

## 0.1 Predictor-Corrector Method

Remainder:

Adams-Bashforth four-step method:

$$w_0 = \alpha, \quad w_1 = \alpha_1, \quad w_2 = \alpha_2, \quad w_3 = \alpha_3$$

$$w_{i+1} = w_i + \frac{h}{24} [55f(t_i, w_i) - 59f(t_{i-1}, w_{i-1}) + 37f(t_{i-2}, w_{i-2}) - 9f(t_{i-3}, w_{i-3})] \quad \text{for } i = 3, 4, 5, \dots, N-1$$

Adams-Moulton three-step method:

$$w_0 = \alpha, \quad w_1 = \alpha_1, \quad w_2 = \alpha_2$$

$$w_{i+1} = w_i + \frac{h}{24} [9f(t_{i+1}, w_{i+1}) + 19f(t_i, w_i) - 5f(t_{i-1}, w_{i-1}) + f(t_{i-2}, w_{i-2})] \quad \text{for } i = 2, 3, \dots, N-1$$

IVP:  $\frac{dy}{dt} = y' = f(t, y); \quad a \leq t \leq b, y(a) = y(t_0) = \alpha$

For  $i = 3$ , from Adams-Bashforth four-step method, we have,

$$w_4 = w_3 + \frac{h}{24} [55f(t_3, w_3) - 59f(t_2, w_2) + 37f(t_1, w_1) - 9f(t_0, w_0)] \quad (1)$$

For Predictor-Corrector method, we denote  $w_4^{(0)}$  for  $w_4$  so

$$w_4^{(0)} = w_3 + \frac{h}{24} [55f(t_3, w_3) - 59f(t_2, w_2) + 37f(t_1, w_1) - 9f(t_0, w_0)] \quad (2)$$

Here we know only  $w_0 = \alpha$ , so, first we need to calculate  $w_1, w_2, w_3$  using RK-4. Then using the values of  $w_0, w_1, w_2, w_3$  we will get  $w_4^{(0)}$  from (2).

Now, we use Adams-Moulton three-step method as a corrector:

$$w_4^{(1)} = w_3 + \frac{h}{24} [9f(t_4, w_4^{(0)}) + 19f(t_3, w_3) - 5f(t_2, w_2) + f(t_1, w_1)] \quad (3)$$

Here  $f(t_4, w_4^{(0)})$  will evaluate using the value of  $w_4^{(0)}$  that already calculated using (2).

After calculation of (3), we will get  $w_4^{(1)}$ . If we will not achieve required accuracy, e.g.,  $|w_4^{(1)} - w_4^{(0)}| < 10^{-4}$ , then we have to proceed in the following way:

$$w_4^{(2)} = w_3 + \frac{h}{24} [9f(t_4, w_4^{(1)}) + 19f(t_3, w_3) - 5f(t_2, w_2) + f(t_1, w_1)] \quad (4)$$

Note that only  $f(t_4, w_4^{(1)})$  have to evaluate but  $f(t_3, w_3), f(t_2, w_2), f(t_1, w_1)$  already evaluated when you perform equation (2).

If  $w_4^{(2)}$  is not achieved desired accuracy, then

$$w_4^{(3)} = w_3 + \frac{h}{24} [9f(t_4, w_4^{(2)}) + 19f(t_3, w_3) - 5f(t_2, w_2) + f(t_1, w_1)] \quad (5)$$

If still not get required accuracy, we will have to repeat these processes.

If required accuracy will achieve (say  $w_4^{(0)}$  or  $w_4^{(1)}$  or  $w_4^{(2)}$  or  $w_4^{(3)}$ ), then

$$w_5^{(1)} = w_4 + \frac{h}{24} [9f(t_5, w_5^{(0)}) + 19f(t_4, w_4) - 5f(t_3, w_3) + f(t_2, w_2)] \quad (6)$$

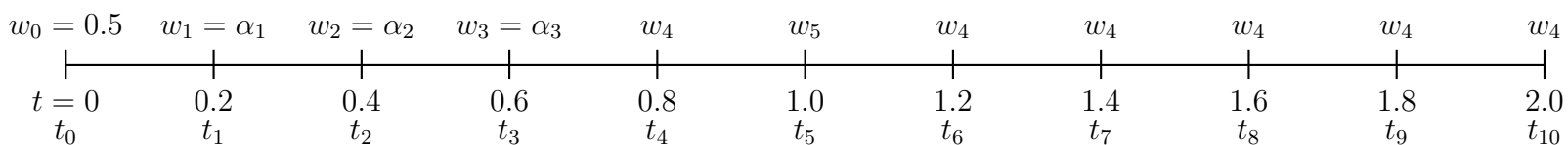
where,

$$w_5^{(0)} = w_4 + \frac{h}{24} [55f(t_4, w_4) - 59f(t_3, w_3) + 37f(t_2, w_2) - 9f(t_1, w_1)] \quad (7)$$

[Here  $w_4$  is either  $w_4^{(0)}$  or  $w_4^{(1)}$  or  $w_4^{(2)}$  or  $w_4^{(3)}$ ]

Equation (6) is repeated until get required accuracy.

**Example.** IVP:  $y' = y - t^2 + 1; 0 \leq t \leq 2, y(0) = 0.5$  and  $N = 10$ , so  $h = 0.2$ .



For Predictor-corrector process; here  $w_0 = \alpha = 0.5$  is known, so we have to evaluate  $w_1, w_2, w_3$  with RK4, then using these values, we will get  $w_4^{(0)}$  from (2). After getting  $w_4^{(0)}$ , we will obtain  $w_4^{(1)}$  using (3).

$w_4^{(1)}$  is the approximate value at  $t = t_4 = 0.8$ . Such process is needed to repeat until  $t = t_{10} = 2$ .

*Note.*

$$w_{i+1}^{(k+1)} = w_i + \frac{h}{24} [9f(t_{i+1}, w_{i+1}^{(k)}) + 19f(t_i, w_i) - 5f(t_{i-1}, w_{i-1}) + f(t_{i-2}, w_{i-2})]$$

Here ' $k$ ' is the iteration index and  $i$  is the grid/node index.

Let  $k = 0$ ; then,

$$w_{i+1}^{(1)} = w_i + \frac{h}{24} [9f(t_{i+1}, w_{i+1}^{(0)}) + 19f(t_i, w_i) - 5f(t_{i-1}, w_{i-1}) + f(t_{i-2}, w_{i-2})]; \quad i = 3, 4, 5, \dots$$

So,

$$w_4^{(1)} = w_3 + \frac{h}{24} [9f(t_4, w_4^{(0)}) + 19f(t_3, w_3) - 5f(t_2, w_2) + f(t_1, w_1)]$$

which is equation (3).

If  $i = 4$ , then we will get equation (6) and so on.

If we put  $k = 1$  and  $i = 3$ , then we will get equation (4) and so on.