

# Designing for Epistemic Uncertainty in Research Synthesis

Alex Kale

Sarah Lee

TJ Goan

Matthew Kay

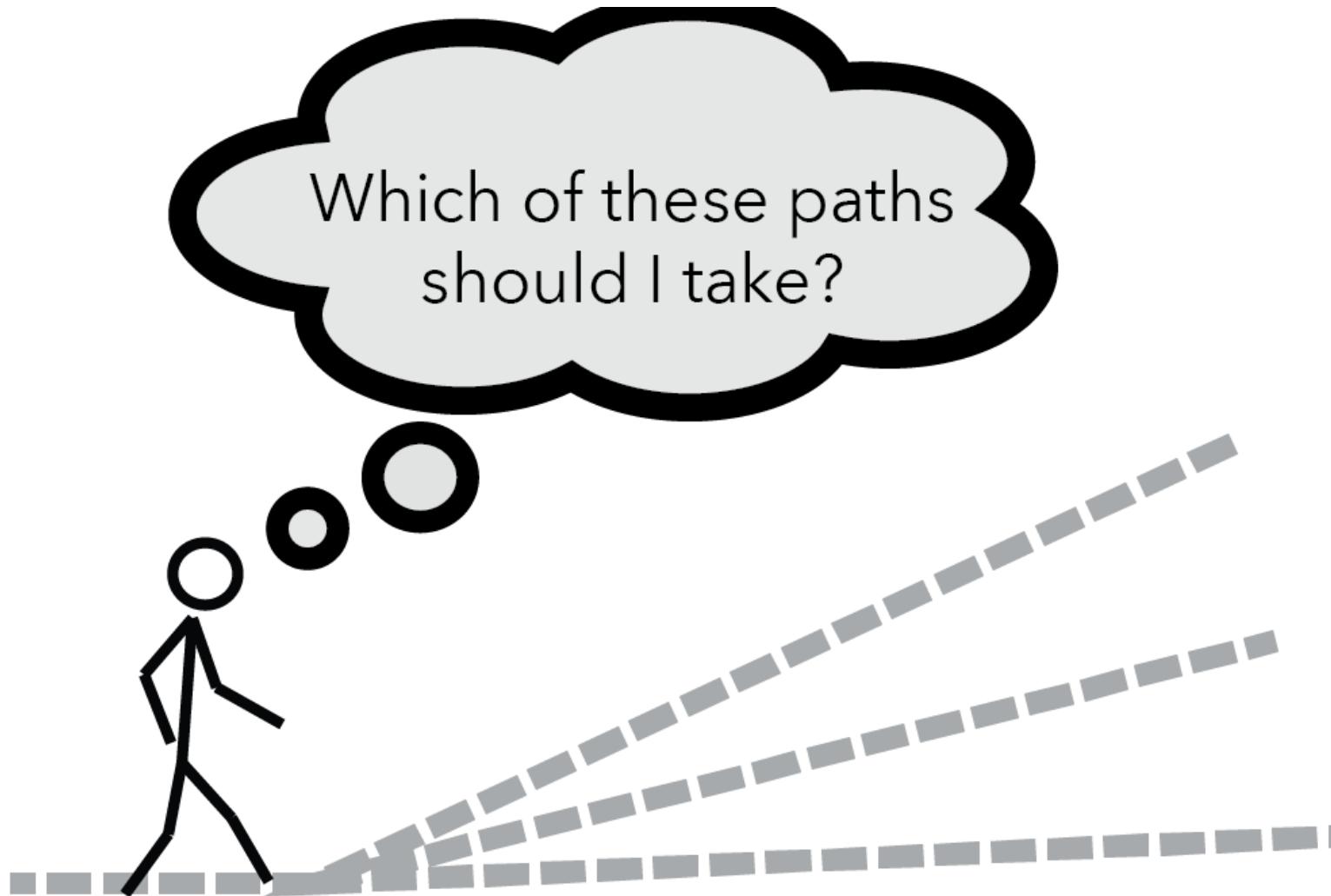
Elizabeth Tipton

Jessica Hullman

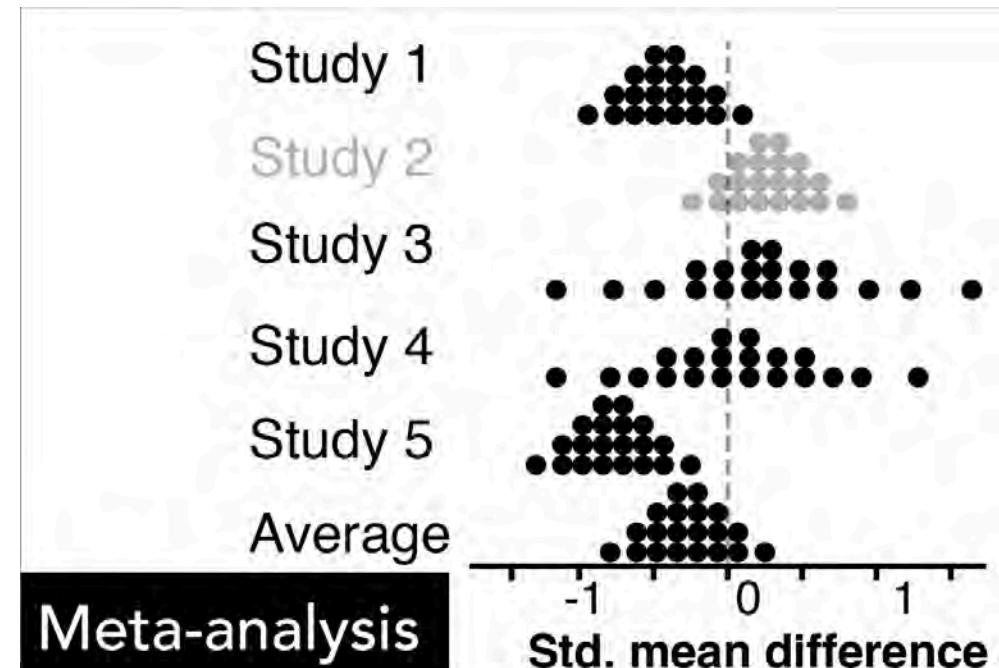
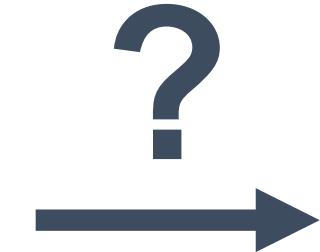


# **Epistemic uncertainty and evidence aggregation**

# Science is full of decision points



# Scientific literature is messy



# Evidence aggregation

## Systematic review

- 
- 💡 Defining a question
  - 🔍 Querying literature
  - 📖 Coding articles

# Evidence aggregation

## Systematic review

- 💡 Defining a question
- 🔍 Querying literature
- 📖 Coding articles

## Meta-analysis

- ➡ Collating study results
- ➡ Statistical inference

# Scientific literature is messy

JAMDA 14 (2013) 661–667  
Journal homepage: [www.jamda.com](http://www.jamda.com)

**Original Study**  
**The Psychosocial Effects of a Companion Robot: A Randomized Controlled Trial**  
Hayley Robinson MSc<sup>a</sup>, Bruce MacDonald PhD<sup>b</sup>, Ngaire Kerse PhD<sup>c</sup>, Elizabeth Broadbent PhD<sup>a,\*</sup>

<sup>a</sup> Department of Psychological Medicine, The University of Auckland, Auckland, New Zealand  
<sup>b</sup> Department of Electrical and Computer Engineering, The University of Auckland, Auckland, New Zealand  
<sup>c</sup> Department of General Practice and Primary Health Care, The University of Auckland, Auckland, New Zealand

**Keywords:** robots, Pano, loneliness, depression, quality of life, human-robot interaction

**Abstract**  
Objectives: To investigate the psychosocial effects of the companion robot, Pano, in a rest home/hospital setting for comparison to a control group.  
Design: Randomized controlled trial. Residents were randomized to the robot intervention group or a control group that attended normal activities instead of Pano sessions. Sessions took place twice a week for an hour over 12 weeks. Over the trial period, observations were conducted of residents' social behavior when interacting as a group with the robot. As a comparison, observations were also conducted of all the interactions during general activities when the resident dog was or was not present.  
Setting: A residential care facility in Auckland, New Zealand.  
Participants: Forty residents in a rest home care.  
Measurements: Residents completed a baseline measure assessing cognitive status, loneliness, depression, and quality of life. At follow-up, residents completed a questionnaire assessing loneliness, depression, and quality of life. During observations, behavior was noted and collated for instances of talking and the dog/bot.  
Results: In comparison with the control group, residents who interacted with the robot had significant decreases in loneliness over the period of the trial. Both the resident dog and the robot made an impact on the social environment in comparison to when neither was present. Residents talked to and interacted the robot more frequently than they did the residents dog. A greater proportion of residents had discussions about the robot in comparison with the resident dog and conversation about the robot occurred more.  
Conclusion: Pano is a positive addition to this environment and has benefits for older people in nursing home care. Pano may be able to address some of the unmet needs of older people that a resident animal may not, particularly relating to loneliness.

Copyright © 2013 · American Medical Directors Association, Inc.

The growing aging population is a major concern for the future.<sup>1</sup> An increasing number of older people will require formal long term care as their health deteriorates and they cannot source as much human care and support in their community.<sup>2</sup> Feeding and social connection that previously gave their life meaning. Even when older people have become used to their new living environment, often the feeling of loneliness and isolation does not abate over time as they find it difficult to form new relationships with the people around them.<sup>3</sup> Research has found that there are negative effects on health for older people after entering formal care. Some early studies have reported that there is a high mortality rate among the aged due to institutionalization,<sup>4,5</sup> whereas other research has found that moving frail elderly from one setting to another results in mental and physical deterioration.<sup>6,7</sup>

Many nursing homes now incorporate animal visitations and interactions into care models. Animals help fulfill criteria aimed at promoting better quality of life by increasing social interactions, decreasing loneliness, countering boredom, and helping foster

No conflict of interest. Australian New Zealand Clinical Trials Registry Trial Number 12120100409111.  
<sup>a</sup> Address correspondence to: Elizabeth Broadbent, PhD, University of Auckland, Private Bag 92019, Auckland, New Zealand.  
<sup>b</sup> E-mail address: [ebroadbent@auckland.ac.nz](mailto:ebroadbent@auckland.ac.nz) (E. Broadbent).

1525-8610/\$ - see front matter Copyright © 2013 · American Medical Directors Association, Inc.  
<https://doi.org/10.1016/j.jamda.2013.06.007>

© Med Sci Monit, 2012; 18(9): CR550-557  
PMID: 22936190

**Effect of a human-type communication robot on cognitive function in elderly women living alone**

Masaaki Tanaka<sup>1</sup><sup>✉</sup>, Akira Ishii<sup>1</sup><sup>✉</sup>, Emi Yamamoto<sup>1</sup><sup>✉</sup>, Hiroki Ogikubo<sup>1</sup><sup>✉</sup>, Masatsugu Okazaki<sup>2</sup><sup>✉</sup>, Kazuro Kamimura<sup>2</sup><sup>✉</sup>, Yasuharu Konishi<sup>2</sup><sup>✉</sup>, Shigeru Emoto<sup>3</sup><sup>✉</sup>, Yasuyoshi Watanabe<sup>1</sup><sup>✉</sup>

<sup>1</sup> Department of Physiology, Osaka City University Graduate School of Medicine, Abeno-ku, Osaka, Japan  
<sup>2</sup> RIP Co., Ltd., Chuo-ku, Osaka, Japan  
<sup>3</sup> ROBOLUTION Co., Ltd., Takasago, Hyogo, Japan  
<sup>4</sup> Center for Molecular Imaging Sciences, RIKEN, Chuo-ku, Hyogo, Japan

**Source of support:** Departmental sources.

**Summary**  
Considering the high prevalence of dementia, it would be of great value to develop effective tools to improve cognitive function. We examined the effects of a humanoid communication robot on cognitive function in elderly women living alone.

**Background:**  
In this study, 34 healthy elderly female volunteers living alone were randomised to living with either a communication robot or a control robot at home for 8 weeks. The shape, voice, and motion features of the communication robot resemble those of a 3-year-old boy, while the control robot was not designed to talk or move. Before living with the robot and 4 and 8 weeks after living with the robot, experiments were conducted to evaluate a variety of cognitive functions as well as saliva cortisol, sleep, and subjective fatigue, motivation, and healing.

**Material/Methods:**  
The Mini-Mental State Examination score, judgement, and verbal memory functions were improved after living with the communication robot; these functions were not altered with the control robot. In addition, the saliva cortisol level was decreased, nocturnal sleeping hours tended to increase, and difficulty in maintaining sleep tended to decrease with the communication robot, although alterations were not shown with the control. The proportions of the participants in whom efforts on attenuation of fatigue, enhancement of motivation, and healing could be recognized were higher in the communication robot group relative to the control group.

**Results:**  
This study demonstrates that living with a human-type communication robot may be effective for improving cognitive functions in elderly women living alone.

**Conclusions:**  
This study demonstrates that living with a human-type communication robot may be effective for improving cognitive functions in elderly women living alone.

**Key words:** cognitive function • elderly • women • human-type communication robot • living alone

**Full-text PDF:** <http://www.medsciemonit.com/fulltext.php?CID=883350>

**Word count:** 3620  
**Tables:** 3  
**Figures:** 2  
**References:** 48

**Author's address:** Masaaki Tanaka, Department of Physiology, Osaka City University Graduate School of Medicine, 3-4-3 Ashimachi, Abeno-ku, Osaka City, Osaka 545-8585, Japan, e-mail: [masa@med.osaka-u.ac.jp](mailto:masa@med.osaka-u.ac.jp)

CR550  
© 2012 Evid Based Clin Med • EBM (ISSN 1619-6879) • Vol 13 No 9 • MEDSCI (Clinical Medicine & Clinical Abstracts) • ISSN 1619-6879

**Robots in Older People's Homes to Improve Medication Adherence and Quality of Life: A Randomised Cross-Over Trial**

Elizabeth Broadbent, Kathy Peri, Ngaire Kerse, Chandimal Jayawardena, Iffan Kuo, Chandan Datta, and Bruce MacDonald  
The University of Auckland, Auckland, New Zealand  
[e.broadbent,k.peri,n.kerse,iku005,b.macdonald\)@auckland.ac.nz](mailto:(e.broadbent,k.peri,n.kerse,iku005,b.macdonald)@auckland.ac.nz), [cjayawardena@unitec.ac.nz](mailto:cjayawardena@unitec.ac.nz), [work.chandan@gmail.com](mailto:work.chandan@gmail.com)

**Abstract.** Healthcare robots are being developed to help older people maintain independence. This randomised cross-over trial aimed to investigate whether healthcare robots were acceptable and feasible and whether the robots could impact quality of life, depression and medication adherence. 29 older adults living in independent units within a retirement village were given robots in their homes for 6 weeks and had a non-robot 6-week control period, in a randomised order. The robots reminded people to take medication, provided memory games, entertainment, skype calls, and blood pressure measurement. The robots were found to be acceptable and feasible, and many participants described them as useful and as friends although not all comments were positive. There were relatively few problems with robot functions. The participants' perceptions of the robots' agency reduced over time. The robots had no significant impact on adherence, depression or quality of life. While the robots were feasible and acceptable, improvements in their reliability and functionality may increase their efficacy.

**Keywords:** robots, quality of life, medication, adherence, blood pressure, companion, acceptance.

## 1 Introduction

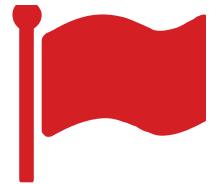
### 1.1 Eldercare Robots

Research teams across the world are developing robots that can provide services to older people to help them cope with age-related declines in physical health and cognitive abilities [1–3]. These robots include companion type robots, such as Pano, that are designed to provide companionship and reduce agitation in patients with dementia [4]. Other robots have been designed to help people with more practical tasks, such as physical assistance [5], health-care related tasks [6] and rehabilitation [7,8].

User trials of such robots to date have often been lab-based, observational, and used wizard of oz scenarios [1]. Few studies have been conducted in real-world settings and even fewer have been randomised controlled trials. Results to date have

M. Beetz et al. (Eds.): ICSR 2014, LNBI 8755, pp. 64–73, 2014.  
© Springer International Publishing Switzerland 2014

# Things that make meta-analysis hard



**Risk of bias**



**Measurement consistency**



**Applicability to target context**

**Sources of epistemic uncertainty**



# **MetaExplorer**

# MetaExplorer

## Scoping view



# MetaExplorer

## Scoping view



# MetaExplorer

## Review management

What is the impact of social robots on depression in older adults?



Upload Paper

Triage

Meta-Analyze

<input type="checkbox"/> Study		Review Status	Include
<input type="checkbox"/> Broadbent-2014.pdf	Review	Completed	<span>Yes</span> <span>No</span>
<input type="checkbox"/> Jøranson-2015.pdf	Review	Completed	<span>Yes</span> <span>No</span>
<input type="checkbox"/> Liang-2017.pdf	Review	Completed	<span>Yes</span> <span>No</span>
<input type="checkbox"/> Moyle-2013.pdf	Review	Completed	<span>Yes</span> <span>No</span>
<input type="checkbox"/> Petersen-2016.pdf	Review	Completed	<span>Yes</span> <span>No</span>
<input type="checkbox"/> Pu-2019-Social robots for older adults.pdf	Review	Not Started	<span>Yes</span> <span>No</span>

# MetaExplorer

## Evidence extraction



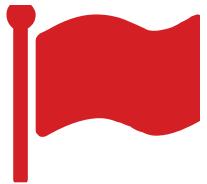
# MetaExplorer

## Evidence extraction



# MetaExplorer

## Triage view



### Risk of bias

> Flag the study result



### Measurement consistency

> Meta-analyze separately



### Applicability to target context

> Show, but don't meta-analyze

Sources of  
epistemic  
uncertainty

# MetaExplorer

## Triage view



# MetaExplorer

## Exploration vs Triage

### Risks of bias

Non-random assignment

Exclusion/attrition

Uncontrolled covariates

### Measurement issues

Unusual control condition

Non-validated scale

Cluster randomization



### Study group 1

Yes

No

Yes

No

Yes

No

### Study group 2

Yes

No

Yes

No

Yes

No

### Less applicable studies

Yes

No

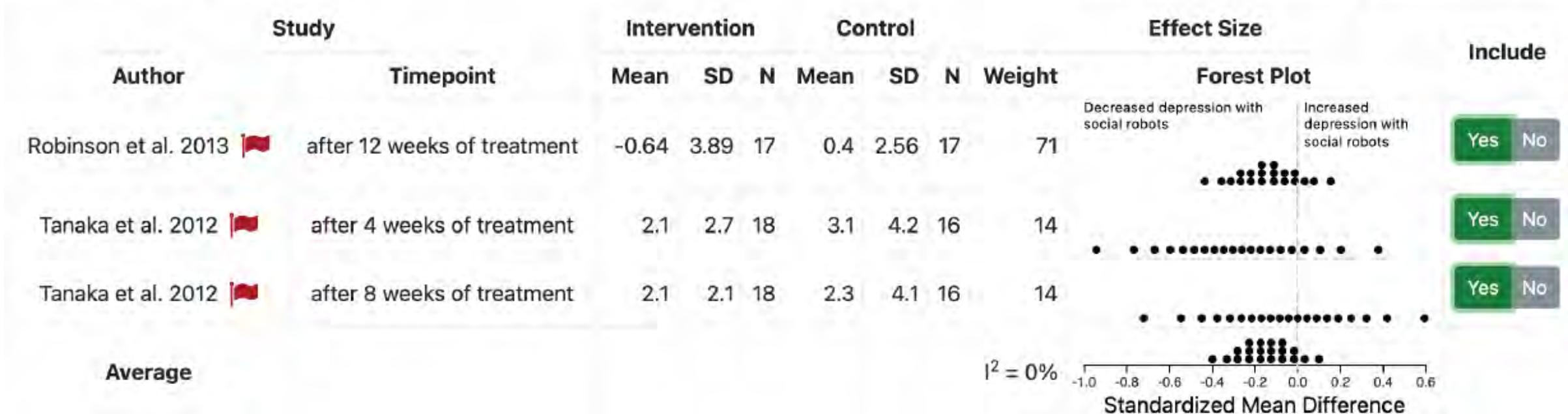
# MetaExplorer

## Visualization & meta-analysis

Between subjects studies

Switch to Original Units

Sort by Effect Size



# MetaExplorer

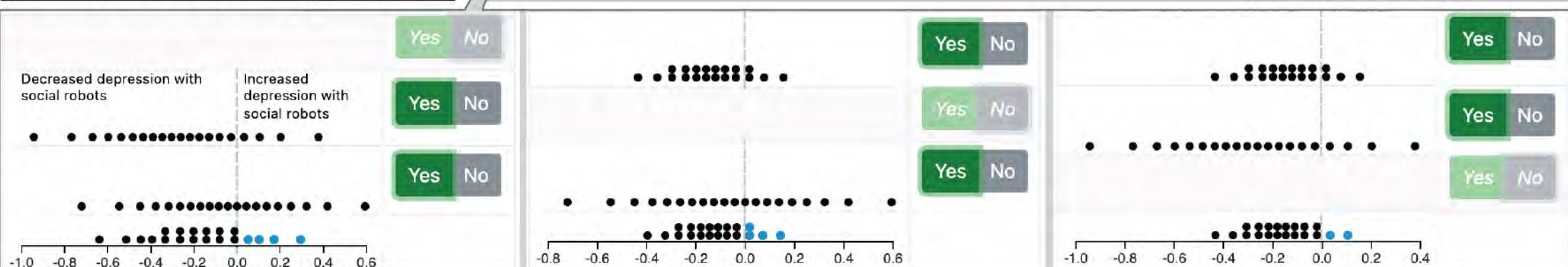
## Visualization & meta-analysis

Note: Study my have failed to isolate intervention effect. Not enough info about participants after exclusions.

Note: Study my have failed to control for baseline depression.

Note: Study my have failed to control for baseline depression.

### Risk of bias flags



### Sensitivity analysis

hypothetical replications showing increased depression with social robots

# MetaExplorer

## Evaluation

Experiments: ground truth is unknown

Case studies: require a huge commitment

Guided tour: hear from experienced meta-analysts

# MetaExplorer

## Evaluation

### Interface as a partner in analysis

*“I would model this tool to be a grouchy reviewer that constantly convincing me not to publish the study because I don’t have a corpus that is good enough, or I don’t have enough certainty.” (P09).*

# MetaExplorer

## Evaluation

### Interface as a partner in analysis

*“Now that I’ve seen this, I really think that needs to be an integral part of a meta-analysis. I have to admit that in meta-analyses I’ve been involved in, these conversations didn’t come up that much. I don’t remember having deep, long conversations about how studies contribute to making policy decisions for particular situations in a particular context.” (P12).*

# MetaExplorer

## Evaluation

Interface as a partner in analysis

### Standardization vs customization

*“I typically think about [epistemic uncertainty] more manually, less systematically. It comes up all the time, but the tool allows you to have a very strict, very formal way of dealing with it.”*  
*(P02).*

# MetaExplorer

## Evaluation

Interface as a partner in analysis

### Standardization vs customization

*“Would you make this more flexible for people who are in engineering or ecology and evolution? Because our experiments or studies are very much different than social psychology, like a lot of ecology and evolution is observational.” (P05).*

# **Retrospective**

# Retrospective

## Interviews with 11 scientists



**4** professors and **1** postdoc @ UW Medical Center  
Healthcare economics, sleep & health, STEM education



**2** PhDs @ Seattle Veterans Affairs Medical Center  
Treatments for PTSD and SUD



**4** scientists @ Naval Air Warfare Center Training Systems Division  
Trainings for military personnel

# Retrospective

Pain points in current practice

## Exploration or post-hoc inference

*“Through those discussions that we have, we’ll have suggestions for different types of analysis we can conduct that might split the hair a little bit differently and give us additional information that we can then decide, ‘Okay, what is the best way to report this now that we’ve looked at it both of these ways?” (P6)*

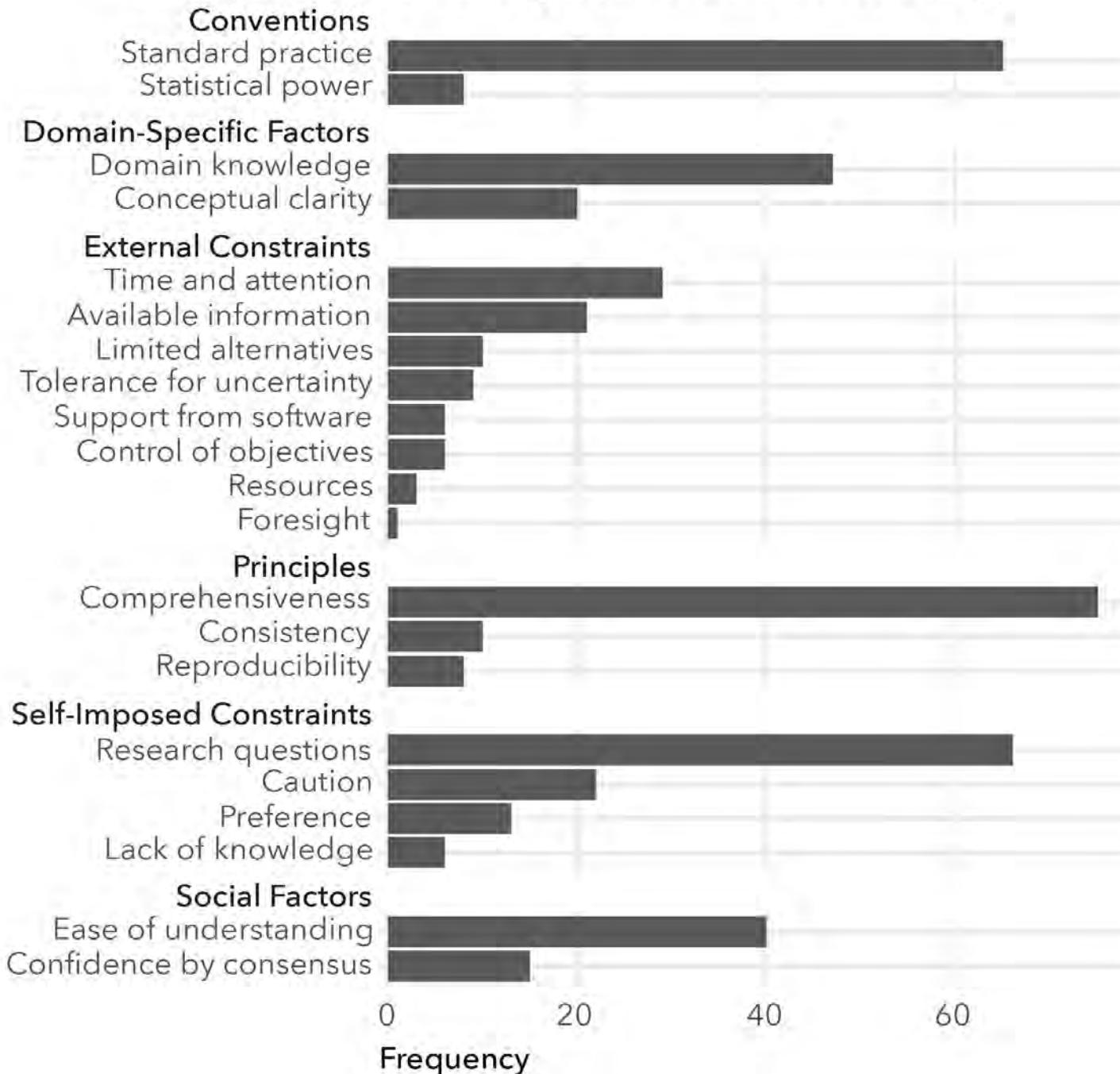
# **Retrospective**

Pain points in current practice

Exploration or post-hoc inference

**Decision rationales documented inconsistently**

# Motivations for Analytical Decision-Making



# Retrospective

Pain points in current practice

Exploration or post-hoc inference

Decision rationales documented inconsistently

Communicating uncertainty

*“They do care about the fidelity of the data, they just don’t want a chart on it.” (P11)*

# **Challenges**

# Challenges

Communicating uncertainty

Collaboration

Workflow customization

Resolving interacting biases

Sophisticated model specifications

Shades of gray in applicability

Interoperability with other tools

# Thanks!

## Discussion

What challenges are most important in your work?

How do you want tools to integrate into your workflow?

Alex Kale



✉️ [kalea@uchicago.edu](mailto:kalea@uchicago.edu)

