MEGAN ROSE LEA AUGER

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EDUCATION

UNIVERSITY OF WASHINGTON, Seattle, WA

PhD Mechanical Engineering
MS Applied Mathematics
MS Mechanical Engineering

Expected June 2023 Expected June 2021 June 2020

COLORADO SCHOOL OF MINES, Golden, CO

BS Mechanical Engineering
Minor in Biomechanical Engineering

Magna Cum Laude *May 2018*

AWARDS & HONORS

National Science Foundation Graduate Research Fellow *Awarded full funding and support for demonstrated potential to contribute to strengthening the vitality of the U.S. science and engineering enterprise* **Sigma Xi Scientific Research Honor Society** *Invited to become an associate member based on independent investigation in a field of pure or applied science*

Michael R. and Patricia K. Starzer Endowment Scholar Awarded full tuition and fees for academic excellence and campus involvement

Don L. and Patricia Warner Scholarship Fund for the Board of Trustees Honors Scholar *Awarded scholarship for academic excellence, participation in varsity athletics, and demonstration of financial need*

Mines Presidential Merit Scholar Awarded scholarship for academic excellence upon beginning undergraduate studies E-Days Engineer Award Selected by the Department of Mechanical Engineering as an outstanding graduating senior

RESEARCH

Modeling and Simulation of Bipedal Locomotion

Sept 2018 - present

Ability & Innovation Lab, University of Washington

Advisors: Dr. Katherine M Steele, Dr. J Nathan Kutz

Data-driven approaches to predict changes in movement after brain injury

Exoskeleton Emulation Aug 2016 – May 2017

Biomechatronics Research Laboratory, Colorado School of Mines

Advisor: Dr. Ozkan Celik

Development of a lower extremity exoskeleton emulator aiding stroke-recovery patients with hemiparesis

PUBLICATIONS

Coming soon

PRESENTATIONS

POSTER

Dynamic Walking May 2020

Discrepancy Modeling in Bipedal Dynamics

Rocky Mountain American Society of Biomechanics

March 2018

The Design and Validation of a Passive Foot Prosthesis with Adjustable Plantarflexion

ORAL

American Society of Biomechanics

submitted for August 2020

Discrepancy Modeling in Bipedal Locomotion

International Society of Biomechanics

Aug 2019

Do Simulated Synergies Accurately Represent Muscle Coordination?

Northwest Biomechanics Symposium

May 2019

Evaluating Altered Muscle Synergies Following Surgical Intervention in Cerebral Palsy Using Matrix Factorization Algorithms

PROFESSIONAL EXPERIENCE

Medtronic Boulder, CO

Specialty Exploration Mechanical Engineering Intern

Summer 2018

Creation and development of new, minimally-invasive technologies for surgical innovations

Medtronic Louisville, CO

Neurosurgical Navigation Hardware Test Engineering Intern

Summer 2017

Explored feasibility of automating optical hardware accuracy testing for neurosurgical navigation

Prytime Medical Devices, Inc

Lakewood, CO

Engineering Intern

Autumn 2017

Developed REBOA (Resuscitative Endovascular Balloon Occlusion of the Aorta) catheter and pulsatile simulator

Procter and Gamble Cincinnati, OH

R&D Process Engineering Intern

Summer 2016

Optimized material characterization product design and process capability of Swiffer Surface Care substrates

Procter and Gamble Cincinnati, OH

R&D Products Research Intern

Summer 2015

Researched and developed consumer-friendly claims and methods for Gain laundry detergent

TEACHING & OUTREACH

Engineering Discovery Days, University of Washington **Solid Mechanics Private Tutor**, Colorado School of Mines

Spring 2019

Spring 2018

SKILLS & COURSEWORK

Computer: Matlab, LaTeX, OpenSim, SolidWorks (Associate Certified), Creo (Pro-E), Nessus, ABAQUS, Minitab, Mastercam CAD/CAM, Solidworks Flow Simulation, Computational Fluid Dynamics, LabVIEW, Mathcad Prime, EES, Excel, Word

Coursework: *Graduate Level:* Mechanical Engineering Analysis I & II (ODEs, PDEs); Scientific Computing; Bio-Inspired Robotics; Biomechanics of Human Movement; Computational Methods for Data Analysis; Inferring Structure of Complex Systems; Automatic Controls; Advanced Methods for ODEs; Linear Systems Theory; Machine Learning Controls