'(t) - \frac{b^2}{2a} v(t) + cv(t) = 0$$

$$av''(t) + \left( \frac{b^2}{4a} - \frac{b^2}{2a} + c \right) v(t) = 0$$

$$av''(t) + \left( \frac{b^2}{4a} - \frac{2b^2}{4a} + \frac{4ac}{4a} \right) v(t) = 0 \Leftrightarrow av''(t) + \left( \frac{-b^2}{4a} + \frac{4ac}{4a} \right) v(t) = 0$$

$$av''(t) - \left( \frac{b^2 - 4ac}{4a} \right) v(t) = 0$$

$$v''(t) = 0 \Rightarrow v(t) = k_3 t + k_4$$

# General Solution

- To find our general solution, we have:

$$\begin{aligned}y(t) &= k_1 e^{-bt/(2a)} + k_2 v(t) e^{-bt/(2a)} \\&= k_1 e^{-bt/(2a)} + (k_3 t + k_4) e^{-bt/(2a)} \\&= c_1 e^{-bt/(2a)} + c_2 t e^{-bt/(2a)}\end{aligned}$$

- Thus the general solution for repeated roots is

$$y(t) = c_1 e^{-bt/(2a)} + c_2 t e^{-bt/(2a)}$$

# Wronskian

- The general solution is

$$y(t) = c_1 e^{-bt/(2a)} + c_2 t e^{-bt/(2a)}$$

- Thus every solution is a linear combination of

$$y_1(t) = e^{-bt/(2a)}, y_2(t) = t e^{-bt/(2a)}$$

- The Wronskian of the two solutions is

$$\begin{aligned} W(y_1, y_2)(t) &= \begin{vmatrix} e^{-bt/(2a)} & t e^{-bt/(2a)} \\ -\frac{b}{2a} e^{-bt/(2a)} & \left(1 - \frac{bt}{2a}\right) e^{-bt/(2a)} \end{vmatrix} \\ &= e^{-bt/a} \left(1 - \frac{bt}{2a}\right) + e^{-bt/a} \left(\frac{bt}{2a}\right) \\ &= e^{-bt/a} \neq 0 \quad \text{for all } t \end{aligned}$$

- Thus  $y_1$  and  $y_2$  form a fundamental solution set for equation.

## Example 1 (1 of 2)

- Consider the initial value problem

$$y'' + 4y' + 4y = 0$$

- Assuming exponential soln leads to characteristic equation:

$$y(t) = e^{rt} \Rightarrow r^2 + 4r + 4 = 0 \Leftrightarrow (r + 2)^2 = 0 \Leftrightarrow r = -2$$

- So one solution is  $y_1(t) = e^{-2t}$  and a second solution is found:

$$y_2(t) = v(t)e^{-2t}$$

$$y_2'(t) = v'(t)e^{-2t} - 2v(t)e^{-2t}$$

$$y_2''(t) = v''(t)e^{-2t} - 4v'(t)e^{-2t} + 4v(t)e^{-2t}$$

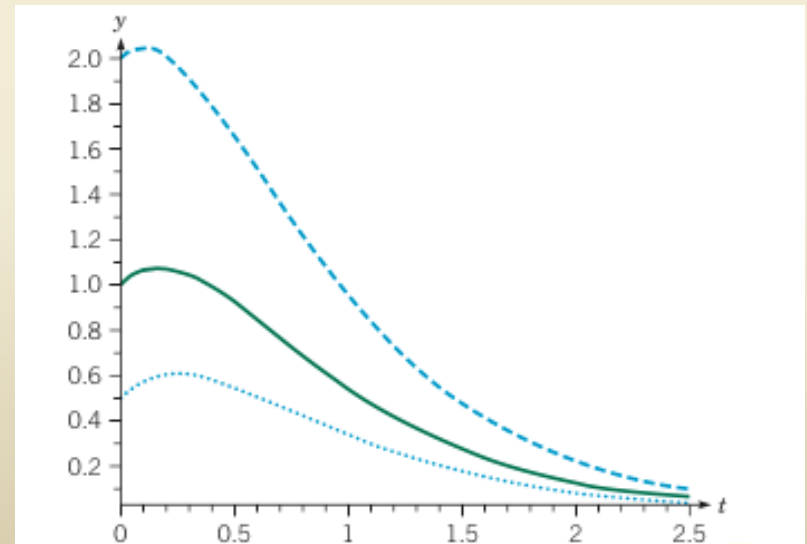
- Substituting these into the differential equation and simplifying yields  $v''(t) = 0$ ,  $v'(t) = k_1$ ,  $v(t) = k_1t + k_2$  where  $c_1$  and  $c_2$  are arbitrary constants.

## Example 1 (2 of 2)

- Letting  $k_1 = 1$  and  $k_2 = 0$ ,  $v(t) = t$  and  $y_2(t) = te^{-2t}$
- So the general solution is

$$y(t) = c_1 e^{-2t} + c_2 t e^{-2t}$$

- Note that both  $y_1$  and  $y_2$  tend to 0 as  $t \rightarrow \infty$  regardless of the values of  $c_1$  and  $c_2$
- Here are three solutions of this equation with different sets of initial conditions.
- $y(0) = 2, y'(0) = 1$  (top)
- $y(0) = 1, y'(0) = 1$  (middle)
- $y(0) = 1/2, y'(0) = 1$  (bottom)



## Example 2 (1 of 2)

- Consider the initial value problem

$$y'' - y' + \frac{1}{4}y = 0, \quad y(0) = 2, \quad y'(0) = \frac{1}{3}$$

- Assuming exponential solution leads to characteristic equation:

$$y(t) = e^{rt} \Rightarrow r^2 - r + \frac{1}{4} = 0 \Leftrightarrow \left(r - \frac{1}{2}\right)^2 = 0 \Leftrightarrow r = \frac{1}{2}$$

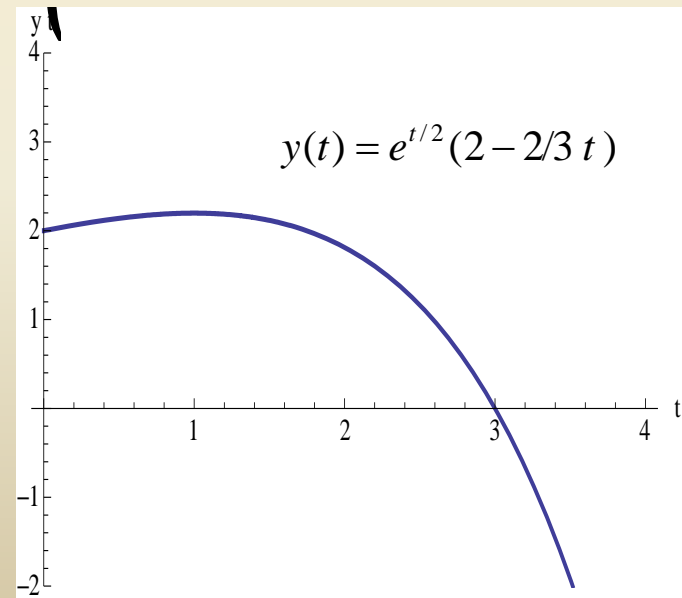
- Thus the general solution is

$$y(t) = c_1 e^{t/2} + c_2 t e^{t/2}$$

- Using the initial conditions:

$$\left. \begin{aligned} c_1 &= 2 \\ \frac{1}{2}c_1 + c_2 &= \frac{1}{3} \end{aligned} \right\} \Rightarrow c_1 = 2, \quad c_2 = -\frac{2}{3}$$

- Thus  $y(t) = 2e^{t/2} - \frac{2}{3}te^{t/2}$





## Example 2 (2 of 2)

- Suppose that the initial slope in the previous problem was increased

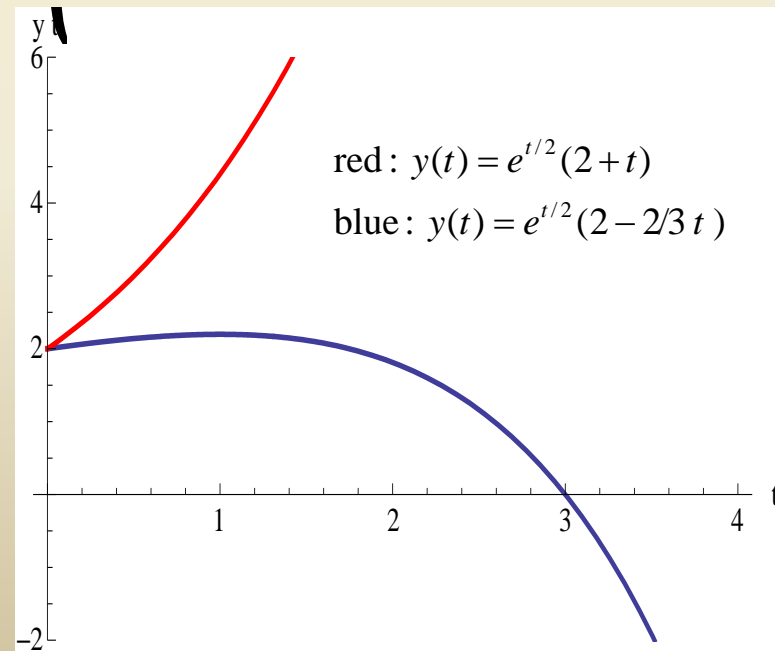
$$y(0) = 2, \quad y'(0) = 2$$

- The solution of this modified problem is

$$y(t) = 2e^{t/2} + te^{t/2}$$

- Notice that the coefficient of the second term is now positive. This makes a big difference in the graph, since the exponential function is raised to a positive power:

$$\lambda = \frac{1}{2} > 0$$



# Reduction of Order

- The method used so far in this section also works for equations with nonconstant coefficients:

$$y'' + p(t)y' + q(t)y = 0$$

- That is, given that  $y_1$  is solution, try  $y_2 = v(t)y_1$ :

$$y_2(t) = v(t)y_1(t)$$

$$y_2'(t) = v'(t)y_1(t) + v(t)y_1'(t)$$

$$y_2''(t) = v''(t)y_1(t) + 2v'(t)y_1'(t) + v(t)y_1''(t)$$

- Substituting these into ODE and collecting terms,

$$y_1v'' + (2y_1' + py_1)v' + (y_1'' + py_1' + qy_1)v = 0$$

- Since  $y_1$  is a solution to the differential equation, this last equation reduces to a first order equation in  $v$  :

$$y_1v'' + (2y_1' + py_1)v' = 0$$

## Example 3: Reduction of Order (1 of 3)

- Given the variable coefficient equation and solution  $y_1$ ,

$$2t^2 y'' + 3ty' - y = 0, \quad t > 0; \quad y_1(t) = t^{-1},$$

use reduction of order method to find a second solution:

$$y_2(t) = v(t) t^{-1}$$

$$y_2'(t) = v'(t) t^{-1} - v(t) t^{-2}$$

$$y_2''(t) = v''(t) t^{-1} - 2v'(t) t^{-2} + 2v(t) t^{-3}$$

- Substituting these into the ODE and collecting terms,

$$2t^2(v''t^{-1} - 2v't^{-2} + 2vt^{-3}) + 3t(v't^{-1} - vt^{-2}) - vt^{-1} = 0$$

$$\Leftrightarrow 2v''t - 4v' + 4vt^{-1} + 3v' - 3vt^{-1} - vt^{-1} = 0$$

$$\Leftrightarrow 2tv'' - v' = 0$$

$$\Leftrightarrow 2tu' - u = 0, \quad \text{where } u(t) = v'(t)$$

## Example 3: Finding $v(t)$ (2 of 3)

- To solve

$$2tu' - u = 0, \quad u(t) = v'(t)$$

for  $u$ , we can use the separation of variables method:

$$2t \frac{du}{dt} - u = 0 \Leftrightarrow \int \frac{du}{u} = \int \frac{1}{2t} dt \Leftrightarrow \ln|u| = 1/2 \ln|t| + C$$

$$\Leftrightarrow |u| = |t|^{1/2} e^C \Leftrightarrow u = ct^{1/2}, \text{ since } t > 0.$$

- Thus

$$v' = ct^{1/2}$$

and hence

$$v(t) = \frac{2}{3} ct^{3/2} + k$$

## Example 3: General Solution (3 of 3)

- Since  $v(t) = \frac{2}{3}ct^{3/2} + k$   
$$y_2(t) = \left( \frac{2}{3}ct^{3/2} + k \right) t^{-1} = \frac{2}{3}ct^{1/2} + k t^{-1}$$
- Recall that  $y_1(t) = t^{-1}$
- So we can neglect the second term of  $y_2$  to obtain
$$y_2(t) = t^{1/2}$$
- The Wronskian of  $y_1(t)$  and  $y_2(t)$  can be computed
$$W[y_1, y_2](t) = \frac{3}{2}t^{-3/2} \neq 0, \quad t > 0$$
- Hence the general solution to the differential equation is

$$y(t) = c_1 t^{-1} + c_2 t^{1/2}$$

# Euler's equation

- Sometimes a differential equation with variable coefficients equation

$$y'' + p(t)y' + q(t)y = 0$$

can be transformed to a linear differential equation with constant coefficients by a change of variables.

- Consider the so-called Euler's equation

$$t^2 y'' + \alpha t p(t) y' + \beta q(t) y = 0$$

where  $\alpha$  and  $\beta$  are some constants (real numbers)

- Let  $t = e^x \Rightarrow x = \ln t$
- Since now  $y = y(t(x)) = y(x)$ , by the chain rule we have

$$\frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt} = \frac{dy}{dx} \frac{1}{t}$$

# Euler's equation

- For the second derivative we have

$$\begin{aligned}\frac{d^2 y}{dt^2} &= \frac{d}{dt} \left( \frac{dy}{dt} \right) = \frac{d}{dt} \left( \frac{dy}{dx} \frac{1}{t} \right) = \frac{d}{dt} \left( \frac{dy}{dx} \right) \frac{1}{t} + \frac{dy}{dx} \frac{d}{dt} \left( \frac{1}{t} \right) = \\ &= \frac{d}{dx} \left( \frac{dy}{dx} \right) \frac{dx}{dt} \frac{1}{t} - \frac{dy}{dx} \frac{1}{t^2} = \frac{d^2 y}{dx^2} \frac{1}{t^2} - \frac{dy}{dx} \frac{1}{t^2}\end{aligned}$$

Then the original equation is transformed to

$$t^2 \left\{ \frac{d^2 y}{dx^2} - \frac{dy}{dx} \right\} \frac{1}{t^2} + \alpha t \frac{dy}{dx} \frac{1}{t} + \beta y = \frac{d^2 y}{dx^2} + (\alpha - 1) \frac{dy}{dx} + \beta y = 0$$

- We can solve it and find  $y(x) = y(\ln t)$
- If  $y_1(x)$  and  $y_2(x)$  form a fundamental set of solutions in  $x$  then  $y_1(\ln t)$  and  $y_2(\ln t)$  form a fundamental set in  $t$

## Example 3 revisited

- Consider the differential equation from Example 3:

$$2t^2 y'' + 3t y' - y = 0 \quad \Rightarrow \quad t^2 y'' + \frac{3}{2}t y' - \frac{1}{2}y = 0$$

It is the Euler's equation with  $\alpha = 3/2$ ,  $\beta = -1/2$

- Upon substitution  $x = \ln t$  it is transformed to

$$\frac{d^2 y}{dx^2} + \frac{1}{2} \frac{dy}{dx} - \frac{1}{2} y = 0$$

which we know how to solve.

- The characteristic equation is  $r^2 + r/2 - 1/2 = 0$  with the roots  $r_1 = -1$ ,  $r_2 = 1/2$ . Therefore  $y(x) = C_1 e^{-x} + C_2 e^{x/2}$
- Upon transforming back to  $t$  we finally get

$$y = C_1 e^{-\ln t} + C_2 e^{\frac{1}{2} \ln t} = C_1 e^{\ln t^{-1}} + C_2 e^{\ln t^{1/2}} = C_1 t^{-1} + C_2 t^{1/2}$$