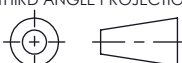



NOTES - (UNLESS OTHERWISE SPECIFIED)

1. ALL DIMENSIONS IN MILLIMETERS.

2. GD&T AS PER ISO1101-2004.

ITEM NO.	PART NUMBER	QTY.
1	Worm Drive Motor	1
2	Motor Adapter	1
3	Side Panel	2
4	Drive Gear	1
5	Square Bar	1
6	Foam	4
7	Foam Holder	3
8	Ball Bearing	1
9	Bearing Connector	1

<div>THIRD ANGLE PROJECTION</div> <div></div>		<div>THIS DOCUMENT IS ISSUED IN STRICT CONFIDENCE ON CONDITION THAT IT IS NOT COPIED, REPRINTED, OR DISCLOSED TO A THIRD PARTY EITHER WHOLLY OR IN PART WITHOUT THE WRITTEN CONSENT OF UNIVERSITY OF CANTERBURY</div>		<div>UNIVERSITY OF CANTERBURY</div> <div>DEPARTMENT OF MECHANICAL ENGINEERING</div>		<div>©</div> <div></div> <div>UNIVERSITY OF CANTERBURY</div> <div><small>The Place Where Learning Takes Root</small></div>	
MATERIAL		SEE PART DRAWINGS		Collection Method			
FINISH		SEE PART DRAWINGS		DESIGN Robocup Team 6	DWG NO. SpinnerAttachmentAssem		REV REV1
TOLERANCE (UNLESS OTHERWISE SPECIFIED)		DRAWN Ethan Te Puni		PROJECT Robocup			
DECIMAL mm		SUPERVISOR XXX		ISSUE DATE 2/10/21		DRAWING NOT TO SCALE	SHEET 1 OF 2
.X ± .1		.XX ± .03		.XXX ± .010		ANG. ± 1°	