CS 5525

Solutions to Homework Assignment 4

Meghendra Singh

November 8, 2016

[15] 1**.**

(a) The estimated conditional probabilities are:

Cond. prob.	Value
P(A +)	3/5 = 0.6
P(B +)	1/5 = 0.2
P(C +)	4/5 = 0.8
P(A -)	2/5 = 0.4
P(B -)	2/5 = 0.4
P(C -)	5/5 = 1

(b) By Bayes theorem we have:

$$P(C_j|A_1, A_2, ..., A_n) = \frac{P(C_j) * P(A_1, A_2, ..., A_n|C_j)}{P(A_1, A_2, ..., A_n)}$$
(1)

and the Naïve (independence among attributes) assumption gives us:

$$P(A_1, A_2, ..., A_n | C_j) = P(A_1 | C_j) P(A_2 | C_j) ... P(A_n | C_j)$$
(2)

By (1) and (2) we have,

$$P(C_j|A_1, A_2, ..., A_n) = \frac{P(C_j) * P(A_1|C_j)P(A_2|C_j)...P(A_n|C_j)}{P(A_1, A_2, ..., A_n)}$$

After ignoring the constant denominator we can estimate the **posterior** probability for a class C_j as:

$$P(C_j|A_1, A_2, ..., A_n) = P(C_j) * P(A_1|C_j)P(A_2|C_j)...P(A_n|C_j)$$

Therefore,

$$\begin{split} P(+|A=0,B=1,C=0) &= P(A=0|+)P(B=1|+)P(C=0|+)P(+) \\ &= \frac{2}{5}*\frac{1}{5}*\frac{1}{5}*\frac{1}{2} \\ &= \frac{1}{125} = 0.008 \end{split}$$

And,

$$P(-|A = 0, B = 1, C = 0) = P(A = 0|-)P(B = 1|-)P(C = 0|-)P(-)$$

$$= \frac{3}{5} * \frac{2}{5} * 0 * \frac{1}{2}$$

$$= 0$$

Since, P(+|A=0,B=1,C=0) > P(-|A=0,B=1,C=0), the test sample will be labeled as '+'.

(c) M-estimate is given by: $P(A_i|C) = \frac{N_{ic} + m*p}{N_c + m}$, given m = 4 and p = 1/2 we get the following conditional probabilities:

Cond. prob.	Value
P(A +)	5/9 = 0.555
P(B +)	3/9 = 0.333
P(C +)	6/9 = 0.666
P(A -)	4/9 = 0.444
P(B -)	4/9 = 0.444
P(C -)	7/9 = 0.777

(d) The posterior probabilities for the two classes, given the test sample (A = 0, B = 1, C = 0) are as follows:

$$P(+|A=0,B=1,C=0) = P(A=0|+)P(B=1|+)P(C=0|+)P(+)$$

$$= \frac{4}{9} \times \frac{3}{9} \times \frac{3}{9} \times \frac{1}{2}$$

$$= \frac{18}{729} = 0.0246$$

$$\begin{split} P(-|A=0,B=1,C=0) &= P(A=0|-)P(B=1|-)P(C=0|-)P(-)\\ &= \frac{5}{9} \times \frac{4}{9} \times \frac{2}{9} \times \frac{1}{2}\\ &= \frac{20}{729} = 0.0274 \end{split}$$

Since, P(+|A=0,B=1,C=0) < P(-|A=0,B=1,C=0), the test sample will be labeled as '-'.

(e) In the first method, absence of a training sample can make the joint conditional probability zero. While the second method (using m-estimates) compensates for such cases and prevents the posterior probability expresion from becoming zero just becasue of one of the conditional probabilities was zero. (b) and (d) above are an example of such a case. Therefore, the second method (m-estimates) is better than the first method.

[15] **2**.

(a) The contingency tables for the six rules are as follows:

$\{b\} \to \{c\}$	c	\overline{c}			
b	3	4			
\overline{b}	2	1			
$Support = \frac{3}{10} = 0.3$					
$Confidence = \frac{3}{7} = 0.428$					

$\boxed{\{a\} \to \{d\}}$	d	\overline{d}			
a	4	1			
\overline{a}	5	0			
$Support = \frac{4}{10} = 0.4$					
$Confidence = \frac{4}{5} = 0.8$					

$\boxed{\{b\} \to \{d\}}$	d	\overline{d}			
b	6	1			
\overline{b}	3	0			
$Support = \frac{6}{10} = 0.6$					
$Confidence = \frac{6}{7} = 0.857$					

$\boxed{\{e\} \to \{c\}}$	c	\overline{c}			
e	2	4			
\overline{e}	3	1			
$Support = \frac{2}{10} = 0.2$					
$Confidence = \frac{2}{6} = 0.333$					

$\boxed{\{c\} \to \{a\}}$	a	\overline{a}			
c	2	3			
\overline{c}	3	2			
$Support = \frac{2}{10} = 0.2$					
$Confidence = \frac{2}{5} = 0.4$					

(b) Rules ranked in decreasing order according to support:

$$\{b\} \to \{d\} > \{a\} \to \{d\} > \{b\} \to \{c\} > \{e\} \to \{c\} \to \{a\}$$

Rules ranked in decreasing order according to confidence:

$$\{b\} \to \{d\} > \{a\} \to \{d\} > \{b\} \to \{c\} > \{c\} \to \{a\} > \{e\} \to \{c\}$$

[15] 3.

The following table gives the support, confidence and lift for the six rules, along with the respective ranks according to each measure (greater magnitude results in lower rank):

Rule	Support	Rank	Confidence	Rank	Lift	Rank
$bread \rightarrow milk$	0.32	1	0.4	4	1	2
$milk \rightarrow bread$	0.32	1	0.8	1	1	2
$coke \rightarrow pepsi$	0.08	2	0.167	6	0.42	3
$pepsi \rightarrow coke$	0.08	2	0.2	5	0.42	3
wine \rightarrow caviar	0.06	3	0.43	3	5.36	1
caviar \rightarrow wine	0.06	3	0.75	2	5.36	1

[10] 4.

The support and confidence for the three rules are as follows:

Rule 1:

$$\{(5 \leq A \leq 8), B=1\} \rightarrow \{C=1\}$$
 : Support = $\frac{2}{12} = 0.166$; Confidence = $\frac{2}{2} = 1$

Rule 2:

$$\{(A \text{ is odd}), B = 1\} \rightarrow \{C = 1\} : \text{Support} = \frac{2}{12} = 0.166 ; \text{Confidence} = \frac{2}{3} = 0.66$$

Rule 3:

$$\{A \text{ is even}\}, C=1\} \rightarrow \{B=1\}$$
: Support $=\frac{2}{12}=0.166$; Confidence $=\frac{2}{4}=0.5$

[15] 5.

Part I: The following table shows the Euclidean distance between each point and the three initial centroids $(A_1, B_1 \ and \ C_1)$ and the cluster assignment after the first iteration, A_1 is considered the centroid of the first cluster, B_1 the centroid of the second cluster and C_1 the centroid of the third cluster:

Euclidean distance	A_1	B_1	C_1	Cluster assignment
A_1	0	3.606	8.062	1
A_2	5	4.243	3.162	3
A_3	8.485	5	7.280	2
B_1	3.606	0	7.211	2
C_1	8.062	7.211	0	3
C_2	2.236	1.414	7.616	2

New centroids after the first iteration are: (2, 10), (5.67, 7) and (1.5, 3.5)

Part II: The final cluster assignments after k-means clustering are:

 $\{1,2,3,5\} \rightarrow \text{cluster 1 and } \{9\} \rightarrow \text{cluster 2}$

- (i) The final centroids are: 2.75 and 9 for clusters 1 and 2 respectively
- (ii) Cohesion or within clusters sum of squares is 8.75
- (iii) Separation or between clusters sum of square is 31.25

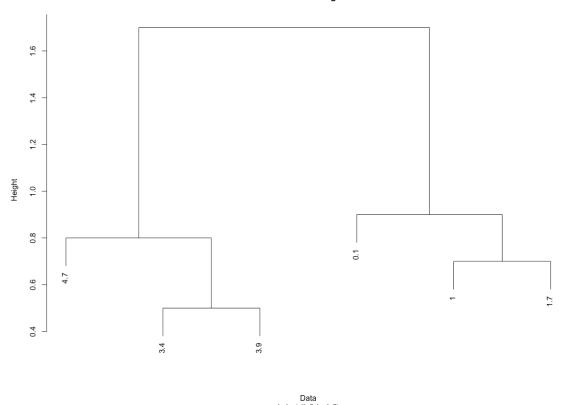
[20] 6.

(a) The initial proximity matrix is as follows:

	0.1	1	1.7	3.4	3.9	4.7
0.1	0	0.9	1.6	3.3	3.8	4.6
1	0.9	0	0.7	2.4	2.9	3.7
1.7	1.6	0.7	0	1.7	2.2	3.0
3.4	3.3	2.4	1.7	0	0.5	1.3
3.9	3.8	2.9	2.2	0.5	0	0.8
4.7	4.6	3.7	3.0	1.3	0.8	0

- (i) Cluster memberships obtained after single linkage, agglomerative, hierarchical clustering are: $\{0.1, 1, 1.7\} \rightarrow \text{cluster 1}$ and $\{3.4, 3.9, 4.7\} \rightarrow \text{cluster 2}$.
- (ii) The dendrogram is as follows:





(b) The initial proximity matrix computed for the four data points A: (0 2 0 0); B. (2 0 1 2); C: (2 1 0 2); D: (2 2 1 0), using the cosine similarity measure is as follows:

	A	В	C	D
A	1	0	0.33	0.66
В	0	1	0.88	0.55
\mathbf{C}	0.33	0.88	1	0.66
D	0.66	0.55	0.667	1

Upon single linkage hierarchical clustering we get the following proximity matrices after two successive merge operations:

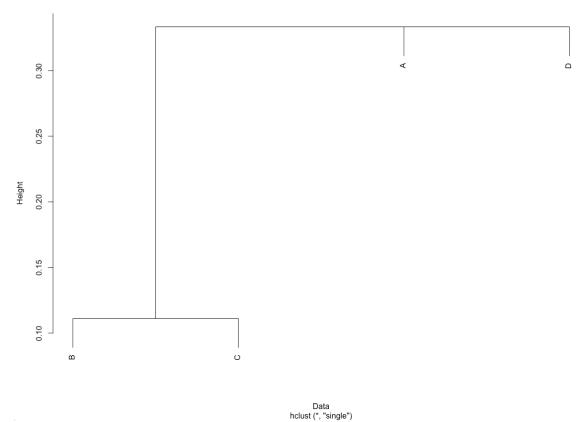
		A	BC	D
	\mathbf{A}	1	0.33	0.66
→ ·	\mathbf{BC}	0.33	1	0.66
	D	0.66	0.66	1

		\mathbf{AD}	BC
\rightarrow	\mathbf{AD}	1	0.66
	\mathbf{BC}	0.66	1

		A	BCD
or	\mathbf{A}	1	0.66
	BCD	0.66	1

There, are two merge operations are possible since we have ${\bf 0.66}$ as the maximum similarity in the proximity matrix between ${\bf A}$ and ${\bf D}$ as well as between ${\bf BC}$ and ${\bf D}$. The dendrogram for the first case is as follows:

Cluster Dendrogram



- (c) Following are the proximity matrices, there reductions on successive merge operations and the cluster dendrograms for the single and complete linkage hierarchical clustering:
- (i) Single linkage:

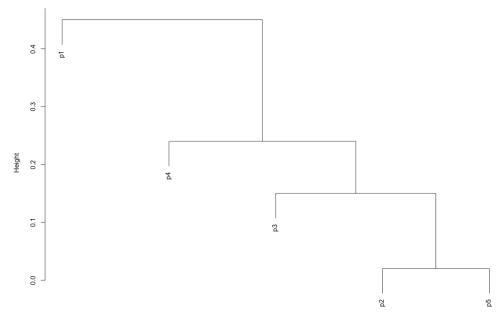
	p1	p2p5	р3	p4
p1	1	0.35	0.41	0.55
p2p5	0.35	1	0.85	0.76
p3	0.41	0.85	1	0.44
p4	0.55	0.76	0.44	1

		p1	p2p3p5	p4
	p1	1	0.41	0.55
→	p2p3p5	0.41	1	0.76
	p4	0.55	0.76	1

		p1	p2p3p4p5
\rightarrow	p1	1	0.55
	p2p3p4p5	0.55	1

The resultant cluster dendrogram is as follows:

Cluster Dendrogram



Data hclust (*, "single")

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(i) Complete linkage:

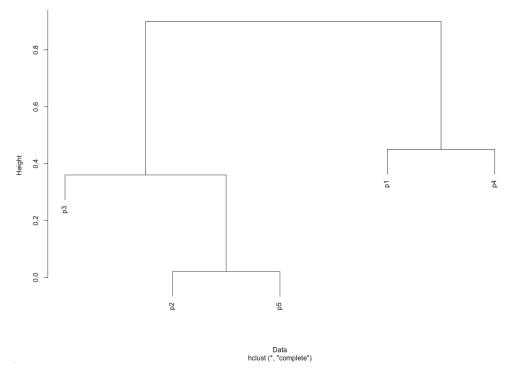
	p1	p2p5	p3	p4
p1	1	0.1	0.41	0.55
p2p5	0.1	1	0.64	0.47
p3	0.41	0.64	1	0.44
p4	0.55	0.47	0.44	1

		p1	p2p3p5	p4
	p1	1	0.1	0.55
\rightarrow	p2p3p5	0.1	1	0.44
	p4	0.55	0.44	1

		p1p4	p2p3p5
\rightarrow	p1p4	1	0.1
	p2p3p5	0.1	1

The resultant cluster dendrogram is as follows:

Cluster Dendrogram



[10] 7.

Upon applying DBSCAN with $\varepsilon=0.15$ and MinPts = 4 we get the following core, border and noise points:

Core points	Border points	Noise points
\mathbf{x} , \mathbf{t} , \mathbf{r} , \mathbf{q} , \mathbf{s} , \mathbf{a} , \mathbf{b} , \mathbf{c} , \mathbf{d} , \mathbf{e} , \mathbf{f} , \mathbf{g} , \mathbf{h} , \mathbf{i} , \mathbf{j} , \mathbf{k} and \mathbf{l}	w, v, y, z, u, p and m	n and o

The following figure shows the core points, border points and noise points in blue, green and red colors respectively:

