

# MEGAN R. EBERS

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Postdoctoral scholar in Applied Mathematics interested in human-centered research challenges. I develop and apply data-driven and reduced-order methods to model complex systems and extract actionable insight from real-world data.

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## RESEARCH INTERESTS

- ML/DL for human health and mobility; sparse sensing; dynamical systems; reduced-order modeling; time series;
- Applications in human-centered research challenges, wearable technology, complex physical and engineering systems

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## EDUCATION

**PhD, Mechanical Engineering** *August 2023*

**University of Washington**, Seattle, WA; Co-advisors: Katherine M Steele, J Nathan Kutz

*Dissertation: Machine learning for dynamical models of human movement*

- **NSF Graduate Research Fellow**
- **NSF AI Institute for Dynamic Systems member**

**MS, Applied Mathematics** *June 2022*

**University of Washington**, Seattle, WA

**MS, Mechanical Engineering** *June 2020*

**University of Washington**, Seattle, WA

**BS, Mechanical Engineering**, minor in Biomechanical Engineering *May 2018*

**Colorado School of Mines**, Golden, CO; Honors: magna cum laude

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## COMPUTATIONAL SKILLS

Python (numpy/scipy, PyTorch, pandas, scikit-learn, TorchDiffEq, Altair, CUDA); MATLAB; HPC; LaTeX; Tableau

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## RELEVANT EXPERIENCE

**Postdoctoral Scholar**, UW Department of Applied Mathematics, NSF AI Institute in Dynamic Systems *Sept 2023 – present*

Data-driven and reduced order modeling of complex dynamical systems

- Creating a reduced-order modeling framework for stable and robust uncertainty quantification with control
- Expanding applications of sparse sensing with mobile sensors for large scale, complex systems (e.g., human movement-based health outcomes, natural disaster monitoring, acoustic object detection, etc) (T5)
- Incorporating discrepancy modeling into established ML frameworks (e.g., reinforcement learning) for improved performance in real-world deployment

**Research assistant**, UW Department of Mechanical Engineering *Aug 2018 – Aug 2023*

Theoretical foundation of discrepancy modeling for dynamical systems

- Developed a data-driven framework to learn missing physics, model systematic residuals, and disambiguate between deterministic and random effects in dynamical systems
- Disseminated findings in a first author publication (P1), an invited minisymposium for SIAM's Conference on Applications of Dynamical Systems (T4), and an interview for Women in Data Science's Stanford conference (T2)

Quantification of individual gait responses to ankle exoskeletons during walking

- Integrated deep learning with discrepancy modeling to model dynamic changes in joint kinematics and muscle activity in response to exoskeleton intervention in nondisabled adults
- Disseminated findings in a first author publication (P3), oral presentations at two academic conferences, and an interview for Women in Data Science's Stanford conference (T2)

Sparse sensing of complex dynamics with mobile sensors

- Leveraged mobile sensor trajectories with shallow recurrent decoder networks for full-state reconstruction (P4)
- Demonstrated sparse yet accurate monitoring of human movement "in-the-wild", turbulent flow, and global sea-surface temperature (T5)

**Machine learning and systems pharmacology intern**, Genentech Research & Early Development *June 2022 – Oct 2022*

- Investigated pharmacology-informed deep learning (DL) techniques to model preclinical pharmacokinetics
- Collaborated with Translational Systems Pharmacology to recommend which drugs progress to clinical trials

## PEER-REVIEWED JOURNAL ARTICLES

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P4. **Ebers MR**, Williams JP, Steele KM, Kutz JN. *Leveraging arbitrary mobile sensor trajectories with shallow recurrent decoder networks for full-state reconstruction*. (Submitted to IEEE Sensors: [arXiv:2307.11793](#))

P3. **Ebers MR**, Rosenberg MC, Kutz JN, Steele KM. *A machine learning approach to quantify complex changes in gait with ankle exoskeletons*. (Published in the [Journal of Biomechanics](#))

P2. Kutz JN, Bramburger J, **Ebers MR**, Koch J, Rahman A. *Universal Dynamics of Damped-Driven Systems: The Logistic Map as a Normal Form for Energy Balance*. (Submitted to Reviews of Modern Physics: [arXiv:2211.11748](#))

P1. **Ebers MR**, Steele KM, Kutz JN. *Discrepancy Modeling Framework: Learning missing physics, modeling systematic errors, and disambiguating between deterministic and random effects* (Accepted in SIADS: [arXiv:2203.05164](#))

## PEER-REVIEWED CONFERENCE ABSTRACTS

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| 2023 | <b>SIAM Conference on Applications of Dynamical Systems</b><br><i>Discrepancy Modeling Framework: Learning missing physics, modeling systematic residuals, and disambiguating between deterministic and random effects</i> |
| 2022 | <b>Northwest Biomechanics Symposium</b><br><i>Do in silico MTU dynamics improve predictions of AFO responses?</i>  |
| 2022 | <b>AI for Dynamic Systems workshop</b><br><i>Discrepancy Modeling Framework: Learning missing physics, modeling systematic residuals, and disambiguating between deterministic and random effects</i>                      |
| 2021 | <b>Dynamic Walking (virtual)</b><br><i>Discrepancy Modeling of Ankle Exoskeleton Walking Can Improve Response Predictions</i>  |
| 2020 | <b>American Society of Biomechanics (virtual)</b><br><i>Biomechanically-Constrained Machine Learning for the Identification of Mechanistic Discrepancies</i>   |
| 2020 | <b>Dynamic Walking (virtual)</b><br><i>Discrepancy Modeling in Bipedal Dynamics</i>  |
| 2018 | <b>International Society of Biomechanics</b><br><i>Do Simulated Synergies Accurately Represent Muscle Coordination?</i>  |
| 2018 | <b>Northwest Biomechanics Symposium</b><br><i>Evaluating Altered Muscle Synergies Following Surgical Intervention in Cerebral Palsy Using Matrix Factorization Algorithms</i>  |
| 2017 | <b>Rocky Mountain American Society of Biomechanics</b><br><i>The Design and Validation of a Passive Foot Prosthesis with Adjustable Plantarflexion</i>   |

## INVITED TALKS

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- T5. UW's eScience Data Science Seminar series, [Mobile Sensing with Shallow Recurrent Decoder Networks](#). January 2024 ([link](#))
- T4. SIAM Conference on Applications of Dynamical Systems, Minisymposium on Hybrid Modeling. May 2023
- T3. Institute for Human and Machine Cognition, Machine Learning for Dynamical Models of Human Movement. April 2023
- T2. Women in Data Science conference, Stanford University. March 2023
- T1. Colorado School of Mines Computational Biomechanics lecture, virtual. April 2021
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