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```
clc;
close all;
clear all;

I=imread('pout.tif');
imshow(I);
title('Original Image');

for J=0.01:0.01:0.02
    figure;
    I0=imnoise(I,'gaussian',0,J);
    imshow(I0);
    title(strcat('Noisy Image (Gaussian,d=',num2str(J),')'));

    figure;
    Mean_Filter(I0,3,1,2,1);
    Mean_Filter(I0,5,1,2,2);

    figure;
    Gaussian_Filter(I0,3,0.3,1,2,1);
    Gaussian_Filter(I0,5,0.6,1,2,2);

    figure;
    I1=imnoise(I,'salt & pepper',J);
    imshow(I1);
    title(strcat('Noisy Image (salt & pepper,d=',num2str(J),')'));

    figure;
    Mean_Filter(I1,3,1,2,1);
    Mean_Filter(I1,5,1,2,2);

    figure;
    Gaussian_Filter(I1,3,0.3,1,2,1);
    Gaussian_Filter(I1,5,0.6,1,2,2);

    figure;
    Median_Filter(I1,3,1,2,1);
    Median_Filter(I1,5,1,2,2);
end
```

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Original Image



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Noisy Image (Gaussian,  $d=0.01$ )



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Mean Filter (3\*3)



Mean Filter (5\*5)



Gaussian Filter (3,0.3)



Gaussian Filter (5,0.6)



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Noisy Image (salt & pepper,  $d=0.01$ )



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Mean Filter (3\*3)



Mean Filter (5\*5)



Gaussian Filter (3,0.3)



Gaussian Filter (5,0.6)



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Median Filter (3\*3)



Median Filter (5\*5)



---

Noisy Image (Gaussian, $d=0.02$ )





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Mean Filter (3\*3)



Mean Filter (5\*5)



Gaussian Filter (3,0.3)



Gaussian Filter (5,0.6)



---

Noisy Image (salt & pepper,  $d=0.02$ )



---

Mean Filter (3\*3)



Mean Filter (5\*5)



Gaussian Filter (3,0.3)



Gaussian Filter (5,0.6)



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Median Filter (3\*3)



Median Filter (5\*5)



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