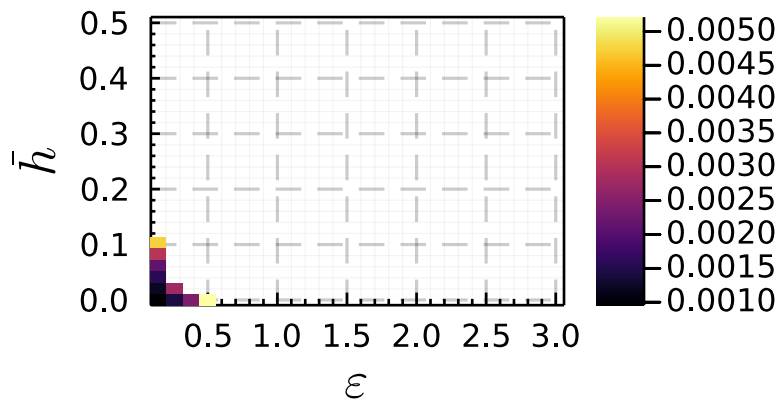
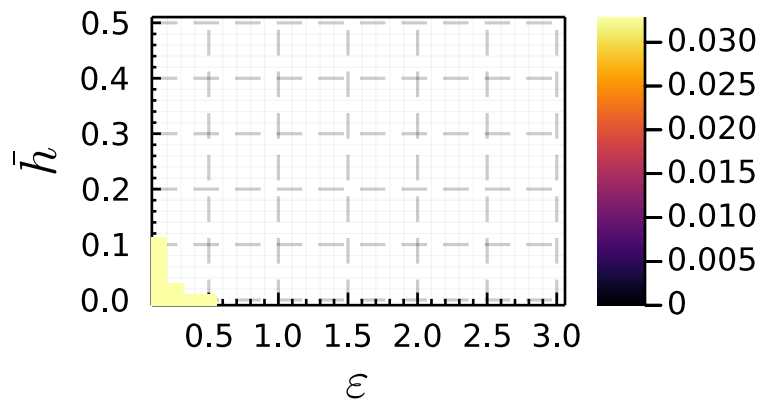
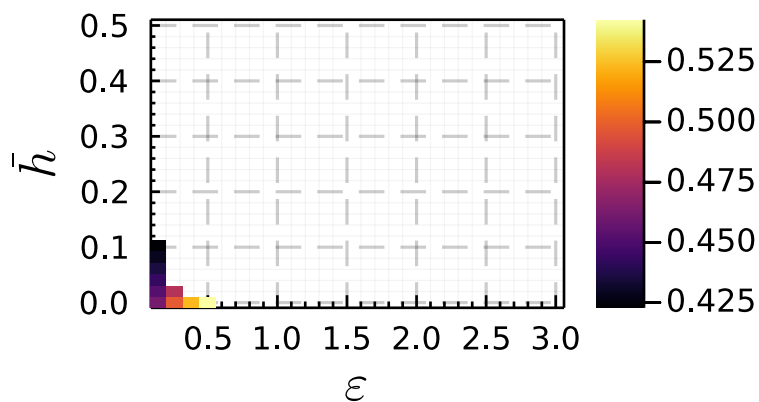


$Std(u_t)$  $Std(z_t)$  $Std(y_t)$  $Std(w_0)$ 