

Exercises in Physics

Assignment # 5

Date Given: May 12, 2022

Date Due: May 19, 2022

P1. (2 points) Find an equation in polar coordinates that has the same graph as the given equation in rectangular coordinates.

(a) $\left(x - \frac{3}{2}\right)^2 + y^2 = \frac{9}{4}$

(b) $\sqrt{(x^2 + y^2)^3} = 3(x^2 - y^2)$

Solution:

(a) $r = 3 \cos \theta$

(b) $r = 3 \cos 2\theta$

P2. (2 points) Sketch the curves

(a) $r = 3 \cos \theta$

(b) $r = 3 \cos 2\theta$

Solution:

(a) As established in Problem P1(a), this curve in rectangular coordinates has the form $\left(x - \frac{3}{2}\right)^2 + y^2 = \frac{9}{4}$, which is apparently the equation for the circle of radius $3/2$ with the center in $(3/2, 0)$.

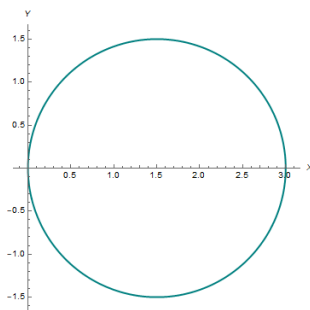


Figure 1: Illustration to Problem 2(a).

(b) The curve can be sketched by plotting points (θ, r) , by setting different values for the angle θ and computing the corresponding values of the radius r . For $\theta \in [0, \pi]$ we get $(0, 3)$, $\left(\frac{\pi}{6}, \frac{3}{2}\right)$, $\left(\frac{\pi}{4}, 0\right)$, $\left(\frac{\pi}{3}, -\frac{3}{2}\right)$, $\left(\frac{\pi}{2}, -3\right)$, $\left(\frac{2\pi}{3}, -\frac{3}{2}\right)$, $\left(\frac{3\pi}{4}, 0\right)$, $\left(\frac{5\pi}{6}, \frac{3}{2}\right)$, $(\pi, 3)$. Plotting them will produce a sketch shown on the left side of Figure 2. The full sketch, obtained for $\theta \in [0, 2\pi]$ is shown on the right side of Figure 2.

P3. (2 points) A jet plane flying at a constant speed v at an altitude $h = 10\text{km}$ is being tracked by radar located at O directly below the line of flight. If the angle θ is decreasing at the rate 0.02 rad/s when $\theta = 60^\circ$, determine the value of \ddot{r} at this instant and the magnitude of the velocity \mathbf{v} of the plane.

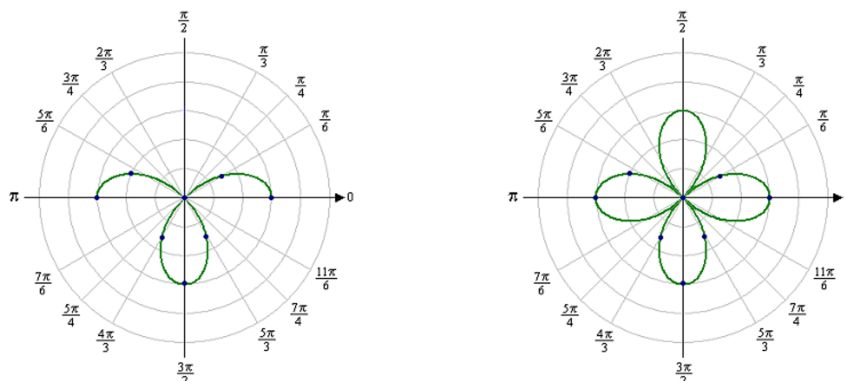


Figure 2: Illustration to Problem 2(b).

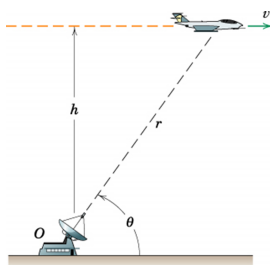


Figure 3: Illustration to Problem 3.

Solution: Since $v = \text{const}$, the acceleration vector \mathbf{a} is zero (in all directions), and therefore $a_r = 0$ and $a_\theta = 0$. From $a_r = \ddot{r} - r\dot{\theta}^2 = 0$ we have $\ddot{r} = r\dot{\theta}^2$, where $\dot{\theta} = -0.02 \text{ rad/s}$. Next, since $r = h/\sin \theta$, we can define $r = \frac{10}{\sqrt{3}/2} \approx 11.547 \approx 11.55 \text{ km}$ and compute

$$\ddot{r} = 11.55(-0.020)^2 = 0.00462 \text{ km/s}^2 = 4.62 \text{ m/s}^2.$$

Having defined r , there are several ways to define v . They can be outlined as follows.

1. From geometric considerations (see Figure 4) it follows that

$$v = |r\dot{\theta}|/\sin \theta = |h\dot{\theta}|/\sin^2 \theta = \frac{|10(-0.02)|}{(\sqrt{3}/2)^2} \approx 0.267 \text{ km/s} \approx 267 \text{ m/s} \approx 960 \text{ km/h}.$$

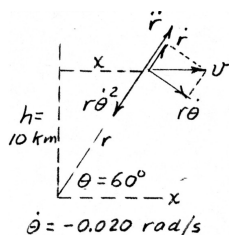


Figure 4: Illustration to Problem 3.

2. For this problem we have $v_r = \dot{r} = v \cos \theta$ and $v_\theta = r\dot{\theta} = -v \sin \theta$. Therefore $v_r/v_\theta = -\cot \theta$ and $\dot{r} = -r\dot{\theta} \cot \theta = -11.55(-0.02)/\sqrt{3} \approx 0.133 \text{ km/s}$, and from $v = \sqrt{v_r^2 + v_\theta^2} = \sqrt{\dot{r}^2 + r^2\dot{\theta}^2} \approx 0.267 \text{ km/s} \approx 267 \text{ m/s} \approx 960 \text{ km/h}$.

3. Yet another (and more general, not requiring v to be constant) way to establish v is as follows. By the problem settings $\mathbf{v} = v\mathbf{i}$. On the other hand, $\mathbf{v} = v_r\mathbf{e}_r + v_\theta\mathbf{e}_\theta$. Recall that

$$\mathbf{e}_r = \cos\theta\mathbf{i} + \sin\theta\mathbf{j} \quad \text{and} \quad \mathbf{e}_\theta = -\sin\theta\mathbf{i} + \cos\theta\mathbf{j}.$$

Therefore

$$v\mathbf{i} = v_r(\cos\theta\mathbf{i} + \sin\theta\mathbf{j}) + v_\theta(-\sin\theta\mathbf{i} + \cos\theta\mathbf{j}) = (v_r\cos\theta - v_\theta\sin\theta)\mathbf{i} + (v_r\sin\theta + v_\theta\cos\theta)\mathbf{j}.$$

From this vector equation we have $v = v_r\cos\theta - v_\theta\sin\theta$ and $0 = v_r\sin\theta + v_\theta\cos\theta$. From the second equation we obtain $v_r = \dot{r} = -v_\theta\cot\theta = -r\dot{\theta}\cot\theta \approx 0.133\text{km/s}$, and from the first equation we establish $v = \dot{r}\cos\theta - r\dot{\theta}\sin\theta \approx 0.267\text{km/s} \approx 267\text{m/s} \approx 960\text{km/h}$

- P4. (4 points)** The slider P can be moved inward by means of the string S as the bar OA rotates about the pivot O . The angular position of the bar is given by $\theta(t) = 0.4 + 0.12t + 0.06t^3$, where θ is in radians and t is in seconds. The position of the slider is given by $r(t) = 0.8 - 0.1t - 0.05t^2$, where r is in meters and t is in seconds.

- Determine the velocity \mathbf{v} and acceleration \mathbf{a} (in terms of \mathbf{e}_r and \mathbf{e}_θ) of the slider at time $t = 2\text{s}$.
- Find the angles which \mathbf{v} and \mathbf{a} make with the positive x -axis (that is the angles between \mathbf{v} and \mathbf{i} and between \mathbf{a} and \mathbf{i}).

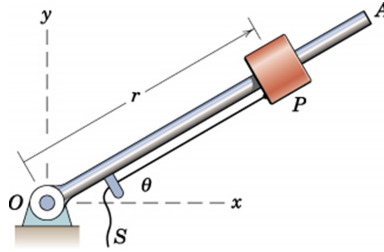


Figure 5: Illustration to Problem 4.

Solution: Here we have

$$\begin{aligned} \theta(t) &= 0.4 + 0.12t + 0.06t^3, & r(t) &= 0.8 - 0.1t - 0.05t^2, \\ \dot{\theta}(t) &= 0.12 + 0.18t^2, & \dot{r}(t) &= -0.1 - 0.1t, \\ \ddot{\theta}(t) &= 0.36t, & \ddot{r}(t) &= -0.1. \end{aligned}$$

At $t = 2\text{s}$ we have

$$\begin{aligned} \theta &= 1.12\text{ rad} & r &= 0.4\text{ m} \\ \dot{\theta} &= 0.84\text{ rad/s} & \dot{r} &= -0.3\text{ m/s} \\ \ddot{\theta} &= 0.72\text{ rad/s}^2 & \ddot{r} &= -0.1\text{ m/s}^2 \end{aligned}$$

Therefore

$$\mathbf{v} = v_r\mathbf{e}_r + v_\theta\mathbf{e}_\theta = \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta = -0.3\mathbf{e}_r + 0.336\mathbf{e}_\theta \text{ m/s}$$

$$\mathbf{a} = a_r\mathbf{e}_r + a_\theta\mathbf{e}_\theta = (\ddot{r} - r\dot{\theta}^2)\mathbf{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\mathbf{e}_\theta = -0.382\mathbf{e}_r - 0.216\mathbf{e}_\theta \text{ m/s}^2$$

To find the angle between \mathbf{v} and \mathbf{i} one notices that $\mathbf{v} \cdot \mathbf{i} = |\mathbf{v}||\mathbf{i}|\cos(\widehat{\mathbf{v}, \mathbf{i}}) = |\mathbf{v}|\cos(\widehat{\mathbf{v}, \mathbf{i}})$. On the other hand, $\mathbf{v} \cdot \mathbf{i} = (v_r\mathbf{e}_r + v_\theta\mathbf{e}_\theta) \cdot \mathbf{i} = v_r(\mathbf{e}_r \cdot \mathbf{i}) + v_\theta(\mathbf{e}_\theta \cdot \mathbf{i})$. Recall that $\mathbf{e}_r = \cos\theta\mathbf{i} + \sin\theta\mathbf{j}$ and $\mathbf{e}_\theta = -\sin\theta\mathbf{i} + \cos\theta\mathbf{j}$, and therefore $(\mathbf{e}_r \cdot \mathbf{i}) = \cos\theta$ and $(\mathbf{e}_\theta \cdot \mathbf{i}) = -\sin\theta$. Therefore

$$\cos(\widehat{\mathbf{v}, \mathbf{i}}) = \frac{v_r\cos\theta - v_\theta\sin\theta}{\sqrt{v_r^2 + v_\theta^2}} \approx -0.96159$$

and

$$\widehat{\mathbf{v}, \mathbf{i}} = 2.86353 \text{ rad} = 164.068^\circ.$$

Similarly, in finding the angle between \mathbf{a} and \mathbf{i} we have $\mathbf{a} \cdot \mathbf{i} = |\mathbf{a}| \cos(\widehat{\mathbf{a}, \mathbf{i}})$, and on the other hand $\mathbf{a} \cdot \mathbf{i} = (a_r \mathbf{e}_r + a_\theta \mathbf{e}_\theta) \cdot \mathbf{i} = a_r (\mathbf{e}_r \cdot \mathbf{i}) + a_\theta (\mathbf{e}_\theta \cdot \mathbf{i}) = a_r \cos \theta - a_\theta \sin \theta$. Therefore

$$\cos(\widehat{\mathbf{a}, \mathbf{i}}) = \frac{a_r \cos \theta - a_\theta \sin \theta}{\sqrt{a_r^2 + a_\theta^2}} \approx 0.0635156$$

and

$$\widehat{\mathbf{a}, \mathbf{i}} = 1.50724 \text{ rad} = 86.3584^\circ.$$