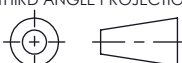



NOTES - (UNLESS OTHERWISE SPECIFIED)

1. ALL DIMENSIONS IN MILLIMETERS.

2. GD&T AS PER ISO1101-2004.

ITEM NO.	PART NUMBER	DESCRIPTION	QTY.
1	Worm Drive Motor		1
2	Motor Adapter	PART DESCRIPTION	1
3	Side Panel	PART DESCRIPTION	2
4	Drive Gear	PART DESCRIPTION	1
5	Square Bar	PART DESCRIPTION	1
6	Foam		4
7	Foam Holder	PART DESCRIPTION	3
8	Ball Bearing		1
9	Bearing Connector	PART DESCRIPTION	1

<div>THIRD ANGLE PROJECTION</div> <div></div>		<div>THIS DOCUMENT IS ISSUED IN STRICT CONFIDENCE ON CONDITION THAT IT IS NOT COPIED, REPRINTED, OR DISCLOSED TO A THIRD PARTY EITHER WHOLLY OR IN PART WITHOUT THE WRITTEN CONSENT OF UNIVERSITY OF CANTERBURY</div>		<div>UNIVERSITY OF CANTERBURY</div> <div>DEPARTMENT OF MECHANICAL ENGINEERING</div>		<div></div> <div>UNIVERSITY OF CANTERBURY</div> <div><small>Te Pihema Kaitiaki o Aotearoa</small></div> <div><small>THE UNIVERSITY OF CANTERBURY</small></div>	
<div>MATERIAL</div> <div>SEE PART DRAWINGS</div>				<div>Collection Method</div>			
<div>FINISH</div> <div>SEE PART DRAWINGS</div>				<div>DESIGN</div> <div>Robocup Team 6</div>	<div>DWG NO.</div> <div>SpinnerAttachmentAssem</div>	<div>REV</div> <div>REV1</div>	
<div>TOLERANCE (UNLESS OTHERWISE SPECIFIED)</div>				<div>DRAWN</div> <div>Ethan Te Puni</div>	<div>PROJECT</div> <div>Robocup</div>		
<div>DECIMAL mm</div> <div>.X ± .1 .XX ± .03 .XXX ± .010 ANG. ± 1°</div>				<div>SUPERVISOR</div> <div>XXX</div>	<div>ISSUE DATE</div> <div>2/10/21</div>	<div>DRAWING</div> <div>NOT TO SCALE</div>	<div>SHEET</div> <div>1 OF 2</div>