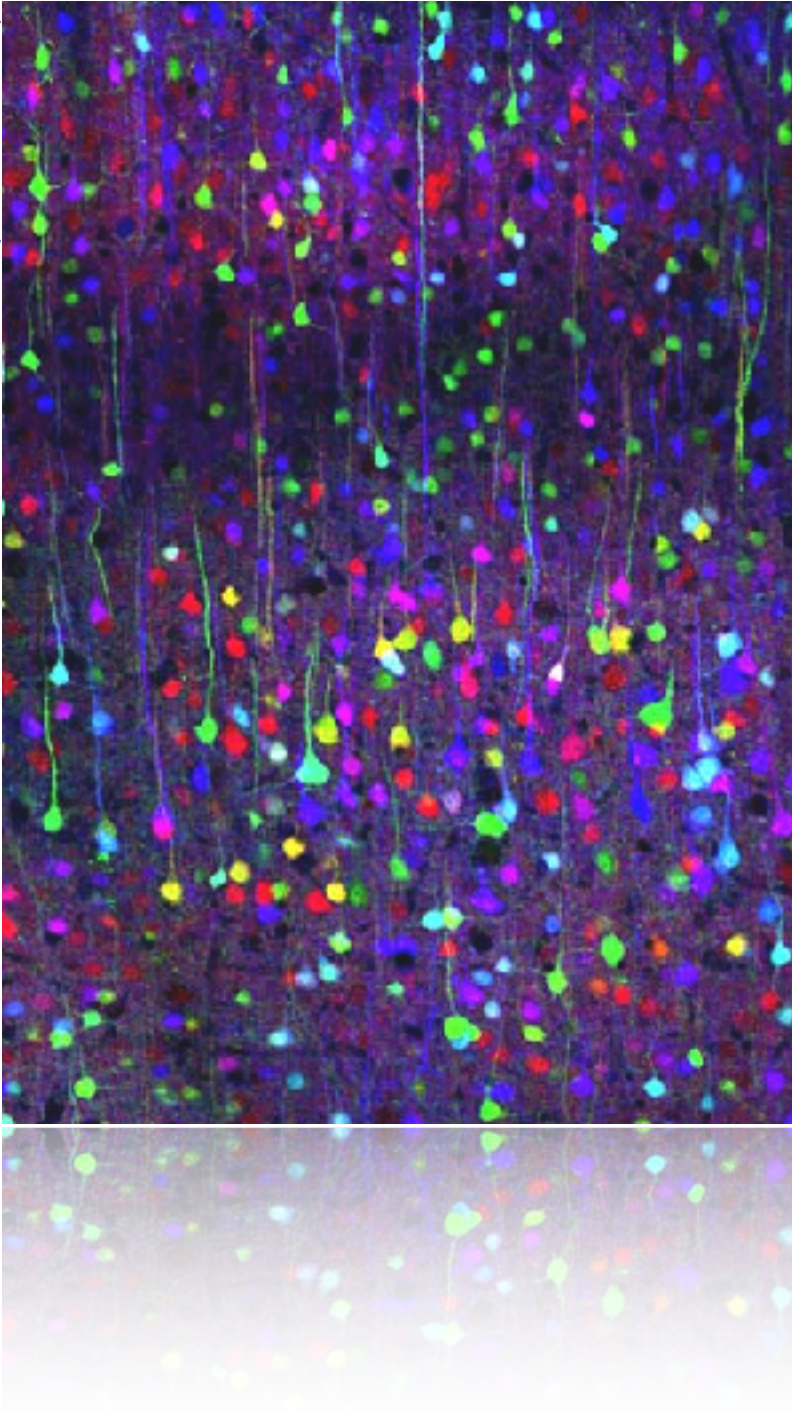


# Bio-deep learning workshop



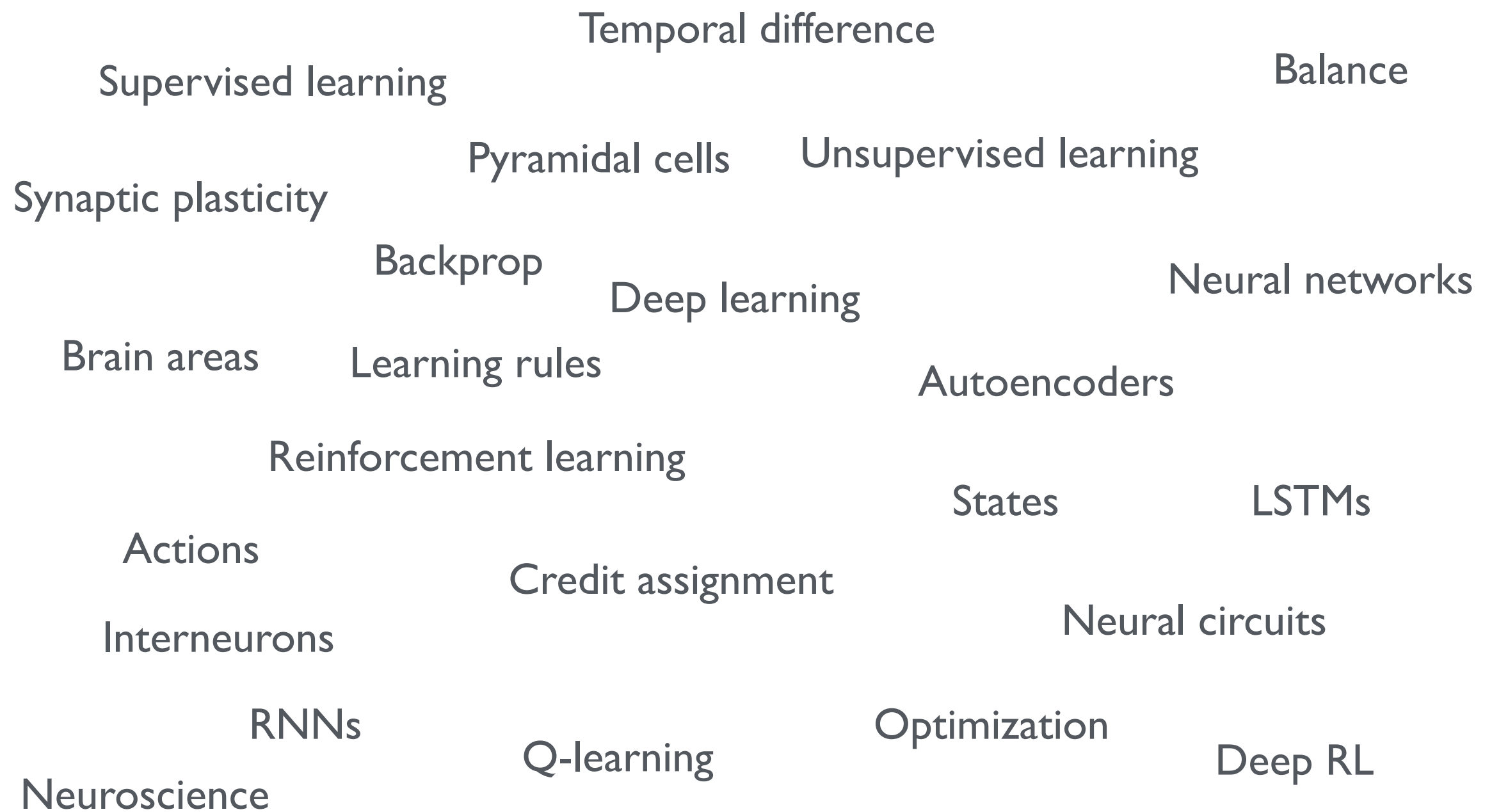
Brainbow (Litchman Lab)



## Introduction: Neural circuits and learning

Rui Ponte Costa

# Neural circuits and learning



# This lecture

A short overview on the credit assignment problem and the different forms of learning in the brain (and machine learning):

**Supervised learning**

**Unsupervised learning**

**Reinforcement learning**

# Given visual input how should you move?

Visual input → Prepare movement → Hit (or not) the ball





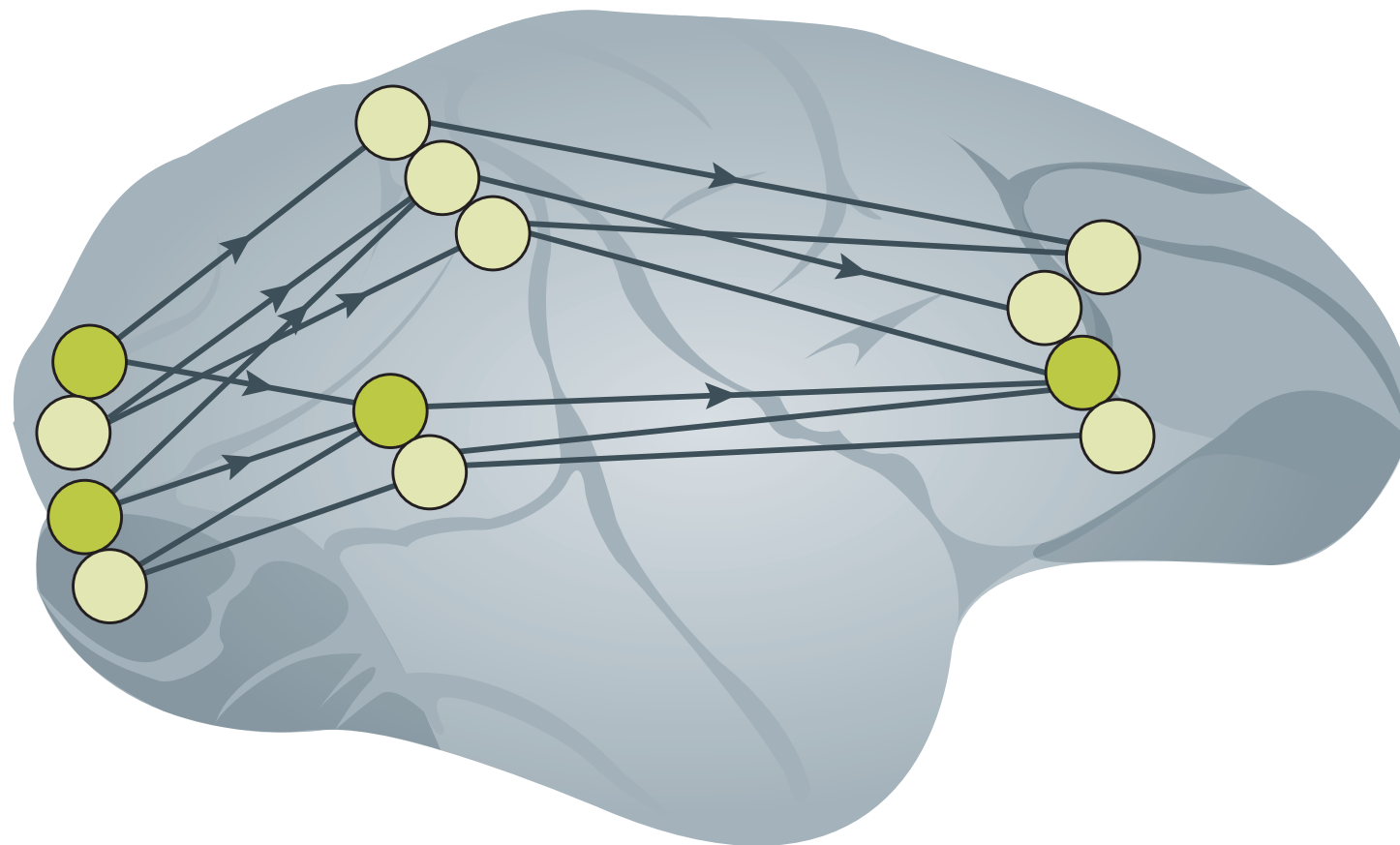
# How does the brain learn to associate visual input with motor output?

Visual input → Prepare movement → Hit (or not) the ball



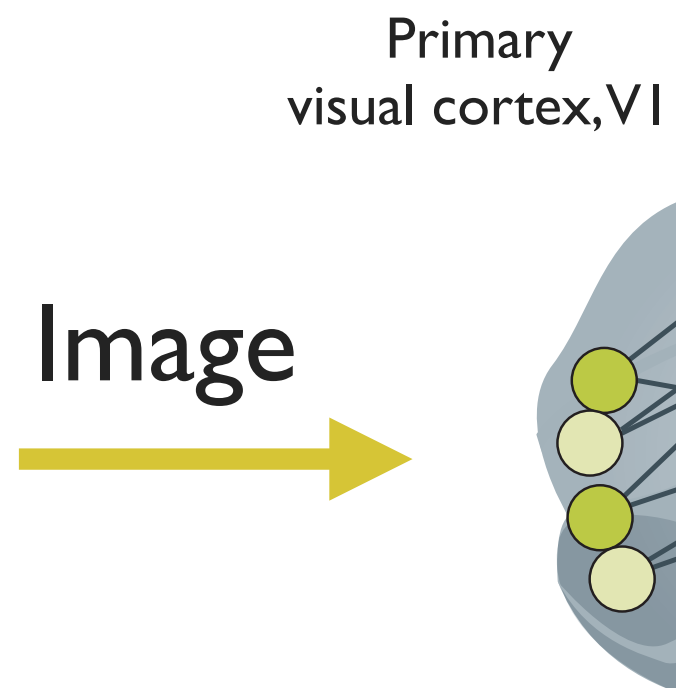
(typically **synapses**)

# How to assign credit to 'parameters' in the brain?



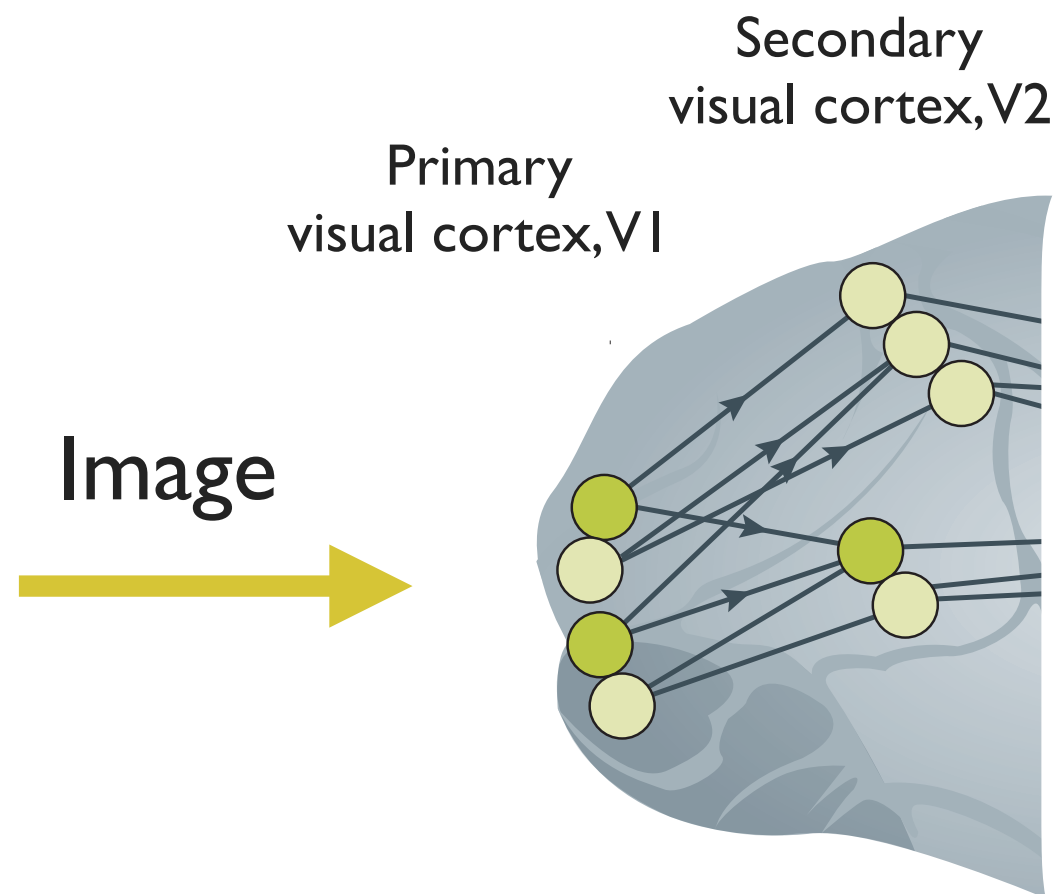
Roelfsema et al. Nature Neuroscience Rev 2018

# How to assign credit in the brain?



Roelfsema et al. Nature Neuroscience Rev 2018

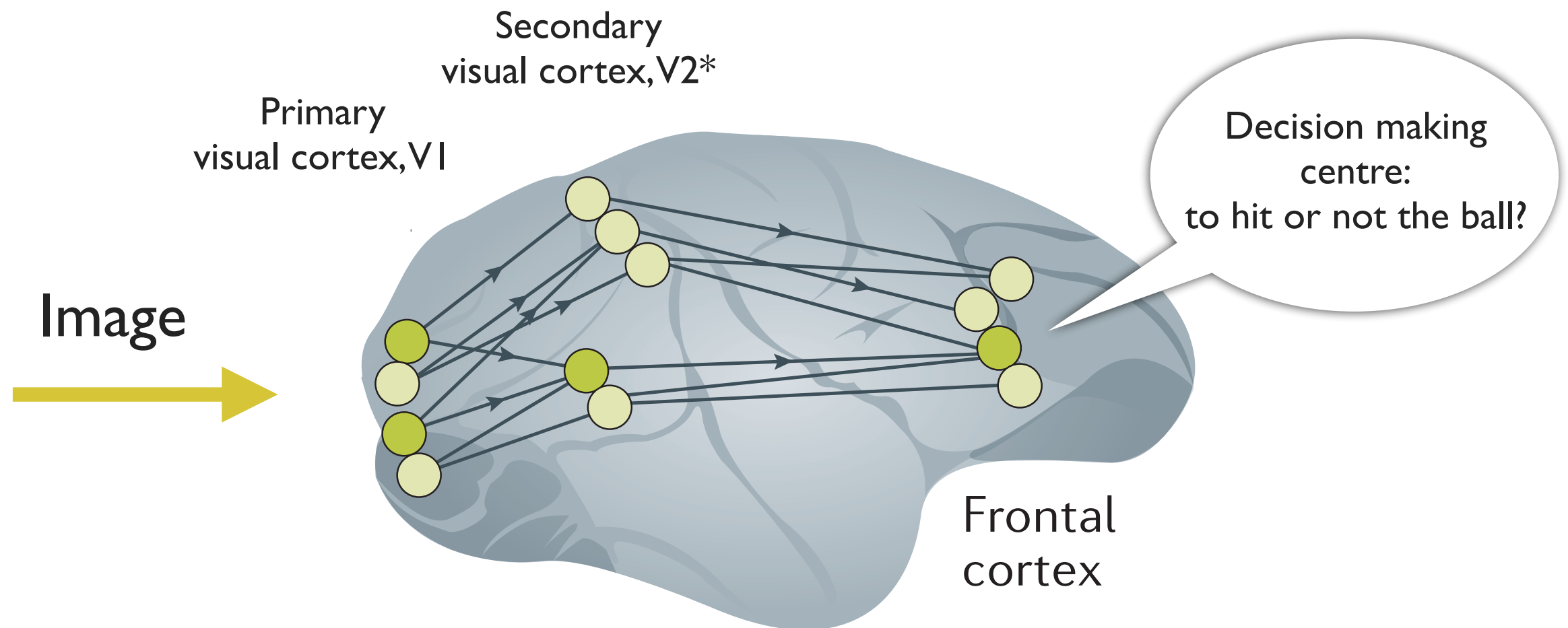
# How to assign credit in the brain?



Roelfsema et al. Nature Neuroscience Rev 2018



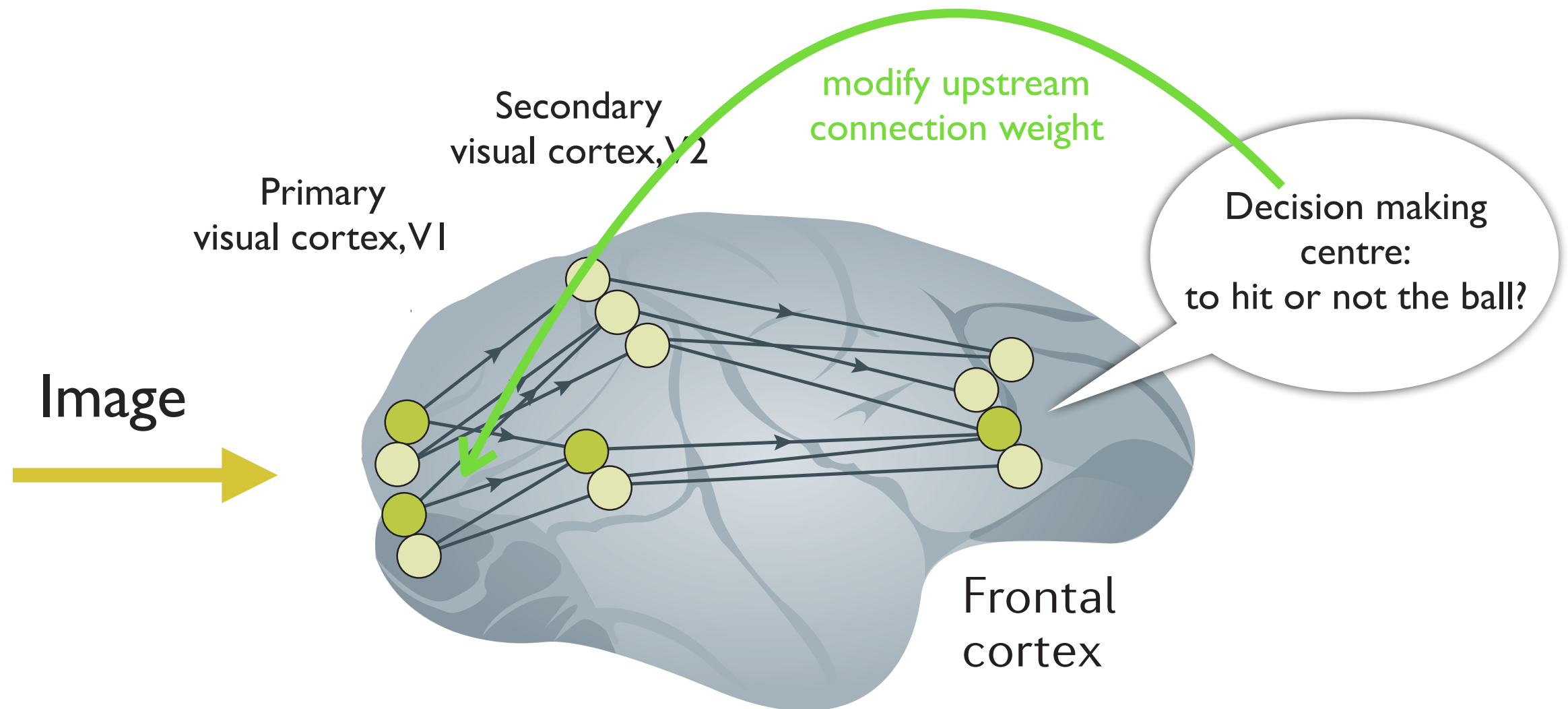
# How to assign credit in the brain?



\*: or associative cortices

Roelfsema et al. Nature Neuroscience Rev 2018

# How to assign credit in the brain?



## **Credit assignment problem:**

Which neural properties (e.g. connection weights) should be modified to improve a given behaviour?

Roelfsema et al. Nature Neuroscience Rev 2018

# Three forms of *credit assignment*

Supervised Learning

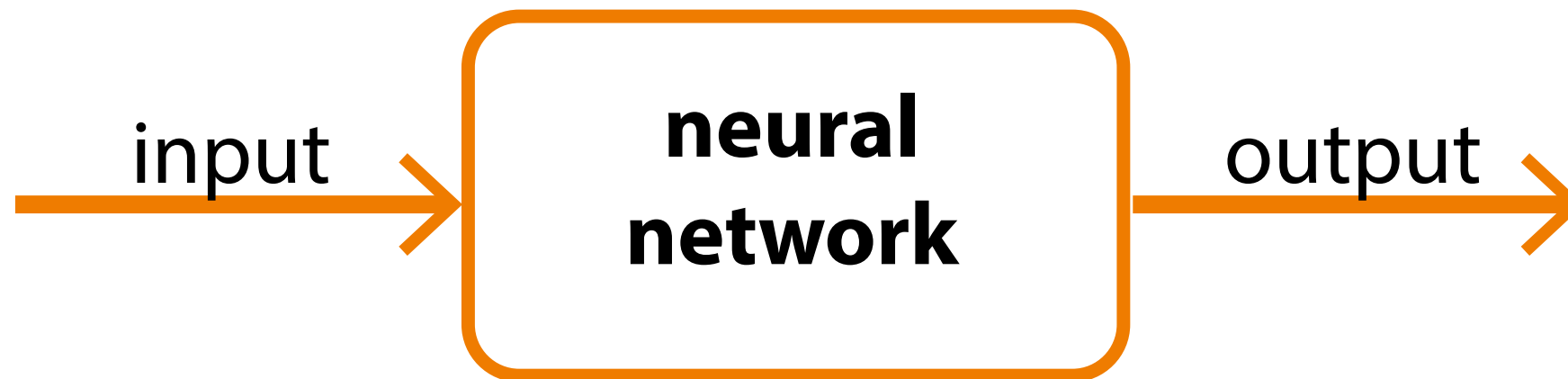
Unsupervised Learning

Reinforcement Learning

# Three forms of *credit assignment*

## Unsupervised Learning:

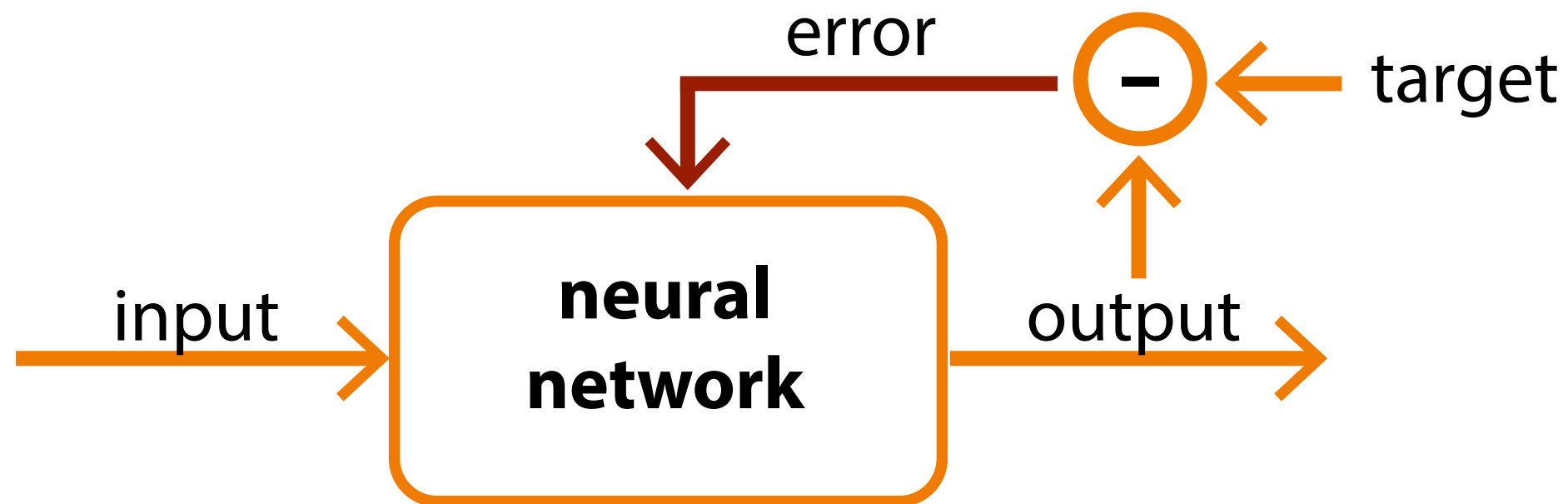
Extracts useful representations of input



# Three forms of *credit assignment*

## Supervised Learning:

Relies on a teaching signal

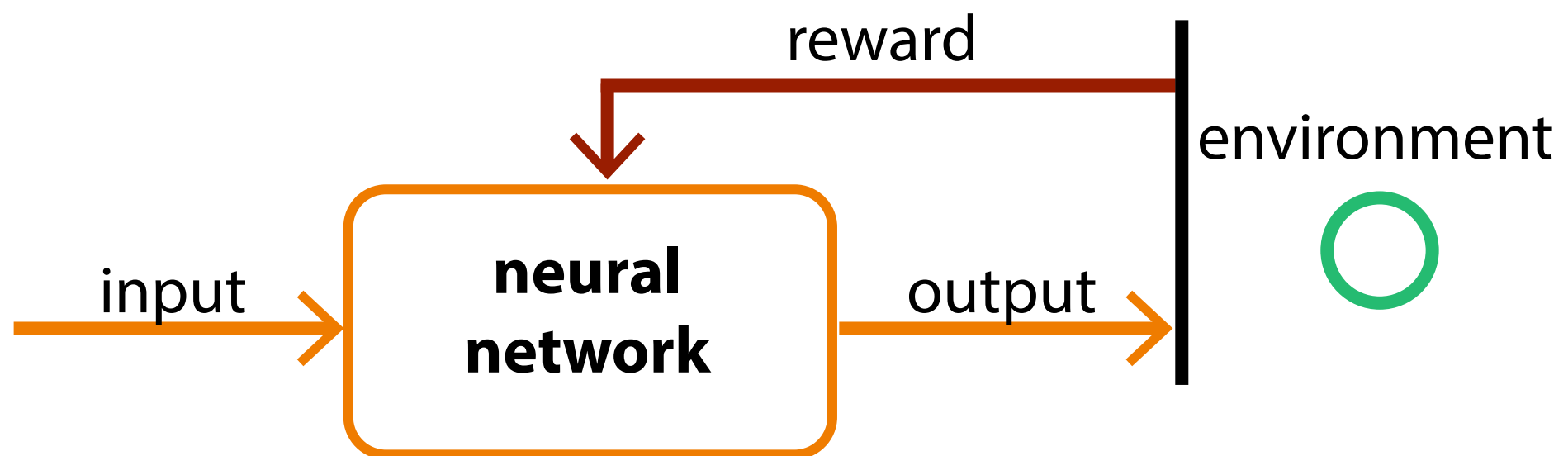




# Three forms of *credit assignment*

## Reinforcement Learning:

Learn to navigate/survive an environment



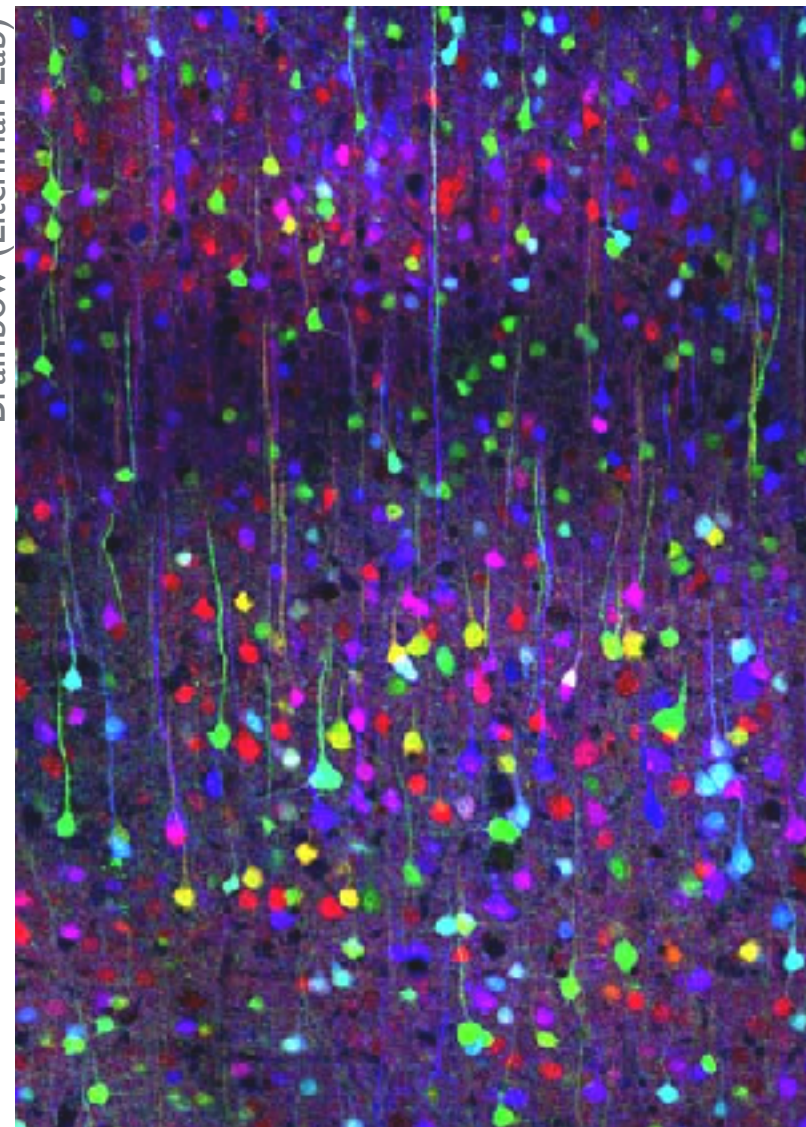
# A feedforward neural network

The brain is like a tropical forest!

With many different neuron *types*  
and *architectures*..

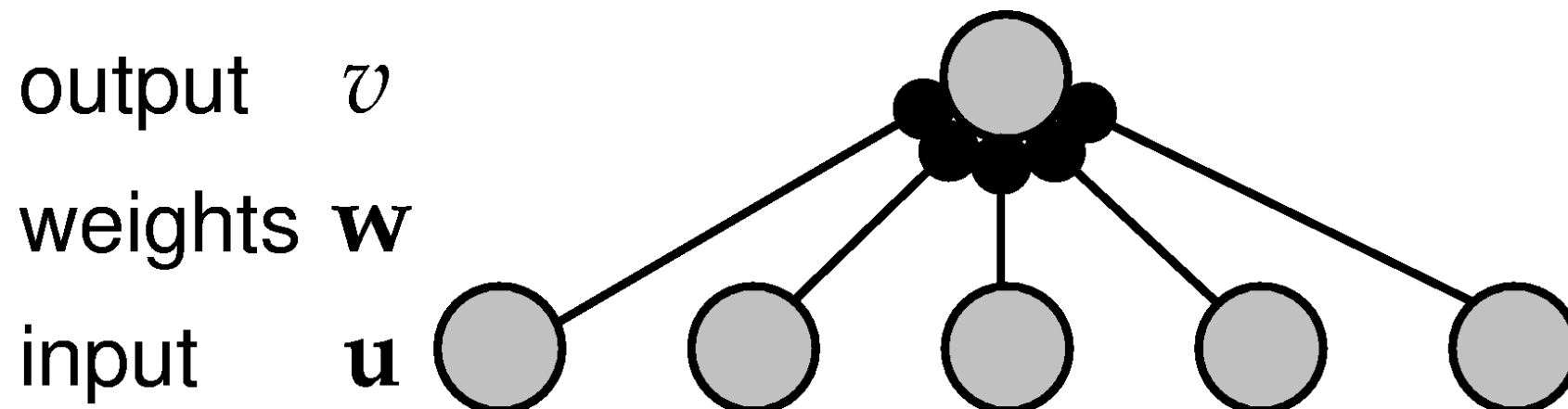
DeFelipe et al. Nat. Neurosci. Reviews 2013

Brainbow (Litchman Lab)



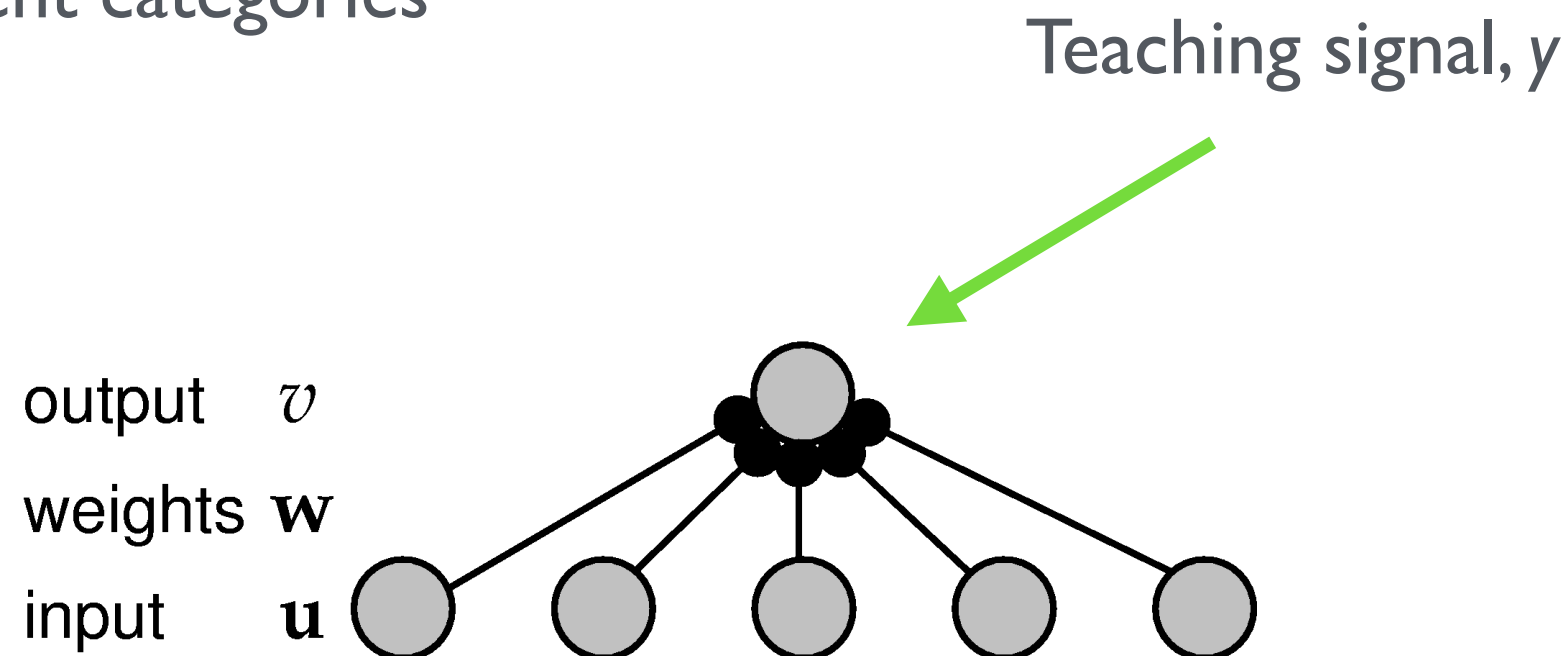
# A feedforward neural network

In theoretical neuroscience we need to abstract out some of this complexity to get at the principles of information processing in the brain!



# Supervised learning

**Goal:** Classify input into different categories



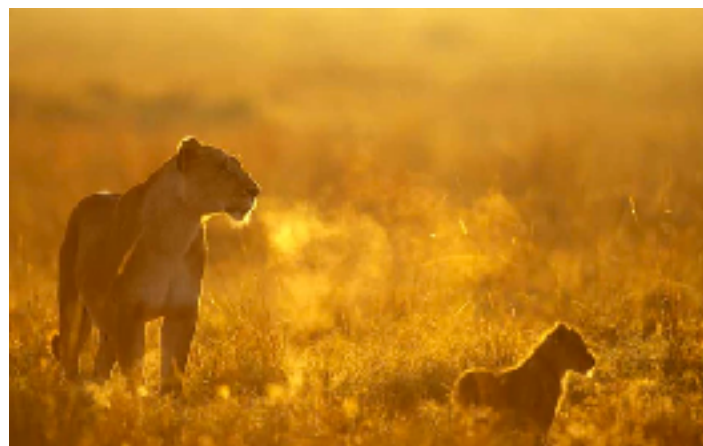
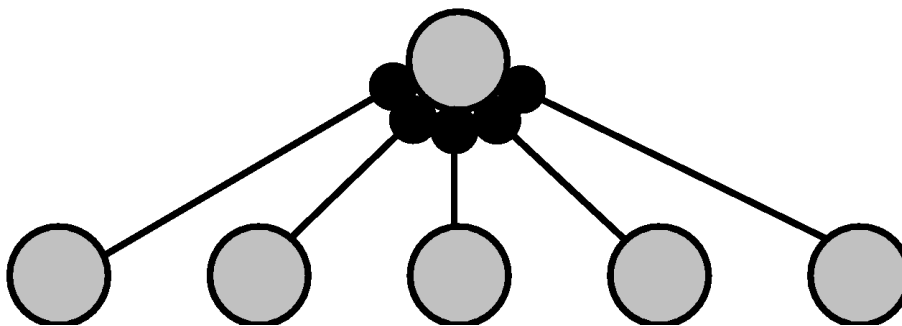
# Supervised learning

$$\text{output, } v = f(wu)$$

where  $f$  is some (non)linear function

Predator, yes/no?  
 $y = \{1, 0\}$

output  $v$   
weights  $w$   
input  $u$





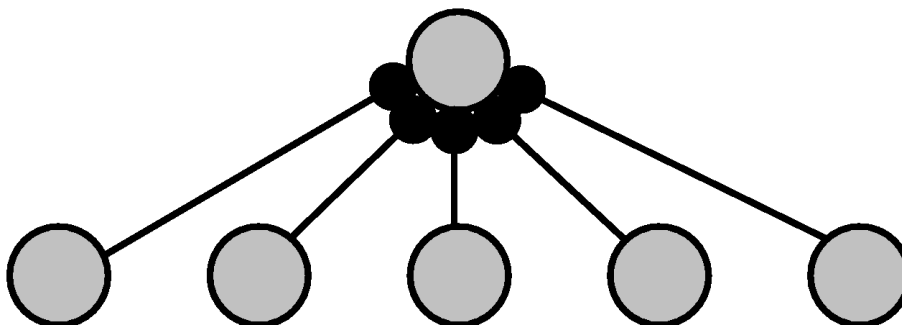
# Supervised learning

Minimise cost

$$\text{cost} = (v - y)^2$$

Predator, yes/no?  
target,  $y = \{1, 0\}$

output  $v$   
weights  $\mathbf{w}$   
input  $\mathbf{u}$



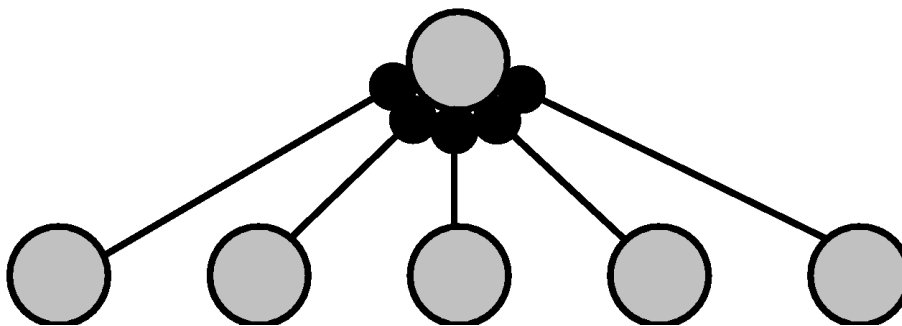
# Supervised learning

Minimise cost

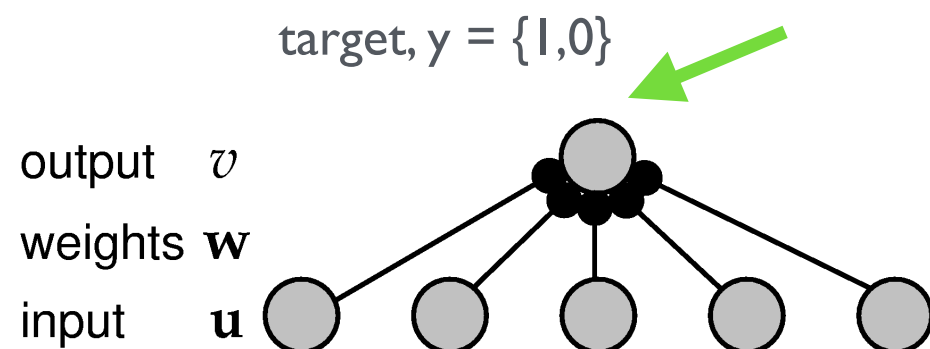
$$\text{cost} = (v - y)^2$$

Predator, yes/no?  
 $y = \{1, 0\}$

output  $v$   
weights  $w$   
input  $u$



# Supervised learning



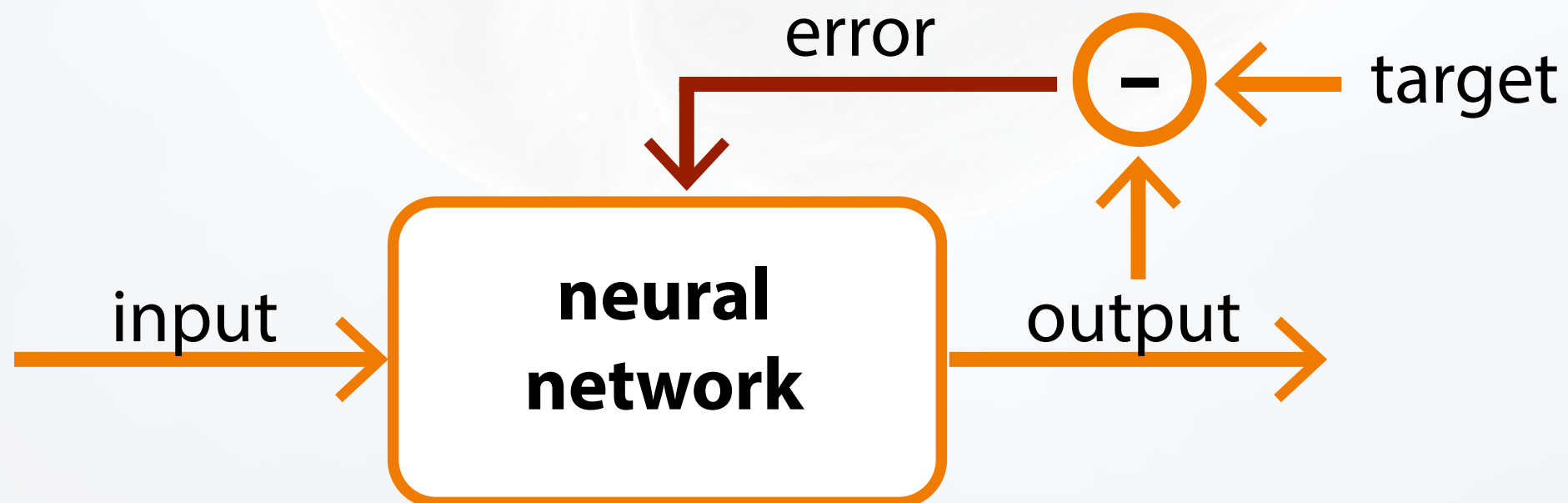
$$\text{cost} = (v - y)^2$$

- The learning rules for  $\mathbf{w}$  can be derived from the cost (or error) function for a particular network: e.g. using the popular backpropagation algorithm
- Examples of methods that use supervised learning:
  - Convolutional neural networks
  - Recurrent neural networks
  - Linear regression
- Animals experience some degree of supervised learning (e.g. with external teacher)

## Group discussion

groups of 2-3 (5 min)

- Can you think of examples of teaching signals that may inform the brain during learning?



## **Group discussion**

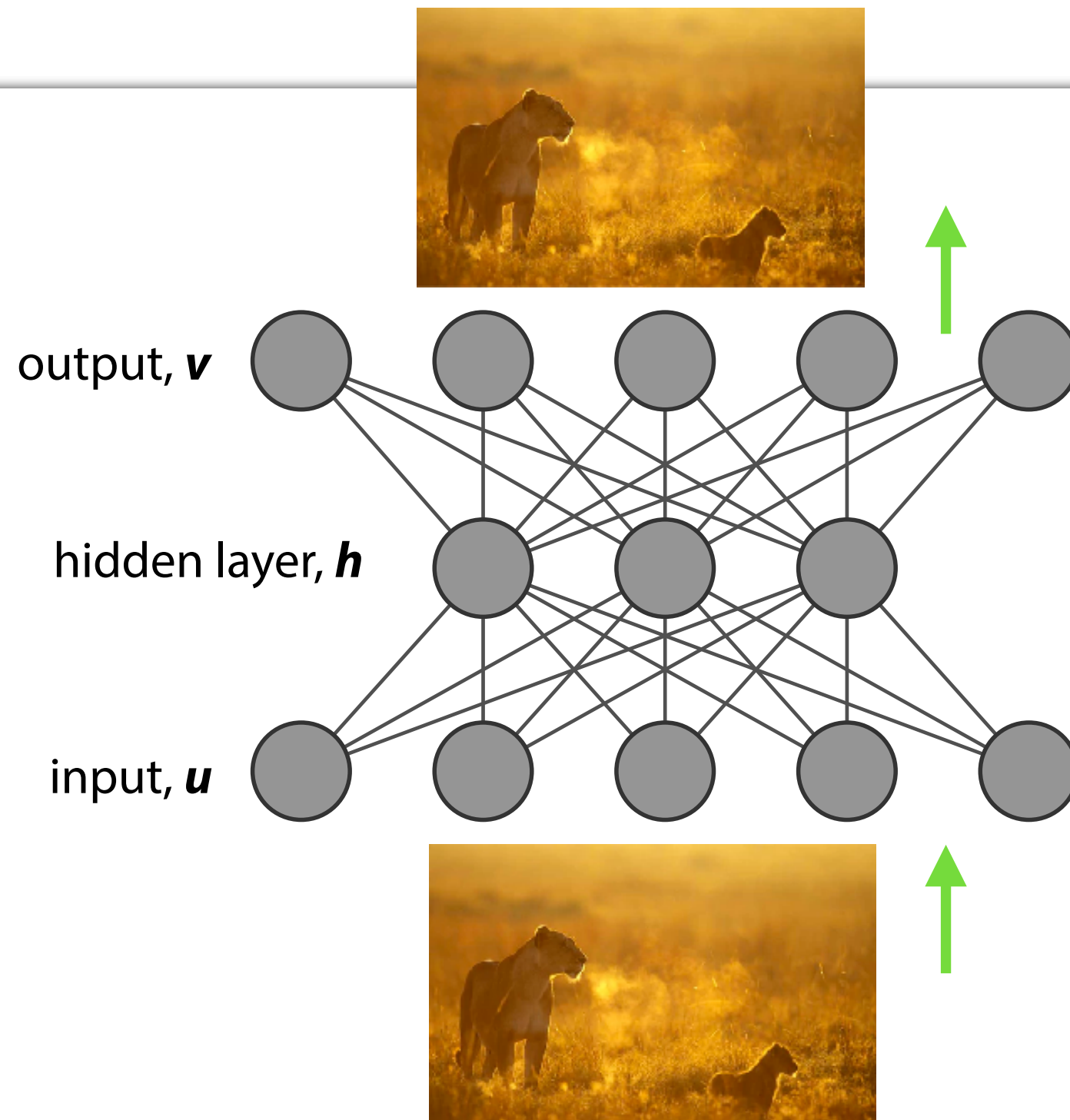
groups of 2-3 (5 min)

- **Can you think of examples of teaching signals that may inform the brain during learning?**
- **Hint: Think in the context of a classroom**



# Unsupervised learning

**Goal:** Extract a representation of the input (dimensionality reduction)



# Unsupervised learning

$$\text{output, } v = f(wh)$$

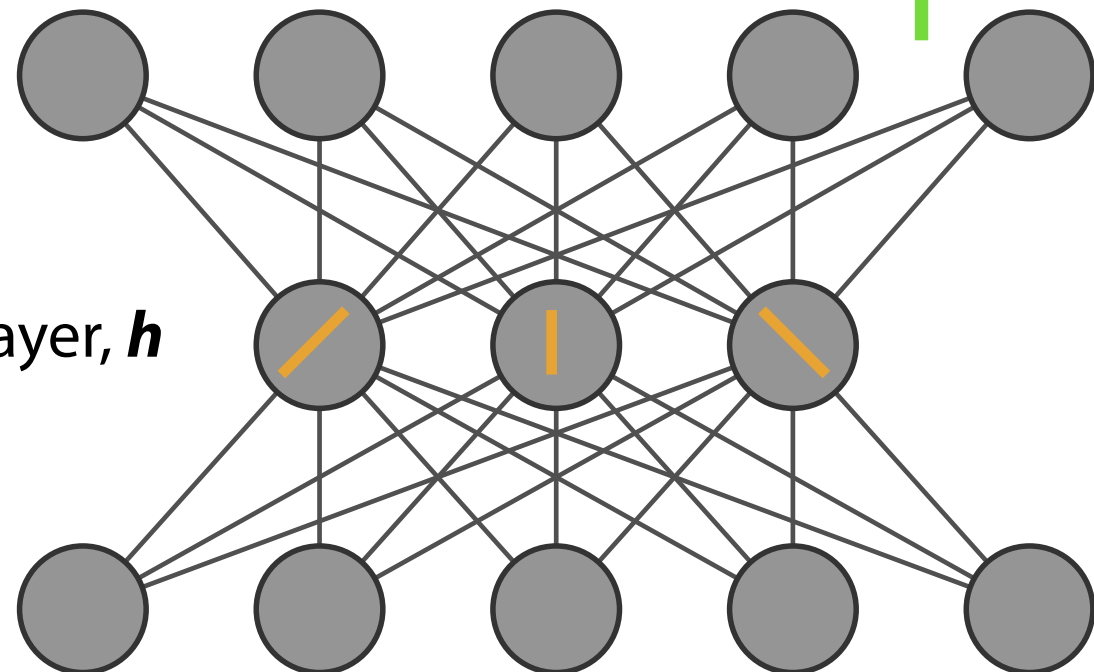
**Learned  
representation**  
(e.g. edges)



output,  $v$

hidden layer,  $h$

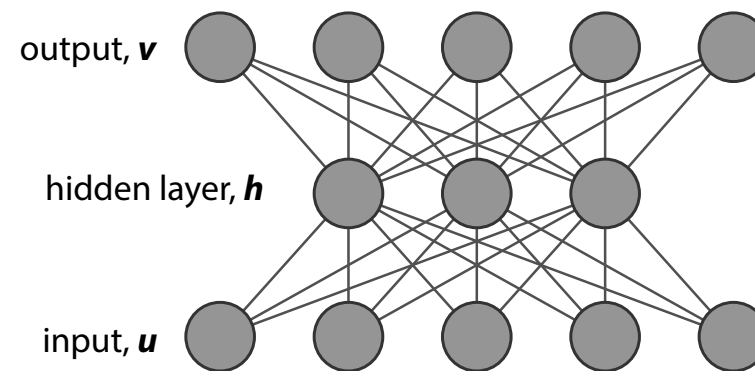
input,  $u$



Minimise cost

$$\text{cost} = (v - u)^2$$

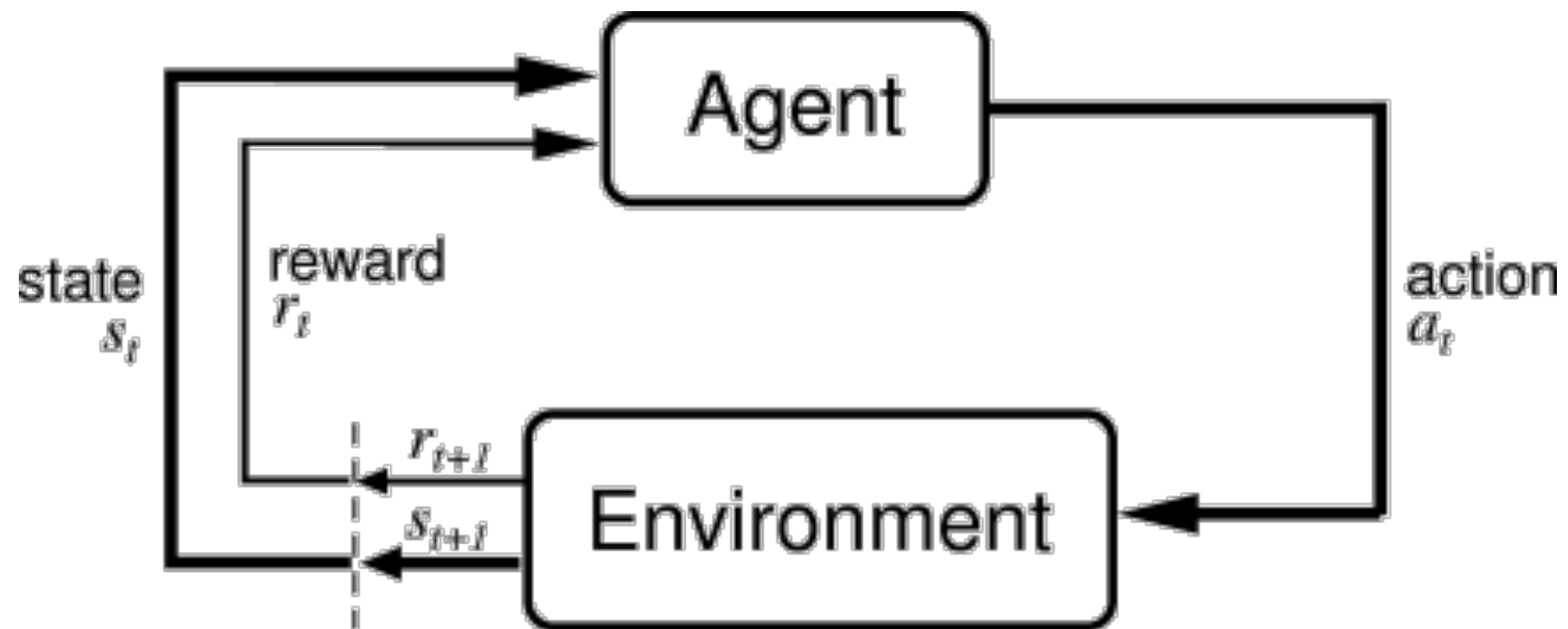
# Unsupervised learning












- The learning rules for  $\mathbf{w}$  can be derived from the cost (or error) function for a particular network, e.g. sparse coding algorithm.
- Examples of unsupervised learning methods:
  - Sparse coding (akin to PCA)
  - Restricted Boltzmann Machines
  - Autoencoders
- Animals are bombarded with vast streams of sensory input with no supervisor

# Reinforcement learning

**Goal:** Find best policy (which actions to take) to maximise reward



# Reinforcement learning

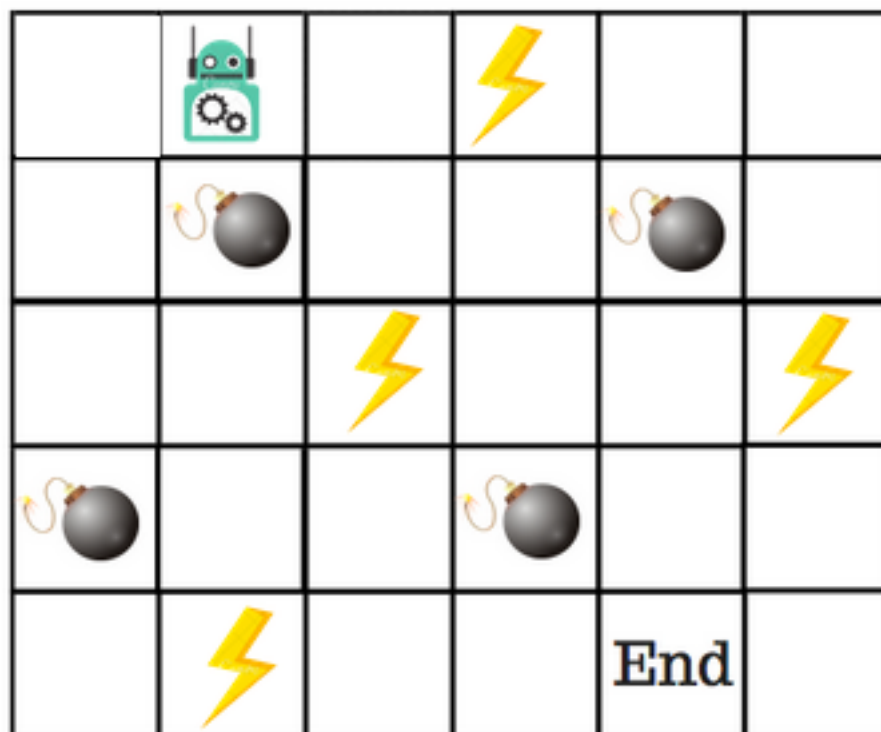
					
					
					
					
				End	

Value table/policy

0.2	0.1	0.1	<b>0.9</b>	0.7	0.5
0.1	<b>0</b>	0.1	0.5	<b>0</b>	0.8
0.5	0.5	<b>1</b>	0.8	0.9	<b>1</b>
<b>0</b>	0.8	0.7	<b>0</b>	0.9	0.9
0.6	<b>1</b>	0.8	0.9	1	0.9



# Reinforcement learning



**Value table/policy**

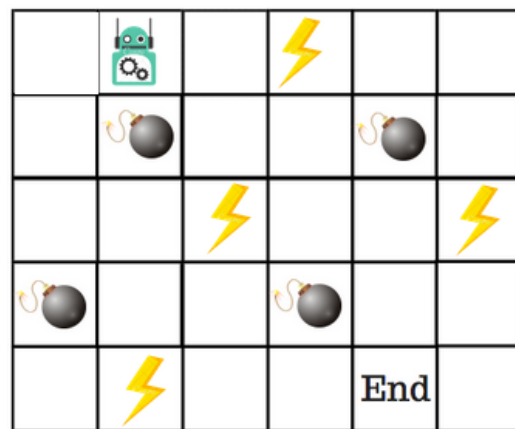
0.2	0.1	0.1	<b>0.9</b>	0.7	0.5
0.1	<b>0</b>	0.1	0.5	<b>0</b>	0.8
0.5	0.5	<b>1</b>	0.8	0.9	<b>1</b>
<b>0</b>	0.8	0.7	<b>0</b>	0.9	0.9
0.6	<b>1</b>	0.8	0.9	1	0.9

Update value table with temporal difference (TD) learning:

$$\underbrace{V(S_t)}_{\text{value}} = V(S_t) + \left( \underbrace{R_{t+1}}_{\text{reward}} + \underbrace{\lambda V(S_{t+1})}_{\text{future value}} - V_t \right)$$

$\lambda$ : discount factor

# Reinforcement learning



0.2	0.1	0.1	<b>0.9</b>	0.7	0.5
0.1	<b>0</b>	0.1	0.5	<b>0</b>	0.8
0.5	0.5	<b>1</b>	0.8	0.9	<b>1</b>
<b>0</b>	0.8	0.7	<b>0</b>	0.9	0.9
0.6	<b>1</b>	0.8	0.9	1	0.9

- The *TD learning equation* enables the agent to gradually learn to predict *future reward* ( $R$ ), based on *value estimates* ( $V_{t+1}$ ).
- Examples of reinforcement learning methods:
  - Temporal difference (TD) learning
  - Q-learning
  - Deep Q-learning
- Because of the role of rewards RL is a common framework in neuroscience

# Different objective/cost functions of learning

## Supervised Learning

$$\text{cost} = (v - y)^2$$

## Unsupervised Learning

$$\text{cost} = (v - u)^2$$

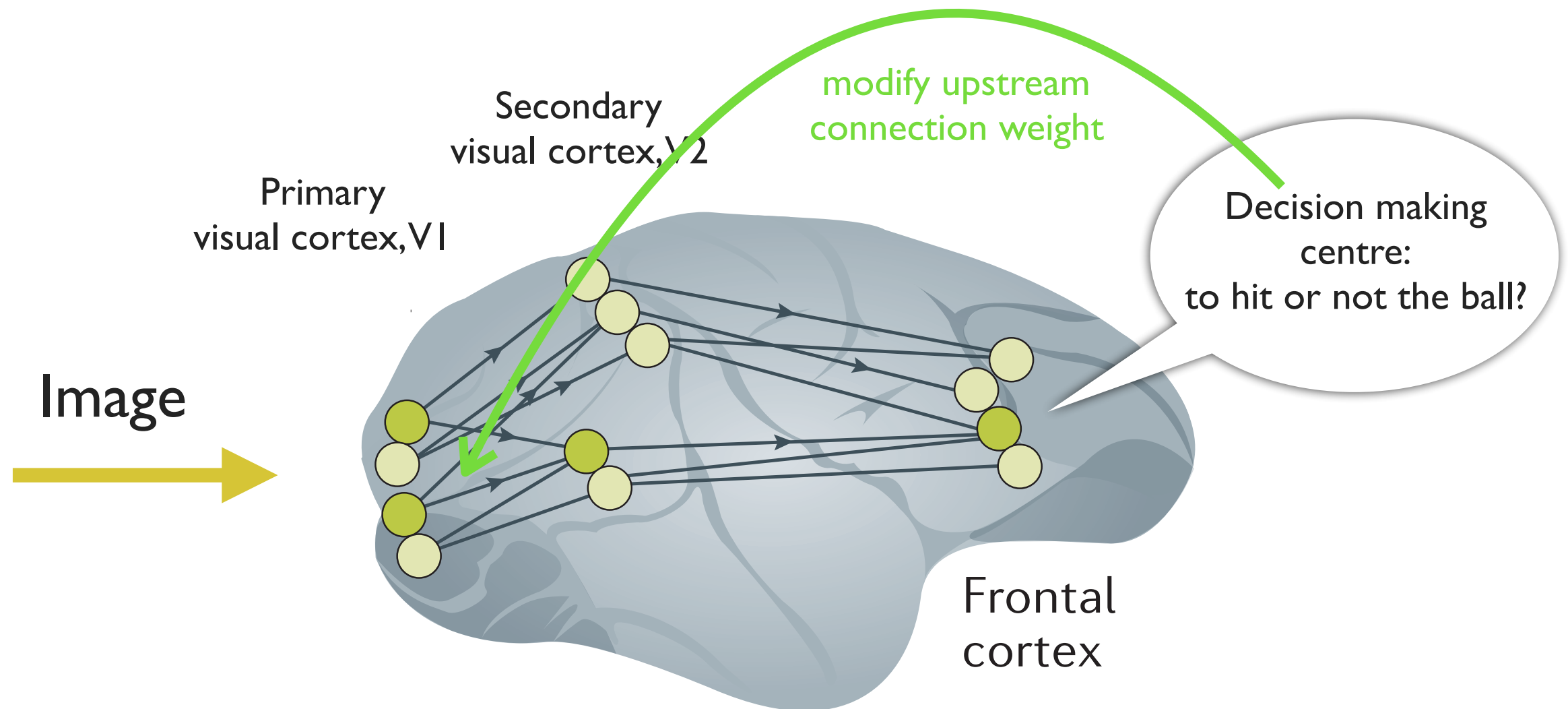
## Reinforcement Learning

$$\underbrace{V(S_t)}_{\text{value}} = V(S_t) + \left( \underbrace{R_{t+1}}_{\text{reward}} + \lambda \underbrace{V(S_{t+1})}_{\text{future value}} - V_t \right)$$

# Summary

- Different forms of learning (or credit assignment) in the brain
- Supervised, unsupervised and reinforcement learning

# How to assign credit in the brain?



Unsupervised and reinforcement learning are the dominant views, but recent research also suggest an important role for supervised learning!

## **Group discussion**

groups of 2-3 (5 min)

- **Which form of learning is more biologically plausible and why?**

# References

## **Text books:**

General theoretical neuroscience: Dayan and Abbott, Principles of Neuroscience (Chapter III)

Deep Learning by Courville, Goodfellow and Bengio

Reinforcement Learning: Sutton & Barto, Reinforcement Learning: An Introduction (see online the newer 2018 edition)

Others: Mackay book on Information Theory, Inference and Learning; Rumelhart and McClelland, Parallel Distributed Processing books

## **Relevant papers:**

- Roelfsema and Holtmaat, Nature Neuroscience Reviews 2018 (recent review on the credit assignment problem)
- Olshausen and Field, Nature 1996 (seminal paper on sparse coding)
- Schultz et al. Science 1997 (seminal paper on neural substrates of reinforcement learning)