

1.4 Conditional Expectations (7.11.2019)

Definition of Cpdf in elementary probability: $P(B|A) = \frac{P(A \cap B)}{P(A)}$, $P(B)$

Question: what happens if $P(A) = 0$?

$$A = \{Y = c\}; c \in \mathbb{R} \text{ and } Y \text{ is random variable}$$

In this section, the general definition of

⊖ Conditional probability

⊖ Expectation, and

⊖ distribution

are introduced.

1.4.1 Conditional expectations:

Definition: X is integrable random variable on (Ω, \mathcal{F}, P)

(i) A a sub- σ -field of $\mathcal{F} \rightarrow E(X|A)$ as unique as random variable

(a) $E(X|A)$ is measurable from (Ω, A) to $(\mathbb{R}, \mathcal{B})$

(b) $\int_A E(X|A) dP = \int_A X dP$ for any $A \in A$

(ii) $B \in \mathcal{F} \rightarrow P(B|A) = E(I_B|A)$

(iii) Y is measurable from (Ω, \mathcal{F}, P) to $(\mathbb{R}, \mathcal{G}) \rightarrow E(X|Y) = E[X|Y]$

Lemma 1.2: $(\Omega, \mathcal{F}) \xrightarrow[\text{is measurable}]{Y} (\mathbb{R}, \mathcal{G})$

Z is function from (Ω, \mathcal{F}) to \mathbb{R}^k

$(\Omega, \sigma(Y)) \xrightarrow[Z \text{ is measurable}]{Z} (\mathbb{R}^k, \mathcal{B}^k)$ if and only if $Z = h \circ Y$ measurable function

Example: X is an integrable random variable on (Ω, \mathcal{F}, P)

A_1, A_2, \dots disjoint events on $(\Omega, \mathcal{F}, P) - \cup A_i = \Omega, P(A_i) > 0$

a_1, a_2, \dots distinct real numbers

$$Y = a_1 I_{A_1} + a_2 I_{A_2} + \dots$$

$$\rightarrow E(X|Y) = \sum_{i=1}^{\infty} \frac{\int_{A_i} X dP}{P(A_i)} I_{A_i}$$

need to verify (a) and (b) above definition

$$A = \sigma(Y)$$

$\sigma(Y) = \sigma(\{A_1, A_2, \dots\})$ then $\sum_{i=1}^{\infty} \frac{\int_{A_i} x dP}{P(A_i)} I_{A_i}$ is measurable on $(\Omega, \sigma(Y))$

$$B \in \mathcal{B}, Y^{-1}(B) = \bigcup_{i: a_i \in B} A_i$$

$$\begin{aligned} \int_{Y^{-1}(B)} x dP &= \sum_{i: a_i \in B} \int_{A_i} x dP \\ &= \sum_{i=1}^{\infty} \frac{\int_{A_i} x dP}{P(A_i)} P(A_i \cap Y^{-1}(B)) \\ &= \int_{Y^{-1}(B)} \left[\sum_{i=1}^{\infty} \frac{\int_{A_i} x dP}{P(A_i)} I_{A_i} \right] dP \end{aligned}$$

h is Borel function on \mathbb{R} and satisfying

$$h(a_i) = \int_{A_i} x \frac{dP}{P(A_i)} \rightarrow E(X|Y) = h \circ Y, E(X|Y=y) = h(y)$$

$A \in \mathcal{F}, X = I_A$ then

$$P(A|Y) = E(X|Y) = \sum_{i=1}^{\infty} \frac{P(A \cap A_i)}{P(A_i)} I_{A_i}$$

$$P(A \cap A_i) / P(A_i) = P(A|A_i) \text{ if } \omega \in A_i$$

proposition 2.9 - X : random n -vector

Y : random m -vector

(X, Y) has a joint pdf $f(x, y)$, $\frac{\partial x \lambda}{\partial y \nu}$ \hookrightarrow finite measures on $(\mathbb{R}^n, \mathcal{B}^n), (\mathbb{R}^m, \mathcal{B}^m)$

$g(x, y)$ is a Borel function on \mathbb{R}^{n+m} for $E|g(X, Y)| < \infty$

then:

$$E[g(X, Y)|Y] = \frac{\int g(x, Y) f(x, Y) d\nu(x)}{\int f(x, Y) d\nu(x)}$$

Proof

Based on lemma 1.2 $h(y)$ is

Borel on $(\Omega, \sigma(Y))$ and because of Fubini's theorem

$$f_Y(y) = \int f(x, y) d\nu(x)$$

$$\int_{Y^{-1}(B)} h(y) dP = \int_B h(y) dP_Y =$$

$$\int \frac{\int g(x, y) f(x, y) d\nu(x)}{\int f(x, y) d\nu(x)} f_Y(y) d\lambda(y)$$

by

$h(Y) \rightarrow$ it is Borel ~~based on~~ Fubini's theorem

$$= \int_{\mathcal{R}^n \times B} g(x,y) f(x,y) d\mu \times \lambda = \int_{\mathcal{R}^n \times B} g(x,y) dP(x,y)$$

$$= \int_{Y^{-1}(B)} g(x,y) dP$$

(X,Y) a random vector with joint pdf $f(x,y)$ the conditional pdf of X when $Y=y$

$$f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)} \quad : \quad f_Y(y) = \int f(x,y) d\mu(x)$$

proposition 1.10 : X, Y, X_1, X_2, \dots integrable random variables on (Ω, \mathcal{F}, P) , \mathcal{A} a sub- σ -field of \mathcal{F}

- (i) if $X = c$, $c \in \mathbb{R} \rightarrow E(X|\mathcal{A}) = c$
- (ii) if $X < Y \rightarrow E(X|\mathcal{A}) \leq E(Y|\mathcal{A})$
- (iii) if $a \in \mathbb{R}$, $b \in \mathbb{R} \rightarrow E(aX + bY|\mathcal{A}) = aE(X|\mathcal{A}) + bE(Y|\mathcal{A})$
- (iv) $E[E(X|\mathcal{A})] = EX$

look the rest in page 40

Example 1.22

X a random variable on (Ω, \mathcal{F}, P) , $EX^2 < \infty$

Y a measurable function from (Ω, \mathcal{F}, P) to (\mathcal{A}, G)

$g(Y)$ is a predictor, i.e. $g \in \mathcal{N} = \{ \text{all Borel functions } g \text{ with } E[g(Y)]^2 < \infty \}$

predictor error : $E[X - g(Y)]^2$

$\Rightarrow E(X|Y)$ is the best predictor of X : if

$$E[X - E(X|Y)]^2 \leq \min_{g \in \mathcal{N}} E[X - g(Y)]^2$$

$$E[X - g(Y)]^2 = E[X - E(X|Y) + E(X|Y) - g(Y)]^2$$

$$= E[X - E(X|Y)]^2 + E[E(X|Y) - g(Y)]^2 + 2E[X - E(X|Y)]E[E(X|Y) - g(Y)]$$

$$= \dots \geq E[X - E(X|Y)]^2$$

1.4.2 independence:

Definition 1.7: (Ω, \mathcal{F}, P) is a probability space

(i) \mathcal{C} a collection of subset in \mathcal{F} . Events in \mathcal{C} are independent if and only if for any positive integer n a distinct events

$$A_1, \dots, A_n \text{ in } \mathcal{C} \rightarrow$$

$$P(A_1 \cap A_2 \cap \dots \cap A_n) = P(A_1) P(A_2) \dots P(A_n)$$

(ii) collections $\mathcal{C}_i \subset \mathcal{F}$, $i \in I$ to be independent if and only if

$\{A_i \in \mathcal{C}_i : i \in I\}$ are independent.

(iii) Random elements X_i , $i \in I$ are independent if and only if

$\sigma(X_i)$, $i \in I$ are independent.

Lemma 1.3: \mathcal{C}_i , $i \in I$ be independent collections of events.

Each \mathcal{C}_i has the property that if $A \in \mathcal{C}_i$ and $B \in \mathcal{C}_i$

then $A \cap B \in \mathcal{C}_i$. Then $\sigma(\mathcal{C}_i)$, $i \in I$ are independent.

For two events A , B with $P(A) > 0$, A and B are independent

$$\text{if } P(B|A) = P(B)$$

proposition 1.11: X a random variable, $E|X| < \infty$

γ_i random k_i -vector, $i=1, 2$

(X, γ_1) and γ_2 are independent then

$$E[X | \gamma_1, \gamma_2] = E[X | \gamma_1]$$