


```

for j = 1:numel(class1_L00(:, 1))
    distance(j + 1, 1) = euclideanDistance(DataPoint, class1_L00(j, :));
end
for j = 1:numel(class2(:, 1))
    distance(j, 2) = euclideanDistance(DataPoint, class2(j, :));
end
for j = 1:numel(class3(:, 1))
    distance(j, 3) = euclideanDistance(DataPoint, class3(j, :));
end
sortedDistance = sort(distance);

A = sortedDistance(1:k, 1);
kA = max(numel(find(A(end) == sortedDistance(:, 1))) + numel(find(A(end) ~=
A(:))), k);
B = sortedDistance(1:k, 2);
kB = max(numel(find(B(end) == sortedDistance(:, 2))) + numel(find(B(end) ~=
B(:))), k);
C = sortedDistance(1:k, 3);
kC = max(numel(find(C(end) == sortedDistance(:, 3))) + numel(find(C(end) ~=
C(:))), k);

V1 = Vn(D, max(A));
V2 = Vn(D, max(B));
V3 = Vn(D, max(C));
N1_L00 = numel(class1_L00(:, 1));

l12 = (kA * N2 * V2) / (kB * N1_L00 * V1);
l32 = (kC * N2 * V2) / (kB * N3 * V3);
l13 = (kA * N3 * V3) / (kC * N1_L00 * V1);

pC1 = N1_L00 / (N1_L00 + N2 + N3);
pC2 = N2 / (N1_L00 + N2 + N3);
pC3 = N3 / (N1_L00 + N2 + N3);

[~, index1] = max([l12, pC2 / pC1]);
if index1 == 1
    [~, index3] = max([l13, pC3 / pC1]);
    if index3 == 1
        TrueClass = 1;
    else
        TrueClass = 3;
    end
else
    [~, index2] = max([l32, pC2 / pC3]);
    if index2 == 1
        TrueClass = 3;
    else
        TrueClass = 2;
    end
end
Data(i, 8) = TrueClass;
if TrueClass ~= 1
    nFNC1 = nFNC1 + 1;
    switch TrueClass
        case 2

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        nFPC12 = nFPC12 + 1;
    case 3
        nFPC13 = nFPC13 + 1;
    end
    display('-----');
    display(['Row Number: ', num2str(i)]);
    display(['Actual Class: ', num2str(Data(i, 1))]);
    display(['Predicted Class: ', num2str(TrueClass)]);
    display('-----');
end
end
nTPC11 = numel(rowC1) - nFNC1;

distance(:) = inf;
for i = min(rowC2):max(rowC2)
    class2_L00 = [Data(setdiff(rowC2, i), 2), Data(setdiff(rowC2, i), 3),
Data(setdiff(rowC2, i), 4), Data(setdiff(rowC2, i), 5), Data(setdiff(rowC2, i), 6),
Data(setdiff(rowC2, i), 7)];
    DataPoint = [Data(i, 2), Data(i, 3), Data(i, 4), Data(i, 5), Data(i, 6),
Data(i, 7)];
    for j = 1:numel(class1(:, 1))
        distance(j, 1) = euclideanDistance(DataPoint, class1(j, :));
    end
    for j = 1:numel(class2_L00(:, 1))
        distance(j + 1, 2) = euclideanDistance(DataPoint, class2_L00(j, :));
    end
    for j = 1:numel(class3(:, 1))
        distance(j, 3) = euclideanDistance(DataPoint, class3(j, :));
    end
    sortedDistance = sort(distance);

    A = sortedDistance(1:k, 1);
    kA = max(numel(find(A(end) == sortedDistance(:, 1))) + numel(find(A(end) ~=
A(:))), k);
    B = sortedDistance(1:k, 2);
    kB = max(numel(find(B(end) == sortedDistance(:, 2))) + numel(find(B(end) ~=
B(:))), k);
    C = sortedDistance(1:k, 3);
    kC = max(numel(find(C(end) == sortedDistance(:, 3))) + numel(find(C(end) ~=
C(:))), k);

    V1 = Vn(D, max(A));
    V2 = Vn(D, max(B));
    V3 = Vn(D, max(C));
    N2_L00 = numel(class2_L00(:, 1));

    l12 = (kA * N2_L00 * V2) / (kB * N1 * V1);
    l32 = (kC * N2_L00 * V2) / (kB * N3 * V3);
    l13 = (kA * N3 * V3) / (kC * N1 * V1);

    pC1 = N1 / (N1 + N2_L00 + N3);
    pC2 = N2_L00 / (N1 + N2_L00 + N3);
    pC3 = N3 / (N1 + N2_L00 + N3);

    [~, index1] = max([l12, pC2 / pC1]);

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if index1 == 1
    [~, index3] = max([l13, pC3 / pC1]);
    if index3 == 1
        TrueClass = 1;
    else
        TrueClass = 3;
    end
else
    [~, index2] = max([l32, pC2 / pC3]);
    if index2 == 1
        TrueClass = 3;
    else
        TrueClass = 2;
    end
end
Data(i, 8) = TrueClass;
if TrueClass ~= 2
    nFNC2 = nFNC2 + 1;
    switch TrueClass
        case 1
            nFPC21 = nFPC21 + 1;
        case 3
            nFPC23 = nFPC23 + 1;
    end
    display('-----');
    display(['Row Number: ', num2str(i - max(rowC1))]);
    display(['Actual Class: ', num2str(Data(i, 1))]);
    display(['Predicted Class: ', num2str(TrueClass)]);
    display('-----');
end
end
nTPC22 = numel(rowC2) - nFNC2;

distance(:) = inf;
for i = min(rowC3):max(rowC3)
    class3_L00 = [Data(setdiff(rowC3, i), 2), Data(setdiff(rowC3, i), 3),
Data(setdiff(rowC3, i), 4), Data(setdiff(rowC3, i), 5), Data(setdiff(rowC3, i), 6),
Data(setdiff(rowC3, i), 7)];
    DataPoint = [Data(i, 2), Data(i, 3), Data(i, 4), Data(i, 5), Data(i, 6),
Data(i, 7)];
    for j = 1:numel(class1(:, 1))
        distance(j, 1) = euclideanDistance(DataPoint, class1(j, :));
    end
    for j = 1:numel(class2(:, 1))
        distance(j, 2) = euclideanDistance(DataPoint, class2(j, :));
    end
    for j = 1:numel(class3_L00(:, 1))
        distance(j + 1, 3) = euclideanDistance(DataPoint, class3_L00(j, :));
    end
    sortedDistance = sort(distance);

    A = sortedDistance(1:k, 1);
    kA = max(numel(find(A(end) == sortedDistance(:, 1))) + numel(find(A(end) ~=
A(:))), k);
    B = sortedDistance(1:k, 2);

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        kB = max(numel(find(B(end) == sortedDistance(:, 2))) + numel(find(B(end) ~=
B(:))), k);
        C = sortedDistance(1:k, 3);
        kC = max(numel(find(C(end) == sortedDistance(:, 3))) + numel(find(C(end) ~=
C(:))), k);

        V1 = Vn(D, max(A));
        V2 = Vn(D, max(B));
        V3 = Vn(D, max(C));
        N3_L00 = numel(class3_L00(:, 1));

        l12 = (kA * N2 * V2) / (kB * N1 * V1);
        l32 = (kC * N2 * V2) / (kB * N3_L00 * V3);
        l13 = (kA * N3_L00 * V3) / (kC * N1 * V1);

        pC1 = N1 / (N1 + N2 + N3_L00);
        pC2 = N2 / (N1 + N2 + N3_L00);
        pC3 = N3_L00 / (N1 + N2 + N3_L00);

        [~, index1] = max([l12, pC2 / pC1]);
        if index1 == 1
            [~, index3] = max([l13, pC3 / pC1]);
            if index3 == 1
                TrueClass = 1;
            else
                TrueClass = 3;
            end
        else
            [~, index2] = max([l32, pC2 / pC3]);
            if index2 == 1
                TrueClass = 3;
            else
                TrueClass = 2;
            end
        end
        Data(i, 8) = TrueClass;
        if TrueClass ~= 3
            nFNC3 = nFNC3 + 1;
            switch TrueClass
                case 1
                    nFPC31 = nFPC31 + 1;
                case 2
                    nFPC32 = nFPC32 + 1;
            end
            display('-----');
            display(['Row Number: ', num2str(i - max(rowC2))]);
            display(['Actual Class: ', num2str(Data(i, 1))]);
            display(['Predicted Class: ', num2str(TrueClass)]);
            display('-----');
        end
    end
    nTPC33 = numel(rowC3) - nFNC3;

    display(['k = ', num2str(k)]);

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Confusion_matrix{1, 1} = 'P\A';
Confusion_matrix{2, 1} = 'C1';
Confusion_matrix{3, 1} = 'C2';
Confusion_matrix{4, 1} = 'C3';
Confusion_matrix{1, 2} = 'C1';
Confusion_matrix{1, 3} = 'C2';
Confusion_matrix{1, 4} = 'C3';

Confusion_matrix{2, 2} = nTPC11;
Confusion_matrix{2, 3} = nFPC21;
Confusion_matrix{2, 4} = nFPC31;

Confusion_matrix{3, 2} = nFPC12;
Confusion_matrix{3, 3} = nTPC22;
Confusion_matrix{3, 4} = nFPC32;

Confusion_matrix{4, 2} = nFPC13;
Confusion_matrix{4, 3} = nFPC23;
Confusion_matrix{4, 4} = nTPC33;

display(Confusion_matrix);

nTPC11 = 0;
nFNC1 = 0;
nFPC12 = 0;
nFPC13 = 0;

nTPC22 = 0;
nFNC2 = 0;
nFPC21 = 0;
nFPC23 = 0;

nTPC33 = 0;
nFNC3 = 0;
nFPC31 = 0;
nFPC32 = 0;
end
-----
Row Number: 3
Actual Class: 2
Predicted Class: 3
-----
-----
Row Number: 4
Actual Class: 2
Predicted Class: 3
-----
-----
Row Number: 15
Actual Class: 2
Predicted Class: 1
-----
-----
Row Number: 23
Actual Class: 2

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Predicted Class: 1

Row Number: 25

Actual Class: 2

Predicted Class: 3

Row Number: 7

Actual Class: 3

Predicted Class: 2

Row Number: 16

Actual Class: 3

Predicted Class: 2

k = 1

Confusion_matrix =

4x4 cell array

{ 'P\A' }	{ 'C1' }	{ 'C2' }	{ 'C3' }
{ 'C1' }	{ [59] }	{ [2] }	{ [0] }
{ 'C2' }	{ [0] }	{ [66] }	{ [2] }
{ 'C3' }	{ [0] }	{ [3] }	{ [46] }

Row Number: 44

Actual Class: 1

Predicted Class: 2

Row Number: 3

Actual Class: 2

Predicted Class: 3

Row Number: 4

Actual Class: 2

Predicted Class: 3

Row Number: 7

Actual Class: 2

Predicted Class: 1

Row Number: 15

Actual Class: 2

Predicted Class: 1

Row Number: 23

Actual Class: 2
Predicted Class: 1

Row Number: 25
Actual Class: 2
Predicted Class: 3

Row Number: 16
Actual Class: 3
Predicted Class: 2

k = 2

Confusion_matrix =

4x4 cell array

{'P\A'}	{'C1'}	{'C2'}	{'C3'}
{'C1' }	{[58]}	{[3]}	{[0]}
{'C2' }	{[1]}	{[65]}	{[1]}
{'C3' }	{[0]}	{[3]}	{[47]}

Row Number: 44

Actual Class: 1
Predicted Class: 2

Row Number: 3
Actual Class: 2
Predicted Class: 3

Row Number: 7
Actual Class: 2
Predicted Class: 1

Row Number: 15
Actual Class: 2
Predicted Class: 1

Row Number: 23
Actual Class: 2
Predicted Class: 1

Row Number: 25
Actual Class: 2
Predicted Class: 3


```
Row Number: 16
Actual Class: 3
Predicted Class: 2
-----
k = 3
```

```
Confusion_matrix =
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```
4x4 cell array
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{'P\A'}	{'C1'}	{'C2'}	{'C3'}
{'C1' }	{[58]}	{[3]}	{[0]}
{'C2' }	{[1]}	{[66]}	{[1]}
{'C3' }	{[0]}	{[2]}	{[47]}