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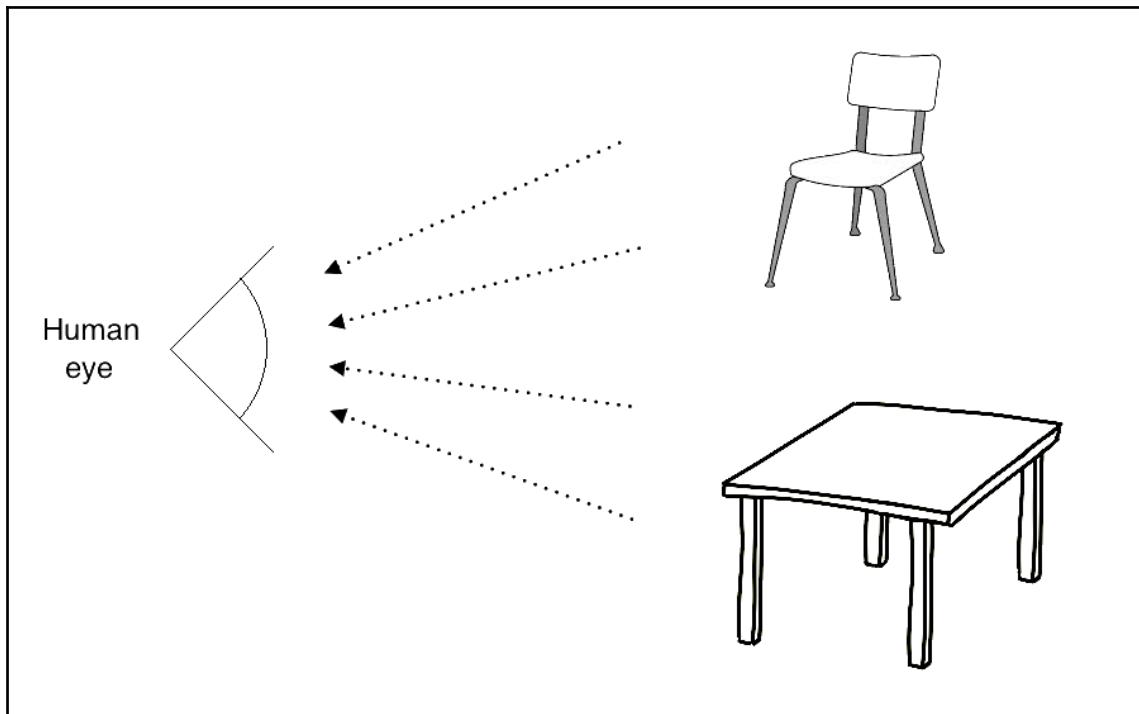
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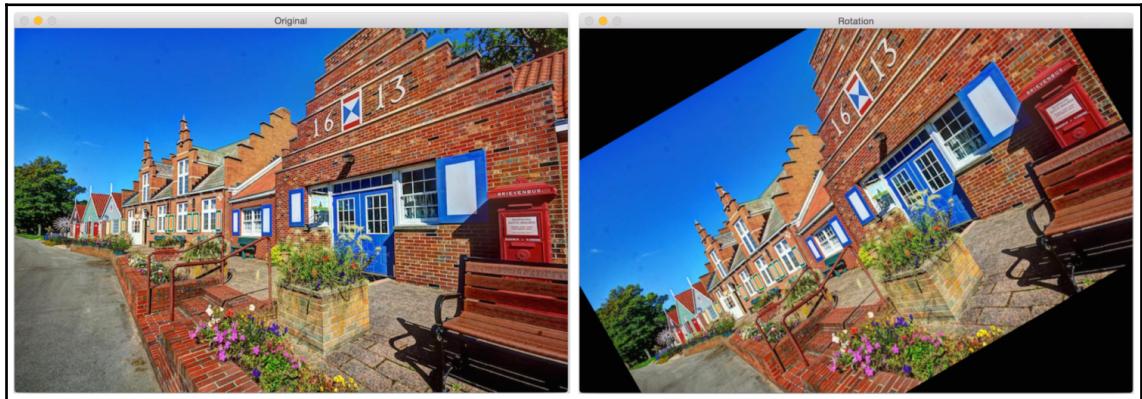
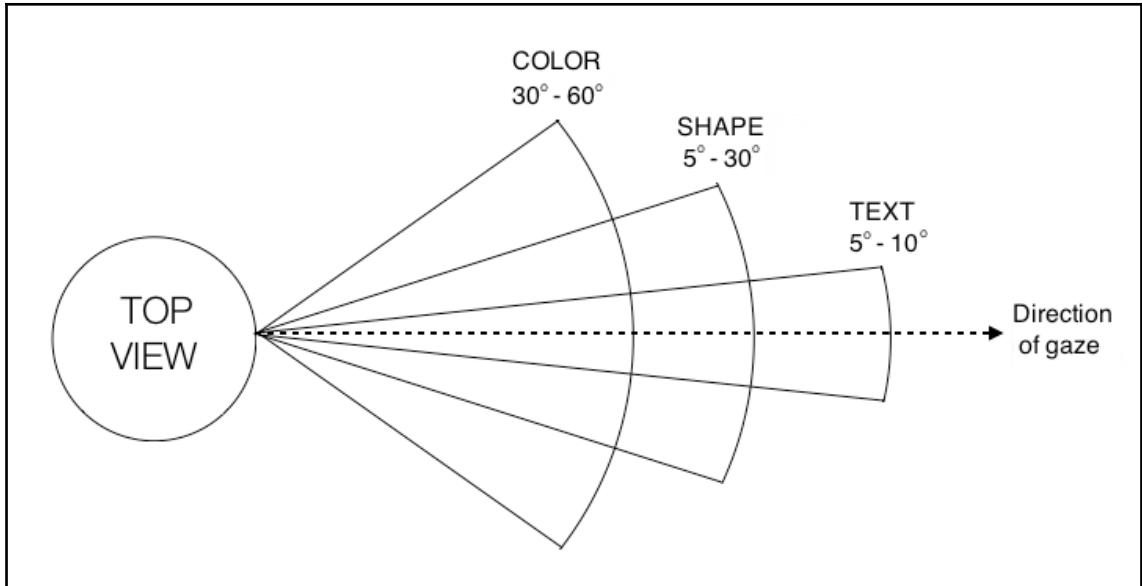
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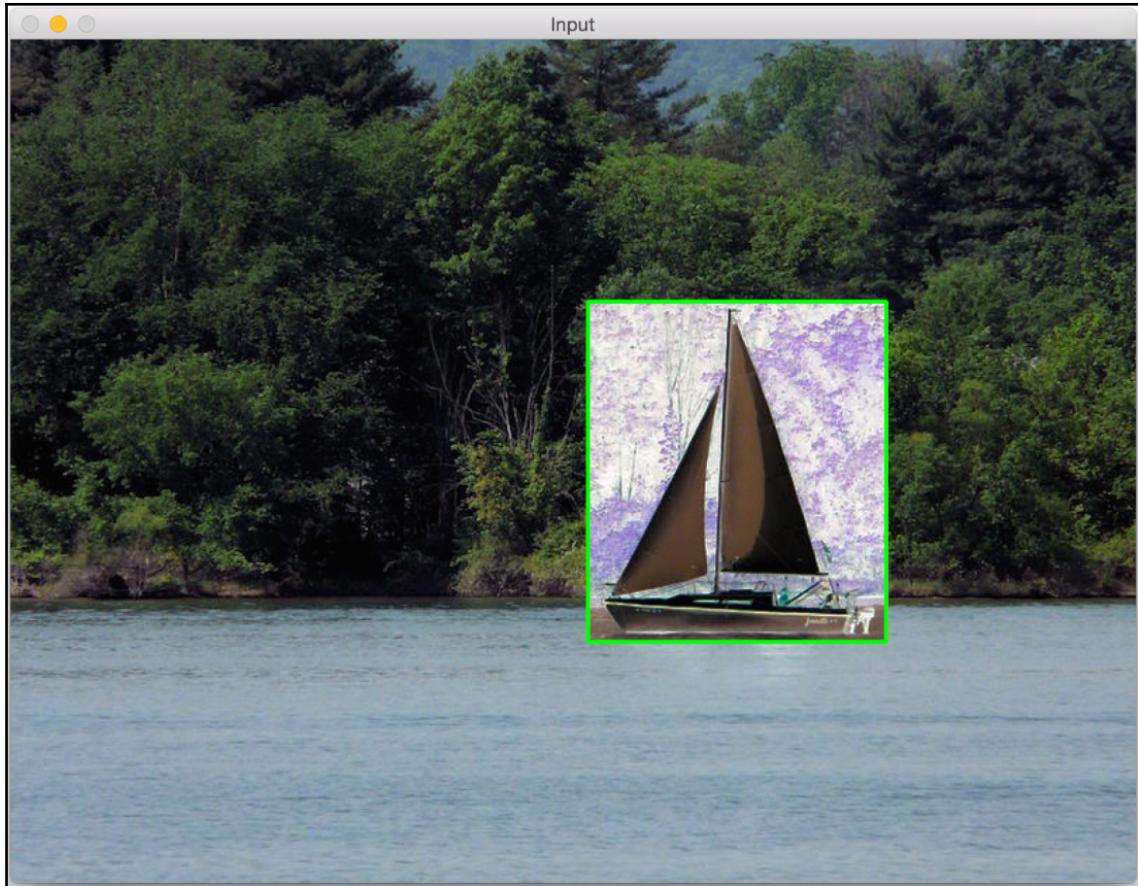
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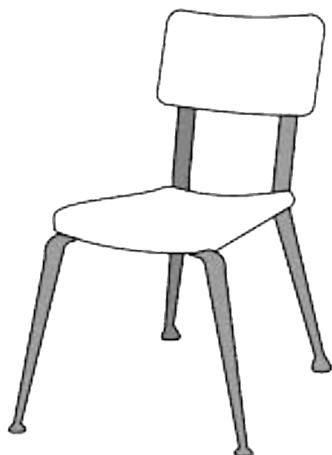
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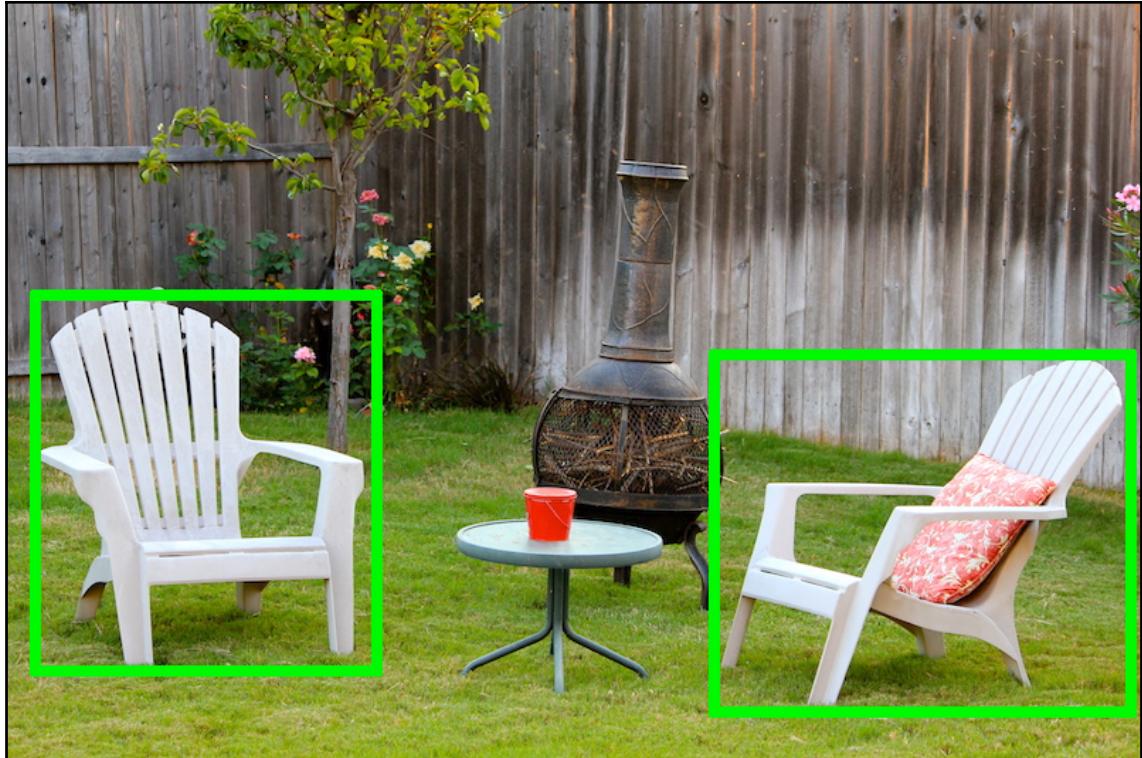
Chapter 1: Getting Started with OpenCV





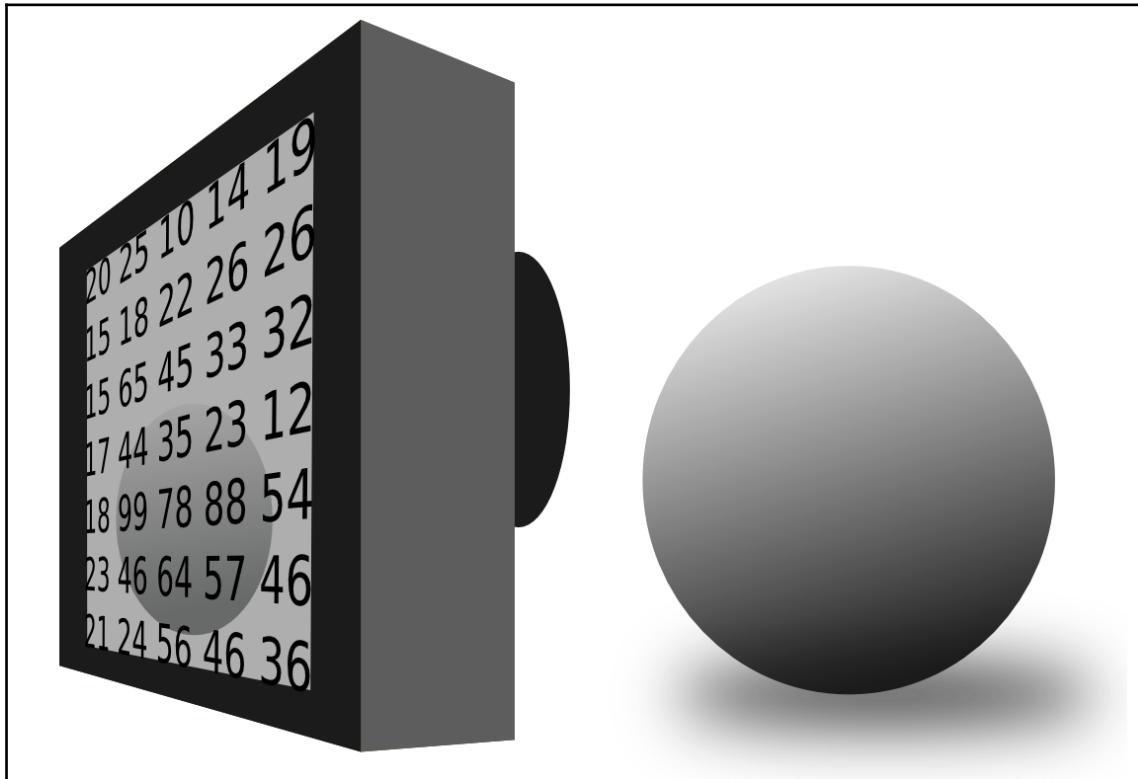








Chapter 2: An Introduction to the Basics of OpenCV



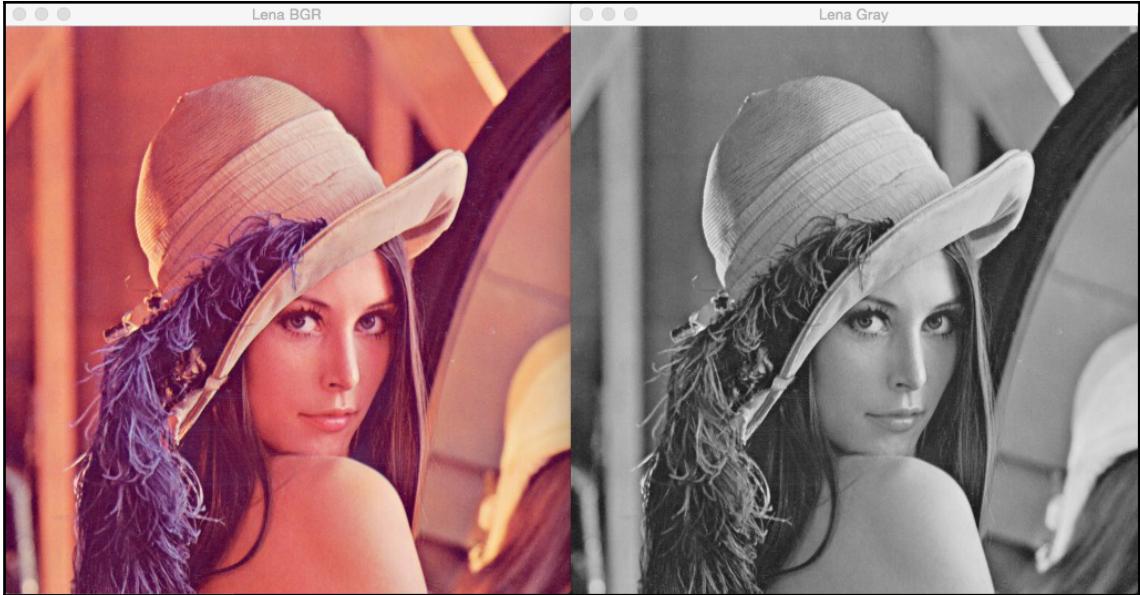
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188	194	189	195	201	196	166	114	113	120	128	131	129
187	200	197	198	190	144	107	106	113	120	125	125	125
198	195	202	183	134	98	97	112	114	115	116	116	118
194	206	178	111	87	99	97	101	107	105	101	97	95
206	168	107	82	80	100	102	91	98	102	104	99	72
160	97	80	86	80	92	80	79	71	74	81	81	64
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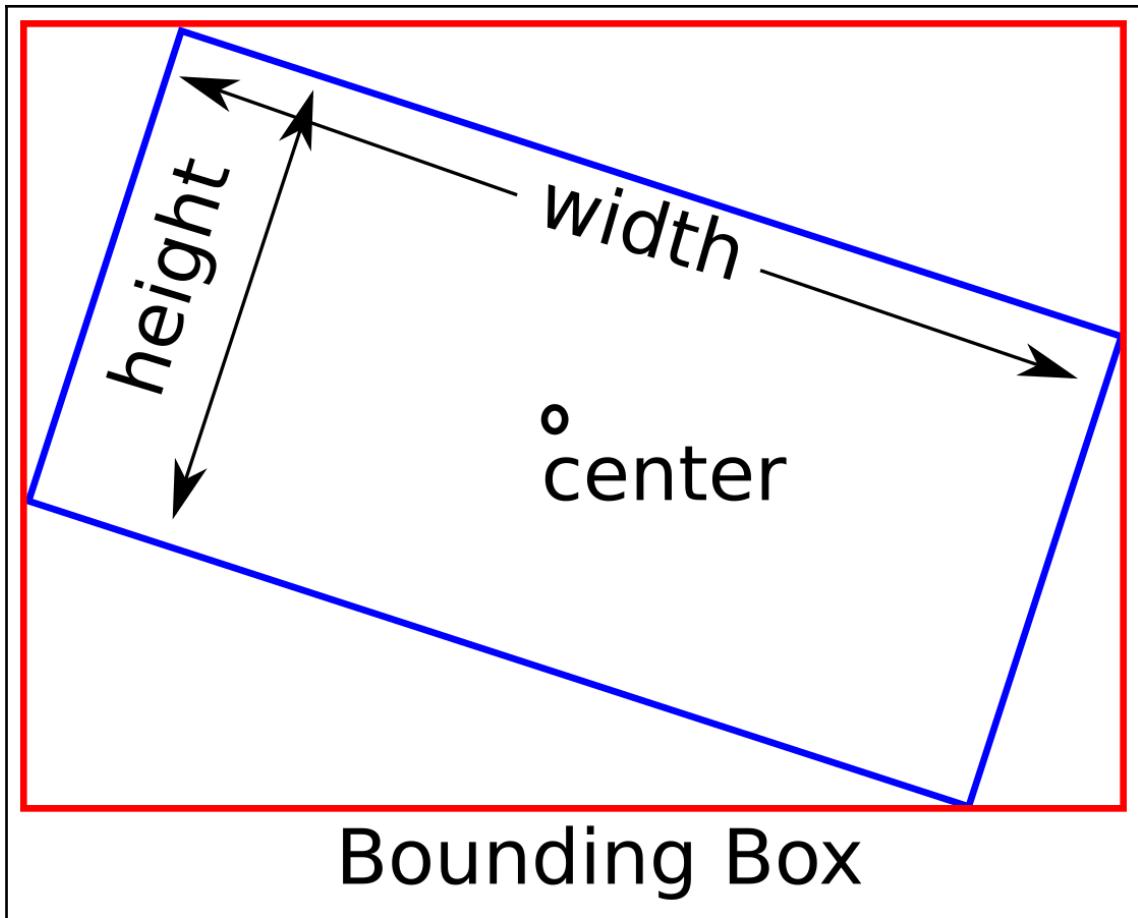
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98	66	76	86	76	83	72	71	55	53	61	61	56	54	54
60	76	74	70	67	64	63	60	55	49	54	52	54		

Blue

Green

Red





[0, 0, 0, 0, 0;	[1, 1, 1, 1, 1;
0, 0, 0, 0, 0;	1, 1, 1, 1, 1;
0, 0, 0, 0, 0;	1, 1, 1, 1, 1;
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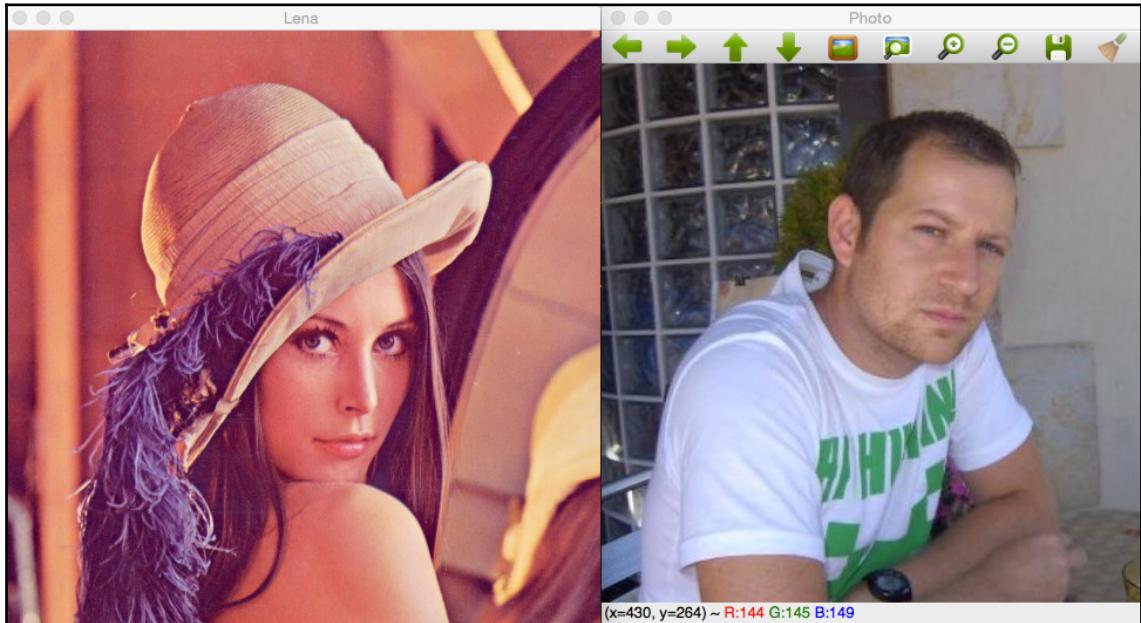
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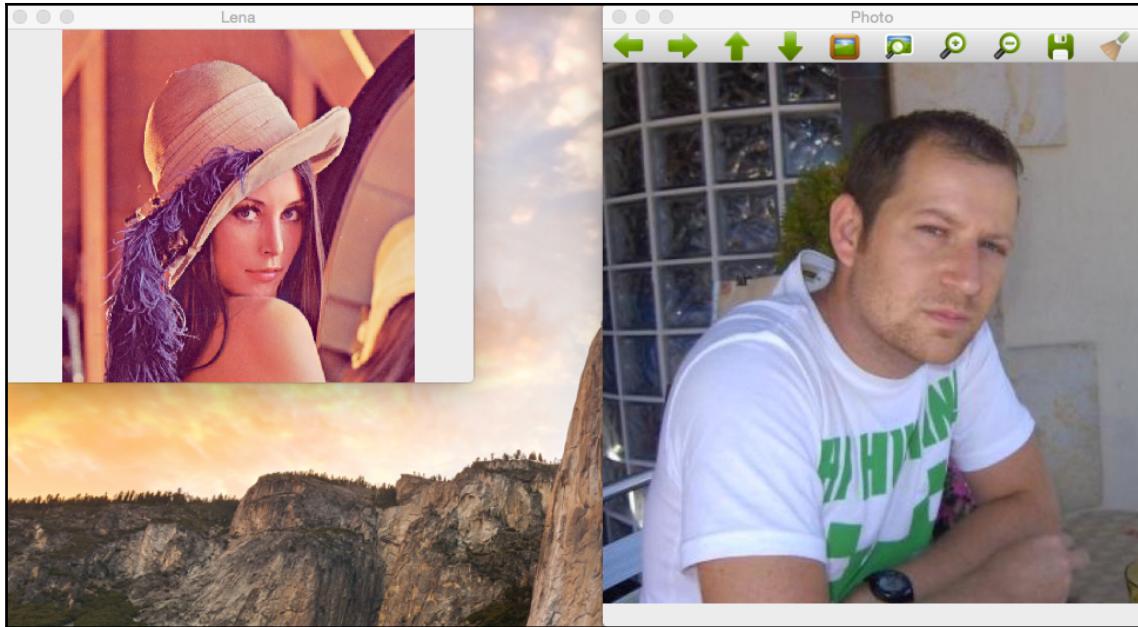
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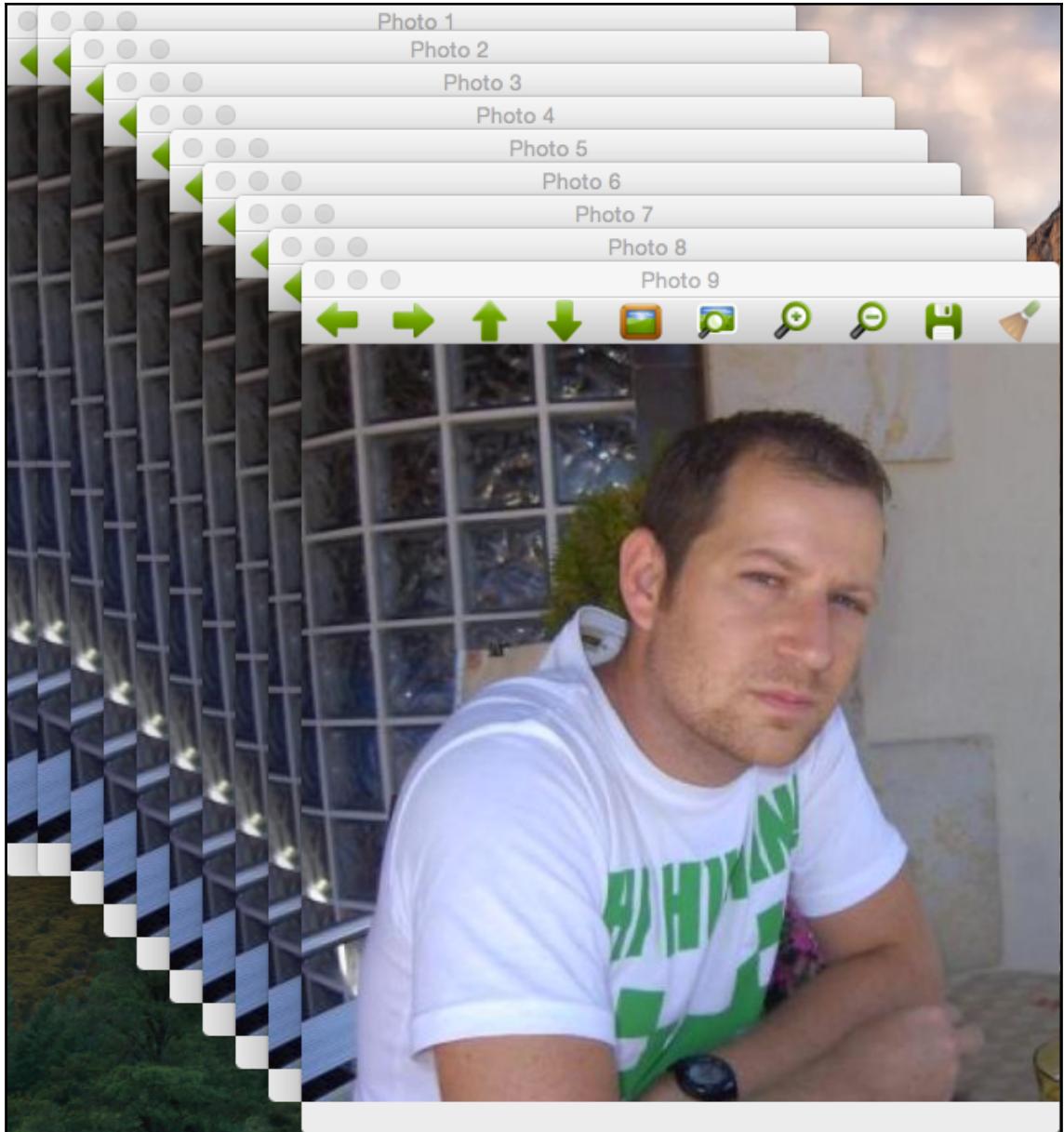
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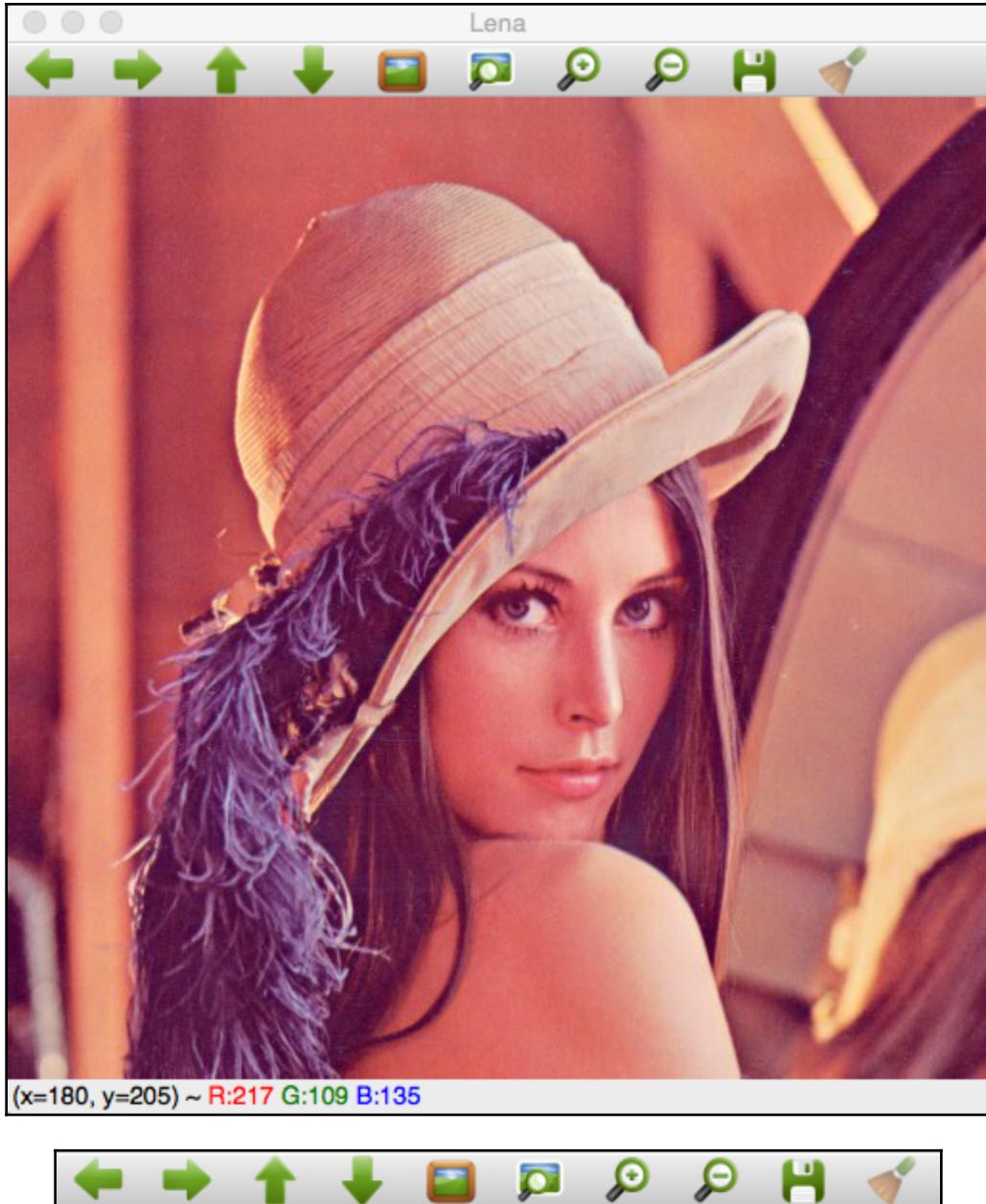
$$[1, 0, 0; \quad * \quad [1, 1; \quad = [1, 1; \\ 0, 1, 0] \quad 1, 1; \quad 1, 1]$$

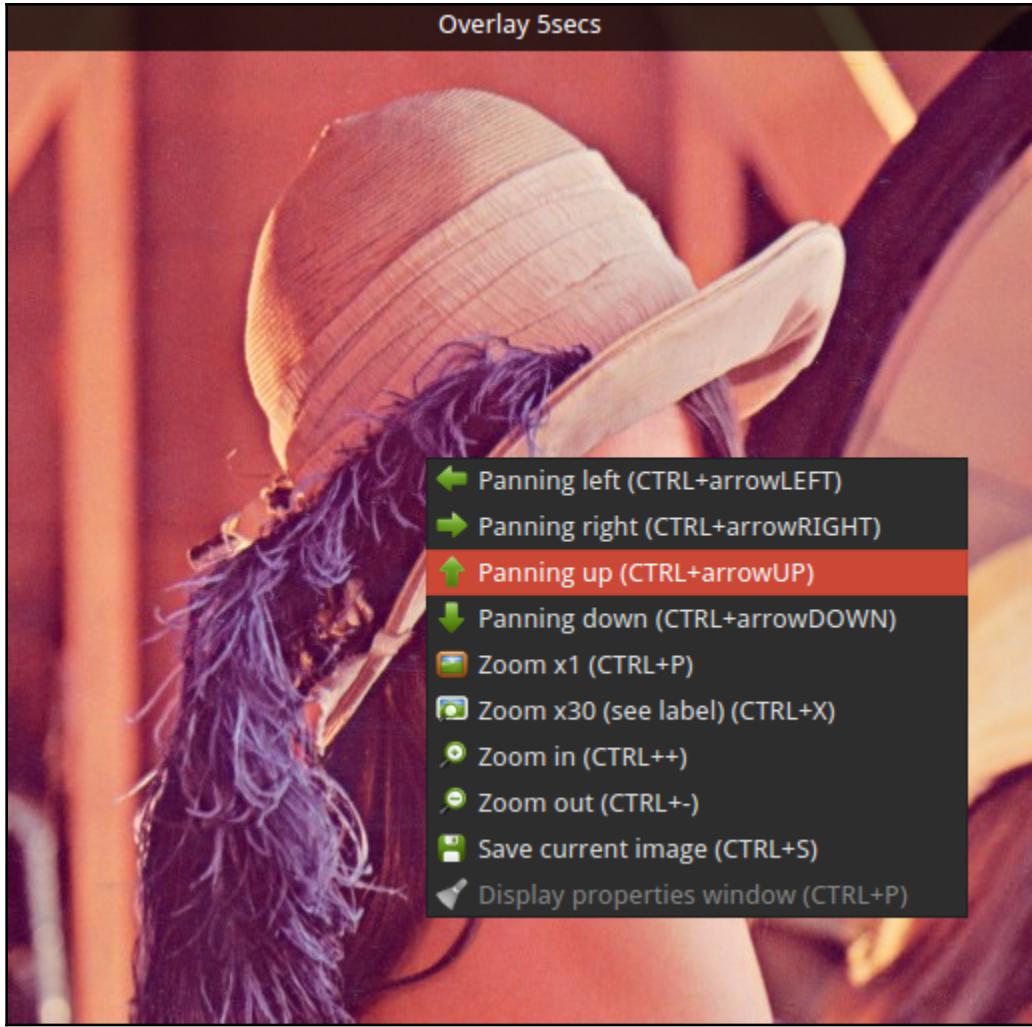
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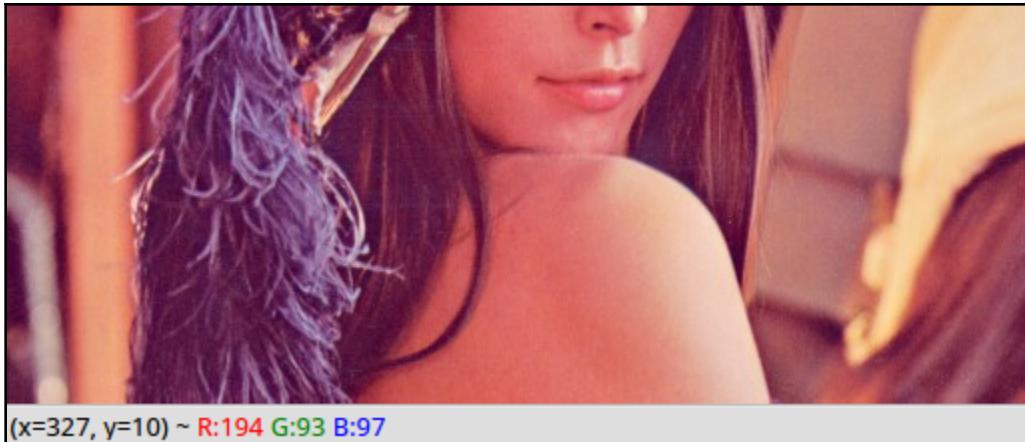




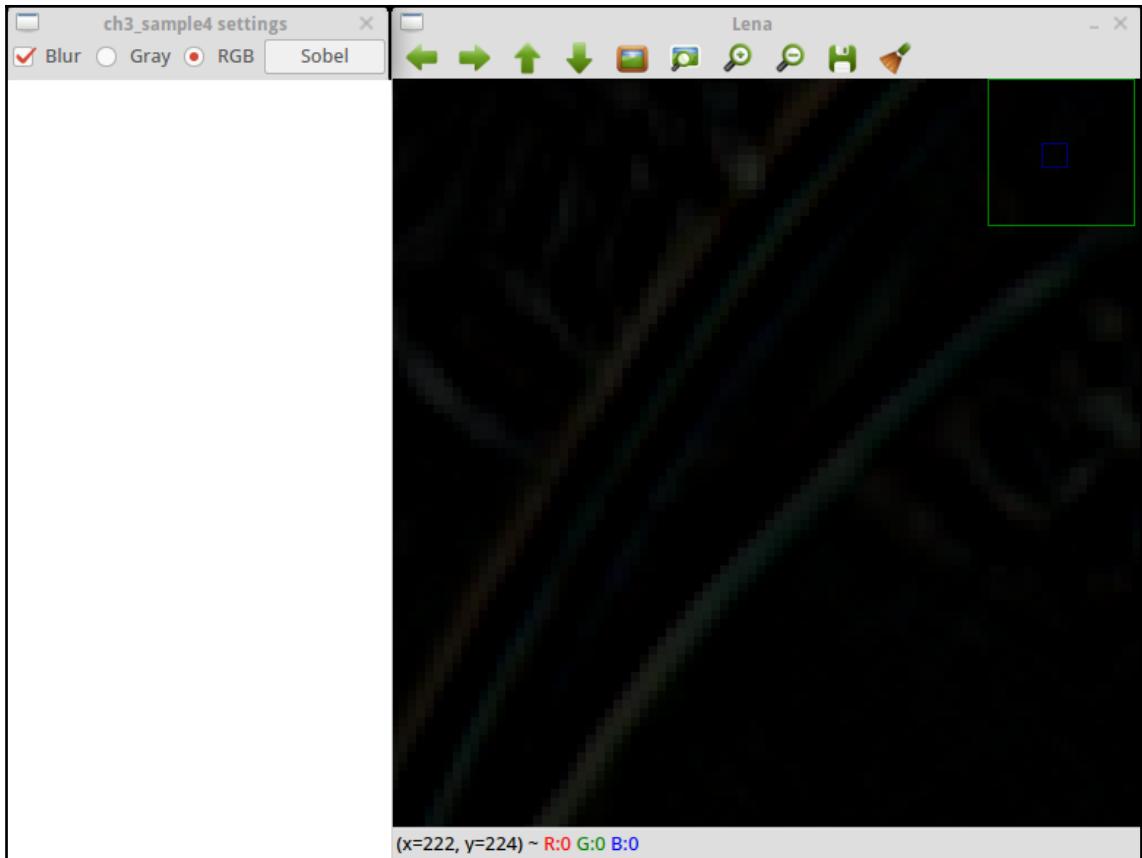


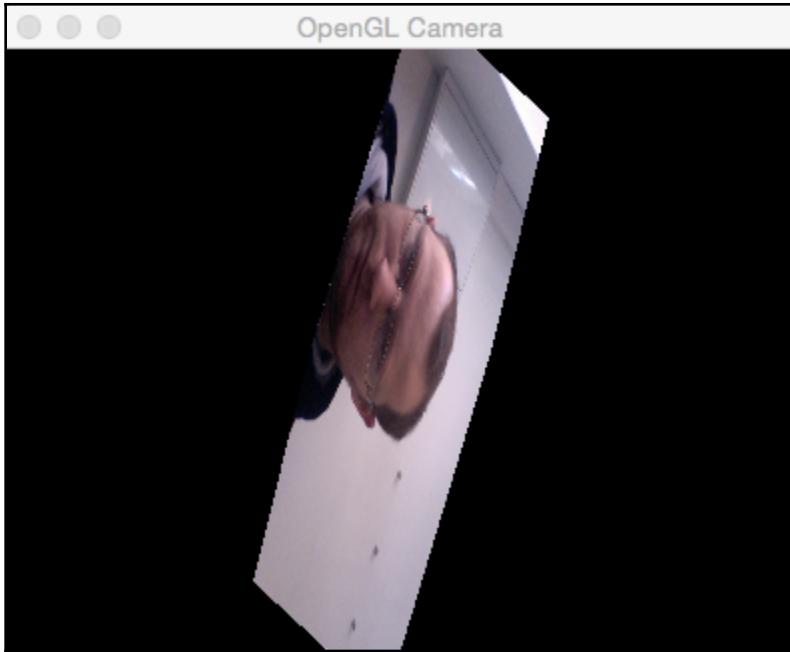




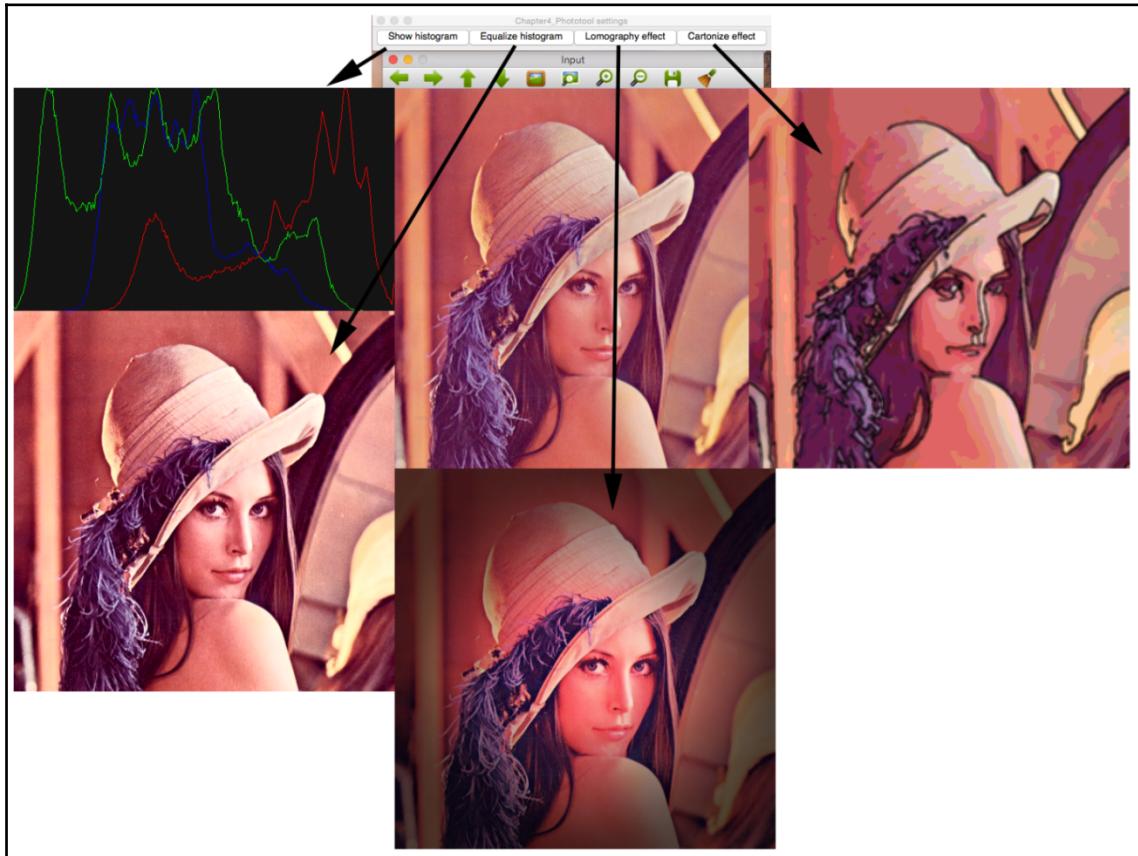


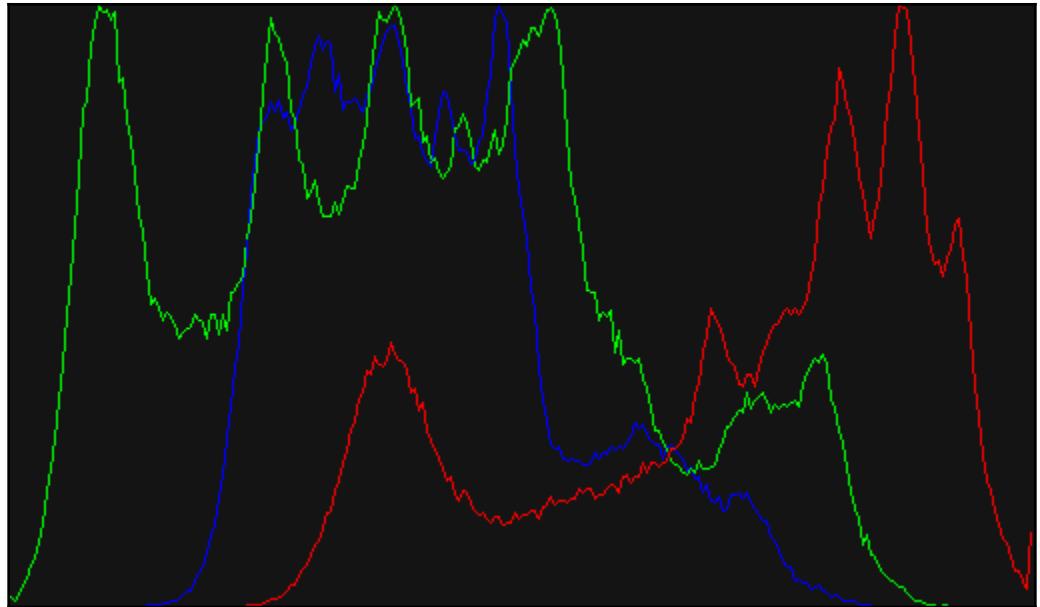
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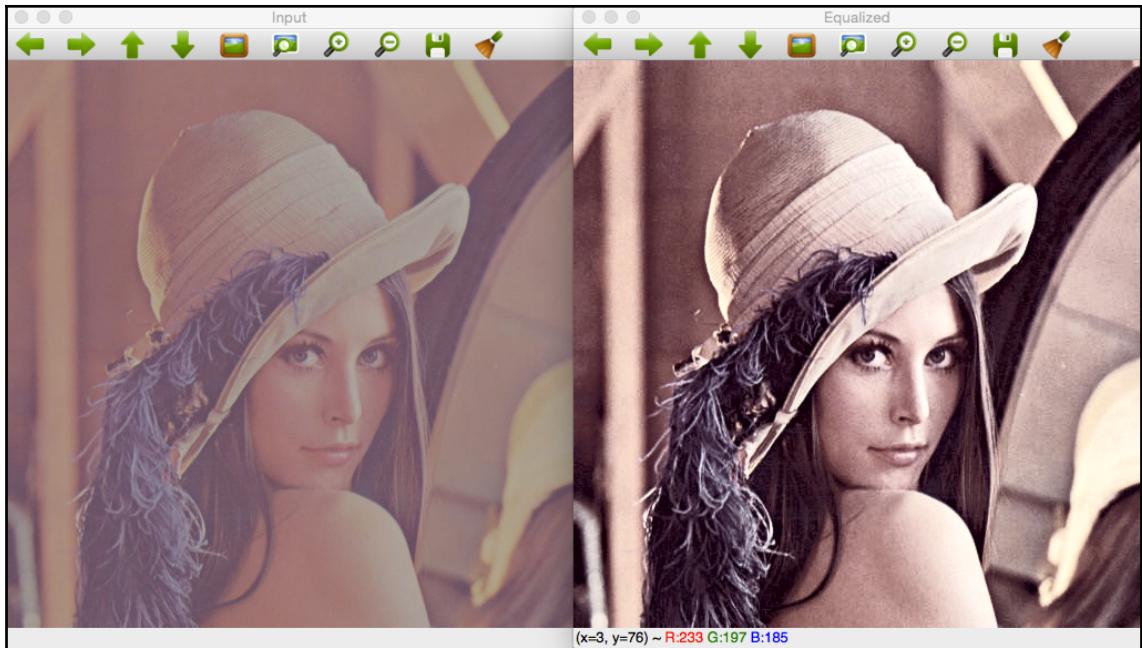




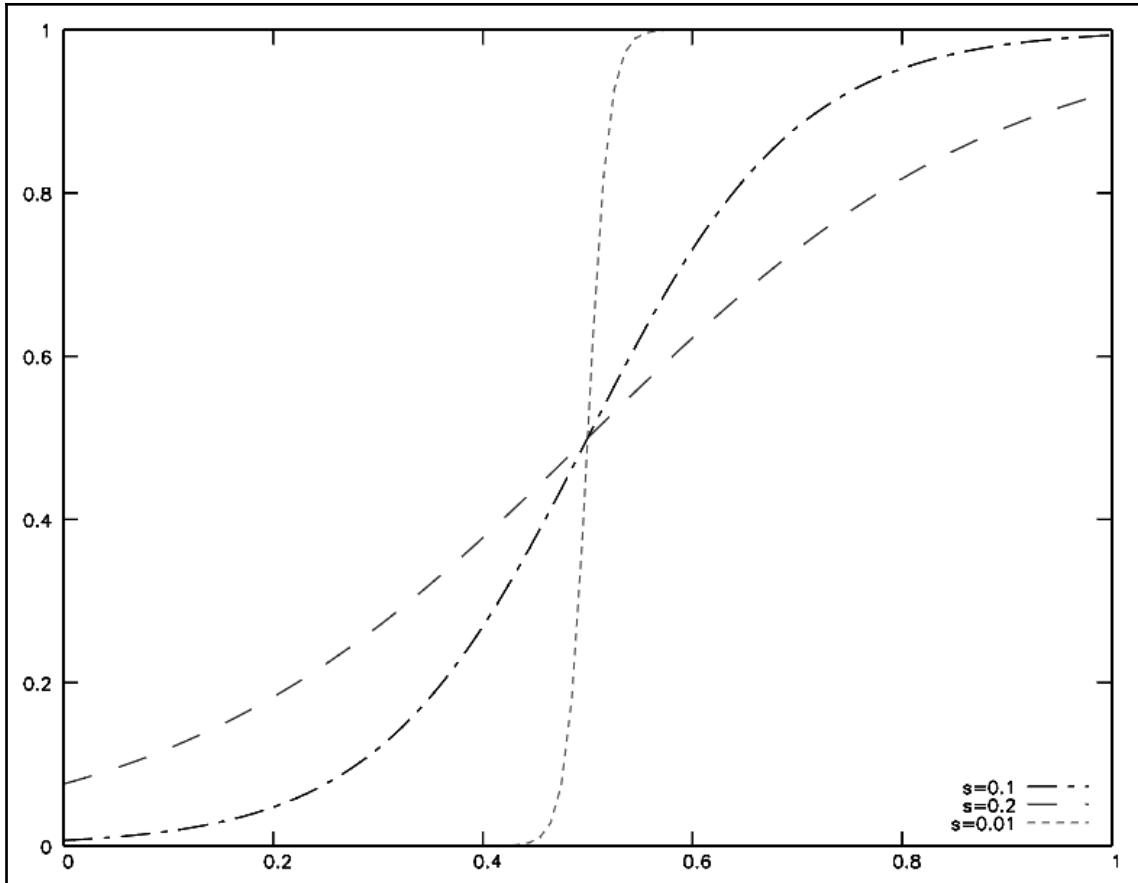
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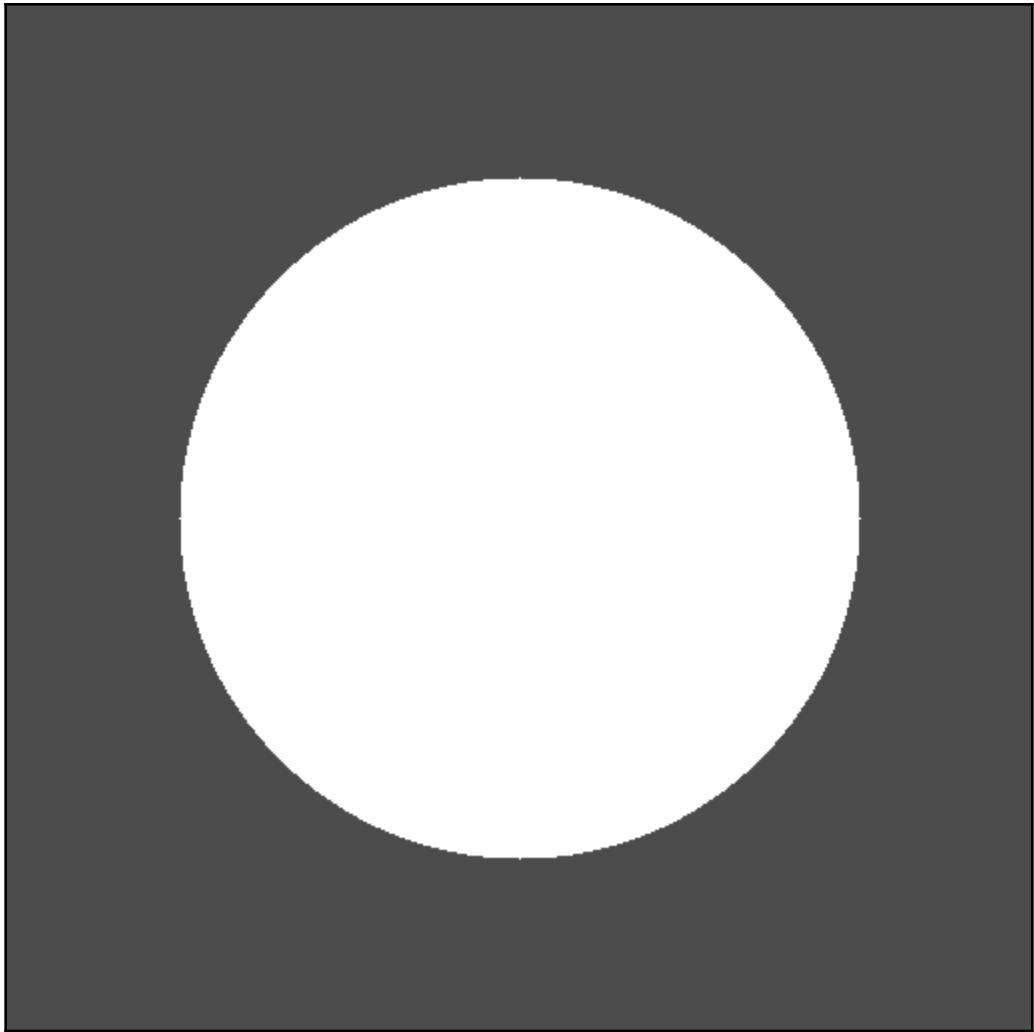


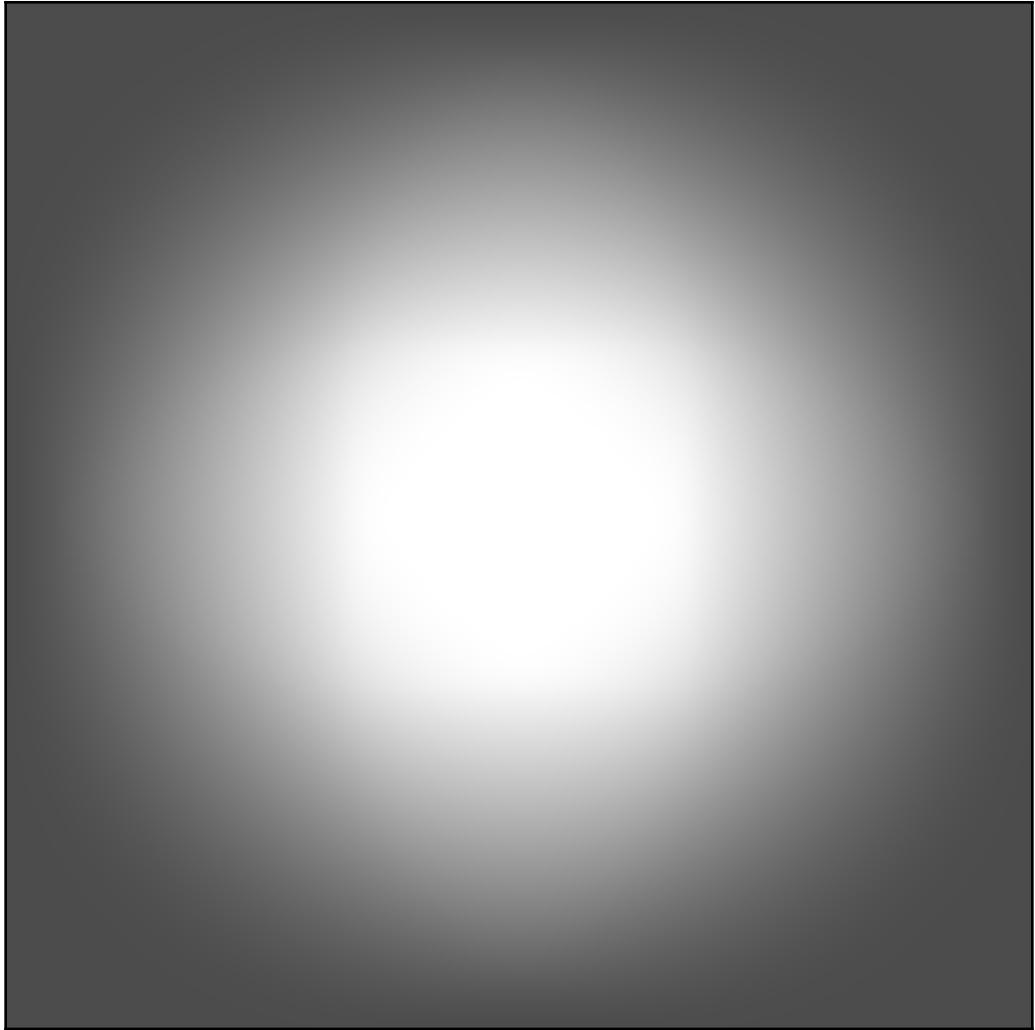


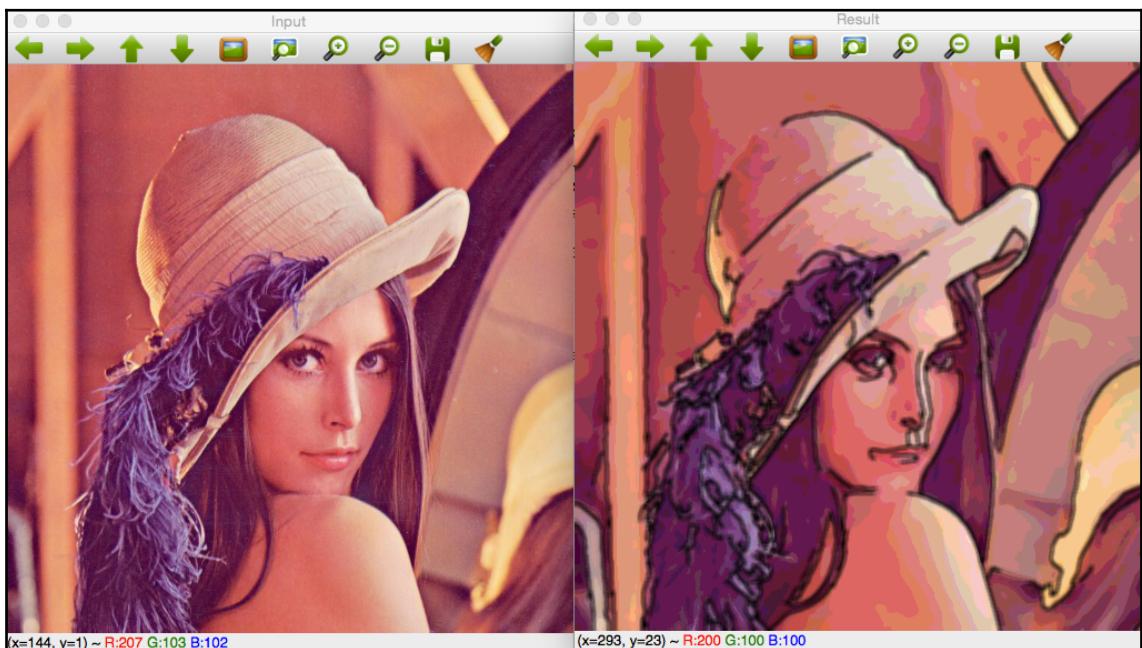
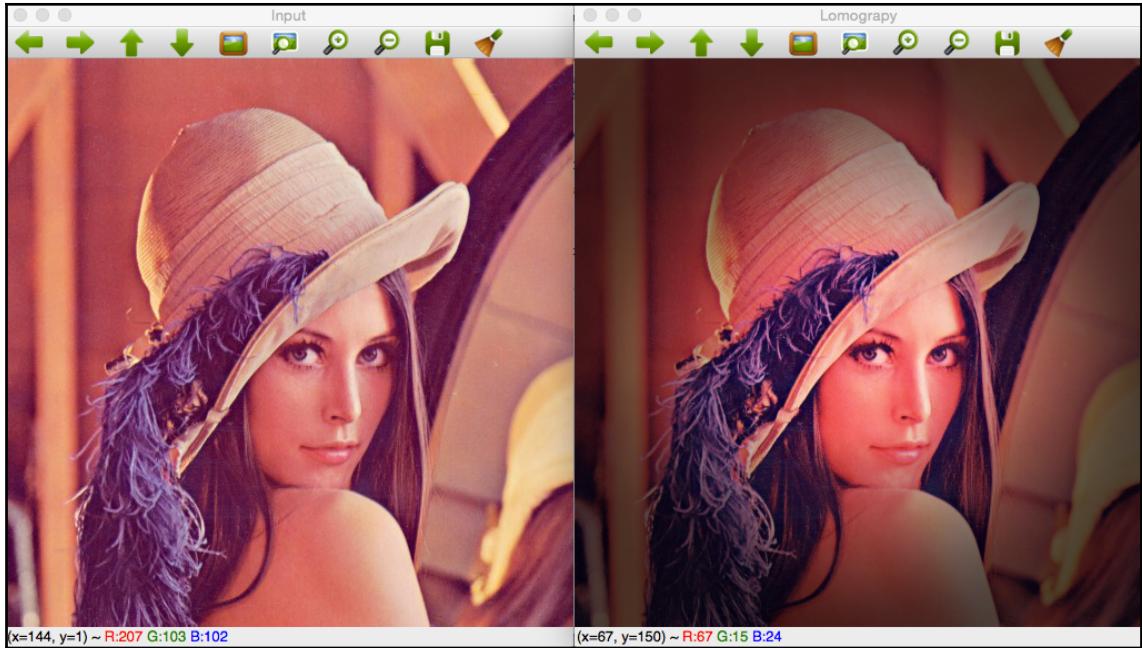


$$\frac{1}{1 + e^{-\frac{x-0.5}{s}}}$$

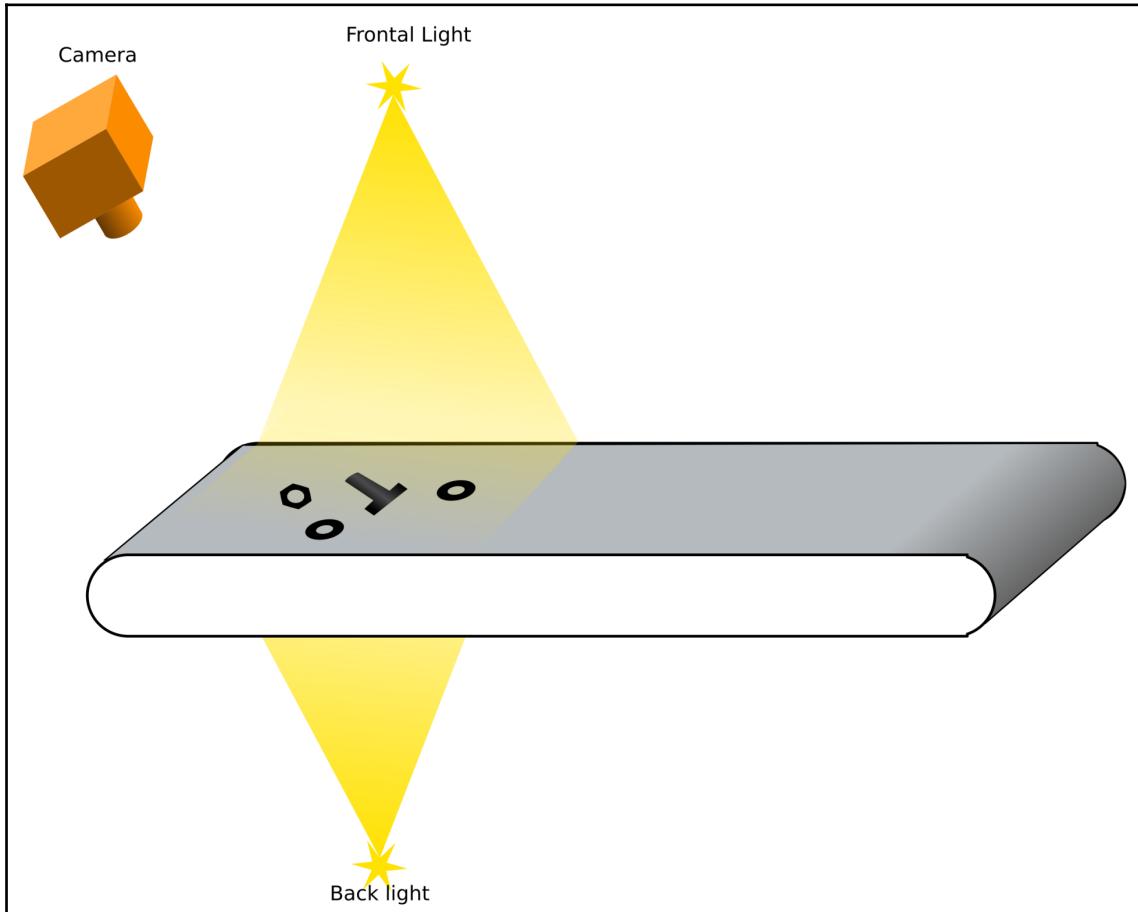


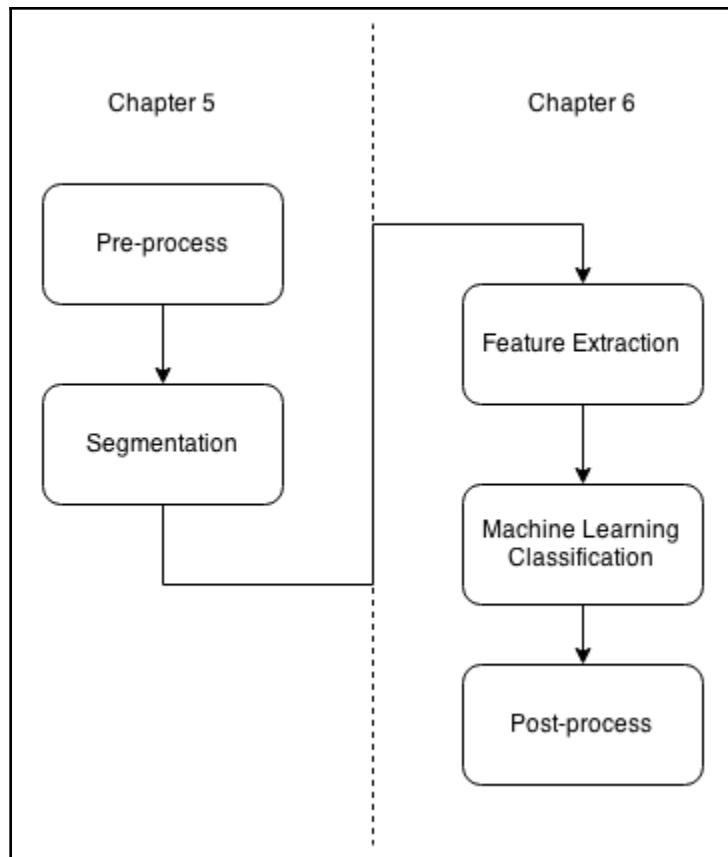
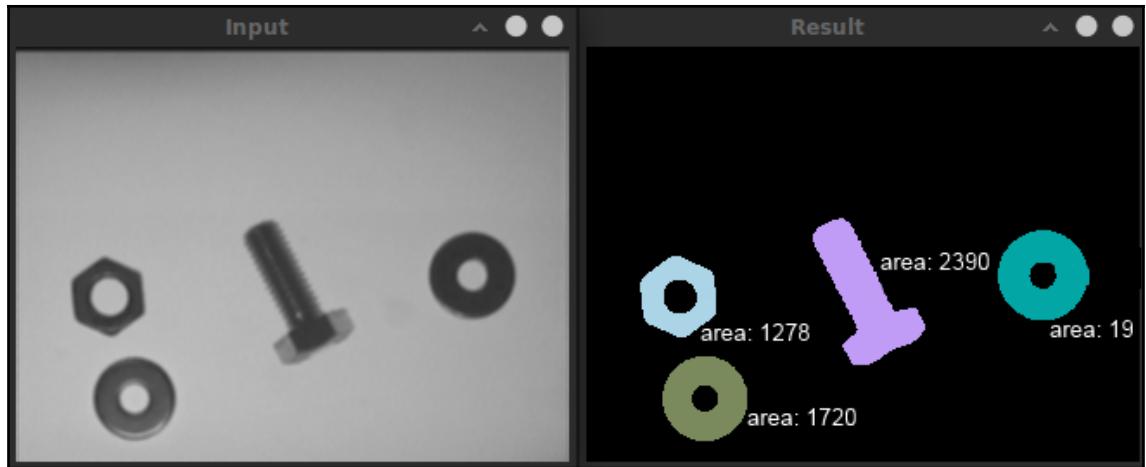


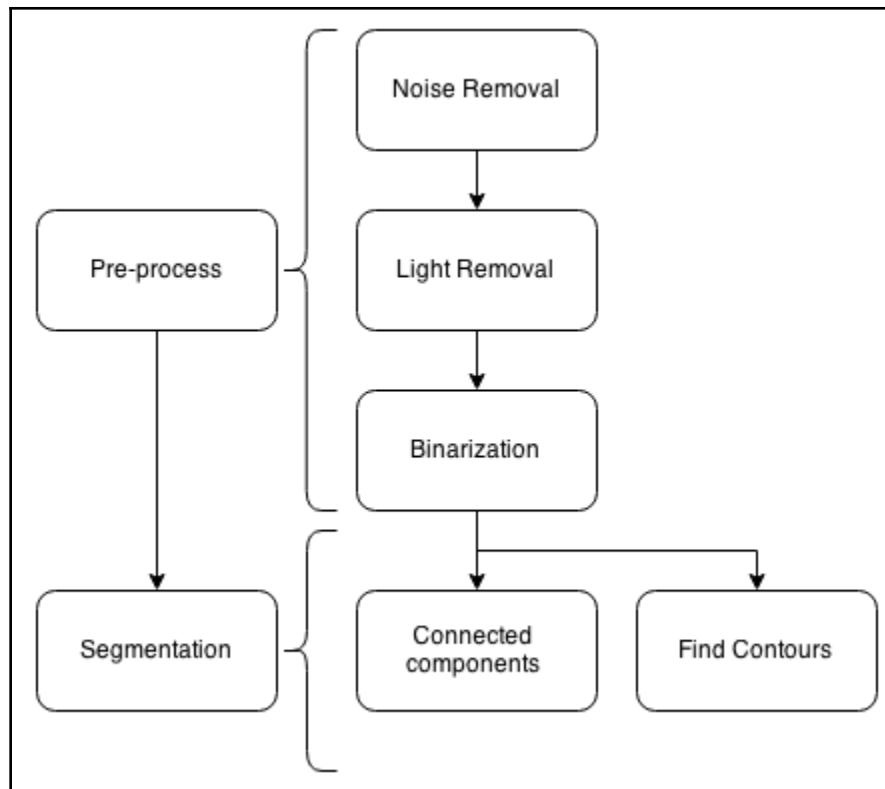


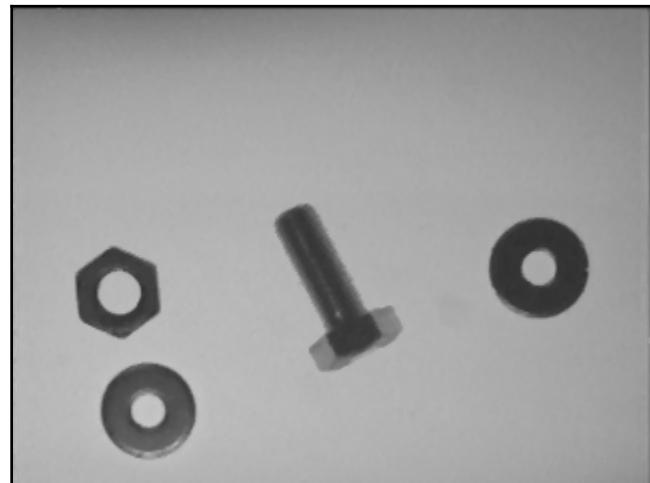
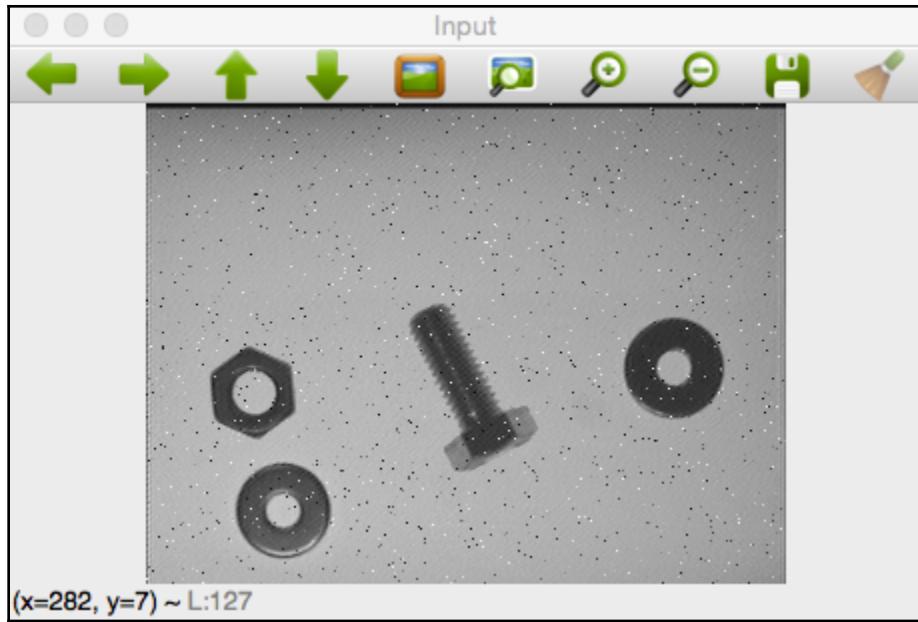


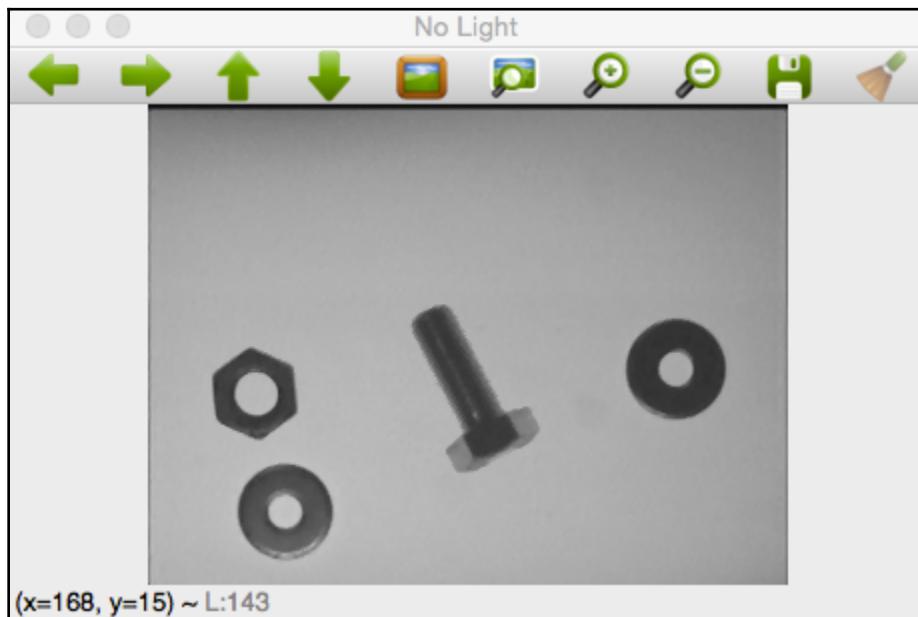
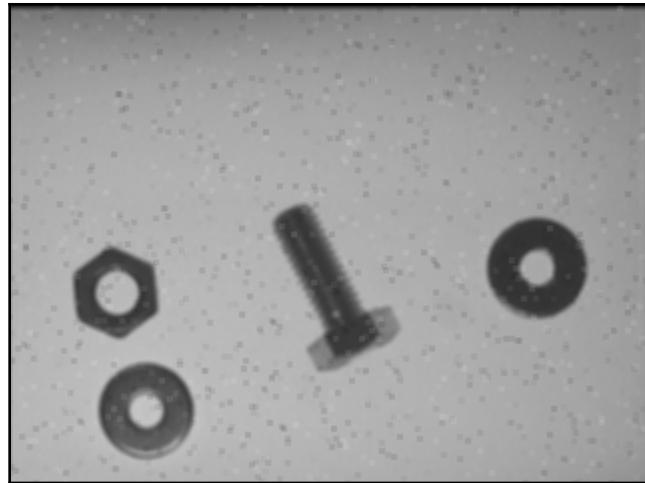
Chapter 5: Automated Optical Inspection, Object Segmentation, and Detection

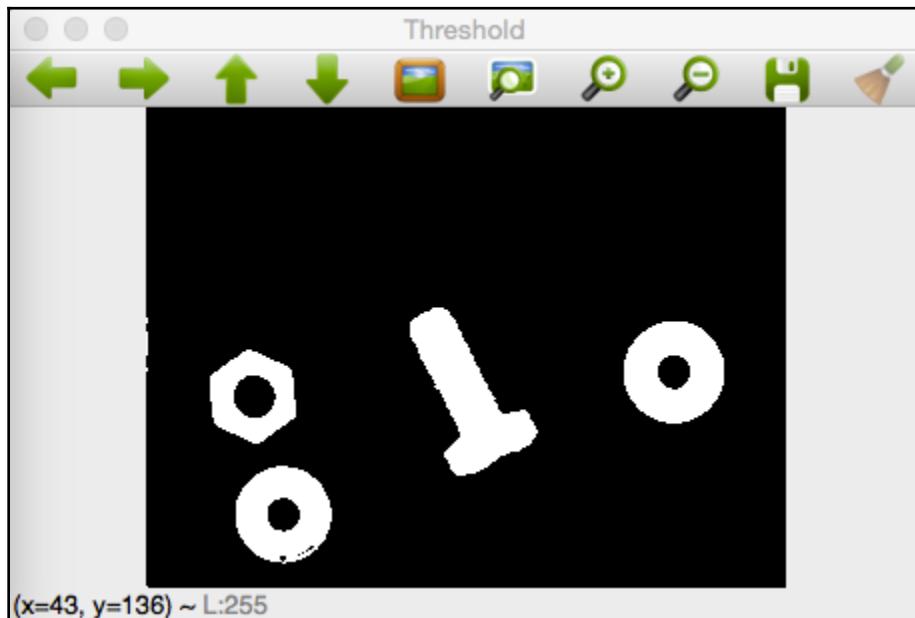


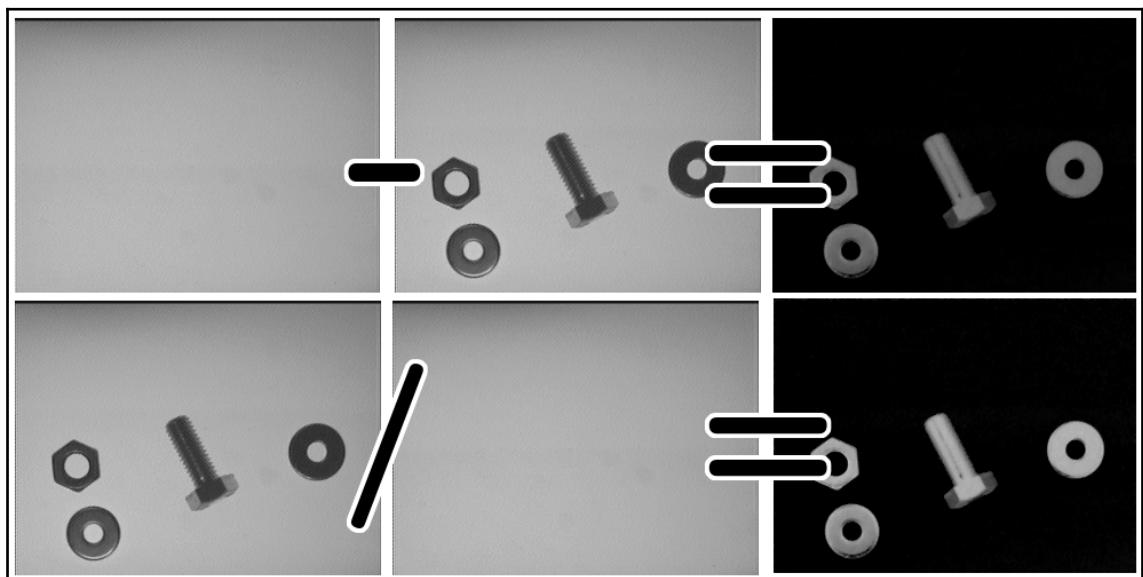
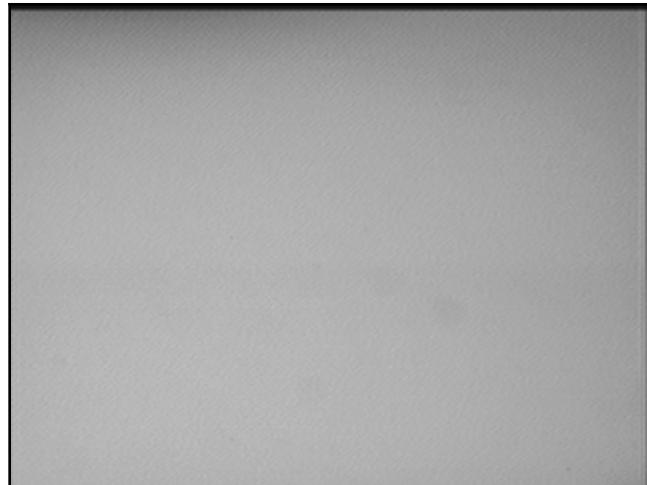


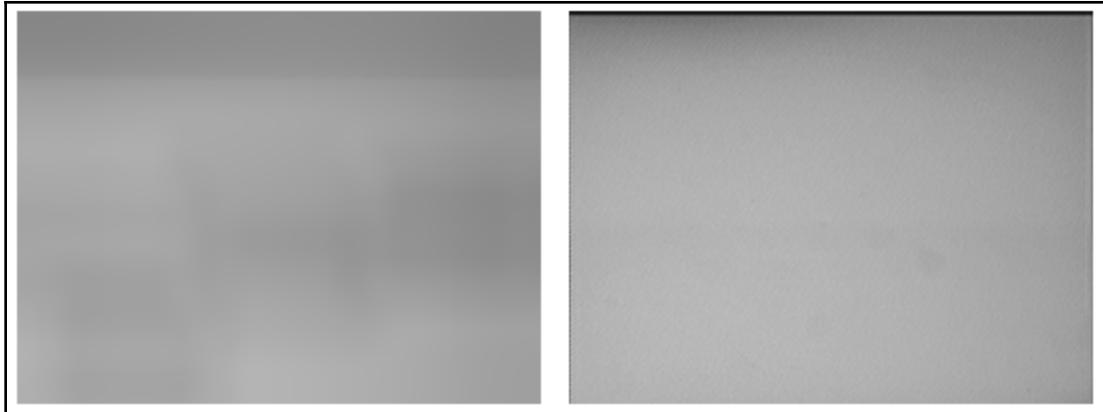






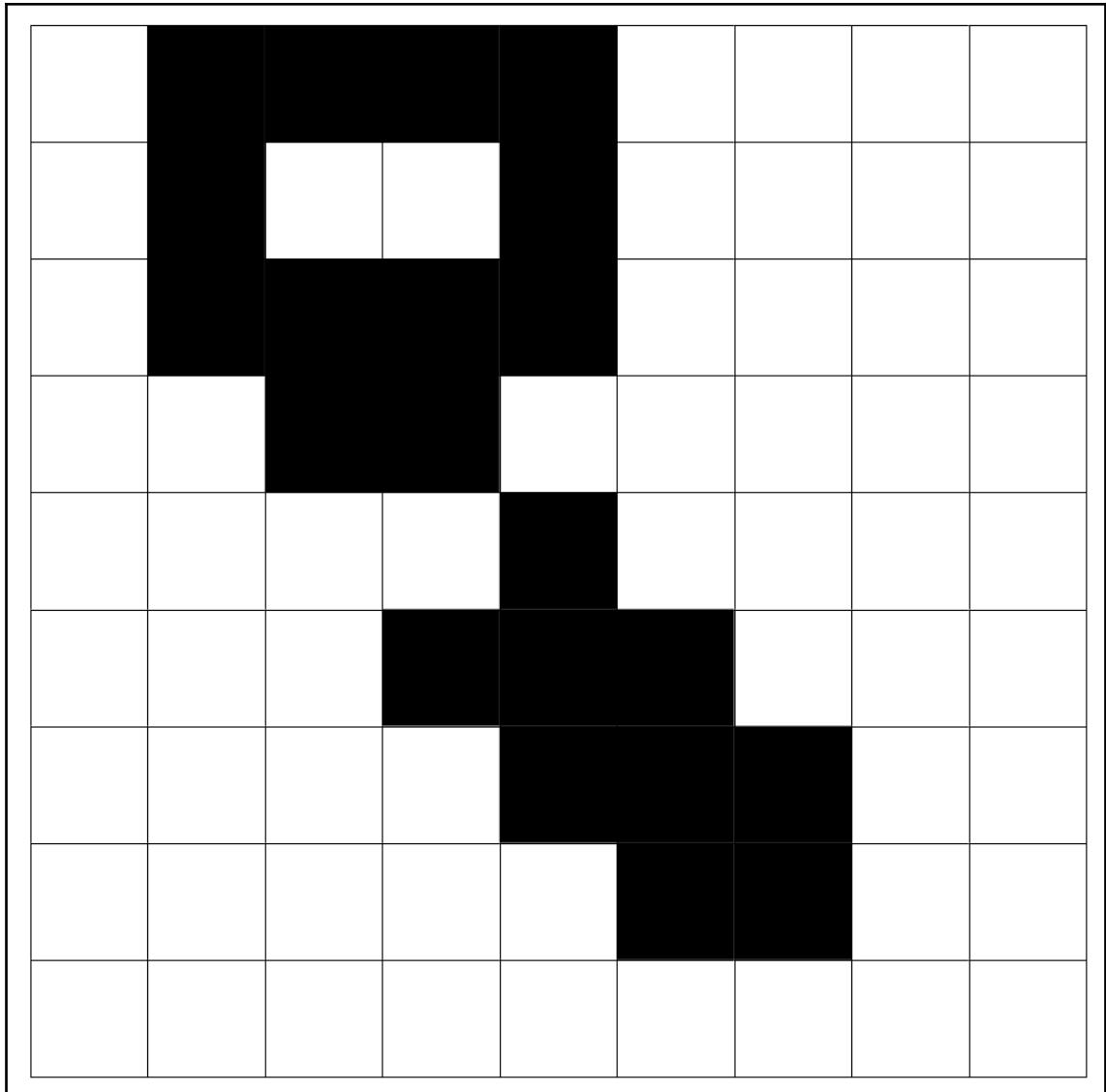


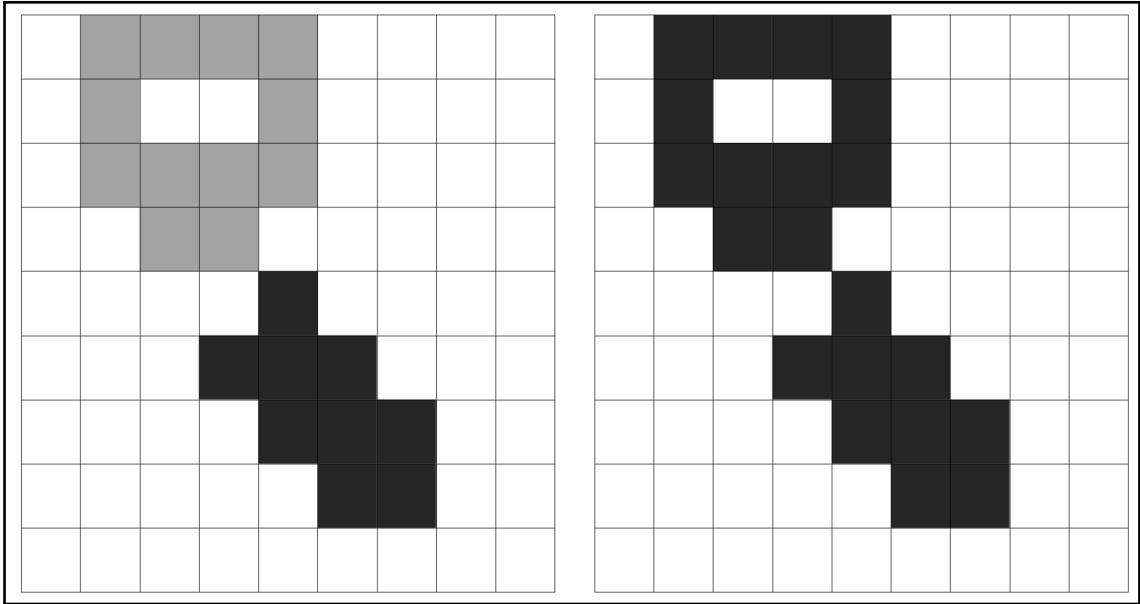


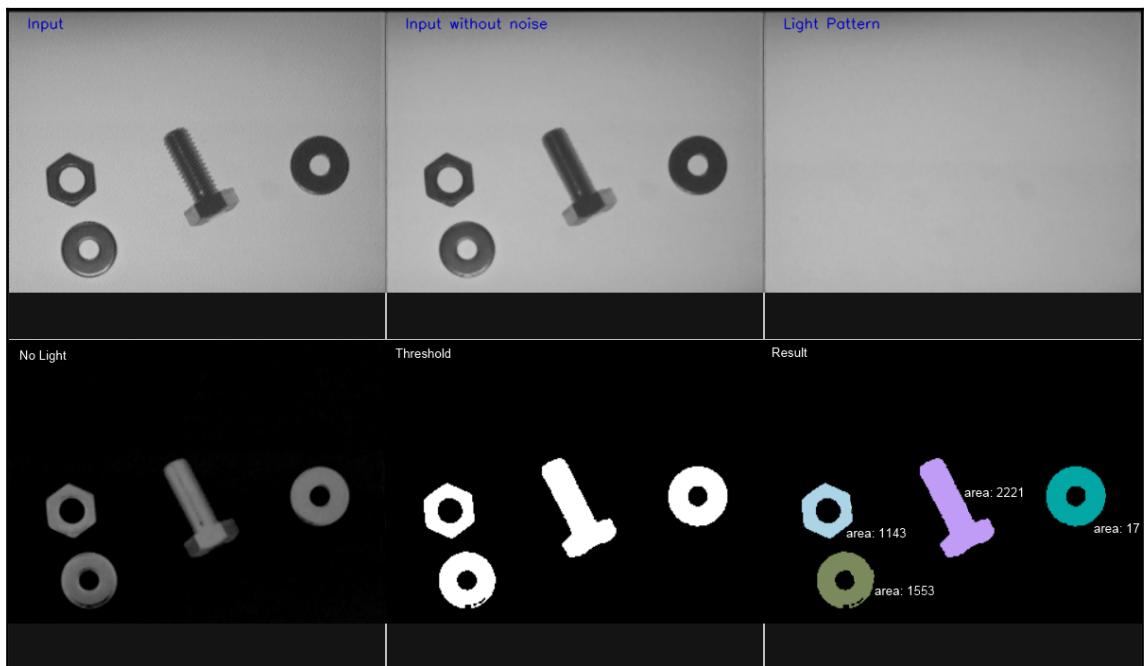
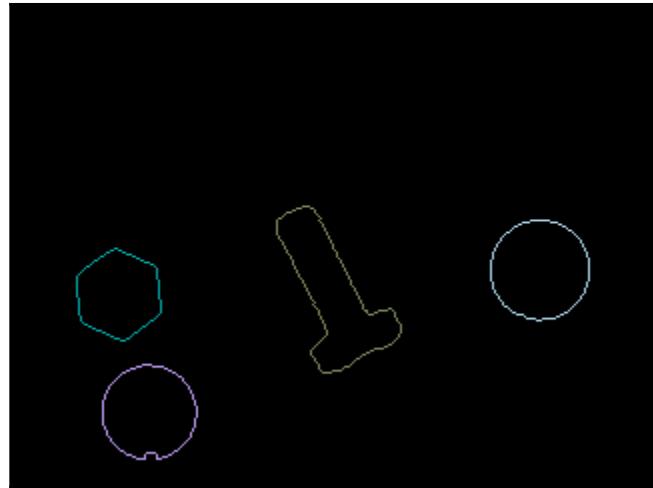


$$I(x, y) = \begin{cases} 0, & \text{if } I(x, y) < \text{threshold} \\ 1, & \text{if } I(x, y) > \text{threshold} \end{cases}$$

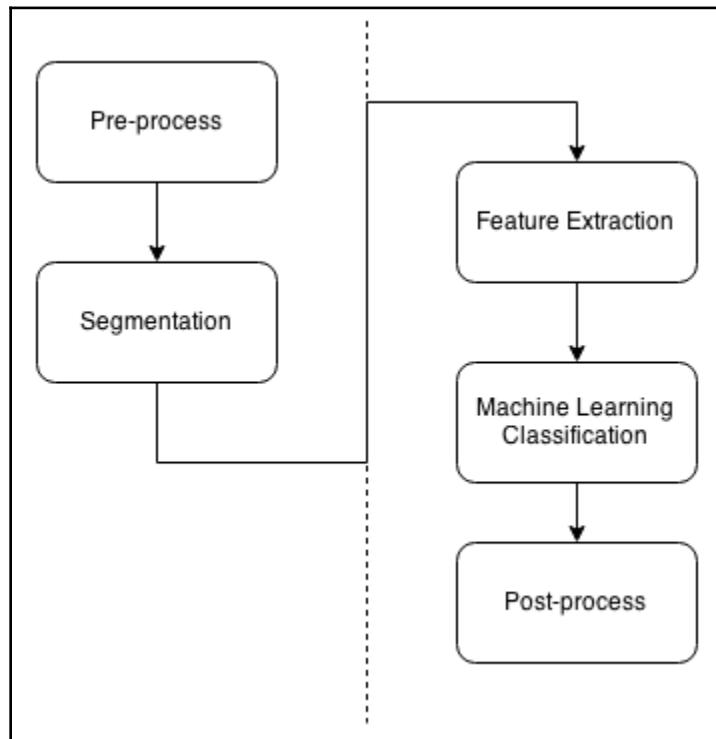
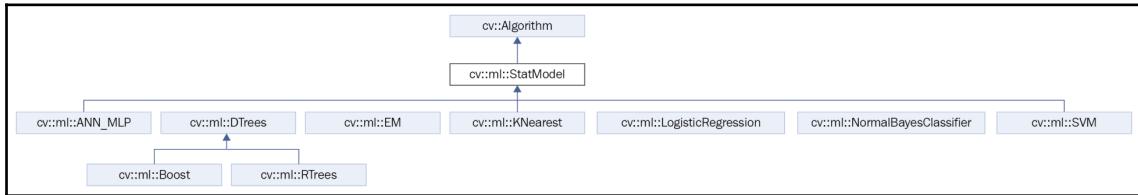
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6	7	8

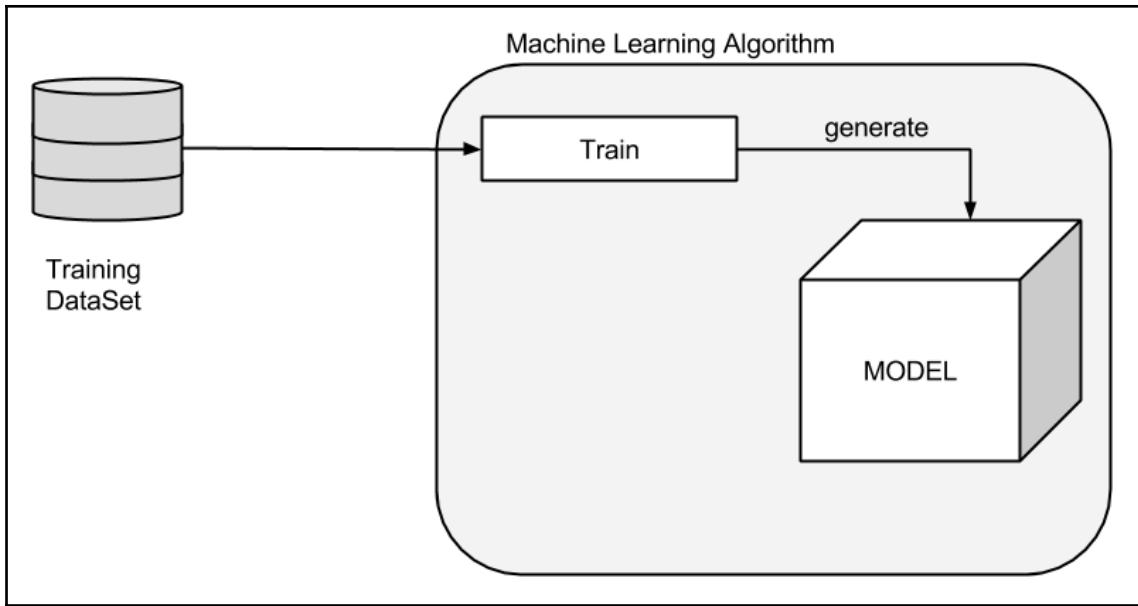


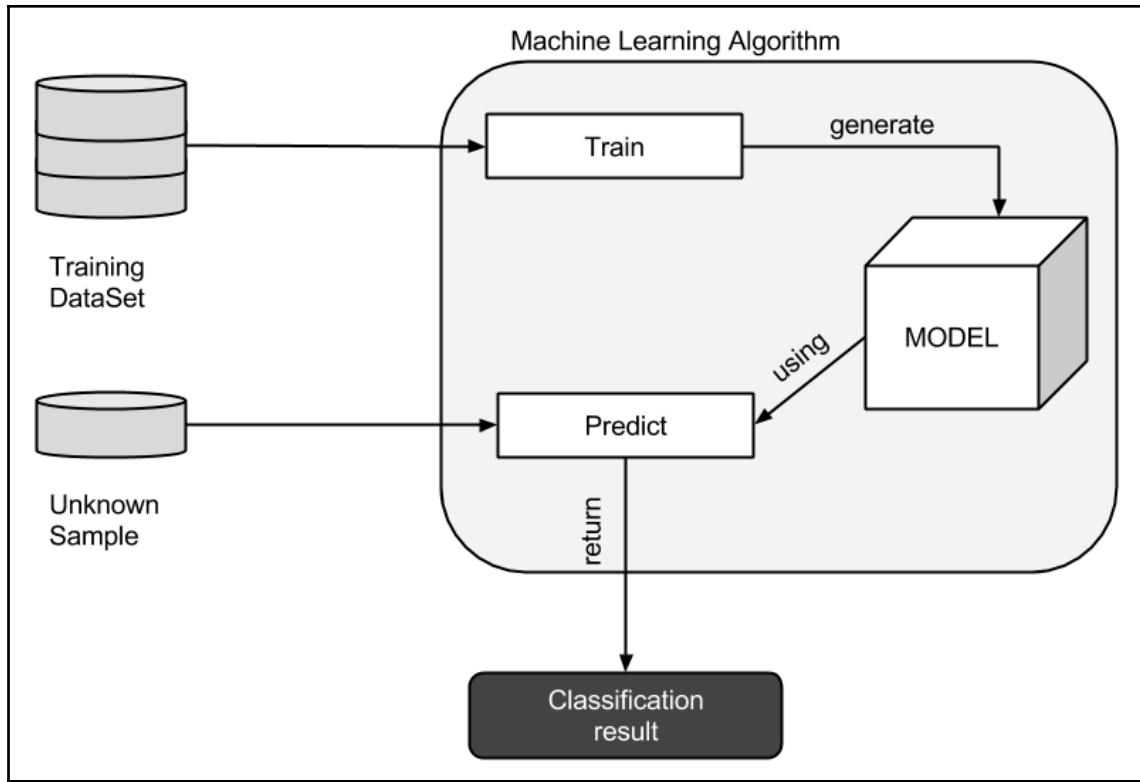


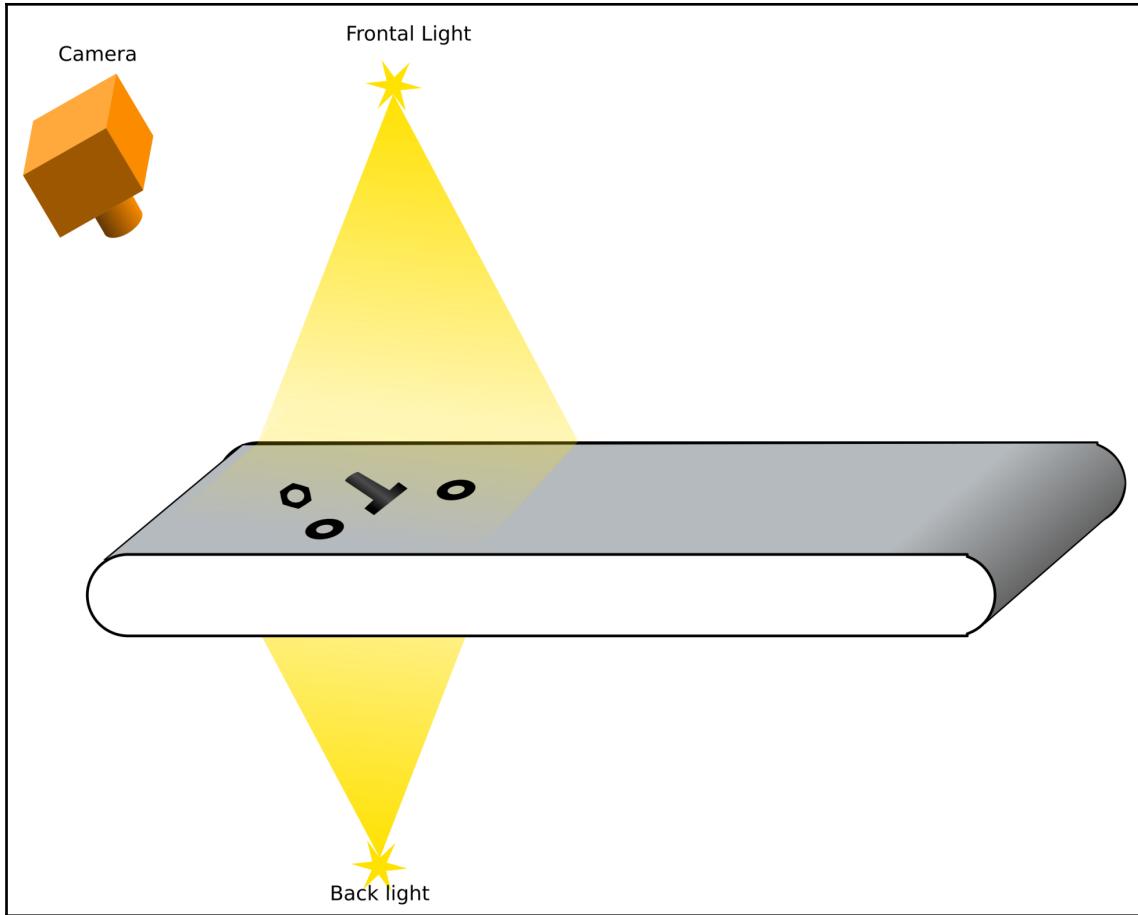


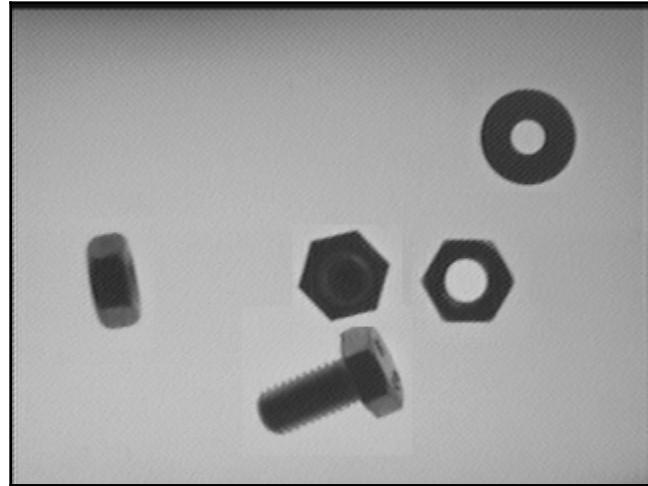
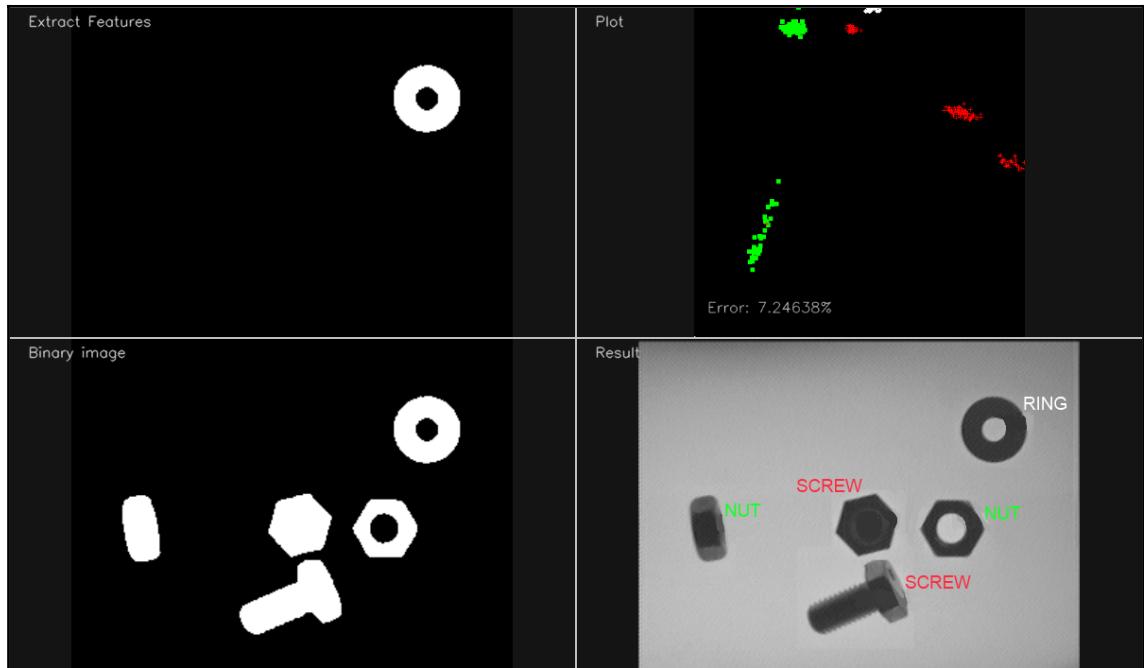
Chapter 6: Learning Object Classification

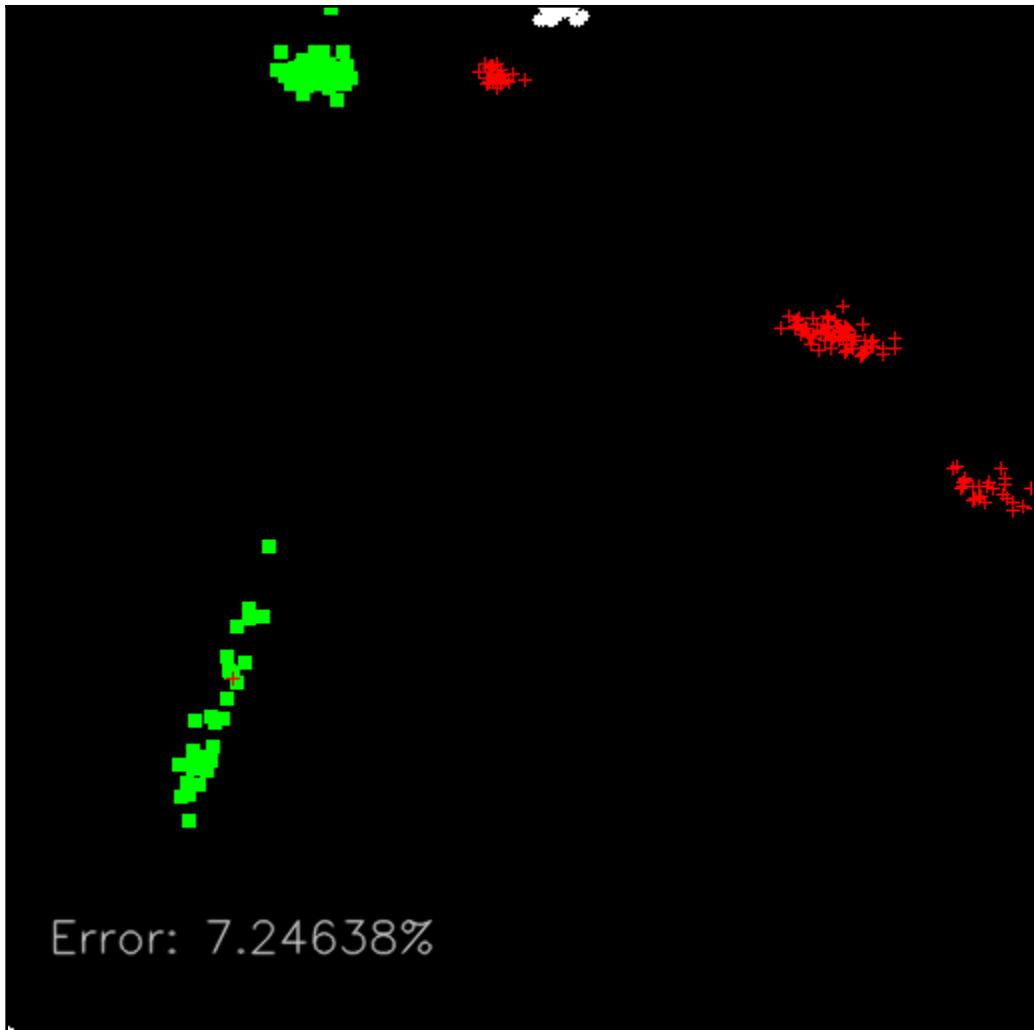


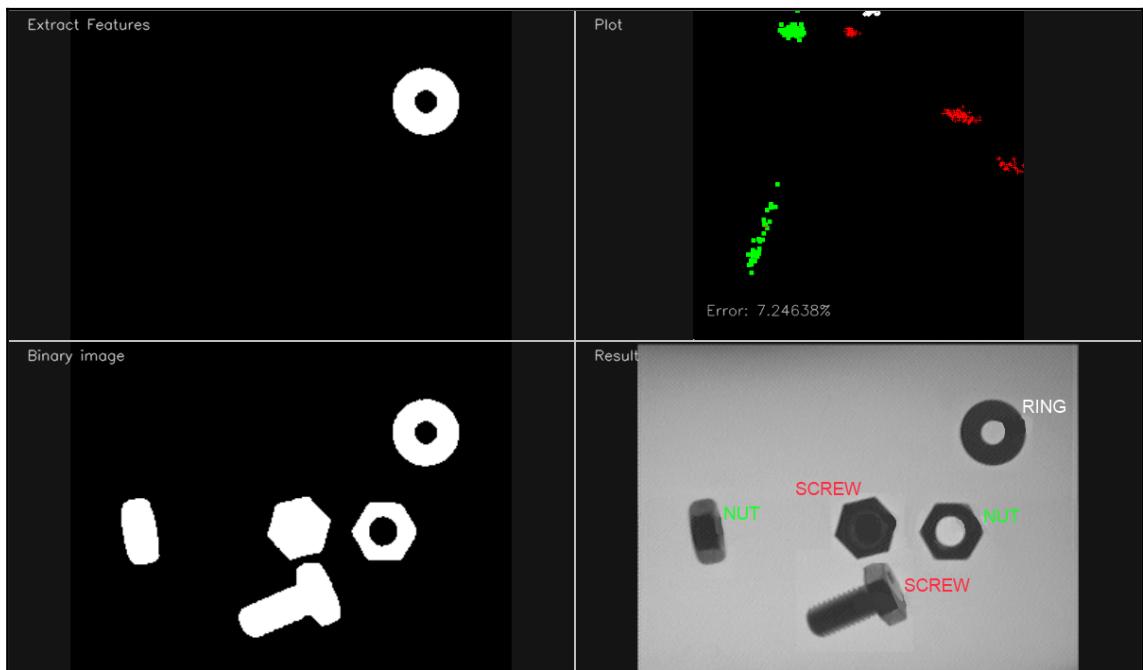
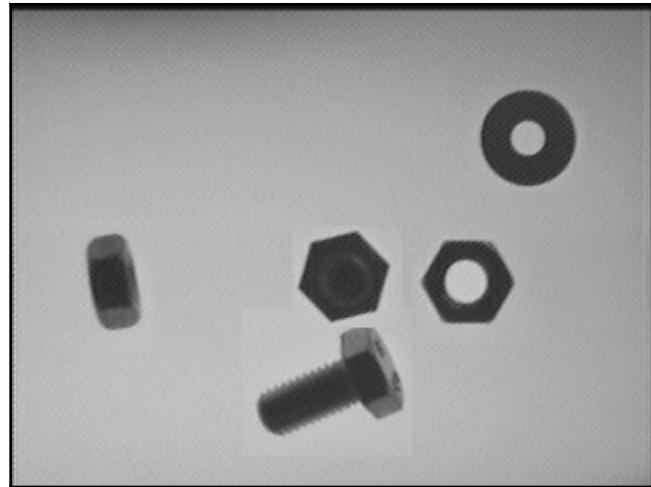




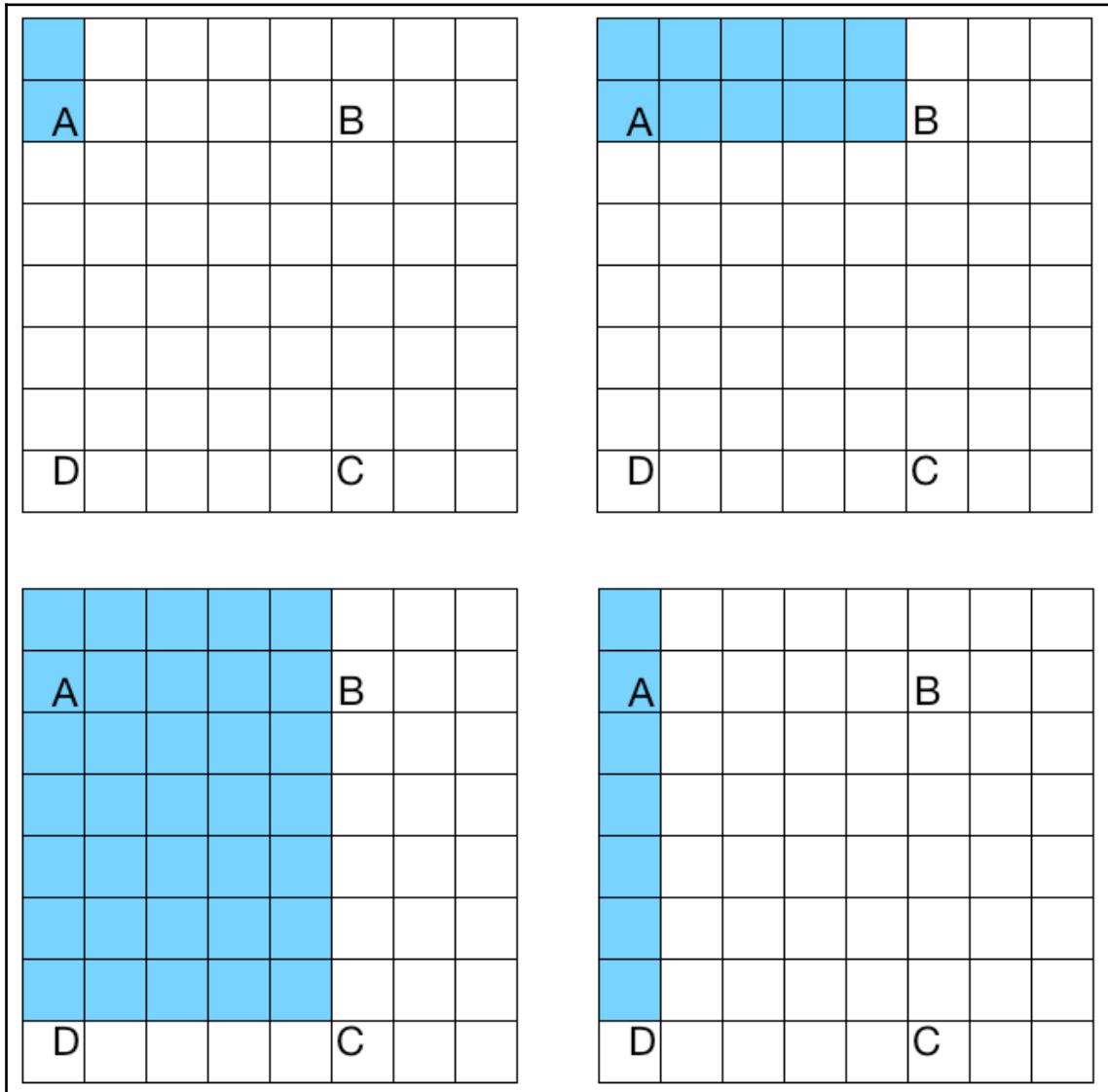


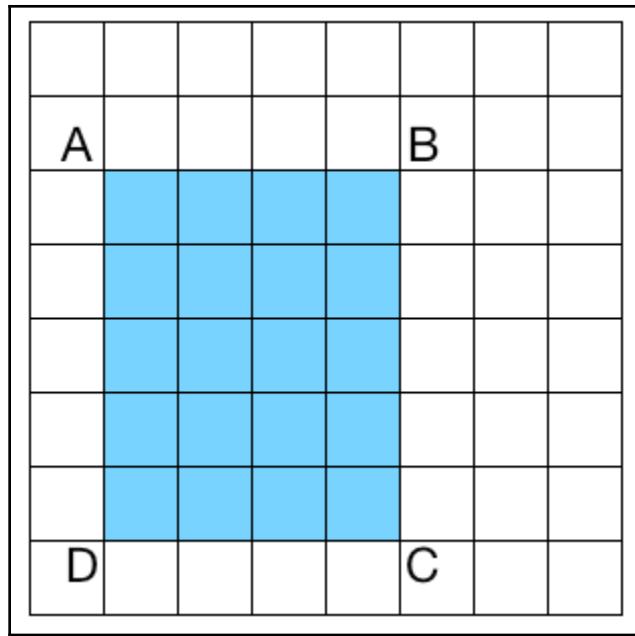


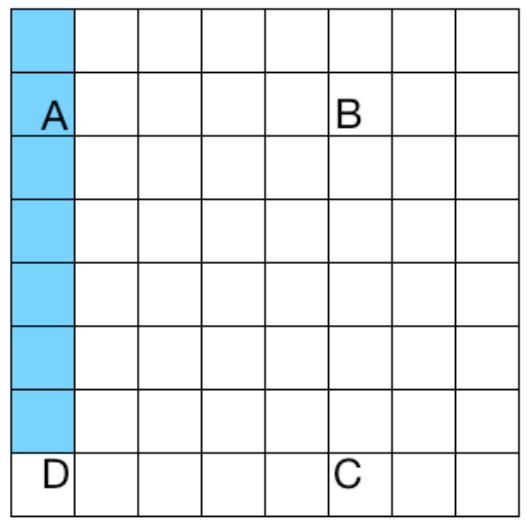
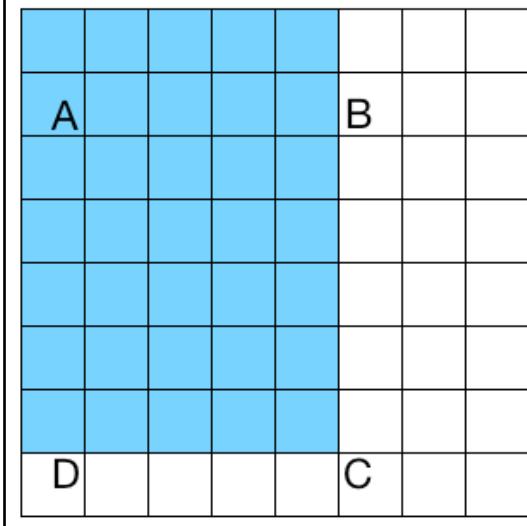
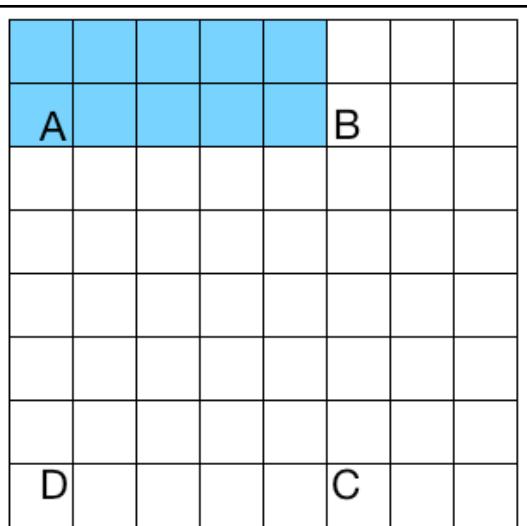
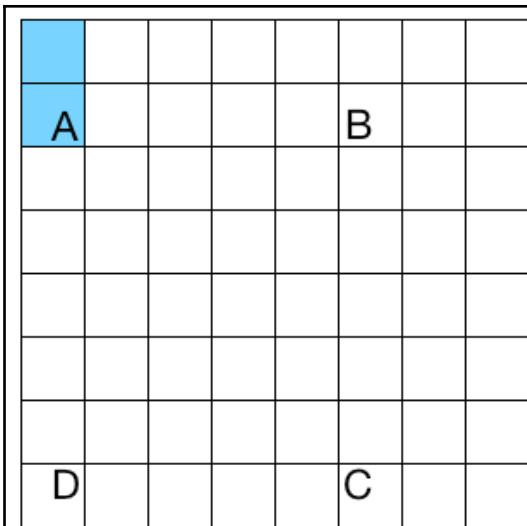




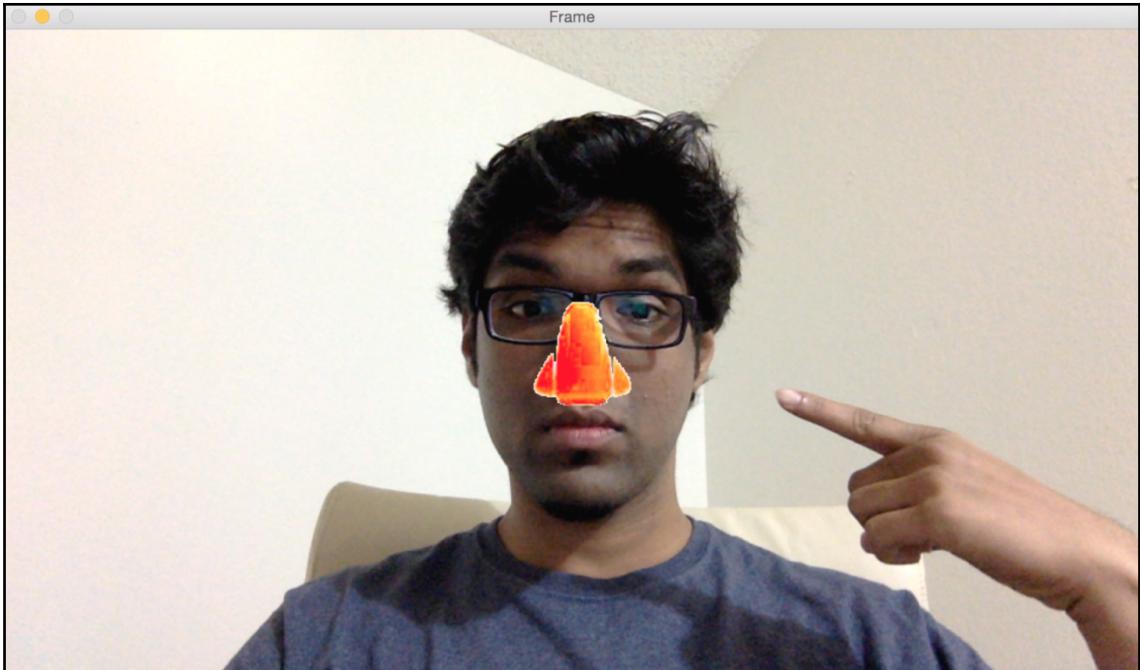
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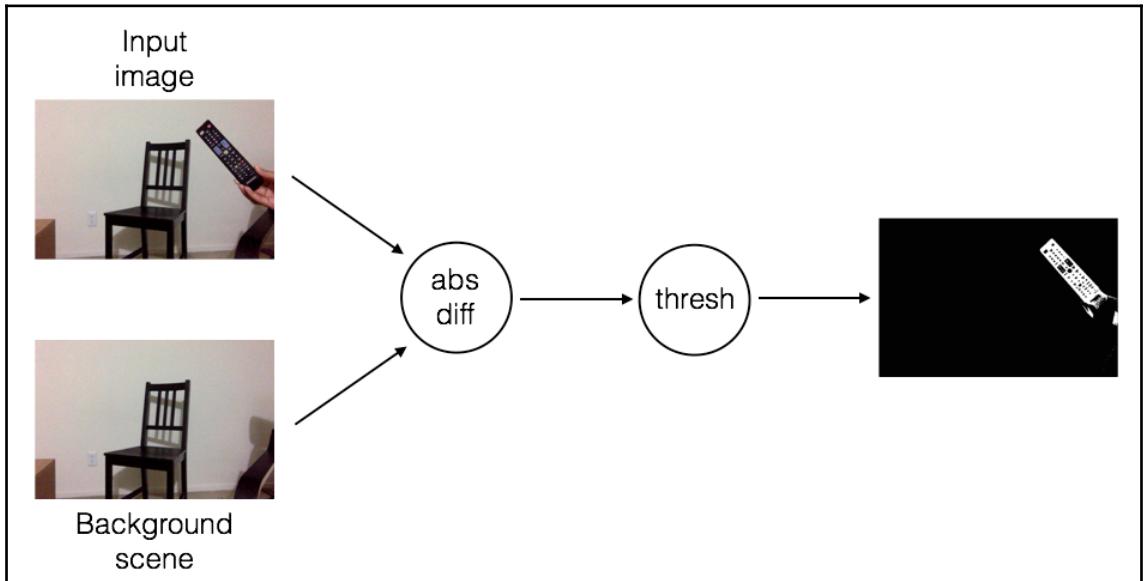
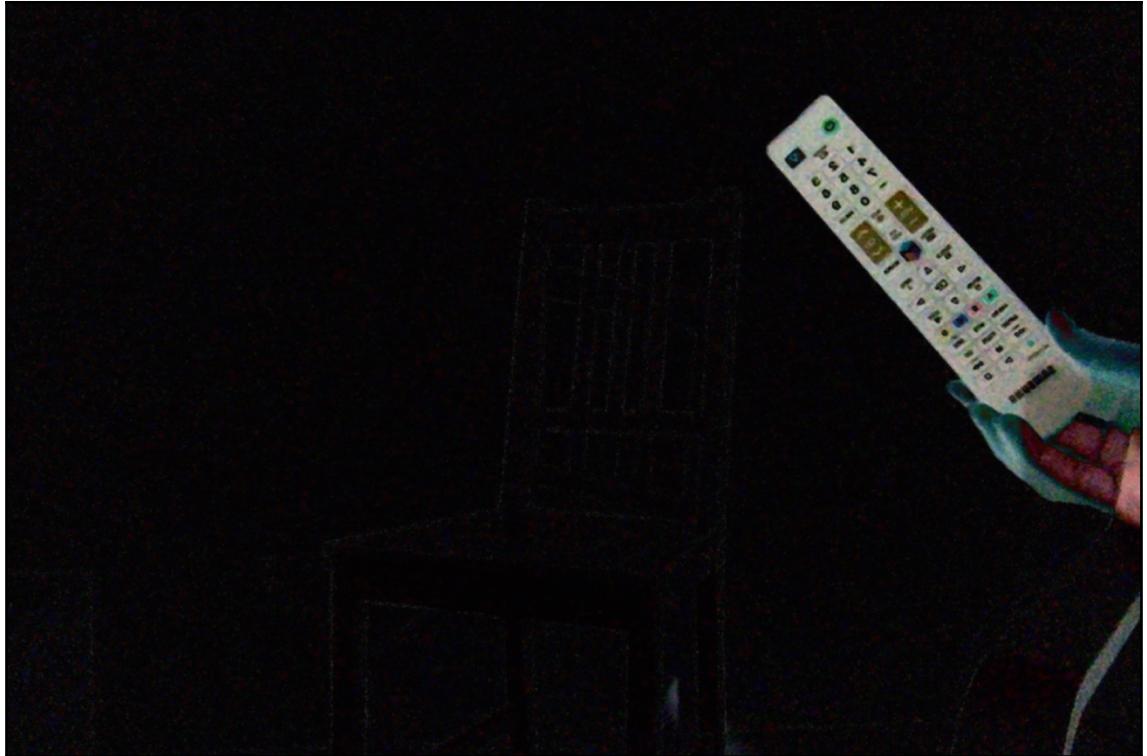




Chapter 8: Video Surveillance, Background Modeling, and Morphological Operations

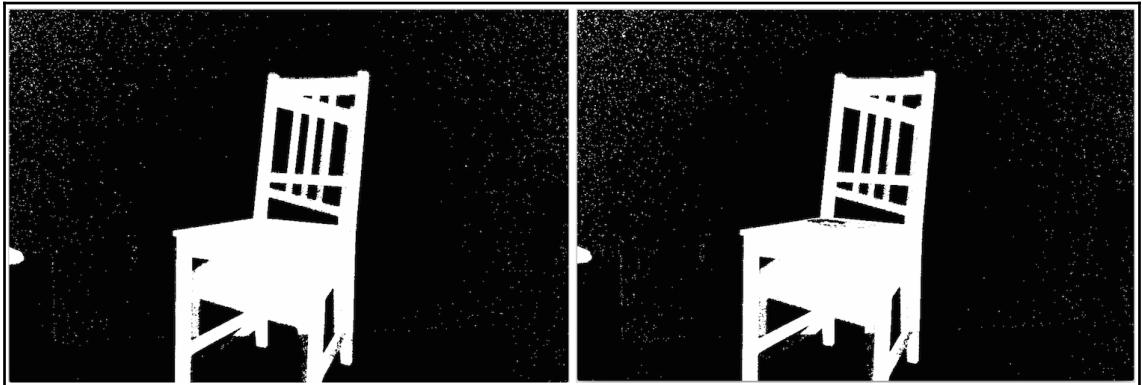


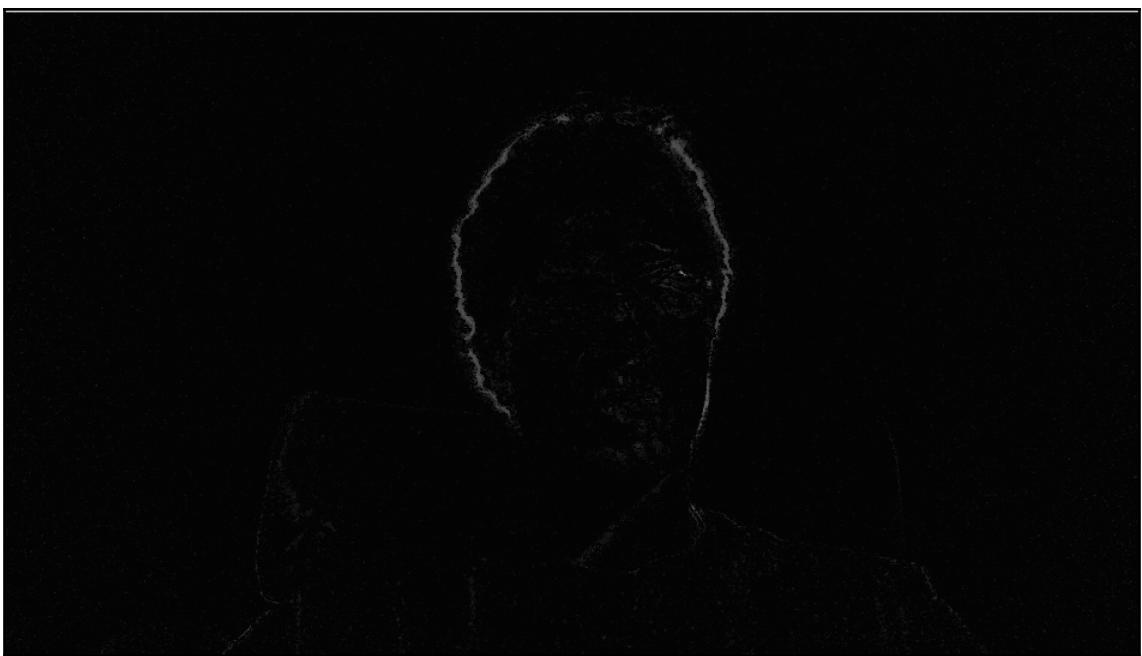


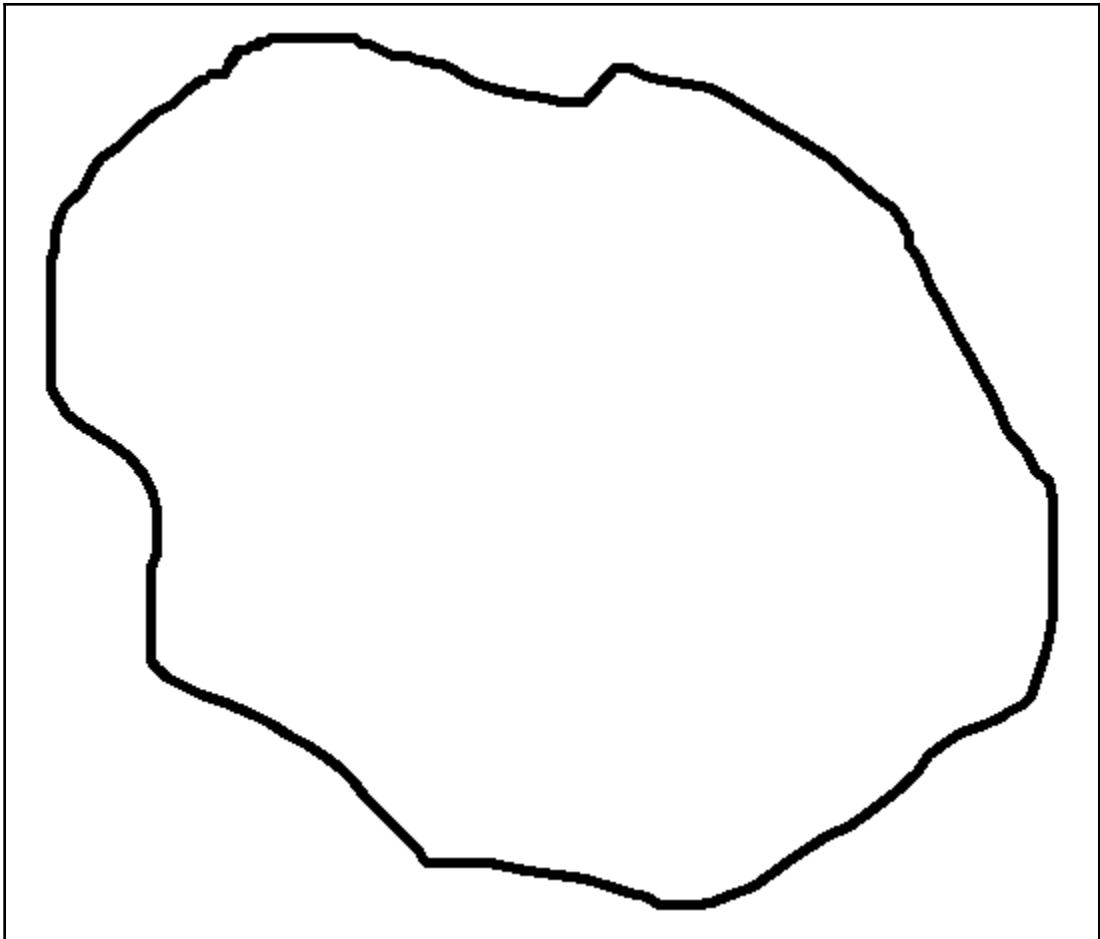


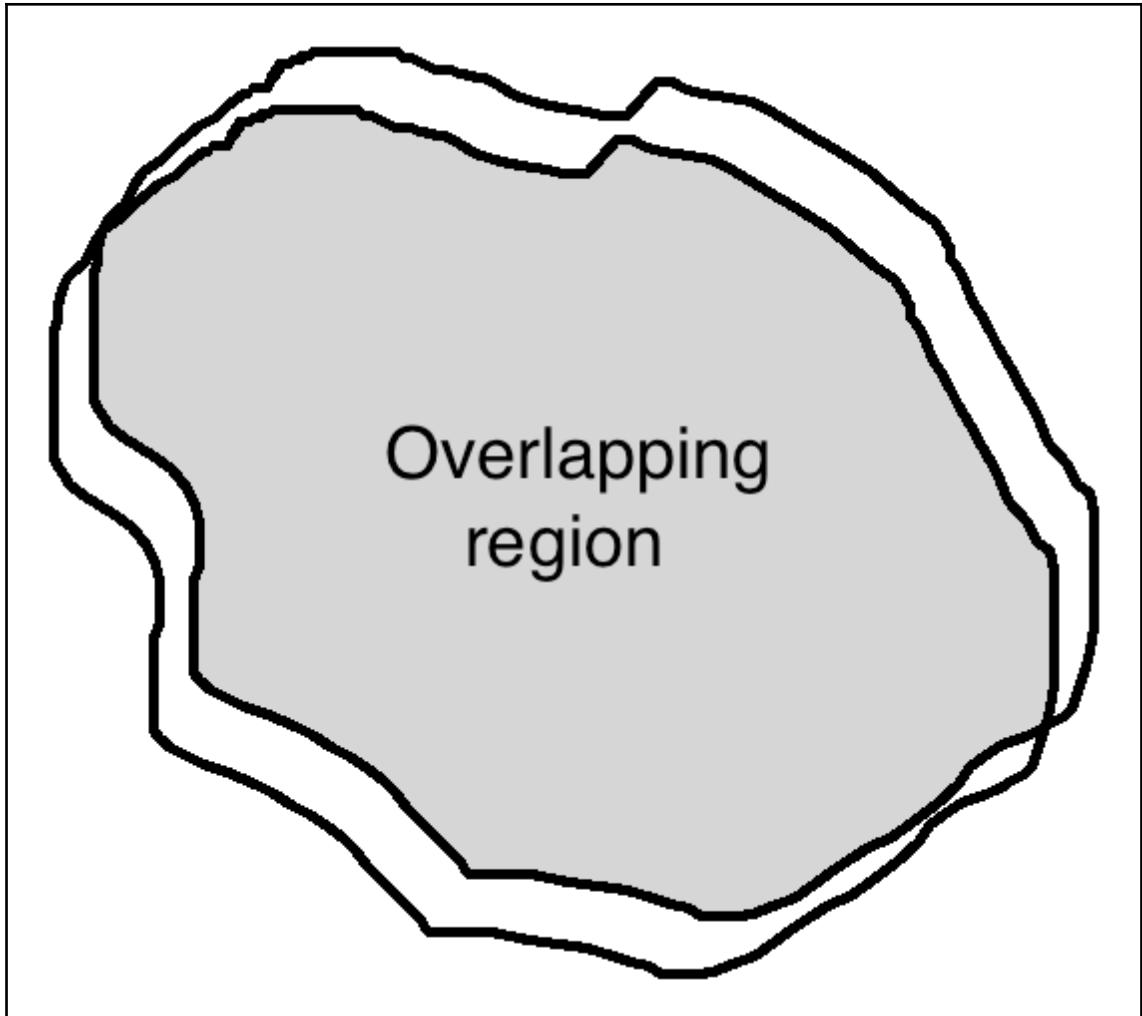




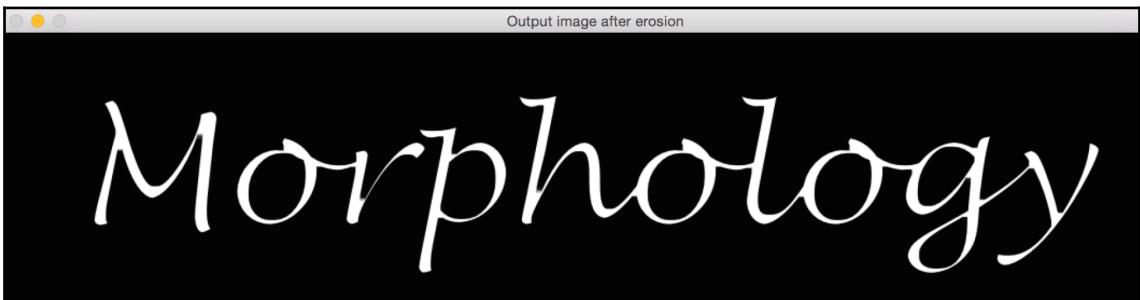
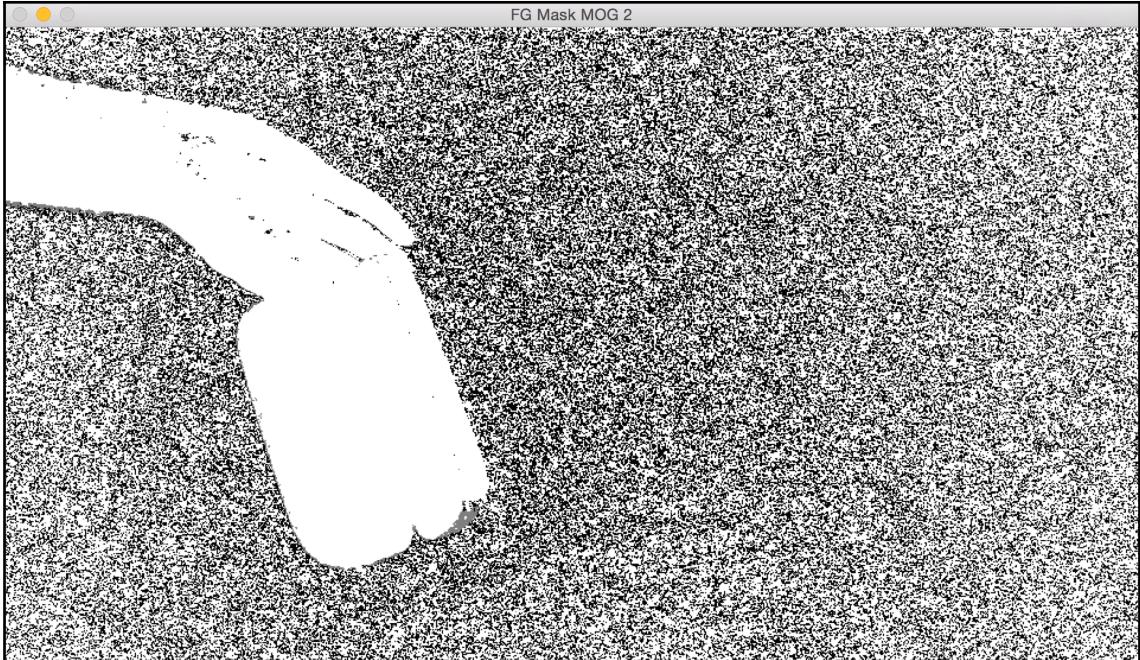


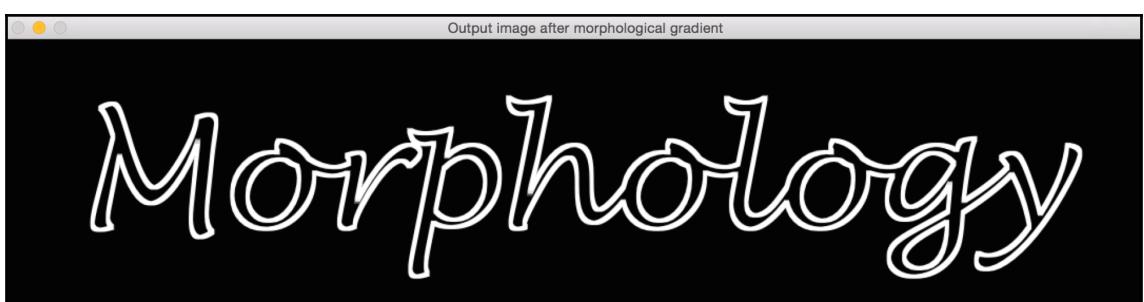
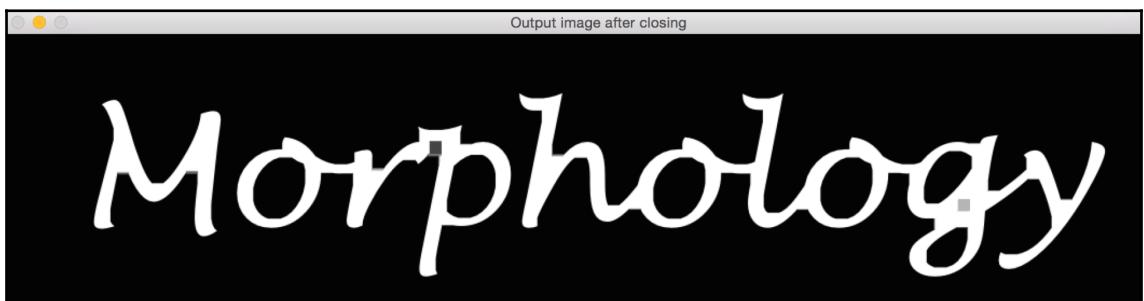
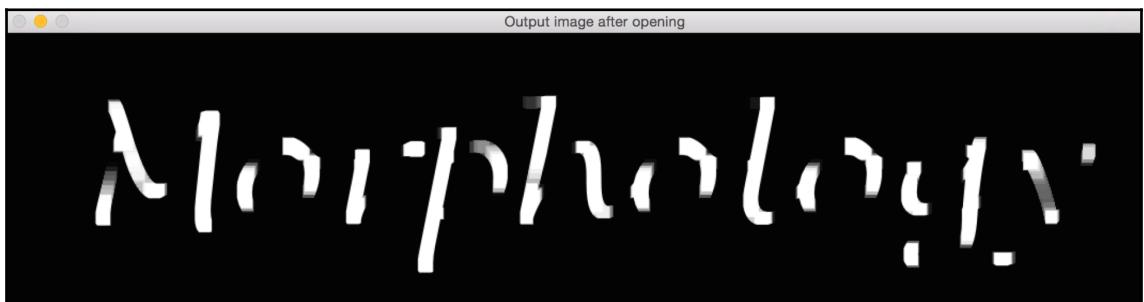
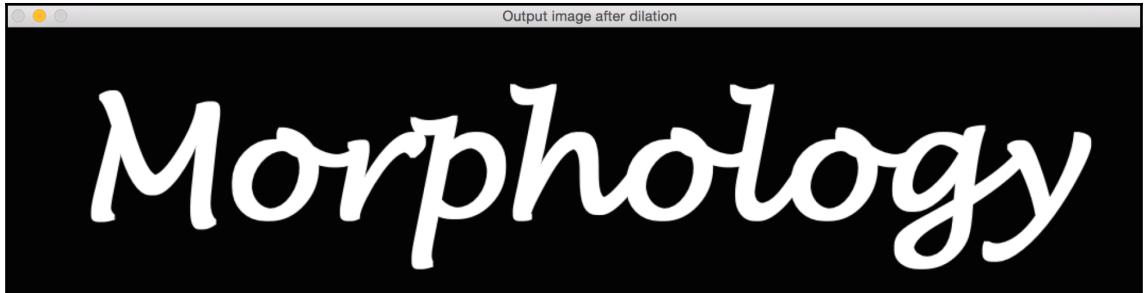


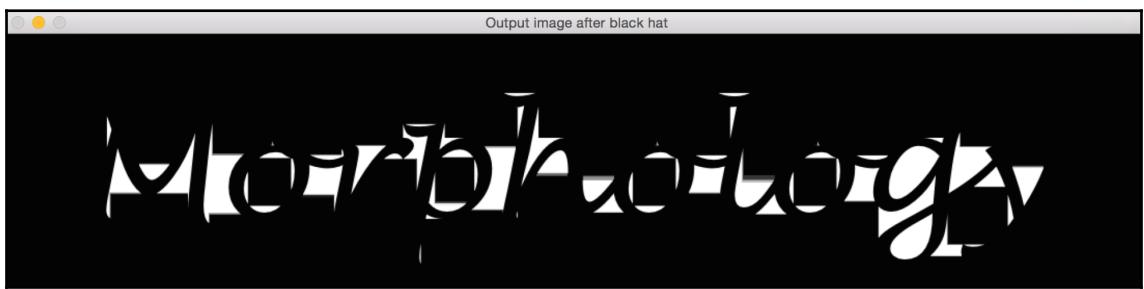
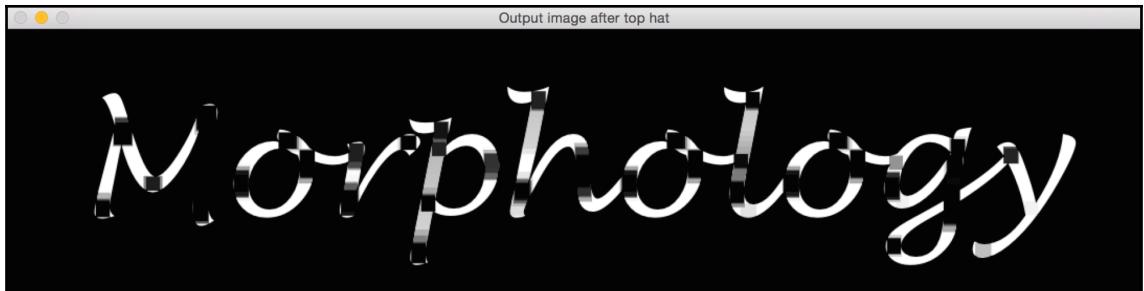






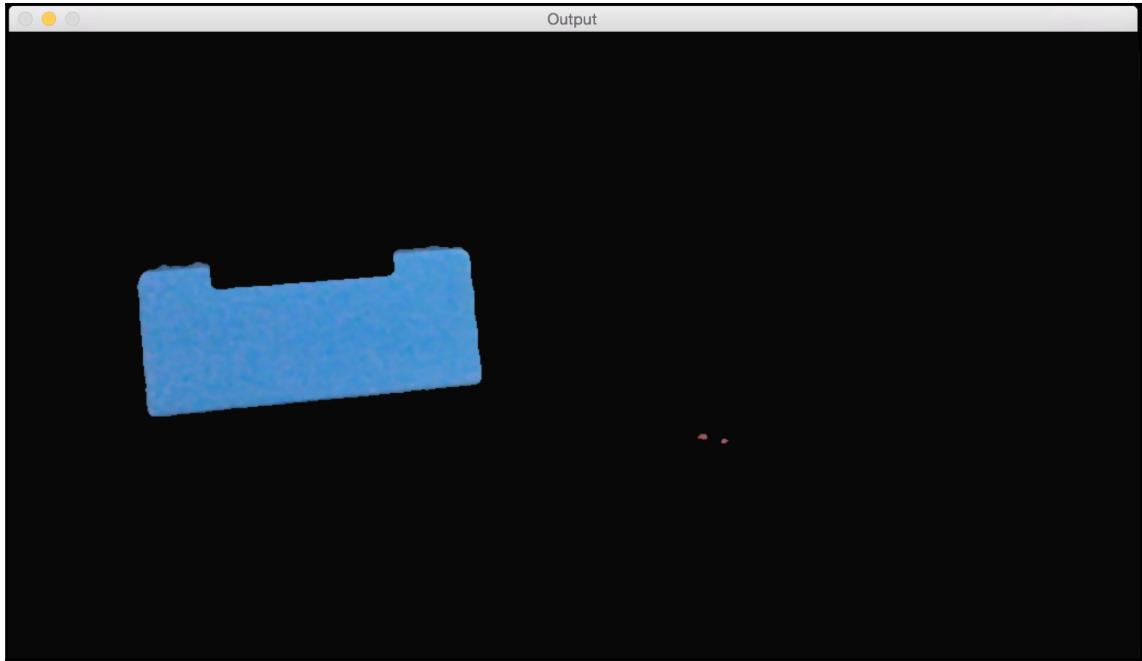






Chapter 9: Learning Object Tracking

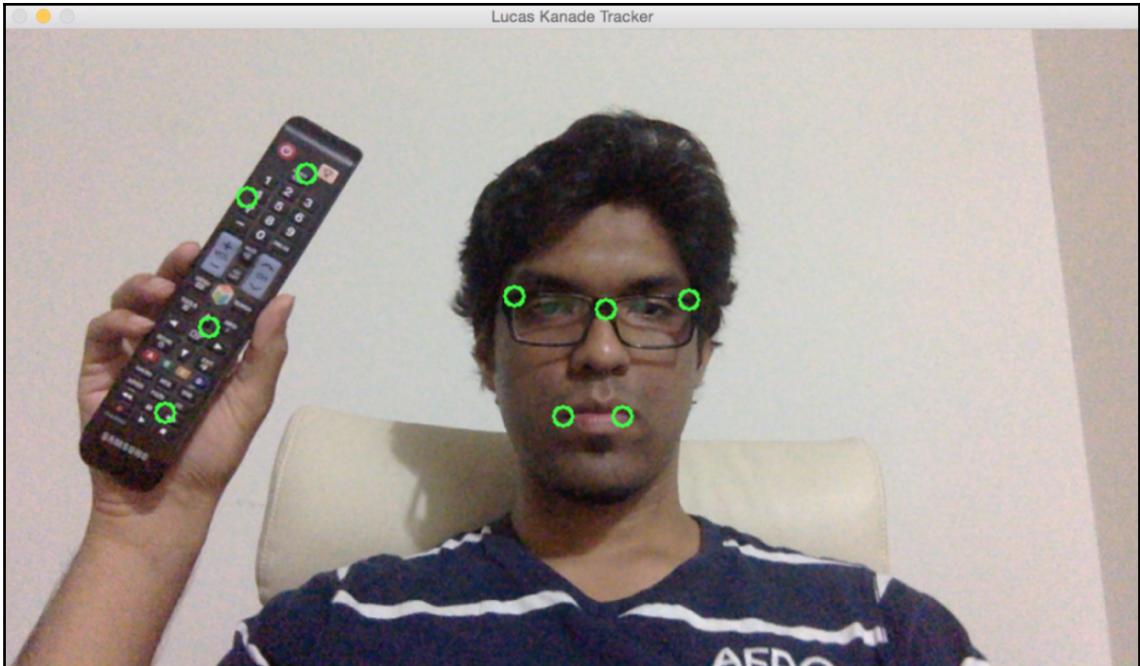


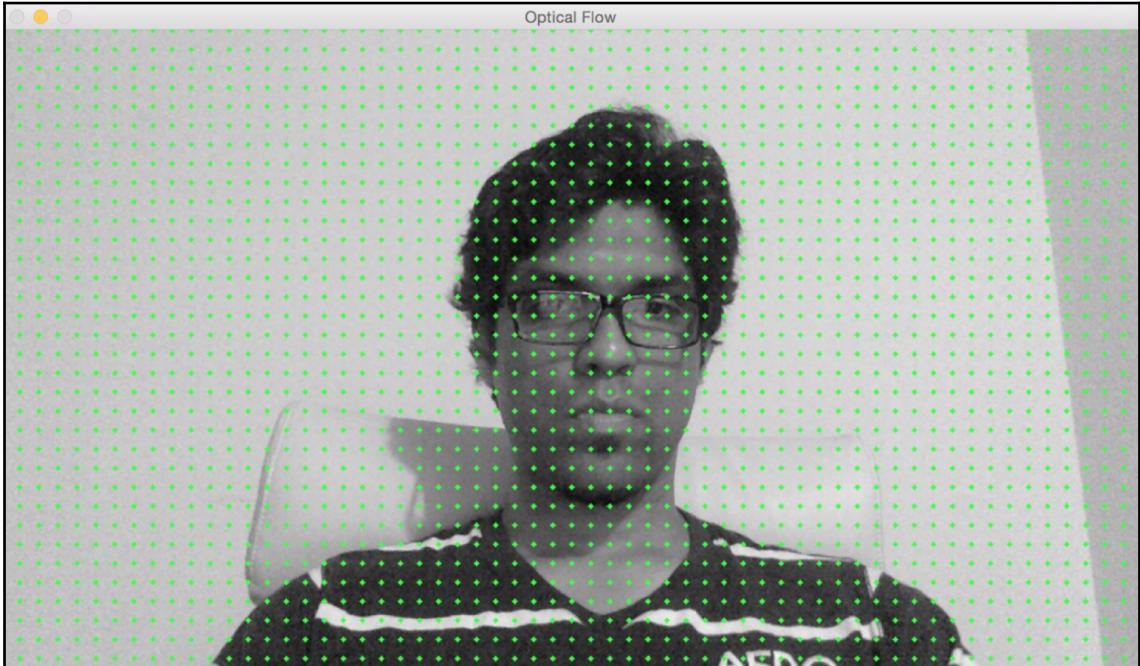
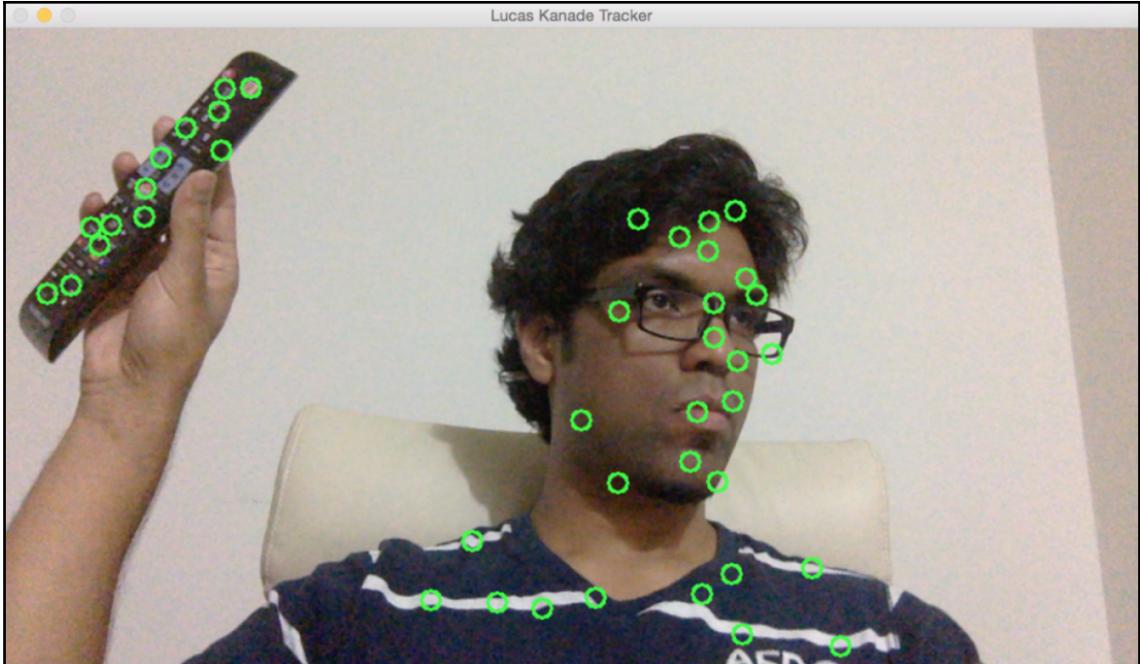


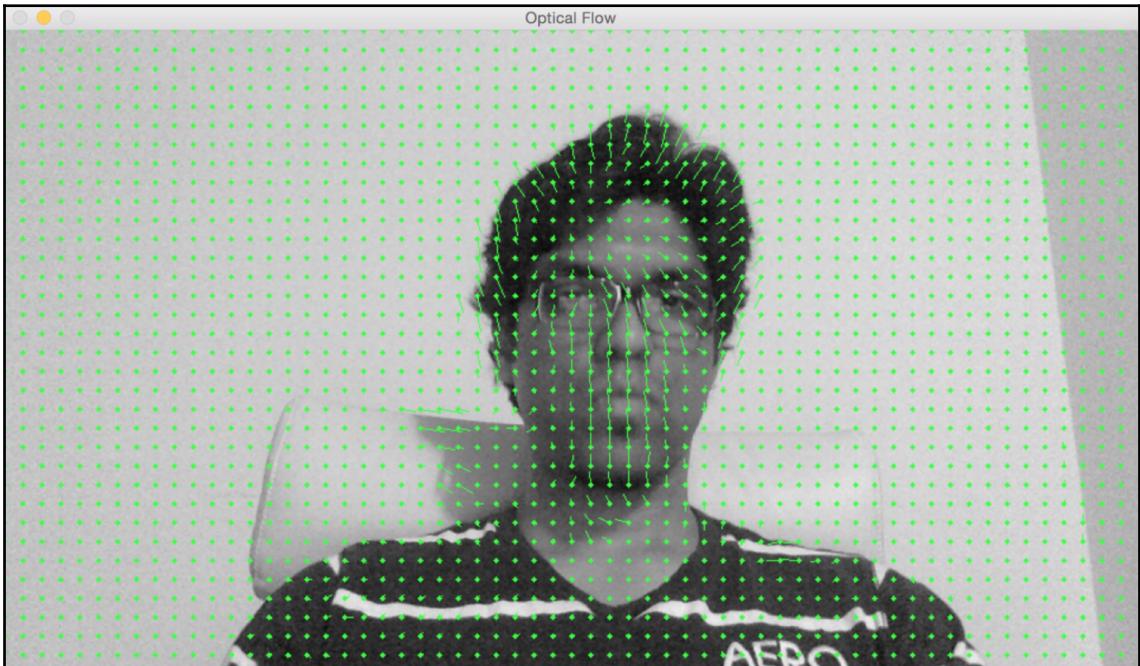
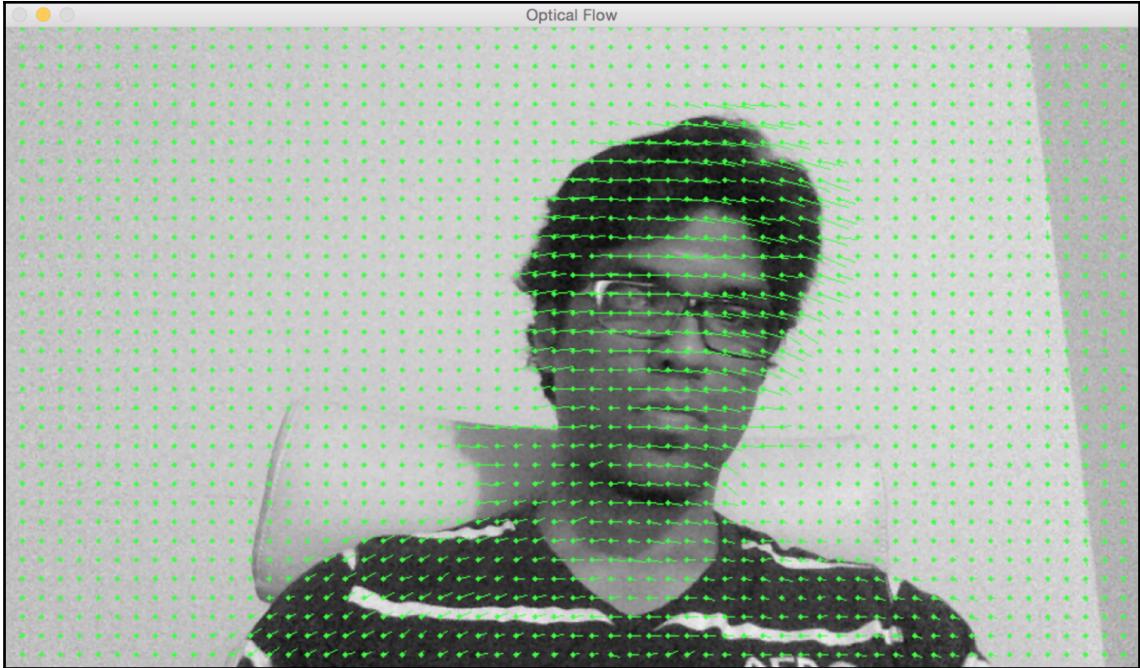












Chapter 10: Developing Segmentation Algorithms for Text Recognition

ATENÇÃO



Leve este cartão com você, pois ele é o comprovante para a retirada do veículo.



Nossa responsabilidade não abrange objetos ou pertences deixados no interior do veículo, assim como eventuais quebras e/ou defeitos mecânicos, já que por razões operacionais nossos funcionários estão impossibilitados de verificar tais itens.



O usuário é responsável pelos danos que vier a causar a outro veículo ou às instalações e equipamentos do estacionamento.

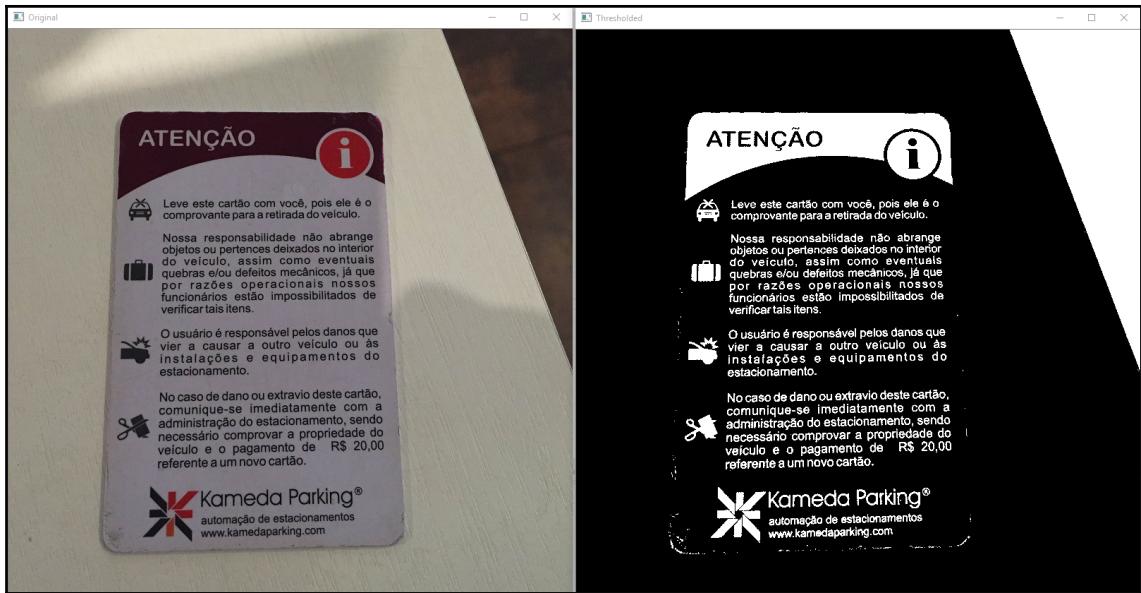


No caso de dano ou extravio deste cartão, comunique-se imediatamente com a administração do estacionamento, sendo necessário comprovar a propriedade do veículo e o pagamento de R\$ 20,00 referente a um novo cartão.

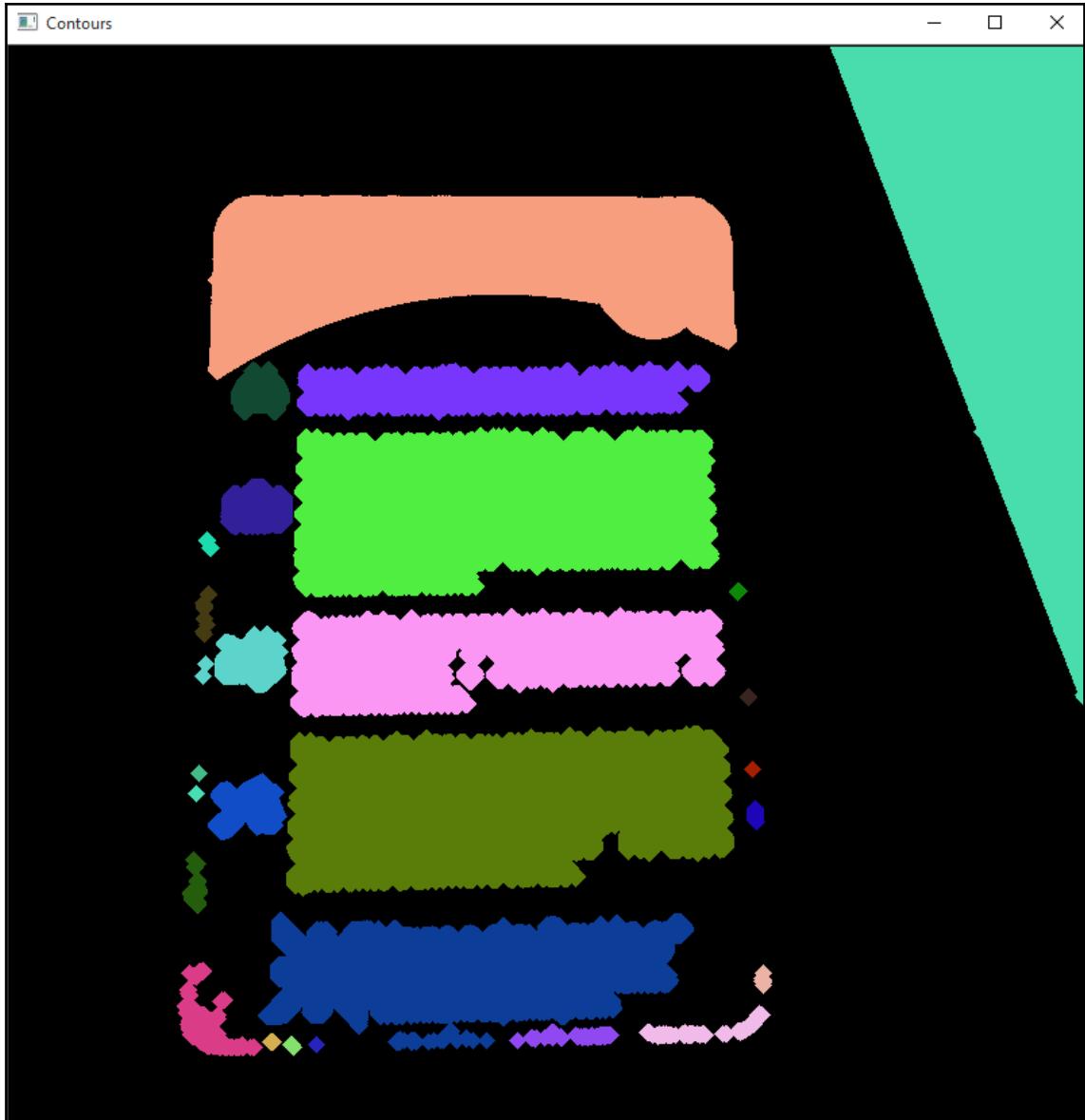


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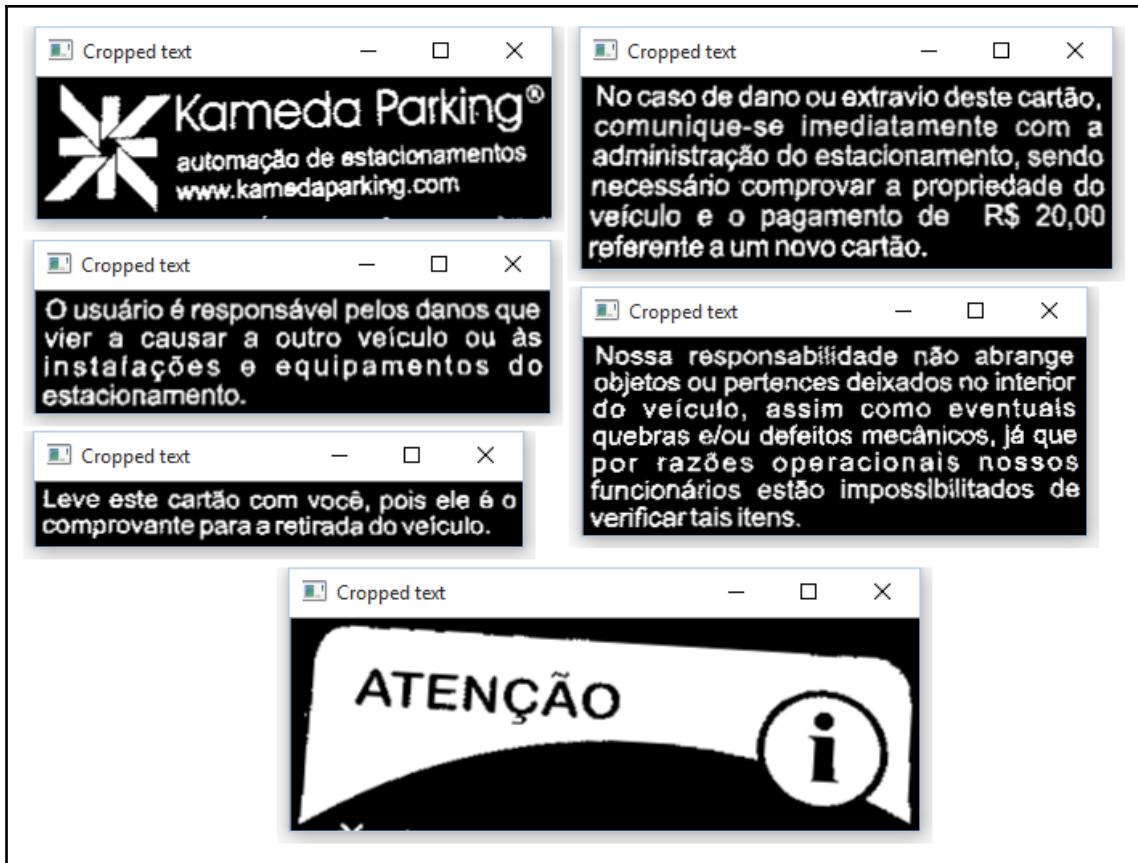
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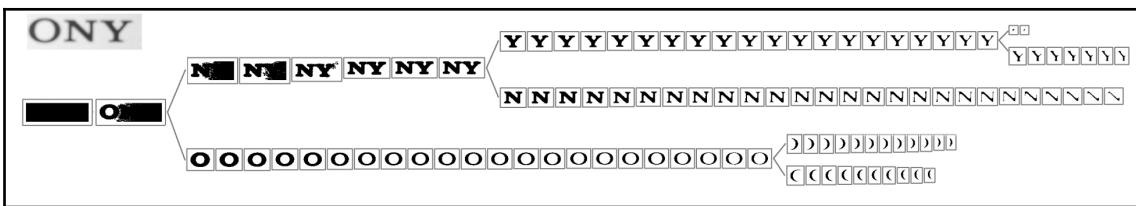






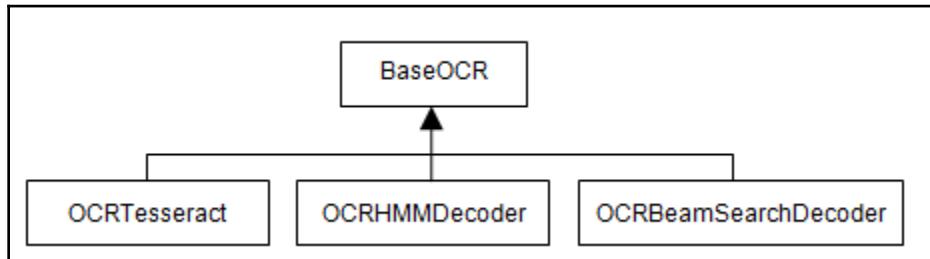


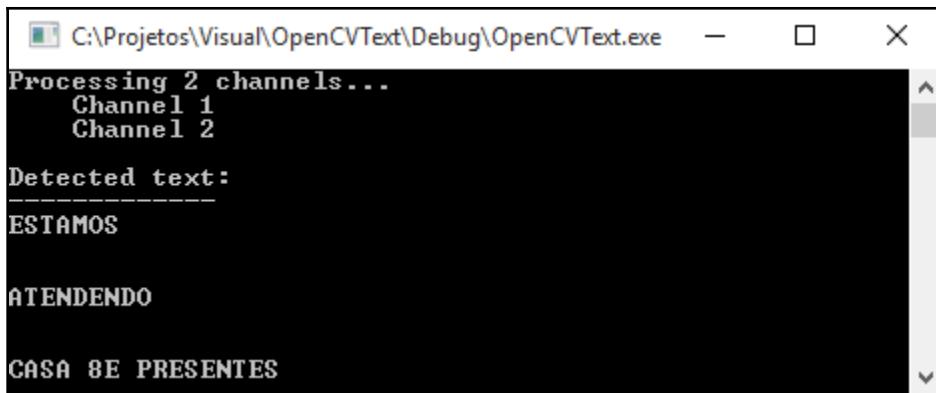
Chapter 11: Text Recognition with Tesseract



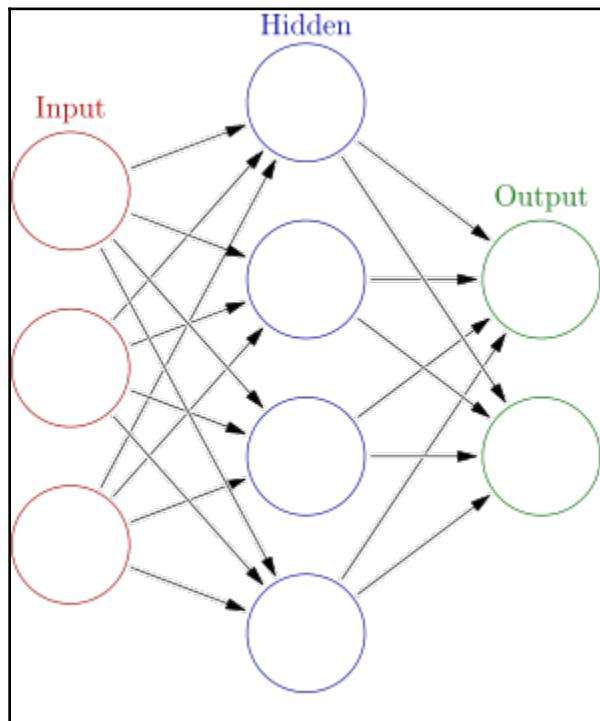


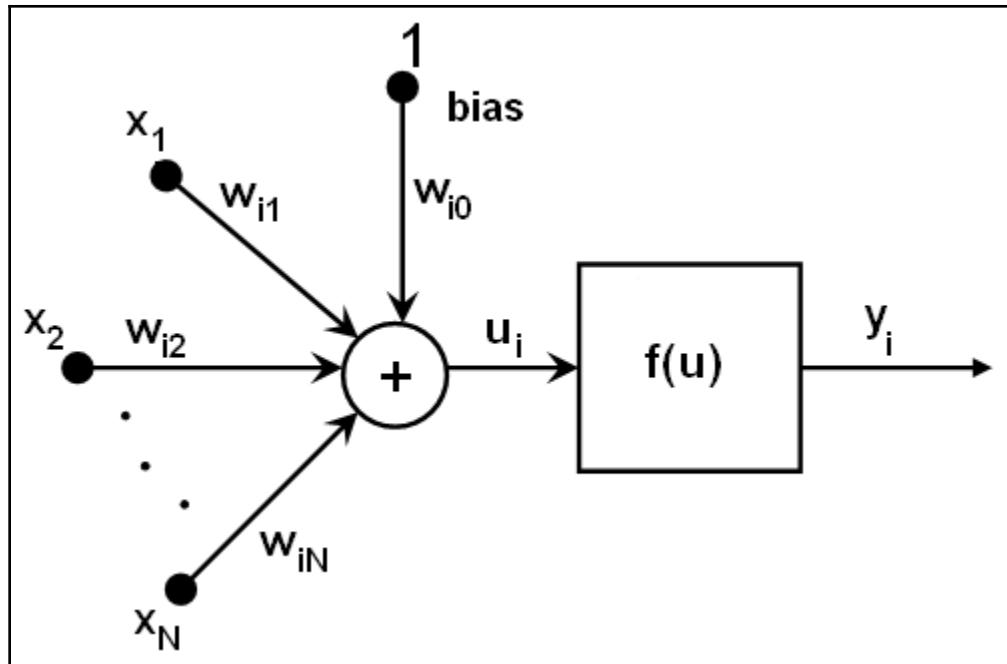




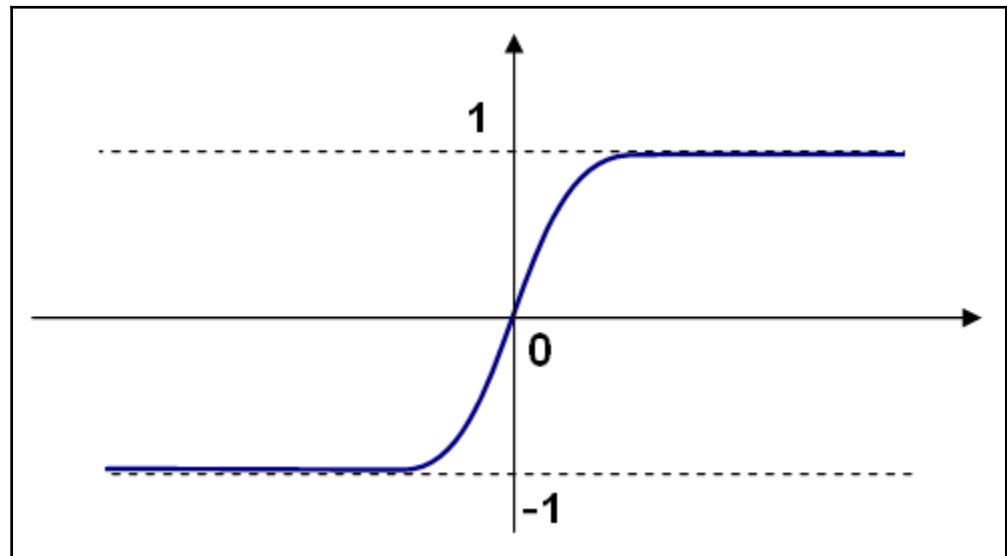


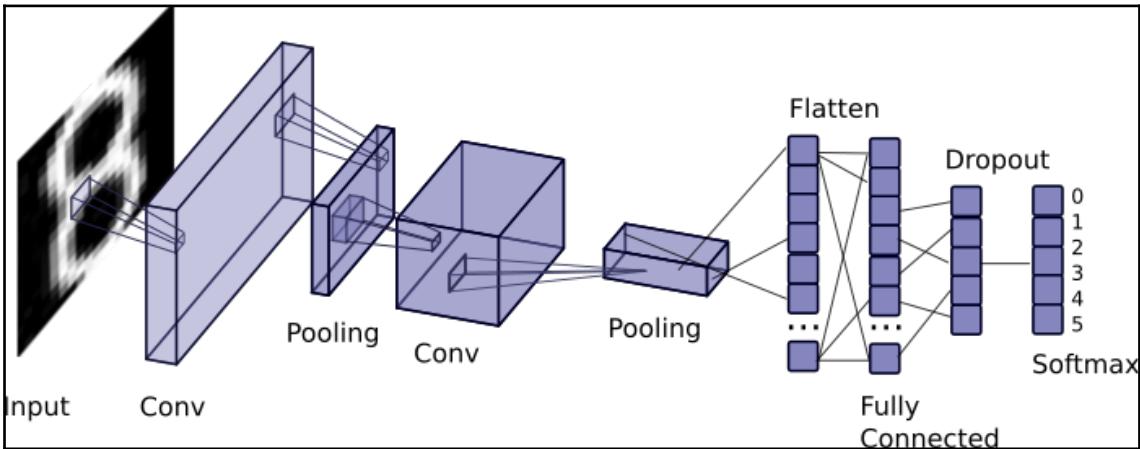
Chapter 12: Deep Learning with OpenCV

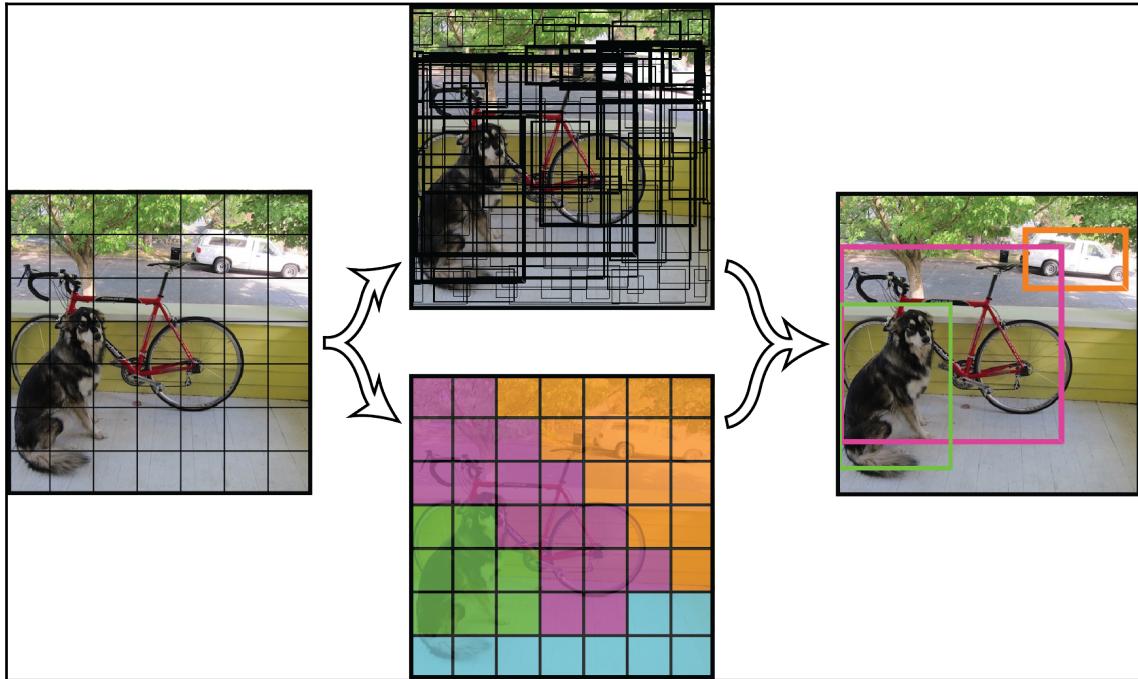
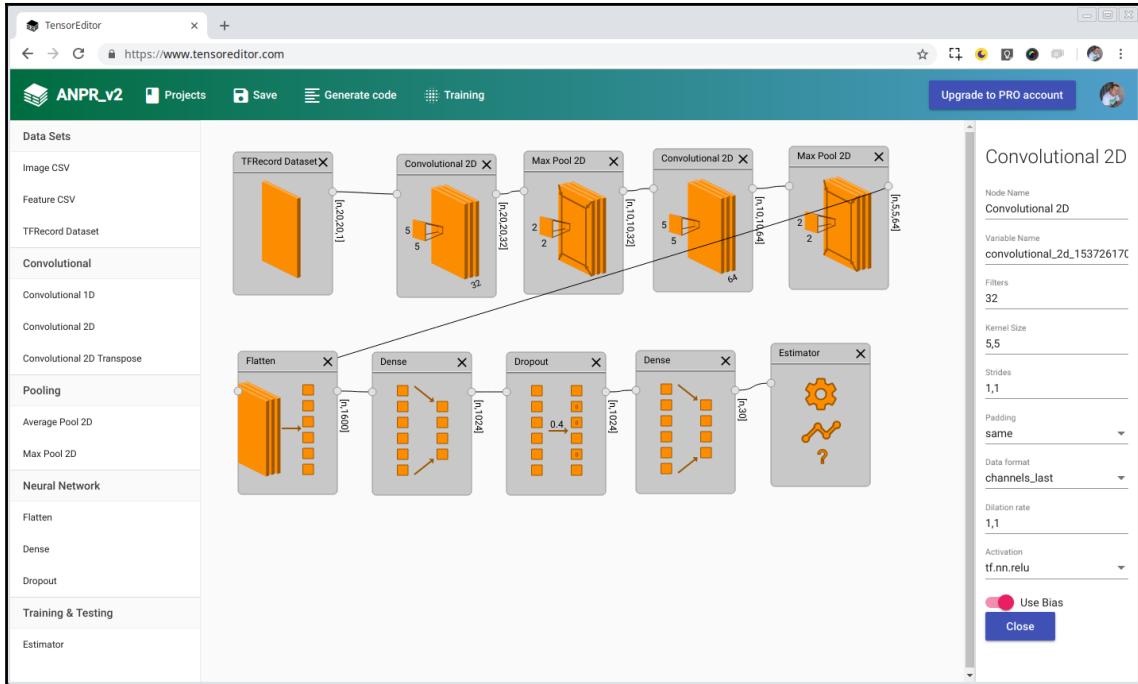


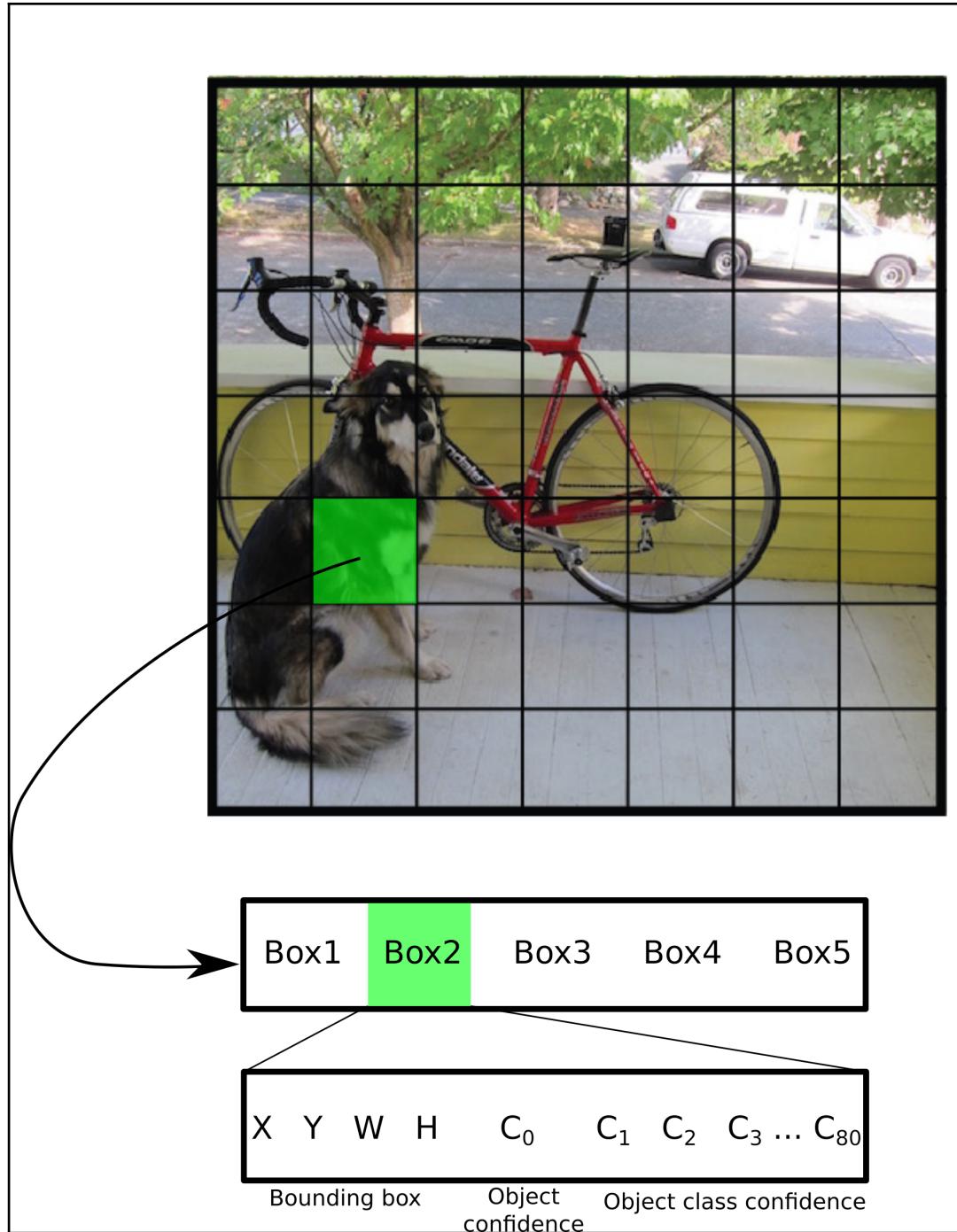


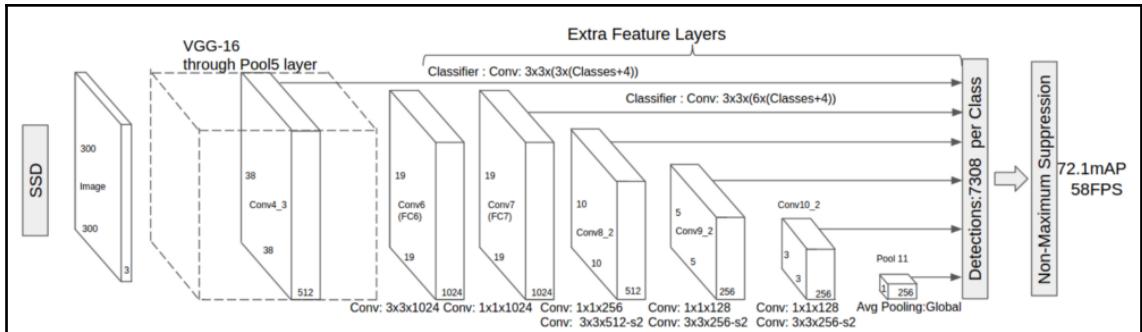
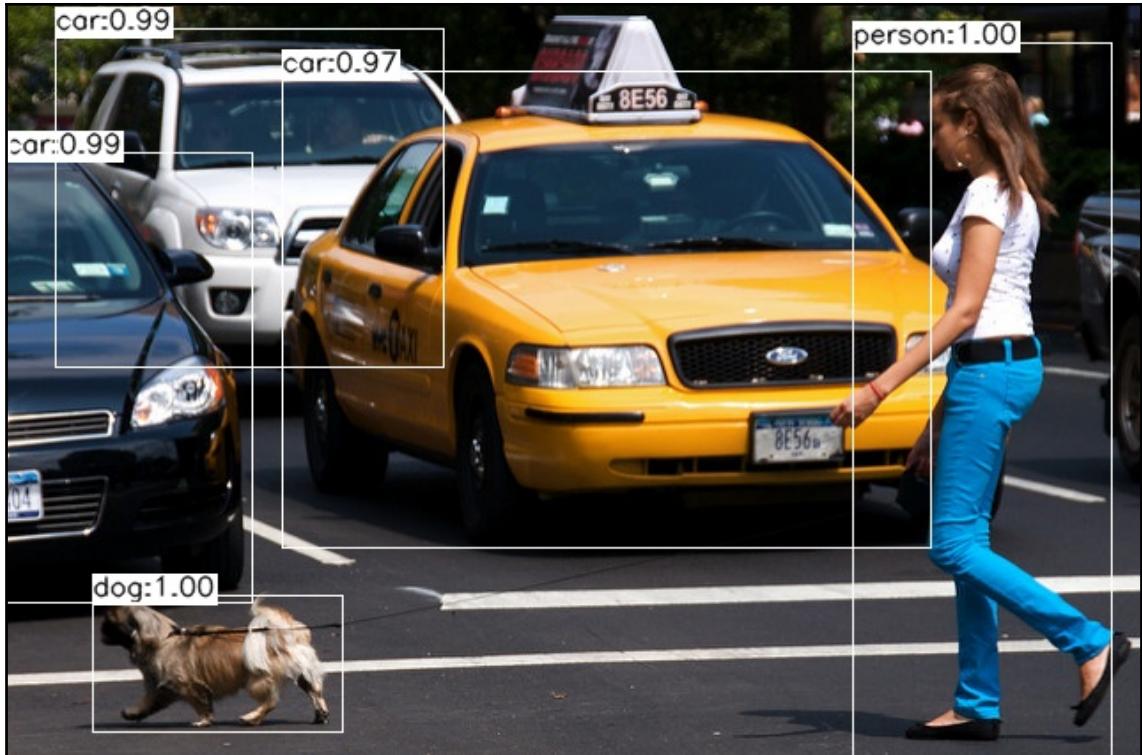
$$y_i = f(bias * W_{i0} + X_1 * W_{i1} + X_2 * W_{i2} + \dots + X_n * W_{in})$$

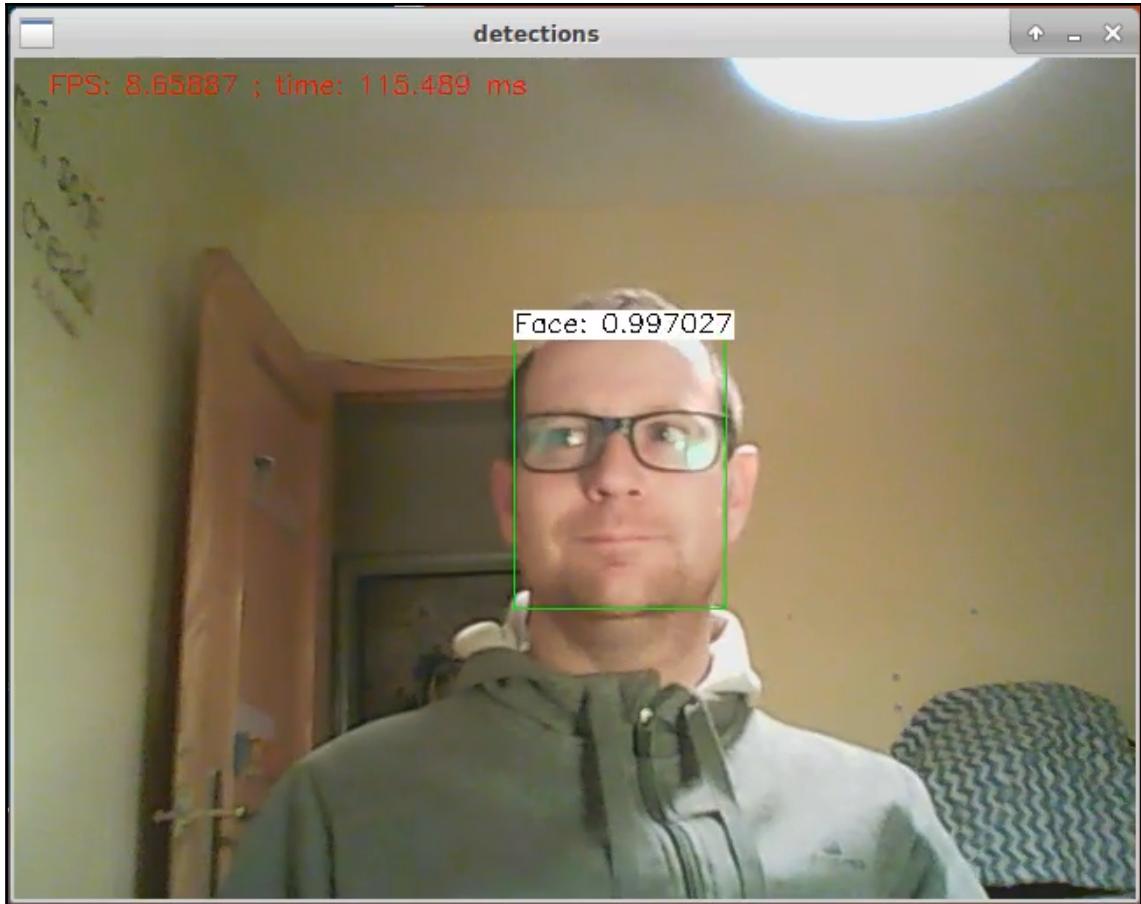












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