

```

clc
clear

filename = 'Iris-Data_dat.txt';
formatSpec = '%3f%6f%3f%3f[%^n\r]';
fileID = fopen(filename, 'r');
IRISData = textscan(fileID, formatSpec, 'Delimiter', ' ', 'WhiteSpace', '',
'ReturnOnError', false);
fclose(fileID);

Data = [IRISData{1}, IRISData{2}, IRISData{3}, IRISData{4}, IRISData{5}];
Data = [Data, zeros(numel(Data(:, 1)), 1)];
D = numel(Data(1, 2:end-1));

[rowC1, ~] = find(Data(:, 1) == 1);
[rowC2, ~] = find(Data(:, 1) == 2);
[rowC3, ~] = find(Data(:, 1) == 3);
distance = zeros(max([numel(rowC1), numel(rowC2), numel(rowC3)]), 3);
distance(:) = inf;

nTPC11 = 0;
nFNC1 = 0;
nFPC12 = 0;
nFPC13 = 0;

nTPC22 = 0;
nFNC2 = 0;
nFPC21 = 0;
nFPC23 = 0;

nTPC33 = 0;
nFNC3 = 0;
nFPC31 = 0;
nFPC32 = 0;

class1 = [Data(rowC1, 2), Data(rowC1, 3), Data(rowC1, 4), Data(rowC1, 5)];
class2 = [Data(rowC2, 2), Data(rowC2, 3), Data(rowC2, 4), Data(rowC2, 5)];
class3 = [Data(rowC3, 2), Data(rowC3, 3), Data(rowC3, 4), Data(rowC3, 5)];
N1 = numel(class1(:, 1));
N2 = numel(class2(:, 1));
N3 = numel(class3(:, 1));

for k = 1:3
    for i = min(rowC1):max(rowC1)
        class1_L00 = [Data(setdiff(rowC1, i), 2), Data(setdiff(rowC1, i), 3),
Data(setdiff(rowC1, i), 4), Data(setdiff(rowC1, i), 5)];
        DataPoint = [Data(i, 2), Data(i, 3), Data(i, 4), Data(i, 5)];
        for j = 1:numel(class1_L00(:, 1))
            distance(j + 1, 1) = euclideanDistance(DataPoint, class1_L00(j, :));
        end
        for j = 1:numel(class2(:, 1))
            distance(j, 2) = euclideanDistance(DataPoint, class2(j, :));
        end
    end
end

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for j = 1:numel(class3(:, 1))
    distance(j, 3) = euclideanDistance(DataPoint, class3(j, :));
end
sortedDistance = sort(distance);

A = sortedDistance(1:k, 1);
kA = max(numel(find(A(end) == sortedDistance(:, 1))) + numel(find(A(end) ~= A(:))), k);
B = sortedDistance(1:k, 2);
kB = max(numel(find(B(end) == sortedDistance(:, 2))) + numel(find(B(end) ~= B(:))), k);
C = sortedDistance(1:k, 3);
kC = max(numel(find(C(end) == sortedDistance(:, 3))) + numel(find(C(end) ~= C(:))), k);

V1 = Vn(D, max(A));
V2 = Vn(D, max(B));
V3 = Vn(D, max(C));
N1_L00 = numel(class1_L00(:, 1));

l12 = (kA * N2 * V2) / (kB * N1_L00 * V1);
l32 = (kC * N2 * V2) / (kB * N3 * V3);
l13 = (kA * N3 * V3) / (kC * N1_L00 * V1);

pC1 = N1_L00 / (N1_L00 + N2 + N3);
pC2 = N2 / (N1_L00 + N2 + N3);
pC3 = N3 / (N1_L00 + N2 + N3);

[~, index1] = max([l12, pC2 / pC1]);
if index1 == 1
    [~, index3] = max([l13, pC3 / pC1]);
    if index3 == 1
        TrueClass = 1;
    else
        TrueClass = 3;
    end
else
    [~, index2] = max([l32, pC2 / pC3]);
    if index2 == 1
        TrueClass = 3;
    else
        TrueClass = 2;
    end
end
Data(i, 6) = TrueClass;
if TrueClass ~= 1
    nFNC1 = nFNC1 + 1;
    switch TrueClass
        case 2
            nFPC12 = nFPC12 + 1;
        case 3
            nFPC13 = nFPC13 + 1;
    end
display('-----');
display(['Row Number: ', num2str(i)]);

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        display(['Actual Class: ', num2str(Data(i, 1))]);
        display(['Predicted Class: ', num2str(TrueClass)]);
        display('-----');
    end
end
nTPC11 = numel(rowC1) - nFNC1;

distance(:) = inf;
for i = min(rowC2):max(rowC2)
    class2_L00 = [Data(setdiff(rowC2, i), 2), Data(setdiff(rowC2, i), 3),
Data(setdiff(rowC2, i), 4), Data(setdiff(rowC2, i), 5)];
    DataPoint = [Data(i, 2), Data(i, 3), Data(i, 4), Data(i, 5)];
    for j = 1:numel(class1(:, 1))
        distance(j, 1) = euclideanDistance(DataPoint, class1(j, :));
    end
    for j = 1:numel(class2_L00(:, 1))
        distance(j + 1, 2) = euclideanDistance(DataPoint, class2_L00(j, :));
    end
    for j = 1:numel(class3(:, 1))
        distance(j, 3) = euclideanDistance(DataPoint, class3(j, :));
    end
sortedDistance = sort(distance);

A = sortedDistance(1:k, 1);
kA = max(numel(find(A(end) == sortedDistance(:, 1))) + numel(find(A(end) ~= A(:))), k);
B = sortedDistance(1:k, 2);
kB = max(numel(find(B(end) == sortedDistance(:, 2))) + numel(find(B(end) ~= B(:))), k);
C = sortedDistance(1:k, 3);
kC = max(numel(find(C(end) == sortedDistance(:, 3))) + numel(find(C(end) ~= C(:))), k);

V1 = Vn(D, max(A));
V2 = Vn(D, max(B));
V3 = Vn(D, max(C));
N2_L00 = numel(class2_L00(:, 1));

l12 = (kA * N2_L00 * V2) / (kB * N1 * V1);
l32 = (kC * N2_L00 * V2) / (kB * N3 * V3);
l13 = (kA * N3 * V3) / (kC * N1 * V1);

pC1 = N1 / (N1 + N2_L00 + N3);
pC2 = N2_L00 / (N1 + N2_L00 + N3);
pC3 = N3 / (N1 + N2_L00 + N3);

[~, index1] = max([l12, pC2 / pC1]);
if index1 == 1
    [~, index3] = max([l13, pC3 / pC1]);
    if index3 == 1
        TrueClass = 1;
    else
        TrueClass = 3;
    end
else

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[~, index2] = max([l32, pC2 / pC3]);
if index2 == 1
    TrueClass = 3;
else
    TrueClass = 2;
end
end
Data(i, 6) = TrueClass;
if TrueClass ~= 2
    nFNC2 = nFNC2 + 1;
    switch TrueClass
        case 1
            nFPC21 = nFPC21 + 1;
        case 3
            nFPC23 = nFPC23 + 1;
    end
    display('-----');
    display(['Row Number: ', num2str(i - max(rowC1))]);
    display(['Actual Class: ', num2str(Data(i, 1))]);
    display(['Predicted Class: ', num2str(TrueClass)]);
    display('-----');
end
nTPC22 = numel(rowC2) - nFNC2;

distance(:) = inf;
for i = min(rowC3):max(rowC3)
    class3_L00 = [Data(setdiff(rowC3, i), 2), Data(setdiff(rowC3, i), 3),
Data(setdiff(rowC3, i), 4), Data(setdiff(rowC3, i), 5)];
    DataPoint = [Data(i, 2), Data(i, 3), Data(i, 4), Data(i, 5)];
    for j = 1:numel(class1(:, 1))
        distance(j, 1) = euclideanDistance(DataPoint, class1(j, :));
    end
    for j = 1:numel(class2(:, 1))
        distance(j, 2) = euclideanDistance(DataPoint, class2(j, :));
    end
    for j = 1:numel(class3_L00(:, 1))
        distance(j + 1, 3) = euclideanDistance(DataPoint, class3_L00(j, :));
    end
    sortedDistance = sort(distance);

    A = sortedDistance(1:k, 1);
    kA = max(numel(find(A(end) == sortedDistance(:, 1))) + numel(find(A(end) ~=
A(:))), k);
    B = sortedDistance(1:k, 2);
    kB = max(numel(find(B(end) == sortedDistance(:, 2))) + numel(find(B(end) ~=
B(:))), k);
    C = sortedDistance(1:k, 3);
    kC = max(numel(find(C(end) == sortedDistance(:, 3))) + numel(find(C(end) ~=
C(:))), k);

    V1 = Vn(D, max(A));
    V2 = Vn(D, max(B));
    V3 = Vn(D, max(C));
    N3_L00 = numel(class3_L00(:, 1));

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l12 = (kA * N2 * V2) / (kB * N1 * V1);
l32 = (kC * N2 * V2) / (kB * N3_L00 * V3);
l13 = (kA * N3_L00 * V3) / (kC * N1 * V1);

pC1 = N1 / (N1 + N2 + N3_L00);
pC2 = N2 / (N1 + N2 + N3_L00);
pC3 = N3_L00 / (N1 + N2 + N3_L00);

[~, index1] = max([l12, pC2 / pC1]);
if index1 == 1
    [~, index3] = max([l13, pC3 / pC1]);
    if index3 == 1
        TrueClass = 1;
    else
        TrueClass = 3;
    end
else
    [~, index2] = max([l32, pC2 / pC3]);
    if index2 == 1
        TrueClass = 3;
    else
        TrueClass = 2;
    end
end
Data(i, 6) = TrueClass;
if TrueClass ~= 3
    nFNC3 = nFNC3 + 1;
    switch TrueClass
        case 1
            nFPC31 = nFPC31 + 1;
        case 2
            nFPC32 = nFPC32 + 1;
    end
    display('-----');
    display(['Row Number: ', num2str(i - max(rowC2))]);
    display(['Actual Class: ', num2str(Data(i, 1))]);
    display(['Predicted Class: ', num2str(TrueClass)]);
    display('-----');
end
nTPC33 = numel(rowC3) - nFNC3;

display(['k = ', num2str(k)]);

Confusion_matrix{1, 1} = 'P\A';
Confusion_matrix{2, 1} = 'C1';
Confusion_matrix{3, 1} = 'C2';
Confusion_matrix{4, 1} = 'C3';
Confusion_matrix{1, 2} = 'C1';
Confusion_matrix{1, 3} = 'C2';
Confusion_matrix{1, 4} = 'C3';

Confusion_matrix{2, 2} = nTPC11;
Confusion_matrix{2, 3} = nFPC21;

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Confusion_matrix{2, 4} = nFPC31;

Confusion_matrix{3, 2} = nFPC12;
Confusion_matrix{3, 3} = nTPC22;
Confusion_matrix{3, 4} = nFPC32;

Confusion_matrix{4, 2} = nFPC13;
Confusion_matrix{4, 3} = nFPC23;
Confusion_matrix{4, 4} = nTPC33;

display(Confusion_matrix);

nTPC11 = 0;
nFNC1 = 0;
nFPC12 = 0;
nFPC13 = 0;

nTPC22 = 0;
nFNC2 = 0;
nFPC21 = 0;
nFPC23 = 0;

nTPC33 = 0;
nFNC3 = 0;
nFPC31 = 0;
nFPC32 = 0;

```

end

Row Number: 21
Actual Class: 2
Predicted Class: 3

Row Number: 23
Actual Class: 2
Predicted Class: 3

Row Number: 34
Actual Class: 2
Predicted Class: 3

Row Number: 7
Actual Class: 3
Predicted Class: 2

Row Number: 20
Actual Class: 3
Predicted Class: 2

Row Number: 34
Actual Class: 3

```

Predicted Class: 2
-----
k = 1

Confusion_matrix =
4x4 cell array

{'P\A'}    {'C1'}    {'C2'}    {'C3'}
{'C1' }    {[50]}    {[ 0]}    {[ 0]}
{'C2' }    {[ 0]}    {[47]}    {[ 3]}
{'C3' }    {[ 0]}    {[ 3]}    {[47]}

-----
Row Number: 21
Actual Class: 2
Predicted Class: 3
-----

-----
Row Number: 23
Actual Class: 2
Predicted Class: 3
-----

-----
Row Number: 34
Actual Class: 2
Predicted Class: 3
-----

-----
Row Number: 7
Actual Class: 3
Predicted Class: 2
-----

-----
Row Number: 20
Actual Class: 3
Predicted Class: 2
-----

-----
Row Number: 34
Actual Class: 3
Predicted Class: 2
-----

k = 2

Confusion_matrix =
4x4 cell array

{'P\A'}    {'C1'}    {'C2'}    {'C3'}
{'C1' }    {[50]}    {[ 0]}    {[ 0]}
{'C2' }    {[ 0]}    {[47]}    {[ 3]}
{'C3' }    {[ 0]}    {[ 3]}    {[47]}

-----
```

```
Row Number: 21
Actual Class: 2
Predicted Class: 3
-----
-----
Row Number: 23
Actual Class: 2
Predicted Class: 3
-----
-----
Row Number: 34
Actual Class: 2
Predicted Class: 3
-----
-----
Row Number: 7
Actual Class: 3
Predicted Class: 2
-----
-----
Row Number: 20
Actual Class: 3
Predicted Class: 2
-----
k = 3

Confusion_matrix =
4x4 cell array

{'P\A'}    {'C1'}    {'C2'}    {'C3'}
{'C1' }    {[50]}    {[ 0]}    {[ 0]}
{'C2' }    {[ 0]}    {[47]}    {[ 2]}
{'C3' }    {[ 0]}    {[ 3]}    {[48]}
```