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```
%CVision with Kinect
```

```
%% Initialise ROS
```

```
roshutdown;
```

```
roslaunch ('http://192.168.0.53:11311/');
```

```
load('objDetector.mat');
```

```
%% list nodes
```

```
roslaunch list
```

```
%% list topics
```

```
rostopic list
```

```
%% subscribe to topics
```

```
imSub = rossubscriber('/camera/rgb/image_raw');
```

```
pcSub = rossubscriber('/camera/depth/points');
```

```
dimSub = rossubscriber('/camera/depth/image_raw');
```

```
%% end of code
```