Indian Institute of Technology Guwahati Mechanical Engineering Instructor: S. K. Dwivedy

Course No: ME 313

Course Name: Dynamics of Machinery



SI No	Roll No	Name	EMail	Project Title	
	150103080	Y BISHAL SINGHA	bishal.singha	Dynamic Analysis of any mechanical components in nuclear power plant with earthquake excitation	
	150103076	VIPUL KUMAR VIJAY	vipul.vijay		
Group 1	150103012	ARUN.V.KAMMATH	arun.kammath		
	150103082	MEGHDEEP JANA	meghdeep		
	150103032	SUHAS MASANA	suhas.masana	Dynamic analysis of gas turbines system	
	150103070	ROHAN AGRAWAL	rohan.2015		
Group 2 Group 3	130103036	ROHAN AGRAWAL	Tonan.2015		
	150103022	BISHAL RAJ GAYAN	b.gayan	Study of balancing of engines of 3 different car models	
	150103078	VISHAL BANSKUWA	v.banskuwa		
	150103040	KATRAVATH VIGNESH	v.katravath		
Group 4	150103020	BHASWATI GOHAIN BARUA	b.bhaswati	Dynamic analysis of 2 link robotic manipulator	
	150103084	ABHINANDAN GOGOI	g.abhinandan		
Group 5	150103030	DIWAKAR KUMAR	k.diwakar	Vibration Analysis of Hybrid Engine	
	150103008	AMAN ANAND	aman.anand		
	150103052	PENMETSA GOPAL KRISHNA	penmetsa		
Group 6	150103006	ALANKAR JHA	j.alankar	Dynamic analysis of general coach of railway bogie	
	150103038	JATIN SONI	s.jatin		
	150103036	JASBIR SARMAL	jasbir		
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Group 7	150103026	DESHMUKH SANDESH NITIN		Domanda analysis of the video sitting an amount of Treets	
	150103010	AMARJITH VISHNU	amarjith	Dynamic analysis of the rider sitting on a moving Tractor	
	150103028	DHONDE SHUBHAM PRAKA	dhonde		

150103068	SOMNATH VATS	v.somnath		
			Dynamic analysis of crane system using ADAMS	
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10010000				
150103002	ABHIJEET	abhijeet.2015	Dynamic analysis of grass cutter (Measure to reduce noise)	
150103014				
150103086	ARNOB DUTTA	arnob.dutta		
150103034	GURUDAYAL	gurudayal	Static & Dynamic force analysis of exoskeleton system	
150103032	GAURAV AGARWAL	gaurav.agarwal		
150103048	NARNAWARE AJINKYA PRA	narnaware		
150103004	ABHISHEK SARATHE	a.sarathe	Gyroscopic action of a system using modified Euler Equation	
150103074	UTTAMKUMARSINGH MANO	u.manojsingh		
150103050	PAPPALA DINESH CHANDRA	c.pappala		
150103042	KUSH GUPTA	kush.gupta		
150103046	MUKESH KHOD	mukesh.khod	Dynamic analysis of a humanoid robot	
		Г		
140103054	PRAVIN KUMAR	pravin.2014	any problem of your choice	
	150103018 150103062 150103002 150103014 150103034 150103032 150103048 150103074 150103050 150103042 150103046	150103018 BEJAWADA THARUNKUMAR 150103062 SATYAM SAURABH 150103002 ABHIJEET 150103014 ASHMIL C IBRAHIM 150103086 ARNOB DUTTA 150103034 GURUDAYAL 150103032 GAURAV AGARWAL 150103048 NARNAWARE AJINKYA PRA 150103004 ABHISHEK SARATHE 150103074 UTTAMKUMARSINGH MANO 150103050 PAPPALA DINESH CHANDRA 150103042 KUSH GUPTA 150103046 MUKESH KHOD	150103018 BEJAWADA THARUNKUMAR bejawada 150103062 SATYAM SAURABH satyam.saurabh 150103002 ABHIJEET abhijeet.2015 150103014 ASHMIL C IBRAHIM ashmil 150103086 ARNOB DUTTA arnob.dutta 150103034 GURUDAYAL gurudayal 150103032 GAURAV AGARWAL gaurav.agarwal 150103048 NARNAWARE AJINKYA PRA narnaware 150103004 ABHISHEK SARATHE a.sarathe 150103074 UTTAMKUMARSINGH MANO u.manojsingh 150103050 PAPPALA DINESH CHANDR/c.pappala 150103042 KUSH GUPTA kush.gupta 150103046 MUKESH KHOD mukesh.khod	

- 1. Read at least 3 to 4 related topics (may refer scopus or google).
- 2. Formulate the problem
- 3. Develop a simplified physical and mathematical model
- 4. Solve the problem either by developing a matlab program or using ADAMS OR ANSYS or any other software.
- 5. Write a brief report and prepare a ppt file for the same.
- 6. Each group will get 10 minutes for presentation and 5 minutes for question answer.

of presentation is on 18th November 2017 9 am-12 noon.

Date