

## PI Planning Simulation

## Features and Starter Stories for Alice



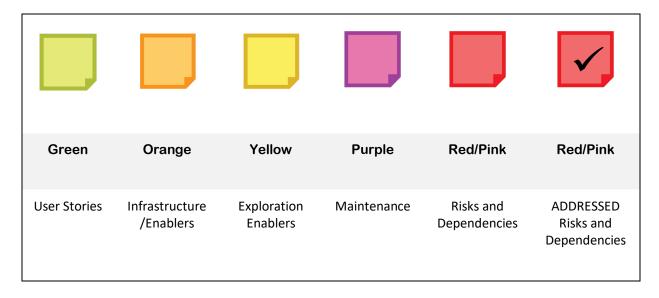
## Instructions:

- Print out (single-sided) and cut out the features and the starter stories
- Participants may find it easiest to cut out the stories and tape them to the appropriate color of the Sticky Note (see Color Coding Sticky Notes Legend below)
- Some Stories are Enablers such as spikes, refactors, or defects
- Features are already prioritized



**NOTE:** The stories for the simulation are Starter Stories. Keep in mind that many are missing, some need to be broken down, or are duplicates in other teams' backlogs.

## **Color Coding Sticky Notes Legend**



**PRIORITY**: 1 **DESCRIPTION:** Make vehicle follow virtual roads based on GPS location in addition to following roads marked by lines As a vehicle control As a vehicle control I can be encoded with the GPS coordinates for I can use the virtual roads for route planning So that I can use them when driving to destinations virtual roads at an installation So that they are included in route planning SIZE: SIZE: As a vehicle control As a vehicle control I can be encoded with the GPS locations where I can be encoded with virtual GPS road locations where cross traffic is likely to exist a stop is required so that the vehicle will treat those locations like other so that the vehicle will treat those locations as stop signs intersections SIZE: 3 SIZE: 3 As a vehicle control As a vehicle control I can be encoded with GPS hard boundaries in I can include virtual stop signs in route planning the virtual road environment So that I avoid routes with many stops when selecting the so that I will never let the vehicle enter those areas optimum route SIZE: 3 SIZE: 5 As a vehicle control As a vehicle control I can ensure I stop at all virtual stop signs I can use hard boundaries in the virtual road So that I avoid accidents at those locations environment in route planning So that I avoid large detours when selecting the optimum route SIZE: 5 SIZE: 5 As a vehicle control engineer I can encode virtual data for the test track So that I can validate the vehicle will follow virtual routes on the test track I SIZE: 3

FEATURE: Follow Unmarked, Virtual Roads

**FEATURE**: Request Delivery

**PRIORITY**: 2

As a mobile app requestor

SIZE: 2

I can save my previous delivery locations
So that I do not have to reenter them

**DESCRIPTION**: Request a delivery on the mobile app



As a mobile app requestor I can enter the pickup location So that the vehicle knows where navigate to retrieve the cargo	As a mobile app supplier I can be notified of the items in the request So that I can prepare them before the vehicle arrives
SIZE:	SIZE:
As a mobile app requestor I can enter the delivery location as an address So that the vehicle knows where to deliver the cargo	As a mobile app requestor I can enter the items I am requesting So that the vehicle can notify my supplier
SIZE: 1	SIZE: 2
	<del></del>
As a mobile app requestor I can enter the delivery location as a GPS coordinate So that the vehicle knows where navigate to retrieve the cargo for locations that have no address	As a mobile app supplier I can be notified the anticipated arrive time when a request is made for my destination So that I can have the cargo ready for pickup NOTE: requires GPS expertise to calculate time
SIZE: 3	SIZE: 3
As a mobile app requestor I can be told an approximate travel time to deliver my cargo So that plan my pickup accordingly NOTE: requires GPS expertise to calculate time	As a mobile app requestor I can be notified if a request is cancelled So that I am not waiting for a request that will never arrive
SIZE: 3	I SIZE: 5
As a mobile app supplier I can cancel a request if I do not have the proper supplies So that the vehicle does not make a useless trip	As a mobile app requestor  I can save entire orders including delivery location, pickup location, and requested cargo So that I can order with a single click
SIZE: 3	SIZE: 5

**FEATURE:** Parallel Park

**PRIORITY**: 3

**DESCRIPTION**: At destination, locate appropriate parallel parking space and park there



As a sensor management

I can detect parallel parking locations with lines when there are no vehicles in adjacent spaces So that I can park using only lines and a curb as reference points



As a vehicle control

I can parallel park the car using only parking lines and the curb as my guide

So that I can park the vehicle



SIZE:

SIZE:

As a sensor management

I can detect an appropriate parallel parking location when other vehicles are parked in adjacent spaces



As a vehicle control

I can center the vehicle between the lines of my parking space

So that I do not block adjacent vehicles from leaving

So that I can park using other vehicles as a reference

SIZE: 3



As a vehicle control

I can adjust centering if one vehicle parked too close to our shared line

So that I do not block adjacent vehicles from leaving



As a sensor management

I can detect an appropriate parking location where lines and other vehicles are involved

So that I can park in spaces using both lines and other vehicles as a reference

SIZE: 3

SIZE: 2

As a vehicle control

I can put the vehicle into park and turn the vehicle off after successfully parking

So that the requester can safely retrieve their items



As a vehicle control

I can detect a red curb

So that I ensure I only park in legal parking locations



SIZE: 1

As a sensor management

I can detect when a parking space has sufficient room but would straddle a parking line

**So that** I can exclude that spot to ensure I always park legally



As a vehicle control

I can parallel park at a curb where there are no lines or vehicles

So that I can park on any street for a requester to retrieve their items

SIZE: 2

SIZE: 3

SIZE: 3

As a vehicle test track

I can be configured with lines and mock vehicles So that we can validate parallel parking scenarios on the test track



SIZE: 2

**FEATURE:** Notify Delivery Arrival

**PRIORITY: 4** 

**DESCRIPTION:** Notify requester of delivery arrival via smartphone app



20

As a mobile app requester

**I can** register for delivery notifications on the mobile application

So that I know when my delivery is arriving

SIZE:

As a vehicle control

I can determine how much time remains until arrival at the delivery destination

**So that** vehicle communications knows when to notify the requester

SIZE:

As a vehicle communications

I can send a notification to the requester's mobile app So that the requester knows the current delivery status

SIZE: 2

As a mobile app requester

I can set the time by which to be notified

**So that** I can be notified of delivery arrival earlier or later than the default value

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SIZE: 5

As a mobile app requester

I can have the delivery time continually sent

**So that** I am always aware of the remaining time until delivery

\_\_\_\_\_

As a mobile app supplier I can be notified when the delivery is complete

So that I know the requester has their cargo

SIZE: 1

SIZE: 3

ENABLER (TECHNICAL SPIKE): Assess the bandwidth necessary to support continually streaming the vehicle's position to the mobile app so that the delivery vehicle can be shown an a real time.

streaming the vehicle's position to the mobile app so that the delivery vehicle can be shown on a real-time map.

As a mobile app requester

I can have my credentials authenticated when interacting with delivery notifications

So that so that only someone with my credentials is

authorized to receive and configure delivery notifications

SIZE: 2

SIZE: 5

**ENABLER (TECHNICAL SPIKE):** Show real-time vehicle tracking on the mobile application.

Use a test double to proxy for the real vehicle position.

SIZE: 5

**FEATURE**: Fleet Management

**PRIORITY:** 5

**DESCRIPTION:** Manage a fleet of autonomous vehicles



As a fleet manager

I can assign the time and days which a vehicle is in operation

So that I balance the work load for each vehicle books

SIZE:

As a fleet manager

I can restrict vehicles to different areas within a facility So that vehicles do not all congregate in one area of the facility and starve other areas of deliveries

SIZE:

I As a fleet manager

I can know the location and status of all my vehicles

I So that see know if I have good delivery coverage and if I So that know their current delivery patterns a vehicle is part of an active delivery

SIZE: 3

I As a fleet manager

I I can see a live map of all my vehicles and their I delivery routes

I SIZE: 5

I As a fleet manager

I can know the total operation time, distance I traveled, and cargo weight hailed for each vehicle So that manage the vehicle maintenance schedule I As a fleet manager

I can see a map of all deliveries made in the past day, I week, and month

I So that look for patterns to adjust the vehicles' area I restrictions and operation times to provide better service

SIZE: 2

As a fleet manager

I can recall a vehicle from the fleet

So that I can take the vehicle offline for maintenance

SIZE: 1

As a vehicle communications

I can send the time, weight, and distance traveled to operations control at the end of each delivery

So that my maintenance can be tracked

I SIZE: 2

As a vehicle communications

I can send my location

So that fleet management can know the location of all vehicles to optimize coverage

SIZE: 2

As a vehicle communications

I can send pickup request data (pick location, delivery location, cargo) when a delivery request is made

So that fleet management can track deliveries

SIZE: 2













FEATURE: Smooth Driving with Fully Loaded Vehicle



**PRIORITY**: 6

**DESCRIPTION**: Eliminate erratic movements and smooth acceleration and turning when vehicle is fully loaded

As a vehicle control I can change the acceleration from a stop So that the vehicle accelerates more smoothly from a stop	As a sensor management I can better predict the behavior of obstacles in front of the vehicle So that the vehicle control can respond to deceleration needs in a timelier manner
SIZE:	SIZE:
As a sensor management I can know the total vehicle weight, including cargo So that the vehicle control will know how smooth or aggressive it can drive the vehicle	As a vehicle control I can track obstacles at a further distance So that I can anticipate movement and respond more quickly to obstacles
SIZE: 3	   SIZE: 3
As a sensor management I can identify road marking at a further distance So that the vehicle control can better anticipate turns and stops	As a vehicle control I can adjust how aggressively I brake So that the vehicle slows more smoothly
SIZE: 2	SIZE: 3
As a vehicle control I can take turns more slowly with heavy cargo loads So that to eliminate the current instability on turns SIZE: 3	As a vehicle control I can use cargo weight to determine when the decelerate and brake So that deceleration and stopping can begin earlier with heavy cargo loads  SIZE: 5
As a test vehicle on the test track I can test the deceleration and braking adjustments So that validate smoother stopping with heavy cargo loads SIZE: 5	

FEATURE: Obey Unique Lane Markings

**PRIORITY:** 7

**DESCRIPTION:** Detect and obey unique road markings found in special (for example government) facilities



As a sensor management I can know the unique road markings at government installations that indicate roadways

So that vehicle control can use them for navigation

SIZE:

As a sensor management

I can know the unique road markings at approximation of a government installations that indicate vielding to traffic So that vehicle control will know to yield in those I locations

SIZE: 2

■ As a vehicle control

I can yield to traffic at the unique road markings I from sensor management

So that I yield at the appropriate locations

SIZE: 3

As a sensor management

I can know the unique road marking at a tarmac indicating no vehicles allowed

So that I do not interfere with flight operations

As a vehicle control

I can de-conflict traditional roadway markings from those found in government installations So that I make correct navigation decisions

SIZE: 5



As a vehicle control

I can identify unique road markings from sensor management for navigating

So that I follow them during delivery



As a sensor management

I can know the unique road markings at government installations that indicate stopping the vehicle

So that vehicle control will know to stop





I can stop at the unique road markings from sensor management

**So that** I stop at the appropriate locations

SIZE: 5



As a sensor management

I can detect signs at government installations that indicate loading zones

So that I know the appropriate locations to park



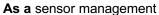


**FEATURE**: Avoid Obstacles Unique to Government Installations



**PRIORITY: 8** 

**DESCRIPTION**: Characterize sensor's ability to detect and process obstacles unique to government installations





I can track a single obstacle that continually changes speed and directions like carts, pedestrians, fork lifts, etc.

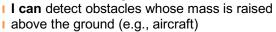
So that vehicle control can respond to the obstacle's dynamic behavior

SIZE:

ENABLER (TECHNICAL SPIKE): Characterize how sensor management recognizes obstacles that approach differently from vehicles on streets as may occur in large, opens spaces

SIZE:

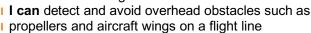
As a sensor management



**So that** the vehicle will avoid the entire object so as not interfere with its operation

SIZE: 5

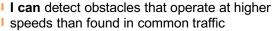
As a sensor management



So that the vehicle avoids collisions with them

SIZE: 3

As a sensor management



So that the vehicle avoids collisions with them

As a sensor management

I can track three obstacles that independently and continually changes speed and direction

So that vehicle control can respond to the object's dynamic behavior

SIZE: 5

SIZE: 3

**As a** sensor management

I can detect railings mounted in the ground So that the vehicle does not collide with them

As a sensor management I can detect speed bumps

> So that the vehicle can slow down for them to not damage the cargo

SIZE: 2

As a sensor management

I can detect imperfections in the road

So that vehicle control can slow down or avoid them and not damage the cargo

SIZE: 3

ENABLER (TECHNICAL SPIKE): Characterize how sensors responds to more than 3 independent objects that continually changing directions and speeds simulating dynamic objects that would be found on a busy flight line or dock

SIZE: 5