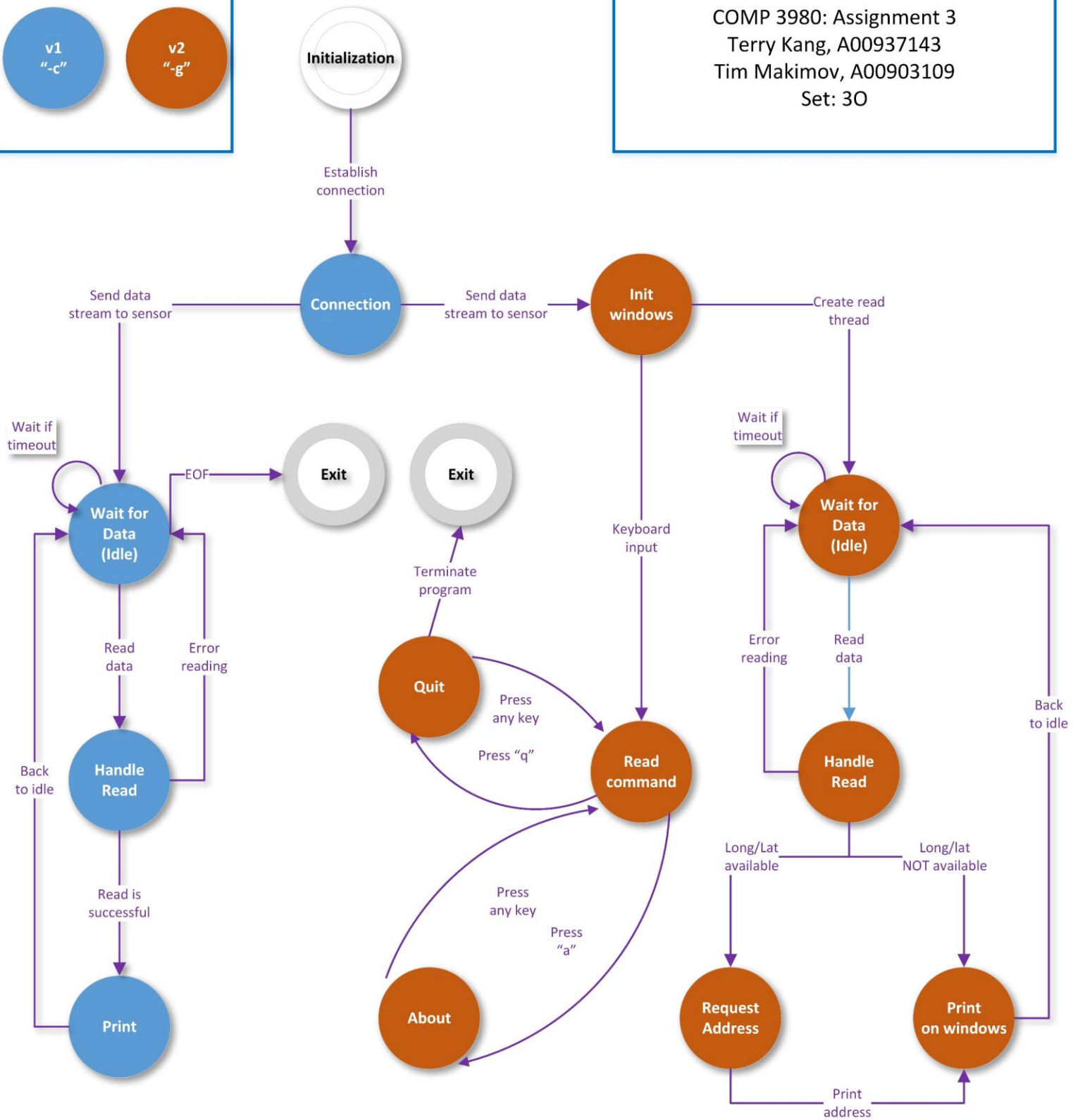


COMP 3980: Assignment 3
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 Set: 30



PSEUDOCODE

V1

Initialization

- Define structure variable for GPS
- Establish socket connection to gps daemon
- Check if source device is not NULL (check if device is detected)

Connection

- Send data stream to sensor to start data report
- Send flags to sensor

Waiting for GPS data

- Set GPS timeout
- Wait for GPS data, if timed out – continue
- If there's data, read GPS data

Handle Read

- If error is returned print error and return to Waiting state
- If data is returned send it to Print state

Print

- Loop through all satellite's channels to check which ones are used
- Check if there any visible satellites
- For all visible satellites print the struct data
- Check if fix is available or not. If it's available, print latitude, longitude
- Else print n/a

Exit

- If user presses EOF – close program

V2

Initialization

- Read argument from user
- If the passing argument is incorrect, show usage and exit
- Establish socket connection to gps daemon
- Check if source device is not NULL (check if device is detected)

Connection

- Send data stream to sensor to start data report
- Send flags to sensor
- If the argument is '-c', go to waiting state of version 1 without ncurses
- If the argument is '-g', go to init window state.

Handle Read

- If error is returned print error and return to Waiting state
- If data is returned send it to Print state

Print

- Loop through all satellite's channels to check which ones are used
- Check if there any visible satellites
- For all visible satellites print the struct data
- Check if fix is available or not. If it's available, print latitude, longitude
- Else print n/a

Exit

- If user presses EOF – close program

Init Windows

- Initialize windows and display full screen with ncurses
- Create a thread for reading data from GPS.
- Start reading command from user for selecting menu.

Read Command

- While reading command
- If press 'a' or 'A', create a window for about and pop it up.
- If press 'q' or 'Q', create a window for quit menu and pop it up

Quit

- Wait for command
- If press 'y', exit program
- If press 'n', close quit window

About

- Shows the information of this program
- Wait for command
- If press any key, close window

Waiting for GPS data v2

- Set GPS timeout
- Wait for GPS data, if timed out – continue

- If there's data, read GPS data

Handle Read v2

- If error is returned print error and return to Waiting state
- If data is returned and the fix is available, send the latitude and longitude to request address state
- If fix is not available, go to print on window state

Request Address

- Send a request to google maps api with the passed latitude and longitude
- Get a response
- If successful, send address to print state to print

Print on Windows

- Loop through all satellite's channels to check which ones are used
- Check if there any visible satellites
- For all visible satellites display the satellite info on window.
- Check if fix is available or not. If it's available, displays the information including latitude, longitude, altitude, speed, status, etc
- Else print n/a

TESTING

Testing procedures for “gpsReader” program

Currently there're 2 versions of the program: v1 and v2. The v1 version has the minimum requirement features and the v2 version has basic GUI implemented using ncurses as well as postal address output based on latitude and longitude.

V1

GPS signal and connection testing

a) Getting fix and reading GPS data

```
PRN: 027 Elevation: 07 Azimuth: 031 SNR: 30 Used: Y
PRN: 009 Elevation: 08 Azimuth: 160 SNR: 26 Used: Y
PRN: 008 Elevation: 36 Azimuth: 057 SNR: 20 Used: Y
PRN: 013 Elevation: 38 Azimuth: 304 SNR: 34 Used: Y
PRN: 030 Elevation: 81 Azimuth: 072 SNR: 22 Used: Y
PRN: 007 Elevation: 49 Azimuth: 100 SNR: 32 Used: Y
PRN: 020 Elevation: 10 Azimuth: 309 SNR: 24 Used: Y
PRN: 028 Elevation: 65 Azimuth: 234 SNR: 30 Used: Y
2016-10-19T09:10:11.000Z: Latitude: 49.221494S Longitude: -123.001621W
Address: n/a
```

Result: Passed

b) Getting no fix – no GPS data can be read

```
PRN: 030 Elevation: 70 Azimuth: 102 SNR: 29 Used: Y
PRN: 005 Elevation: 06 Azimuth: 249 SNR: 22 Used: Y
PRN: 008 Elevation: 28 Azimuth: 048 SNR: 23 Used: Y
PRN: 013 Elevation: 47 Azimuth: 294 SNR: 38 Used: Y
PRN: 007 Elevation: 38 Azimuth: 109 SNR: 20 Used: N
PRN: 011 Elevation: 25 Azimuth: 091 SNR: 26 Used: Y
PRN: 028 Elevation: 77 Azimuth: 250 SNR: 24 Used: Y
PRN: 015 Elevation: 20 Azimuth: 313 SNR: 26 Used: Y
2016-10-19T09:38:44.000Z: Latitude: n/a Longitude: n/a
Address: n/a
```

Result: Passed

1. Test arguments

Incorrect argument is passed

```
pi@raspberrypi:~/timterry/v2 $ ./dcgps d
Usage: ./dcgps [-h | -c | -g]
  -h      Show this help, then exit
  -c      version 1 without user interface
  -g      version 2 with user interface
pi@raspberrypi:~/timterry/v2 $
```

Result: Passed

2. GPS signal and connection testing

a) Getting fix and reading GPS data

[illegible]

Result: Passed

b) Getting no fix – no GPS data can't be read

```
pi@raspberrypi: ~/timerry/v2
(M) Host: (Q) Exit
=====
Time: 2016-10-19T09:37:54.000Z
Latitude: n/a
Longitude: n/a
Address: n/a
Altitude: n/a
Speed: n/a
Climb: n/a
Status: NO Fix
=====
PRN: 30 Elev: 70 Azim: 102 SNR: 27.000000 Used: Y
PRN: 13 Elev: 47 Azim: 294 SNR: 38.000000 Used: Y
PRN: 20 Elev: 87 Azim: 298 SNR: 16.000000 Used: Y
PRN: 11 Elev: 25 Azim: 918 SNR: 29.000000 Used: Y
PRN: 28 Elev: 77 Azim: 250 SNR: 24.000000 Used: Y
PRN: 15 Elev: 20 Azim: 313 SNR: 30.000000 Used: Y
PRN: 15 Elev: 20 Azim: 313 SNR: 30.000000 Used: Y
=====
Press 'A' or 'a' to read about this program.
Press 'Q' or 'q' to quit this program
=====
```

Result: Passed

[illegible]

Result: Passed