MEGAN R. EBERS

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Postdoctoral scholar in Applied Mathematics interested in human-centered research challenges. I develop and apply data-driven and reduced-order methods to model complex systems and extract actionable insight from real-world data.

RESEARCH INTERESTS

- ML/DL for human health and mobility; sparse sensing; dynamical systems; reduced-order modeling; time series;
- Applications in human-centered research challenges, wearable technology, complex physical and engineering systems

EDUCATION

PhD, Mechanical Engineering

August 2023

University of Washington, Seattle, WA; Co-advisors: Katherine M Steele, J Nathan Kutz

Dissertation: Machine learning for dynamical models of human movement

- NSF Graduate Research Fellow
- NSF AI Institute for Dynamic Systems member

MS, Applied Mathematics

June 2022

University of Washington, Seattle, WA

MS, Mechanical Engineering
University of Washington, Seattle, WA

June 2020

BS, Mechanical Engineering, minor in Biomechanical Engineering

Colorado School of Mines, Golden, CO; Honors: magna cum laude

May 2018

COMPUTATIONAL SKILLS

Python (numpy/scipy, PyTorch, pandas, scikit-learn, TorchDiffEq, Altair, CUDA); MATLAB; HPC; LaTeX; Tableau

RELEVANT EXPERIENCE

Postdoctoral Scholar, UW Department of Applied Mathematics, NSF AI Institute in Dynamic Systems

Data-driven and reduced order modeling of complex dynamical systems

Sept 202

Sept 2023 – present

- Creating a reduced-order modeling framework for stable and robust uncertainty quantification with control
- Expanding applications of sparse sensing with mobile sensors for large scale, complex systems (e.g., human movement-based health outcomes, natural disaster monitoring, acoustic object detection, etc) (T5)
- Incorporating discrepancy modeling into established ML frameworks (e.g., reinforcement learning) for improved performance in real-world deployment

Research assistant, UW Department of Mechanical Engineering

Aug 2018 – Aug 2023

Theoretical foundation of discrepancy modeling for dynamical systems

- Developed a data-driven framework to learn missing physics, model systematic residuals, and disambiguate between deterministic and random effects in dynamical systems
- Disseminated findings in a first author publication (P1), an invited minisymposium for SIAM's Conference on Applications of Dynamical Systems (T4), and an interview for Women in Data Science's Stanford conference (T2)

Quantification of individual gait responses to ankle exoskeletons during walking

- Integrated deep learning with discrepancy modeling to model dynamic changes in joint kinematics and muscle activity in response to exoskeleton intervention in nondisabled adults
- Disseminated findings in a first author publication (P3), oral presentations at two academic conferences, and an interview for Women in Data Science's Stanford conference (T2)

Sparse sensing of complex dynamics with mobile sensors

- Leveraged mobile sensor trajectories with shallow recurrent decoder networks for full-state reconstruction (P4)
- Demonstrated sparse yet accurate monitoring of human movement "in-the-wild", turbulent flow, and global sea-surface temperature (T5)

Machine learning and systems pharmacology intern, Genentech Research & Early Development June 2022 – Oct 2022

- Investigated pharmacology-informed deep learning (DL) techniques to model preclinical pharmacokinetics
- Collaborated with Translational Systems Pharmacology to recommend which drugs progress to clinical trials

PEER-REVIEWED JOURNAL ARTICLES

- P4. <u>Ebers MR</u>, Williams JP, Steele KM, Kutz JN. *Leveraging arbitrary mobile sensor trajectories with shallow recurrent decoder networks for full-state reconstruction.* (Submitted to IEEE Sensors: arXiv:2307.11793)
- P3. **Ebers MR**, Rosenberg MC, Kutz JN, Steele KM. *A machine learning approach to quantify complex changes in gait with ankle exoskeletons.* (Published in the Journal of Biomechanics)
- P2. Kutz JN, Bramburger J, <u>Ebers MR</u>, Koch J, Rahman A. *Universal Dynamics of Damped-Driven Systems: The Logistic Map as a Normal Form for Energy Balance.* (Submitted to Reviews of Modern Physics: arXiv:2211.11748)
- P1. **Ebers MR**, Steele KM, Kutz JN. *Discrepancy Modeling Framework: Learning missing physics, modeling systematic errors, and disambiguating between deterministic and random effects* (Accepted in SIADS: <u>arXiv:2203.05164</u>)

PEER-REVIEWED CONFERENCE ABSTRACTS

2023	SIAM Conference on Applications of Dynamical Systems Discrepancy Modeling Framework: Learning missing physics, modeling systematic residuals, and disambiguating between deterministic and random effects
2022	Northwest Biomechanics Symposium Do in silico MTU dynamics improve predictions of AFO responses?
2022	AI for Dynamic Systems workshop Discrepancy Modeling Framework: Learning missing physics, modeling systematic residuals, and disambiguating between deterministic and random effects
2021	Dynamic Walking (virtual) Discrepancy Modeling of Ankle Exoskeleton Walking Can Improve Response Predictions
2020	American Society of Biomechanics (virtual) Biomechanically-Constrained Machine Learning for the Identification of Mechanistic Discrepancies
2020	Dynamic Walking (virtual) Discrepancy Modeling in Bipedal Dynamics
2018	International Society of Biomechanics Do Simulated Synergies Accurately Represent Muscle Coordination?
2018	Northwest Biomechanics Symposium Evaluating Altered Muscle Synergies Following Surgical Intervention in Cerebral Palsy Using Matrix Factorization Algorithms
2017	Rocky Mountain American Society of Biomechanics The Design and Validation of a Passive Foot Prosthesis with Adjustable Plantarflexion

INVITED TALKS

- T5. UW's eScience Data Science Seminar series, Mobile Sensing with Shallow, Recurrent Decoder Networks. January 2024
- T4. SIAM Conference on Applications of Dynamical Systems, Minisymposium on Hybrid Modeling. May 2023
- T3. Institute for Human and Machine Cognition, Machine Learning for Dynamical Models of Human Movement. April 2023
- T2. Women in Data Science conference, Stanford University. March 2023
- T1. Colorado School of Mines Computational Biomechanics lecture, virtual. April 2021