RODCUP Documentation

Parts Summary





Contents

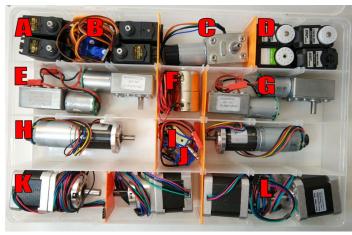
| Parts Summary Page 1 | 03 |
|-----------------------------|----|
| Parts Summary Page 2 | 04 |
| Actuators | 05 |
| Sensors | 06 |
| Hardware Box 1 | 07 |
| Hardware Box 2 | 08 |
| Hardware Box 3 | 09 |
| Green Box | 10 |
| Blue Box | 11 |
| Additional Materials | 12 |
| Services Available | 12 |
| Tools Available | 12 |





Parts Summary

Actuators



Sensors



Hardware Box 1



Hardware Box 2



Hardware Box 3



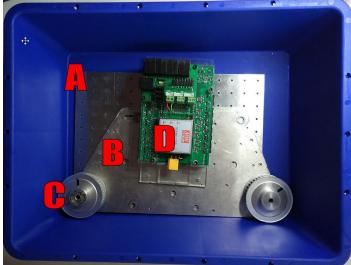




Green Box

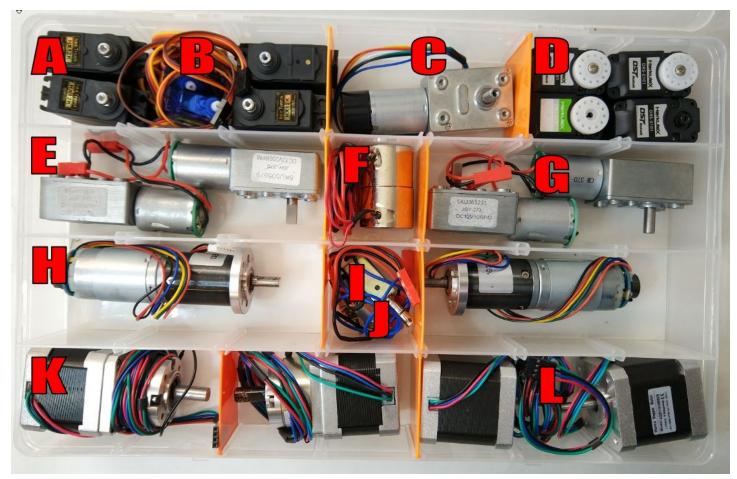
Blue Box







Actuators 🔝



| ID (| Qty | Cost | Description | Part Number | Major Parameters |
|------|-----|------|---|---------------|------------------------------|
| A | 4 | 14.0 | Standard servo | HX12K | 7.4V, 9.4kg.cm |
| В | 2 | 02.5 | Small servo | SG90 | 5V 1.5kg.cm |
| C | 1 | 22.0 | DC Motor 90RPM, includes gearbox and encoder | JGY-370 | 12V, 90RPM |
| D | 4 | 58.0 | Smart servo | DRS-0101 | 7.4V, 12kg.cm, Gear: 1:266 |
| E | 2 | 15.0 | DC Motor 200RPM, includes gear box | SKU505979 | 12V, 200RPM |
| F | 2 | 06.6 | Electromagnet | JK-P30/22 | 12V, 0.4A, 10kg |
| G | 2 | 15.0 | DC Motor 10RPM, includes gearbox | SKU365231 | 12V, 10RPM |
| Η | 2 | 70.0 | DC Motor 143RPM, includes gearbox and encoder | 28PA51G | 12V, 143RPM, 3.6A, 5.5kgf.cm |
| I | 1 | 03.8 | Solenoid | TAU-0530T | 12V, 1.5A, 0.4N-7N |
| J | 1 | 04.8 | Small DC Motor with gearbox | N20 | 12V, 0.3A, 148RPM |
| K | 2 | 50.0 | Stepper motor with gearbox NEMA17 | 36PA5.2G/42BY | YG40-160-4A 1.6A,1.8deg/step |
| L | 2 | 32.0 | Stepper motor NEMA17 | 42BYGHM809 | 1.7A, 0.9deg/step |

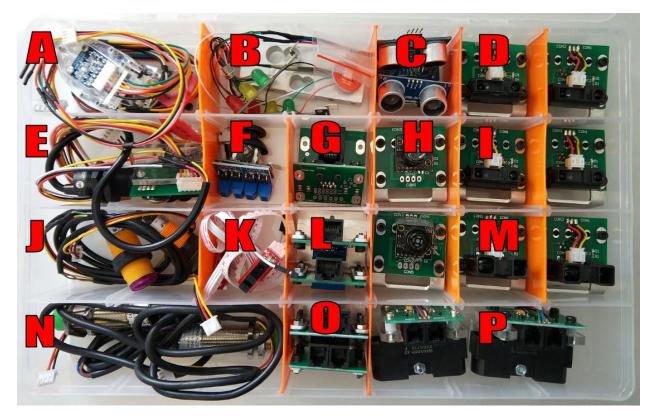
From Green box

| M | 1 | 60.0 | Large Servo | RDS5160 | 7.4V, 5A, 65kg.cm, 270deg |
|---|---|------|-------------|----------|---------------------------|
| N | 1 | 01.6 | Speaker | MP001193 | 0.5W, 8ohm |
| O | 1 | 04.0 | Fan | MC32893 | 12V, 0.15A |





Sensors %



| ID | Qty | Cost | Description | Part Number | Major Parameters |
|----|-----|------|---|-------------------|-------------------------|
| A1 | 1 | 14.0 | Color Sensor | TCS34725 | |
| A2 | 1 | 36.0 | IMU | SEN0253 | BNO055+BMP280 |
| A3 | 1 | 02.0 | Load Sensor | HX711 | |
| B1 | 2 | 03.5 | Load Cell | | 1kg, 10kg |
| B2 | 5 | 00.5 | Microswitches | SV-163-1C25 | |
| C | 4 | 01.8 | Low cost ultrasound sensors | HC-SR04 | |
| D | 2 | 0.80 | IR Distance Sensor | 0A41SK | 4-30cm |
| E1 | 1 | 30.0 | IR Camera | SEN0158 | |
| E2 | 2 | 04.8 | TOF Camera I2C | VL53L0XV2 | |
| E3 | 1 | 60.0 | TOF Camera Serial | TFmini | |
| F1 | 1 | 01.5 | Analogue Joystick | | |
| F2 | 1 | 01.5 | Digital Joystick | | |
| F3 | 1 | 02.2 | Rotary Encoder | | |
| F4 | 2 | 01.0 | Variable resistor | | 10k |
| F5 | 2 | 02.0 | Digital Switch | | |
| G | 2 | 02.5 | Digital Breakout board, Digital pullup | | |
| Н | 2 | 60.0 | Ultrasonic distance sensor | HRLV-MaxSonar-EZ0 | 300-5000mm` |
| I | 2 | 08.0 | IR Distance Sensor | GP2Y0A21YK0F | 10 to 80cm |
| J | 2 | 06.0 | IR Distance Sensor, Adjustable, Digital Out | | |
| K | 2 | 01.0 | Optical Endstop | | |
| L | 2 | 02.5 | Digital Breakout board | | |
| M | 2 | 08.0 | IR Distance Sensor | GP2Y0A02YK0F | 20-150cm |
| N | 2 | 25.0 | Inductive Proximity | | |
| O | 2 | 02.5 | Analogue Breakout board | | |
| P | 2 | 25.0 | IR Distance Sensor | 2Y0A710K | 100-500cm |
| | | | | | |





○ Hardware Box 1 ^{★★}



| ID | Qty | Cost | Description | Part Number | Major Parameters |
|----|-----|------|------------------------------|-------------|-------------------------|
| A1 | 1 | 02.2 | Anti Backlash Nut | | T8 screw Lead 8mm |
| A2 | 1 | 01.8 | Anti Backlash Nut | | T8 screw Lead 8mm |
| В | 2 | 03.5 | Trapezoidal lead screw block | | |
| C | 1 | 02.0 | Linear rail support block | | |
| D1 | 3 | 02.0 | Shaft Coupler | | |
| D2 | 2 | 01.0 | Shaft Coupler | | |
| E1 | 1 | 03.5 | Rod ends | | |
| E2 | 1 | 02.5 | Rod ends | | |
| F | 4 | 01.8 | Rigid Flange Coupling | | |
| G | 2 | 02.5 | Trapezoidal lead screw nut | | |
| Н | 4 | 01.2 | Linear Ball Bearings, | LM8UU, 8mm | |
| I1 | 1 | 02.2 | Servo arm Aluminum 25T | | |
| I2 | 1 | 05.0 | Servo arm Aluminum 25T Long | | |
| J | 2 | 02.5 | Pillow block bearing | KP08 | |
| K | 2 | 04.5 | Flange pillow block bearing, | KFL08 | |
| L | 4 | 8.00 | Plastic pulley wheels, Nylon | | |
| M | 4 | 00.6 | Aluminum 90 degree bracket | | |
| N | 6 | 02.5 | Pulley GT2 | | |
| O | 2 | 06.0 | Pulley XL | 20-XL-10BF | |
| P | 8 | 02.5 | Aluminum cutouts | | |
| Q | 6 | 02.5 | Aluminum cutouts | | |
| R | 5 | 00.6 | Plastic hinge | | |
| S | 16 | 01.0 | Flanged bearings | F608ZZ | |
| T | 12 | 03.0 | Drive track support hardware | | |
| U | 2 | 18.0 | Linear rail | MGN9 C | 200mm long |





₩ Hardware Box 2 📽

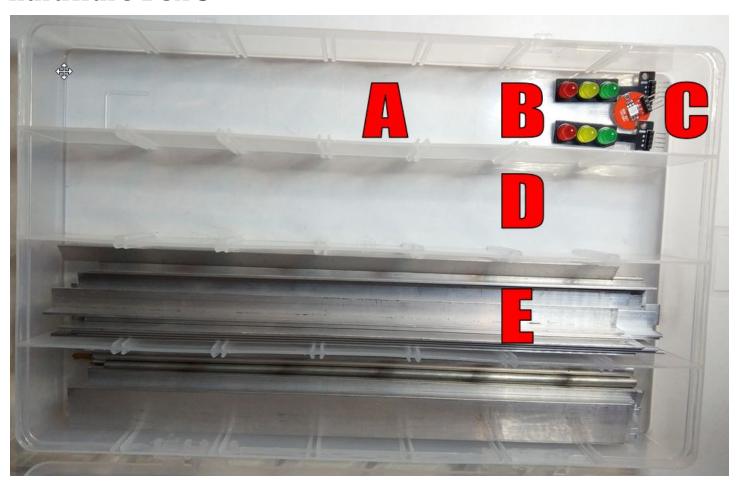


| ID Qty Cost | Description | Part Number | Major Parameters |
|-------------|--|-------------|--------------------------------------|
| A1 2 | Trapezoidal lead screw 300mm | | 300, 150, 100mm available |
| A2 2 | Trapezoidal lead screw 150mm | | |
| A3 2 | Trapezoidal lead screw 100mm | | |
| B 2 | Robot tracks | 880-8M | |
| C 2 | Timing belt. | 320 XL | |
| D 9 | Open beam Aluminum profile, Robot main chassis s | support, | 223.5mm |
| E1 1 | Timing belt open ended, | GT2 | 2m open ended, closed loop |
| E2 1 | Timing belt | GT2 | |
| E3 1 | Timing belt | GT2 | |
| F 16 | Open beam Aluminum profile | | 300, 210, 150, 120, 90, 60, 45, 30mm |





Hardware Box 3 😩



ID Qty Description

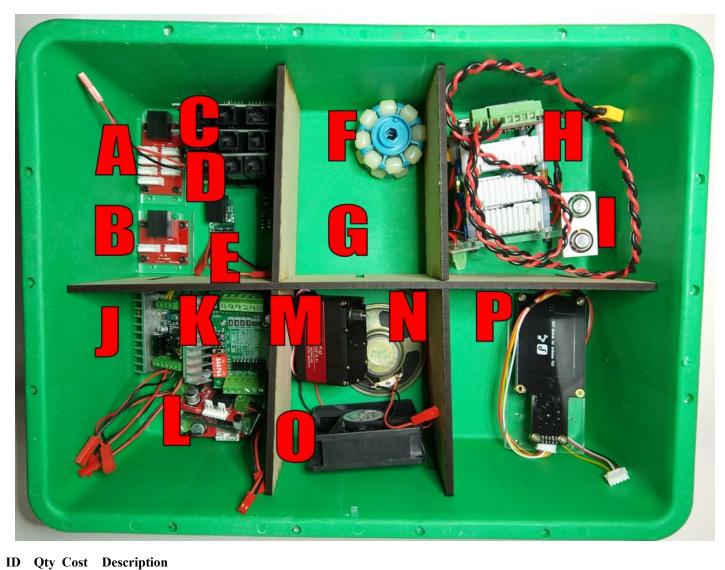
- A 2 Smart LED
- B 2 Traffic light LED
- C 1 RGB LED
- D 1 Cables
- E 1 Aluminium extrusion profiles, 300mm lengths
 - A selection of the following lengths are in the kit...
 - A 25mm right angle aluminium
 - B 12mm right angle aluminium
 - C 12mm box section aluminium
 - D 12mm U shaped aluminium
 - E 25mm flat bar aluminium
 - F 12mm flat bar aluminium
 - G 8mm round bar aluminium
 - H 6.5mm round bar aluminium

Longer lengths of Aluminium extrusion profiles are available on request.





Green Box 🏝



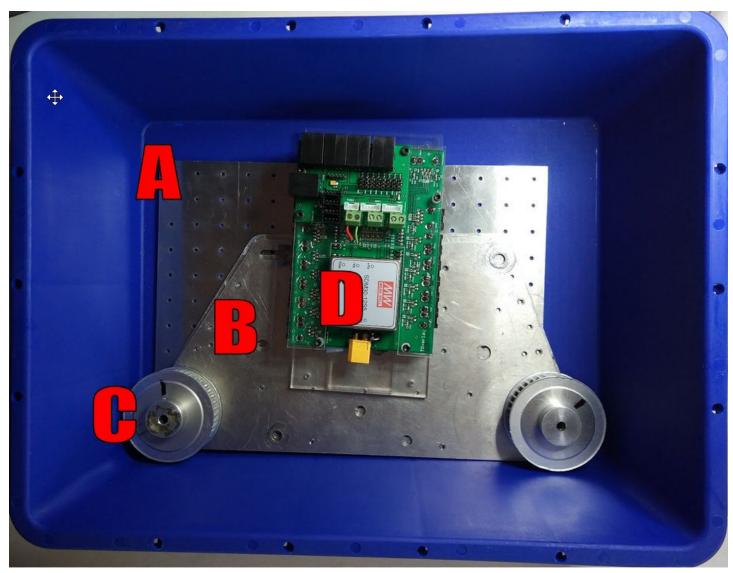
| A | 1 | 02.5 | I2C distribution board |
|----|---|-------|---|
| В | 1 | 02.5 | Serial distribution board |
| C | 2 | 04.0 | IO Test board |
| D | 1 | 04.0 | Servo distribution board 12 channel |
| E | 2 | 02.5 | Servo distribution board mini, 2 channel |
| F | 2 | 04.0 | Omni wheel |
| G1 | 2 | 07.5 | Skate wheel |
| G2 | 2 | 20.0 | Mecanum Wheel |
| Н | 1 | 25.0 | Power supply protection and distribution module |
| I | 1 | 02.5 | Power switch, green on, red off |
| J | 1 | 125.0 | DC motor drive board, 2 channel |
| K | 2 | 08.0 | Stepper motor drive board |
| L | 2 | 08.0 | DC motor drive board |
| M | 1 | 60.0 | Large servo |
| N | 1 | 01.6 | Speaker |
| O | 1 | 04.0 | Fan |
| P | 1 | 25.0 | RFID Board |
| | | | |

Sabertooth dual 12A motor driver









| ID | Qty Cost | Description |
|----|----------|--|
| A | 1 | Robot top plate, holes spaced 20mm apart, 3mm hole |
| В | 2 | Robot side plate, see file Body02.zip in 08Models for hole layout |
| C | 2 | Main drive pulley, held on flat of drive motor shaft with two grub screws, 2mm hex tool to tighten |
| D | 1 | CPU, Arduino Mega with custom connectors and safety features |





本Additional Materials

| ID Qty | Cost | Description |
|--------|----------|---|
| A 2 | 02.5 | Corflute sheet 600*600*3mm |
| B12 | 06.0 | MDF sheet 600*600*6mm |
| B22 | 04.0 | MDF sheet 600*600*4.75mm |
| C 2 | 04.0 | Aluminium sheet 300*300*2mm |
| D 2 | 04.0 | Perspex sheet 300*300*2mm |
| E 2 | 06.0 | Perspex sheet 300*300*4.5mm |
| F 2 | 09.0 | Perspex sheet 300*300*6mm |
| G 1 | 16.0 | Perspex sheet 300*300*10mm |
| H 1 | 12.0 | 3D Printing Filament 200g, 6c per gram for PLA |
| I 1 | 15.0 | Additional 1m of open beam Aluminium extrusion |
| J 3 | 01.0 | Magnets, Countersunk Ring Magnets 22mm x 5mm, Hole: 5.2mm, N50 Neodymium Magnet |
| Larger | sizes of | materials are available on request |



Email or see Julian Murphy with your job requests.

Specialised 3D Printing, supply file in STL or 3MF file format, Max size 250*210*210mm Laser cutting, supply file in DXF file format, Max size 1200*900*10mm Waterjet cutting, supply file in DXF file format, Max size 300*300*20mm Power guillotine, supply printed diagram or marked out on sheet to cut, straight lines only Parts repair and or replacement

Parts purchasing, supply links of website to purchase in email



Mechatronics Lab(24 Hour access)

Soldering iron, Oscilloscope, Signal Generator, Power supply Tools can be found on the peg board, or in the **Yellow** boxes

3D Printing(24 Hour access)

PRUSA I3 MK3s printer with 0.4mm nozzle

Student Workshop (Open 9-5 week days, Non Supervised)

Drill, Drill with XY table, power sander, bandsaw

Bender, roller, hand guillotine, notcher

To use powered tools you must see a staff member and explain what you want to do before power is turned on in the room. Hand tools can freely be used without an explanation.

Student Training Workshop (Available 9-4 Friday, and by appointment other days, Supervision)

Lathe, mill, drill, bandsaw









This documentation brought to you by the letter R, the number 1.6181 and King Julian



