

On the role of multiple datasources for Semantic Parsing

First Author

Affiliation / Address line 1
Affiliation / Address line 2
Affiliation / Address line 3
email@domain

Second Author

Affiliation / Address line 1
Affiliation / Address line 2
Affiliation / Address line 3
email@domain

Abstract

This work presents a preliminary foray into the need for, and the challenges involved in building joint learning systems that benefit from multiple sources of semantic information.

1 Introduction

There exist multiple, rich lexical resources for semantic information such as FrameNet (Fillmore et al., 2002), PropBank (Palmer et al., 2005), VerbNet (Kipper et al., 2008); each of them the result of painstaking annotation efforts by teams of linguistics over several years. Systems for semantic parsing tasks have mostly focused on using only a single resource. For instance, Semafor (Das et al., 2010) is a frame-semantic parsing system based on supervised learning that uses FrameNet data to train a model. The Illinois-semantic role labeling system (Punyakanok et al., 2008) uses PropBank annotations. Often, a single resource despite being very high quality does not contain comprehensive annotations for every semantic entity and will not cover all semantic concepts. For instance, PropBank annotations are very rich in verbs, but very sparse in nouns. These resources also differ in the granularity of the annotated data - FrameNet frames are semantically finer-grained as compared to the PropBank rolesets. However, together these complementary sources provide a very good and diverse coverage of the semantic space - a fact that should be exploited by systems in order to achieve a better performance on semantic analysis.

From a supervised learning perspective, the problem of combining the knowledge across these resources can be viewed as a joint learning problem. If we treat the annotation schema of each resource as one label-space, then we can formulate this as a multitask learning problem across tasks with different label spaces. The goal of a sys-

tem should then be to learn a model over the different label spaces. This problem also manifests in the information extraction community, where there are multiple knowledge-bases confirming to different ontologies.

To see an example illustrating the need for models that integrate resources, consider the following sentence:

*The award celebrates businesses that
innovate products which appeal to social
good.*

The three predicates in the above sentence have been rendered in a different font. The frame-semantic parsing output from Semafor is shown in Figure 1. While the system completely misses two of the predicates, one of them *appeal* is not recognized correctly. The reasons for the errors are: the first two predicates do not have an annotation in FN, and the third one is annotated in the context of appeals in a court of law. More importantly, all three predicates have an appropriate annotation in PB.

The following list indicates the scenarios where a joint model based on both FrameNet and PropBank data can improve frame-semantic parsing accuracies in a system like Semafor. The examples and numbers presented below were obtained from the latest FrameNet release (1.5) and for PB we consider only the WSJ section of the annotations.

- Frames with none or very few annotations in FN. The frame *Manipulation* does not have any annotations for the verb *hold*, whereas PB-WSJ has 117 instances (that had an extractable argument mapping) for this frame-target combination. The frame *Experienter_obj* has several predicates without any annotations, for example *appeal*, *harass*, *worry*, *boggle*. The first three of these have annotations in the PB-WSJ data. There are 984 such predicates in FN that have been



Figure 1: Frame semantic parsing output from Semafor for an example sentence.

assigned to frames, but with no sentence annotations available.

- Frames with few known targets or targets with no associated frames. For example, the frame *Giving* has 19 known verbs as targets in FN. Synonyms of *giving* such as *allot*, *assign*, *designate*, *allocate* are not present in FN. Overall, there are 475 verbs in the PB WSJ data that are not targets for any frame in FrameNet. Some examples are: *involve*, *lurk*, *nominate*, *ladle*, *entice*, *bank*.

Ideally, a joint learning system should also be able to suggest new targets for a frame based on the lexical similarity with the frame’s existing targets.

Linguistic resources to map the different annotations have been built, but to a very limited extent. SemLink (Bonial et al., 2014) is one such database that maps and unifies different lexical resources of semantic information: such as PropBank (PB), FrameNet (FN), VerbNet (VN). The mappings that SemLink provides are available at two different levels: (a) sentence level parallel annotations - the WSJ section of the PB data has been annotated with the appropriate frames and frame-elements as well as VerbNet classes wherever possible, thereby giving detailed PB, VN and FN annotations for each sentence (b) concept/roleset level mappings - these are coarse-level mappings defined between a PB roleset and a VN roleset or a FN frame and a VN roleset. These mappings can be one-to-one, one-to-many or many-to-many depending on the semantic generality of the involved rolesets. To go from a PB roleset to a FN frame, one has to go via the VN roleset first.

In this work, we will focus on Semafor as the target system whose performance we want to improve. We are hence interested in using the SemLink mappings to get FN compatible data. The type (a) mappings can be directly used to aug-

ment the FN annotations; in the next section we present an analysis on the quantity and usability of the available mappings. Using the type (b) annotations first requires disambiguating the frame-to-roleset labels and then aligning the predicate arguments of the roleset with those expected in the frame. Note that the two argument sets might be of different cardinality.

2 Data analysis

We present some statistics of the data resources in Tables 1 and 2. The first table summarizes the SemLink mappings for the PB WSJ data. The total number of annotated PB instances are 74977, a majority of which do not have the corresponding FN labels due to various difficulties in mapping them. Around 31% of the predicates have the frame label *IN* meaning “indefinite”. For these cases the mapping from VN to FN does not clearly indicate which Frame the instance should be. About 20% of the instances are labeled *NF* or “no frame” as FrameNet currently does not have an appropriate frame class for the semantic concept represented by the PB predicate. Of the remaining, 21% are incomplete as they only have frame labels and no argument annotations. Most of these are predicates with modifier arguments. This leaves about 29% usable mappings, 9% of which had argument pointer and other issues. Eventually, we were able to extract about 15323 instances.

The second table compares the extracted PB-WSJ annotations with the original FN annotations (version 1.4) used to train the Semafor model. The number of annotations at the sentence-level and frame-level are shown. It is evident that FN has a much higher annotation density - around 9 frames per sentence, as compared to around 1.2 for the PB derived data .

The mappings we obtained increase the number of annotations for around 170 frames. Figure 2

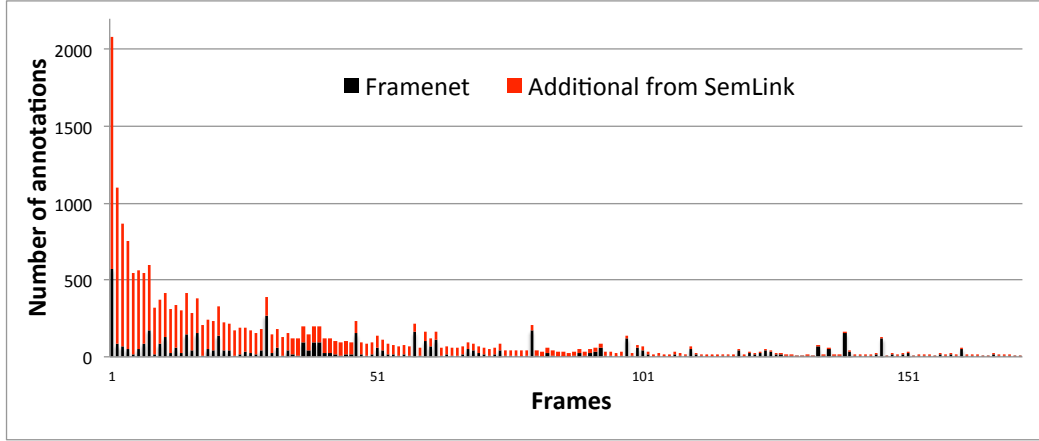


Figure 2: The number of new annotations per frame obtained upon extracting the WSJ mapping from SemLink. The bars are coloured (red) to indicate the contribution from the new annotations. Only frames for which new annotations were found are shown.

FN frame annotation	Verb tokens from PB	% of all
Frame label = <i>NF</i>	14624	20%
Frame label = <i>IN</i>	22982	31%
Frame with no arguments	15533	21%
Frame with at least 1 argument mappable	15323	20%
Instances not mapped due to other issues	6516	9%
Total PB predicate tokens (instances)	74977	100%

Table 1: Statistics of PB-WSJ data from SemLink

Annotation unit	Count
Sentences in FN 1.4	2780
Annotation sets in FN 1.4 (i.e frame instances)	23940
Annotation density	8.6
Sentences in PB WSJ data	38594
Verb tokens in PB WSJ	74977
Annotation density	1.9
Sentences extracted from SemLink PB-WSJ	12896
Annotation sets extracted	15323
Annotation density	1.2

Table 2: Comparison of annotation density

shows a stacked bar-chart plotting the annotations for every frame, sorted in decreasing order of additional frames obtained. The highest is around 1500 new annotations for the frame *Statement*.

2.1 Noisy SemLink annotations

Since SemLink was built, FrameNet has updated frame definitions, some new frames were introduced and old ones deleted or divided into finer categories, irrelevant predicates moved to proper frames etc. Hence some of the SemLink annotations are obsolete and sub-optimal. For example, the frame *Statement* does not contain the target `complain.v` anymore as a new frame *Complain* was introduced. There are around 3000 such instances with obsolete annotations. These can be detected easily and they are also not semantically absurd, but correcting these will require re-annotation on a case-by-case basis.

Additionally, there are some mistakes in some of the annotations due to the existence of multiple frame matches for a particular predicate. For example, in the sentence *McMoRan Energy Partners will be liquidated*, the frame for `liquidate` is *Killing* - all 14 occurrences of `liquidate` have this error. The sentence *Speaker Jim Wright.. attempting to direct the president* has the frame annotation *Behind_the_scenes* which refers to film “direction”. There are 17 instances with this frame erroneously marked. These kind of errors are hard to detect. The SemLink mappings can thus not be used as gold-standard annotations to train models. One possibility is to use this data as low-confidence training data.

3 Models for joint learning

This problem of learning from multiple resources can be formulated in different ways. We present here a spectrum of possible approaches, each relying either on a different methodology or manipulating the available data differently. For simplicity, let us assume there are two resources D_1, D_2 . Let $X_1, X_2 \in \mathcal{X}$ represent the set of data instances (i.e sentences) from the two sources and $Y_1 \in \mathcal{Y}$, $Y_2 \in \mathcal{Y}'$ be the labels.

- Learning a deterministic mapping $\phi : \mathcal{Y}' \rightarrow \mathcal{Y}$ between the label spaces from the two resources. Such a mapping can be used to transform the annotations from one resource into the labeling schema used by the other. We could then train a model using $\{X_1, Y_1\} \cup \{X_2, \phi(Y_2)\}$. The SemLink mappings we discussed earlier give us such a function ϕ that gives a limited and ambiguous mapping.
- A two-stage pipeline that trains a model on D_1 say θ_1 and apply it on X_2 . The output labels can be used as features along with X_2 to train the model θ_2 on D_2 .
- A bootstrapping approach that uses co-training similar to (Clark et al., 2003), where we iteratively improve one model using the output from the other. This is the same as the pipeline approach described above, performed for several iterations. At iteration t , we obtain θ_1^t and apply it on X_2 . The output labels are used as features along with X_2 to train the model θ_2^t . In the next iteration ($t + 1$), the output labels of θ_2^t applied on X_1 can be used as features to train θ_1^{t+1} .
- A multi-task learning based objective function that maximizes the log likelihood over the two data sources D_1 and D_2 . The parameters from the two tasks can be coupled together using a feature transformation (Argyriou et al., 2006), or based on feature correspondences learned using unlabeled data (Blitzer et al., 2006).

4 Evaluation

As indicated in the introduction, a model encompassing multiple resources can fill in various types of gaps in the FN annotations. It is infeasible to measure improvements for predicates which

are not already frame targets in FN. For existing frame-predicates with no argument annotations, the SemLink mappings can be used as test data.

Acknowledgments

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