MEGAN EBERS

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EDUCATION

UNIVERSITY OF WASHINGTONSeattle, WAPh.D., Mechanical EngineeringExpected June 2023M.S., Applied MathematicsExpected June 2021M.S., Mechanical EngineeringJune 2020

COLORADO SCHOOL OF MINES,

B.S., Mechanical Engineering, Magna Cum Laude
Minor: Biomechanical Engineering

May 2018

AWARDS & HONORS

National Science Foundation Graduate Research Fellow
"Predicting Locomotor Response to Exoskeleton Augmentation: Data-Driven Motor Control"

Sigma Xi Scientific Research Honor Society

E-Days Engineer Award

Michael R. and Patricia K. Starzer Endowment Scholar

Don L. and Patricia Warner Scholarship Fund for the Board of Trustees Honors Scholar

Mines Presidential Merit Scholar

Fall 2014

RESEARCH

Altered Control in Bipedal Locomotion

Sept 2018 - present

Ability & Innovation Lab, University of Washington

Co-advisor: Katherine M. Steele

Kutz Research Group, University of Washington

Co-advisor: J. Nathan Kutz

Data-driven approaches to predict changes in movement after brain injury

Exoskeleton Emulation Aug 2016 – May 2017

Biomechatronics Research Laboratory, Colorado School of Mines

Advisor: Dr. Ozkan Celik

Development of lower extremity exoskeleton emulator aiding stroke-recovery patients with hemiparesis

TEACHING & MENTORING

Graduate Mentor, Ability & Innovation Lab, University of Washington Qilang (Damon) Ding - UW ME senior undergraduate student *UWIN Innovation Undergrad Fellowship awarded Fall 2019*

Sept 2019 - June 2020

Solid Mechanics Tutor, Colorado School of Mines

Spring 2018

PEER-REVIEWED JOURNAL ARTICLES

Megan Ebers, J. Nathan Kutz, Katherine M. Steele. *Biomechanically-Constrained Machine Learning for Human Mobility Rehabilitation*. 2020 (in preparation)

PEER-REVIEWED CONFERENCE ABSTRACTS

American Society of Biomechanics (virtual)

August 2020

Biomechanically-Constrained Machine Learning for the Identification of Mechanistic Discrepancies

Dynamic Walking (virtual)

May 2020

Discrepancy Modeling in Bipedal Dynamics

International Society of Biomechanics

Do Simulated Synergies Accurately Represent Muscle Coordination?

Northwest Biomechanics Symposium

May 2018

August 2018

Evaluating Altered Muscle Synergies Following Surgical Intervention in Cerebral Palsy Using Matrix Factorization Algorithms

Rocky Mountain American Society of Biomechanics

March 2017

The Design and Validation of a Passive Foot Prosthesis with Adjustable Plantarflexion

PROFESSIONAL EXPERIENCE

Medtronic Boulder, CO

Specialty Exploration Mechanical Engineering Intern

Summer 2018

Creation and development of new, minimally-invasive technologies for surgical innovations

Medtronic Louisville, CO

Neurosurgical Navigation Hardware Test Engineering Intern

Summer 2017

Explored feasibility of automating optical hardware accuracy testing for neurosurgical navigation

Prvtime Medical Devices, Inc

Lakewood, CO

Engineering Intern Autumn 2017

Developed REBOA (Resuscitative Endovascular Balloon Occlusion of the Aorta) catheter and pulsatile simulator

Procter and Gamble Cincinnati, OH

R&D Process Engineering Intern

Summer 2016

Optimized material characterization product design and process capability of Swiffer Surface Care substrates

Procter and Gamble Cincinnati, OH

R&D Products Research Intern

Summer 2015

Researched and developed consumer-friendly claims and methods for Gain laundry detergent

OUTREACH

Engineering Discovery Days, University of Washington STEM Mentor for High School girls, Holdingford Jr./Sr. High, MN Spring 2019

Winter 2016 - present

SKILLS & COURSEWORK

Computer: Matlab, OpenSim, LaTeX, SolidWorks (Associate Certified), Creo (Pro-E), Nessus, ABAQUS, Minitab, Mastercam CAD/CAM, Solidworks Flow Simulation, Computational Fluid Dynamics

Coursework: Graduate Level: Mechanical Engineering Analysis I & II (ODEs, PDEs); Scientific Computing; Bio-Inspired Robotics; Biomechanics of Human Movement; Computational Methods for Data Analysis; Inferring Structure of Complex Systems; Automatic Controls; Linear Systems Theory; Applied Complex Analysis; Advanced Methods for ODEs; Machine **Learning Control**