Thesis

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Chapter 1

Introduction

The broad goal of this thesis is to tackle a clustering problem in the scope of mixtures model framework. More precisely, we will study the clustering of points drawn from high-dimensional Gaussian mixtures distributions. Thus, in the first part of this section we present the Gaussian mixture model and the second part we describe the well know Expectation-Maximization algorithm (EM). We will also present the limitations of this algorithm in high-dimensional setting.

1.1 The Gaussian mixture model

The Gaussian mixture model is an important framework for clustering problems. It assumes that the observations are drawn from a mixture distribution the components of which are Gaussian with parameters (μ_k, Σ_k) :

$$\varphi_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(x) = \frac{1}{(2\pi)^{p/2} |\boldsymbol{\Sigma}_k|^{1/2}} \exp\left(-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu}_k)^{\top} \boldsymbol{\Sigma}_k^{-1} (\boldsymbol{x} - \boldsymbol{\mu}_k)\right)$$
(1.1)

Let $\boldsymbol{\theta}$ be the list containing all the unknown parameters of a Gaussian mixture model: the family of means $\boldsymbol{\mu} = (\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_K) \in (\mathbb{R}^p)^K$, the family of covariance matrices $\boldsymbol{\Sigma} = (\boldsymbol{\Sigma}_1, \dots, \boldsymbol{\Sigma}_k) \in (\mathcal{S}_{++}^p)^K$ and the vector of cluster probabilities $\boldsymbol{\pi} = (\pi_1, \dots, \pi_k) \in [0, 1]^K$ such that $\mathbf{1}_p^{\mathsf{T}} \boldsymbol{\pi} = 1$. The density of one observation \boldsymbol{X}_1 is then given by:

$$p_{\theta}(\boldsymbol{x}) = \sum_{k=1}^{K} \pi_k \varphi_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(\boldsymbol{x}), \qquad \forall \boldsymbol{x} \in \mathbb{R}^p,$$
 (1.2)

where $\boldsymbol{\theta} = (\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi})$.

This model can be interpreted from a latent variable perspective. Let Z be a discrete random variable taking its values in the set [K] and such

that $\mathbf{P}(Z=k)=\pi_k$ for every $k\in[K]$. The random variable Z indicates the cluster from which the observation X is drawn. Considering that all the conditional distributions X|Z=k are Gaussian, we get the following formula for the marginal density of X:

$$p_{\theta}(\boldsymbol{x}) = \sum_{k=1}^{K} \mathbf{P}(Z=k) p_{\theta}(\boldsymbol{x}|Z=k) = \sum_{k=1}^{K} \pi_{k} \varphi_{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}}(\boldsymbol{x}), \quad \forall \boldsymbol{x} \in \mathbb{R}^{p}. \quad (1.3)$$

In the clustering problem, the goal is to assign X to a cluster or, equivalently, to predict the cluster Z of the vector \mathbf{X} . A prediction function in such a context is $g: \mathbb{R}^p \to [K]$ such that $g(\mathbf{X})$ is as close as possible to Z. If we measure the risk of a prediction function g in terms of misclassification error rate $R_{\theta}(g) = \mathbf{P}_{\theta}(g(\mathbf{X}) \neq Z)$, then it is well known that the optimal (Bayes) predictor $g_{\theta}^* \in \arg\min_g R_{\theta}(g)$ is provided by the rule

$$g_{\boldsymbol{\theta}}^*(\boldsymbol{x}) = \arg \max_{k \in [K]} \tau_k(\boldsymbol{x}, \boldsymbol{\theta}),$$

where $\tau_k(\boldsymbol{x}, \boldsymbol{\theta}) = p_{\boldsymbol{\theta}}(Z = k | \boldsymbol{X} = \boldsymbol{x})$ stands for the conditional probability of the latent variable Z given \boldsymbol{X} . In the Gaussian mixture model, Bayes's rule implies that

$$\tau_k(\boldsymbol{x}, \boldsymbol{\theta}) = \frac{p_{\boldsymbol{\theta}}(\boldsymbol{x}|Z=k)\mathbf{P}(Z=k)}{p_{\boldsymbol{\theta}}(\boldsymbol{x})} = \frac{\pi_k \varphi_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(\boldsymbol{x})}{\sum_{k'=1}^K \pi_{k'} \varphi_{\boldsymbol{\mu}_{k'}, \boldsymbol{\Sigma}_{k'}}(\boldsymbol{x})}$$
(1.4)

Since the true value of the parameter $\boldsymbol{\theta}$ is not available, formula (1.4) can not be directly used for solving the problem of clustering. Instead, a natural strategy is to estimate $\boldsymbol{\theta}$ by some vector $\hat{\boldsymbol{\theta}}$, based on a sample $\boldsymbol{X}_1, \ldots, \boldsymbol{X}_n$ drawn from the density $p_{\boldsymbol{\theta}}$, and then to define the clustering rule by

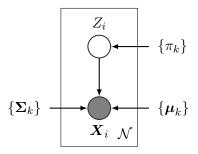
$$\widehat{g}(\boldsymbol{x}) = g_{\widehat{\boldsymbol{\theta}}}^*(\boldsymbol{x}) = \arg\max_{k \in [K]} \tau_k(\boldsymbol{x}, \widehat{\boldsymbol{\theta}}) = \arg\max_{k \in [K]} \widehat{\pi}_k \varphi_{\widehat{\boldsymbol{\mu}}_k, \widehat{\boldsymbol{\Sigma}}_k}(\boldsymbol{x}).$$
(1.5)

A common approach to estimating the parameter θ is to rely on the likelihood maximization.

Let X_1, \ldots, X_n with $X_i \in \mathbb{R}^p$ be a set of iid observations drawn from the density p_{θ} given by (1.2). The following graphical model depicts the scheme of the observations:

The log-likelihood of the Gaussian mixture model is

$$\ell_n(\boldsymbol{\theta}) = \sum_{i=1}^n \log p_{\boldsymbol{\theta}}(\boldsymbol{x}_i) = \sum_{i=1}^n \log \left\{ \sum_{k=1}^K \pi_k \varphi_{(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}(\boldsymbol{x}_i) \right\}.$$
 (1.6)



Because of the presence in this equation of the logarithm of a sum, the maximization of the log-likelihood is a difficult nonlinear and nonconvex problem. In particular, this is not a exponential family distribution yielding simple expressions. A commonly used approach for approximately maximizing (1.6) with respect to θ is the Expectation-Maximization (EM) Algorithm [Dempster et al., 1977] that we recall below.

Summarizing the content of this section, we can describe the following natural approach to solving the clustering problem under Gaussian mixture modeling assumption:

Input: data vectors $x_1, \ldots, x_n \in \mathbb{R}^p$ and the number of clusters KOutput: function $\widehat{g}: \mathbb{R}^p \to [K]$ 1: Estimate $\theta = (\pi, \mu, \Sigma)$ by maximizing the log-likelihood: $\widehat{\theta} \in \arg\max_{\theta \in \Theta} \ell(\theta|x_1, \ldots, x_n) = \arg\max_{\pi, \mu, \Sigma} \sum_{i=1}^n \log \left\{ \sum_{k=1}^K \pi_k \varphi_{\mu_k, \Sigma_k}(x_i) \right\}.$ (1.7)

2: Output the clustering rule:

$$\widehat{g}(\cdot) = \arg \max_{k \in [K]} \widehat{\pi}_k \varphi_{\widehat{\boldsymbol{\mu}}_k, \widehat{\boldsymbol{\Sigma}}_k}(\cdot). \tag{1.8}$$

Figure 1.1: Clustering under Gaussian mixture modeling

1.2 EM Algorithm

The goal of the EM algorithm is to approximate a solution of the problem (1.7). Since this optimization problem contains a nonconvex cost function, it is impossible to design a polynomial time algorithm that provably converges to the global maximum point. Instead, the EM algorithm provides a

sequence $\{\widehat{\boldsymbol{\theta}}(t)\}_{t\in\mathbb{N}}$ of parameter values such that the cost function (i.e., the log-likelihood) evaluated at these values forms an increasing sequence that converges to a local maximum.

The main idea underlying the EM algorithm is the following representation of the log-likelihood of one observation derived from the log-sum inequality:

$$\log \left\{ \sum_{k=1}^{K} \pi_k \varphi_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(\boldsymbol{x}_i) \right\} = \max_{\boldsymbol{\tau} \in [0,1]^K \ \boldsymbol{\tau}^\top \boldsymbol{1}_K = 1} \sum_{k=1}^{K} \left\{ \tau_k \log \varphi_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(\boldsymbol{x}_i) + \tau_k \log(\pi_k/\tau_k) \right\}.$$

$$(1.9)$$

Let us denote by $\mathcal{T} = (\tau_{i,k})$ a $n \times K$ matrix with nonnegative entries such that $\mathcal{T}\mathbf{1}_K = \mathbf{1}_n$, that is each row of \mathcal{T} is a probability distribution on [K]. Combining (1.7) and (1.9), we get

$$\widehat{\boldsymbol{\theta}} \in \underset{\boldsymbol{\theta} = (\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma})}{\operatorname{arg \, max}} \sum_{i=1}^{N} \sum_{k=1}^{K} \left\{ \tau_{i,k} \log \varphi_{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}}(\boldsymbol{x}_{i}) + \tau_{i,k} \log(\pi_{k}/\tau_{i,k}) \right\}. \tag{1.10}$$

The great advantage of this new representation of the log-likelihood function is that the cost function in (1.10), considered as a function of $\boldsymbol{\theta}$ and $\boldsymbol{\mathcal{T}}$, is biconcave, *i.e.*, it is concave with respect to $\boldsymbol{\theta}$ for every fixed $\boldsymbol{\mathcal{T}}$ and concave with respect to $\boldsymbol{\mathcal{T}}$ for every fixed $\boldsymbol{\theta}$. In such a situation, one can apply the alternating maximization approach to sequentially improve on an initial point. In the present context, an additional attractive feature of the cost function in (1.10) is that the two optimization problems involved in the alternating maximization procedure admit explicit solutions.

Lemma 1. Let us introduce the cost function

$$F(\boldsymbol{\theta}, \boldsymbol{\mathcal{T}}) = \sum_{i=1}^{n} \sum_{k=1}^{K} \left\{ \tau_{i,k} \log \varphi_{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}}(\boldsymbol{x}_{i}) + \tau_{i,k} \log(\pi_{k}/\tau_{i,k}) \right\}.$$
(1.11)

Then, the following two optimization problems

$$\widehat{\boldsymbol{\theta}}(\boldsymbol{\mathcal{T}}) \in \arg\max_{\boldsymbol{\theta}} F(\boldsymbol{\theta}, \boldsymbol{\mathcal{T}}), \qquad \widehat{\boldsymbol{\mathcal{T}}}(\boldsymbol{\theta}) \in \arg\max_{\boldsymbol{\mathcal{T}}} F(\boldsymbol{\theta}, \boldsymbol{\mathcal{T}})$$
 (1.12)

has explicit solutions given by

$$\widehat{\pi}_k = \frac{1}{n} \sum_{i=1}^n \tau_{i,k}, \qquad \widehat{\boldsymbol{\mu}}_k = \frac{1}{n\widehat{\pi}_k} \sum_{i=1}^n \tau_{i,k} \boldsymbol{x}_i, \qquad \forall k \in [K],$$
 (1.13)

$$\widehat{\boldsymbol{\Sigma}}_k = \frac{1}{n\widehat{\pi}_k} \sum_{i=1}^n \tau_{i,k} (\boldsymbol{x}_i - \widehat{\boldsymbol{\mu}}_k) (\boldsymbol{x}_i - \widehat{\boldsymbol{\mu}}_k)^\top, \qquad \forall k \in [K],$$
 (1.14)

$$\widehat{\tau}_{i,k} = \frac{\pi_k \varphi_{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k}(\boldsymbol{x}_i)}{\sum_{k' \in [K]} \pi_{k'} \varphi_{\boldsymbol{\mu}_{k'}, \boldsymbol{\Sigma}_{k'}}(\boldsymbol{x}_i)}, \quad \forall k \in [K], \ \forall i \in [n].$$
(1.15)

Input: data vectors $x_1, \ldots, x_n \in \mathbb{R}^p$ and the number of clusters K Output: parameter estimate $\widehat{\theta} = \{\widehat{\mu}_k, \widehat{\Sigma}_k, \pi_k\}_{k \in [K]}$

1: Initialize t=0, $\theta=\theta^0$.

2: Repeat

3: Update the parameter \mathcal{T} :

$$\tau_{i,k}^t = \frac{\pi_k^t \varphi_{\boldsymbol{\mu}_k^t, \boldsymbol{\Sigma}_k^t}(\boldsymbol{x}_i)}{\sum_{k' \in [K]} \pi_{k'}^t \varphi_{\boldsymbol{\mu}_{k'}^t, \boldsymbol{\Sigma}_{k'}^t}(\boldsymbol{x}_i)}.$$

4: Update the parameter θ :

$$\begin{split} \pi_k^{t+1} &= \frac{1}{n} \sum_{i=1}^n \tau_{i,k}^t, \qquad \pmb{\mu}_k^{t+1} = \frac{1}{n \pi_k^{t+1}} \sum_{i=1}^n \tau_{i,k}^t \pmb{x}_i, \\ \pmb{\Sigma}_k^{t+1} &= \frac{1}{n \pi_k^{t+1}} \sum_{i=1}^n \tau_{i,k}^t (\pmb{x}_i - \pmb{\mu}_k^{t+1}) (\pmb{x}_i - \pmb{\mu}_k^{t+1})^\top. \end{split}$$

5: increment t: t = t + 1.

6: Until stopping rule.

7: Return θ^t .

Figure 1.2: EM algorithm for Gaussian mixtures

Based on this result, the EM algorithm is defined as in Figure 1.2. The algorithm operates iteratively and needs a criterion to determine when the iterations should be stopped. There is no clear consensus on this point in the statistical literature, but it is a commonly used practice to stop when one of the following conditions is fulfilled:

- i) The number of iterations t exceeds a pre-specified level t_{max} .
- ii) The increase of the log-likelihood over past t_0 iterations is not significantly different from zero: $\ell_n(\boldsymbol{\theta}^t) \ell_n(\boldsymbol{\theta}^{t-t_0}) \leq \varepsilon$ for some pre-specified values $t_0 \in \mathbb{N}$ and $\varepsilon > 0$.

EM is conceptually easy and each iteration increases the log-likelihood:

$$\ell_n(\boldsymbol{\theta}^{t+1}) > \ell_n(\boldsymbol{\theta}^t), \quad \forall t \in \mathbb{N}.$$

The complexity at each step of the EM algorithm is $O(Knp^2)$ and it usually requires many iterations to converge. In a high-dimensional setting when p is large, the quadratic dependence on p may result in prohibitively large running times. However, the computation of the elements of the covariance

matrices Σ_k^t and the mean vectors μ_k^t can be parallelized which may lead to considerable savings in the running time.

Chapter 2

Estimating the number of clusters

The idea is to add a regularization term on the estimation of the $n \times K$ matrix \mathcal{T} , the estimate of the number of clusters K will be the number of non-empty columns of \mathcal{T} .

We consider a maximum number of clusters M, we note the convex set $A = \{ \tau \in \mathbb{R}^M : \sum_{k=1}^M \tau_k = 1, \tau_k \geq 0 \ \forall k \in [M] \}$ and the "indicator" function $\chi_A(.)$ defined by:

$$\chi_A(x) = \begin{cases} 0 & \text{if } x \in A, \\ \infty & \text{if } x = 0 \end{cases}$$

We note $\mathcal{T}_{.,k}$ the k^{th} column and $\mathcal{T}_{i,.}$ the i^{th} line of \mathcal{T} . We will estimate \mathcal{T} using the same equation ??, ?? with a regularization term:

$$F^{pen}(\boldsymbol{\theta}, \boldsymbol{\mathcal{T}}) = \sum_{k=1}^{K} \left(\sum_{i=1}^{n} \left\{ \tau_{i,k} \log \varphi_{\boldsymbol{\mu}_{k},\boldsymbol{\Omega}_{k}}(\boldsymbol{x}_{i}) + \tau_{i,k} \log(\pi_{k}/\tau_{i,k}) \right\} - \lambda_{k} ||\boldsymbol{\Omega}_{k}||_{1,1} \right) + \sum_{k=1}^{K} ||\boldsymbol{\mathcal{T}}_{.,k}||_{2} + \sum_{i=1}^{n} \chi_{A}(\boldsymbol{\mathcal{T}}_{i,.})$$

Removing the penalization on Ω :

$$F^{pen}(\boldsymbol{\theta}, \boldsymbol{\mathcal{T}}) = \sum_{k=1}^{K} \left(\sum_{i=1}^{n} \left\{ \tau_{i,k} \log \varphi_{\boldsymbol{\mu}_{k}, \boldsymbol{\Omega}_{k}}(\boldsymbol{x}_{i}) + \tau_{i,k} \log(\pi_{k}/\tau_{i,k}) \right\} + \sum_{k=1}^{K} ||\boldsymbol{\mathcal{T}}_{.,k}||_{2} + \sum_{i=1}^{n} \chi_{A}(\boldsymbol{\mathcal{T}}_{i,.})$$

and the optimization problem:

$$\widehat{\mathcal{T}}(\boldsymbol{\theta}) \in \arg \max_{\boldsymbol{\mathcal{T}}} F^{pen}(\boldsymbol{\theta}, \boldsymbol{\mathcal{T}})$$
 (2.1)

Unfortunately, the regularization term prevents to derive explicit solution as in previous chapters. Furthermore, we cant separate the objective function since we optimize along columns and lines of \mathcal{T} . The objective function $F^{pen}(\theta, \mathcal{T})$ rewritten $F^{pen}_{\theta}(\mathcal{T})$ can be split into two terms:

$$F_{\theta}^{pen}(\mathcal{T}) = f(\mathcal{T}) + g(\mathcal{T}) \tag{2.2}$$

with:

$$f(\mathcal{T}) = \sum_{k=1}^{K} \left(\sum_{i=1}^{n} \left\{ \tau_{i,k} \log \varphi_{\boldsymbol{\mu}_{k},\boldsymbol{\Omega}_{k}}(\boldsymbol{x}_{i}) + \tau_{i,k} \log(\pi_{k}/\tau_{i,k}) \right\} + \sum_{k=1}^{K} ||\mathcal{T}_{.,k}||_{2}$$
$$g(\mathcal{T}) = \sum_{i=1}^{n} \chi_{A}(\mathcal{T}_{i,.})$$

f is convex and differentiable on its domain, g is also convex but not smooth. We will tackle this problem by using a proximal method:

$$\mathcal{T}^{k+1} = \mathbf{prox}_{\lambda g} (\mathcal{T}^k - \lambda \nabla f(\mathcal{T}^k)) = P_A(\mathcal{T}^k - \lambda \nabla f(\mathcal{T}^k)) \\
= \underset{\mathcal{T}: \forall K, \mathcal{T}^k \in A}{\operatorname{arg min}} \left(||\mathcal{T} - (\mathcal{T}^k - \lambda \nabla f(\mathcal{T}^k))||_2^2 \right)$$

The gradient of f on \mathcal{T} is given by:

$$\begin{split} \left[\nabla_{\mathcal{T}} f(\mathcal{T})\right]_{i,j} &= \left[\frac{\partial f}{\partial \mathcal{T}_{ij}}(\mathcal{T})\right]_{i,j} \\ &= \log(\varphi_{\boldsymbol{\mu}_{j},\boldsymbol{\Omega}_{j}}(x_{i})) + \log(\frac{\pi_{j}}{\tau_{i,j}}) + \frac{\tau_{i,j}}{||\mathcal{T}_{..i}||_{2}} - 1 \end{split}$$

We will use FISTA to accelerate the convergence

We use the algorithm of last chapter with the new estimation procedure of ${\mathcal T}$

Input:
Output: parameter estimate
$$\mathcal{T}$$
1: Initialize $t_1 = 1$ and $\boldsymbol{\xi}^0$ with
$$\boldsymbol{\xi}_{i,k}^0 = \frac{\pi_k^0 \varphi_{\boldsymbol{\mu}_k^0, \boldsymbol{\Omega}_k^0}(\boldsymbol{x}_i)}{\sum_{k' \in [K]} \pi_{k'}^0 \varphi_{\boldsymbol{\mu}_k^0, \boldsymbol{\Omega}_{k'}^0}(\boldsymbol{x}_i)}$$
2: Repeat
$$\boldsymbol{\mathcal{T}}^k = \underset{\boldsymbol{\mathcal{T}}: \forall K, \boldsymbol{\mathcal{T}}^k \in A}{\arg\min} \left(||\boldsymbol{\mathcal{T}} - (\boldsymbol{\xi}^k - \lambda \nabla f(\boldsymbol{\xi}^k))||_2^2 \right)$$

$$t^{k+1} = \frac{1 + \sqrt{1 + 4 * (t^k)^2}}{2}$$

$$\boldsymbol{\xi}^{k+1} = \boldsymbol{\mathcal{T}}^k + \left(\frac{t^k - 1}{t^{k+1}} \right) (\boldsymbol{\mathcal{T}}^k - \boldsymbol{\mathcal{T}}^{k-1})$$

Figure 2.1: \mathcal{T} estimation with FISTA

2.1 Sparse Weights Vector Estimation

In previous models, we knew the number of components K in the Gaussian mixture. In reality this parameter is unknown. A common method to select the number of clusters is to use the Bayesian Information Criterion given by:

$$BIC(K) = -\log \ell_n(\widehat{\boldsymbol{\theta}}^K) + K.\log(n)$$
 (2.3)

And select the model which minimizes the BIC. This can be done by running EM algorithm over a large number of models which is computationally expensive. We fit a model with an arbitrarily large number of components K and penalyze the weights vector $\boldsymbol{\pi}$. The penalized negative log-likelihood is:

$$\ell_n(\boldsymbol{\theta}) = -\frac{1}{n} \sum_{i=1}^n \log \left\{ \sum_{j=1}^K \pi_k \varphi_{(\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}(\boldsymbol{x}_i) \right\} + \lambda \sum_{j=1}^{K-1} \pi_j^{1/\gamma} \quad \gamma \ge 1$$
 (2.4)

Such that:

$$\sum_{j=1}^{K-1} \pi_j \le 1 \quad \text{and} \quad \pi_K = 1 - \sum_{j=1}^{K-1} \pi_j$$
 (2.5)

```
Input: data vectors \boldsymbol{x}_1,\dots,\boldsymbol{x}_n\in\mathbb{R}^p and the number of clusters K
Output: parameter estimate \widehat{\boldsymbol{\theta}}=\{\widehat{\boldsymbol{\mu}}_k,\widehat{\boldsymbol{\Omega}}_k,\widehat{\boldsymbol{\pi}}_k\}_{k\in[K]}
1: Initialize t=0, \boldsymbol{\theta}=\boldsymbol{\theta}^0.
2: Repeat
3: Update the parameter \mathcal{T} with previous algorithm
4: Update the parameter \boldsymbol{\theta}:
\boldsymbol{\pi}_k^{t+1}=\frac{1}{n}\sum_{i=1}^n\tau_{i,k}^t,
\boldsymbol{\mu}_k^{t+1}=\frac{1}{n\pi_k^{t+1}}\sum_{i=1}^n\tau_{i,k}^t\boldsymbol{x}_i
\boldsymbol{\Sigma}_{n,k}=\frac{1}{n^2\pi_k^{t+1}}\sum_{i=1}^n\tau_{i,k}^{t+1}(\boldsymbol{x}_i-\widehat{\boldsymbol{\mu}}_k^{t+1})(\boldsymbol{x}_i-\widehat{\boldsymbol{\mu}}_k^{t+1})^{\top}
\boldsymbol{\Omega}_k^{t+1}\in \arg\min_{\boldsymbol{\Omega}\succeq 0}\Big\{-\frac{1}{2}\log|\boldsymbol{\Omega}|+\frac{1}{2}tr(\boldsymbol{\Sigma}_{N,k}\boldsymbol{\Omega})+\frac{\lambda_k}{n\pi_k^{t+1}}||\boldsymbol{\Omega}||_{1,1}\Big\}
5: increment t: t=t+1.
6: Until stopping rule.
7: Return \boldsymbol{\theta}^t.
```

Figure 2.2: Graphical lasso algorithm for Gaussian mixtures with cluster number discovery

and $\sum_{i=1}^{K-1} \pi_{i}^{1/\gamma}$ is not convex, to rectify it let note $\alpha_{j} = \pi^{1/\gamma}$, then:

$$\widehat{\boldsymbol{\alpha}} \in \underset{\boldsymbol{\alpha} \in \mathbb{R}^{K-1}}{\min} \left\{ -\frac{1}{n} \sum_{i=1}^{n} \log \left\{ \sum_{j=1}^{K} \alpha_{j}^{\gamma} \varphi_{(\boldsymbol{\mu}_{j}, \boldsymbol{\Sigma}_{j})}(\boldsymbol{x}_{i}) \right\} + \lambda \sum_{j=1}^{K-1} \alpha_{j} \right\} \quad \gamma \geq 1, \quad (2.6)$$

such that: $\sum_{j=1}^{K-1} \alpha_{j}^{\gamma} \leq 1$ and $\alpha_{K}^{\gamma} = 1 - \sum_{j=1}^{K-1} \alpha_{j}^{\gamma}$. We denote $f_{\theta}(\alpha)$ this cost function.

If we note A the K-1 dimensional unit sphere and χ_A the indicator function of A (0 in A, ∞ elsewhere), the minimization problem can be rewritten as

$$\widehat{\boldsymbol{\alpha}} \in \arg\min_{\boldsymbol{\alpha} \in \mathbb{R}^{K-1}} \{ f_{\boldsymbol{\theta}}(\boldsymbol{\alpha}) + \chi_A(\boldsymbol{\alpha}) \}. \tag{2.7}$$

To solve this minimization problem, we can use a proximal gradient method and Nesterov acceleration for the following iterative procedure:

$$\widehat{\alpha}^{t+1} = \operatorname{prox}_{\chi_A}(\alpha^t - h\nabla f_{\theta}(\alpha^t))$$
(2.8)

$$= \underset{x \in \mathbb{R}^{K-1}}{\operatorname{arg\,min}} \left\{ \chi_A(x) + \frac{1}{2} ||x - (\boldsymbol{\alpha}^t - h\nabla f_{\boldsymbol{\theta}}(\boldsymbol{\alpha}^t))||^2 \right\}$$
 (2.9)

$$= P_A(\boldsymbol{\alpha}^t - h\nabla f_{\boldsymbol{\theta}}(\boldsymbol{\alpha}^t)). \tag{2.10}$$

This iteration procedure gives us the following algorithm

Input: θ

Output: parameter estimate $\widehat{\boldsymbol{\pi}} = (\boldsymbol{\alpha}_1^{\gamma},...,\boldsymbol{\alpha}_{K-1}^{\gamma},1-\sum_{j=1}^{K-1}\boldsymbol{\alpha}_j^{\gamma})^t$ 1: Initialize t=0, $s_0=1$ and $\boldsymbol{\xi}^0 = (\boldsymbol{\pi}_1^{1/\gamma},...,\boldsymbol{\pi}_{K-1}^{1/\gamma})$

1: Initialize
$$t=0$$
, $s_0=1$ and $\boldsymbol{\xi}^0=(\boldsymbol{\pi}_1^{1/7},...,\boldsymbol{\pi}_{K-1}^{1/7})$

2: Repeat

3:

$$\alpha^t = P_A(\xi^t - h\nabla f_{\theta}(\xi^t)) \tag{2.11}$$

$$s_{t+1} = \frac{1 + \sqrt{1 + 4 * s_t^2}}{2} \tag{2.12}$$

$$\boldsymbol{\xi}^{t+1} = \boldsymbol{\alpha}^t + \left(\frac{s_t - 1}{s_{t+1}}\right) \left(\boldsymbol{\alpha}^t - \boldsymbol{\alpha}^{t-1}\right)$$
 (2.13)

increment t: t = t + 1. 5:

Until stopping rule.

Figure 2.3: Estimation of α

and the final algorithm for estimating the gaussian mixture with a penalized weight vector is

Input: data vectors $x_1, \ldots, x_n \in \mathbb{R}^p$ and a large number of clusters K

Output: parameter estimate $\widehat{\boldsymbol{\theta}} = \{\widehat{\boldsymbol{\mu}}_k, \widehat{\boldsymbol{\Sigma}}_k, \widehat{\boldsymbol{\pi}}_k\}_{k \in [K]}$ Initialize t = 0, $\boldsymbol{\theta} = \boldsymbol{\theta}^0$

1: Initialize t=0, $\boldsymbol{\theta}=\boldsymbol{\theta}^0$

2: Repeat

3: Update the parameter ${\mathcal T}$

$$\tau_{i,k}^{t} = \frac{\pi_k^t \varphi_{\boldsymbol{\mu}_k^t, \boldsymbol{\Omega}_k^t}(\boldsymbol{x}_i)}{\sum_{k' \in [K]} \pi_{k'}^t \varphi_{\boldsymbol{\mu}_{k'}^t, \boldsymbol{\Omega}_{k'}^t}(\boldsymbol{x}_i)}.$$
 (2.14)

4: Update parameters μ, Σ .

$$\boldsymbol{\mu}_{k}^{t+1} = \frac{1}{n\pi_{k}^{t+1}} \sum_{i=1}^{n} \tau_{i,k}^{t} \boldsymbol{x}_{i}, \tag{2.15}$$

$$\Sigma_k^{t+1} = \frac{1}{n\pi_k^{t+1}} \sum_{i=1}^n \tau_{i,k}^t (\boldsymbol{x}_i - \boldsymbol{\mu}_k^{t+1}) (\boldsymbol{x}_i - \boldsymbol{\mu}_k^{t+1})^\top.$$
 (2.16)

5: Update the parameter π with previous algorithm

6: increment t: t = t + 1

7: Until stopping rule.

Figure 2.4: Algorithm for estimating sparse weights vector on GMM

Ci-dessous, les résultats de l'algorithme d'estimation parcimonieuse des poids du mélange sur des données simulées. En vert notre algorithme et en rouge la méthode EM+BIC. En abscisse le nombre de vrais clusters, K. En ordonnée, le logarithme de l'erreur $\|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_1$. Pour chaque K, 50 simulations ont été éffectuées. Nous représentons les premiers et troisièmes quartiles ainsi que la médiane.

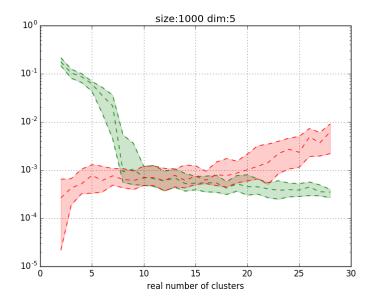


Figure 2.5: Vert: Notre algorithme. Rouge: EM+BIC

Chapter 3

Algorithm 2

We consider the diagonal matrix $D_{\lambda} = diag(\lambda_1, \dots, \lambda_K)$.

Input: data vectors $\boldsymbol{x}_1, \dots, \boldsymbol{x}_n \in \mathbb{R}^p$, the number of clusters K and D_{λ}

Output: parameter estimate $\widehat{\boldsymbol{\theta}} = \{\widehat{\boldsymbol{\mu}}_k, \widehat{\boldsymbol{\Omega}}_k, \pi_k\}_{k \in [K]}$

1: Initialize t=0, $\theta=\theta^0$.

2: Repeat

3: Update the parameter \mathcal{T} :

$$\tau_{i,k}^t = \frac{\pi_k^t \varphi_{\boldsymbol{\mu}_k^t, \boldsymbol{\Omega}_k^t}(\boldsymbol{x}_i)}{\sum_{k' \in [K]} \pi_{k'}^t \varphi_{\boldsymbol{\mu}_{k'}^t, \boldsymbol{\Omega}_{k'}^t}(\boldsymbol{x}_i)}.$$

4: Update the parameter θ :

$$(\mu^k, B^k) \in \underset{(\mu, B) \in \mathbb{R}^p \times \mathbb{R}^{p \times p}, B_{jj} = 1}{\arg \min} \left\{ \frac{1}{N} \sum_{n=1}^N \tau_n^k(t) || (x_n - \mu)^T B ||_2^2 + || D_\lambda B ||_{1,1} \right\}$$

$$\pi_k^{t+1} =$$

$$\mu_k^{t+1} =$$

$$\Omega_k^{t+1}$$

5: increment t: t = t + 1.

6: Until stopping rule.

7: Return θ^t .

Figure 3.1: Lasso for Gaussian mixtures

Chapter 4

structural analysis on Σ approach

We consider a multivariate Gaussian distribution with mean $\boldsymbol{\mu}^*$ and covariance $\boldsymbol{\Sigma}^*$ and $Y_1,\ldots,Y_N\in\mathbb{R}^p$ iid drawn from this distribution. We would like to estimate $\boldsymbol{\mu}^*$ and $\boldsymbol{\Sigma}^*$. We know that $\widehat{\boldsymbol{\mu}}_n=\bar{Y}_n$, then wlog we consider $\boldsymbol{\mu}^*=0$, the problem is to estimate $\boldsymbol{\Sigma}^*$. We will study the precision matrix and consider that $\boldsymbol{\Sigma}^{-1}$ is sparse. We note $\boldsymbol{\Sigma}^{-1}=\Omega$, Y_n the n-th random variable and Y_n^i the i-th component of this vector. If $\boldsymbol{\Sigma}_{ij}^{-1}=0\Rightarrow Y^i\perp\!\!\!\perp Y^j$ conditionally to $Y^{l\neq\{i,j\}}$. Thus, it makes sense to impose a L_1 penalty on $\boldsymbol{\Sigma}^{-1}$ to increase its sparsity.

4.1 Graphical Lasso

Let consider a multivariate normal distribution with parameters μ^* , Σ^* with density;

$$\mathcal{N}(x|\mu^*, \Sigma^*) = \frac{1}{(2\pi)^{d/2} |\Sigma^*|^{1/2}} \exp^{-\frac{1}{2}(x-\mu^*)^T \Sigma^{-1*}(x-\mu^*)}$$
(4.1)

We consider $\mu = 0$. Given N datapoints X_1, \ldots, X_N and $X_i \in \mathbb{R}^d$, the log-likelihood is given by:

$$\mathcal{L}(\Sigma) = \log \left(\prod_{n=1}^{N} \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp^{-\frac{1}{2}(x_n)^T \Sigma^{-1}(x_n)} \right)$$

$$= -\frac{dN}{2} \log 2\pi - \frac{N}{2} \sum_{n=1}^{N} \log |\Sigma^*| - \frac{1}{2} \sum_{n=1}^{N} x_n^T \Sigma^{*,-1} x_n$$
(4.2)

Note that $x_n^T \Sigma^{*,-1} x_n = tr(x_n^T \Sigma^{*,-1} x_n)$, and therefore:

$$\sum_{n=1}^{N} x_n^T \Sigma^{*,-1} x_n = tr\left(\sum_{n=1}^{N} x_n^T \Sigma^{*,-1} x_n\right) = tr\left(\left[\sum_{n=1}^{N} x_n^T x_n\right] \Sigma^{*,-1}\right) = tr(S_N \Sigma^*)$$
(4.3)

Where S_N is the empirical covariance matrix. We can replace that in the log-likelihood expression:

$$\mathcal{L}(\Sigma) = -\frac{dN}{2}\log 2\pi - \frac{N}{2}\sum_{n=1}^{N}\log|\Sigma^*| - \frac{1}{2}tr(S_N\Sigma^*)$$
(4.4)

Finally:

$$\mathcal{L}(\Sigma) = C + \frac{N}{2} \log |\Sigma^{-1}| - \frac{1}{2} tr(S_n \Sigma^{-1})$$

$$\tag{4.5}$$

Where C is a constant (dependent on N). Thus, considering the sparsity of the precision matrix $\Omega = \Sigma^{-1}$, we impose a penalization to the maximum likelihood estimator of Ω

$$\widehat{\Omega} \in argmin\{ \log |\Omega| - tr(S_N\Omega) - \lambda ||\Omega||_1 \}$$
(4.6)

A reason to use the L_1 penalization instead of the ridge is that for an L_p penalization, the problem is convex for $p \geq 1$ and we have parsimonious property for $p \leq 1$. This is a convex optimization problem, however the complexity is $O(p^3)$ (Source, high dim & var select Buhlmann 2006? Wassermann)

4.2 Column-Wise Lasso

We consider a gaussian vector $Y \in \mathbb{R}^d$, $Y \sim \mathcal{N}(0, \Sigma)$. We can write $Y = (Y^1, Y^{2:d})$. With this decomposition we can write the covariance matrix as following:

$$\Sigma = \begin{pmatrix} \sigma_1^2 & \Sigma_{12} & \Sigma_{12}^T & \Sigma_{22} \end{pmatrix} \tag{4.7}$$

and according to theorem[?]: If Σ_{22} is inversible, then:

$$\mathbf{E}[Y^{1}|Y^{2:d}] = \Sigma_{12}\Sigma_{22}^{-1}Y^{2:d}
Var[Y^{1}|Y^{2:d}] = \sigma_{1}^{2} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{12}^{T}$$
(4.8)

We have the following identity:

$$(\omega_{11} \quad \Omega_{12} \quad \Omega_{12}^T \quad \Omega_{22}) (\sigma_1^2 \quad \Sigma_{12} \quad \Sigma_{12}^T \quad \Sigma_{22}) = (1 \quad 0 \quad 0 \quad I_{p-1})$$
 (4.9)

Which gives the following equations:

$$\begin{cases} \omega_{11}\sigma_1^2 + \Omega_{12}\Sigma_{12}^T &= 1 & (*) \\ \omega_{11}\Sigma_{12} + \Omega_{12}\Sigma_{22} &= 0 & (**) \\ \Omega_{12}^T\Sigma_{12} + \Omega_{22}\Sigma_{22} &= I_{p-1} & (***) \end{cases}$$

$$(4.10)$$

With (**) we have $-\omega_{11}\Sigma_{12}\Sigma_{22}^{-1}=\Omega_{12}$ and injected to (*) we have:

$$\begin{cases} \mathbf{E}[Y^{1}|Y^{2:d}] &= -\frac{1}{\omega_{11}}\Omega_{12}Y^{2:d} \\ Var[Y^{1}|Y^{2:d}] &= \frac{1}{\omega_{11}} \end{cases}$$
(4.11)

Finally, $Y^1 - \mathbf{E}[Y^1|Y^{2:d}]$ is a gaussian vector of \mathbb{R}^{d-1} , centered, independent of $Y^{2:d}$ and of covariance matrix $\sigma_1^2 - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{12}^T$. If we denote $\xi^1 \sim \mathcal{N}(0,1)$ we have $Y^1 - \mathbf{E}[Y^1|Y^{2:d}] = \frac{1}{\sqrt{\omega_{11}}}\xi^1$.

Therefore, for Y_1, \ldots, Y_n iid of law $\mathcal{N}(0, \Sigma^*)$ we have:

$$Y_{i}^{1} = -\frac{1}{\omega_{11}^{*}} \Omega_{12} Y_{i}^{2:d} + \frac{1}{\sqrt{\omega_{11}^{*}}} \xi_{i}^{1}$$

$$= -\sum_{j=2}^{d} \frac{w_{ij}^{*}}{\omega_{11}^{*}} Y_{i}^{j} + \frac{1}{\sqrt{\omega_{11}^{*}}} \xi_{i}^{1}$$

$$(4.12)$$

and

$$\beta_1^{*T} Y_i = \frac{1}{\sqrt{\omega_{11}^*}} \xi_i^1 \Rightarrow \beta_1^{*T} \mathbf{Y} = \frac{1}{\sqrt{\omega_{11}^*}} \boldsymbol{\xi}^1$$
 (4.13)

with

$$\beta_1^* = \frac{1}{\sqrt{\omega_{11}^*}} \left[w_{11}^* \ w_{12} \vdots w_{1d} \right] \in \mathbb{R}^d \quad \text{and} \quad \boldsymbol{Y} = \left[verifier \ \right]$$
 (4.14)

4.2.1 The Square-Root Lasso

Chapter 5

Optimal Kullback-Leibler Aggregation in Mixture Density Estimation by Maximum Likelihood

5.1 Abstract

We study the maximum likelihood estimator of density of n independent observations, under the assumption that it is well approximated by a mixture with a large number of components. The main focus is on statistical properties with respect to the Kullback-Leibler loss. We establish risk bounds taking the form of sharp oracle inequalities both in deviation and in expectation. A simple consequence of these bounds is that the maximum likelihood estimator attains the optimal rate $((\log K)/n)^{1/2}$, up to a possible logarithmic correction, in the problem of convex aggregation when the number K of components is larger than $n^{1/2}$. More importantly, under the additional assumption that the Gram matrix of the components satisfies the compatibility condition, the obtained oracle inequalities yield the optimal rate in the sparsity scenario. That is, if the weight vector is (nearly) D-sparse, we get the rate $(D \log K)/n$. As a natural complement to our oracle inequalities, we introduce the notion of nearly-D-sparse aggregation and establish matching lower bounds for this type of aggregation.

5.2 Introduction

Assume that we observe n independent random vectors $X_1, \ldots, X_n \in \mathcal{X}$ drawn from a probability distribution P^* that admits a density function f^* with respect to some reference measure ν . The goal is to estimate the unknown density by a mixture density. More precisely, we assume that for a given family of mixture components f_1, \ldots, f_K , the unknown density of the observations f^* is well approximated by a convex combination f_{π} of these components, where

$$f_{\pi}(\boldsymbol{x}) = \sum_{j=1}^{K} \pi_j f_j(\boldsymbol{x}), \quad \boldsymbol{\pi} \in \mathbb{B}_+^K = \left\{ \boldsymbol{\pi} \in [0, 1]^K : \sum_{j=1}^K \pi_j = 1 \right\}.$$
 (5.1)

The assumption that the component densities $\mathcal{F} = \{f_j : j \in [K]\}$ are known essentially means that they are chosen from a dictionary obtained on the basis of previous experiments or expert knowledge.

We focus on the problem of estimation of the density function f_{π} and the weight vector π from the simplex \mathbb{B}_{+}^{K} under the sparsity scenario: the ambient dimension K can be large, possibly larger than the sample size n, but most entries of π are either equal to zero or very small.

Our goal is to investigate the statistical properties of the Maximum Likelihood Estimator (MLE), defined by

$$\widehat{\boldsymbol{\pi}} \in \underset{\boldsymbol{\pi} \in \Pi}{\operatorname{arg\,min}} \left\{ -\frac{1}{n} \sum_{i=1}^{n} \log f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i}) \right\}, \tag{5.2}$$

where the minimum is computed over a suitably chosen subset Π of \mathbb{B}_+^K . In the present work, we will consider sets $\Pi = \Pi_n(\mu)$, depending on a parameter $\mu > 0$ and the sample $\{\boldsymbol{X}_1, \dots, \boldsymbol{X}_n\}$, defined by

$$\Pi_n(\mu) = \left\{ \boldsymbol{\pi} \in \mathbb{B}_+^K : \min_{i \in [n]} \sum_{j=1}^K \pi_j f_j(\boldsymbol{X}_i) \ge \mu \right\}.$$
 (5.3)

Note that the objective function in (5.2) is convex and the same is true for set (5.3). Therefore, the MLE $\widehat{\pi}$ can be efficiently computed even for large K by solving a problem of convex programming. To ease notation, very often, we will omit the dependence of $\Pi_n(\mu)$ on μ and write Π_n instead of $\Pi_n(\mu)$.

The quality of an estimator $\widehat{\pi}$ can be measured in various ways. For instance, one can consider the Kullback-Leibler divergence

$$KL(f^*||f_{\widehat{\boldsymbol{\pi}}}) = \begin{cases} \int_{\mathcal{X}} f^*(\boldsymbol{x}) \log \frac{f^*(\boldsymbol{x})}{f_{\widehat{\boldsymbol{\pi}}}(\boldsymbol{x})} \nu(d\boldsymbol{x}), & \text{if } P^*(f^*(\boldsymbol{X}) = 0 \text{ and } f_{\widehat{\boldsymbol{\pi}}}(\boldsymbol{X}) > 0) = 0, \\ +\infty, & \text{otherwise,} \end{cases}$$
(5.4)

which has the advantage of bypassing identifiability issues. One can also consider the (well-specified) setting where $f^* = f_{\beta^*}$ for some $\beta^* \in \mathbb{B}_+^K$ and measure the quality of estimation through a distance between the vectors $\widehat{\boldsymbol{\pi}}$ and $\boldsymbol{\pi}^*$ (such as the ℓ_1 -norm $\|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_1$ or the Euclidean norm $\|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_2$). The main contributions of the present work are the following:

- (a) We demonstrate that in the mixture model there is no need to introduce sparsity favoring penalty in order to get optimal rates of estimation under the Kullback-Leibler loss in the sparsity scenario. In fact, the constraint that the weight vector belongs to the simplex acts as a sparsity inducing penalty. As a consequence, there is no need to tune a parameter accounting for the magnitude of the penalty.
- (b) We show that the maximum likelihood estimator of the mixture density simultaneously attains the optimal rate of aggregation for the Kullback-Leibler loss for at least three types of aggregation: model-selection, convex and *D*-sparse aggregation.
- (c) We introduce a new type of aggregation, termed nearly D-sparse aggregation that extends and unifies the notions of convex and D-sparse aggregation. We establish strong lower bounds for the nearly D-sparse aggregation and demonstrate that the maximum likelihood estimator attains this lower bound up to logarithmic factors.

5.2.1 Related work

The results developed in the present work aim to gain a better understanding (a) of the statistical properties of the maximum likelihood estimator over a high-dimensional simplex and (b) of the problem of aggregation of density estimators under the Kullback-Leibler loss. Various procedures of aggregation¹ for density estimation have been studied in the literature with respect to different loss functions. [Catoni, 1997, Yang, 2000, Juditsky et al., 2008] investigated different variants of the progressive mixture rules, also known as mirror averaging [Yuditskiĭ et al., 2005, Dalalyan and Tsybakov, 2012], with respect to the Kullback-Leibler loss and established model selection type oracle inequalities² in expectation. Same type of guarantees, but holding with high probability, were recently obtained in [Bellec, 2014, Butucea et al., 2016]

¹We refer the interested reader to [Tsybakov, 2014] for an up to date introduction into aggregation of statistical procedures.

²This means that they prove that the expected loss of the aggregate is almost as small as the loss of the best element of the dictionary $\{f_1, \ldots, f_K\}$.

for the procedure termed Q-aggregation, introduced in other contexts by [Dai et al., 2012, Rigollet, 2012].

Aggregation of estimators of a probability density function under the L_2 -loss was considered in [Rigollet and Tsybakov, 2007], where it was shown that a suitably chosen unbiased risk estimate minimizer is optimal both for convex and linear aggregation. The goal in the present work is to go beyond the settings of the aforementioned papers in that we want simultaneously to do as well as the best element of the dictionary, the best convex combination of the dictionary elements but also the best sparse convex combination. Note that the latter task was coined D-aggregation in [Lounici, 2007] (see also [Bunea et al., 2007]). In the present work, we rename it in D-sparse aggregation, in order to make explicit its relation to sparsity.

Key differences between the latter work and ours are that we do not assume the sparsity index to be known and we are analyzing an aggregation strategy that is computationally tractable even for large K. This is also the case of [Bunea et al., 2010, Bertin et al., 2011], which are perhaps the most relevant references to the present work. These papers deal with the L_2 -loss and investigate the lasso and the Dantzig estimators, respectively, suitably adapted to the problem of density estimation. Their methods handle dictionary elements $\{f_j\}$ which are not necessarily probability density functions, but has the drawback of requiring the choice of a tuning parameter. This choice is a nontrivial problem in practice. Instead, we show here that the optimal rates of sparse aggregation with respect to the Kullback-Leibler loss can be attained by procedure which is tuning parameter free.

Risk bounds for the maximum likelihood and other related estimators in the mixture model have a long history [Li and Barron, 1999, Li, 1999, Rakhlin et al., 2005]. For the sake of comparison we recall here two elegant results providing non-asymptotic guarantees for the Kullback-Leibler loss.

Theorem 5.2.1 (Theorem 5.1 in [Li, 1999]). Let \mathcal{F} be a finite dictionary of cardinality K of density functions such that $\max_{f \in \mathcal{F}} \|f^*/f\|_{\infty} \leq V$. Then, the maximum likelihood estimator over \mathcal{F} , $\widehat{f}_{\mathcal{F}}^{\mathrm{ML}} \in \arg\max_{f \in \mathcal{F}} \sum_{i=1}^{n} \log f(\mathbf{X}_i)$, satisfies the inequality

$$\mathbf{E}_{f^*} \left[\mathrm{KL} \left(f^* || \widehat{f}_{\mathcal{F}}^{\mathrm{ML}} \right) \right] \le \left(2 + \log V \right) \left(\min_{f \in \mathcal{F}} \mathrm{KL} (f^* || f) + \frac{2 \log K}{n} \right). \tag{5.5}$$

Inequality (5.5) is an inexact oracle inequality in expectation that quantifies the ability of $\widehat{f}_{\mathcal{F}}^{\mathrm{ML}}$ to solve the problem of model-selection aggregation. The adjective inexact refers to the fact that the "bias term" $\min_{f \in \mathcal{F}} \mathrm{KL}(f^*||f)$ is multiplied by factor strictly larger than one. It is noteworthy that the

remainder term $\frac{2\log K}{n}$ corresponds to the optimal rate of model-selection aggregation [Juditsky and Nemirovski, 2000, Tsybakov, 2003]. In relation with Theorem 5.2.1, it is worth mentioning a result of [Yang, 2000] and [Catoni, 1997], see also Theorem 5 in [Lecué, 2006] and Corollary 5.4 in [Juditsky et al., 2008], establishing a risk bound similar to (5.5) without the extra factor $2 + \log V$ for the so called mirror averaging aggregate.

Theorem 5.2.2 (page 226 in [Rakhlin et al., 2005]). Let \mathcal{F} be a finite dictionary of cardinality K of density functions and let $\mathcal{C}_k = \{f_{\pi} : \|\pi\|_0 \leq k\}$ be the set of all the mixtures of at most k elements of \mathcal{F} ($k \in [K]$). Assume that f^* and the densities f_k from \mathcal{F} are bounded from below and above by some positive constants m and M, respectively. Then, there is a constant C depending only on m and M such that, for any tolerance level $\delta \in (0,1)$, the maximum likelihood estimator over \mathcal{C}_k , $\widehat{f}_{\mathcal{C}_k}^{\mathrm{ML}} \in \arg\max_{f \in \mathcal{C}_k} \sum_{i=1}^n \log f(\mathbf{X}_i)$, satisfies the inequality

$$KL(f^*||\widehat{f}_{\mathcal{C}_k}^{ML}) \le \min_{f \in \mathcal{C}_k} KL(f^*||f) + C\left(\frac{\log(K/\delta)}{n}\right)^{1/2}$$
(5.6)

with probability at least $1 - \delta$.

This result is remarkably elegant and can be seen as an exact oracle inequality in deviation for D-sparse aggregation (for D=k). Furthermore, if we choose k=K in Theorem 5.2.2, then we get an exact oracle inequality for convex aggregation with a rate-optimal remainder term [Tsybakov, 2003]. However, it fails to provide the optimal rate for D-sparse aggregation.

Closing this section, we would like to mention the recent work [Xia and Koltchinskii, 2016], where oracle inequalities for estimators of low rank density matrices are obtained. They share a common feature with those obtained in this work: the adaptation to the unknown sparsity or rank is achieved without any additional penalty term. The constraint that the unknown parameter belongs to the simplex acts as a sparsity inducing penalty.

5.2.2 Additional notation

In what follows, for any $i \in [n]$, we denote by \mathbf{Z}_i the vector $[f_1(\mathbf{X}_i), \dots, f_K(\mathbf{X}_i)]^{\top}$ and by \mathbf{Z} the $n \times K$ matrix $[\mathbf{Z}_1^{\top}, \dots, \mathbf{Z}_n^{\top}]^{\top}$. We also define $\ell(u) = -\log u$, $u \in (0, +\infty)$, so that the MLE $\widehat{\boldsymbol{\pi}}$ is the minimizer of the function

$$L_n(\boldsymbol{\pi}) = \frac{1}{n} \sum_{i=1}^n \ell(\boldsymbol{Z}_i^{\top} \boldsymbol{\pi}). \tag{5.7}$$

For any set of indices $J \subseteq [K]$ and any $\boldsymbol{\pi} = (\pi_1, \dots, \pi_K)^\top \in \mathbb{R}^K$, we define $\boldsymbol{\pi}_J$ as the K-dimensional vector whose j-th coordinate equals π_j if $j \in J$ and 0 otherwise. We denote the cardinality of any $J \subseteq [K]$ by |J|. For any set $J \subset \{1, \dots, K\}$ and any constant $c \geq 0$, we introduce the compatibility constants [van de Geer and Bühlmann, 2009] of a $K \times K$ positive semidefinite matrix \mathbf{A} ,

$$\kappa_{\mathbf{A}}(J, c) = \inf \left\{ \frac{c^2 |J| \|\mathbf{A}^{1/2} \boldsymbol{v}\|_2^2}{(c \|\boldsymbol{v}_J\|_1 - \|\boldsymbol{v}_{J^c}\|_1)^2} : \boldsymbol{v} \in \mathbb{R}^K, \|\boldsymbol{v}_{J^c}\| < c \|\boldsymbol{v}_J\|_1 \right\}, \quad (5.8)$$

$$\bar{\kappa}_{\mathbf{A}}(J,c) = \inf \left\{ \frac{|J| \|\mathbf{A}^{1/2} \mathbf{v}\|_{2}^{2}}{\|\mathbf{v}_{J}\|_{1}^{2}} : \mathbf{v} \in \mathbb{R}^{K}, \|\mathbf{v}_{J^{c}}\|_{1} < c \|\mathbf{v}_{J}\|_{1} \right\}.$$
 (5.9)

The risk bounds established in the present work involve the factors $\kappa_{\mathbf{A}}(J,3)$ and $\bar{\kappa}_{\mathbf{A}}(J,1)$. One can easily check that $\bar{\kappa}_{\mathbf{A}}(J,3) \leq \kappa_{\mathbf{A}}(J,3) \leq \frac{9}{4}\bar{\kappa}_{\mathbf{A}}(J,1)$. We also recall that the compatibility constants of a matrix \mathbf{A} are bounded from below by the smallest eigenvalue of \mathbf{A} .

Let us fix a function $f_0: \mathcal{X} \to \mathbb{R}$ and denote $\bar{f}_k = f_k - f_0$ and $\bar{Z}_i = [\bar{f}_1(X_i), \dots, \bar{f}_K(X_i)]^{\top}$ for $i \in [n]$. In the results of this work, the compatibility factors are used for the empirical and population Gram matrices of vectors \bar{Z}_k , that is when $\mathbf{A} = \widehat{\Sigma}_n$ and $\mathbf{A} = \Sigma$ with

$$\widehat{\boldsymbol{\Sigma}}_n = \frac{1}{n} \sum_{i=1}^n \bar{\boldsymbol{Z}}_i \bar{\boldsymbol{Z}}_i^\top, \qquad \boldsymbol{\Sigma} = \mathbf{E}[\bar{\boldsymbol{Z}}_1 \bar{\boldsymbol{Z}}_1^\top]. \tag{5.10}$$

The general entries of these matrices are respectively $(\widehat{\boldsymbol{\Sigma}}_n)_{k,l} = \frac{1}{n} \sum_{i=1}^n \bar{f}_k(\boldsymbol{X}_i) \bar{f}_l(\boldsymbol{X}_i)$ and $(\boldsymbol{\Sigma})_{k,l} = \mathbf{E}[\bar{f}_k(\boldsymbol{X}_1)\bar{f}_l(\boldsymbol{X}_1)].$

We assume that there exist positive constants m and M such that for all densities f_k with $k \in [K]$, we have

$$\forall x \in \mathcal{X}, \quad m \le f_k(x) \le M. \tag{5.11}$$

We use the notation V=M/m. It is worth mentioning that the set of dictionaries satisfying simultaneously this boundedness assumption and the aforementioned compatibility condition is not empty. For instance, one can consider the functions $f_k(x)=1+1/2\sin(2\pi kx)$ for $k\in[K]$. These functions are probability densities w.r.t. the Lebesgue measure on $\mathcal{X}=[0,1]$. They are bounded from below and from above by 1/2 and 3/2, respectively. Taking $f_0(x)=1$, the corresponding Gram matrix is $\Sigma=1/8\,\mathrm{I}_K$, which has all eigenvalues equal to 1/8.

5.2.3 Agenda

The rest of the paper is organized as follows. In Section 5.3, we state our main theoretical contributions and discuss their consequences. Possible relaxations of the conditions, as well as lower bounds showing the tightness of the established risk bounds, are considered in Section 5.4. A brief summary of the paper and some future directions of research are presented in Section 5.5. The proofs of all theoretical results are postponed to Section 5.6 and Section 5.7.

5.3 Oracle inequalities in deviation and in expectation

In this work, we prove several non-asymptotic risk bounds that imply, in particular, that the maximum likelihood estimator is optimal in model-selection aggregation, convex aggregation and D-sparse aggregation (up to log-factors). In all the results of this section we assume the parameter μ in (5.3) to be equal to 0.

Theorem 5.3.1. Let \mathcal{F} be a set of $K \geq 4$ densities satisfying the boundedness condition (5.11). Denote by $f_{\widehat{\pi}}$ the mixture density corresponding to the maximum likelihood estimator $\widehat{\pi}$ over Π_n defined in (5.7). There are constants $c_1 \leq 32V^3$, $c_2 \leq 288M^2V^6$ and $c_3 \leq 128M^2V^6$ such that, for any $\delta \in (0, 1/2)$, the following inequalities hold

$$KL(f^*||f_{\widehat{\pi}}) \le \inf_{\substack{J \subset [K] \\ \boldsymbol{\pi} \in \mathbb{B}_+^K}} \left\{ KL(f^*||f_{\boldsymbol{\pi}}) + c_1 \left(\frac{\log(K/\delta)}{n} \right)^{1/2} \|\boldsymbol{\pi}_{J^c}\|_1 + \frac{c_2|J|\log(K/\delta)}{n\kappa_{\widehat{\Sigma}_n}(J,3)} \right\},$$
(5.12)

$$\operatorname{KL}(f^*||f_{\widehat{\pi}}) \leq \inf_{\substack{J \subset [K] \\ \pi_{I^c} = 0}} \inf_{\substack{\pi \in \mathbb{B}_+^K \\ \pi_{I^c} = 0}} \left\{ \operatorname{KL}(f^*||f_{\pi}) + \frac{c_3|J|\log(K/\delta)}{n\bar{\kappa}_{\widehat{\Sigma}_n}(J,1)} \right\}$$
(5.13)

with probability at least $1 - \delta$.

The proof of this and the subsequent results stated in this section are postponed to Section 5.6. Comparing the two inequalities of the above theorem, one can notice two differences. First, the term proportional to $\|\boldsymbol{\pi}_{J^c}\|_1$ is absent in the second risk bound, which means that the risk of the MLE is compared to that of the best mixture with a weight sequences supported by J. Hence, this risk bound is weaker than the first one provided by (5.12).

Second, the compatibility factor $\bar{\kappa}_{\widehat{\Sigma}_n}(J,1)$ in (5.13) is larger that its counterpart $\kappa_{\widehat{\Sigma}_n}(J,3)$ in (5.12). This entails that in the cases where the oracle is expected to be sparse, the remainder term of the bound in (5.12) is slightly looser than that of (5.13).

A first and simple consequence of Theorem 5.2.1 is obtained by taking $J = \emptyset$ in the right hand side of the first inequality. Then, $\|\boldsymbol{\pi}_{J^c}\|_1 = \|\boldsymbol{\pi}\|_1 = 1$ and we get

$$KL(f^*||f_{\widehat{\boldsymbol{\pi}}}) \le \inf_{\boldsymbol{\pi} \in \mathbb{B}_+^K} KL(f^*||f_{\boldsymbol{\pi}}) + c_1 \left(\frac{\log(K/\delta)}{n}\right)^{1/2}.$$
 (5.14)

This implies that for every dictionary \mathcal{F} , without any assumption on the smallness of the coherence between its elements, the maximum likelihood estimator achieves the optimal rate of convex aggregation, up to a possible logarithmic correction, in the high-dimensional regime $K \geq n^{1/2}$. In the case of regression with random design, an analogous result has been proved by Lecué and Mendelson [2013] and Lecué [2013]. One can also remark that the upper bound in (5.14) is of the same form as the one of Theorem 5.2.2 stated in section 5.2.1 above.

The main compelling feature of our results is that they show that the MLE adaptively achieves the optimal rate of aggregation not only in the case of convex aggregation, but also for the model-selection aggregation and D-(convex) aggregation. For handling these two cases, it is more convenient to get rid of the presence of the compatibility factor of the empirical Gram matrix $\hat{\Sigma}_n$. The latter can be replaced by the compatibility factor of the population Gram matrix, as stated in the next result.

Theorem 5.3.2. Let \mathcal{F} be a set of K densities satisfying the boundedness condition (5.11). Denote by $f_{\widehat{\pi}}$ the mixture density corresponding to the maximum likelihood estimator $\widehat{\pi}$ over Π_n defined in (5.7). There are constants $c_4 \leq 32V^3 + 4$, $c_5 \leq 4.5M^2(8V^3 + 1)^2$ and $c_6 \leq 2M^2(8V^3 + 1)^2$ such that, for any $\delta \in (0, 1/2)$, the following inequalities hold

$$KL(f^*||f_{\widehat{\pi}}) \leq \inf_{\substack{J \subset [K] \\ \pi \in \mathbb{B}_+^K}} \left\{ KL(f^*||f_{\pi}) + c_4 \left(\frac{\log(K/\delta)}{n} \right)^{1/2} \|\pi_{J^c}\|_1 + \frac{c_5 |J| \log(K/\delta)}{n \kappa_{\Sigma}(J,3)} \right\},$$
(5.15)

$$\operatorname{KL}(f^*||f_{\widehat{\pi}}) \leq \inf_{\substack{J \subset [K] \\ \pi_{J^c} = 0}} \inf_{\substack{\pi \in \mathbb{B}_+^K \\ \pi_{J^c} = 0}} \left\{ \operatorname{KL}(f^*||f_{\pi}) + \frac{c_6|J|\log(K/\delta)}{n\bar{\kappa}_{\Sigma}(J,1)} \right\}$$
(5.16)

³In fact, the optimal rate of convex aggregation when $K \geq n^{1/2}$ is of order $\left(\frac{\log(K/n^{1/2})}{n}\right)^{1/2}$. Therefore, even the $\log K$ term is optimal whenever $K \geq Cn^{1/2+\alpha}$ for some $\alpha > 0$.

with probability at least $1-2\delta$.

The main advantage of the upper bounds provided by Theorem 5.3.2 as compared with those of Theorem 5.3.1 is that the former is deterministic, whereas the latter involves the compatibility factor of the empirical Gram matrix which is random. The price to pay for getting rid of randomness in the risk bound is the increased values of the constants c_4 , c_5 and c_6 . Note, however, that this price is not too high, since obviously $1 \le M \le L$ and, therefore, $c_4 \le 1.25c_1$, $c_5 \le 1.56c_2$ and $c_6 \le 1.56c_3$. In addition, the absence of randomness in the risk bound allows us to integrate it and to convert the bound in deviation into a bound in expectation.

Theorem 5.3.3 (Bound in Expectation). Let \mathcal{F} be a set of K densities satisfying the boundedness condition (5.11). Denote by $f_{\widehat{\pi}}$ the mixture density corresponding to the maximum likelihood estimator $\widehat{\pi}$ over Π_n defined in (5.7). There are constants $c_7 \leq 20V^3 + 8$, $c_8 \leq M^2(22V^3 + 3)^2$ and $c_9 \leq M^2(15V^3 + 2)^2$ such that

$$\mathbf{E}[\mathrm{KL}(f^*||f_{\widehat{\boldsymbol{\pi}}})] \leq \inf_{\substack{J \subset [K] \\ \boldsymbol{\pi} \in \mathbb{B}_+^K}} \left\{ \mathrm{KL}(f^*||f_{\boldsymbol{\pi}}) + c_7 \left(\frac{\log K}{n}\right)^{1/2} \|\boldsymbol{\pi}_{J^c}\|_1 + \frac{c_8|J|\log K}{n\kappa_{\boldsymbol{\Sigma}}(J,3)} \right\},\tag{5.17}$$

$$\mathbf{E}[\mathrm{KL}(f^*||f_{\widehat{\pi}})] \le \inf_{\substack{J \subset [K] \\ \pi_{|U} = 0}} \inf_{\substack{\pi \in \mathbb{B}_+^K \\ \pi_{|U} = 0}} \left\{ \mathrm{KL}(f^*||f_{\pi}) + \frac{c_9|J|\log K}{n\bar{\kappa}_{\Sigma}(J,1)} \right\}.$$
 (5.18)

In inequality (5.18), upper bounding the infimum over all sets J by the infimum over the singletons, we get

$$\mathbf{E}[\mathrm{KL}(f^*||f_{\widehat{\pi}})] \le \inf_{j \in [K]} \left\{ \mathrm{KL}(f^*||f_j) + \frac{c_9 \log K}{n\bar{\kappa}_{\Sigma}(J,1)} \right\}. \tag{5.19}$$

This implies that the maximum likelihood estimator $f_{\hat{\pi}}$ achieves the rate $\frac{\log K}{n}$ in model-selection type aggregation. This rate is known to be optimal in the model of regression [Rigollet, 2012]. If we compare this result with Theorem 5.2.1 stated in Section 5.2.1, we see that the remainder terms of these two oracle inequalities are of the same order (provided that the compatibility factor is bounded away from zero), but inequality (5.19) has the advantage of being exact.

We can also apply (5.18) to the problem of convex aggregation with small dictionary, that is for K smaller than $n^{1/2}$. Upper bounding |J| by |K|, we get

$$\mathbf{E}[\mathrm{KL}(f^*||f_{\widehat{\pi}})] \le \inf_{\boldsymbol{\pi} \in \mathbb{B}_+^K} \mathrm{KL}(f^*||f_{\boldsymbol{\pi}}) + \frac{c_9 K \log K}{n\bar{\kappa}_{\boldsymbol{\Sigma}}([K], 1)}.$$
 (5.20)

Assuming, for instance, the smallest eigenvalue of Σ bounded away from zero (which is a quite reasonable assumption in the context of low dimensionality), the above upper bound provides a rate of convex aggregation of the order of $\frac{K \log K}{n}$. Up to a logarithmic term, this rate is known to be optimal for convex aggregation in the model of regression.

Finally, considering all the sets J of cardinal smaller than D (with $D \le K$) and setting $\bar{\kappa}_{\Sigma}(D, 1) = \inf_{J:|J| \le D} \bar{\kappa}_{\Sigma}(J, 1)$, we deduce from (5.18) that

$$\mathbf{E}[\mathrm{KL}(f^*||f_{\widehat{\pi}})] \le \inf_{\boldsymbol{\pi} \in \mathbb{B}_+^K: \|\boldsymbol{\pi}\|_0 \le D} \mathrm{KL}(f^*||f_{\boldsymbol{\pi}}) + \frac{c_9 D \log K}{n\bar{\kappa}_{\boldsymbol{\Sigma}}(D, 1)}.$$
 (5.21)

According to [Rigollet and Tsybakov, 2011, Theorem 5.3], in the regression model, the optimal rate of D-sparse aggregation is of order $(D/n)\log(K/D)$, whenever $D=o(n^{1/2})$. Inequality (5.21) shows that the maximum likelihood estimator over the simplex achieves this rate up to a logarithmic factor. Furthermore, this logarithmic inflation disappears when the sparsity D is such that, asymptotically, the ratio $\frac{\log D}{\log K}$ is bounded from above by a constant $\alpha < 1$. Indeed, in such a situation the optimal rate $\frac{D \log (K/D)}{n} = \frac{D \log K}{n} (1 - \frac{\log D}{\log K})$ is of the same order as the remainder term in (5.21), that is $\frac{D \log K}{n}$.

5.4 Discussion of the conditions and possible extensions

In this section, we start by announcing lower bounds for the Kullback-Leibler aggregation in the problem of density estimation. Then we discuss the implication of the risk bounds of the previous section to the case where the target is the weight vector $\boldsymbol{\pi}$ rather than the mixture density $f_{\boldsymbol{\pi}}$. Finally, we present some extensions to the case where the boundedness assumption is violated.

5.4.1 Lower bounds for nearly-D-sparse aggregation

As mentioned in previous section, the literature is replete with lower bounds on the minimax risk for various types of aggregation. However most of them concern the regression setting either with random or with deterministic design. Lower bounds of aggregation for density estimation were first established by Rigollet [2006] for the L_2 -loss. In the case of Kullback-Leibler aggregation in density estimation, the only lower bounds we are aware are those established by Lecué [2006] for model-selection type aggregation. It is worth emphasizing here that the results of the aforementioned two papers

provide weak lower bounds. Indeed, they establish the existence of a dictionary for which the minimax excess risk is lower bounded by the suitable quantity. In contrast with this, we establish here strong lower bounds that hold for every dictionary satisfying the boundedness and the compatibility conditions.

Let $\mathcal{F} = \{f_1, \ldots, f_K\}$ be a dictionary of density functions on $\mathcal{X} = [0, 1]$. We say that the dictionary \mathcal{F} satisfies the boundedness and the compatibility assumptions if for some positive constants m, M and κ , we have $m \leq f_j(x) \leq M$ for all $j \in [K]$, $x \in \mathcal{X}$. In addition, we assume in this subsection that all the eigenvalues of the Gram matrix Σ belong to the interval $[\varkappa_*, \varkappa^*]$, with $\varkappa_* > 0$ and $\varkappa^* < \infty$.

For every $\gamma \in (0,1)$ and any $D \in [K]$, we define the set of nearly-D-sparse convex combinations of the dictionary elements $f_j \in \mathcal{F}$ by

$$\mathcal{H}_{\mathcal{F}}(\gamma, D) = \Big\{ f_{\boldsymbol{\pi}} : \boldsymbol{\pi} \in \mathbb{B}_{+}^{K} \text{ such that } \exists J \subset [K] \text{ with } \|\boldsymbol{\pi}_{J^{c}}\|_{1} \leq \gamma \text{ and } |J| \leq D \Big\}.$$

$$(5.22)$$

In simple words, f_{π} belongs to $\mathcal{H}_{\mathcal{F}}(\gamma, D)$ if it admits a γ -approximately D-sparse representation in the dictionary \mathcal{F} . We are interested in bounding from below the minimax excess risk

$$\mathcal{R}\left(\mathcal{H}_{\mathcal{F}}(\gamma, D)\right) = \inf_{\widehat{f}} \sup_{f^*} \left\{ \mathbf{E}[\mathrm{KL}(f^*||\widehat{f})] - \inf_{f_{\pi} \in \mathcal{H}_{\mathcal{F}}(\gamma, D)} \mathrm{KL}(f^*||f_{\pi}) \right\}, \quad (5.23)$$

where the inf is over all possible estimators of f^* and the sup is over all density functions over [0,1]. Note that the estimator \hat{f} is not necessarily a convex combination of the dictionary elements. Furthermore, it is allowed to depend on the parameters γ and D characterizing the class $\mathcal{H}_{\mathcal{F}}(\gamma, D)$. It follows from (5.17), that if the dictionary satisfies the boundedness and the compatibility condition, then

$$\mathcal{R}(\mathcal{H}_{\mathcal{F}}(\gamma, D)) \le C\left\{ \left(\frac{\gamma^2 \log K}{n}\right)^{1/2} + \frac{D \log K}{n} \right\} \bigwedge \left(\frac{\log K}{n}\right)^{1/2}, \tag{5.24}$$

for some constant C depending only on m, M and \varkappa_* . Note that the last term accounts for the following phenomenon: If the sparsity index D is larger than a multiple of \sqrt{n} , then the sparsity bears no advantage as compared to the ℓ_1 constraint. The next result implies that this upper bound is optimal, at least up to logarithmic factors.

Theorem 5.4.1. Assume that $\log(1 + eK) \leq n$. Let $\gamma \in (0,1)$ and $D \in [K]$ be fixed. There exists a constant A depending only on m, M, \varkappa_* and \varkappa^* such that

$$\mathcal{R}(\mathcal{H}_{\mathcal{F}}(\gamma, D)) \ge A \left\{ \left[\frac{\gamma^2}{n} \log \left(1 + \frac{K}{\gamma \sqrt{n}} \right) \right]^{1/2} + \frac{D \log(1 + K/D)}{n} \right\} \bigwedge \left[\frac{1}{n} \log \left(1 + \frac{K}{\sqrt{n}} \right) \right]^{1/2}.$$
(5.25)

This is the first result providing lower bounds on the minimax risk of aggregation over nearly-D-sparse aggregates. To the best of our knowledge, even in the Gaussian sequence model, such a result has not been established to date. It has the advantage of unifying the results on convex and D-sparse aggregation, as well as extending them to a more general class. Let us also stress that the condition $\log(1+eK) \leq n$ is natural and unavoidable, since it ensures that the right hand side of (5.24) is smaller than the trivial bound $\log V$.

5.4.2 Weight vector estimation

The risk bounds carried out in the previous section for the problem of density estimation in the Kullback-Leibler loss imply risk bounds for the problem of weight vector estimation. Indeed, under the boundedness assumption (5.11), the Kullback-Leibler divergence between two mixture densities can be shown to be equivalent to the squared Mahalanobis distance between the weight vectors of these mixtures with respect to the Gram matrix. In order to go from the Mahalanobis distance to the Euclidean one, we make use of the restricted eigenvalue

$$\kappa_{\boldsymbol{\Sigma}}^{\mathrm{RE}}(s,c) = \inf \left\{ \|\boldsymbol{\Sigma}^{1/2} \boldsymbol{v}\|_{2}^{2} : \exists J \subset [K] \text{ s.t. } |J| \leq s, \ \|\boldsymbol{v}_{J^{c}}\|_{1} \leq c \|\boldsymbol{v}_{J}\|_{1} \text{ and } \|\boldsymbol{v}_{J}\|_{2} = 1 \right\}. \tag{5.26}$$

This strategy leads to the next result.

Proposition 1. Let \mathcal{F} be a set of $K \geq 4$ densities satisfying condition (5.11). Denote by $f_{\widehat{\pi}}$ the mixture density corresponding to the maximum likelihood estimator $\widehat{\pi}$ over Π_n defined in (5.7). Let π^* the weight-vector of the best mixture density: $\pi^* \in \arg\min_{\pi} \mathrm{KL}(f^*||f_{\pi})$, and let J^* be the support of π^* . There are constants $c_{10} \leq M^2(64V^3 + 8)$ and $c_{11} \leq 4M^2(8V^3 + 1)$ such that, for any $\delta \in (0, 1/2)$, the following inequalities hold

$$\|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_1 \le \frac{c_{10}|J^*|}{\bar{\kappa}_{\Sigma}(J^*, 1)} \left(\frac{\log(K/\delta)}{n}\right)^{1/2},$$
 (5.27)

$$\|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_2 \le \frac{c_{11}}{\kappa_{\Sigma}^{\text{RE}}(|J^*|, 1)} \left(\frac{2|J^*|\log(K/\delta)}{n}\right)^{1/2},$$
 (5.28)

$$\|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_2^2 \le \frac{c_{11}}{\kappa_{\mathbf{\Sigma}}^{\text{RE}}(|J^*|, 1)} \left(\frac{2\log(K/\delta)}{n}\right)^{1/2} \tag{5.29}$$

with probability at least $1-2\delta$.

In simple words, this result tells us that the wight estimator $\widehat{\pi}$ attains the minimax rate of estimation $|J^*|(\frac{\log(K)}{n})^{1/2}$ over the intersection of the ℓ_1

and ℓ_0 balls, when the error is measured by the ℓ_1 -norm, provided that the compatibility factor of the dictionary \mathcal{F} is bounded away from zero. The optimality of this rate—up to logarithmic factors—follows from the fact that the error of estimation of each nonzero coefficients of π^* is at least $cn^{-1/2}$ (for some c > 0), leading to a sum of the absolute values of the errors at least of the order $|J^*|n^{-1/2}$. The logarithmic inflation of the rate is the price to pay for not knowing the support J^* . It is clear that this reasoning is valid only when the sparsity $|J^*|$ is of smaller order than $n^{1/2}$. Indeed, in the case $|J^*| \geq cn^{1/2}$, the trivial bound $\|\widehat{\pi} - \pi^*\|_1 \leq 2$ is tighter than the one in (5.27).

Concerning the risk measured by the Euclidean norm, we underline that there are two regimes characterized by the order between upper bounds in (5.28) and (5.29). Roughly speaking, when the signal is highly sparse in the sense that $|J^*|$ is smaller than $(n/\log K)^{1/2}$, then the smallest bound is given by (5.28) and is of the order $\frac{|J^*|\log(K)|}{n}$. This rate is can be compared to the rate $\frac{|J^*|\log(K/|J^*|)}{n}$, known to be optimal in the Gaussian sequence model. In the second regime corresponding to mild sparsity, $|J^*| > (n/\log K)^{1/2}$, the smallest bound is the one in (5.29). The latter is of order $(\frac{\log(K)}{n})^{1/2}$, which is known to be optimal in the Gaussian sequence model. For various results providing lower bounds in regression framework we refer the interested reader to [Raskutti et al., 2011, Rigollet and Tsybakov, 2011, Wang et al., 2014].

5.4.3 Extensions to the case of vanishing components

In the previous sections we have deliberately avoided any discussion of the role of the parameter μ , present in the search space $\Pi_n(\mu)$ of the problem (5.2)-(5.3). In fact, when all the dictionary elements are separated from zero by a constant m, a condition assumed throughout previous sections, choosing any value of $\mu \leq m$ is equivalent to choosing $\mu = 0$. Therefore, the choice of this parameter does not impact the quality of estimation. However, this parameter might have strong influence in practice both on statistical and computational complexity of the maximum likelihood estimator. A first step in understanding the influence of μ on the statistical complexity is made in the next paragraphs.

Let us consider the case where the condition $\min_x \min_j f_j(x) \geq m > 0$ fails, but the upper-boundedness condition $\max_x \max_j f_j(x) \leq M$ holds true. In such a situation, we replace the definition V = M/m by $V = M/\mu$. We also define the set $\Pi^*(\mu) = \{ \pi \in \mathbb{B}_+^K : P^*(f_{\pi}(X) \geq \mu) = 1 \}$. In order to keep mathematical formulae simple, we will only state the equivalent of (5.13) in the case of m = 0. All the other results of the previous section can be extended in a similar way.

Proposition 2. Let \mathcal{F} be a set of $K \geq 2$ densities satisfying the boundedness condition $\sup_{\boldsymbol{x} \in \mathcal{X}} f_j(\boldsymbol{x}) \leq M$. Denote by $f_{\widehat{\boldsymbol{\pi}}}$ the mixture density corresponding to the maximum likelihood estimator $\widehat{\boldsymbol{\pi}}$ over $\Pi_n(\mu)$ defined in (5.7). There is a constant $\overline{c} \leq 128M^2V^4$ such that, for any $\delta \in (0, 1/2)$,

$$\operatorname{KL}(f^*||f_{\widehat{\boldsymbol{\pi}}}) \leq \inf_{\substack{J \subset [K] \\ \boldsymbol{\pi}_{J^c} = 0}} \inf_{\substack{\boldsymbol{\pi} \in \Pi^*(\mu) \\ \boldsymbol{\pi}_{J^c} = 0}} \left\{ \operatorname{KL}(f^*||f_{\boldsymbol{\pi}}) + \frac{\bar{c}|J| \log(K/\delta)}{n\bar{\kappa}_{\widehat{\boldsymbol{\Sigma}}_n}(J,1)} \right\} + \int_{\mathcal{X}} (\log \mu - \log f_{\widehat{\boldsymbol{\pi}}})_+ f^* d\nu$$
(5.30)

on an event of probability at least $1 - \delta$. Furthermore, if $\inf_{x \in \mathcal{X}} f^*(x) \ge \mu$, then, on the same event, we have

$$||f^* - f_{\widehat{\pi}}||_{L^2(P^*)}^2 \le 2M^2 \inf_{\substack{J \subset [K] \\ \pi_{I^c} = 0}} \inf_{\substack{\pi \in \Pi^*(\mu) \\ \pi_{I^c} = 0}} \left\{ KL(f^*||f_{\pi}) + \frac{\bar{c}|J|\log(K/\delta)}{n\bar{\kappa}_{\widehat{\Sigma}_n}(J,1)} \right\}. (5.31)$$

The last term present in the first upper bound, $\int_{\mathcal{X}} (\log \mu - \log f_{\widehat{\pi}})_+ f^* d\nu$ is the price we pay for considering densities that are not lower bounded by a given constant. A simple, non-random upper bound on this term is $\int_{\mathcal{X}} \max_{k \in [K]} (\log \mu - \log f_k)_+ f^* d\nu$. Providing a tight upper bound on this kind or remainder terms is an important problem which lies beyond the scope of the present work.

5.5 Conclusion

In this paper, we have established exact oracle inequalities for the maximum likelihood estimator of a mixture density. This oracle inequality clearly highlights the interplay of three sources of error: misspecification of the model of mixture, departure from D-sparsity and stochastic error of estimating D nonzero coefficients. We have also proved a lower bound that show that the remainder terms of our upper bounds are optimal, up to logarithmic terms. This lower bound is valid not only for the maximum likelihood estimator, but for any estimator of the density function. As a consequence, the maximum likelihood estimator has a nearly optimal excess risk in the minimax sense.

In all the results of the present paper, we have assumed that the components of the mixture model are deterministic. From a practical point of view, it might be reasonable to choose these components in a data driven way, using, for instance, a hold-out sample. This question, as well as the problem of tuning the parameter μ , constitute interesting and challenging avenues for future research.

5.6 Proofs of results stated in previous sections

This section collects the proofs of the theorems and claims stated in previous sections.

5.6.1 Proof of Theorem **5.3.1**

The main technical ingredients of the proof are a strong convexity argument and a control of the maximum of an empirical process. The corresponding results are stated in Lemma 5.6.2 and Proposition 5.6.1, respectively, deferred to Section 5.6.6. We denote by $\bar{\mathbf{Z}}$ the $n \times K$ matrix $[\bar{\mathbf{Z}}_1, \dots, \bar{\mathbf{Z}}_K]$.

Since $\widehat{\pi}$ is a minimizer of $L_n(\cdot)$, see (5.2) and (5.7), we know that $L_n(\widehat{\pi}) \leq L_n(\pi)$ for every π . However, this inequality can be made sharper using the (local) strong convexity of the function $\ell(u) = -\log(u)$. Indeed, Lemma 5.6.2 below shows that

$$\frac{1}{n} \sum_{i=1}^{n} \ell(f_{\widehat{\pi}}(\boldsymbol{X}_i)) \le \frac{1}{n} \sum_{i=1}^{n} \ell(f_{\pi}(\boldsymbol{X}_i)) - \frac{1}{2M^2 n} \|\bar{\mathbf{Z}}(\widehat{\pi} - \boldsymbol{\pi})\|_2^2.$$
 (5.32)

On the other hand, if we set $\varphi(\pi, \mathbf{x}) = \int (\log f_{\pi}) f^* d\nu - \log f_{\pi}(\mathbf{x})$, we have $\mathbf{E}_{f^*}[\varphi(\pi, \mathbf{X}_i)] = 0$ and

$$\ell(f_{\boldsymbol{\pi}}(\boldsymbol{X}_i)) = \mathrm{KL}(f^*||f_{\boldsymbol{\pi}}) - \int_{\mathcal{X}} f^* \log f^* d\nu + \varphi(\boldsymbol{\pi}, \boldsymbol{X}_i). \tag{5.33}$$

Combining inequalities (5.32) and (5.33), we get

$$KL(f^*||f_{\widehat{\boldsymbol{\pi}}}) \le KL(f^*||f_{\boldsymbol{\pi}}) - \frac{1}{2M^2n} \|\bar{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_2^2 + \frac{1}{n} \sum_{i=1}^n (\varphi(\boldsymbol{\pi}, \boldsymbol{X}_i) - \varphi(\widehat{\boldsymbol{\pi}}, \boldsymbol{X}_i)).$$

$$(5.34)$$

The next step of the proof consists in establishing a suitable upper bound on the noise term $\Phi_n(\pi) - \Phi_n(\widehat{\pi})$ where

$$\Phi_n(\boldsymbol{\pi}) = \frac{1}{n} \sum_{i=1}^n \varphi(\boldsymbol{\pi}, \boldsymbol{X}_i). \tag{5.35}$$

According to the mean value theorem, setting $\zeta_n := \sup_{\bar{\pi} \in \Pi_n} \|\nabla \Phi_n(\bar{\pi})\|_{\infty}$, for every vector $\pi \in \Pi_n$, it holds that

$$|\Phi_n(\widehat{\boldsymbol{\pi}}) - \Phi_n(\boldsymbol{\pi})| \le \sup_{\bar{\boldsymbol{\pi}} \in \mathbf{\Pi}_n} \|\nabla \Phi_n(\bar{\boldsymbol{\pi}})\|_{\infty} \|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}\|_1 = \zeta_n \|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}\|_1.$$
 (5.36)

This inequality, combined with (5.34), yields

$$KL(f^*||f_{\widehat{\pi}}) \le KL(f^*||f_{\pi}) - \frac{1}{2M^2n} \|\bar{\mathbf{Z}}(\widehat{\pi} - \pi)\|_2^2 + \zeta_n \|\widehat{\pi} - \pi\|_1.$$
 (5.37)

Using the Gram matrix $\widehat{\mathbf{\Sigma}}_n = 1/n\overline{\mathbf{Z}}^{\top}\overline{\mathbf{Z}}$, the quantity $\|\overline{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_2$ can be rewritten as

$$\|\bar{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_{2}^{2} = n\|\widehat{\boldsymbol{\Sigma}}_{n}^{1/2}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_{2}^{2}.$$
 (5.38)

We proceed with applying the following result [Bellec et al., 2016, Lemma 2].

Lemma 5.6.1 (Bellec et al. [2016], Lemma 2). For any pair of vectors $\boldsymbol{\pi}, \boldsymbol{\pi}' \in \mathbb{R}^K$, for any pair of scalars $\mu > 0$ and $\gamma > 1$, for any $K \times K$ symmetric matrix \mathbf{A} and for any set $J \subset [p]$, the following inequality is true

$$2\mu\gamma^{-1}(\|\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}}\|_{1} + \gamma\|\boldsymbol{\pi}\|_{1} - \gamma\|\widehat{\boldsymbol{\pi}}\|_{1}) - \|\mathbf{A}(\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}})\|_{2}^{2} \leq 4\mu\|\boldsymbol{\pi}_{J^{c}}\|_{1} + \frac{(\gamma + 1)^{2}\mu^{2}|J|}{\gamma^{2}\kappa_{\mathbf{A}^{2}}(J, c_{\gamma})},$$

$$(5.39)$$
where $c_{\gamma} = (\gamma + 1)/(\gamma - 1)$.

Choosing $\mathbf{A} = \widehat{\boldsymbol{\Sigma}}_n^{1/2}/(\sqrt{2}\,M)$, $\mu = \zeta_n$ and $\gamma = 2$ (thus $c_{\gamma} = 3$) we get the inequality

$$\zeta_{n} \|\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}}\|_{1} - \|\mathbf{A}(\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}})\|_{2}^{2} \le 4\zeta_{n} \|\boldsymbol{\pi}_{J^{c}}\|_{1} + \frac{9\zeta_{n}^{2}|J|}{4\kappa_{\mathbf{A}^{2}}(J,3)}, \qquad \forall J \in \{1,\dots,p\}.$$
(5.40)

One can check that $\kappa_{\mathbf{A}^2}(J,3) = \kappa_{\widehat{\Sigma}_n}(J,3)/(2M^2)$. Combining the last inequality with (5.37), we arrive at

$$KL(f^*||f_{\widehat{\pi}}) \le KL(f^*||f_{\pi}) + 4\zeta_n \|\pi_{J^c}\|_1 + \frac{9M^2\zeta_n^2|J|}{2\kappa_{\widehat{\Sigma}_n}(J,3)}.$$
 (5.41)

Since the last inequality holds for every π , we can insert an \inf_{π} in the right hand side. Furthermore, in view of Proposition 5.6.1 below, with probability larger than $1-\delta$, ζ_n is bounded from above by $8V^3(\frac{\log(K/\delta)}{n})^{1/2}$. This completes the proof of (5.12).

To prove (5.13), we follow the same steps as above up to inequality (5.37). Then, we remark that for every π in the simplex satisfying $\pi_{J^c} = 0$, it holds

$$\|(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})_{J^c}\|_1 = \|\widehat{\boldsymbol{\pi}}_{J^c}\|_1 = 1 - \|\widehat{\boldsymbol{\pi}}_J\|_1 = \|\boldsymbol{\pi}_J\|_1 - \|\widehat{\boldsymbol{\pi}}_J\|_1 \le \|(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})_J\|_1. \quad (5.42)$$

Therefore, $\|\widehat{\Sigma}_n^{1/2}(\widehat{\pi} - \pi)\|_2^2 \ge \text{we have with probability at least } 1 - \delta$

$$\zeta_{n} \|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}\|_{1} - \frac{1}{2M^{2}n} \|\mathbf{Z}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_{2}^{2} \leq 2\zeta_{n} \|(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})_{J}\|_{1} - \frac{1}{2M^{2}} \|\widehat{\boldsymbol{\Sigma}}_{n}^{1/2}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_{2}^{2}
(5.43)$$

$$\leq 2\zeta_{n} \|(\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}})_{J}\|_{1} - \frac{\bar{\kappa}_{\widehat{\boldsymbol{\Sigma}}_{n}}(J, 1) \|(\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}})_{J}\|_{1}^{2}}{2M^{2}|J|}$$

$$\leq \frac{2\zeta_{n}^{2}M^{2}|J|}{\bar{\kappa}_{\widehat{\boldsymbol{\Sigma}}_{n}}(J, 1)}.$$
(5.45)

Replacing the right hand term in (5.37) and taking the infimum, we get the claim of the corollary. Since, in view of Proposition 5.6.1 below, with probability larger than $1 - \delta$, ζ_n is bounded from above by $8V^3(\frac{\log(K/\delta)}{n})^{1/2}$, we get the claim of (5.13).

5.6.2 Proof of Theorem **5.3.2**

Let us denote $v = \hat{\pi} - \pi$. According to (5.37) and (5.38), we have

$$KL(f^*||f_{\widehat{\pi}}) \leq KL(f^*||f_{\pi}) + \zeta_n \|\widehat{\pi} - \pi\|_1 - \frac{1}{2M^2} \|\widehat{\Sigma}_n^{1/2}(\widehat{\pi} - \pi)\|_2^2$$

$$\leq KL(f^*||f_{\pi}) + \zeta_n \|\mathbf{v}\|_1 - \frac{1}{2M^2} \|\mathbf{\Sigma}^{1/2}\mathbf{v}\|_2^2 + \frac{1}{2M^2} \mathbf{v}^{\top} (\mathbf{\Sigma} - \widehat{\mathbf{\Sigma}}_n) \mathbf{v}.$$
(5.47)

As \boldsymbol{v} is the difference of two vectors lying on the simplex, we have $\|\boldsymbol{v}\|_1 \leq 2$. Let $\|\boldsymbol{\Sigma} - \widehat{\boldsymbol{\Sigma}}_n\|_{\infty} = \max_{j,j'} |(\boldsymbol{\Sigma} - \widehat{\boldsymbol{\Sigma}}_n)_{j,j'}|$ stand for the largest (in absolute values) element of the matrix $\boldsymbol{\Sigma} - \widehat{\boldsymbol{\Sigma}}_n$. We have

$$\boldsymbol{v}^{\top}(\boldsymbol{\Sigma} - \widehat{\boldsymbol{\Sigma}}_n)\boldsymbol{v} \leq \|\boldsymbol{\Sigma} - \widehat{\boldsymbol{\Sigma}}_n\|_{\infty}\|\boldsymbol{v}\|_1^2 \leq 2\|\boldsymbol{\Sigma} - \widehat{\boldsymbol{\Sigma}}_n\|_{\infty}\|\boldsymbol{v}\|_1.$$
 (5.48)

Setting $\bar{\zeta}_n = \zeta_n + M^{-2} \| \mathbf{\Sigma} - \widehat{\mathbf{\Sigma}}_n \|_{\infty}$, we get

$$KL(f^*||f_{\widehat{\pi}}) \le KL(f^*||f_{\pi}) + \bar{\zeta}_n \|\widehat{\pi} - \pi\|_1 - \frac{1}{2M^2} \|\Sigma^{1/2}(\widehat{\pi} - \pi)\|_2^2.$$
 (5.49)

Following the same steps as those used for obtaining (5.41), we arrive at

$$KL(f^*||f_{\widehat{\pi}}) \le KL(f^*||f_{\pi}) + 4\bar{\zeta}_n \|\boldsymbol{\pi}_{J^c}\|_1 + \frac{9\bar{\zeta}_n^2 M^2 |J|}{2\kappa_{\Sigma}(J,3)}.$$
 (5.50)

The last step consists in evaluating the quantiles of the random variable $\bar{\zeta}_n$. To this end, one checks that the Hoeffding inequality combined with the union bound yields

$$\mathbf{P}\Big\{\|\mathbf{\Sigma} - \widehat{\mathbf{\Sigma}}_n\|_{\infty} > t\Big\} \le K(K-1)\exp(-2nt^2/M^4), \quad \forall t > 0. \quad (5.51)$$

In other terms, for every $\delta \in (0,1)$, we have

$$\mathbf{P}\Big\{\|\mathbf{\Sigma} - \widehat{\mathbf{\Sigma}}_n\|_{\infty} \le M^2 \Big(\frac{\log(K^2/\delta)}{2n}\Big)^{1/2}\Big\} \ge 1 - \delta.$$
 (5.52)

Note that for $\delta \leq 1$, we have $\log(K^2/\delta) \leq 2\log(K/\delta)$. Combining with Proposition 5.6.1, this implies that $\bar{\zeta}_n \leq (8V^3+1)\left(\frac{\log(K/\delta)}{n}\right)^{1/2}$ with probability larger than $1-2\delta$. This completes the proof of (5.15). The proof of (5.16) is omitted since it repeats the same arguments as those used for proving (5.13).

5.6.3 Proof of Theorem 5.3.3

According to (5.50), for any $\pi \in \Pi$ and any $J \subset \{1, ..., K\}$, we have

$$\mathbf{E}[\mathrm{KL}(f^*||f_{\widehat{\pi}})] \le \mathrm{KL}(f^*||f_{\pi}) + 4\|\boldsymbol{\pi}_{J^c}\|_1 \mathbf{E}[\bar{\zeta}_n] + \frac{9M^2|J|}{2\kappa_{\Sigma}(J,3)} \mathbf{E}[\bar{\zeta}_n^2].$$
 (5.53)

Recall now that $\bar{\zeta}_n = \zeta_n + M^{-2} \| \widehat{\Sigma}_n - \Sigma \|_{\infty}$ and, according to Proposition 5.6.1, we have

$$\mathbf{E}[\zeta_n] \le 4V^3 \left(\frac{2\log(2K^2)}{n}\right)^{1/2} \quad \text{and} \quad \mathbf{Var}[\zeta_n] \le \frac{V^2}{2n}. \tag{5.54}$$

Using Theorem 5.7.2, one easily checks that

$$\mathbf{E}[\|\widehat{\mathbf{\Sigma}}_n - \mathbf{\Sigma}\|_{\infty}] \le M^2 \left(\frac{\log(2K^2)}{2n}\right)^{1/2}.$$
 (5.55)

This implies that

$$\mathbf{E}[\bar{\zeta}_n] \le (8V^3 + 1) \left(\frac{\log(2K^2)}{2n}\right)^{1/2}.$$
 (5.56)

Similarly, in view of the Efron-Stein inequality, we have $\operatorname{Var}[\|\widehat{\Sigma}_n - \Sigma\|_{\infty}] \leq \frac{M^4}{2n}$. This implies that

$$\mathbf{E}[\bar{\zeta}_n^2] \le (\mathbf{E}[\bar{\zeta}_n])^2 + \left\{ (\mathbf{Var}[\zeta_n])^{1/2} + M^{-2} (\mathbf{Var}[\|\widehat{\Sigma}_n - \Sigma\|_{\infty}])^{1/2} \right\}^2$$
 (5.57)

$$\leq (8V^3 + 1)^2 \frac{\log(2K^2)}{2n} + \frac{(V+1)^2}{2n} \tag{5.58}$$

$$\leq 1.615(8V^3 + 1)^2 \frac{\log K}{n}. (5.59)$$

Combining (5.56), (5.59) and (5.53), we get the desired result.

5.6.4 Proof of Proposition 1

Using the strong convexity of the function $u \mapsto \log u$ over the interval [m, M] and the fact that π^* minimizes the convex function $\pi \mapsto \mathrm{KL}(f^*||f_{\pi})$, we get

$$KL(f^*||f_{\widehat{\pi}}) \ge KL(f^*||f_{\pi^*}) + \frac{1}{2M^2} \|\widehat{\Sigma}_n^{1/2}(\widehat{\pi} - \pi^*)\|_2^2.$$
 (5.60)

Combining with (5.49), in which we replace π by π^* , we get

$$\|\mathbf{\Sigma}^{1/2}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*)\|_2^2 \le 2M^2 \bar{\zeta}_n \|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_1. \tag{5.61}$$

Let us set $\mathbf{v} = \widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*$. If $\mathbf{v} = 0$, then the claims are trivial. In the rest of this proof, we assume $\|\mathbf{v}\|_1 > 0$. In view of (5.42), we have $\|\mathbf{v}\|_1 \leq 2\|\mathbf{v}_{J^*}\|_1$. Therefore, using the definition of the compatibility factor, we get

$$\|\boldsymbol{v}\|_{1}^{2} \leq 4\|\boldsymbol{v}_{J^{*}}\|_{1}^{2} \leq \frac{4|J^{*}|\|\boldsymbol{\Sigma}^{1/2}\boldsymbol{v}\|_{2}^{2}}{\bar{\kappa}(J^{*},1)} \leq \frac{8|J^{*}|M^{2}\bar{\zeta}_{n}\|\boldsymbol{v}\|_{1}}{\bar{\kappa}(J^{*},1)}.$$
 (5.62)

We have already checked that $\bar{\zeta}_n \leq (8V^3 + 1) \left(\frac{\log(K/\delta)}{n}\right)^{1/2}$ with probability larger than $1 - 2\delta$. Dividing both sides of inequality (5.62) by $\|\boldsymbol{v}\|_1$ and using the aforementioned upper bound on $\bar{\zeta}_n$, we get the desired bound on $\|\boldsymbol{v}\|_1 = \|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*\|_1$.

In order to bound the error $\boldsymbol{v} = \widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}^*$ in the Euclidean norm, we denote by \widehat{J} the set of $D = |J^*|$ indices corresponding to D largest entries of the vector $(|v_1|, \ldots, |v_K|)$. Since $\|\boldsymbol{v}\|_1 \leq 2\|\boldsymbol{v}_{J^*}\|_1$, we clearly have $\|\boldsymbol{v}\|_1 \leq 2\|\boldsymbol{v}_{\widehat{J}}\|_1$. Therefore,

$$\|\boldsymbol{v}\|_{2}^{2} = \|\boldsymbol{v}_{\hat{J}}\|_{2}^{2} + \|\boldsymbol{v}_{\hat{J}^{c}}\|_{2}^{2} \tag{5.63}$$

$$\leq \|\boldsymbol{v}_{\hat{J}}\|_{2}^{2} + \|\boldsymbol{v}_{\hat{J}^{c}}\|_{\infty} \|\boldsymbol{v}_{\hat{J}^{c}}\|_{1} \tag{5.64}$$

$$\leq \|\boldsymbol{v}_{\hat{\jmath}}\|_{2}^{2} + \frac{\|\boldsymbol{v}_{\hat{\jmath}}\|_{1}}{D} \|\boldsymbol{v}_{\hat{\jmath}c}\|_{1} \tag{5.65}$$

$$\leq \|\boldsymbol{v}_{\widehat{J}}\|_{2}^{2} + \frac{1}{D} \|\boldsymbol{v}_{\widehat{J}}\|_{1}^{2} \leq 2 \|\boldsymbol{v}_{\widehat{J}}\|_{2}^{2}. \tag{5.66}$$

Combining this inequality with the definition of the restricted eigenvalue and inequality (5.61) above, we arrive at

$$\|\boldsymbol{v}_{\widehat{J}}\|_{2}^{2} \leq \frac{\|\boldsymbol{\Sigma}^{1/2}\boldsymbol{v}\|_{2}^{2}}{\kappa^{\mathrm{RE}}(D,1)} \leq \frac{2M^{2}\bar{\zeta}_{n}\|\boldsymbol{v}\|_{1}}{\kappa^{\mathrm{RE}}(D,1)} \leq \frac{4M^{2}\bar{\zeta}_{n}(\|\boldsymbol{v}_{\widehat{J}}\|_{1}\wedge1)}{\kappa^{\mathrm{RE}}(D,1)} \leq \frac{4M^{2}\bar{\zeta}_{n}(\sqrt{D}\|\boldsymbol{v}_{\widehat{J}}\|_{2}\wedge1)}{\kappa^{\mathrm{RE}}(D,1)}.$$
(5.67)

Dividing both sides by $\|\boldsymbol{v}_{\hat{i}}\|_2$, taking the square and using (5.66), we get

$$\|\boldsymbol{v}\|_{2} \leq \sqrt{2} \, \|\boldsymbol{v}_{\widehat{J}}\|_{2} \leq \frac{4\sqrt{2}M^{2} |J^{*}|^{1/2} \, \bar{\zeta}_{n}}{\kappa^{\text{RE}}(|J^{*}|, 1)} \bigwedge \frac{2\sqrt{2}M\bar{\zeta}_{n}^{1/2}}{\kappa^{\text{RE}}(|J^{*}|, 1)^{1/2}}. \tag{5.68}$$

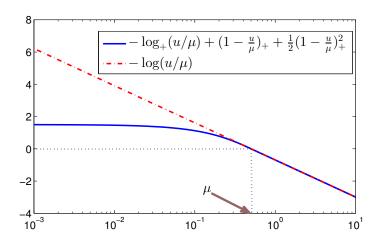


Figure 5.1: The plot of the function $u \mapsto \bar{\ell}(u)$, used in the proof of Proposition 2, superposed on the plot of the function $u \mapsto \ell(u) = -\log u$. We see that the former is a strongly convex surrogate of the latter.

This inequality, in conjunction with the upper bound on $\bar{\zeta}_n$ used above, completes the proof of the second claim.

5.6.5 Proof of Proposition 2

We repeat the proof of Theorem 5.3.1 with some small modifications. First of all, we replace the function $\ell(u) = -\log(u)$ by the function

$$\bar{\ell}(u) = \begin{cases} -\log(u/\mu), & \text{if } u \ge \mu, \\ (1 - \frac{u}{\mu}) + \frac{1}{2}(1 - \frac{u}{\mu})^2, & \text{if } u \in (0, \mu). \end{cases}$$
 (5.69)

One easily checks that this function is twice continuously differentiable with a second derivative satisfying $M^{-2} \leq \bar{\ell}''(u) \leq \mu^{-2}$ for every $u \in (0, M)$. Furthermore, since $\bar{\ell}(u) = \ell(u/\mu)$ for every $u \geq \mu$, we have $\bar{L}_n(\widehat{\boldsymbol{\pi}}) = L_n(\widehat{\boldsymbol{\pi}})$, where we have used the notation $\bar{L}_n(\boldsymbol{\pi}) = \frac{1}{n} \sum_{i=1}^n \bar{\ell}(f_{\boldsymbol{\pi}}(\boldsymbol{X}_i))$. Therefore, similarly to (5.32), we get

$$\frac{1}{n} \sum_{i=1}^{n} \bar{\ell}(f_{\widehat{\pi}}(\boldsymbol{X}_i)) \le \frac{1}{n} \sum_{i=1}^{n} \bar{\ell}(f_{\pi}(\boldsymbol{X}_i)) - \frac{1}{2M^2n} \|\bar{\mathbf{Z}}(\widehat{\pi} - \boldsymbol{\pi})\|_2^2, \tag{5.70}$$

for every $\boldsymbol{\pi} \in \Pi^*(\mu)$. Let us define $\bar{\varphi}(\boldsymbol{\pi}, \boldsymbol{x}) = \bar{\ell}(f_{\boldsymbol{\pi}}(\boldsymbol{x})) - \int \bar{\ell}(f_{\boldsymbol{\pi}}) f^* d\nu$ and $\bar{\Phi}_n(\boldsymbol{\pi}) = \frac{1}{n} \sum_{i=1}^n \bar{\varphi}(\boldsymbol{\pi}, \boldsymbol{X}_i)$. We have

$$\int \bar{\ell}(f_{\widehat{\boldsymbol{\pi}}}) f^* d\nu \leq \int \bar{\ell}(f_{\boldsymbol{\pi}}) f^* d\nu - \frac{1}{2M^2 n} \|\bar{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_2^2 + \frac{1}{n} \sum_{i=1}^n \left(\varphi(\boldsymbol{\pi}, \boldsymbol{X}_i) - \varphi(\widehat{\boldsymbol{\pi}}, \boldsymbol{X}_i) \right)$$

 $\leq \int \bar{\ell}(f_{\pi}) f^* d\nu - \frac{1}{2M^2 n} \|\bar{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_2^2 + \underbrace{\sup_{\boldsymbol{\pi} \in \Pi_n(0)} \|\nabla \bar{\Phi}_n(\boldsymbol{\pi})\|_{\infty}}_{:=\xi_n} \|\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}\|_1.$

Notice that $\pi \in \Pi^*(\mu)$ implies that $\bar{\ell}(f_{\pi}) = \log \mu - \log f_{\pi}$ and that $\bar{\ell}(f_{\widehat{\pi}}) \geq \log \mu - \log f_{\widehat{\pi}} - (\log \mu - \log f_{\widehat{\pi}})_+$. Therefore, along the lines of the proof of (5.13) (see, namely, (5.45)), we get

$$KL(f^*||f_{\widehat{\pi}}) \le KL(f^*||f_{\pi}) + \frac{2\xi_n^2 M^2 |J|}{\bar{\kappa}_{\widehat{\Sigma}_n}(J, 1)} + \int_{\mathcal{X}} (\log \mu - \log f_{\widehat{\pi}})_+ f^* d\nu. \quad (5.73)$$

We can repeat now the arguments of Proposition 5.6.1 with some minor modifications. We first rewrite ξ_n as $\xi_n = \max_{l=1,\dots,K} \xi_{l,n}$ with $\xi_{l,n} = \sup_{\boldsymbol{\pi} \in \Pi_n(0)} |\partial_l \bar{\Phi}_n(\boldsymbol{\pi})|$. One checks that the bounded difference inequality and the Efron-Stein inequality can be applied with an additional factor 2, since for $F_l(\mathbf{X}) = \sup_{\boldsymbol{\pi} \in \Pi_n(0)} |\partial_l \bar{\Phi}_n(\boldsymbol{\pi})|$, we have

$$|F_l(\mathbf{X}) - F_l(\mathbf{X}')| \le \frac{2M}{n\mu} = \frac{2V}{n}.$$
(5.74)

Therefore, for every $l \in [K]$, with probability larger than $1 - (\delta/K)$, we have $\xi_{l,n} \leq \mathbf{E}[\xi_{l,n}] + V(\frac{2\log(K/\delta)}{n})^{1/2}$ and $\mathbf{Var}[\xi_n] \leq (2V)^2/n$. By the union bound, we obtain that with probability larger than $1 - \delta$, $\xi_n \leq \max_l \mathbf{E}[\xi_{l,n}] + V(\frac{2\log(K/\delta)}{n})^{1/2}$. Thus, to upper bound $\mathbf{E}[\xi_{l,n}]$, we use the symmetrization argument:

$$\mathbf{E}[\xi_{l,n}] \leq 2\mathbf{E}\left[\sup_{\boldsymbol{\pi}\in\Pi_{n}(0)} \left| \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \bar{\ell}'(f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i})) f_{l}(\boldsymbol{X}_{i}) \right| \right]$$

$$\leq 2M\mathbf{E}\left[\sup_{\boldsymbol{\pi}\in\Pi_{n}(0)} \left| \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \bar{\ell}'(f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i})) \right| \right]$$
[Boucheron et al., 2013, Th. 11.5]
$$\leq \frac{2M}{\mu} \mathbf{E}\left[\left| \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \right| \right] + 2M\mathbf{E}\left[\sup_{\boldsymbol{\pi}\in\Pi_{n}(0)} \left| \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} [\bar{\ell}'(f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i})) - \bar{\ell}'(0)] \right| \right].$$
(5.77)

Note that the function $\bar{\ell}'$, the derivative of $\bar{\ell}$ defined in (5.69), is by construction Lipschitz with constant $1/\mu^2$. Therefore, in view of the contraction principle,

$$\mathbf{E}[\xi_{l,n}] \le \frac{2M}{\mu} \mathbf{E}\left[\left(\frac{1}{n}\sum_{i=1}^{n} \epsilon_i\right)^2\right]^{1/2} + \frac{4M}{\mu^2} \mathbf{E}\left[\sup_{\boldsymbol{\pi} \in \Pi_n(0)} \frac{1}{n}\sum_{i=1}^{n} \epsilon_i f_{\boldsymbol{\pi}}(\boldsymbol{X}_i)\right]$$
(5.78)

$$\leq \frac{2M}{\mu\sqrt{n}} + \frac{4M}{\mu^2} \mathbf{E} \left[\sup_{k \in [K]} \frac{1}{n} \sum_{i=1}^n \epsilon_i f_k(\boldsymbol{X}_i) \right]$$
 (5.79)

$$\leq \frac{2M}{\mu\sqrt{n}} + \frac{8M^2}{\mu^2} \left(\frac{\log K}{2n}\right)^{1/2} \leq \frac{2V^2(1 + 2\sqrt{2\log K})}{\sqrt{n}}.$$
 (5.80)

As a consequence, we proved that with probability larger than $1-\delta$, we have $\xi_n \leq 8V^2(\frac{\log K}{n})^{1/2}$. This completes the proof of the first inequality. In order to prove the second one, we simply change the way we have evaluated the term $\int \bar{\ell}(f_{\widehat{\pi}})f^*$ in the left hand side of (5.71). Since $\bar{\ell}$ is strongly convex with a second order derivative bounded from below by $1/M^2$, we have $\bar{\ell}(f_{\widehat{\pi}}) \geq \bar{\ell}(f^*) + \bar{\ell}'(f^*)(f_{\widehat{\pi}} - f^*) + \frac{1}{2M^2}(f_{\widehat{\pi}} - f^*)^2$. Since f^* is always larger than μ , the derivative $\bar{\ell}'(f^*)$ equals $1/f^*$. Integrating over \mathcal{X} , we get the second inequality of the proposition.

5.6.6 Auxiliary results

We start by a general convex result based on the strong convexity of the -log function to derive a bound on the estimated log-likelihood.

Lemma 5.6.2. Let us assume that $M = \max_{j \in [K]} ||f_j||_{\infty} < \infty$. Then, for any $\pi \in \mathbb{B}_+^K$, it holds that

$$L_n(\widehat{\boldsymbol{\pi}}) \le L_n(\boldsymbol{\pi}) - \frac{1}{2M^2n} \|\bar{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_2^2.$$
 (5.81)

Proof. Recall that $\widehat{\pi}$ minimizes the function L_n defined in (5.7) over Π_n . Furthermore, the function $u \mapsto \ell(u)$ is clearly strongly convex with a second order derivative bounded from below by $1/M^2$ over the set $u \in (0, M]$. Therefore, for every $\widehat{u} \in (0, M]$, the function $\widetilde{\ell}$ given by:

$$\widetilde{\ell}(u) = \ell(u) - \frac{1}{2M^2} (\widehat{u} - u)^2, \quad u \in (0, M],$$
(5.82)

is convex. This implies that the mapping

$$\boldsymbol{\pi} \mapsto \widetilde{L}_n(\boldsymbol{\pi}) = L_n(\boldsymbol{\pi}) - \frac{1}{2M^2n} \|\mathbf{Z}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})\|_2^2$$
 (5.83)

is convex over the set $\pi \in \mathbb{B}_+^K$. This yields⁴

$$\widetilde{L}_n(\boldsymbol{\pi}) - \widetilde{L}_n(\widehat{\boldsymbol{\pi}}) \ge \sup_{\boldsymbol{v} \in \partial \widetilde{L}_n(\widehat{\boldsymbol{\pi}})} \boldsymbol{v}^{\top}(\boldsymbol{\pi} - \widehat{\boldsymbol{\pi}}), \quad \forall \boldsymbol{\pi} \in \mathbb{B}_+^K.$$
 (5.84)

Using the Karush-Kuhn-Tucker conditions and the fact that $\widehat{\boldsymbol{\pi}}$ minimizes L_n , we get $\mathbf{0}_K \in \partial L_n(\widehat{\boldsymbol{\pi}}) = \partial \widetilde{L}_n(\widehat{\boldsymbol{\pi}})$. This readily gives $\widetilde{L}_n(\boldsymbol{\pi}) - \widetilde{L}_n(\widehat{\boldsymbol{\pi}}) \geq 0$, for any $\boldsymbol{\pi} \in \mathbb{B}_+^K$. The last step is to remark that $\mathbf{Z}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi}) = \overline{\mathbf{Z}}(\widehat{\boldsymbol{\pi}} - \boldsymbol{\pi})$, since both $\widehat{\boldsymbol{\pi}}$ and $\boldsymbol{\pi}$ have entries summing to one.

The core of our results lies in the following proposition which bound the deviations of the empirical process part.

Proposition 5.6.1 (Supremum of Empirical Process). For any $\boldsymbol{\pi} \in \mathbb{B}_+^K$ and $\boldsymbol{x} \in \mathcal{X}$, define $\varphi(\boldsymbol{\pi}, \boldsymbol{x}) = \int (\log f_{\boldsymbol{\pi}}) f^* - \log f_{\boldsymbol{\pi}}(\boldsymbol{x})$ and consider $\Phi_n(\boldsymbol{\pi}) = \frac{1}{n} \sum_{i=1}^n \varphi(\boldsymbol{\pi}, \boldsymbol{X}_i)$. If $K \geq 2$, then for any $\delta \in (0, 1)$, with probability at least $1 - \delta$, we have

$$\zeta_n = \sup_{\boldsymbol{\pi} \in \Pi_n} \left\| \nabla \Phi_n(\boldsymbol{\pi}) \right\|_{\infty} \le 8V^3 \left(\frac{\log(K/\delta)}{n} \right)^{1/2}. \tag{5.85}$$

Furthermore, we have $\mathbf{E}[\zeta_n] \leq 4V^3 \left(\frac{2\log(2K^2)}{n}\right)^{1/2}$ and $\mathbf{Var}[\zeta_n] \leq V^2/(2n)$.

Proof. To ease notation, let us denote $g_{\pi,l}(x) = \frac{f_l(x)}{f_{\pi}(x)} - \mathbf{E}\left[\frac{f_l(X)}{f_{\pi}(X)}\right]$ and

$$F(\mathbf{X}) = \sup_{\boldsymbol{\pi} \in \Pi_n} \left\| \nabla \Phi_n(\boldsymbol{\pi}) \right\|_{\infty} = \sup_{(\boldsymbol{\pi}, l) \in \Pi_n \times [K]} \left| \frac{1}{n} \sum_{i=1}^n g_{\boldsymbol{\pi}, l}(\boldsymbol{X}_i) \right|, \tag{5.86}$$

where $\mathbf{X} = (\mathbf{X}_1, \dots, \mathbf{X}_n)$. To derive a bound on F, we will use the McDiarmid concentration inequality that requires the bounded difference condition to hold for F. For some $i_0 \in [n]$, let $\mathbf{X}' = (\mathbf{X}_1, \dots, \mathbf{X}'_{i_0}, \dots, \mathbf{X}_n)$ be a new sample obtained from \mathbf{X} by modifying the i_0 -th element \mathbf{X}_i and by leaving all the others unchanged. Then, we have

$$F(\mathbf{X}) - F(\mathbf{X}') = \sup_{(\boldsymbol{\pi}, l) \in \Pi_n \times [K]} \left| \frac{1}{n} \sum_{i=1}^n g_{\boldsymbol{\pi}, l} (\boldsymbol{X}_i) \right| - \sup_{(\boldsymbol{\pi}, l) \in \Pi \times [K]} \left| \frac{1}{n} \sum_{i=1}^n g_{\boldsymbol{\pi}, l} (\boldsymbol{X}'_i) \right|$$

$$(5.87)$$

$$\leq \sup_{(\boldsymbol{\pi},l)\in\Pi_n\times[K]} \left| \frac{1}{n} \sum_{i=1}^n g_{\boldsymbol{\pi},l}(\boldsymbol{X}_i) - \frac{1}{n} \sum_{i=1}^n g_{\boldsymbol{\pi},l}(\boldsymbol{X}_i') \right|$$
 (5.88)

$$= \sup_{(\boldsymbol{\pi}, l) \in \Pi_n \times [K]} \left| \frac{1}{n} \left(g_{\boldsymbol{\pi}, l} (\boldsymbol{X}_{i_0}) - g_{\boldsymbol{\pi}, l} (\boldsymbol{X}'_{i_0}) \right) \right| \le \frac{V}{n}, \tag{5.89}$$

⁴We denote by ∂g the sub-differential of a convex function g.

where the last inequality is a direct consequence of assumption (5.11). Therefore, using the McDiarmid concentration inequality recalled in Theorem 5.7.3 below, we check that the inequality

$$F(\mathbf{X}) \le \mathbf{E}(F(\mathbf{X})) + V\sqrt{\frac{\log(1/\delta)}{2n}}$$
 (5.90)

holds with probability at least $1-\delta$. Furthermore, in view of the Efron-Stein inequality, we have

$$\mathbf{Var}[\zeta_n] = \mathbf{Var}[F(\mathbf{X})] \le \frac{V^2}{2n}.$$
 (5.91)

Let us denote $\mathcal{G} := \{(f_l/f_{\pi}) - 1, (\pi, l) \in \Pi_n \times [K]\}$ and $\mathfrak{R}_{n,q}(\mathcal{G})$ the Rademacher complexity of \mathcal{G} given by

$$\mathfrak{R}_{n}(\mathcal{G}) = \mathbf{E}_{\epsilon} \left[\sup_{(\boldsymbol{\pi}, l) \in \Pi_{n} \times [K]} \left| \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \left(\frac{f_{l}(\boldsymbol{X}_{i})}{f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i})} - 1 \right) \right| \right], \tag{5.92}$$

with $\epsilon_1, \ldots, \epsilon_n$ independent and identically distributed Rademacher random variables independent of X_1, \ldots, X_n . Using the symmetrization inequality (see, for instance, Theorem 2.1 in Koltchinskii [2011]) we have

$$\mathbf{E}[F(\mathbf{X})] = \mathbf{E}[\zeta_n] \le 2\mathbf{E}[\mathfrak{R}_n(\mathcal{G})]. \tag{5.93}$$

Lemma 5.6.3. The Rademacher complexity defined in (5.92) satisfies

$$\Re_n(\mathcal{G}) \le 4V^3 \sqrt{\frac{\log K}{n}}.$$
 (5.94)

Proof. The proof relies on the contraction principle of Ledoux and Talagrand [1991] that we recall in Section 5.7.3 for the convenience. We apply this principle to the random variables $X_{i,(\boldsymbol{\pi},l)} = f_{\boldsymbol{\pi}}(\boldsymbol{X}_i)/f_l(\boldsymbol{X}_i) - 1$ and to the function $\psi(x) = (1+x)^{-1} - 1$. Clearly ψ is Lipschitz on $[\frac{1}{V} - 1, V - 1]$ with the Lipschitz constant equal to V^2 and $\psi(0) = 0$. Therefore

$$\mathfrak{R}_{n}(\mathcal{G}) \leq \mathbf{E}_{\epsilon} \left[\sup_{(\boldsymbol{\pi},l)} \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \psi(\boldsymbol{X}_{i,(\boldsymbol{\pi},l)}) \right] + \mathbf{E}_{\epsilon} \left[\sup_{(\boldsymbol{\pi},l)} \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} (-\psi)(\boldsymbol{X}_{i,(\boldsymbol{\pi},l)}) \right]$$
(5.95)

$$\leq 2V^{2}\mathbf{E}_{\epsilon} \left[\sup_{(\boldsymbol{\pi},l)\in\Pi_{n}\times[K]} \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \boldsymbol{X}_{i,(\boldsymbol{\pi},l)} \right]$$
 (5.96)

$$=2V^{2}\mathbf{E}_{\epsilon}\left[\sup_{(\boldsymbol{\pi},l)\in\Pi_{n}\times[K]}\frac{1}{n}\sum_{i=1}^{n}\epsilon_{i}\left(\frac{f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i})}{f_{l}(\boldsymbol{X}_{i})}-1\right)\right].$$
(5.97)

Expanding $f_{\pi}(\boldsymbol{X}_i)$ we obtain

$$\mathbf{E}_{\epsilon} \left[\sup_{(\boldsymbol{\pi},l)} \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \left(\frac{f_{\boldsymbol{\pi}}(\boldsymbol{X}_{i})}{f_{l}(\boldsymbol{X}_{i})} - 1 \right) \right] = \mathbf{E}_{\epsilon} \left[\sup_{(\boldsymbol{\pi},l)} \sum_{k=1}^{K} \frac{\pi_{k}}{n} \sum_{i=1}^{n} \epsilon_{i} \left(\frac{f_{k}(\boldsymbol{X}_{i})}{f_{l}(\boldsymbol{X}_{i})} - 1 \right) \right]$$

$$= \mathbf{E}_{\epsilon} \left[\max_{k,l \in [K]} \frac{1}{n} \sum_{i=1}^{n} \epsilon_{i} \left(\frac{f_{k}(\boldsymbol{X}_{i})}{f_{l}(\boldsymbol{X}_{i})} - 1 \right) \right].$$

$$(5.99)$$

We apply now Theorem 5.7.2 with s = (k, l), $N = K^2$, a = -V, b = V and $Y_{i,s} = \epsilon_i \left(\frac{f_k(\mathbf{X}_i)}{f_l(\mathbf{X}_i)} - 1 \right)$. This yields

$$\mathbf{E}_{\epsilon} \left[\max_{k,l \in [K]} \frac{1}{n} \sum_{i=1}^{n} \epsilon_i \left(\frac{f_k(\boldsymbol{X}_i)}{f_l(\boldsymbol{X}_i)} - 1 \right) \right] \le 2V \left(\frac{\log K^2}{2n} \right)^{1/2}. \tag{5.100}$$

This completes the proof of the lemma.

Combining inequalities (5.90,5.93) and Lemma 5.6.3, we get that the inequality

$$F(\mathbf{X}) \le 8V^3 \left(\frac{\log K}{n}\right)^{1/2} + V\left(\frac{\log(1/\delta)}{2n}\right)^{1/2}$$
 (5.101)

holds with probability at least $1 - \delta$. Noticing that $V \ge 1$ and, for $K \ge 2$, $\delta \in (0, K^{-1/31})$ we have $8\sqrt{\log K} + \sqrt{(1/2)\log(1/\delta)} \le 8\sqrt{\log(K/\delta)}$, we get the first claim of the proposition. The second claim is a direct consequence of Lemma 5.6.3 and (5.93).

5.7 Proof of the lower bound for nearly-Dsparse aggregation

We prove the minimax lower bound for estimation in Kullback-Leibler risk using the following slightly adapted version of Theorem 2.5 from Tsybakov [2009]. Throughout this section, we denote by $\lambda_{\min,\Sigma}(k)$ and $\lambda_{\max,\Sigma}(k)$, respectively, the smallest and the largest eigenvalue of all $k \times k$ principal minors of the matrix Σ .

Theorem 5.7.1. For some integer $L \geq 4$ assume that $\mathcal{H}_{\mathcal{F}}(\gamma, D)$ contains L elements $f_{\boldsymbol{\pi}^{(1)}}, \ldots, f_{\boldsymbol{\pi}^{(L)}}$ satisfying the following two conditions.

(i)
$$\mathrm{KL}(f_{\boldsymbol{\pi}^{(j)}}||f_{\boldsymbol{\pi}^{(k)}}) \ge 2s > 0$$
, for all pairs (j,k) such that $1 \le j < k \le L$.

(ii) For product densities f_{ℓ}^n defined on \mathcal{X}^n by $f_{\ell}^n(\boldsymbol{x}_1,\ldots,\boldsymbol{x}_n) = f_{\boldsymbol{\pi}^{(\ell)}}(\boldsymbol{x}_1) \times \ldots \times f_{\boldsymbol{\pi}^{(\ell)}}(\boldsymbol{x}_n)$ it holds

$$\max_{\ell \in [L]} \mathrm{KL}(f_{\ell}^n || f_1^n) \le \frac{\log L}{16}. \tag{5.102}$$

Then

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma, D)} \mathbf{P}_f(\mathrm{KL}(f||\widehat{f}) \ge s) \ge 0.17. \tag{5.103}$$

To establish the bound claimed in Theorem 5.4.1, we will split the problem into two parts, corresponding to the following two subsets of $\mathcal{H}_{\mathcal{F}}(\gamma, D)$

$$\mathcal{H}_{\mathcal{F}}(0,D) = \left\{ f_{\boldsymbol{\pi}} : \boldsymbol{\pi} \in \mathbb{B}_{+}^{K} \text{ such that } \exists J \subset [K] \text{ with } \|\boldsymbol{\pi}_{J^{c}}\|_{1} = 0 \text{ and } |J| \leq D \right\},$$

$$\mathcal{H}_{\mathcal{F}}(\gamma,1) = \left\{ f_{\boldsymbol{\pi}} : \boldsymbol{\pi} \in \mathbb{B}_{+}^{K} \text{ such that } \pi_{1} = 1 - \gamma \text{ and } \sum_{j=2}^{K} \pi_{j} = \gamma \right\}.$$
(5.104)

We will show that over $\mathcal{H}_{\mathcal{F}}(0,D)$, we have a lower bound of order $\log(1+K/D)/n$ while over $\mathcal{H}_{\mathcal{F}}(\gamma,1)$, a lower bound of order $\left[\frac{\gamma^2}{n}\log\left(1+K/(\gamma\sqrt{n})\right)\right]^{1/2}$ holds true. Therefore, the lower bound over $\mathcal{H}_{\mathcal{F}}(\gamma,D)$ is larger than the average of these bounds.

For any $M \ge 1$ and $k \in [M-1]$, let Ω_k^M be the subset of $\{0,1\}^M$ defined by

$$\Omega_k^M := \left\{ \boldsymbol{\omega} \in \{0, 1\}^M : \|\boldsymbol{\omega}\|_1 = k \right\}.$$
(5.105)

Before starting, we remind here a version of the Varshamov-Gilbert lemma (see, for instance, [Rigollet and Tsybakov, 2011, Lemma 8.3]) which will be helpful for deriving our lower bounds.

Lemma 5.7.1. Let $M \geq 4$ and $k \in [M/2]$ be two integers. Then there exist a subset $\Omega \subset \Omega_k^M$ and an absolute constant C_1 such that

$$\|\boldsymbol{\omega} - \boldsymbol{\omega}'\|_1 \ge \frac{k+1}{4} \quad \forall \boldsymbol{\omega}, \boldsymbol{\omega}' \in \Omega \text{ s.t. } \boldsymbol{\omega} \ne \boldsymbol{\omega}'$$
 (5.106)

and $L = |\Omega|$ satisfies $L \ge 4$ and

$$\log L \ge C_1 k \log \left(1 + \frac{eM}{k} \right). \tag{5.107}$$

We will also use the following lemma that allows us to relate the KL-divergence $\mathrm{KL}(f_{\pi}||f_{\pi'})$ to the Euclidean distance between the weight vectors π and π' .

Lemma 5.7.2. If the dictionary \mathcal{F} satisfies the boundedness assumption (5.11), then for any $f_{\boldsymbol{\pi}}, f_{\boldsymbol{\pi}'} \in \mathcal{H}_{\mathcal{F}}(\gamma, D)$ we have

$$\frac{1}{2V^2M} \|\mathbf{\Sigma}^{1/2}(\boldsymbol{\pi}' - \boldsymbol{\pi})\|_2^2 \le \text{KL}(f_{\boldsymbol{\pi}}||f_{\boldsymbol{\pi}'}) \le \frac{V^2}{2m} \|\mathbf{\Sigma}^{1/2}(\boldsymbol{\pi}' - \boldsymbol{\pi})\|_2^2.$$
 (5.108)

Proof. Using the Taylor expansion, one can check that for any $u \in [1/L, L]$, we have $(1-u) + \frac{1}{2V^2}(u-1)^2 \le -\log u \le (1-u) + \frac{V^2}{2}(u-1)^2$. Therefore,

$$\frac{1}{2V^2} \int_{\mathcal{X}} \left(\frac{f_{\pi'}}{f_{\pi}} - 1 \right)^2 f_{\pi} \, d\nu \le \text{KL}(f_{\pi}||f_{\pi'}) \le \frac{V^2}{2} \int_{\mathcal{X}} \left(\frac{f_{\pi'}}{f_{\pi}} - 1 \right)^2 f_{\pi} \, d\nu. \quad (5.109)$$

Since \mathcal{F} satisfies the boundedness assumption, we get

$$\frac{1}{2MV^2} \int_{\mathcal{X}} (f_{\pi'} - f_{\pi})^2 d\nu \le \text{KL}(f_{\pi}||f_{\pi'}) \le \frac{V^2}{2m} \int_{\mathcal{X}} (f_{\pi'} - f_{\pi})^2 d\nu. \quad (5.110)$$

The claim of the lemma follows from these inequalities and the fact that $\int_{\mathcal{X}} (f_{\pi'} - f_{\pi})^2 d\nu = \|\mathbf{\Sigma}^{1/2} (\pi' - \pi)\|_2^2.$

5.7.1 Lower bound on $\mathcal{H}_{\mathcal{F}}(0,D)$

We show here that the lower bound $(D/n)\log(1+eK/D)\wedge((1/n)\log(1+K/\sqrt{n}))^{1/2}$ holds when we consider the worst case error for f^* belonging to the set $\mathcal{H}_{\mathcal{F}}(0,D)$.

Proposition 3. If $\log(1 + eK) \le n$ then, for the constant

$$C_2 = \frac{C_1 m \bar{\kappa}_{\Sigma}(2D, 0)}{2^9 V^2 M (C_1 m \vee 4V^2 \lambda_{\max \Sigma}(2D))} \ge \frac{C_1 m \varkappa_*}{2^9 V^2 M (C_1 m \vee 4V^2 \varkappa^*)}, \quad (5.111)$$

we have

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(0,D)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge C_2 \, \frac{D \log(1 + K/D)}{n} \bigwedge \left(\frac{\log(1 + K/\sqrt{n})}{n} \right)^{1/2} \right) \ge 0.17.$$

$$(5.112)$$

Proof. We assume that $D \leq K/2$. The case D > K/2 can be reduced to the case D = K/2 by using the inclusion $\mathcal{H}_{\mathcal{F}}(0, K/2) \subset \mathcal{H}_{\mathcal{F}}(0, D)$. Let us set $A_1 = 4 \vee 16V^2 \lambda_{\max, \Sigma}(2D)/(C_1m)$ and denote by d the largest integer such that

$$d \le D$$
 and $d^2 \log \left(1 + \frac{eK}{d}\right) \le A_1 n.$ (5.113)

According to Lemma 5.7.1, there exists a subset $\Omega = \{\boldsymbol{\omega}^{(\ell)} : \ell \in [L]\}$ of Ω_d^K of cardinality $L \geq 4$ satisfying $\log L \geq C_1 d \log(1 + eK/d)$ such that for any pair of distinct elements $\boldsymbol{\omega}^{(\ell)}$, $\boldsymbol{\omega}^{(\ell')} \in \Omega$ we have $\|\boldsymbol{\omega}^{(\ell)} - \boldsymbol{\omega}^{(\ell')}\|_1 \geq d/4$. Using these binary vectors $\boldsymbol{\omega}^{(\ell)}$, we define the set $\mathcal{D} = \{\boldsymbol{\pi}^{(1)}, \dots, \boldsymbol{\pi}^{(L)}\} \subset \mathbb{B}_+^K$ as follows:

$$\boldsymbol{\pi}^{(1)} = \boldsymbol{\omega}^{(1)}/d, \quad \boldsymbol{\pi}^{(\ell)} = (1 - \varepsilon)\boldsymbol{\pi}^{(1)} + \varepsilon \boldsymbol{\omega}^{(\ell)}/d, \quad \ell = 2, \dots, L.$$
 (5.114)

Clearly, for every $\varepsilon \in [0, 1]$, the vectors $\boldsymbol{\pi}^{(\ell)}$ belong to \mathbb{B}_{+}^{K} . Furthermore, for any pair of distinct values $\ell, \ell' \in [L]$, we have $\|\boldsymbol{\pi}^{(\ell)} - \boldsymbol{\pi}^{(\ell')}\|_{q}^{q} = (\varepsilon/d)^{q} \|\boldsymbol{\omega}^{(\ell)} - \boldsymbol{\omega}^{(\ell')}\|_{1} \ge (\varepsilon/d)^{q} d/4$. In view of Lemma 5.7.2, this yields

$$KL(f_{\boldsymbol{\pi}^{(\ell)}}||f_{\boldsymbol{\pi}^{(\ell')}}) \ge \frac{\bar{\kappa}_{\boldsymbol{\Sigma}}(2d,0)}{4V^2Md} \|\boldsymbol{\pi}^{(\ell)} - \boldsymbol{\pi}^{(\ell')}\|_{1}^{2} \ge \frac{\bar{\kappa}_{\boldsymbol{\Sigma}}(2D,0)}{64V^2M} \times \frac{\varepsilon^2}{d}.$$
 (5.115)

Let us choose

$$\varepsilon^2 = \frac{d^2 \log(1 + eK/d)}{nA_1}. (5.116)$$

It follows from (5.113) that $\varepsilon \leq 1$. Inserting this value of ε in (5.115), we get

$$KL(f_{\pi^{(\ell)}}||f_{\pi^{(\ell')}}) \ge 2C_2 \frac{d\log(1 + eK/d)}{n}.$$
 (5.117)

This shows that condition (i) of Theorem 5.7.1 is satisfied with $s = C_2 (d/n) \log(1 + eK/d)$. For the second condition of the same theorem, we have

$$\max_{\ell \in [L]} KL(f_{\ell}^{n} || f_{1}^{n}) = n \max_{\ell} KL(f_{\pi^{(\ell)}} || f_{\pi^{(1)}})$$
(5.118)

$$\leq \frac{nV^2 \lambda_{\max, \Sigma}(2d)}{2m} \max_{\ell} \|\boldsymbol{\pi}^{(\ell)} - \boldsymbol{\pi}^{(1)}\|_2^2$$
 (5.119)

$$\leq \frac{nV^2 \lambda_{\max, \Sigma}(2D)}{m} \times \frac{\varepsilon^2}{d},\tag{5.120}$$

since one can check that $\|\boldsymbol{\pi}^{(\ell)} - \boldsymbol{\pi}^{(1)}\|_2^2 \leq (\varepsilon/d)^2 \|\boldsymbol{\omega}^{(\ell)} - \boldsymbol{\omega}^{(1)}\|_1 \leq 2\varepsilon^2/d$. Therefore, using the definition of ε , we get

$$\max_{\ell \in [L]} \mathrm{KL}(f_{\ell}^{n} || f_{1}^{n}) \leq \frac{nV^{2} \lambda_{\max, \Sigma}(2D)}{m} \times \frac{C_{1} dm \log(1 + eK/d)}{16nV^{2} \lambda_{\max, \Sigma}(2D)}$$
(5.121)

$$= \frac{C_1 d \log(1 + eK/d)}{16} \le \frac{\log L}{16}.$$
 (5.122)

Theorem 5.7.1 implies that

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(0,D)} \mathbf{P}_f \left(\text{KL}(f||\widehat{f}) \ge C_2 \frac{d \log(1 + eK/d)}{n} \right) \ge 0.17.$$
 (5.123)

We use the fact that d is the largest integer satisfying (5.113). Therefore, either d+1>D or

$$(d+1)^2 \log\left(1 + \frac{eK}{d+1}\right) \le A_1 n.$$
 (5.124)

If $d \geq D$, then the claim of the proposition follows from (5.123), since $d \log(1 + eK/d) \geq D \log(1 + eK/D)$. On the other hand, if (5.124) is true, then

$$d\log(1 + eK/d) \ge \frac{1}{2}(d+1)\log(1 + eK/(d+1)) \ge \frac{1}{2}(A_1n\log(1 + eK/(d+1)))^{1/2}.$$
(5.125)

In addition, $d^2 \log(1 + eK/d) \leq A_1 n$ implies that $(d+1)^2 \leq A_1 n$. Combining the last two inequalities, we get the inequality $d \log(1 + eK/d) \geq \frac{1}{2} \left(A_1 n \log(1 + eK/\sqrt{A_1 n})\right)^{1/2} \geq \left(n \log(1 + eK/\sqrt{n})\right)^{1/2}$. Therefore, in view of (5.123), we get the claim of the proposition.

5.7.2 Lower bound on $\mathcal{H}_{\mathcal{F}}(\gamma, 1)$

Next result shows that the lower bound $\frac{\gamma^2}{n} \log \left(1 + \frac{K}{\gamma \sqrt{n}}\right)$ holds for the worst case error when f^* belongs to the set $\mathcal{H}_{\mathcal{F}}(\gamma, 1)$.

Proposition 4. Assume that

$$\left(\frac{\log(1+eK)}{n}\right)^{1/2} \le 2\gamma. \tag{5.126}$$

Then, for the constant $C_3 = \frac{C_1 m \bar{\kappa}_{\Sigma}(2D,0)}{2^{12} V^4 M \lambda_{\max,\Sigma}(2D)}$, it holds that

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_F(\gamma, 1)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge C_3 \left\{ \frac{\gamma^2}{n} \log \left(1 + \frac{K}{\gamma \sqrt{n}} \right) \right\}^{1/2} \right) \ge 0.17. \quad (5.127)$$

Proof. Let C > 2 be a constant the precise value of which will be specified later. Denote by d the largest integer satisfying

$$d\sqrt{\log(1 + eK/d)} \le C\gamma\sqrt{n}. (5.128)$$

Note that $d \geq 1$ in view of the condition $(\frac{\log(1+eK)}{n})^{1/2} \leq 2\gamma$ of the proposition. This readily implies that $d \leq C\gamma\sqrt{n}$ and, therefore,

$$\frac{\gamma}{d} \ge C^{-1} \left\{ \frac{1}{n} \log \left(1 + \frac{eK}{C\gamma\sqrt{n}} \right) \right\}^{1/2} \ge 2C^{-2} \left\{ \frac{1}{n} \log \left(1 + \frac{K}{\gamma\sqrt{n}} \right) \right\}^{1/2}. \quad (5.129)$$

Let us first consider the case $d \leq (K-1)/2$. According to Lemma 5.7.1, there exists a subset $\Omega \subset \Omega_d^{K-1}$ of cardinality L satisfying $\log L \geq C_1 \log \left(1 + \frac{e(K-1)}{d}\right)$ and $\|\boldsymbol{\omega}^{(\ell)} - \boldsymbol{\omega}^{(\ell')}\|_1 \geq d/4$ for any pair of distinct elements $\boldsymbol{\omega}, \boldsymbol{\omega}'$ taken

from Ω . With these binary vectors in hand, we define the set $\mathcal{D} \subset \mathbb{B}_+^K$ of cardinality L as follows:

$$\mathcal{D} = \left\{ \boldsymbol{\pi} = \left(1 - \gamma, \gamma \boldsymbol{\omega} / d \right) : \quad \omega \in \Omega \right\}.$$
 (5.130)

It is clear that all the vectors of \mathcal{D} belong to $\mathcal{H}_{\mathcal{F}}(\gamma,1)$. Let us fix now an element of \mathcal{D} and denote it by π^1 , the corresponding element of Ω being denoted by ω^1 . We have

$$\max_{\boldsymbol{\pi} \in \mathcal{D}} KL(f_{\boldsymbol{\pi}}^{n} || f_{\boldsymbol{\pi}^{1}}^{n}) \leq \frac{nV^{2}}{2m} \max_{\boldsymbol{\pi} \in \mathcal{D}} \|\boldsymbol{\Sigma}^{1/2}(\boldsymbol{\pi} - \boldsymbol{\pi}^{1})\|_{2}^{2}$$
 (5.131)

$$\leq \frac{nV^2 \lambda_{\max, \Sigma}(2d)\gamma^2}{2md^2} \max_{\boldsymbol{\omega} \in \Omega} \|\boldsymbol{\omega} - \boldsymbol{\omega}^1\|_2^2$$
 (5.132)

$$\leq \frac{nV^2 \lambda_{\max, \mathbf{\Sigma}}(2d)\gamma^2}{md}.$$
(5.133)

The definition of d yields $(d+1)\sqrt{\log(1+eK/(d+1))} > C\gamma\sqrt{n}$, which implies that

$$\frac{\gamma^2}{d} \le 2(d+1)\frac{\gamma^2}{(d+1)^2} \le 2(d+1)\frac{\log\left(1 + eK/(d+1)\right)}{nC^2} \le \frac{4d\log\left(1 + e(K-1)/d\right)}{nC^2}.$$
(5.134)

Combined with eq. (5.133), this implies that

$$\max_{\boldsymbol{\pi} \in \mathcal{D}} \mathrm{KL}(f_{\boldsymbol{\pi}}^n || f_{\boldsymbol{\pi}^1}^n) \le \frac{nV^2 \lambda_{\max, \boldsymbol{\Sigma}}(2d)}{m} \times \frac{4d \log \left(1 + e(K - 1)/d\right)}{nC^2} \tag{5.135}$$

$$= \frac{4V^2 \lambda_{\max, \Sigma}(2d)}{mC^2} \times d\log\left(1 + e(K - 1)/d\right). \tag{5.136}$$

Choosing

$$C^2 = 2 \vee \frac{64V^2 \lambda_{\max, \Sigma}(2d)}{C_1 m}$$

we get that $\max_{\boldsymbol{\pi} \in \mathcal{D}} \mathrm{KL}(f_{\boldsymbol{\pi}}^n || f_{\boldsymbol{\pi}^1}^n) \leq \frac{1}{16} C_1 d \log \left(1 + e(K-1)/d\right) \leq \frac{\log L}{16}$. Furthermore, for any $\boldsymbol{\pi}, \boldsymbol{\pi}' \in \mathcal{D}$, in view of Lemma 5.7.2 and (5.129), we

have

$$KL(f_{\pi}||f_{\pi'}) \ge \frac{\bar{\kappa}_{\Sigma}(2d,0)}{4V^2Md} \|\pi - \pi'\|_{1}^{2} = \frac{\bar{\kappa}_{\Sigma}(2d,0)\gamma^{2}}{4V^2Md^{3}} \|\omega - \omega'\|_{1}^{2}$$
 (5.137)

$$\geq \frac{\bar{\kappa}_{\Sigma}(2d,0)}{64V^2M} \times \frac{\gamma^2}{d} \tag{5.138}$$

$$\geq \frac{\bar{\kappa}_{\Sigma}(2d,0)}{32V^2MC^2} \times \left\{ \frac{\gamma^2}{n} \log\left(1 + \frac{K}{\gamma\sqrt{n}}\right) \right\}^{1/2}.$$
 (5.139)

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Since $\frac{\bar{\kappa}_{\Sigma}(2d,0)}{32V^2MC^2} = 2C_3$, this implies that Theorem 5.7.1 can be applied, which leads to the inequality

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma, 1)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge C_3 \left\{ \frac{\gamma^2}{n} \log \left(1 + \frac{K}{\gamma \sqrt{n}} \right) \right\}^{1/2} \right) \ge 0.17. \quad (5.140)$$

To complete the proof of the proposition, we have to consider the case d > (K-1)/2. In this case, we can repeat all the previous arguments for d = K/2 and get the desired inequality.

5.7.3 Lower bound holding for all densities

Now that we have lower bounds in probability for $\mathcal{H}_{\mathcal{F}}(0,D)$ and $\mathcal{H}_{\mathcal{F}}(\gamma,1)$, we can derive a lower bound in expectation for $\mathcal{H}_{\mathcal{F}}(\gamma,D)$. In particular, to prove Theorem 5.4.1, we will use the inequality

$$\mathcal{R}(\mathcal{H}_{\mathcal{F}}(\gamma, D)) \ge \inf_{\widehat{f}} \sup_{f^* \in \mathcal{H}_{\mathcal{F}}(0, D) \cup \mathcal{H}_{\mathcal{F}}(\gamma, 1)} \mathbf{E}[\mathrm{KL}(f^* || \widehat{f})]. \tag{5.141}$$

Proof of Theorem 5.4.1. To ease notation, let us define

$$r(n,K,\gamma,D) = \left[\frac{\gamma^2}{n}\log\left(1 + \frac{K}{\gamma\sqrt{n}}\right)\right]^{1/2} + \frac{D\log(1 + K/D)}{n} \bigwedge\left(\frac{\log(1 + K/\sqrt{n})}{n}\right)^{1/2}.$$
(5.142)

We first consider the case where the dominating term is the first one, that is

$$\left[\frac{\gamma^2}{n}\log\left(1+\frac{K}{\gamma\sqrt{n}}\right)\right]^{1/2} \ge \frac{3D\log(1+K/D)}{n}.\tag{5.143}$$

On the one hand, since $D \geq 1$, we have

$$\frac{3D\log(1+K/D)}{n} \ge \frac{\log(1+eK)}{n}.$$
 (5.144)

On the other hand, using the inequality $\log(1+x) \leq x$, we get

$$\left[\frac{\gamma^{2}}{n}\log\left(1+\frac{K}{\gamma\sqrt{n}}\right)\right]^{1/2} \leq \frac{\gamma}{\sqrt{n}} \left[\log(1+eK) + \log\left(1+\frac{1}{e^{2}\gamma^{2}n}\right)\right]^{1/2}$$

$$\leq \gamma \left[\frac{\log(1+eK)}{n}\right]^{1/2} + \frac{\gamma}{\sqrt{n}} \left[\frac{1}{e^{2}\gamma^{2}n}\right]^{1/2}$$

$$\leq \gamma \left[\frac{\log(1+eK)}{n}\right]^{1/2} + \frac{\log(1+eK)}{2n}.$$
(5.146)

Combining (5.143), (5.144) and (5.147), we get

$$\left(\frac{\log(1+eK)}{n}\right)^{1/2} \le 2\gamma. \tag{5.148}$$

This implies that we can apply Proposition 4, which yields

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma, D)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge C_3 \left\{ \frac{\gamma^2}{n} \log \left(1 + \frac{K}{\gamma \sqrt{n}} \right) \right\}^{1/2} \right) \ge 0.17. \quad (5.149)$$

In view of (5.143), this implies that

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma, D)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge \frac{3}{4} C_3 \, r(n, K, \gamma, D) \right) \ge 0.17. \tag{5.150}$$

We now consider the second case, where the dominating term in the rate is the second one, that is

$$\left[\frac{\gamma^2}{n}\log\left(1 + \frac{K}{\gamma\sqrt{n}}\right)\right]^{1/2} \le \frac{3D\log(1 + K/D)}{n} \bigwedge \left(\frac{\log(1 + K/\sqrt{n})}{n}\right)^{1/2}.$$
(5.151)

In view of Proposition 3, we have

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma, D)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge C_2 \frac{D \log(1 + K/D)}{n} \bigwedge \left(\frac{\log(1 + K/\sqrt{n})}{n} \right)^{1/2} \right) \ge 0.17.$$

$$(5.152)$$

In view of (5.151), we get

$$\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma, D)} \mathbf{P}_f \left(\mathrm{KL}(f||\widehat{f}) \ge \frac{1}{4} C_2 \, r(n, K, \gamma, D) \right) \ge 0.17. \tag{5.153}$$

Thus, we have proved that $\log(1+eK) \leq n$ implies that $\inf_{\widehat{f}} \sup_{f \in \mathcal{H}_{\mathcal{F}}(\gamma,D)} \mathbf{P}_f \big(\mathrm{KL}(f||\widehat{f}) \geq C_4 \, r(n,K,\gamma,D) \big) \geq 0.17$ for some constant $C_4 > 0$, whatever the relation between γ and D. The desired lower bound follows now from the Tchebychev inequality $\mathbf{E} \big[\mathrm{KL}(f||\widehat{f}) \big] \geq C_4 \, r(n,K,\gamma,D) \mathbf{P}_f \big(\mathrm{KL}(f||\widehat{f}) \geq C_4 \, r(n,K,\gamma,D) \big)$.

Appendix A: Concentration inequalities

This section contains some well-known results, which are recalled here for the sake of the self-containedness of the paper. **Theorem 5.7.2.** For each s = 1, ..., N, let $Y_{1,s}, ..., Y_{n,s}$ be n independent and zero mean random variables such that for some real numbers a, b we have $\mathbf{P}(Y_{i,s} \in [a,b]) = 1$ for all $i \in [n]$ and $s \in [N]$. Then, we have

$$\mathbf{E}\Big[\max_{s\in[N]} \frac{1}{n} \sum_{i=1}^{n} Y_{i,s}\Big] \le (b-a) \Big(\frac{\log N}{2n}\Big)^{1/2}, \quad \mathbf{E}\Big[\max_{s\in[N]} \Big|\frac{1}{n} \sum_{i=1}^{n} Y_{i,s}\Big|\Big] \le (b-a) \Big(\frac{\log(2N)}{2n}\Big)^{1/2}.$$
(5.154)

Proof. We denote $Z_s = \frac{1}{n} \sum_{i=1}^n Y_{i,s}$ for s = 1, ..., N and $Z_s = -\frac{1}{n} \sum_{i=1}^n Y_{i,s}$ for s = N+1, ..., 2N. For every $s \in [2N]$, the logarithmic moment generating function $\psi_s(\lambda) = \log \mathbf{E}[e^{\lambda Z_s}]$ satisfies

$$\psi_s(\lambda) = \log\left(\prod_i \mathbf{E}[e^{\lambda Y_{i,s}/n}]\right) = \sum_{i=1}^n \log \mathbf{E}[e^{\lambda Y_{i,s}/n}] \le \frac{\lambda^2 (b-a)^2}{8n}, \quad (5.155)$$

where the last inequality is a consequence of the Hoeffding lemma (see, for instance, Lemma 2.2 in [Boucheron et al., 2013]). This means that Z_s is sub-Gaussian with variance-factor $\nu = (b-a)^2/4n$. Therefore, Theorem 2.5 from [Boucheron et al., 2013] yields $\mathbf{E}[\max_s Z_s] \leq \sqrt{2\nu \log(2N)}$, which completes the proof.

We group and state together the bounded differences and the Efron-Stein inequalities (Boucheron et al. [2013], Theorems 6.2 and 3.1, respectively).

Theorem 5.7.3. Assume that a function f satisfies the bounded difference condition: there exist constants c_i , i = 1, ..., n such that for all i = 1, ..., n, all $X = (X_1, ..., X_i, ..., X_n)$ and $X' = (X_1, ..., X_i', ..., X_n)$ where only the ith vector is changed

$$|f(X) - f(X')| \le c_i. (5.156)$$

Denote

$$\nu = \sum_{i=1}^{n} c_i^2. \tag{5.157}$$

Let $Z = f(X_1, ..., X_n)$ where X_i are independent. Then, for every $\delta \in (0, 1)$,

$$\mathbf{P}\left\{Z \le \mathbf{E}Z + \left(\frac{\nu \log(1/\delta)}{2}\right)^{1/2}\right\} \ge 1 - \delta, \quad and \quad \mathbf{Var}[Z] \le \frac{\nu}{2}. \quad (5.158)$$

Next we state the contraction principle of [Ledoux and Talagrand, 1991]; a proof can be found in (Boucheron et al. [2013], Theorem 11.6).

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Theorem 5.7.4. Let x_1, \ldots, x_n be vectors whose real-valued components are indexed by \mathcal{T} , that is, $x_i = (x_{i,s})_{s \in \mathcal{T}}$. For each $i = 1, \ldots, n$ let $\varphi_i : \mathbb{R} \to \mathbb{R}$ be a 1-Lipschitz function such that $\varphi_i(0) = 0$. Let $\epsilon_1, \ldots, \epsilon_n$ be independent Rademacher random variables, and let $\Psi : [0, \infty) \to \mathbb{R}$ be a non-decreasing convex function. Then

$$\mathbf{E}\left[\Psi\left(\frac{1}{2}\sup_{s\in\mathcal{T}}\left|\sum_{i=1}^{n}\epsilon_{i}\varphi_{i}(x_{i,s})\right|\right)\right] \leq \mathbf{E}\left[\Psi\left(\sup_{s\in\mathcal{T}}\left|\sum_{i=1}^{n}\epsilon_{i}x_{i,s}\right|\right)\right]$$
(5.159)

$$\mathbf{E}\left[\Psi\left(\sup_{s\in\mathcal{T}}\sum_{i=1}^{n}\epsilon_{i}\varphi_{i}(x_{i,s})\right)\right] \leq \mathbf{E}\left[\Psi\left(\sup_{s\in\mathcal{T}}\sum_{i=1}^{n}\epsilon_{i}x_{i,s}\right)\right].$$
 (5.160)

Chapter 6

Numerical Experiments

In this section we describe the implementation of the algorithm. We also compare its performance with different alternative methods.

6.1 Implementation details

In this section we describe the implementation of the algorithm described in the previous chapter. But before anything else, we remind the reader the problem setting and the estimator considered.

6.1.1 Problem considered

We observe n independent random vectors $X_1, \ldots, X_n \in \mathcal{X}$ drawn from a probability distribution P^* that admits a density function f^* . Given a family of mixture components f_1, \ldots, f_K , we assumed that this unknown density is well approximated by a convex combination f_{π} of these components

$$f_{\pi}(\boldsymbol{x}) = \sum_{j=1}^{K} \pi_j f_j(\boldsymbol{x}), \quad \pi \in \mathbb{B}_+^K = \left\{ \pi \in [0, 1]^K : \sum_{j=1}^K \pi_j = 1 \right\}.$$
 (6.1)

The component densities $\mathcal{F} = \{f_j : j \in [K]\}$ are assumed to be given by previous experiments or expert knowledge. The problem of construction of this family is an open problem that we try to address in section? Our objective is to estimate the weight vector $\boldsymbol{\pi}$ from the simplex \mathbb{B}_+^K under the sparsity scenario and investigate the statistical properties of the Maximum Likelihood Estimator (MLE), defined by

$$\widehat{\boldsymbol{\pi}} \in \underset{\boldsymbol{\pi} \in \Pi}{\operatorname{arg\,min}} \Big\{ -\frac{1}{n} \sum_{i=1}^{n} \log f_{\boldsymbol{\pi}}(\boldsymbol{X}_i) \Big\}, \tag{6.2}$$

where the minimum is computed over a suitably chosen subset Π of \mathbb{B}_{+}^{K} .

6.1.2 Implementation

The computation of eq. (6.2) is fairly simple as the objective function and the set Π are convex and can be easily solved by convex programming. We wrote the algorithm in Python and used the modeling language CVXPYDiamond and Boyd [2016].

We give a dictionary of densities in input. Give pseudo code

```
from sklearn.base import BaseEstimator
import numpy as np
from cvxpy import *
class WeightEstimator(BaseEstimator):
    def __init__(self, densities_dict, select_threshold=10e-3):
        self.densities_dict = densities_dict
        self.K = len(self.densities_dict)
        self.select_threshold = select_threshold
    def fit(self, X):
        self.F = np.array([self.densities_dict[i].pdf(X) for i in range(sel
        F = np.array([self.densities_dict[i].pdf(X) for i in range(self.K)]
        self.pi = Variable(self.K)
        constraints = [sum_entries(self.pi) == 1, self.pi >= 0, self.pi <=</pre>
        objective = Minimize(-sum_entries(log(F * self.pi)))
        prob = Problem(objective, constraints)
        prob.solve()
```

6.2 Alternative methods considered

6.2.1 SPADES

not working

From Bunea et al. [2010]

6.2.2 Adaptive Dantzig density estimation

We will compare our method with the Adaptive Dantzig estimator in the density model which has been introduced in Bertin et al. [2011]. This method is similar to ours as it construct an estimator of the unknown density from a linear mixtures of functions taken from a dictionary. The key idea of this paper is to minimize the ℓ_1 -norm of the weight vector of the linear

combination under an adaptive Dantzig constraint. This constraint comes from sharp concentration inequalities. We recall here some material about the Dantzig selector. It has been introduced by Candes and Tao [2007] in the linear regression model

$$Y = A\lambda_0 + \epsilon \tag{6.3}$$

where $Y \in \mathbb{R}^n$, A is a n by M matrix, $\epsilon \in \mathbb{R}^n$ is the noise vector and λ_0 the unknown regression parameter to estimate. The Dantzig estimator is then defined by_____

Définir ℓ_1 et ℓ_{∞}

$$\widehat{\lambda}^D = \arg\min \lambda \in \mathbb{R}^M \|\lambda\|_1 \quad \text{subject to} \quad \|A^T (A\lambda - Y)\|_{\infty} \le \eta.$$
 (6.4)

where η is the regularization parameter. Bickel et al. [2009] considered the non-parametric regression framework

$$Y_i = f(x_i) + e_i, \quad i = 1, \dots, n$$
 (6.5)

where f is an unknown function, the design points $(x_i)_{i=1,...,n}$ are known and $(e_i)_{i=1,...,n}$ is a noise vector. One can estimate f as a weighted sum f_{λ} of elements of a dictionary $D = (\varphi_m)_{m=1,...,M}$

$$f_{\lambda} = \sum_{i=1}^{M} \lambda_m \varphi_m. \tag{6.6}$$

The goal of Bertin et al. [2011] was to estimate an unknown density f_0 with respect to a known measure dx on \mathbb{R} by using the observation of n-sample X_1, \ldots, X_n and build a linear mixture density f_{λ} of elements of the dictionary D as in eq. (6.6). Let us consider the empirical scalar product of f_0 and φ_m

$$\widehat{\beta}_m = \frac{1}{n} \sum_{i=1}^n \varphi_m(X_i) \xrightarrow{\text{a.s.}} \int \varphi_m(x) f_0(x) dx = \beta_{0,m}, \tag{6.7}$$

and the Gram matrix associated to the dictionary D

$$G_{m,m'} = \int \varphi_m(x)\varphi_{m'}(x)dx \quad \text{with} \quad 1 \le m, m' \le M.$$
 (6.8)

The scalar product of f_{λ} and φ_m is therefore

$$\int \varphi_m(x) f_{\lambda}(x) dx = \sum_{m'=1}^M \lambda_{m'} \int \varphi_{m'}(x) \varphi_m(x) dx = (G\lambda)_m.$$
 (6.9)

The Dantzig estimate $\widehat{\lambda}^D$ is then obtained by solving the following constrained minimization problem

$$\begin{cases} \text{minimize} & \|\lambda\|_1\\ \text{subject to} & |(G\lambda)_m - \widehat{\beta}| \le \eta_{\gamma,m} & m \in \{1, \dots, M\}, \end{cases}$$

where for a constant $\gamma > 0$ chosen

$$\eta_{\gamma,m} = \sqrt{\frac{2\tilde{\sigma}_m^2 \gamma \log M}{n}} + \frac{2\|\varphi_m\|_{\infty} \gamma \log M}{3n},\tag{6.10}$$

with

$$\tilde{\sigma}_m^2 = \hat{\sigma}_m^2 + 2\|\varphi_m\|_{\infty} \sqrt{\frac{2\hat{\sigma}_m^2 \gamma \log M}{n}} + \frac{8\|\varphi_m\|_{\infty}^2 \gamma \log M}{n}, \tag{6.11}$$

and

$$\widehat{\sigma}_m^2 = \frac{1}{n(n-1)} \sum_{i=2}^n \sum_{j=1}^{i-1} (\varphi_m(X_i) - \varphi_m(X_j)). \tag{6.12}$$

Note that $\eta_{\gamma,m}$ depends on the data which explains the name Adaptive Dantzig. The authors of Bertin et al. [2011] derived the form of $\eta_{\gamma,m}$ from sharp concentration inequalities (see theorem 1 of Bertin et al. [2011]). More precisely, if we consider $\lambda_0 = (\lambda_{0,m})_{m=1,\dots,M}$ such that the projection of f_0 on the space spanned by D is

$$\mathbf{P}_D f_0 = \sum_{m=1}^M \lambda_{0,m} \varphi_m, \tag{6.13}$$

a expliquer

parler des hypotheses sur la matrice Gram then $(G\lambda_0)_m = \beta_{0,m}$ and the parameter $\eta_{\gamma,m}$ can be seen as the smallest quantity such that, for $\gamma > 1$, we have $|\beta_{0,m} - \widehat{\beta}_m| \leq \eta_{\gamma,m}$ with high probability. The main result of this paper is a bound on the L_2 risk of the adaptive Dantzig density estimator with high probability without any assumptions on the unknown density f_0 . The discussion of this result goes beyond the scope of this section. Note that the assumption $\gamma > 1$ is an almost necessary condition to have a theoretical control on the quadratic error $\mathbf{E} \| \widehat{f}^D - f_0 \|_2^2$. Therefore, we will follow the choice of $\gamma = 1.01$ made by the authors in our experiments. The pseudo code of the procedure is given in fig. 6.1. The Adaptive Dantzig density estimator is noted \widehat{f}^{AD} .

- 1: Input: A sample $X_1, \ldots, X_n \in \mathbb{R}^p$ and the dictionary D =
- 2: Output: Dantzig density estimate $\hat{f}^{AD} = f_{\hat{\lambda}^D}$.

- 3: **Init:** Set $\gamma = 1.01$. 4: Compute $\widehat{\beta}_m = \frac{1}{n} \sum_{i=1}^{N} \varphi_m(X_i)$. 5: Compute $\widehat{\sigma}_m^2 = \frac{1}{n(n-1)} \sum_{i=2}^{n} \sum_{j=1}^{i-1} (\varphi_m(X_i) \varphi_m(X_j))^2$.
- 6: Compute $\tilde{\sigma}_m^2$.

$$\tilde{\sigma}_m^2 = \hat{\sigma}_m^2 + 2\|\varphi_m\|_{\infty} \sqrt{\frac{2\hat{\sigma}_m^2 \gamma \log M}{n}} + \frac{8\|\varphi_m\|_{\infty}^2 \gamma \log M}{n}. \quad (6.14)$$

7: Compute $\eta_{\gamma,m}$

$$\eta_{\gamma,m} = \sqrt{\frac{2\tilde{\sigma}_m^2 \gamma \log M}{n}} + \frac{2\|\varphi_m\|_{\infty} \gamma \log M}{3n}.$$

8: Compute the coefficients $\widehat{\lambda}^{D,\gamma}$ of the Dantzig estimate, $\widehat{\lambda}^{D,\gamma}$ $\arg\min_{\lambda\in\mathbb{R}^M} \|\lambda\|_1$ such that λ satisfies the Dantzig constraint

$$\forall m \in \{1, \dots, m\}, \quad |(G\lambda)_m - \widehat{\beta}_m| \le \eta_{\gamma, m}.$$
 (6.15)

9: Compute the mixture density $f_{\widehat{\lambda}^D} = \sum_{m=1}^M \widehat{\lambda}_m^D \varphi_m$.

Figure 6.1: Adaptive Dantzig density estimation procedure

6.2.3Kernel density estimation

The kernel density estimator is a well established non-parametric way of estimating the probability density function of a random variable. We will recall in this section some material about KDE.

Let X_1, \ldots, X_n be i.i.d random variables drawn from an unknown probability density f with respect to the Lebesgue measure on \mathbb{R} . The kernel density estimator f_h is given by

$$\widehat{f}_h(x) \triangleq \frac{1}{n} \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) \tag{6.16}$$

where $K: \mathbb{R} \to \mathbb{R}$ and $\int K(u)du = 1$ is called a Kernel and h is the bandwidth. We used gaussian kernels and the Sheather and Jones bandwidth selection procedure (Sheather and Jones [1991]) described below

à ajouter

6.3 Experimental Evaluations

In the experimental evaluation, we had to construct a set of target densities with different shapes to evaluate the performances of the estimators. We also had to build different density (more generally functions) dictionaries. Finally we assessed the performance through the Kullback-Leibler and L_2 distance.

6.3.1 Dictionaries considered

- 1. Gaussians
- 2. A union of Gaussians and Laplacians densities called D_{GL} . The Gaussians has their means in $\{0, 0.2, 0.4, 0.6, 0.8, 1\}$ and their variances in $\{0.001, 0.01, 0.1, 1\}$. The Laplacians has their means in $\{0, 0.2, 0.4, 0.6, 0.8, 1\}$ and their scales in $\{0.05, 0.1, 0.5, 1\}$. Therefore, D_{GL} has 48 elements.

verifier les scales par rapport au code

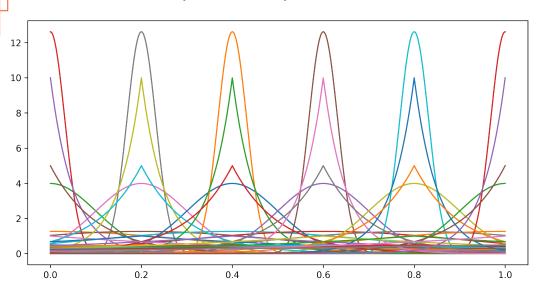


Figure 6.2: D_{GL} , union of Gaussians and Laplacians densities.

not positive

3. Haar wavelet basis?

not positive

4. Daubechies wavelet?

6.3.2 Densities considered

We considered 5 target densities corresponding to 5 different scenarios. The 1^{st} and 2^{nd} will asses the performance of our method on uniform based densities, the 3^{rd} and 4^th on dictionary based density. The last one is a complex

density made from elements which are not in the dictionary that we will consider.

- 1. f_{unif} : A uniform density on [0, 1].
- 2. f_{rect} : A mixture of uniform densities on subintervals. This density is called "Rectangular"

$$f_{rect}(x) = \frac{10}{7} \mathbf{1}_{[0,1/5]} + \frac{5}{7} \mathbf{1}_{[1/5,2/5]} + \frac{10}{7} \mathbf{1}_{[2/5,3/5]} + \frac{10}{7} \mathbf{1}_{[4/5,1]}$$
 (6.17)

3. f_{gauss} : A mixture of 5 Gaussian densities taken from the dictionary D_{GL} equally centered in [0, 1] with same variance.

$$f_{gauss}(x) = \sum_{k=1}^{5} 0.2 f_k(x)$$
 with $f_k = \varphi_{(k/5,0.001)}$ (6.18)

4. $f_{gauss-lapl}$: A mixture of 5 Gaussian and Laplacian densities taken from the dictionary D_{GL} with different variances and scales.

$$f_{gauss-lapl}(x) = 0.2 \left(\varphi_{(0,10^{-2})} + \varphi_{(0.2,10^{-3})} + \varphi_{(0.6,10^{-3})} + \operatorname{Lapl}_{(0.4,0.2)} + \operatorname{Lapl}_{(0.8,0.1)} \right)$$
(6.19)

5. f_{ext} : A mixture of Gaussian and Laplacian densities taken from another dictionary D_{out} .

attention a recuperer les derniers resul-

$$f_{ext}(x) = \sum_{k=1}^{7} \frac{1}{7} f_k(x)$$
 with $f_k \in D_{out}$ (6.20)

These target densities are plotted in fig. 6.3.

6.3.3 Discussion of the results

The results are plotted in fig. 6.4. The dictionary used for the Adaptive Dantzig and the Maximum likelihood density estimator is D_{GL} . Note that it is interesting to compare the MLE to A.D as both methods relies on a dictionary. We also benchmarked our method with the Gaussian kernel density estimator. KDE refers to the kernel density estimate with Scott's rule as chosen by default in the Python library Scipy and KDE-SJ refers to the KDE with the Sheather-Jones bandwidth selector. For each scenario of target density, f_{unif} , f_{rect} , f_{gauss} , $f_{gauss-lapl}$, f_{ext} and for each sample size N with $N \in \{100, 500, 1000\}$, we ran 200 simulations.

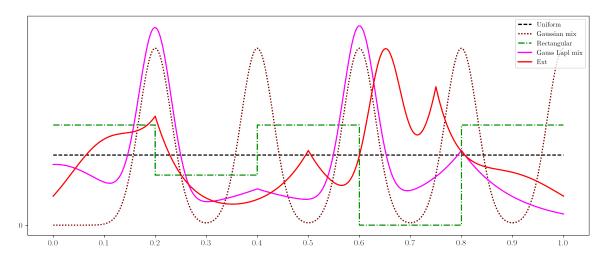


Figure 6.3: Five target densities considered.

At first glance, the performance of the MLE seems good in Kullback-Leibler loss and L_2 . The method showing the worst performance in all scenarios is the Adaptive Dantzig. The MLE present a relative small variance, smaller than KDE-SJ which is the best KDE method studied regarding the loss. Another interesting observation is the small impact of the size of sample for the MLE.

We will cover each scenarios. Surprisingly the MLE performance is as good as kernel based methods on the uniform case since the dictionary given could not provide a good mixture density that approach well this target density. However, this is not the case for the rectangular density f_{rect} which shows the worst performance for the MLE. It should be possible to increase the performance of the MLE by adding uniform densities on different segments of [0, 1] in the dictionary. The performance of the MLE is better in the next three scenarios. When the target density is the mixture of Gaussians f_{qauss} , the MLE presents the best result, with a small variance, both in L_2 and KL loss. The second best is KDE-SJ. Note that the default KDE in Scipy with Scott's rule presents the worse result in this scenario which should have reasonably performed well considering the use of Gaussian kernels. This observation should come to mind of the practitioner when applying kernel density estimators with default package setting. The fourth scenario, $f_{qauss-lapl}$ is a more complex density made from elements of the dictionary D_{GL} and the MLE is the best method. Surprisingly the L_2 and KL loss of KDE are not similar. Finally, in the last scenario, we wanted to measure the performance of the dictionary based methods against a target density which is not a mixture of elements of the dictionary, f_{ext} . MLE has a good performance in KL loss

but performs badly compared to Kernel methods in L_2 loss. The adaptive Dantzig shows better results in this scenario.

To conclude, the performance of the MLE method in these simulations is promising to achieve a good mixture density estimate. We would like to mention the computational efficiency of the MLE method as it is a convex problem, the whole procedure to construct the estimator is simple and its dimension is the size of the dictionary considered. During our simulations, the MLE method showed a huge difference in time computation compared to the Adaptive Dantzig. At the light of the results in the uniform and rectangular case, the choice of the dictionary is a cornerstone in constructing a good mixture density, this is a classical problem of dictionary-based methods. In the next section, we will test the MLE method with real datasets.

6.4 Real use case

The code is available on github



Figure 6.4: Results of Adaptive Dantzig, Kernel density estimator with Scott Rule (KDE), Kernel density estimator with the Sheather-Jones bandwidth selector (KDE SJ) and Maximum likelihood estimator. Left column, KL loss, right, L_2 . From top to bottom the target density is f_{unif} , f_{rect} , f_{gauss} , $f_{gauss-lapl}$, f_{ext} . With 200 simulations.

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