

### UC24A

# **Universal Controllers with Digital Display**

#### **Features**

- Large easy-to-read liquid crystal display (LCD), with LED backlight (white)
- A stylish bi-directional rotating dial and two compact touch keys to provide ease of operation
- Choice of single on-off or 0-10 VDC output, on-off plus 0-10 VDC outputs or dual 0-10 VDC outputs
- Configurable operating parameters and selectable functions via setup menu
- Choice of engineering units and display scale
- Universal input for variuous applications
- PI or P control algorithm
- Digital input for day/night changeover
- Digital input for economy mode activation
- Retains last entered settings on power resumption

#### **Selectable Functions**

- Choice of 9 application specfic control models
- Configurable primary input to suit passive TE10 NTC temperature sensor or active 0-10 VDC
- Choice of °C, °F, % or no specified unit
- Choice of display range and setpoint range
- Secondary 0-10 VDC input for remote setpoint override or higher signal selection
- Adjustable proportional band and integral time
- Adjustable 0(2)-10 VDC output limit
- Adjustable ECO mode setpoint value
- Adjustable setpoint differential (SD) value

- Adjustable control bandwidth (CB)
- Offset adjustment of measured value reading
- Choice of constant display of primary analog input value or setpoint value
- Choice of 0-10 VDC or 2-10 VDC outputs via jumper setting

#### General

The UC24A Series microprocessorbased universal controllers with digital display are designed for comfort control in heating, ventilating, airconditioning and refrigeration installations. They can be mounted on a control panel or wall in plant rooms.

The UC24A Series is a stand-alone universal controller which performs both primary and auxiliary control functions. Applications include measurement and control of temperature, relative humidity, absolute humidity, enthalpy, pressure differential, volumetric airflow and indoor air quality. The input scale can be set from –99 to 999 units. The start and end points of output voltage can be any value from 0 to 10 VDC.

The microprocessor combines a proportional plus integral (PI) algorithm with advanced adaptive control logic. The proportional component of the algorithm adjusts the control output in response to changes in the measured environment. The integral component of the algorithm adjusts the control



output to eliminate offset (difference between the setpoint and the actual sensing element). This provides precise and stable control under various system capacity and varying load conditions without the need for tuning or calibrating the control algorithm in the field. The digital display of input value, setpoint value and operating mode provides the user with an attractive and functional controller that is easy to use.

A bi-directional rotating dial allows change of settings such as temperature setpoint values.

#### Ordering

To order, specify complete model number.

# Figure 1: Display Control Unit Layout

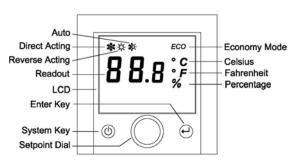
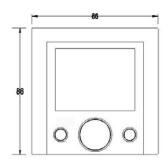




Figure 2: Dimensions in mm



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# **Specifications**

Product model number	UC24A
Power requirements	24 V ±15%, 50/60 Hz
Power consumption	1 VA @ 24 VAC
Analog outputs	2-10 or 0-10 VDC jumper selectable, factory setting 0-10 VDC
Display range	-99 to 999 in 1 increments: accuracy ±1
Setpoint range	-99 to 999 in 1 increments: accuracy ±1
Constant display on LCD	Choice of constant display of analog input or setpoint value
Offset adjustment of indication	-50 to 99, factory setting 0
Display engineering unit	°C, °F, % or no specified unit
Proportional band	Adjustable 1 to 20 for °C, °F or % engineering unit setting, factory setting 5; Adjustable 1 to 99 for no specified engineering unit setting
Integral time	Adjustable 0 to 30 minutes in 1 minute increments, factory setting 15 minutes.  Setting = 0 means integral time being turned off.
Universal input X1	Passive TE10 NTC temperature sensor (-50 to 110°C) or 0-10 VDC active input
Analog input X2	0-10 VDC active input
Analog outputs Y1 and Y2	0(2)-10 VDC, 20,000 $\Omega$ minimum output impedance, 1,000 $\Omega$ internal impedance
Digital output Q1	20 VA @ 24 VAC
Input sampling time	2 s
Setpoint differential for on-off control mode (SD)	1-20 for °C, °F or % engineering unit setting, factory setting 1); 1-99 for no specified unit
Independent deadband between RA and DA setpoints	-99 to 99
0(2)-10 VDC outputs	Choice of 0-10 VDC or 2-10 VDC output via jumper JP2 (factory setting 0-10 VDC)
High-end and low-end setpoint values	See parameters setup menu
Day/night action control changeover	Via external contact
Enclosure	Material: Self-extinguishing, molded ABS
	Finish: Off white housing and dark grey faceplate
Protective class	IP30
Ambient/Storage temperature limits	0 to 50°C / -30 to 50°C, 10% to 90% RH non-condensing
Electrical ratings	On-off output: 24 V, 0.3 A resistive, 0.3 A inductive, 50/60 Hz
Connectors	Non-removable screw-type terminal blocks
Power and voltage signal wires	Wire size 1 mm <sup>2</sup> or 18 AWG solid copper recommended
Temperature sensor wires	22 AWG twisted shielded pair double-insulated cable
Accessories and options	See Figure 6: Accessories
Agency approval	CE Mark compliant to EMC Directive pending
Dimensions	See Figure 2: Dimensions in mm
Shipping weight	0.12 kg (0.3 lb)

The performance specifications above are nominal and subject to tolerances and application variables of generally acceptable industry standards.

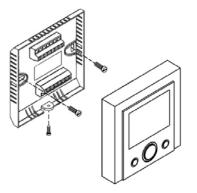
The manufacturer shall not be liable for damages resulting from misapplication or misuse of its products.

### **Figure 3: Cover Removal Procedure**



- 1. Loosen the fixed screw.
- Slightly twist the screw driver to crack open the cover from the base.
- Hold the base firmly with one hand and remove the cover with another hand by pulling away from the base forcibly.

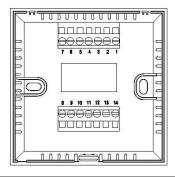
# Figure 4: Mounting Details

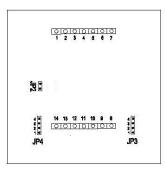


### Mounting

The universal controller can be surface mounted or secured to a standard European 75 x 75 x 35 mm electrical box or on a control panel. See Figure 4: Mounting Details. Two mounting screws are included.

Figure 5: Wiring Terminals and Jumper Settings



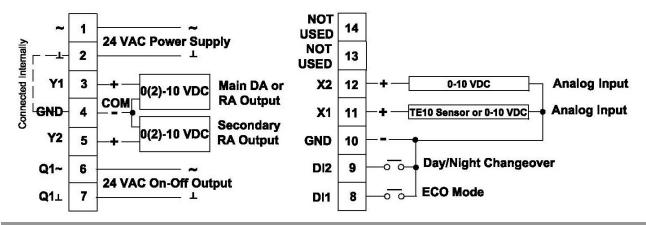


	Jumper Settings		
Jumper	Jumper Position		
JP2	Open for 2-10 VDC output and closed for 0-10 VDC output (factory setting)		
JP3	Type of X1 input: insertion of 3 & 4 for 0-10 VDC active input (factory setting); 1 & 2 for TE10 Series NTC sensor input		
JP4	Always at positions 3 and 4 for X2 with 0-10 VDC active input		

Figure 6: Accessories

Description	Part No.
Probe-type Temperature Sensor	TE10-1
Duct-mount Temperature Sensor	TE10-2
Wall-mount Temperature Sensor	TE10-3

Figure 7: Wiring Diagram



## **Inputs and Outputs**

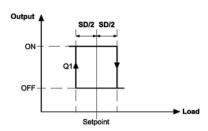
Input/Output Point	Terminal No	<u>Description</u>
Universal input X1	11	The universal input X1 is used as the primary input with a passive TE10
		Series temperature sensor or a 0-10 VDC active signal. Refer to jumper
		Settings table and setup menu for setting details.
Analog input X2	12	The analog input X2 is used as the secondary input with a 0-10 VDC active
		signal that allows remote setpoint override, higher input signal priority or .
		higher output priority. Refer to setup menu for configuring details.
Digital input DI1	8	The digital input DI1 is used to activate the ECO (economy or energy
		saving) mode.
Digital input DI2	9	The digital input DI2 is used to activate day/night changeover.
Analog output Y1	3	The 0-10 VDC output can be configured for either reverse acting (RA) or .
		direct acting (DA).
Analog output Y2	5	The 0-10 VDC output is for reverse acting only.
Digital output Q1	6 & 7	The 24 VAC output can be configured for either reverse action or direct.
		action.

# **Graphic Representation of Application Specific Control**

Application No. 1: Single RA On-Off Output

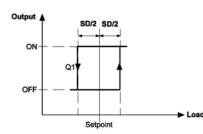
Application No. 2: Single DA On-Off Output

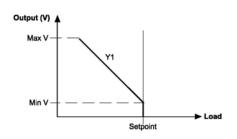
Application No. 3: Single RA 0(2)-10VDC Output



Max V

Min V

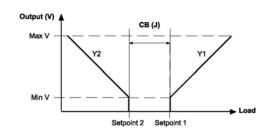




Application No. 4: Single DA 0(2)-10VDC Output

Single DA 0(2)-10VDC Output

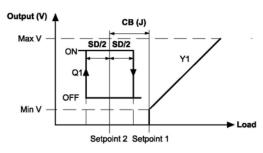
Output (V)

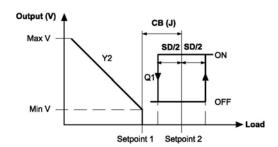


Application No. 5: DA 0(2)-10 VDC + RA 0(2)-10VDC Outputs

Application No. 6:
DA 0(2)-10 VDC + RA On-Off Outputs

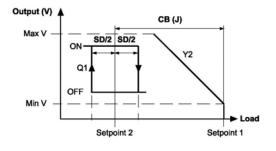
Application No. 7: RA 0(2)-10 VDC + DA On-Off Outputs

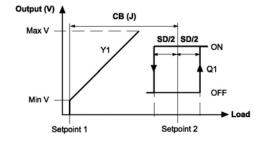




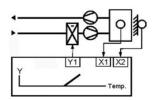
Application No. 8: RA 0(2)-10 VDC + RA On-Off Outputs

Application No. 9: DA 0(2)-10 VDC + DA On-Off Outputs



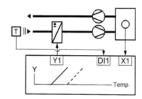


### Typical Applications of X1, X2, DI1 and DI2



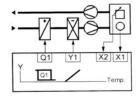
#### **Higher Input Priority**

X2 is acting as the input signal to calculate the output value of Y1 when its value is greater than the value of X1 and its value will be displayed on the LCD.



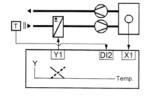
#### **ECO** mode

The local setpoint will be overridden by ECO mode setpoint when DI1 contact is closed



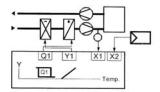
#### Remote Setpoint Override

A 0-10VDC signal input to X2 is acting as remote setpoint for Y1/Q1 outputs and its value will be displayed on the



### Day/night Changeover

The action of Y1 output is reversed when DI2 contact is closed.



#### **Higher Output Priority**

X2 is acting as the output value of Y1 when its value is greater than the calculated output value of the cooling sequence. X2 must be the output from another controller.

**Notes**: For details on how to configure X1, X2 and ECO mode functions, refer to the setup menu shown on Page 6. Illustration of application specific control is provided on Page 4.

### **Wiring Notes**

- The controller is designed for 24 VAC power supply.
- Move jumper JP2 to open position if 2-10 VDC proportional output is required.
- Conventional cables can be used for the controller but shielded cables are recommended if and when installed in an intense EMI environment.
- 22 or 24 AWG twisted shielded pair double-insulated cable is recommended as temperature sensor wiring and its length must not exceed 25 m.
- Do not bundle and run power wiring and sensor wiring in the same conduit.
- Run the external sensor wires away from any electric motors or power wiring. Failure to do so may result in poor controller performance due to electrical noise.
- When several isolated double-wound step-down transformers are used in a control loop, observe the polarities of the AC power supply of all devices including the universal controller.

### **Operation Notes**

#### Operation

- LCD shows ambient temperature constantly except when set point adjustment is being made.
- $\blacksquare$  Press the system key  $\Phi$  to enter into the desired operating mode.
- Increase or decrease temperature set point by rotating the adjustment dial clockwise or counter-clockwise. When the dial is rotated, the LCD shows the existing setpoint setting.

#### **ECO** mode

- When the ECO contact closes, it will override the operating mode and operate the controller in energy saving mode despite the controller being in operating or standby mode.
- In ECO mode, the factory-set cut-in points will be activated and all operating keys are locked out until the ECO contact opens.

### Day/Night Mode

When the DI2 contact closes, it will reverse the Y1 output action of the controller and maintain the desired ambient temperature at night.

#### **Parameter Setup Mode**

The controller allows authorized service agent to change a number of operating parameters in the field. For setup procedure details, refer to the parameter setup manual.

### **Error Reporting**

All controller outputs will be shut down when error is reported.

# Parameter Setup Menu

Symbol	Function	Description
0	MCU firmware revision level	Firmware revision 0x.x appears after entering the setup menu
1	Choice of application specific control	ID I = application 01 - single RA on-off output ID2 = application 02 - single DA on-off output ID3 = application 03 - single RA 0-10 VDC output ID4 = application 04 - single DA 0-10 VDC output (factory setting) ID5 = application 05 - dual DA 0-10 VDC and RA 0-10 VDC outputs ID6 = application 06 - dual DA 0-10 VDC and RA on-off outputs ID7 = application 07 - dual RA 0-10 VDC and DA on-off outputs ID8 = application 08 - dual RA 0-10 VDC and RA on-off outputs ID9 = application 09 - dual DA 0-10 VDC and DA on-off outputs
5	Configuration of universal input X1	20 I = active 0-10 VDC (factory setting) when JP3 is shorted between 3 & 4 202 = passive TE10 Series NTC sensor when JP3 is shorted between 1 & 2
Ξ	Choice of engineering unit	∃-C = °C ∃-F = °F ∃-P = % (factory setting) ∃-D = no specified unit
4	Low-end value of universal input readout (X1)	From: -50 (when 202 and 3-C are set), default setting = -50 or -99 (when 201 and 3-C, 201 and 3-F, or 201 and 3-0 are set), default setting = 0 or -58 (when 202 and 3-F are set), default setting = 58 or 0 (when 201 and 3-P are set) (factory setting)  To: current high-end value of X1 minus 4 units
5	High-end value of universal input readout (X1)	From: current low-end value of X1 plus 4 To: IID (when 202 and 3-£ are set), default setting = IID or 999 (when 201 and 3-£, 201 and 3-F, or 201 and 3-D are set), default setting = 50 or 230 (when 202 and 3-F are set), default setting = 230 or IDD (when 201 and 3-P are set) (factory setting)
6		500 = no action (factory setting) 60 I = remote setpoint override (local setpoint value overriden by X2 value) 602 = higher input priority (X1 is overriden by X2 only when X2 value is higher) 603 = higher output priority (0-10 VDC calculated output value of Y1 is overridden by X2 value when X2 value is higher)
7	Proportional band	When <b>3-</b> C, <b>3-</b> F or <b>3-</b> P is selected, <b>10</b> I = 1 <b>705</b> = 5 (factory setting) <b>720</b> = 20; When <b>3-0</b> is selected, <b>70</b> I = 1 <b>199</b> = 99
8	Integral time	<b>BDD</b> = 0 min <b>B I5</b> = 15 min. (factory setting) <b>B3D</b> = 30 min.; setting = 0 means integral time being turned off.
A	Low-end value of X1 setpoint range	From low-end value of universal input readout of X1 to high-end value of setpoint range minus 4 units
Ь	High-end value of X1 setpoint range	From low-end value of setpoint range plus 4 units to high-end value of universal input readout of X1
C	Minimum limit of Y1 and Y2 outputs (Min %)	From c@@ (factory setting) to value of maximum limit minus 1 (Example: c@ ! = 10%)
Ь	Maximum limit of Y1 and Y2 outputs (Max %)	From value of minimum limit plus 1 to d ID (factory setting) (Example: d ID = 100%)
Ε	ECO mode setpoint value of RA output(s)	From low-end value of setpoint range to ECO mode DA setpoint value minus 4
F	ECO mode setpoint value 0f DA output(s)	From ECO mode RA setpoint value plus 4 to high-end value of setpoint range
G	Setpoint differential (SD)	GD I = 1 (factory setting)G2D = 20 when 3-C, 3-F or 3-P is selected; or GD I = 1G59 = 99 when 3-D is selected
h	Display offset for readout value of X1 input	-50 to 99, factory setting = 0
ם	Control bandwidth between setpoint 1 and setpoint 2 (available and functional only for Applications No. 5, 6, 7, 8 and 9)	-99 to 99, factory setting = 2
u	Choice of constant display of X1 input or set- point value	u- I = constant display of X1 input value (factory setting) u- Z = constant display of setpoint value
rs	Restoration of default factory settings	Γ5 I = Retain current settings (factory setting) Γ52 = Restore default factory settings

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