

Lecture 10: Classification examples

Reading: Chapter 4

STATS 202: Data mining and analysis

October 14, 2019

Recap: Predicting default

Used LDA to predict credit card default in a dataset of 10K people.

Predicted “yes” if $P(\text{default} = \text{yes}|X) > 0.5$.

		<i>True default status</i>		
		No	Yes	Total
<i>Predicted default status</i>	No	9,644	252	9,896
	Yes	23	81	104
	Total	9,667	333	10,000

- ▶ The error rate among people who do **not** default (false positive rate) is very low.
- ▶ However, the rate of false negatives is 76%.
- ▶ It is possible that false negatives are a bigger source of concern!
- ▶ One possible solution: Change the **threshold**.

Example. Predicting default

Changing the threshold to 0.2 makes it easier to classify to “yes”.

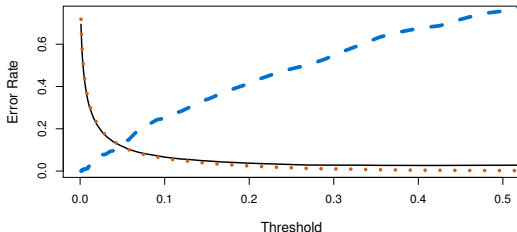
Predicted “yes” if $P(\text{default} = \text{yes}|X) > 0.2$.

		<i>True default status</i>		
		No	Yes	Total
<i>Predicted default status</i>	No	9,432	138	9,570
	Yes	235	195	430
	Total	9,667	333	10,000

Note that the rate of false positives became higher! That is the price to pay for fewer false negatives.

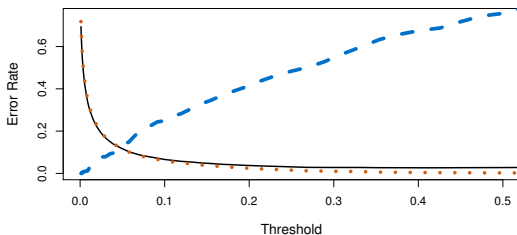
Example. Predicting default

Let's visualize the dependence of the error on the threshold:



- ▶ — False negative rate (error for defaulting customers)
- ▶ False positive rate (error for non-defaulting customers)
- ▶ — 0-1 loss or total error rate = $\frac{\#FP + \#FN}{n}$

Example. Predicting default



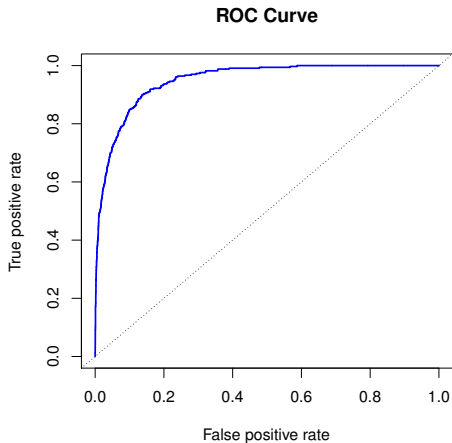
- ▶ — False negative rate (error for defaulting customers)
- ▶ False positive rate (error for non-defaulting customers)
- ▶ — 0-1 loss or total error rate

$$\text{0-1 error rate} = \frac{\#FP + \#FN}{n}$$

$$= (\text{FP rate}) \times \frac{n - m}{n} + (\text{FN rate}) \times \frac{m}{n}$$

where $m = \#$ of people who did default, $n =$ total sample size

Example. The ROC curve



- ▶ Displays the performance of the method for any choice of threshold.
- ▶ TP rate = 1-FN rate
- ▶ The area under the curve (AUC) measures the quality of the classifier:
 - ▶ 0.5 is the AUC for a random classifier
 - ▶ The closer AUC is to 1, the better.

Thinking about the loss function is important

Most of the **regression** methods we've studied aim to minimize the RSS, while **classification** methods aim to minimize the 0-1 loss.

In classification, we often care about certain kinds of error more than others; i.e. the natural loss function is not the 0-1 loss.

Changing the classification threshold to trade off between false positives and false negatives is an example of **tuning** a classifier to perform well with respect to a problem-specific objective.

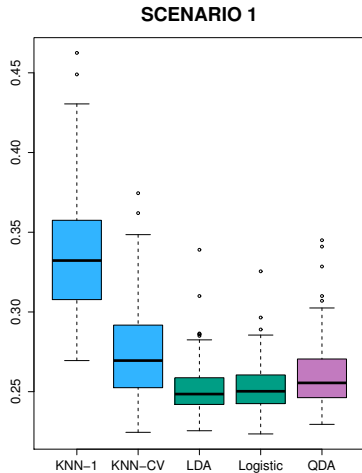
- ▶ e.g. Find the threshold that brings the False negative rate below an acceptable level.

Comparing classification methods through simulation

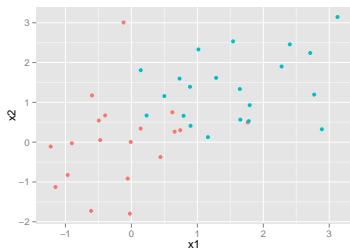
1. Simulate 100 random training sets from several different known distributions with 2 predictors and a binary response variable.
2. Compare the test error (0-1 loss) for the following methods:
 - ▶ KNN-1
 - ▶ KNN-CV (parameter K selected using cross-validation)
 - ▶ Logistic regression
 - ▶ Linear discriminant analysis (LDA)
 - ▶ Quadratic discriminant analysis (QDA)

Check that the logistic regression boundary is linear!

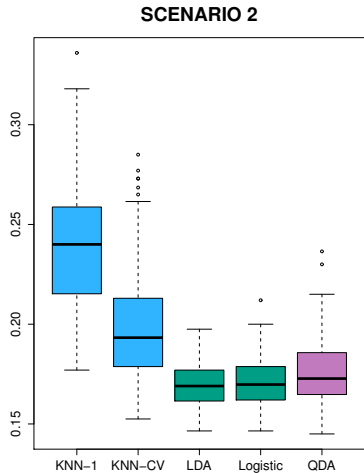
Scenario 1



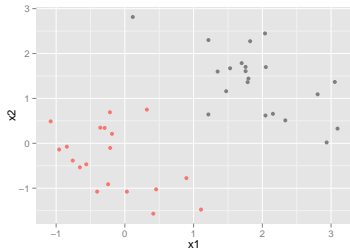
- In each class, (X_1, X_2) uncorrelated and bivariate normal, means differ between classes.



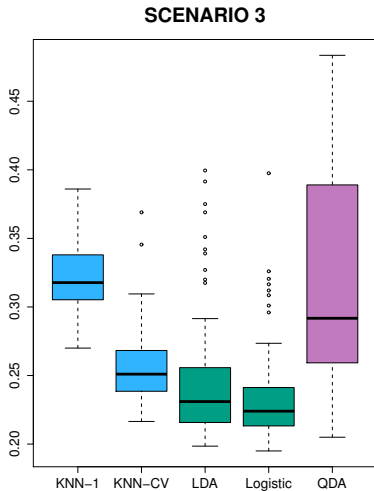
Scenario 2



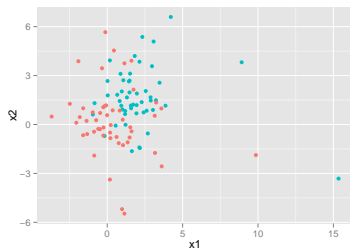
- In each class, (X_1, X_2) is bivariate normal with correlation -0.5 , means differ between classes.



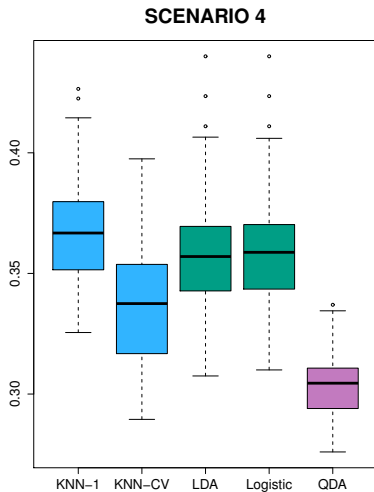
Scenario 3



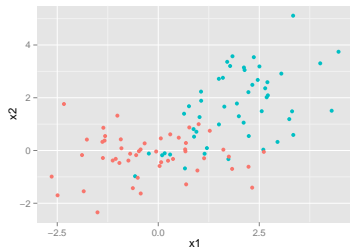
- In each class, (X_1, X_2) independent Student t random variables, means differ between classes.



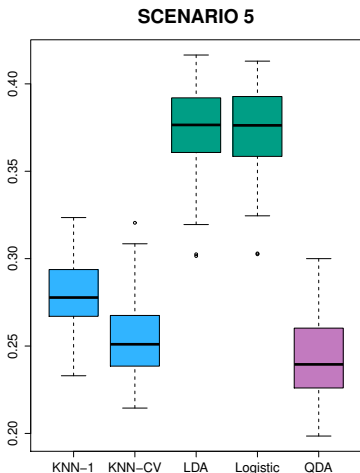
Scenario 4



- ▶ In each class, (X_1, X_2) bivariate normal, means differ between classes.
- ▶ First class has correlation 0.5, second class has correlation -0.5.



Scenario 5

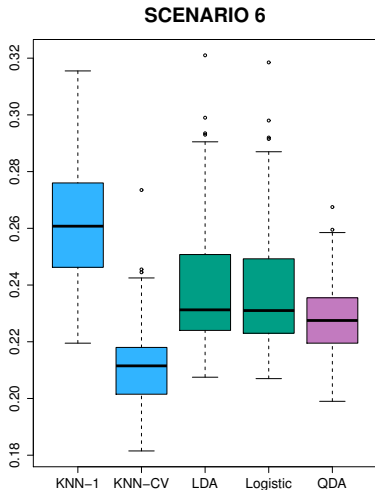


- ▶ X_1, X_2 uncorrelated, standard normal.
- ▶ Response Y was sampled from:

$$P(Y = 1|X) = \frac{e^{\beta_0 + \beta_1(X_1^2) + \beta_2(X_2^2) + \beta_3(X_1X_2)}}{1 + e^{\beta_0 + \beta_1(X_1^2) + \beta_2(X_2^2) + \beta_3(X_1X_2)}}$$

- ▶ The true decision boundary is quadratic.
- ▶ Note: We could also modify logistic regression to include quadratic terms, in the same way that we modified linear regression!

Scenario 6



- ▶ X_1, X_2 uncorrelated, standard normal.
- ▶ Response Y was sampled from:

$$P(Y = 1|X) = \frac{e^{f_{\text{nonlinear}}(X_1, X_2)}}{1 + e^{f_{\text{nonlinear}}(X_1, X_2)}}.$$

- ▶ The true decision boundary is very rough.

Cross-validation

Key question: Given a single training set, how do we choose the supervised learning method with the best test error or select the tuning parameter for the method, e.g.

- ▶ k in k -nearest neighbors,
- ▶ the number of variables to include in forward or backward selection,
- ▶ the order of a polynomial in polynomial regression?

The **validation set** or **hold-out** approach is one way to approximate the test error:

- ▶ Divide the data into two parts.
- ▶ Train each model on one part.
- ▶ Compute the error on the other.

Validation set approach

Goal: Estimate the test error for a supervised learning method.

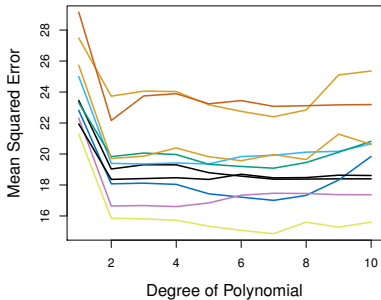
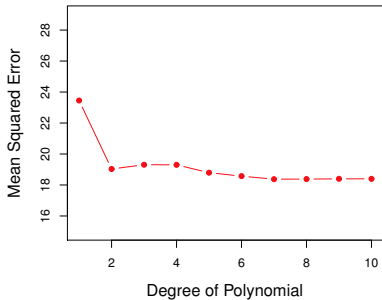
Strategy:

- ▶ Split the data in two parts.
- ▶ Train the method on the first part.
- ▶ Compute the error on the second part.



Validation set approach

Polynomial regression to estimate mpg from horsepower in the Auto data.



Problems: 1. Every split yields a different estimate of the error.
2. Only a subset of points is used to evaluate the model.

Leave one out cross-validation

- ▶ For every $i = 1, \dots, n$:
 - ▶ train the model on every point except i ,
 - ▶ compute the test error on the held out point.
- ▶ Average the test errors.



Leave one out cross-validation

- ▶ For every $i = 1, \dots, n$:
 - ▶ train the model on every point except i ,
 - ▶ compute the test error on the held out point.
- ▶ Average the test errors.

$$CV_{(n)} = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i^{(-i)})^2$$

Prediction for the i sample without using the i th sample.

Leave one out cross-validation

- ▶ For every $i = 1, \dots, n$:
 - ▶ train the model on every point except i ,
 - ▶ compute the test error on the held out point.
- ▶ Average the test errors.

$$\text{CV}_{(n)} = \frac{1}{n} \sum_{i=1}^n \mathbf{1}(y_i \neq \hat{y}_i^{(-i)})$$

... for a classification problem.

Leave one out cross-validation

Computing $CV_{(n)}$ can be computationally expensive, since it involves fitting the model n times.

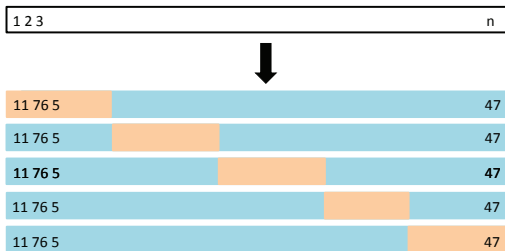
For linear regression, there is a shortcut:

$$CV_{(n)} = \frac{1}{n} \sum_{i=1}^n \left(\frac{y_i - \hat{y}_i}{1 - h_{ii}} \right)^2$$

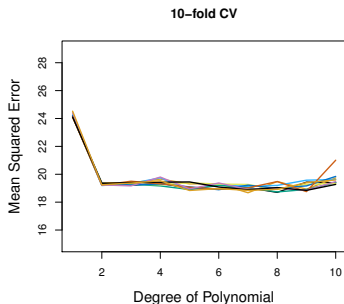
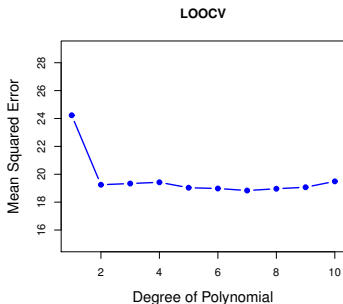
where h_{ii} is the leverage statistic.

k -fold cross-validation

- ▶ Split the data into k subsets or *folds*.
- ▶ For every $i = 1, \dots, k$:
 - ▶ train the model on every fold except the i th fold,
 - ▶ compute the test error on the i th fold.
- ▶ Average the test errors.



LOOCV vs. k -fold cross-validation



- ▶ k -fold CV depends on the chosen split.
- ▶ In k -fold CV, we train the model on less data than what is available. This introduces **bias** into the estimates of test error.
- ▶ In LOOCV, the training samples highly resemble each other. This increases the **variance** of the test error estimate.