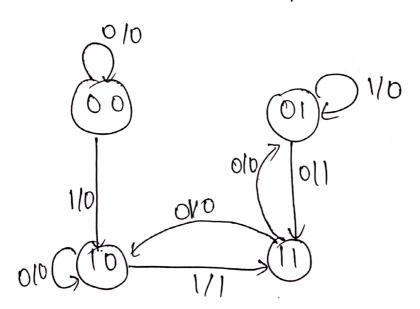


As the output depends only on the present state hence more state machine.

2 For the given circult

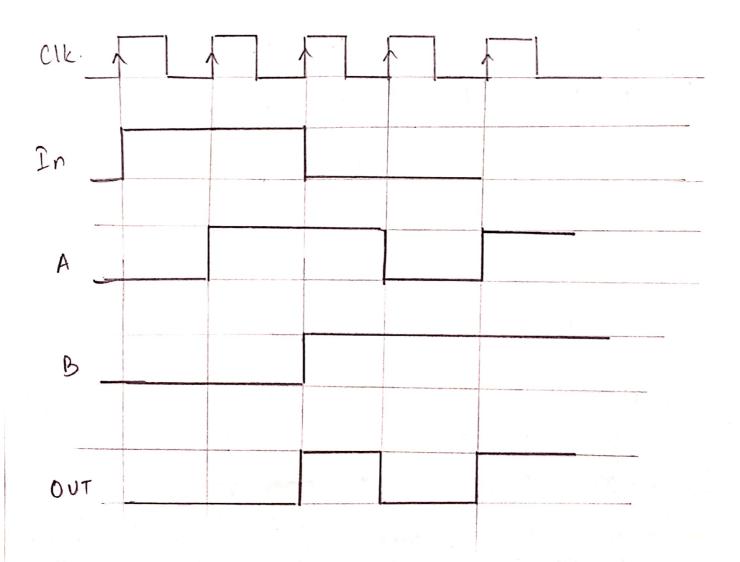
JA = XB+ XB = 7	AB.
KA = XB	* A
JB- XA	
KB = XA.	
Out = AB	

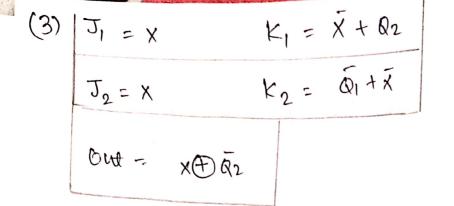
Д	1.0		X(PB)	XB KA	XA	XA KB	A	BT	out.
******	B	X	JA	-	Ó	0	0		0
0	0	0	0	0	-	0		D	0
0	0	1	1	O	0	V		•	
\Diamond	1	0	1	1	0	D			m
0		1	D	0	0	0	0	1	0
1	0	0	O	O	0	0		0	O
1	0	1	1	0		1	l	1	
(l	0	1	(0	0	0		0
1	1	1	O	D		1		D	0
				Stalt	rep	risent	ation		



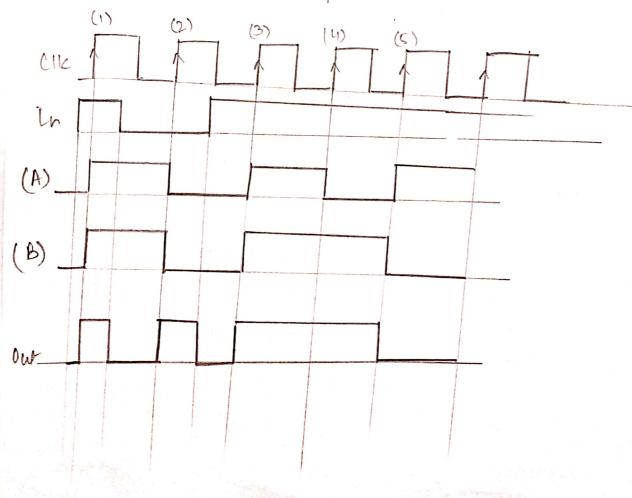
State graph

1	1			XDB	XB	AX	X Pi				
/	A	B	X	74	KA	JB	KB	A	B	Out =	(AA)
	0	0	D	0	0	0	0	0	0	D	
	0	0	١	l	O	Ø	O		0	D	
		0	1	1	D		l	l		61	
	1	1	0	1		0	O	0	١	0	
	0		0	1		O	0		1	1	





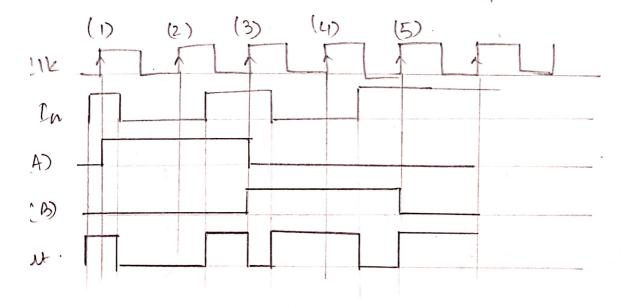
A	8	In	JA	KA	JB	KB	A	B	out.
0	0	1	1	0	1	0		1	
		D	O	1	0	1	0	0	
0	0		1	0	1	1		1	
	1	1	1		1	D	0	1	
0		1	1	1	1	1	1	0	
1							1	U	

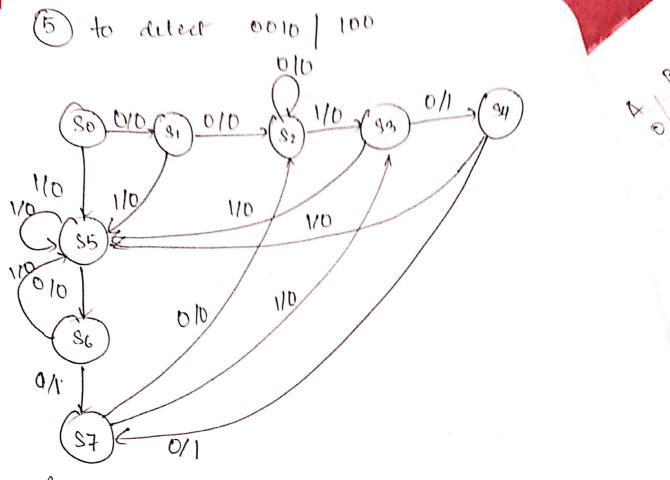


1	$k_1 = k_2 = X$
/	J1 = Q2 X
	out = XP Q2

	and committee of the committee of	
\mathcal{I}_2	-	XQI
	-	Control of the Contro

A	B	In	J_{A}	KN	JB	KB	At	Bt	Owt
0	b	1	1	1	0	1	1	0	
1	D	0	0	O	D	0	(D	
1	0	1	l	١	•	1	0	1	
0)	0	O	0	0	0	\bigcirc)	
0	l	1	D	1	0		0	0	





Present State	Next	Sfatt	Ou	tput
20		X=1	X=0	X=1
	31	\$5	0	0
71	S2	\$5	0	D
S_2	8 2	Sz	0	D
83	Sy	\$5		
<u>S</u> 4				0
	SA S2	\$5	1	0
Ss	S/6 S4	\$5	O	
36	37	85		O
The second secon				-6-
\$7	Sz	53	0	

From here S2 = S7 and S6 = S4

0

.. So and Sq redundant states.

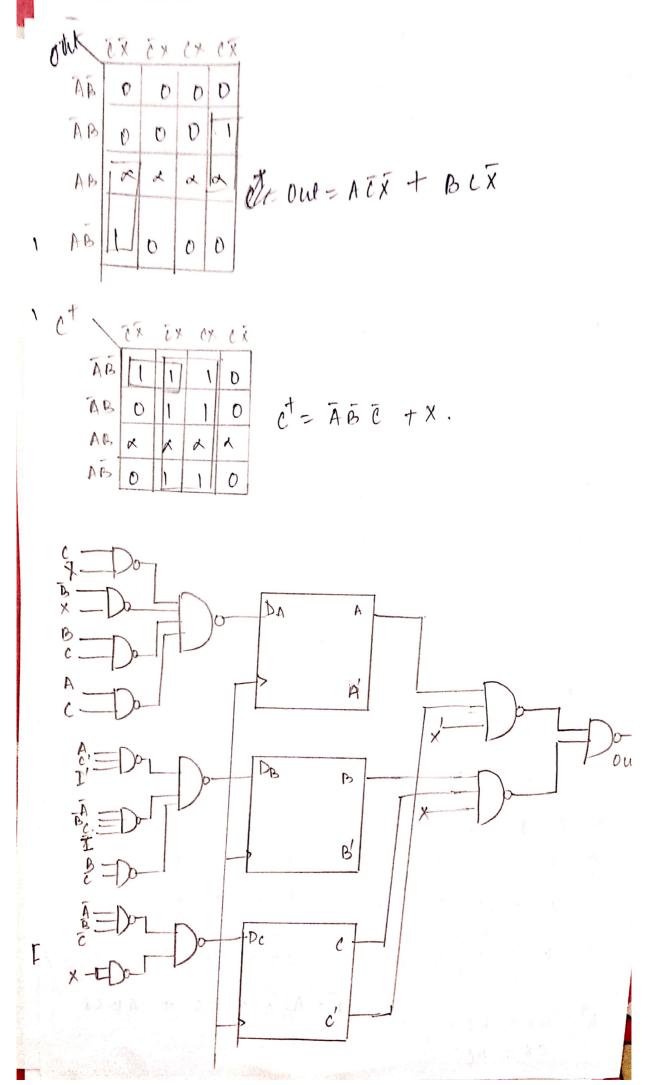
Sto	ta	table	
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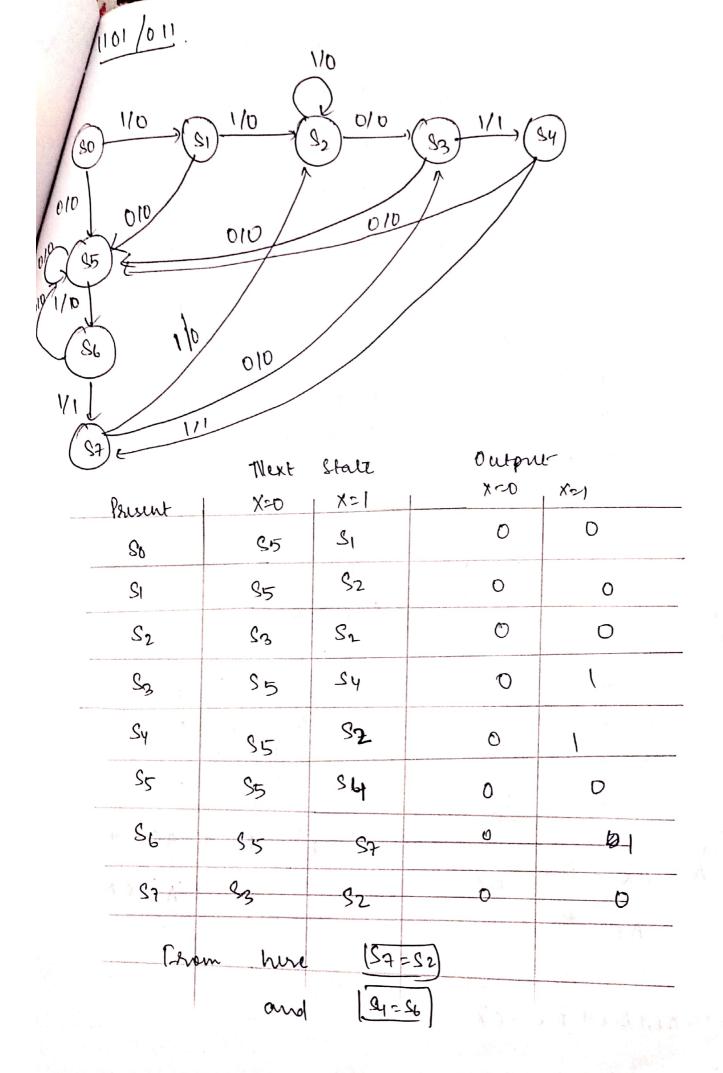
	A	B	C	jn	A	B+	CT	Out
	0	0	0	D	0	0	Ø 1	0
	0	D	0	1	1	0		0
	0	0	1	0	O	1	0	0
	_0	٥	.		l	0	1	O
-	Q	1	0	0	0	1	U	0
	0	1	đ)	0	l)	0
	0	١		0	1	0	D	1
	0	Ţ	((D	1	0
	İ	D	D	0	0	l	D	1
	\	D	6	1	1	٥		O
	1	0	1	0	1	0	D	0
		0	1	1	l	0		0
				1	tB	,		

A							
\	ēx	T	X	CX	L	CX	
AB	0					0	
ĀB	_ 0		0	Ī			
AB	<i>></i>	3	Χ.	2	+	X	
AB	0		1			را دول	The state of the s
		- 1					

0				
\	ēΣ	ēΧ	CX	CX
ĀB	0	0	0	1
ĀB	1	1	D	D
AB	0	a	d	×
AB		O	D	D

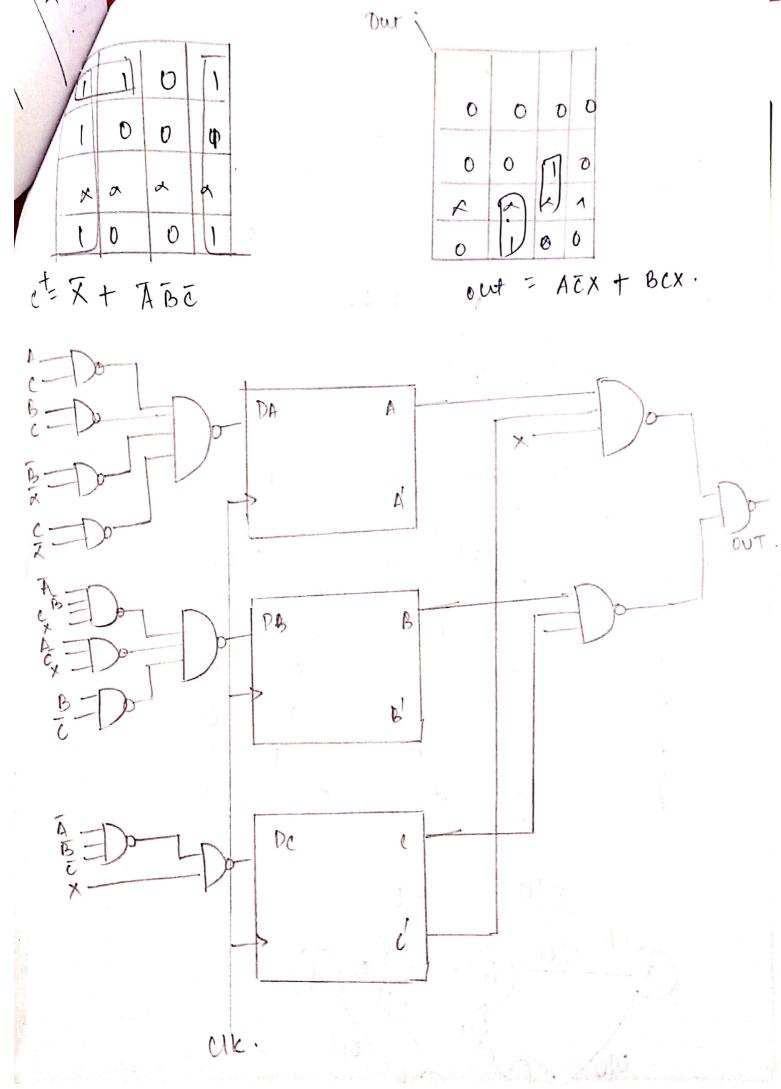
B= ACX + BC + ABCX



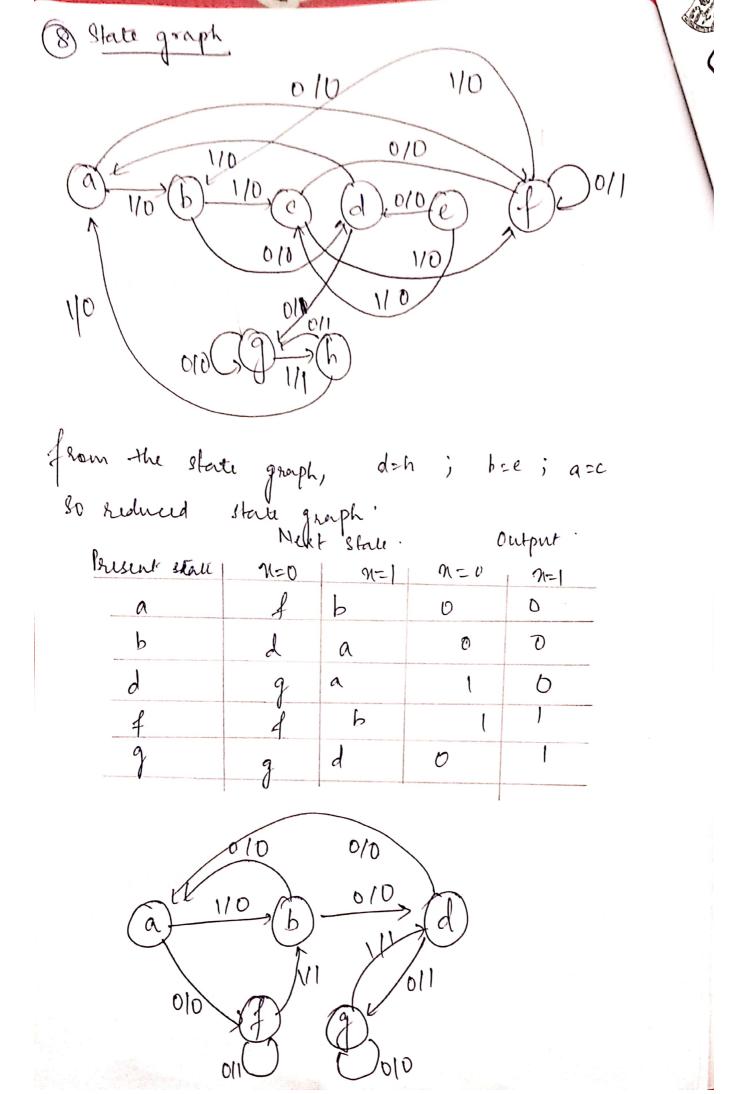


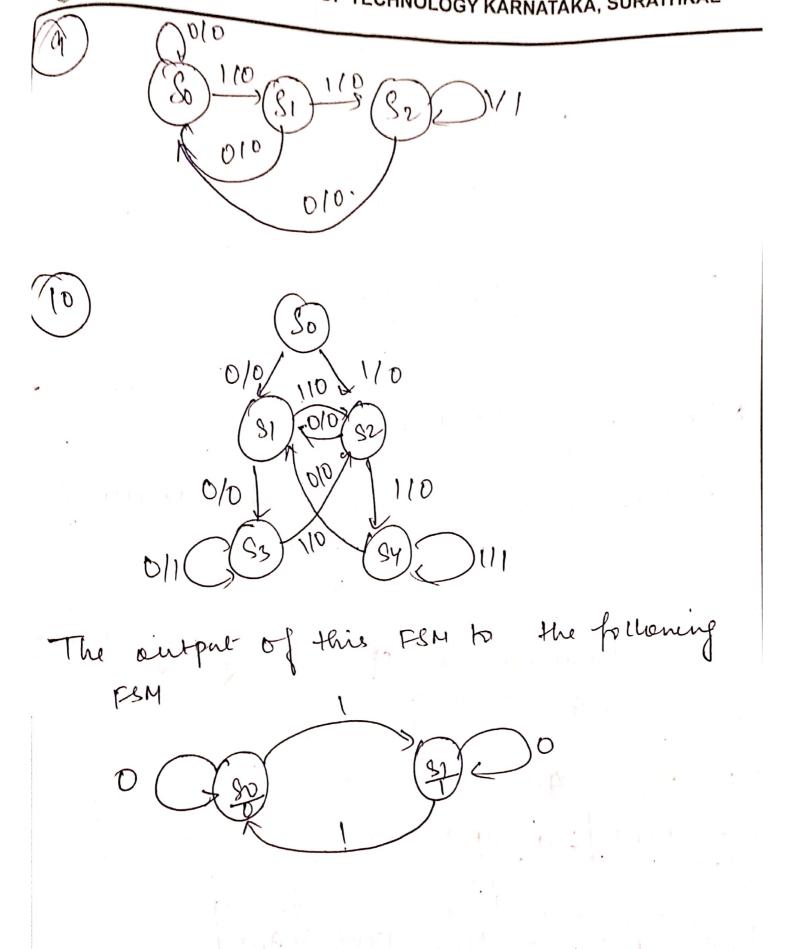
-	A	B	C	In	A	1B	+ (ct, Output			
	•	0	0	0	(0		0			
	O	0	0		0	0		0			
	0	0		0	•	0)	0			
	0	0	1		0	1	O	D			
	Q		O	0	0	1	1	0			
	0		0		0	1	0,,	0			
	0 1 1										
		0	0	0	1001						
	1	5		0 1 0 1							
	101010										
A [†] (000											
AB y O O TI											
AB O							[] D O				
AB	0	1				0 1	0	Ō			
A = c	えーる	x +	3 e		Ь	† = k		ACX +			
	e +	·	- T					ĀBCX.			

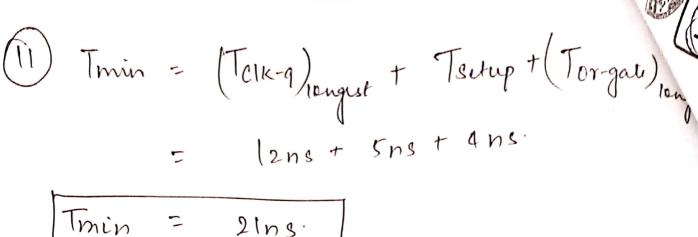
= AC+BC+BX+CX



Scanned by CamScanner





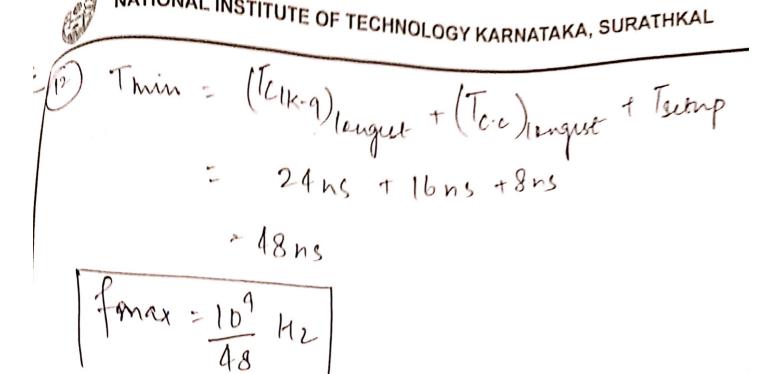


=)
$$f_{\text{max}} = \frac{10^9}{21} \text{ Hz}$$

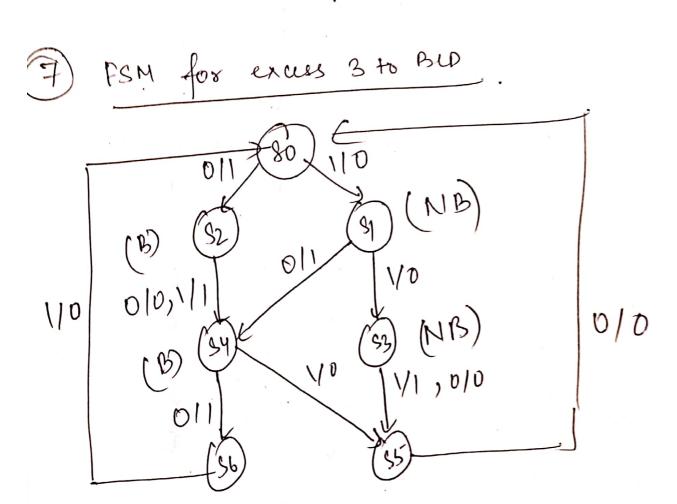
Minimum delay = (6+1) rs.

the minimum dulay should bame positive stack for hold time = Ins-3ns = 4ns.

- Minimum time after rising edge at which the input can change



Carellest can be changed at 12ns. latest can be changed at . 38ns.



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) I			\$ 2		31			0
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S	3				S5	55		O	1
-	Ч				56		55		O
	5				02	_		0	×
S	6					80		X	0
A 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	B00001111000011	C 0 0 1 1 0 0 1 1 0 0 0 1 1 0 0 0	D 1 0 1 0 1 0 1 0 1	AT 10010111100000	1001000 0000 0000 0000	10101010101010101010101010101010101010	out.		
	personal services	out I have been	The state of the s	Respondent of			the of Special Section of the	Penasana de ma	

=) gine Q AB+ ACT + ABC B = Bcī + BCI C7 +B7 + BC ABT +ACT +BI DA A ABC B II Dc. C