

## Autonomous Steering Agents

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# Chapter 1

## Intent

- 1- implementing ai using autonomous steering agents
- 2- implementing smart agents using genetics algorithms
- 3- implementing smart agents using neural network

### 1.1 Dependencies

```
$sudo apt-get install libglu1-mesa-dev freeglut3-dev mesa-common-dev
```

```
$sudo apt-get install libboost-all-dev
```

### 1.2 Resources

Jan Schiffmann : Nature of Code

Fernando Bevilacqua : Understanding Steering Behaviors

Jer Thorp : Living in Data

OpenGL :

<https://videotutorialsrock.com/index.php>

<https://www.opengl.org/resources/libraries/glut/spec3/node1.html>

<https://learnopengl.com/Getting-started/Coordinate-Systems>



## Chapter 2

# Todo List

Member `wander::wander ()`

business logic will be changed





## Chapter 3

# Hierarchical Index

### 3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

color . . . . .	19
entity . . . . .	22
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## Chapter 4

# Class Index

### 4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## Chapter 5

# File Index

### 5.1 File List

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<a href="#">include/flee.h</a>	Agents flee from mouse scenario . . . . .	93
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src/pvector.cpp	Pvector class implementation . . . . .	139
src/random.cpp	Utility class for random operations . . . . .	140
src/scenario.cpp	Scenario base class implementation . . . . .	140
src/steeringBehavior.cpp	Implementation of autonomous steering behaviors . . . . .	142
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## Chapter 6

# Class Documentation

### 6.1 agent Class Reference

```
#include <agent.h>
```

#### Public Member Functions

- `agent ()`  
*default constructor.*
- `agent (float x, float y)`  
*constructor.*
- `~agent ()`  
*destructor*
- `void updatePosition (bool arrive)`  
*position update calculations*
- `void setFeatures (float s, float f, float r, float m)`  
*initialize the agent attributes*
- `string getName ()`  
*name attribute getter*
- `void setName (string n)`  
*name attribute setter*
- `float getMass ()`  
*mass attribute getter*
- `void setMass (float m)`  
*mass attribute setter*
- `void draw (graphics view) override`  
*agent drawing*

## Public Attributes

- [point position](#)  
*position of the agent*
- [pvector velocity](#)  
*velocity of the agent*
- [point targetPoint](#)  
*target of the agent*
- float [maxSpeed](#)  
*maximum speed of the agent*
- float [maxForce](#)  
*maximum force of the agent*
- [pvector steering](#)  
*steering force of the apply*
- [pvector force](#)  
*force of the agent*
- [pvector acceleration](#)  
*acceleration of the agent*
- [pvector desiredVelocity](#)  
*desired velocity of the agent*
- float [r](#)  
*radius of the agent*
- int [id](#)  
*id of the agent*
- bool [arrive](#) = false  
*has arriving behavior or not*

### 6.1.1 Detailed Description

Definition at line 21 of file agent.h.

### 6.1.2 Constructor & Destructor Documentation

#### 6.1.2.1 [agent\(\)](#) [1/2]

```
agent::agent ( )
```

default constructor.

See also

[agent\(float x, float y\)](#)

Definition at line 16 of file agent.cpp.

```
17 {  
18  
19 }
```



### 6.1.2.2 agent() [2/2]

```
agent::agent (
    float x,
    float y )
```

constructor.

**Parameters**

<i>x</i>	position x of the agent
<i>y</i>	position y of the agent

**See also**[agent\(\)](#)

Definition at line 37 of file agent.cpp.

```

38 {
39     position      = point(x, y);
40     velocity      = pvector(0.6, 0.0);
41     acceleration  = pvector(0.0, 0.0);
42     steering      = pvector(0.0, 0.0);
43     desiredVelocity = pvector(0.0, 0.0);
44     force         = pvector(0.0, 0.0);
45     targetPoint   = point(0.0, 0.0);
46     entityColor   = RED;
47 }
```

**6.1.2.3 ~agent()**

```
agent::~agent ( )
```

destructor

Definition at line 78 of file agent.cpp.

```

79 {
80
81 }
```

**6.1.3 Member Function Documentation****6.1.3.1 draw()**

```
void agent::draw (
    graphics view ) [override], [virtual]
```

agent drawing

**Parameters**

<i>view</i>	graphics to draw
-------------	------------------

Implements [entity](#).

Definition at line 83 of file agent.cpp.

```

83         {
84     this->updatePosition(this->arrive);
85     view.drawAgent(*this);
86 }

```

### 6.1.3.2 getMass()

```
float agent::getMass ( )
```

mass attribute getter

Definition at line 29 of file agent.cpp.

```

29     {
30     return mass;
31 }

```

### 6.1.3.3 getName()

```
string agent::getName ( )
```

name attribute getter

Definition at line 21 of file agent.cpp.

```

21     {
22     return name;
23 }

```

### 6.1.3.4 setFeatures()

```

void agent::setFeatures (
    float s,
    float f,
    float r,
    float m )

```

initialize the agent attributes

#### Parameters

<i>s</i>	maximum velocity
<i>f</i>	maximum force
<i>r</i>	radius for arriving behavior
<i>m</i>	mass

Definition at line 70 of file agent.cpp.

```

71 {
72     this->maxSpeed = s;
73     this->maxForce = f;

```

```

74     this->r = r;
75     this->mass = m;
76 }

```

### 6.1.3.5 setMass()

```

void agent::setMass (
    float m )

```

mass attribute setter

#### Parameters

<i>m</i>	set value
----------	-----------

Definition at line 33 of file agent.cpp.

```

33     {
34         mass = m;
35     }

```

### 6.1.3.6 setName()

```

void agent::setName (
    string n )

```

name attribute setter

#### Parameters

<i>n</i>	set value
----------	-----------

Definition at line 25 of file agent.cpp.

```

25     {
26         name = n;
27     }

```

### 6.1.3.7 updatePosition()

```

void agent::updatePosition (
    bool arrive )

```

position update calculations

#### Parameters

<i>arrive</i>	has arriving behavior or not
---------------	------------------------------

See also

[agent\(\)](#)

Definition at line 49 of file agent.cpp.

```
50 {  
51     force.limit(maxForce);  
52     acceleration = force;  
53     velocity += acceleration;  
54  
55     //arriving behavior implementation  
56     if(arrive == true){  
57         pvector diff = targetPoint - position;  
58         if(diff.magnitude() > r)  
59             velocity.limit(maxSpeed);  
60         else  
61             velocity.limit(maxSpeed * diff.magnitude() / r);  
62     }  
63     else  
64         velocity.limit(maxSpeed);  
65  
66     position = position + velocity;  
67     force = pvector(0,0);  
68 }
```

## 6.1.4 Member Data Documentation

### 6.1.4.1 acceleration

`pvector agent::acceleration`

acceleration of the agent

Definition at line 124 of file agent.h.

### 6.1.4.2 arrive

`bool agent::arrive = false`

has arriving behavior or not

Definition at line 144 of file agent.h.

### 6.1.4.3 desiredVelocity

`pvector agent::desiredVelocity`

desired velocity of the agent

Definition at line 129 of file agent.h.

#### 6.1.4.4 force

```
pvector agent::force
```

force of the agent

Definition at line 119 of file agent.h.

#### 6.1.4.5 id

```
int agent::id
```

id of the agent

Definition at line 139 of file agent.h.

#### 6.1.4.6 maxForce

```
float agent::maxForce
```

maximum force of the agent

Definition at line 109 of file agent.h.

#### 6.1.4.7 maxSpeed

```
float agent::maxSpeed
```

maximum speed of the agent

Definition at line 104 of file agent.h.

#### 6.1.4.8 position

```
point agent::position
```

position of the agent

Definition at line 89 of file agent.h.

#### 6.1.4.9 r

```
float agent::r
```

radius of the agent

Definition at line 134 of file agent.h.

#### 6.1.4.10 steering

```
pvector agent::steering
```

steering force of the apply

Definition at line 114 of file agent.h.

#### 6.1.4.11 targetPoint

```
point agent::targetPoint
```

target of the agent

Definition at line 99 of file agent.h.

#### 6.1.4.12 velocity

```
pvector agent::velocity
```

velocity of the agent

Definition at line 94 of file agent.h.

The documentation for this class was generated from the following files:

- [include/agent.h](#)
- [src/agent.cpp](#)

## 6.2 color Class Reference

```
#include <color.h>
```

## Public Member Functions

- [color](#) ()  
*default constructor.*
- [color](#) (float r, float g, float b)  
*constructor.*

## Static Public Member Functions

- static [color](#) [getColor](#) (int index)  
*gets colorbar colors*

## Public Attributes

- float [R](#)  
*portion of red color*
- float [G](#)  
*portion of green color*
- float [B](#)  
*portion of blue color*

### 6.2.1 Detailed Description

Definition at line 23 of file color.h.

### 6.2.2 Constructor & Destructor Documentation

#### 6.2.2.1 [color\(\)](#) [1/2]

```
color::color ( )
```

default constructor.

See also

[color\(float r, float g, float b\)](#)

Definition at line 13 of file color.cpp.

```
14 {  
15  
16 }
```

#### 6.2.2.2 [color\(\)](#) [2/2]

```
color::color (  
    float r,  
    float g,  
    float b )
```

constructor.



### Parameters

<i>r</i>	red (0-255)
<i>g</i>	green (0-255)
<i>b</i>	blue (0-255)

### See also

[path\(\)](#)

Definition at line 19 of file color.cpp.

```
20 {  
21     R = r;  
22     G = g;  
23     B = b;  
24 }
```

## 6.2.3 Member Function Documentation

### 6.2.3.1 getColor()

```
color color::getColor (  
    int index ) [static]
```

gets colorbar colors

### Parameters

<i>index</i>	color id
--------------	----------

Definition at line 26 of file color.cpp.

```
26 {  
27     switch (index)  
28     {  
29         case 0: return WHITE; break;  
30         case 1: return BLUE; break;  
31         case 2: return RED; break;  
32         case 3: return YELLOW; break;  
33         case 4: return GREEN; break;  
34         case 5: return BLACK; break;  
35         case 6: return CYAN; break;  
36         case 7: return MAGENDA; break;  
37     }  
38     return RED;  
39 }  
40 }
```

## 6.2.4 Member Data Documentation

#### 6.2.4.1 B

```
float color::B
```

portion of blue color

Definition at line 53 of file color.h.

#### 6.2.4.2 G

```
float color::G
```

portion of green color

Definition at line 48 of file color.h.

#### 6.2.4.3 R

```
float color::R
```

portion of red color

Definition at line 43 of file color.h.

The documentation for this class was generated from the following files:

- include/[color.h](#)
- src/[color.cpp](#)

## 6.3 entity Class Reference

```
#include <entity.h>
```

### Public Member Functions

- [entity](#) ()  
*default constructor.*
- string [getName](#) ()  
*getter of the name*
- void [setName](#) (string name)  
*name attribute setter*
- int [getId](#) ()  
*getter of the id attribute*
- void [setId](#) (int id)  
*id attribute setter*
- virtual void [draw](#) ([graphics](#) view)=0  
*overriden by child classes*

## Public Attributes

- [color](#) `entityColor`  
*color of the entity*

### 6.3.1 Detailed Description

Definition at line 10 of file `entity.h`.

### 6.3.2 Constructor & Destructor Documentation

#### 6.3.2.1 `entity()`

```
entity::entity ( )
```

default constructor.

Definition at line 3 of file `entity.cpp`.

```
3         {  
4     entityColor = RED;  
5 }
```

### 6.3.3 Member Function Documentation

#### 6.3.3.1 `draw()`

```
virtual void entity::draw (  
    graphics view ) [pure virtual]
```

overridden by child classes

Parameters

<code>view</code>	<code>graphics</code>
-------------------	-----------------------

Implemented in [agent](#), [obstacle](#), and [path](#).

#### 6.3.3.2 `getId()`

```
int entity::getId ( )
```

getter of the id attribute

Definition at line 15 of file entity.cpp.

```
15         {  
16         return id;  
17     }
```

### 6.3.3.3 getName()

```
string entity::getName ( )
```

getter of the name

Definition at line 7 of file entity.cpp.

```
7         {  
8         return name;  
9     }
```

### 6.3.3.4 setId()

```
void entity::setId (  
    int id )
```

id attribute setter

#### Parameters

<i>id</i>	setter
-----------	--------

Definition at line 19 of file entity.cpp.

```
19         {  
20         this->id = id;  
21     }
```

### 6.3.3.5 setName()

```
void entity::setName (  
    string name )
```

name attribute setter

#### Parameters

<i>name</i>	setter
-------------	--------

Definition at line 11 of file entity.cpp.

```
11     {
```

```
12     this->name = name;
13 }
```

## 6.3.4 Member Data Documentation

### 6.3.4.1 entityColor

`color` `entity::entityColor`

color of the entity

Definition at line 48 of file `entity.h`.

The documentation for this class was generated from the following files:

- `include/entity.h`
- `src/entity.cpp`

## 6.4 evade Class Reference

```
#include <evade.h>
```

### Public Member Functions

- `evade ()`  
*default constructor.*

### Static Public Member Functions

- static void `loop ()`  
*loop function of evading scenario*

### Additional Inherited Members

#### 6.4.1 Detailed Description

Definition at line 15 of file `evade.h`.

#### 6.4.2 Constructor & Destructor Documentation

### 6.4.2.1 evade()

```
evade::evade ( )
```

default constructor.

Definition at line 31 of file evade.cpp.

```
32 {
33     name = "evading";
34     createAgent(STATIC, nullptr, nullptr, nullptr);
35     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );
36 }
```

## 6.4.3 Member Function Documentation

### 6.4.3.1 loop()

```
void evade::loop ( ) [static]
```

loop function of evading scenario

#### Note

opengl callback forces that function to be static

Definition at line 15 of file evade.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         if((*it).getName() == "lion"){
19             (*it).targetPoint = view.getMousePosition();
20             (*it).force = behavior.seek(*it);
21             (*it).arrive = true;
22         }
23         else{//gazelle
24             (*it).force = behavior.evade(agents, *it, view, "lion");
25         }
26     }
27     refresh();
28 }
29 }
```

The documentation for this class was generated from the following files:

- include/[evade.h](#)
- src/[evade.cpp](#)

## 6.5 flee Class Reference

```
#include <flee.h>
```

### Public Member Functions

- [flee \(\)](#)  
*default constructor.*

## Static Public Member Functions

- static void [loop](#) ()  
*evading scenario loop function*

## Additional Inherited Members

### 6.5.1 Detailed Description

Definition at line 14 of file `flee.h`.

### 6.5.2 Constructor & Destructor Documentation

#### 6.5.2.1 `flee()`

```
flee::flee ( )
```

default constructor.

Definition at line 24 of file `flee.cpp`.

```
25 {  
26     int agentCount = 196;  
27     name = "fleeing troop";  
28     createAgent(TROOP, &agentCount, nullptr, nullptr);  
29     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );  
30 }
```

### 6.5.3 Member Function Documentation

#### 6.5.3.1 `loop()`

```
void flee::loop ( ) [static]
```

evading scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file `flee.cpp`.

```
16 {  
17     for(auto it = agents.begin(); it < agents.end(); it++){  
18         (*it).force = behavior.flee((*it), view, view.getMousePosition());  
19     }  
20  
21     refresh();  
22 }
```

The documentation for this class was generated from the following files:

- `include/flee.h`
- `src/flee.cpp`

## 6.6 flock Class Reference

```
#include <flock.h>
```

### Public Member Functions

- [flock](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*flocking scenario loop function*

### Additional Inherited Members

#### 6.6.1 Detailed Description

Definition at line 15 of file flock.h.

#### 6.6.2 Constructor & Destructor Documentation

##### 6.6.2.1 flock()

```
flock::flock ( )
```

default constructor.

Definition at line 36 of file flock.cpp.

```
37 {  
38     int agentCount = 50;  
39     float maxForce = 0.3;  
40     float maxSpeed = 0.8;  
41     name = "flocking agents";  
42     createAgent(RANDOM, &agentCount, &maxForce, &maxSpeed);  
43     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );  
44 }
```

#### 6.6.3 Member Function Documentation



### 6.6.3.1 loop()

```
void flock::loop ( ) [static]
```

flocking scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file flock.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         view.forceInScreen((*it));
19
20         pvector sep = behavior.separation(agents, *it);
21         sep.mul(1.5);
22         pvector ali = behavior.align(agents, *it);
23         ali.mul(4);
24         pvector coh = behavior.cohesion(agents, *it);
25         coh.mul(0.1);
26
27         (*it).force = sep + ali + coh;
28         (*it).desiredVelocity = (*it).force + (*it).velocity;
29         (*it).targetPoint = (*it).position + (*it).desiredVelocity;
30         (*it).arrive = true;
31     }
32
33     refresh();
34 }
```

The documentation for this class was generated from the following files:

- [include/flock.h](#)
- [src/flock.cpp](#)

## 6.7 flowField Class Reference

```
#include <flowField.h>
```

### Public Member Functions

- [flowField \(\)](#)  
*default constructor.*
- [flowField \(pvector p\)](#)  
*constructor.*
- [pvector getField \(int x, int y\)](#)  
*get force at individual pixel*

### 6.7.1 Detailed Description

Definition at line 18 of file flowField.h.

## 6.7.2 Constructor & Destructor Documentation

### 6.7.2.1 flowField() [1/2]

```
flowField::flowField ( )
```

default constructor.

See also

[flowField\(pvector p\)](#)

Definition at line 15 of file flowField.cpp.

```
16 {  
17  
18 }
```

### 6.7.2.2 flowField() [2/2]

```
flowField::flowField (  
    pvector p )
```

constructor.

Parameters

<i>p</i>	force vector
----------	--------------

See also

[flowField\(\)](#)

Definition at line 10 of file flowField.cpp.

```
11 {  
12     createFlowField(p);  
13 }
```

## 6.7.3 Member Function Documentation

### 6.7.3.1 getField()

```
pvector flowField::getField (  
    int x,  
    int y )
```

get force at individual pixel

## Parameters

<i>x</i>	coordinate
<i>y</i>	coordinate

## Returns

force at specified position

Definition at line 39 of file flowField.cpp.

```
40 {
41     return uniformField[x][y];
42 }
```

The documentation for this class was generated from the following files:

- include/flowField.h
- src/flowField.cpp

## 6.8 graphics Class Reference

```
#include <graphics.h>
```

### Public Member Functions

- void [drawAgent](#) ([agent](#) &[agent](#))  
*drawing with corresponding angle*
- void [drawLine](#) ([point](#) p1, [point](#) p2, [color](#) cl)  
*drawing line*
- void [drawPath](#) ([path](#) &[path](#))  
*draws path*
- void [drawPoint](#) ([point](#) p)  
*draws point*
- void [drawCircle](#) ([point](#) p, float radius, [color](#) color)  
*draws circle*
- void [drawText](#) (string text, [point](#) p)  
*draws text on screen*
- void [forceInScreen](#) ([agent](#) &[agent](#))  
*changes agent position so that it stays in screen*
- void [refreshScene](#) ()  
*update agent position*
- [point](#) [getMousePosition](#) ()  
*gets mouse position*
- void [initGraphics](#) (int \*argv, char \*\*argc, void(\*callback)())  
*initialization of graphics*

## Static Public Member Functions

- static void `timerEvent` (int value)  
*periodic timer event*
- static void `handleKeyPress` (unsigned char key, int x, int y)  
*key press event*
- static void `mouseButton` (int button, int state, int x, int y)  
*mouse press event*
- static void `handleResize` (int w, int h)  
*event triggered with screen resizing*
- static void `mouseMove` (int x, int y)  
*event triggered with mouse movements*

## Static Public Attributes

- static int `target_x` = `-WIDTH`  
*mouse position x*
- static int `target_y` = `HEIGHT`  
*mouse position y*

### 6.8.1 Detailed Description

Definition at line 22 of file `graphics.h`.

### 6.8.2 Member Function Documentation

#### 6.8.2.1 `drawAgent()`

```
void graphics::drawAgent (
    agent & agent )
```

drawing with corresponding angle

#### Parameters

<i>agent</i>	instance to change
--------------	--------------------

Definition at line 159 of file `graphics.cpp`.

```
160 {
161     glPushMatrix();
162     glTranslatef(agent.position.x, agent.position.y, 0.0f);
163     glRotatef(agent.velocity.getAngle(), 0.0f, 0.0f, 1.0f);
164     glBegin(GL_TRIANGLES);
165     glColor3f( agent.entityColor.R, agent.entityColor.G, agent.entityColor.B);
166     glVertex3f( 1.0f, 0.0f, 0.0f);
167     glVertex3f(-1.0f, 0.5f, 0.0f);
168     glVertex3f(-1.0f, -0.5f, 0.0f);
169     glEnd();
170     glPopMatrix();
```

```
171 }
```

### 6.8.2.2 drawCircle()

```
void graphics::drawCircle (
    point p,
    float radius,
    color color )
```

draws circle

#### Parameters

<i>p</i>	center of the circle
<i>radius</i>	radius of the circle
<i>color</i>	of the circle

Definition at line 136 of file graphics.cpp.

```
137 {
138     glColor3f(color.R, color.G, color.B);
139     glBegin(GL_LINE_STRIP);
140     glLineWidth(2);
141     for (int i = 0; i <= 300; i++) {
142         float angle = 2 * PI * i / 300;
143         float x = cos(angle) * radius;
144         float y = sin(angle) * radius;
145         glVertex2d(p.x + x, p.y + y);
146     }
147     glEnd();
148 }
```

### 6.8.2.3 drawLine()

```
void graphics::drawLine (
    point p1,
    point p2,
    color cl )
```

drawing line

#### Parameters

<i>p1</i>	start point of the line
<i>p2</i>	end point of the line
<i>color</i>	of the line

Definition at line 126 of file graphics.cpp.

```
127 {
128     glColor3f( cl.R, cl.G, cl.B);
129     glLineWidth(2);
130     glBegin(GL_LINES);
131     glVertex2f(p1.x, p1.y);
132     glVertex2f(p2.x, p2.y);
```

```

133     glEnd();
134 }

```

#### 6.8.2.4 drawPath()

```

void graphics::drawPath (
    path & path )

```

draws path

##### Parameters

<i>path</i>	to draw
-------------	---------

Definition at line 112 of file graphics.cpp.

```

113 {
114     point p1, p2;
115     for(auto it = path.points.begin(); it < path.points.end()-1; it++){
116         p1 = point((*it).x, (*it).y - path.width/2) ;
117         p2 = point((*it+1).x, (*it+1).y - path.width/2);
118         drawLine(p1, p2, path.entityColor);
119
120         p1 = point((*it).x, (*it).y + path.width/2) ;
121         p2 = point((*it+1).x, (*it+1).y + path.width/2);
122         drawLine(p1, p2, path.entityColor);
123     }
124 }

```

#### 6.8.2.5 drawPoint()

```

void graphics::drawPoint (
    point p )

```

draws point

##### Parameters

<i>p</i>	point to draw
----------	---------------

Definition at line 150 of file graphics.cpp.

```

151 {
152     glColor3f(1,1,1);
153     glPointSize(4.0);
154     glBegin(GL_POINTS);
155     glVertex2f(p.x, p.y);
156     glEnd();
157 }

```

#### 6.8.2.6 drawText()

```

void graphics::drawText (
    string text,
    point p )

```

draws text on screen

#### Parameters

<i>p</i>	position of the text
<i>text</i>	to display

Definition at line 21 of file graphics.cpp.

```

22 {
23     glColor3f (0.0, 0.0, 1.0);
24     glRasterPos2f(p.x, p.y);
25     for ( string::iterator it=text.begin(); it!=text.end(); ++it){
26         glutBitmapCharacter(GLUT_BITMAP_9_BY_15, *it);
27     }
28 }
```

#### 6.8.2.7 forceInScreen()

```

void graphics::forceInScreen (
    agent & agent )
```

changes agent position so that it stays in screen

#### Parameters

<i>agent</i>	instance
--------------	----------

Definition at line 61 of file graphics.cpp.

```

62 {
63     if (agent.position.x > WIDTH)
64         agent.position.x -= 2 * WIDTH;
65     if (agent.position.x < -WIDTH)
66         agent.position.x += 2 * WIDTH;
67     if (agent.position.y > HEIGHT)
68         agent.position.y -= 2 * HEIGHT;
69     if (agent.position.y < -HEIGHT)
70         agent.position.y += 2 * HEIGHT;
71 }
```

#### 6.8.2.8 getMousePosition()

```

point graphics::getMousePosition ( )
```

gets mouse position

#### Returns

mouse point

Definition at line 56 of file graphics.cpp.

```

57 {
58     return point (graphics::target_x, graphics::target_y);
59 }
```

### 6.8.2.9 handleKeypress()

```
void graphics::handleKeypress (
    unsigned char key,
    int x,
    int y ) [static]
```

key press event

#### Parameters

<i>key</i>	pressed
<i>x</i>	unused but required for OpenGL
<i>y</i>	unused but required for OpenGL

Definition at line 105 of file graphics.cpp.

```
106 {
107     if (key == ESC){
108         exit(0);
109     }
110 }
```

### 6.8.2.10 handleResize()

```
void graphics::handleResize (
    int w,
    int h ) [static]
```

event triggered with screen resizing

#### Parameters

<i>w</i>	width of the screen
<i>h</i>	height of the screen

Definition at line 81 of file graphics.cpp.

```
82 {
83     glViewport(0, 0, w, h); //Tell OpenGL how to convert from coordinates to pixel values
84     glMatrixMode(GL_PROJECTION); //Switch to setting the camera perspective
85     glLoadIdentity(); //Reset the camera
86     //Set the camera perspective
87     gluPerspective(45.0, //The camera angle
88                   (double)w / (double)h, //The width-to-height ratio
89                   1.0, //The near z clipping coordinate
90                   200.0); //The far z clipping coordinate
91 }
```

### 6.8.2.11 initGraphics()

```
void graphics::initGraphics (
    int * argv,
```



```
char ** argc,  
void(*)() callback )
```

initialization of graphics

## Parameters

<i>argv</i>	user parameters
<i>argc</i>	count of user parameters
<i>callback</i>	loop function for openGL periodic callback

Definition at line 39 of file graphics.cpp.

```

40 {
41     glutInit(argv, argc);
42     glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGB | GLUT_DEPTH);
43     glutInitWindowSize(400, 400);
44     glutCreateWindow("Autonomous Steering Agents");
45     glClearColor(0.7f, 0.7f, 0.7f, 1.0f); //set background color
46     glEnable(GL_DEPTH_TEST);
47     glutDisplayFunc(*callback);
48     glutMouseFunc(graphics::mouseButton);
49     glutPassiveMotionFunc(graphics::mouseMove);
50     glutKeyboardFunc(graphics::handleKeypress);
51     glutReshapeFunc(graphics::handleResize);
52     glutTimerFunc(20, graphics::timerEvent, 0);
53     glutMainLoop();
54 }
```

### 6.8.2.12 mouseButton()

```

void graphics::mouseButton (
    int button,
    int state,
    int x,
    int y ) [static]
```

mouse press event

## Parameters

<i>button</i>	mouse key pressed
<i>state</i>	down/up etc.
<i>x</i>	unused but required for openGL
<i>y</i>	unused but required for openGL

Definition at line 99 of file graphics.cpp.

```

100 {
101     if (button == GLUT_LEFT_BUTTON && state == GLUT_DOWN){
102     }
103 }
```

### 6.8.2.13 mouseMove()

```

void graphics::mouseMove (
    int x,
    int y ) [static]
```

event triggered with mouse movements

## Parameters

<i>x</i>	osition of the mouse
<i>y</i>	position of the mouse

Definition at line 73 of file graphics.cpp.

```

74 {
75     //TODO: mouse position to glut
76     //TODO: magic numbers
77     graphics::target_x = x / 5.88 - 34;
78     graphics::target_y = 34 - y / 5.88;
79 }
```

### 6.8.2.14 refreshScene()

```
void graphics::refreshScene ( )
```

update agent position

Definition at line 30 of file graphics.cpp.

```

31 {
32     glutSwapBuffers();
33     glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
34     glMatrixMode(GL_MODELVIEW); //Switch to the drawing perspective
35     glLoadIdentity(); //Reset the drawing perspective
36     glTranslatef(0.0f, 0.0f, -85.0f); //Move to the center of the triangle
37 }
```

### 6.8.2.15 timerEvent()

```
void graphics::timerEvent (
    int value ) [static]
```

periodic timer event

## Parameters

<i>value</i>	period as ms
--------------	--------------

Definition at line 93 of file graphics.cpp.

```

94 {
95     glutPostRedisplay(); //Tell GLUT that the display has changed
96     glutTimerFunc(value, timerEvent, 20);
97 }
```

## 6.8.3 Member Data Documentation

### 6.8.3.1 target\_x

```
int graphics::target_x = -WIDTH [static]
```

mouse position x

Definition at line 130 of file graphics.h.

### 6.8.3.2 target\_y

```
int graphics::target_y = HEIGHT [static]
```

mouse position y

Definition at line 135 of file graphics.h.

The documentation for this class was generated from the following files:

- [include/graphics.h](#)
- [src/graphics.cpp](#)

## 6.9 mouseFollower Class Reference

```
#include <mouseFollower.h>
```

### Public Member Functions

- [mouseFollower](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*mouse following scenario loop function*

### Additional Inherited Members

#### 6.9.1 Detailed Description

Definition at line 14 of file mouseFollower.h.

#### 6.9.2 Constructor & Destructor Documentation

### 6.9.2.1 mouseFollower()

```
mouseFollower::mouseFollower ( )
```

default constructor.

Definition at line 25 of file mouseFollower.cpp.

```
26 {
27     int agentCount = 30;
28     float maxForce = 0.3;
29     float maxSpeed = 0.6;
30     name = "mouse following";
31     createAgent(RANDOM, &agentCount, &maxForce, &maxSpeed);
32     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );
33 }
```

## 6.9.3 Member Function Documentation

### 6.9.3.1 loop()

```
void mouseFollower::loop ( ) [static]
```

mouse following scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file mouseFollower.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         (*it).targetPoint = view.getMousePosition();
19         (*it).force = behavior.seek(*it);
20         (*it).arrive = true;
21     }
22     refresh();
23 }
```

The documentation for this class was generated from the following files:

- include/mouseFollower.h
- src/mouseFollower.cpp

## 6.10 obstacle Class Reference

```
#include <obstacle.h>
```

### Public Member Functions

- [obstacle \(\)](#)  
*default constructor.*
- [obstacle \(point p, float r\)](#)  
*constructor*
- void [draw \(graphics view\)](#) override  
*overriden draw implementation*

## Public Attributes

- [point p](#)  
*center point of the obstacle*
- [float r](#)  
*radius of the obstacle*

### 6.10.1 Detailed Description

Definition at line 15 of file obstacle.h.

### 6.10.2 Constructor & Destructor Documentation

#### 6.10.2.1 `obstacle()` [1/2]

```
obstacle::obstacle ( )
```

default constructor.

See also

[obstacle\(point p, float r](#)

Definition at line 16 of file obstacle.cpp.

```
17 {
18     p = point(0,0);
19     r = 5;
20     entityColor = RED;
21 }
```

#### 6.10.2.2 `obstacle()` [2/2]

```
obstacle::obstacle (
    point p,
    float r )
```

constructor

Parameters

<i>p</i>	center of the circular obstacle
<i>r</i>	radius of the obstacle

See also

[obstacle\(point p, float r\);](#)

Definition at line 23 of file obstacle.cpp.

```
24 {  
25     this->p = p;  
26     this->r = r;  
27     entityType = RED;  
28 }
```

## 6.10.3 Member Function Documentation

### 6.10.3.1 draw()

```
void obstacle::draw (  
    graphics view ) [override], [virtual]
```

overridden draw implementation

Implements [entity](#).

Definition at line 30 of file obstacle.cpp.

```
30     {  
31     view.drawCircle(p, r, entityType);  
32 }
```

## 6.10.4 Member Data Documentation

### 6.10.4.1 p

[point](#) obstacle::p

center point of the obstacle

Definition at line 34 of file obstacle.h.

### 6.10.4.2 r

float obstacle::r

radius of the obstacle

Definition at line 39 of file obstacle.h.

The documentation for this class was generated from the following files:

- include/[obstacle.h](#)
- src/[obstacle.cpp](#)

## 6.11 obstacleAvoidance Class Reference

```
#include <obstacleAvoidance.h>
```

### Public Member Functions

- [obstacleAvoidance](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*obstacle avoidance scenario loop function*
- static void [createObstacle](#) (vector< [obstacle](#) > &[obstacles](#))  
*creation of list of obstacles*

### Static Public Attributes

- static vector< [obstacle](#) > [obstacles](#)  
*list of obstacles*

### Additional Inherited Members

#### 6.11.1 Detailed Description

Definition at line 15 of file obstacleAvoidance.h.

#### 6.11.2 Constructor & Destructor Documentation

##### 6.11.2.1 obstacleAvoidance()

```
obstacleAvoidance::obstacleAvoidance ( )
```

default constructor.

Definition at line 42 of file obstacleAvoidance.cpp.

```
43 {
44     name = "avoid obstacles";
45     createAgent(STATIC, nullptr, nullptr, nullptr);
46     createObstacle(obstacles);
47     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );
48 }
```

#### 6.11.3 Member Function Documentation

##### 6.11.3.1 createObstacle()

```
void obstacleAvoidance::createObstacle (
    vector< obstacle > & obstacles ) [static]
```

creation of list of obstacles



## Parameters

<i>obstacles</i>	list to be created
------------------	--------------------

## Note

opengl callback forces that function to be static

Definition at line 35 of file obstacleAvoidance.cpp.

```

36 {
37     obstacles.push_back(obstacle(point(0,0), 8));
38     obstacles.push_back(obstacle(point(-20,0), 3));
39     obstacles.push_back(obstacle(point(20,-10), 4));
40 }
```

## 6.11.3.2 loop()

```
void obstacleAvoidance::loop ( ) [static]
```

obstacle avoidance scenario loop function

## Note

opengl callback forces that function to be static

Definition at line 17 of file obstacleAvoidance.cpp.

```

18 {
19     for(auto it = agents.begin(); it < agents.end(); it++){
20         (*it).targetPoint = view.getMousePosition();
21         pvector seek = behavior.seek(*it);
22         seek.mul(0.5);
23
24         pvector avoid = behavior.avoid(obstacles, *it);
25         (*it).force = avoid + seek;
26         (*it).arrive = true;
27
28         for(auto it = obstacles.begin(); it < obstacles.end(); it++){
29             (*it).draw(view);
30         }
31     }
32     refresh();
33 }
```

## 6.11.4 Member Data Documentation

## 6.11.4.1 obstacles

```
vector< obstacle > obstacleAvoidance::obstacles [static]
```

list of obstacles

## Note

opengl callback forces that function to be static

Definition at line 32 of file obstacleAvoidance.h.

The documentation for this class was generated from the following files:

- include/[obstacleAvoidance.h](#)
- src/[obstacleAvoidance.cpp](#)

## 6.12 path Class Reference

```
#include <path.h>
```

### Public Member Functions

- [path](#) ()  
*default constructor.*
- [path](#) (float [width](#))  
*donstructor.*
- void [addPoint](#) ([point](#) p)  
*adds a new point to the path*
- void [draw](#) ([graphics](#) view)  
*overriden draw implementation*

### Public Attributes

- vector< [point](#) > [points](#)  
*list of points added to the path*
- int [width](#)  
*width of the path*

### 6.12.1 Detailed Description

Definition at line 17 of file path.h.

### 6.12.2 Constructor & Destructor Documentation

#### 6.12.2.1 [path\(\)](#) [1/2]

```
path::path ( )
```

default constructor.

See also

[path\(float width\)](#)

Definition at line 16 of file path.cpp.

```
17 {  
18     entityColor = BLUE;  
19     width = 8;  
20 }
```

#### 6.12.2.2 [path\(\)](#) [2/2]

```
path::path (  
    float width )
```

donstructor.

## Parameters

<i>width</i>	The width of the path.
--------------	------------------------

## See also

[path\(\)](#)

Definition at line 22 of file path.cpp.

```
23 {  
24     this->width = width;  
25     entityColor = BLUE;  
26 }
```

## 6.12.3 Member Function Documentation

### 6.12.3.1 addPoint()

```
void path::addPoint (  
    point p )
```

adds a new point to the path

## Parameters

<i>point</i>	to add to the path
--------------	--------------------

Definition at line 11 of file path.cpp.

```
12 {  
13     points.push_back(p);  
14 }
```

### 6.12.3.2 draw()

```
void path::draw (  
    graphics view ) [virtual]
```

overriden draw implementation

Implements [entity](#).

Definition at line 28 of file path.cpp.

```
28 {  
29     view.drawPath(*this);  
30 }
```

## 6.12.4 Member Data Documentation

### 6.12.4.1 points

```
vector<point> path::points
```

list of points added to the path

Definition at line 41 of file path.h.

### 6.12.4.2 width

```
int path::width
```

width of the path

Definition at line 46 of file path.h.

The documentation for this class was generated from the following files:

- include/path.h
- src/path.cpp

## 6.13 pathFollower Class Reference

```
#include <pathFollower.h>
```

### Public Member Functions

- [pathFollower \(\)](#)  
*default constructor.*

### Static Public Member Functions

- static void [loop \(\)](#)  
*path follower scenario loop function*
- static void [createPath \(path &p\)](#)  
*creates path*

### Static Public Attributes

- static [path myPath](#)  
*path that will be followed*

## Additional Inherited Members

### 6.13.1 Detailed Description

Definition at line 14 of file pathFollower.h.

### 6.13.2 Constructor & Destructor Documentation

#### 6.13.2.1 pathFollower()

```
pathFollower::pathFollower ( )
```

default constructor.

Definition at line 38 of file pathFollower.cpp.

```
39 {
40     int agentCount = 40;
41     float maxForce = 0.2;
42     float maxSpeed = 0.4;
43     myPath = path(8);
44     createPath(myPath);
45     name = "path following";
46     createAgent(RANDOM, &agentCount, &maxForce, &maxSpeed);
47     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );
48 }
```

### 6.13.3 Member Function Documentation

#### 6.13.3.1 createPath()

```
void pathFollower::createPath (
    path & p ) [static]
```

creates path

##### Parameters

<i>path</i>	to create
-------------	-----------

##### Note

opengl callback forces that function to be static

Definition at line 30 of file pathFollower.cpp.

```
31 {
32     p.addPoint(point(-40, 5));
33     p.addPoint(point(-14, 15));
```

```

34     p.addPoint(point( 10, 7));
35     p.addPoint(point( 40, 12));
36 }

```

### 6.13.3.2 loop()

```
void pathFollower::loop ( ) [static]
```

path follower scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 17 of file pathFollower.cpp.

```

18 {
19     for(auto it = agents.begin(); it < agents.end(); it++){
20         pvector flwpth = behavior.stayInPath(*it, myPath, view);
21         pvector sep = behavior.separation(agents, *it);
22         sep.mul(5);
23         (*it).force = sep + flwpth;
24     }
25     myPath.draw(view);
26 }
27 refresh();
28 }

```

## 6.13.4 Member Data Documentation

### 6.13.4.1 myPath

```
path pathFollower::myPath [static]
```

path that will be followed

#### Note

opengl callback forces that function to be static

Definition at line 38 of file pathFollower.h.

The documentation for this class was generated from the following files:

- include/pathFollower.h
- src/pathFollower.cpp

## 6.14 point Class Reference

```
#include <point.h>
```

## Public Member Functions

- [point](#) ()  
*default constructor*
- [point](#) (float [x](#), float [y](#))  
*constructor*
- void [div](#) (float [d](#))  
*divide point*
- void [mul](#) (float [d](#))  
*multiply point*
- void [print](#) (const string &[s](#))  
*debug function*
- void [getNormalPoint](#) ([point](#) [predicted](#), [point](#) [start](#), [point](#) [end](#))  
*provides normal point on a vector of a point*
- [point operator+](#) ([pvector](#) const &[obj](#))  
*overloaded + operator*
- [point operator+](#) ([point](#) const &[obj](#))  
*overloaded + operator*
- [pvector operator-](#) ([point](#) const &[obj](#))  
*overloaded - operator*
- bool [operator==](#) ([point](#) const &[obj](#))  
*overloaded == operator*

## Public Attributes

- float [x](#)  
*x position*
- float [y](#)  
*y position*

### 6.14.1 Detailed Description

Definition at line 15 of file [point.h](#).

### 6.14.2 Constructor & Destructor Documentation

#### 6.14.2.1 [point\(\)](#) [1/2]

```
point::point ( )
```

default constructor

See also

[point\(float x, float y\)](#)

Definition at line 21 of file [point.cpp](#).

```
22 {  
23     x = 0;  
24     y = 0;  
25 }
```

### 6.14.2.2 point() [2/2]

```
point::point (
    float x,
    float y )
```

constructor

#### Parameters

<i>x</i>	position x of the point
<i>y</i>	position y of the point

See also

[point\(\)](#)

Definition at line 15 of file point.cpp.

```
16 {
17     this->x = x;
18     this->y = y;
19 }
```

## 6.14.3 Member Function Documentation

### 6.14.3.1 div()

```
void point::div (
    float d )
```

divide point

#### Parameters

<i>d</i>	scalar to divide position of the point
----------	--

Definition at line 42 of file point.cpp.

```
43 {
44     x = x / d;
45     y = y / d;
46 }
```

### 6.14.3.2 getNormalPoint()

```
void point::getNormalPoint (
    point predicted,
```



```

    point start,
    point end )

```

provides normal point on a vector of a point

#### Parameters

<i>predicted</i>	point that caller require normal on the vector
<i>start</i>	point of the vector
<i>end</i>	point of the vector

Definition at line 71 of file point.cpp.

```

72 {
73     pvector a = predicted - start;
74     pvector b = end - start;
75     b.normalize();
76     float a_dot_b = a.dotProduct(b);
77     b.mul(a_dot_b);
78     point normalPoint = start + b;
79     this->x = normalPoint.x;
80     this->y = normalPoint.y;
81 }

```

#### 6.14.3.3 mul()

```

void point::mul (
    float d )

```

multiply point

#### Parameters

<i>d</i>	scalar to multiply position of the point
----------	--

Definition at line 48 of file point.cpp.

```

49 {
50     x = x * d;
51     y = y * d;
52 }

```

#### 6.14.3.4 operator+() [1/2]

```

point point::operator+ (
    point const & obj )

```

overloaded + operator

#### Parameters

<i>obj</i>	point to add
------------	--------------

**Returns**

sum

Definition at line 55 of file point.cpp.

```
56 {  
57     point res;  
58     res.x = x + obj.x;  
59     res.y = y + obj.y;  
60     return res;  
61 }
```

**6.14.3.5 operator+() [2/2]**

```
point point::operator+ (  
    pvector const & obj )
```

overloaded + operator

**Parameters**

<i>obj</i>	vector to add
------------	---------------

**Returns**

sum

Definition at line 27 of file point.cpp.

```
28 {  
29     point res;  
30     res.x = x + obj.x;  
31     res.y = y + obj.y;  
32     return res;  
33 }
```

**6.14.3.6 operator-()**

```
pvector point::operator- (  
    point const & obj )
```

overloaded - operator

**Parameters**

<i>obj</i>	point to subtract
------------	-------------------

**Returns**

difference

Definition at line 63 of file point.cpp.

```

64 {
65     pvector res;
66     res.x = x - obj.x;
67     res.y = y - obj.y;
68     return res;
69 }

```

### 6.14.3.7 operator==()

```

bool point::operator== (
    point const & obj )

```

overloaded == operator

#### Parameters

<i>obj</i>	point to compare
------------	------------------

#### Returns

comparison result

Definition at line 35 of file point.cpp.

```

36 {
37     if(x == obj.x && y == obj.y)
38         return true;
39     return false;
40 }

```

### 6.14.3.8 print()

```

void point::print (
    const string & s )

```

debug function

#### Parameters

<i>s</i>	explanation string of the log
----------	-------------------------------

Definition at line 83 of file point.cpp.

```

84 {
85     cout << " " << s << " " << x << " " << y << endl;
86 }

```

## 6.14.4 Member Data Documentation

#### 6.14.4.1 x

```
float point::x
```

x position

Definition at line 88 of file point.h.

#### 6.14.4.2 y

```
float point::y
```

y position

Definition at line 93 of file point.h.

The documentation for this class was generated from the following files:

- [include/point.h](#)
- [src/point.cpp](#)

## 6.15 prison Class Reference

```
#include <prison.h>
```

### Public Member Functions

- [prison](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*prisoning scenario loop function*

### Additional Inherited Members

#### 6.15.1 Detailed Description

Definition at line 15 of file prison.h.

#### 6.15.2 Constructor & Destructor Documentation

### 6.15.2.1 prison()

```
prison::prison ( )
```

default constructor.

Definition at line 31 of file prison.cpp.

```
32 {
33     int agentCount = 30;
34     float maxForce = 0.6;
35     float maxSpeed = 0.6;
36
37     name = "stay in prison";
38     createAgent(RANDOM, &agentCount, &maxForce, &maxSpeed);
39     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );
40 }
```

## 6.15.3 Member Function Documentation

### 6.15.3.1 loop()

```
void prison::loop ( ) [static]
```

prisoning scenario loop function

prison loop function

#### Note

opengl callback forces that function to be static

Definition at line 18 of file prison.cpp.

```
19 {
20     for(auto it = agents.begin(); it < agents.end(); it++){
21         view.drawLine(point(-WALL, WALL), point(WALL, WALL), BLUE);
22         view.drawLine(point(WALL, WALL), point(WALL, -WALL), BLUE);
23         view.drawLine(point(WALL, -WALL), point(-WALL, -WALL), BLUE);
24         view.drawLine(point(-WALL, WALL), point(-WALL, -WALL), BLUE);
25         (*it).force = behavior.stayInArea(*it, WALL - DISTANCE);
26         (*it).force += behavior.separation(agents, *it);
27     }
28     refresh();
29 }
```

The documentation for this class was generated from the following files:

- include/prison.h
- src/prison.cpp

## 6.16 pursuit Class Reference

```
#include <pursuit.h>
```

## Public Member Functions

- [pursuit\(\)](#)

*default constructor.*

## Static Public Member Functions

- static void [loop\(\)](#)

*pursuing scenario loop function*

## Additional Inherited Members

### 6.16.1 Detailed Description

Definition at line 14 of file pursuit.h.

### 6.16.2 Constructor & Destructor Documentation

#### 6.16.2.1 pursuit()

```
pursuit::pursuit ( )
```

default constructor.

Definition at line 31 of file pursuit.cpp.

```
32 {  
33     name = "pursuit";  
34     createAgent(STATIC, nullptr, nullptr, nullptr);  
35     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );  
36 }
```

### 6.16.3 Member Function Documentation

### 6.16.3.1 loop()

```
void pursuit::loop ( ) [static]
```

pursuing scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file pursuit.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         if((*it).getName() == "gazelle"){
19             (*it).targetPoint = view.getMousePosition();
20             (*it).force = behavior.seek(*it);
21         }
22         else{//lion
23             (*it).force = behavior.pursuit(agents, *it, view, "gazelle");
24         }
25         (*it).arrive = true;
26     }
27     refresh();
28 }
29 }
```

The documentation for this class was generated from the following files:

- include/pursuit.h
- src/pursuit.cpp

## 6.17 pvector Class Reference

```
#include <pvector.h>
```

### Public Member Functions

- [pvector \(\)](#)  
*default constructor*
- [pvector \(float x, float y\)](#)  
*constructor*
- float [magnitude \(\)](#)  
*calculates magnitude of the vector*
- [pvector & normalize \(\)](#)  
*normalize*
- void [div \(float i\)](#)  
*vector division*
- void [mul \(float i\)](#)  
*vector multiplication*
- void [add \(pvector p\)](#)  
*addition of vectors*
- void [limit \(float limit\)](#)  
*vector limitation*
- float [getAngle \(\)](#)

- calculates vector angle*
- float `dotProduct` (`pvector` v)  
*dot product of two vectors*
- float `angleBetween` (`pvector` v)  
*angle calculation between two vectors*
- void `print` (const string &s)  
*debug function*
- `pvector operator+=` (`pvector` const &obj)  
*overloaded += operator*
- `pvector operator+` (`pvector` const &obj)  
*overloaded + operator*
- `pvector operator-` (`pvector` const &obj)  
*overloaded - operator*
- `pvector operator-` (`point` const &obj)  
*overloaded - operator*
- `pvector operator+` (`point` const &obj)  
*overloaded + operator*
- bool `operator==` (`pvector` const &obj)  
*overloaded == operator*

## Public Attributes

- float `x`  
*x magnitude of the vector*
- float `y`  
*y magnitude of the vector*

### 6.17.1 Detailed Description

Definition at line 17 of file `pvector.h`.

### 6.17.2 Constructor & Destructor Documentation

#### 6.17.2.1 `pvector()` [1/2]

```
pvector::pvector ( )
```

default constructor

See also

`pvector(float x, float y)`

Definition at line 35 of file `pvector.cpp`.

```
36 {
37     x = 0;
38     y = 0;
39 }
```



### 6.17.2.2 pvector() [2/2]

```
pvector::pvector (
    float x,
    float y )
```

constructor

Parameters

<i>x</i>	magnitude of the vector
<i>y</i>	magnitude of the vector

See also

[pvector\(\)](#)

Definition at line 41 of file pvector.cpp.

```
42 {
43     this->x = x;
44     this->y = y;
45 }
```

## 6.17.3 Member Function Documentation

### 6.17.3.1 add()

```
void pvector::add (
    pvector p )
```

addition of vectors

Parameters

<i>p</i>	vector to add
----------	---------------

Definition at line 59 of file pvector.cpp.

```
60 {
61     x = x + p.x;
62     y = y + p.y;
63 }
```

### 6.17.3.2 angleBetween()

```
float pvector::angleBetween (
    pvector v )
```

angle calculation between two vectors

**Parameters**

<i>v</i>	vector to calculate angle
----------	---------------------------

**Returns**

angle

Definition at line 23 of file pvector.cpp.

```
24 {  
25     float angle = this->dotProduct(v) / (this->magnitude() * v.magnitude());  
26     angle = acos(angle) * 180 / PI;  
27     return angle;  
28 }
```

**6.17.3.3 div()**

```
void pvector::div (  
    float i )
```

vector division

**Parameters**

<i>i</i>	scalar value to divide
----------	------------------------

Definition at line 47 of file pvector.cpp.

```
48 {  
49     x = x / i;  
50     y = y / i;  
51 }
```

**6.17.3.4 dotProduct()**

```
float pvector::dotProduct (  
    pvector v )
```

dot product of two vectors

**Parameters**

<i>v</i>	vector to calculate dot product
----------	---------------------------------

**Returns**

returns scalar dot product

Definition at line 30 of file pvector.cpp.

```

31 {
32     return ((x * v.x) + (y * v.y));
33 }

```

### 6.17.3.5 getAngle()

```
float pvector::getAngle ( )
```

calculates vector angle

#### Returns

angle

Definition at line 16 of file pvector.cpp.

```

17 {
18     float angle;
19     angle = atan2 (this->y, this->x) * 180 / PI;
20     return angle;
21 }

```

### 6.17.3.6 limit()

```
void pvector::limit (
    float limit )
```

vector limitation

#### Parameters

<i>limit</i>	value to restrict vector magnitude
--------------	------------------------------------

Definition at line 84 of file pvector.cpp.

```

85 {
86     this->normalize();
87     this->mul(limit);
88 }

```

### 6.17.3.7 magnitude()

```
float pvector::magnitude ( )
```

calculates magnitude of the vector

#### Returns

magnitude of the vector

Definition at line 65 of file pvector.cpp.

```

66 {
67     return sqrt((this->x * this->x) + (this->y * this->y));
68 }

```

### 6.17.3.8 mul()

```
void pvector::mul (
    float i )
```

vector multiplication

#### Parameters

<i>i</i>	scalar value to multiply
----------	--------------------------

Definition at line 53 of file pvector.cpp.

```
54 {
55     x = x * i;
56     y = y * i;
57 }
```

### 6.17.3.9 normalize()

```
pvector & pvector::normalize ( )
```

normalize

#### Returns

normalized vector

Definition at line 70 of file pvector.cpp.

```
71 {
72     float magnitude = this->magnitude();
73     if(magnitude != 0){
74         this->x = this->x / magnitude;
75         this->y = this->y / magnitude;
76     }
77     else{
78         this->x = 0;
79         this->y = 0;
80     }
81     return *this;
82 }
```

### 6.17.3.10 operator+() [1/2]

```
pvector pvector::operator+ (
    point const & obj )
```

overloaded + operator

#### Parameters

<i>obj</i>	point to add
------------	--------------

**Returns**

sum

Definition at line 112 of file pvector.cpp.

```
113 {  
114     pvector res;  
115     res.x = x + obj.x;  
116     res.y = y + obj.y;  
117     return res;  
118 }
```

**6.17.3.11 operator+() [2/2]**

```
pvector pvector::operator+ (  
    pvector const & obj )
```

overloaded + operator

**Parameters**

<i>obj</i>	vector to add
------------	---------------

**Returns**

sum

Definition at line 90 of file pvector.cpp.

```
91 {  
92     pvector res;  
93     res.x = x + obj.x;  
94     res.y = y + obj.y;  
95     return res;  
96 }
```

**6.17.3.12 operator+=()**

```
pvector pvector::operator+= (  
    pvector const & obj )
```

overloaded += operator

**Parameters**

<i>obj</i>	vector to add
------------	---------------

**Returns**

sum

Definition at line 98 of file pvector.cpp.

```
99 {  
100     x = x + obj.x;  
101     y = y + obj.y;  
102     return *this;  
103 }
```

### 6.17.3.13 operator-() [1/2]

```
pvector pvector::operator- (  
    point const & obj )
```

overloaded - operator

#### Parameters

<i>obj</i>	point to subtract
------------	-------------------

#### Returns

difference

Definition at line 120 of file pvector.cpp.

```
121 {  
122     pvector res;  
123     res.x = x - obj.x;  
124     res.y = y - obj.y;  
125     return res;  
126 }
```

### 6.17.3.14 operator-() [2/2]

```
pvector pvector::operator- (  
    pvector const & obj )
```

overloaded - operator

#### Parameters

<i>obj</i>	vector to subtract
------------	--------------------

#### Returns

difference

Definition at line 133 of file pvector.cpp.

```
134 {  
135     pvector res;  
136     res.x = x - obj.x;  
137     res.y = y - obj.y;  
138     return res;  
139 }
```

### 6.17.3.15 operator==()

```
bool pvector::operator== (
    pvector const & obj )
```

overloaded == operator

#### Parameters

<i>obj</i>	vector to check if equal
------------	--------------------------

#### Returns

comparison result

Definition at line 105 of file pvector.cpp.

```
106 {
107     if (x == obj.x && y == obj.y)
108         return true;
109     return false;
110 }
```

### 6.17.3.16 print()

```
void pvector::print (
    const string & s )
```

debug function

#### Parameters

<i>s</i>	identification text
----------	---------------------

Definition at line 128 of file pvector.cpp.

```
129 {
130     cout << s << " " << x << " " << y << endl;
131 }
```

## 6.17.4 Member Data Documentation

### 6.17.4.1 x

```
float pvector::x
```

x magnitude of the vector

Definition at line 140 of file pvector.h.

#### 6.17.4.2 y

```
float pvector::y
```

y magnitude of the vector

Definition at line 145 of file pvector.h.

The documentation for this class was generated from the following files:

- [include/pvector.h](#)
- [src/pvector.cpp](#)

## 6.18 random Class Reference

```
#include <random.h>
```

### Static Public Member Functions

- static void [createRandomArray](#) (int \*arr, int size)  
*random array generation*

#### 6.18.1 Detailed Description

Definition at line 9 of file random.h.

#### 6.18.2 Member Function Documentation

##### 6.18.2.1 createRandomArray()

```
void random::createRandomArray (  
    int * arr,  
    int size ) [static]
```

random array generation

##### Parameters

<i>arr</i>	struct that includes random values
<i>size</i>	of the array

Definition at line 14 of file random.cpp.



```

14                                     {
15     srand(time(NULL));
16     for(int i=0; i<size; i++)
17         arr[i] = i+1;
18
19     for (int i=0; i < size; i++){
20         int r = rand() % size;
21         swap(arr[i], arr[r]);
22     }
23 }

```

The documentation for this class was generated from the following files:

- include/[random.h](#)
- src/[random.cpp](#)

## 6.19 scenario Class Reference

```
#include <scenario.h>
```

### Public Member Functions

- [scenario](#) ()  
*default constructor.*
- void [createAgent](#) (int type, int \*count, float \*force, float \*speed)  
*agent creation*
- void [initGL](#) (int \*argv, char \*\*argc)  
*graphics initialization*

### Static Public Member Functions

- static void [refresh](#) ()  
*refreshes all items*

### Public Attributes

- void(\* [callback](#) )()  
*openGL screen refresh callback function, used as main loop in derived classes*

### Static Public Attributes

- static vector< [agent](#) > [agents](#)  
*structure stores agents*
- static [graphics view](#)  
*graphics instance used*
- static [steeringBehavior](#) [behavior](#)  
*behavior instance used*
- static string [name](#)  
*scenario name*

### 6.19.1 Detailed Description

Definition at line 19 of file scenario.h.

### 6.19.2 Constructor & Destructor Documentation

#### 6.19.2.1 scenario()

```
scenario::scenario ( )
```

default constructor.

Definition at line 27 of file scenario.cpp.

```
28 {
29     view = graphics();
30 }
```

### 6.19.3 Member Function Documentation

#### 6.19.3.1 createAgent()

```
void scenario::createAgent (
    int type,
    int * count,
    float * force,
    float * speed )
```

agent creation

##### Parameters

<i>type</i>	type of creation method
<i>count</i>	number of agents to be created
<i>force</i>	max force of agents to be created
<i>speed</i>	max speed of agents to be created

Definition at line 107 of file scenario.cpp.

```
108 {
109     if(type == TROOP){
110         createTroop(*count);
111     }
112     else if(type == RANDOM){
113         createRandomAgents(*count, *force, *speed);
114     }
115     else if(type == STATIC){
116         createStaticAgents();
117     }
118     else{
```

```
119         //error message
120     }
121 }
```

### 6.19.3.2 initGL()

```
void scenario::initGL (
    int * argv,
    char ** argc )
```

graphics initialization

#### Parameters

<i>argv</i>	list of user arguments
<i>argc</i>	number of user arguments

Definition at line 22 of file scenario.cpp.

```
23 {
24     view.initGraphics(argc, argv, callback);
25 }
```

### 6.19.3.3 refresh()

```
void scenario::refresh ( ) [static]
```

refreshes all items

#### Note

opengl callback forces that function to be static

Definition at line 32 of file scenario.cpp.

```
33 {
34     point textPosition = point(-34, 32.25);
35
36     for(auto it = agents.begin(); it < agents.end(); it++){
37         (*it).draw(view);
38     }
39
40     view.drawText(name, textPosition);
41     view.refreshScene();
42 }
```

## 6.19.4 Member Data Documentation

#### 6.19.4.1 agents

```
vector< agent > scenario::agents [static]
```

structure stores agents

##### Note

opengl callback forces that function to be static

Definition at line 52 of file scenario.h.

#### 6.19.4.2 behavior

```
steeringBehavior scenario::behavior [static]
```

behavior instance used

##### Note

opengl callback forces that function to be static

Definition at line 64 of file scenario.h.

#### 6.19.4.3 callback

```
void(* scenario::callback) ()
```

OpenGL screen refresh callback function, used as main loop in derived classes

Definition at line 75 of file scenario.h.

#### 6.19.4.4 name

```
string scenario::name [static]
```

scenario name

##### Note

opengl callback forces that function to be static

Definition at line 70 of file scenario.h.

## 6.19.4.5 view

```
graphics scenario::view [static]
```

graphics instance used

## Note

opengl callback forces that function to be static

Definition at line 58 of file scenario.h.

The documentation for this class was generated from the following files:

- include/scenario.h
- src/scenario.cpp

## 6.20 steeringBehavior Class Reference

```
#include <steeringBehavior.h>
```

## Public Member Functions

- [pvector stayInArea](#) ([agent](#) &[agent](#), int turnPoint)  
*gets reflection force*
- [pvector inFlowField](#) ([agent](#) &[agent](#), [flowField](#) &flow)  
*gets flow field force*
- [pvector stayInPath](#) ([agent](#) &[agent](#), [path](#) &[path](#), [graphics](#) view)  
*gets force to follow path*
- [pvector seek](#) ([agent](#) &[agent](#))  
*force to seek*
- [pvector separation](#) (vector< [agent](#) > agents, [agent](#) &[agent](#))  
*force to separate*
- [pvector cohesion](#) (vector< [agent](#) > boids, [agent](#) &[agent](#))  
*force to cohesion*
- [pvector align](#) (vector< [agent](#) > boids, [agent](#) &[agent](#))  
*force to align*
- [pvector wander](#) ([agent](#) &[agent](#))  
*force to wander*
- [pvector pursuit](#) (vector< [agent](#) > boids, [agent](#) &pursuer, [graphics](#) view, string name)  
*force to pursue*
- [pvector evade](#) (vector< [agent](#) > boids, [agent](#) &evader, [graphics](#) view, string name)  
*force to evade*
- [pvector flee](#) ([agent](#) &[agent](#), [graphics](#) &view, [point](#) p)  
*force to flee*
- [pvector avoid](#) (vector< [obstacle](#) > obstacles, [agent](#) &[agent](#))  
*force to avoid*
- void [setAngle](#) ([pvector](#) &p, float angle)  
*applies angle on vector*

### 6.20.1 Detailed Description

Definition at line 35 of file steeringBehavior.h.

### 6.20.2 Member Function Documentation

#### 6.20.2.1 align()

```
pvector steeringBehavior::align (
    vector< agent > boids,
    agent & agent )
```

force to align

##### Parameters

<i>agent</i>	to be aligned
<i>boids</i>	list of all the agents

##### Returns

force to be applied

Definition at line 119 of file steeringBehavior.cpp.

```
120 {
121     float neighborDist = 30;
122     pvector sum {0,0};
123     int count = 0;
124     for(auto it = boids.begin(); it < boids.end(); it++){
125         float d = (agent.position - (*it).position).magnitude();
126         if( (d > 0) && (d < neighborDist) ){
127             sum += (*it).velocity;
128             count++;
129         }
130     }
131     if(count > 0){
132         sum.div(count);
133         sum.normalize().mul(agent.maxSpeed);
134         agent.steering = sum - agent.velocity;
135         return agent.steering;
136     }
137     return pvector(0,0);
138 }
```

#### 6.20.2.2 avoid()

```
pvector steeringBehavior::avoid (
    vector< obstacle > obstacles,
    agent & agent )
```

force to avoid

## Parameters

<i>agent</i>	agent that will avoid from obstacles
<i>obstacles</i>	list of all existing objects

## Returns

force to be applied

Definition at line 183 of file steeringBehavior.cpp.

```

184 {
185     float dynamic_length = agent.velocity.magnitude() / agent.maxSpeed;
186     pvector vel = agent.velocity;
187     vel.normalize().mul(dynamic_length);
188     pvector ahead = vel + agent.position;
189     vel.mul(6);
190     pvector ahead2 = vel + agent.position;
191     //view.drawPoint(point(ahead.x, ahead.y));
192     //view.drawPoint(point(ahead2.x, ahead2.y));
193
194     for(auto it = obstacles.begin(); it < obstacles.end(); it++){
195         float dist = (ahead - (*it).p).magnitude();
196         float dist2 = (ahead2 - (*it).p).magnitude();
197         if(dist < (*it).r + 2 || dist2 < (*it).r + 2){
198             pvector avoidance = ahead - (*it).p;
199             avoidance.normalize().mul(20);
200             /*a = point(avoidance.x, avoidance.y);
201             view.drawLine(agent.position, agent.position + a, color(0,1,0));*/
202             return avoidance;
203         }
204     }
205     return pvector(0,0);
206 }
```

## 6.20.2.3 cohesion()

```

pvector steeringBehavior::cohesion (
    vector< agent > boids,
    agent & agent )
```

force to cohesion

## Parameters

<i>agent</i>	to go to center of other agents, with specified distance
<i>boids</i>	list of all the agents

## Returns

force to be applied

Definition at line 140 of file steeringBehavior.cpp.

```

141 {
142     float neighborDist = 20;
143     point sum {0,0};
144     int count = 0;
145     for(auto it = boids.begin(); it < boids.end(); it++){
146         float d = (agent.position - (*it).position).magnitude();
147         if( (d > 0) && (d < neighborDist) ){
```

```

148         sum = sum + (*it).position;
149         count++;
150     }
151 }
152 if(count>0){
153     sum.div(count);
154     agent.targetPoint = sum;
155     return seek(agent);
156 }
157 return pvector(0,0);
158 }

```

#### 6.20.2.4 evade()

```

pvector steeringBehavior::evade (
    vector< agent > boids,
    agent & evader,
    graphics view,
    string name )

```

force to evade

##### Parameters

<i>evader</i>	agent that will escape
<i>view</i>	used for debugging
<i>boids</i>	list of all the agents
<i>name</i>	other agent to evade

##### Returns

force to be applied

Definition at line 47 of file steeringBehavior.cpp.

```

48 {
49     agent target;
50     for(auto it = boids.begin(); it < boids.end(); it++){
51         if((*it).getName() == name){
52             target = *it;
53         }
54     }
55
56     point p = point(evader.position.x + 2, evader.position.y - 2);
57     view.drawText(evader.getName(), p);
58     p = point(target.position.x + 2, target.position.y - 2);
59     view.drawText(target.getName(), p);
60
61     pvector targetVel = target.velocity;
62     targetVel.mul(5); //TODO: magic number
63
64     point futurePos = target.position + targetVel;
65     view.drawPoint(futurePos);
66
67     pvector dist = evader.position - futurePos;
68     dist.normalize().mul( 1 / dist.magnitude() );
69
70     evader.targetPoint = evader.position + dist;
71     return flee(evader, view, futurePos);
72 }

```



### 6.20.2.5 flee()

```
pvector steeringBehavior::flee (
    agent & agent,
    graphics & view,
    point p )
```

force to flee

#### Parameters

<i>agent</i>	agent that will flee
<i>view</i>	used for debugging
<i>p</i>	point that agent flees

#### Returns

force to be applied

Definition at line 28 of file steeringBehavior.cpp.

```
29 {
30     int radius = 15;
31
32     pvector dist = agent.targetPoint - p;
33     view.drawPoint(agent.targetPoint);
34
35     if(dist.magnitude() < radius){
36         agent.arrive = false;
37         agent.desiredVelocity = agent.position - p;
38     }
39     else{
40         agent.arrive = true;
41         agent.desiredVelocity = agent.targetPoint - agent.position;
42     }
43     agent.steering = agent.desiredVelocity - agent.velocity;
44     return agent.steering;
45 }
```

### 6.20.2.6 inFlowField()

```
pvector steeringBehavior::inFlowField (
    agent & agent,
    flowField & flow )
```

gets flow field force

#### Parameters

<i>agent</i>	unit to apply flow field
<i>flow</i>	field

#### Returns

force to be applied

Definition at line 238 of file steeringBehavior.cpp.

```

239 {
240     //pos_x, pos_y must be non negative integer
241     int pos_x = abs((int)agent.position.x) % WIDTH;
242     int pos_y = abs((int)agent.position.y) % HEIGHT;
243     //TODO: modification required for non uniform fields
244     return flow.getField(pos_x, pos_y);
245 }

```

### 6.20.2.7 pursuit()

```

pvector steeringBehavior::pursuit (
    vector< agent > boids,
    agent & pursuer,
    graphics view,
    string name )

```

force to pursue

#### Parameters

<i>pursuer</i>	agent that will follow specified agent
<i>view</i>	used for debugging
<i>boids</i>	list of all the agents
<i>name</i>	other agent to pursue

#### Returns

force to be applied

Definition at line 74 of file steeringBehavior.cpp.

```

75 {
76     agent target;
77     for(auto it = boids.begin(); it < boids.end(); it++){
78         if((*it).getName() == name){
79             target = *it;
80         }
81     }
82
83     point p = point(target.position.x + 2, target.position.y - 2);
84     view.drawText(target.getName(), p);
85     p = point(pursuer.position.x + 2, pursuer.position.y - 2);
86     view.drawText(pursuer.getName(), p);
87
88     float dist = (target.position - pursuer.position).magnitude();
89     float t = dist / target.maxSpeed;
90
91     pvector targetVel = target.velocity;
92     targetVel.mul(t);
93     point futurePos = target.position + targetVel;
94     pursuer.targetPoint = futurePos;
95     return seek(pursuer);
96 }

```

### 6.20.2.8 seek()

```

pvector steeringBehavior::seek (
    agent & agent )

```

force to seek

## Parameters

<i>agent</i>	that will go to specific target point
--------------	---------------------------------------

## Returns

force to be applied

Definition at line 208 of file steeringBehavior.cpp.

```

209 {
210     agent.desiredVelocity = agent.targetPoint - agent.position;
211     agent.steering = agent.desiredVelocity - agent.velocity;
212     return agent.steering;
213 }
```

## 6.20.2.9 separation()

```

pvector steeringBehavior::separation (
    vector< agent > agents,
    agent & agent )
```

force to separate

## Parameters

<i>agent</i>	agent that will be stayed away
<i>agents</i>	list of all the agents

## Returns

force to be applied

Definition at line 160 of file steeringBehavior.cpp.

```

161 {
162     float desiredSeparation = 5;
163     pvector sum = pvector(0,0);
164     int count = 0;
165     for(auto it = agents.begin(); it < agents.end(); it++){
166         float d = (agent.position - (*it).position).magnitude();
167         if( (d > 0) && (d < desiredSeparation) ){
168             pvector diff = agent.position - (*it).position;
169             diff.normalize().div(d);
170             sum = sum + diff;
171             count++;
172         }
173     }
174     if(count > 0){
175         sum.div(count);
176         sum.normalize().mul(agent.maxSpeed);
177         agent.steering = sum - agent.velocity;
178         return agent.steering;
179     }
180     return pvector(0,0);
181 }
```

### 6.20.2.10 setAngle()

```
void steeringBehavior::setAngle (
    pvector & p,
    float angle )
```

applies angle on vector

#### Parameters

<i>angle</i>	that will be set
<i>p</i>	vector that angle will be applied

Definition at line 22 of file steeringBehavior.cpp.

```
23 {
24     p.x = cos ( angle * PI / 180.0 );
25     p.y = sin ( angle * PI / 180.0 );
26 }
```

### 6.20.2.11 stayInArea()

```
pvector steeringBehavior::stayInArea (
    agent & agent,
    int turnPoint )
```

gets reflection force

#### Parameters

<i>agent</i>	unit to check
<i>turnpoint</i>	defines border to apply force

#### Returns

force to be applied

Definition at line 247 of file steeringBehavior.cpp.

```
248 {
249     if(agent.position.x >= turnPoint){
250         agent.desiredVelocity = pvector( -agent.maxSpeed, agent.velocity.y );
251         agent.steering = agent.desiredVelocity - agent.velocity;
252         return agent.steering;
253     }
254     else if(agent.position.x <= -turnPoint){
255         agent.desiredVelocity = pvector( agent.maxSpeed, agent.velocity.y );
256         agent.steering = agent.desiredVelocity - agent.velocity;
257         return agent.steering;
258     }
259     else if(agent.position.y >= turnPoint){
260         agent.desiredVelocity = pvector( agent.velocity.x, -agent.maxSpeed );
261         agent.steering = agent.desiredVelocity - agent.velocity;
262         return agent.steering;
263     }
264     else if(agent.position.y <= -turnPoint){
265         agent.desiredVelocity = pvector( agent.velocity.x, agent.maxSpeed );
266         agent.steering = agent.desiredVelocity - agent.velocity;
267         return agent.steering;
268     }
```

```

269     return pvector(0,0);
270 }

```

### 6.20.2.12 stayInPath()

```

pvector steeringBehavior::stayInPath (
    agent & agent,
    path & path,
    graphics view )

```

gets force to follow path

#### Parameters

<i>agent</i>	to follow the pathk
<i>path</i>	to follow
<i>view</i>	used for debugging

#### Returns

force to be applied

Definition at line 215 of file steeringBehavior.cpp.

```

216 {
217     float worldRecord = 1000000;
218     point normalPoint, predictedPos, start, end;
219     pvector distance;
220     for(auto it = path.points.begin(); it < path.points.end()-1; it++){
221         start = point((*it).x, (*it).y);
222         end = point((*it+1).x, (*it+1).y);
223         predictedPos = agent.position + agent.velocity;
224         normalPoint.getNormalPoint(predictedPos, start, end);
225         if (normalPoint.x < start.x || normalPoint.x > end.x){
226             normalPoint = end;
227         }
228         distance = predictedPos - normalPoint;
229         if (distance.magnitude() < worldRecord){
230             worldRecord = distance.magnitude();
231             agent.targetPoint = end;
232         }
233         view.drawPoint(agent.targetPoint);
234     }
235     return seek(agent);
236 }

```

### 6.20.2.13 wander()

```

pvector steeringBehavior::wander (
    agent & agent )

```

force to wander

#### Parameters

<i>agent</i>	agent that will wander
--------------	------------------------

**Returns**

force to be applied

Definition at line 98 of file steeringBehavior.cpp.

```

99 {
100     pvector circleCenter = agent.velocity;
101     circleCenter.normalize().mul(CIRCLE_DISTANCE + CIRCLE_RADIUS);
102
103     int wanderAngle = (rand() % 360);
104     pvector displacement {0, 1};
105     setAngle(displacement, wanderAngle);
106     displacement.mul(CIRCLE_RADIUS);
107
108     agent.desiredVelocity = displacement + circleCenter;
109     agent.steering = agent.desiredVelocity - agent.velocity;
110
111     //move it to the center when it is out of screen
112     if(agent.position.x > WIDTH || agent.position.x < -WIDTH ||
113        agent.position.y > HEIGHT || agent.position.y < -HEIGHT)
114         agent.position = point(0,0);
115
116     return agent.steering;
117 }
```

The documentation for this class was generated from the following files:

- include/steeringBehavior.h
- src/steeringBehavior.cpp

## 6.21 wander Class Reference

```
#include <wander.h>
```

### Public Member Functions

- [wander \(\)](#)  
*default constructor*

### Static Public Member Functions

- static void [loop \(\)](#)  
*wander scenario loop function*

### Additional Inherited Members

#### 6.21.1 Detailed Description

Definition at line 14 of file wander.h.

#### 6.21.2 Constructor & Destructor Documentation

### 6.21.2.1 wander()

```
wander::wander ( )
```

default constructor

**Todo** business logic will be changed

Definition at line 24 of file wander.cpp.

```
25 {
26     int agentCount = 30;
27     float maxForce = 0.3;
28     float maxSpeed = 0.6;
29
30     name = "wandering objects";
31     createAgent(RANDOM, &agentCount, &maxForce, &maxSpeed);
32     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );
33 }
```

## 6.21.3 Member Function Documentation

### 6.21.3.1 loop()

```
void wander::loop ( ) [static]
```

wander scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file wander.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         (*it).force = behavior.wander(*it);
19     }
20
21     refresh();
22 }
```

The documentation for this class was generated from the following files:

- include/wander.h
- src/wander.cpp

## 6.22 windy Class Reference

```
#include <windy.h>
```

## Public Member Functions

- `windy ()`  
*default constructor.*

## Static Public Member Functions

- static void `loop ()`  
*windy scenario loop function*

## Static Public Attributes

- static `flowField flow`  
*flow field used*

## Additional Inherited Members

### 6.22.1 Detailed Description

Definition at line 15 of file windy.h.

### 6.22.2 Constructor & Destructor Documentation

#### 6.22.2.1 windy()

```
windy::windy ( )
```

default constructor.

Definition at line 29 of file windy.cpp.

```
30 {  
31     int agentCount = 30;  
32     float maxForce = 0.3;  
33     float maxSpeed = 0.6;  
34  
35     name = "flow field";  
36     createAgent(RANDOM, &agentCount, &maxForce, &maxSpeed);  
37     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );  
38 }
```

### 6.22.3 Member Function Documentation



### 6.22.3.1 loop()

```
void windy::loop ( ) [static]
```

windy scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 17 of file windy.cpp.

```
18 {  
19     for(auto it = agents.begin(); it < agents.end(); it++){  
20         flow = flowField(pvector(GRAVITY));  
21         (*it).force = behavior.inFlowField(*it, flow);  
22     }  
23     flow = flowField(pvector(WIND_WEST));  
24     (*it).force += behavior.inFlowField(*it, flow);  
25 }  
26 refresh();  
27 }
```

## 6.22.4 Member Data Documentation

### 6.22.4.1 flow

```
flowField windy::flow [static]
```

flow field used

#### Note

opengl callback forces that function to be static

Definition at line 32 of file windy.h.

The documentation for this class was generated from the following files:

- include/[windy.h](#)
- src/[windy.cpp](#)



## Chapter 7

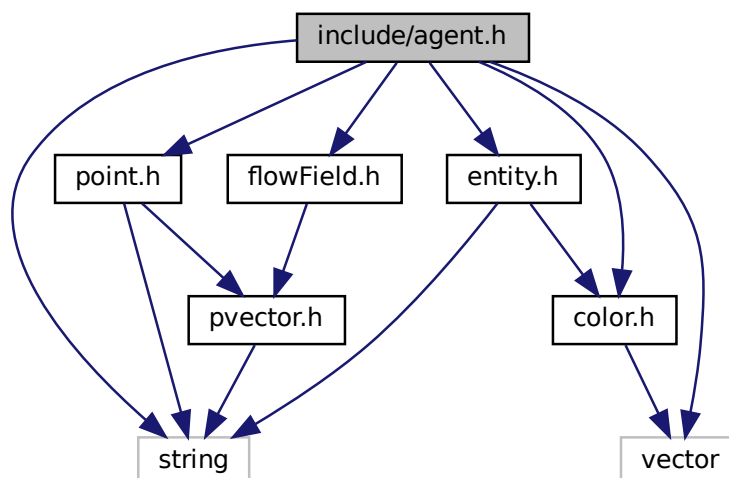
# File Documentation

### 7.1 include/agent.h File Reference

agent class defines all agent specifications

```
#include "point.h"  
#include "color.h"  
#include "entity.h"  
#include "flowField.h"  
#include <vector>  
#include <string>
```

Include dependency graph for agent.h:







#### 7.2.2.2 BLUE

```
#define BLUE color(0,0,1)
```

Definition at line 11 of file color.h.

#### 7.2.2.3 CYAN

```
#define CYAN color(0,1,1)
```

Definition at line 13 of file color.h.

#### 7.2.2.4 GREEN

```
#define GREEN color(0,1,0)
```

Definition at line 12 of file color.h.

#### 7.2.2.5 MAGENDA

```
#define MAGENDA color(1,0,1)
```

Definition at line 16 of file color.h.

#### 7.2.2.6 RED

```
#define RED color(1,0,0)
```

Definition at line 14 of file color.h.

#### 7.2.2.7 WHITE

```
#define WHITE color(1,1,1)
```

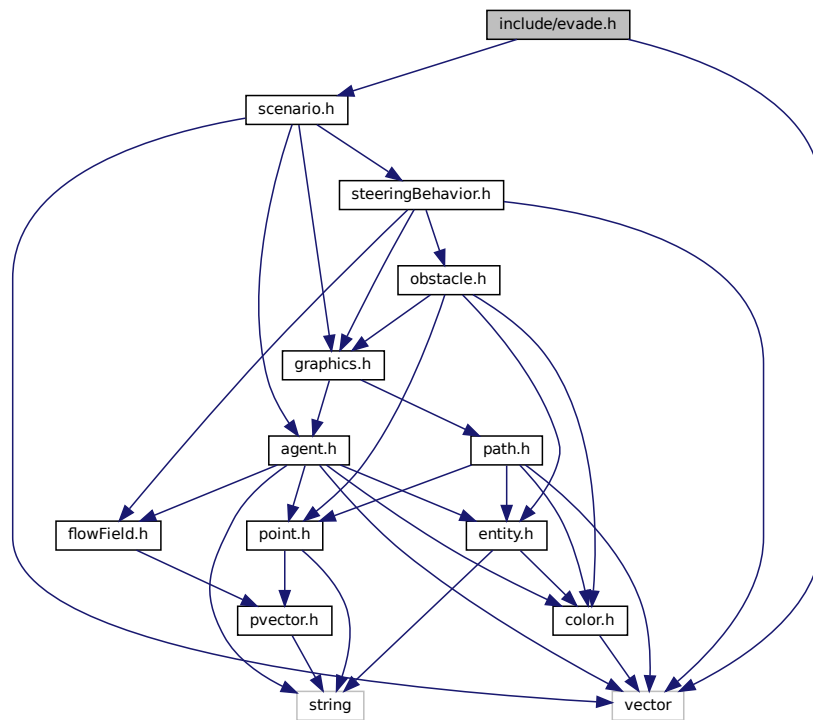
Definition at line 17 of file color.h.



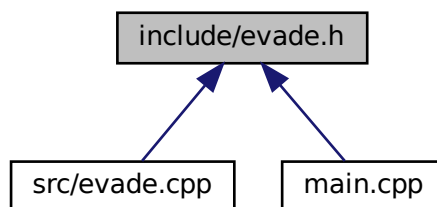
## 7.4 include/evade.h File Reference

evade class inherited from scenario class

```
#include "scenario.h"
#include <vector>
Include dependency graph for evade.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

- class [evade](#)



### 7.4.1 Detailed Description

evade class inherited from scenario class

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

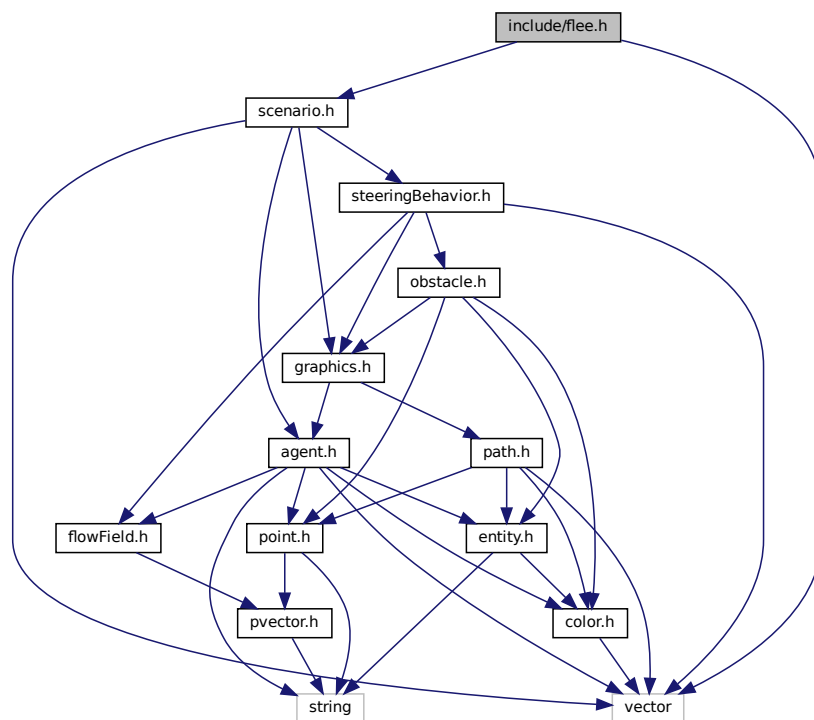
#### Date

15.05.2021

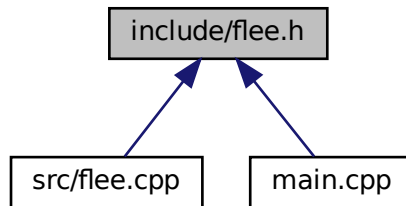
## 7.5 include/flee.h File Reference

agents flee from mouse scenario

```
#include "scenario.h"
#include <vector>
Include dependency graph for flee.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [flee](#)

### 7.5.1 Detailed Description

agents flee from mouse scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

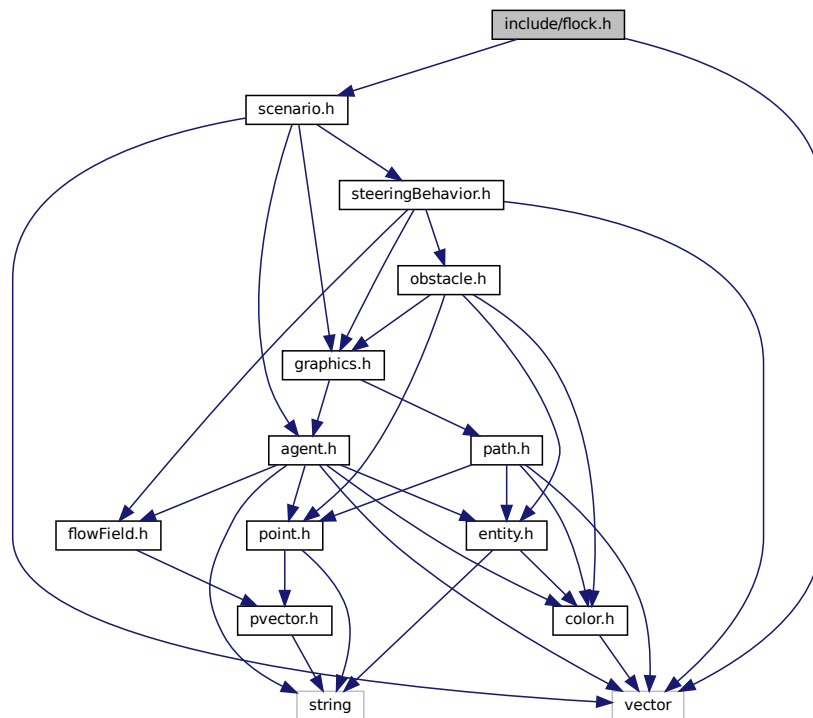
15.05.2021

## 7.6 include/flock.h File Reference

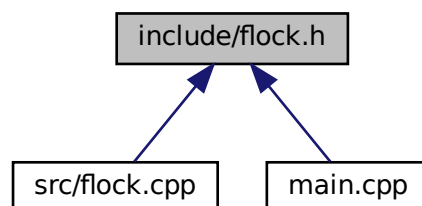
flocking agents scenario

```
#include "scenario.h"
#include <vector>
```

Include dependency graph for flock.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [flock](#)

### 7.6.1 Detailed Description

flocking agents scenario

## Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

## Date

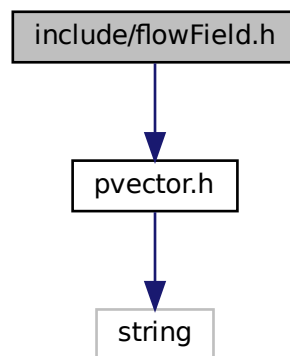
15.05.2021

## 7.7 include/flowField.h File Reference

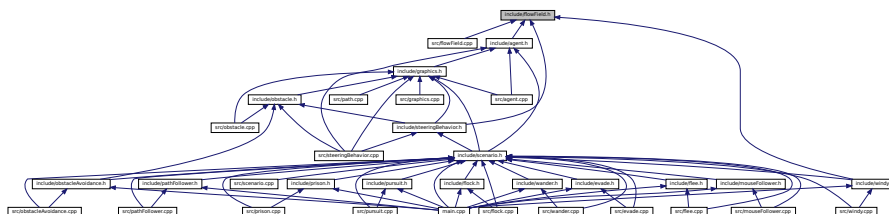
[flowField](#) class, screen can be filled with a force for each pixel

```
#include "pvector.h"
```

Include dependency graph for flowField.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [flowField](#)

## Macros

- `#define FIELD_WIDTH 34`
- `#define FIELD_HEIGHT 34`
- `#define WIND_WEST 0.1, 0.0`
- `#define GRAVITY 0.0, -0.1`

### 7.7.1 Detailed Description

`flowField` class, screen can be filled with a force for each pixel

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

13.05.2021

### 7.7.2 Macro Definition Documentation

#### 7.7.2.1 FIELD\_HEIGHT

```
#define FIELD_HEIGHT 34
```

Definition at line 13 of file `flowField.h`.

#### 7.7.2.2 FIELD\_WIDTH

```
#define FIELD_WIDTH 34
```

Definition at line 12 of file `flowField.h`.

#### 7.7.2.3 GRAVITY

```
#define GRAVITY 0.0, -0.1
```

Definition at line 16 of file `flowField.h`.



## Macros

- `#define WIDTH 34`
- `#define HEIGHT 34`
- `#define ESC 27`
- `#define PI 3.14159265`

### 7.8.1 Detailed Description

graphics class, drives openGL

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.8.2 Macro Definition Documentation

#### 7.8.2.1 ESC

```
#define ESC 27
```

Definition at line 16 of file graphics.h.

#### 7.8.2.2 HEIGHT

```
#define HEIGHT 34
```

Definition at line 14 of file graphics.h.

#### 7.8.2.3 PI

```
#define PI 3.14159265
```

Definition at line 17 of file graphics.h.

### 7.8.2.4 WIDTH

```
#define WIDTH 34
```

Definition at line 13 of file graphics.h.

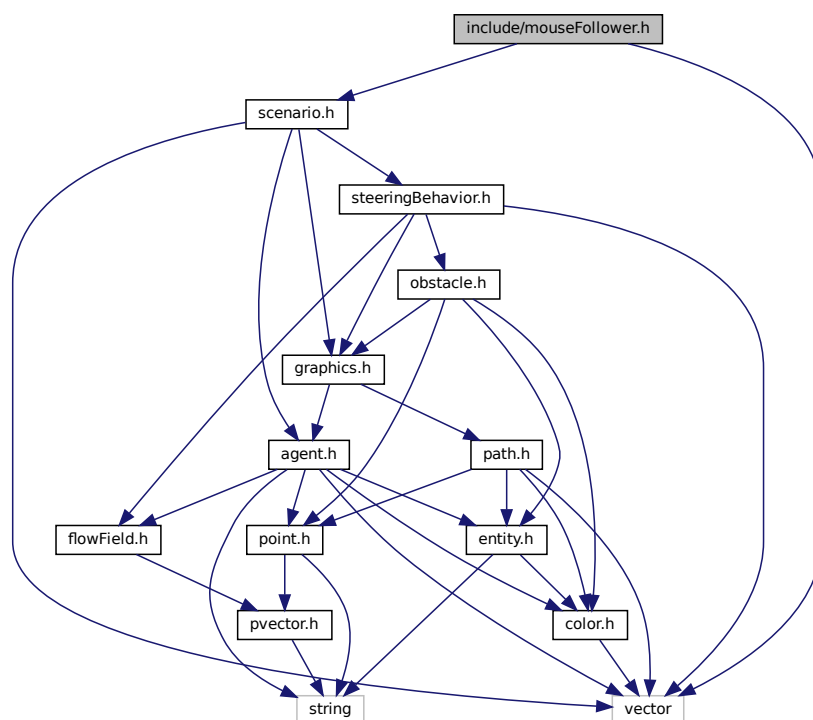
## 7.9 include/mouseFollower.h File Reference

agents follow mouse scenario

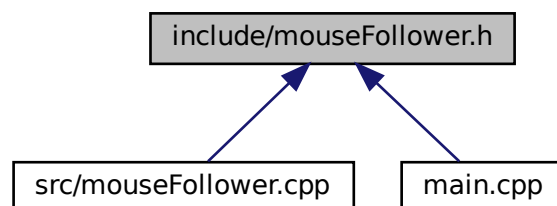
```
#include "scenario.h"
```

```
#include <vector>
```

Include dependency graph for mouseFollower.h:



This graph shows which files directly or indirectly include this file:





## Classes

- class [mouseFollower](#)

### 7.9.1 Detailed Description

agents follow mouse scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

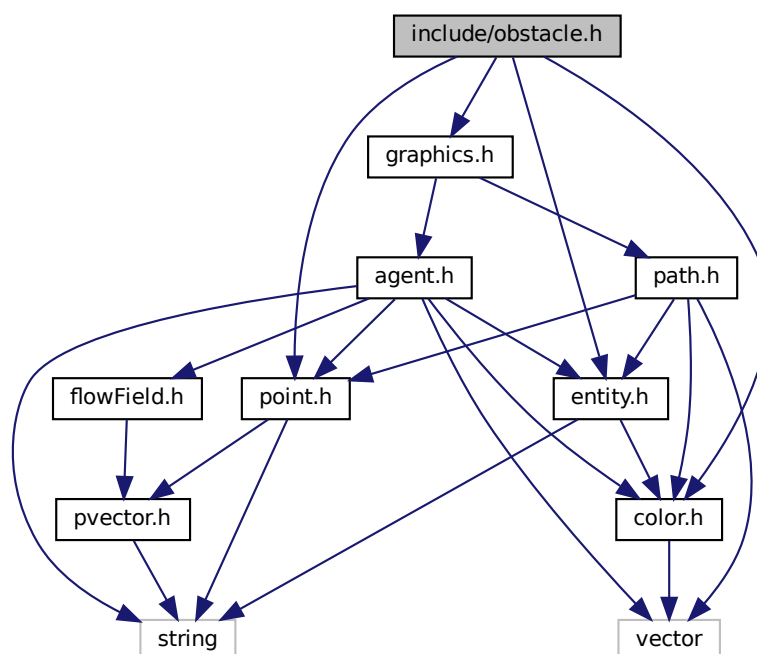
#### Date

15.05.2021

## 7.10 include/obstacle.h File Reference

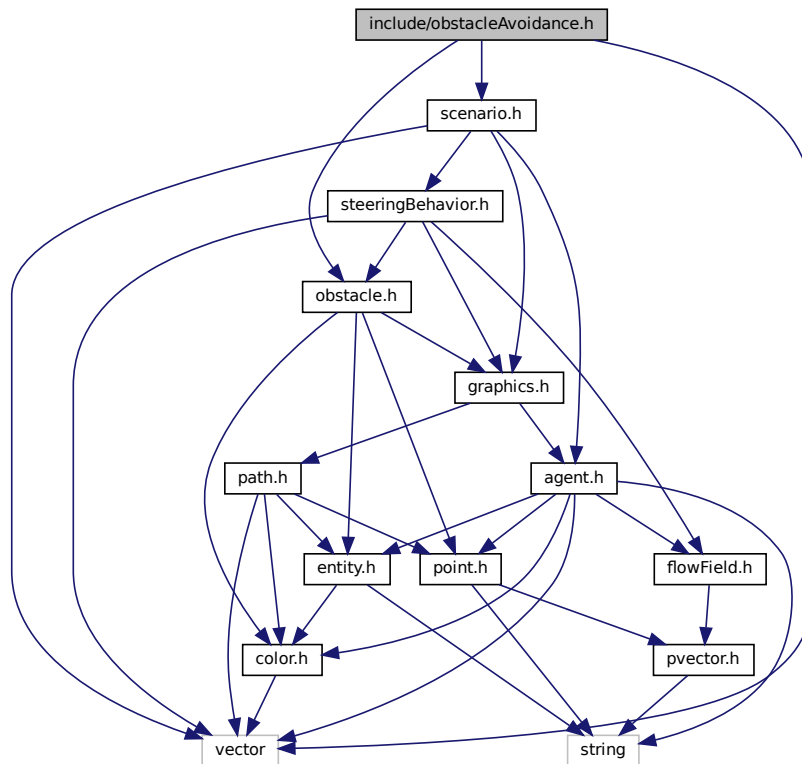
circular obstacles for agent avoidance behaviors

```
#include "point.h"
#include "graphics.h"
#include "color.h"
#include "entity.h"
Include dependency graph for obstacle.h:
```

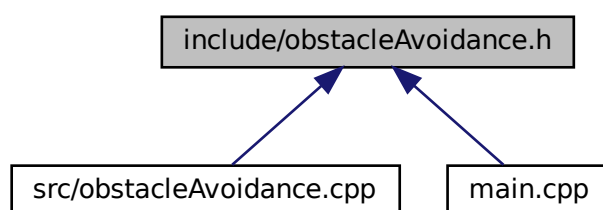




Include dependency graph for obstacleAvoidance.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [obstacleAvoidance](#)

### 7.11.1 Detailed Description

agents avoid from obstacles scenario



## Classes

- class [path](#)

### 7.12.1 Detailed Description

path class used for path following steering behaviors.

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

12.05.2021

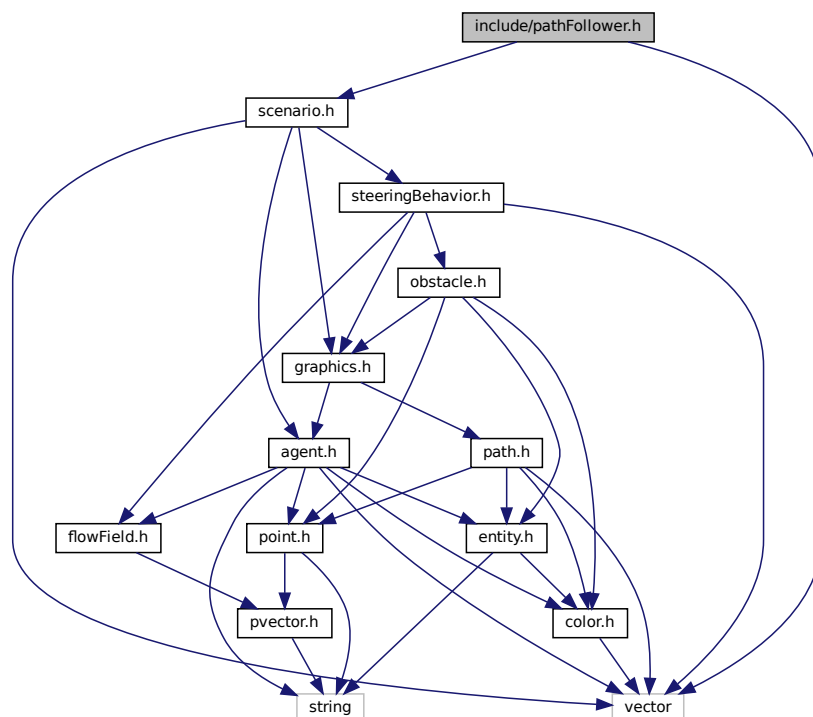
## 7.13 include/pathFollower.h File Reference

path following scenario

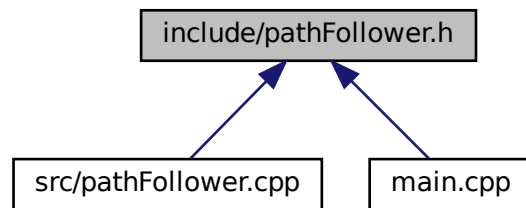
```
#include "scenario.h"
```

```
#include <vector>
```

Include dependency graph for pathFollower.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [pathFollower](#)

### 7.13.1 Detailed Description

path following scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

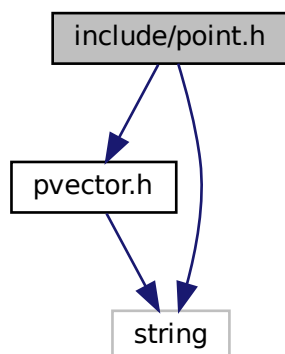
15.05.2021

## 7.14 include/point.h File Reference

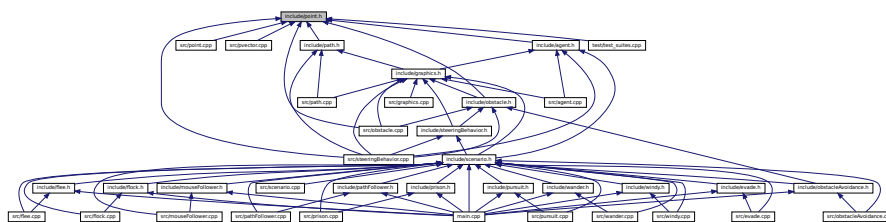
point class used for point operations

```
#include "pvector.h"  
#include <string>
```

Include dependency graph for point.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [point](#)

### 7.14.1 Detailed Description

point class used for point operations

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

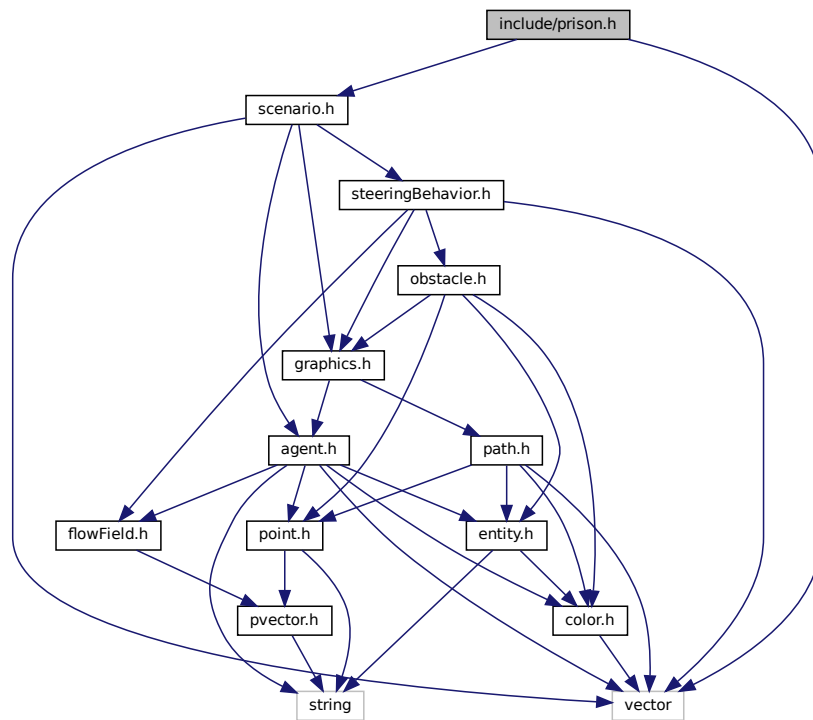
#### Date

15.05.2021

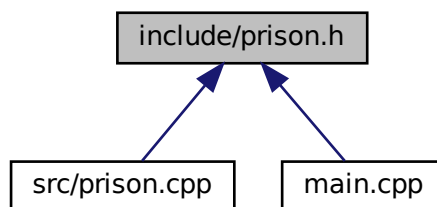
## 7.15 include/prison.h File Reference

agents cant escape from field scenario

```
#include "scenario.h"
#include <vector>
Include dependency graph for prison.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

- class [prison](#)



### 7.15.1 Detailed Description

agents cant escape from field scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

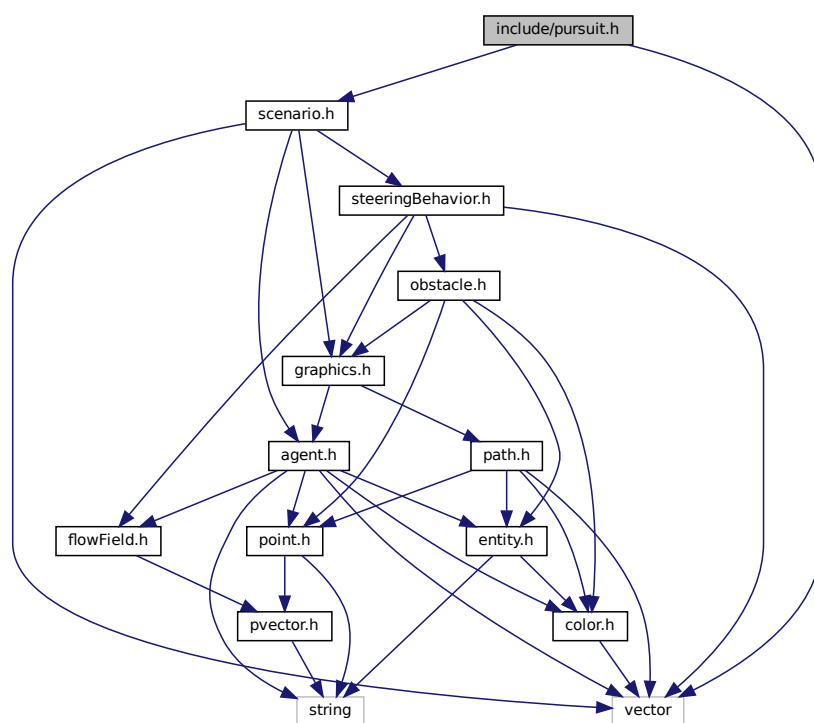
#### Date

15.05.2021

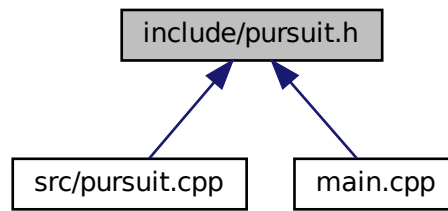
## 7.16 include/pursuit.h File Reference

one agent pursue other one scenario

```
#include "scenario.h"
#include <vector>
Include dependency graph for pursuit.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [pursuit](#)

### 7.16.1 Detailed Description

one agent pursue other one scenario

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

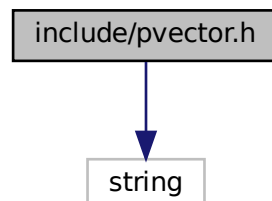
15.05.2021

## 7.17 include/pvector.h File Reference

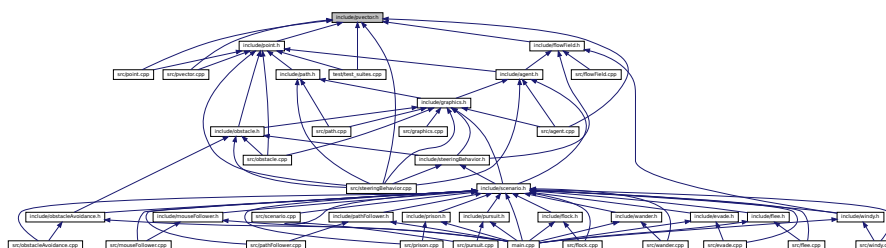
pvector class used for 2D vector operations

```
#include <string>
```

Include dependency graph for pvector.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [pvector](#)

## Macros

- `#define` [PI](#) 3.14159265

### 7.17.1 Detailed Description

pvector class used for 2D vector operations

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.17.2 Macro Definition Documentation

#### 7.17.2.1 PI

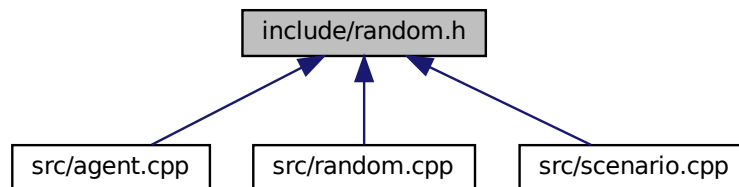
```
#define PI 3.14159265
```

Definition at line 11 of file pvector.h.

## 7.18 include/random.h File Reference

utility class for random operations

This graph shows which files directly or indirectly include this file:



### Classes

- class [random](#)

### 7.18.1 Detailed Description

utility class for random operations

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

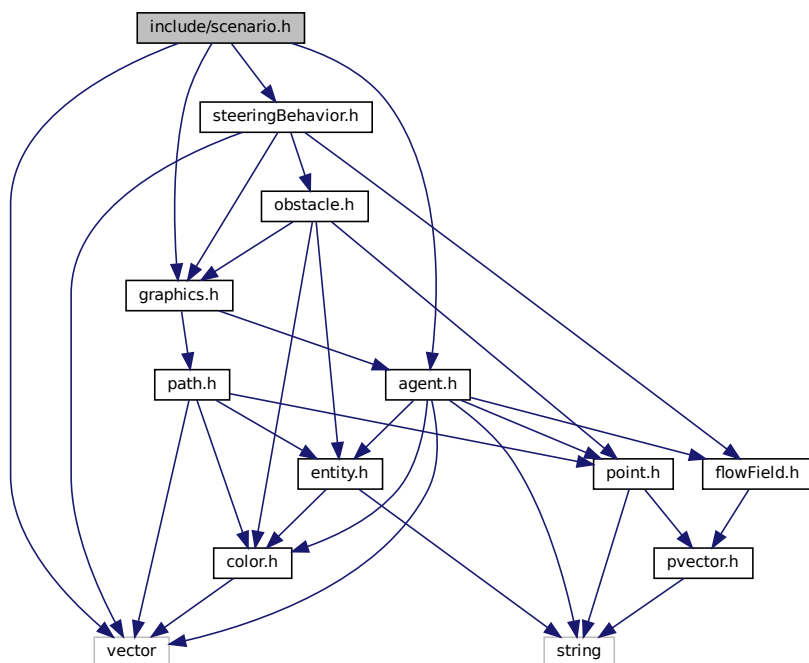
15.05.2021

## 7.19 include/scenario.h File Reference

base class for all scenarios

```
#include "agent.h"
#include "graphics.h"
#include "steeringBehavior.h"
```

Include dependency graph for scenario.h:



- class **scenario**

- enum types { RANDOM =0, STATIC, TROOP }

15.05.2021

## 7.19.2 Enumeration Type Documentation

### 7.19.2.1 types

enum `types`

Enumerator

RANDOM	
STATIC	
TROOP	

Definition at line 17 of file scenario.h.

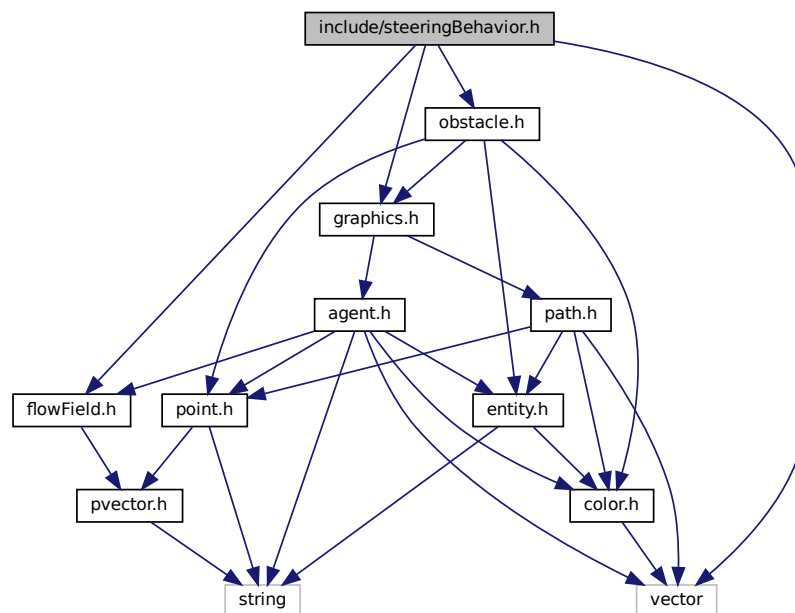
```
17 { RANDOM=0, STATIC, TROOP };
```

## 7.20 include/steeringBehavior.h File Reference

functions for autonomous steering behaviors

```
#include "flowField.h"
#include <vector>
#include "graphics.h"
#include "obstacle.h"
```

Include dependency graph for steeringBehavior.h:



- class `steeringBehavior`

- #define **CIRCLE\_DISTANCE** 0.1
- #define **CIRCLE\_RADIUS** 0.4
- #define **FOLLOW\_MOUSE** 1
- #define **STAY\_IN\_FIELD** 2
- #define **IN\_FLOW\_FIELD** 3
- #define **AVOID\_OBSTACLE** 4
- #define **STAY\_IN\_PATH** 5
- #define **FLOCK** 6
- #define **WANDER** 7
- #define **FLEE** 8
- #define **PURSUIT** 9
- #define **EVADE** 10

functions for autonomous steering behaviors

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

15.05.2021

#### 7.20.2.1 AVOID OBSTACLE

Definition at line 21 of file steeringBehavior.h.

#### 7.20.2.2 CIRCLE\_DISTANCE

```
#define CIRCLE_DISTANCE 0.1
```

Definition at line 15 of file steeringBehavior.h.

#### 7.20.2.3 CIRCLE\_RADIUS

```
#define CIRCLE_RADIUS 0.4
```

Definition at line 16 of file steeringBehavior.h.

#### 7.20.2.4 EVADE

```
#define EVADE 10
```

Definition at line 27 of file steeringBehavior.h.

#### 7.20.2.5 FLEE

```
#define FLEE 8
```

Definition at line 25 of file steeringBehavior.h.

#### 7.20.2.6 FLOCK

```
#define FLOCK 6
```

Definition at line 23 of file steeringBehavior.h.

#### 7.20.2.7 FOLLOW\_MOUSE

```
#define FOLLOW_MOUSE 1
```

Definition at line 18 of file steeringBehavior.h.



### 7.20.2.8 IN\_FLOW\_FIELD

```
#define IN_FLOW_FIELD 3
```

Definition at line 20 of file steeringBehavior.h.

### 7.20.2.9 PURSUIT

```
#define PURSUIT 9
```

Definition at line 26 of file steeringBehavior.h.

### 7.20.2.10 STAY\_IN\_FIELD

```
#define STAY_IN_FIELD 2
```

Definition at line 19 of file steeringBehavior.h.

### 7.20.2.11 STAY\_IN\_PATH

```
#define STAY_IN_PATH 5
```

Definition at line 22 of file steeringBehavior.h.

### 7.20.2.12 WANDER

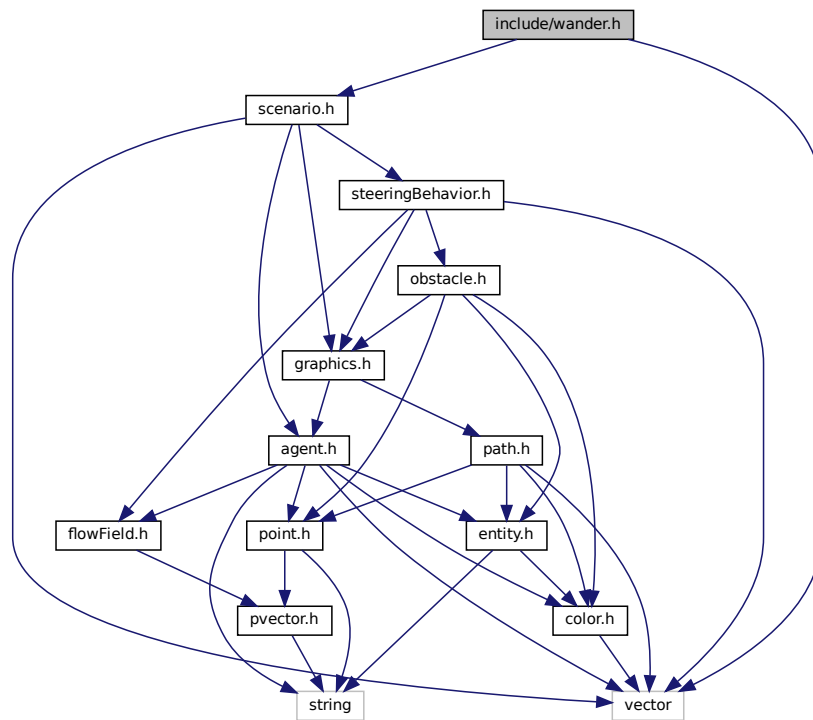
```
#define WANDER 7
```

Definition at line 24 of file steeringBehavior.h.

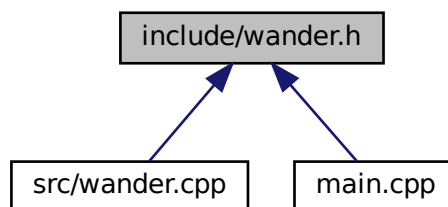
## 7.21 include/wander.h File Reference

random wandering agents scenario

```
#include "scenario.h"
#include <vector>
Include dependency graph for wander.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

- class [wander](#)

### 7.21.1 Detailed Description

random wandering agents scenario

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

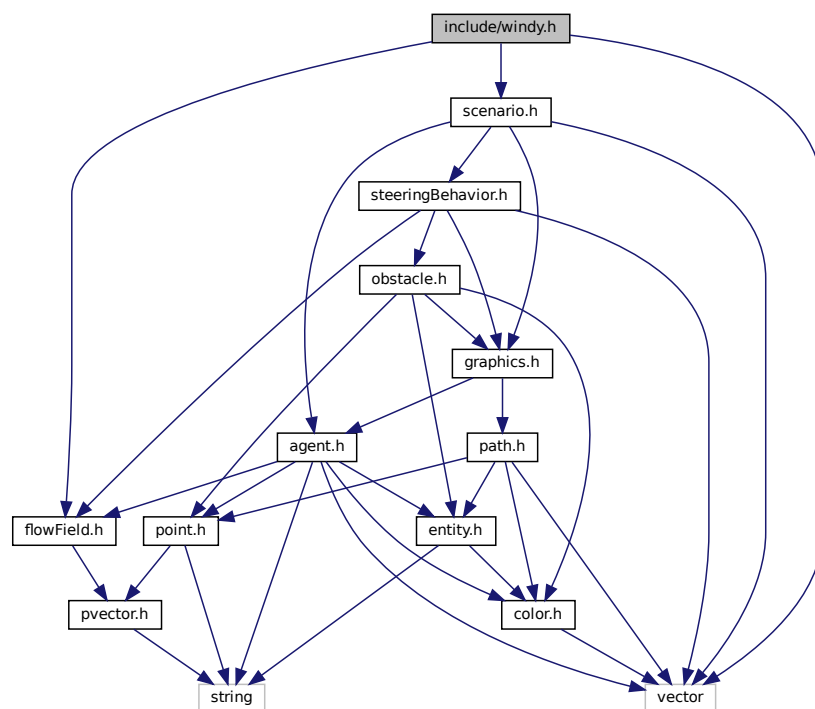
Date

15.05.2021

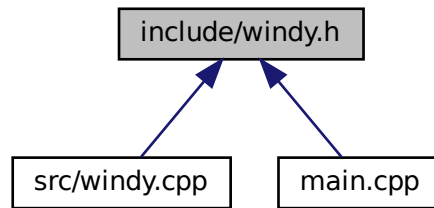
## 7.22 include/windy.h File Reference

windy air scenario

```
#include "scenario.h"  
#include "flowField.h"  
#include <vector>  
Include dependency graph for windy.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [windy](#)

### 7.22.1 Detailed Description

windy air scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

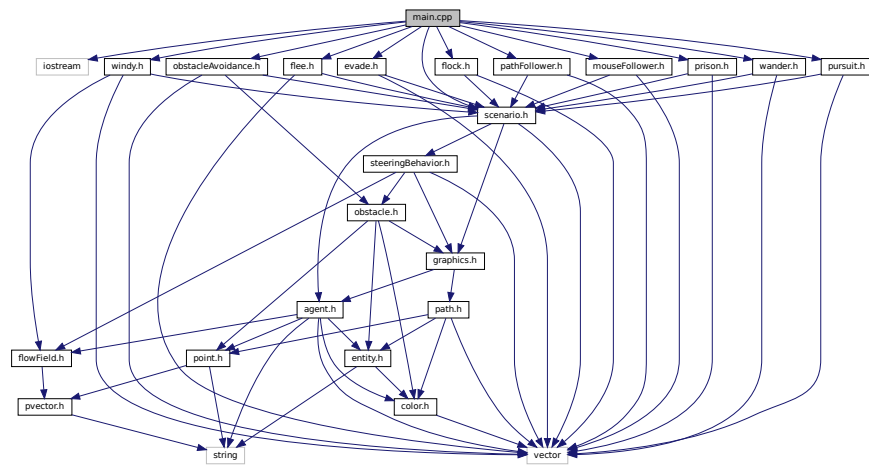
## 7.23 main.cpp File Reference

client code

```
#include <iostream>
#include "mouseFollower.h"
#include "prison.h"
#include "windy.h"
#include "wander.h"
#include "pursuit.h"
#include "flee.h"
#include "scenario.h"
#include "evade.h"
#include "flock.h"
#include "pathFollower.h"
```

```
#include "obstacleAvoidance.h"
```

Include dependency graph for main.cpp:



## Functions

- void `menu` ()  
*displays menu*
- int `main` (int argc, char \*\*argv)  
*main routine*

## Variables

- int `mode`  
*specifies user selected scenario*

### 7.23.1 Detailed Description

client code

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

### 7.23.2 Function Documentation

### 7.23.2.1 main()

```
int main (
    int argc,
    char ** argv )
```

main routine

Definition at line 48 of file main.cpp.

```
48     {
49         menu();
50
51         scenario* sc;
52
53         if(mode == FOLLOW_MOUSE){
54             *sc = mouseFollower();
55         }
56         else if(mode == STAY_IN_FIELD){
57             *sc = prison();
58         }
59         else if(mode == IN_FLOW_FIELD){
60             *sc = windy();
61         }
62         else if(mode == WANDER){
63             *sc = wander();
64         }
65         else if(mode == PURSUIT){
66             *sc = pursuit();
67         }
68         else if(mode == FLEE){
69             *sc = flee();
70         }
71         else if(mode == EVADE){
72             *sc = evade();
73         }
74         else if(mode == FLOCK){
75             *sc = flock();
76         }
77         else if(mode == STAY_IN_PATH){
78             *sc = pathFollower();
79         }
80         else if(mode == AVOID_OBSTACLE){
81             *sc = obstacleAvoidance();
82         }
83
84         sc->initGL(&argc, argv);
85
86         return 0;
87     }
```

### 7.23.2.2 menu()

```
void menu ( )
```

displays menu

Definition at line 31 of file main.cpp.

```
31     {
32         cout << "Follow Mouse       : 1" << endl;
33         cout << "Stay in Field       : 2" << endl;
34         cout << "In Flow Field      : 3" << endl;
35         cout << "OBSTACLE AVOIDANCE : 4" << endl;
36         cout << "Stay in Path       : 5" << endl;
37         cout << "FLOCK              : 6" << endl;
38         cout << "WANDER              : 7" << endl;
39         cout << "FLEE                : 8" << endl;
40         cout << "PURSUIT             : 9" << endl;
41         cout << "EVADE               : 10" << endl;
42         cin >> mode;
43     }
```

### 7.23.3 Variable Documentation

#### 7.23.3.1 mode

```
int mode
```

specifies user selected scenario

Definition at line 26 of file main.cpp.

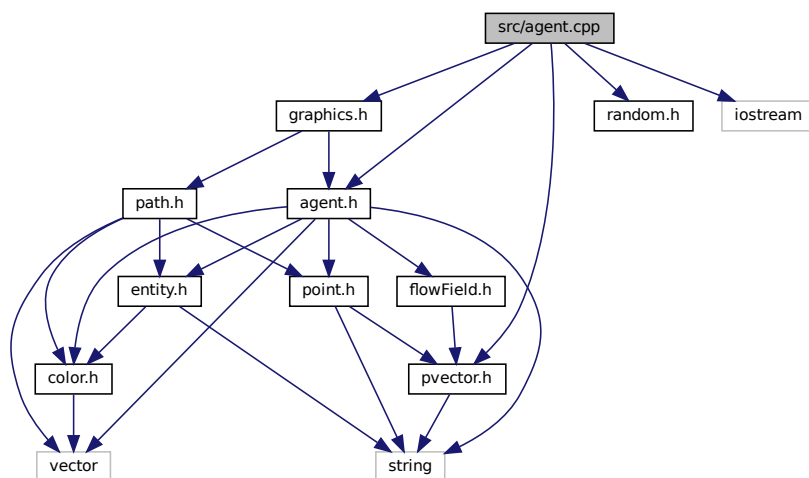
## 7.24 README.md File Reference

## 7.25 src/agent.cpp File Reference

implementation of the agent class

```
#include "agent.h"
#include "pvector.h"
#include "graphics.h"
#include "random.h"
#include <iostream>
```

Include dependency graph for agent.cpp:



### 7.25.1 Detailed Description

implementation of the agent class

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

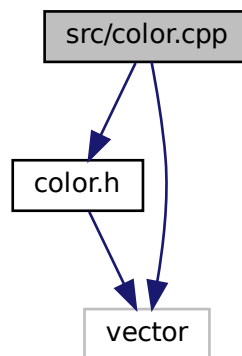
Date

14.05.2021

## 7.26 src/color.cpp File Reference

color class implementation

```
#include "color.h"  
#include <vector>  
Include dependency graph for color.cpp:
```



### 7.26.1 Detailed Description

color class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

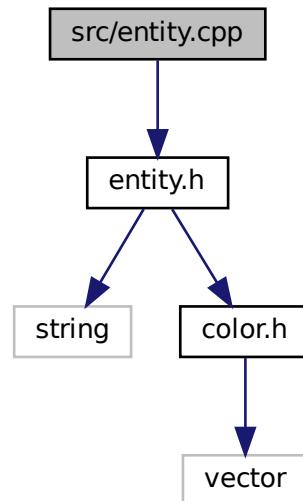
13.05.2021

## 7.27 src/entity.cpp File Reference

```
#include "entity.h"
```



Include dependency graph for entity.cpp:

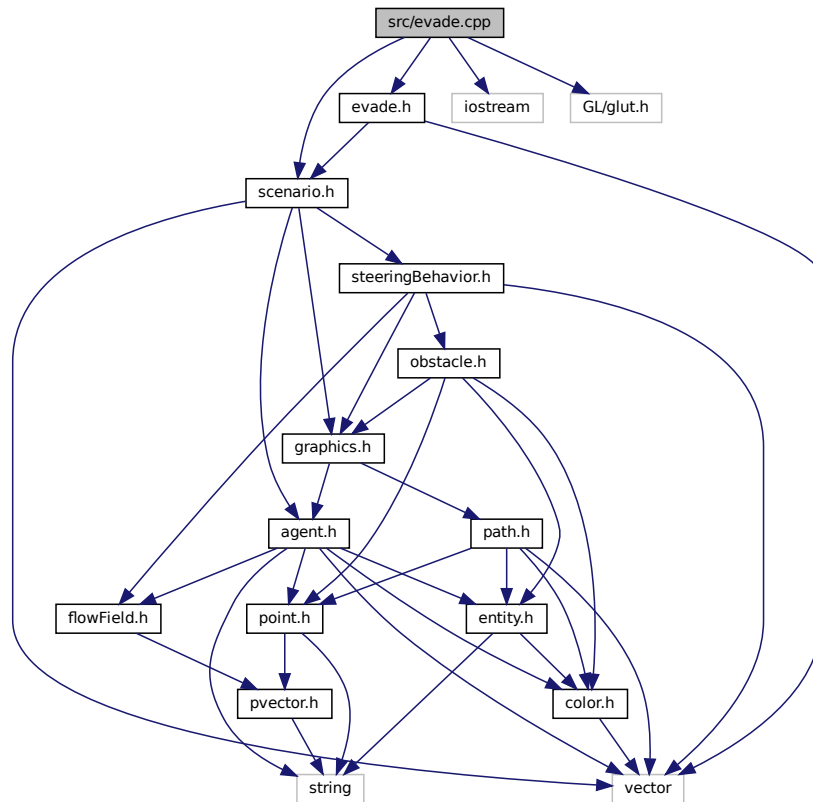


## 7.28 src/evade.cpp File Reference

evade class implementation

```
#include "scenario.h"
#include "evade.h"
#include <iostream>
#include <GL/glut.h>
```

Include dependency graph for evade.cpp:



### 7.28.1 Detailed Description

evade class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

## 7.29 src/flee.cpp File Reference

flee class implementation

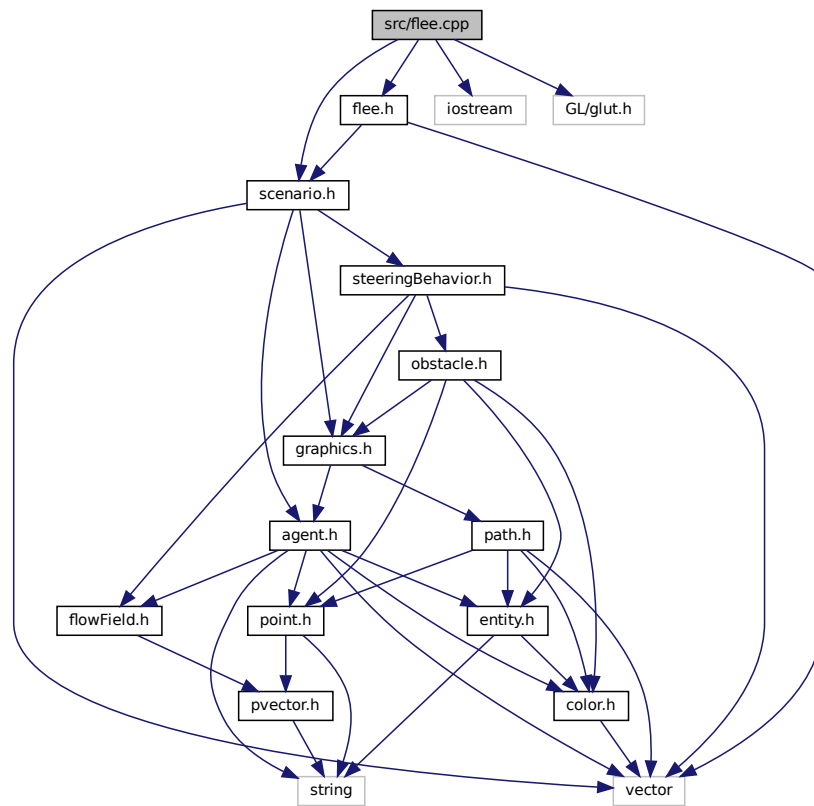
```

#include "scenario.h"
#include "flee.h"
#include <iostream>

```

```
#include <GL/glut.h>
```

Include dependency graph for flee.cpp:



### 7.29.1 Detailed Description

flee class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

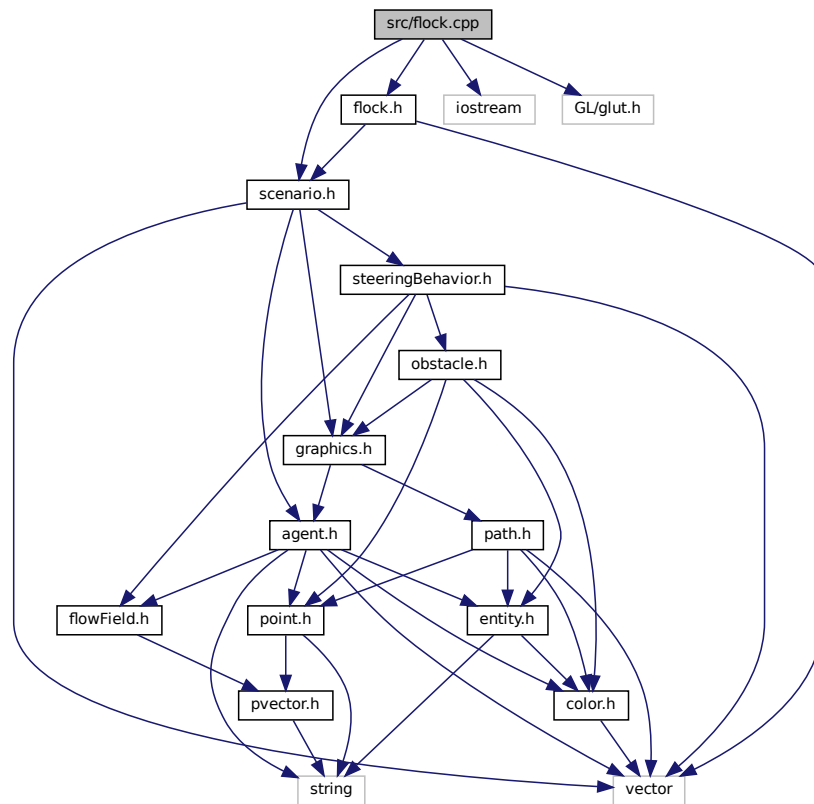
15.05.2021

## 7.30 src/flock.cpp File Reference

flock class implementation

```
#include "scenario.h"
#include "flock.h"
#include <iostream>
```

```
#include <GL/glut.h>
Include dependency graph for flock.cpp:
```



### 7.30.1 Detailed Description

flock class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

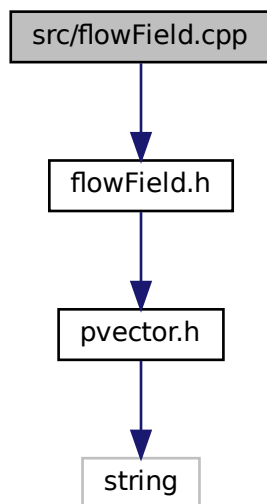
15.05.2021

## 7.31 src/flowField.cpp File Reference

[flowField](#) class implementation

```
#include "flowField.h"
```

Include dependency graph for flowField.cpp:



### 7.31.1 Detailed Description

`flowField` class implementation

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

13.05.2021

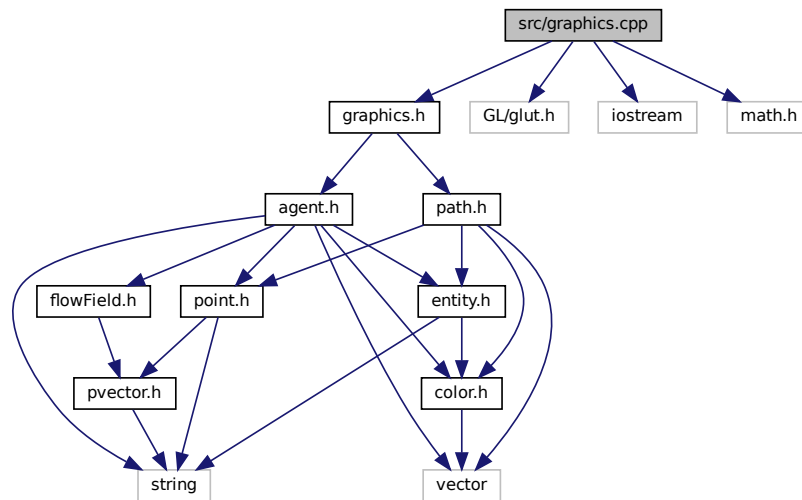
## 7.32 src/graphics.cpp File Reference

`graphics` class implementation

```
#include "graphics.h"
#include <GL/glut.h>
#include <iostream>
```

```
#include "math.h"
```

Include dependency graph for graphics.cpp:



### 7.32.1 Detailed Description

graphics class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

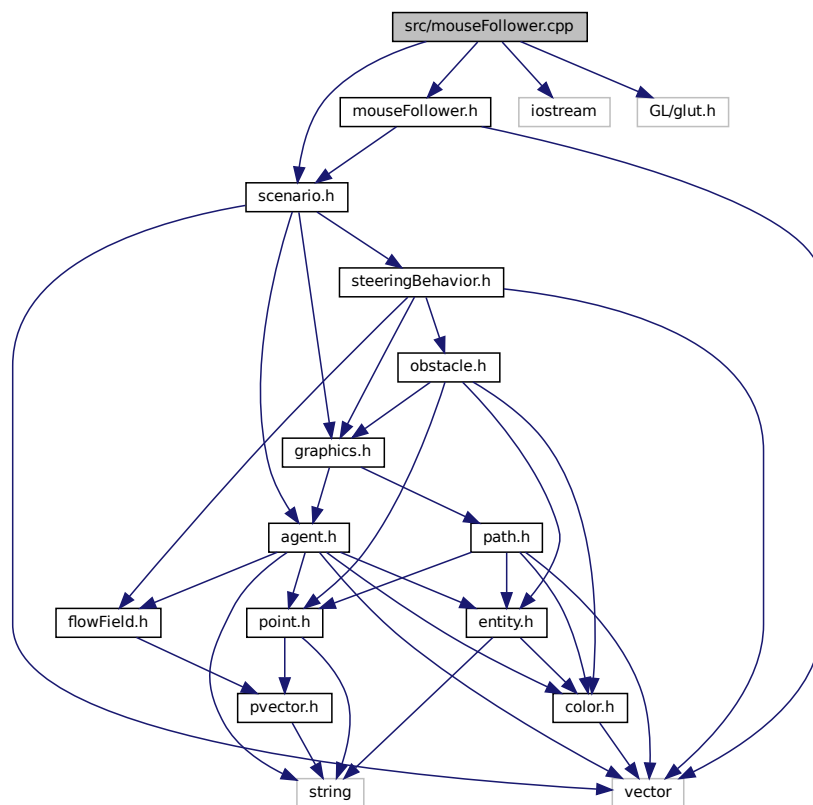
## 7.33 src/mouseFollower.cpp File Reference

`mouseFollower` class implementation

```
#include "scenario.h"
#include "mouseFollower.h"
#include <iostream>
```

```
#include <GL/glut.h>
```

Include dependency graph for mouseFollower.cpp:



### 7.33.1 Detailed Description

[mouseFollower](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

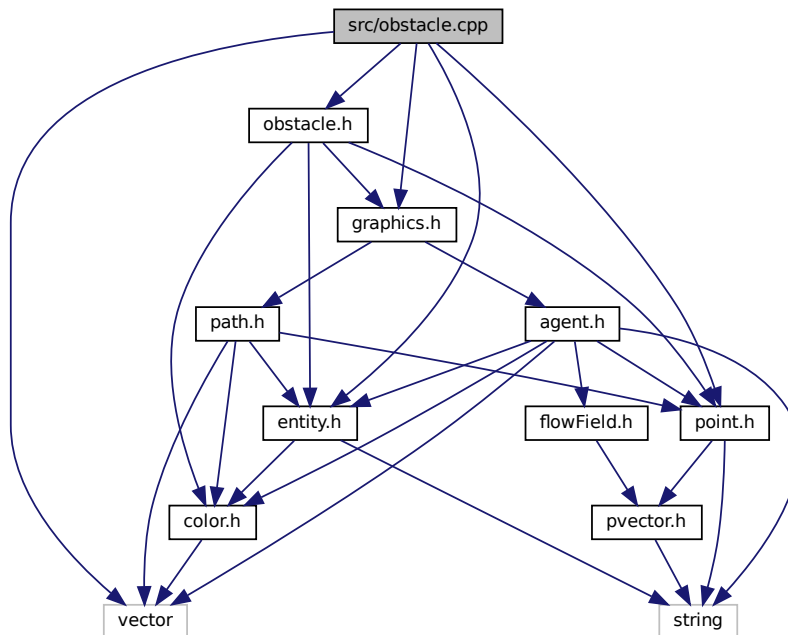
15.05.2021

## 7.34 src/obstacle.cpp File Reference

obstacle class implementation

```
#include "obstacle.h"
#include "graphics.h"
#include "point.h"
```

```
#include "entity.h"
#include <vector>
Include dependency graph for obstacle.cpp:
```



### 7.34.1 Detailed Description

obstacle class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

12.05.2021

## 7.35 src/obstacleAvoidance.cpp File Reference

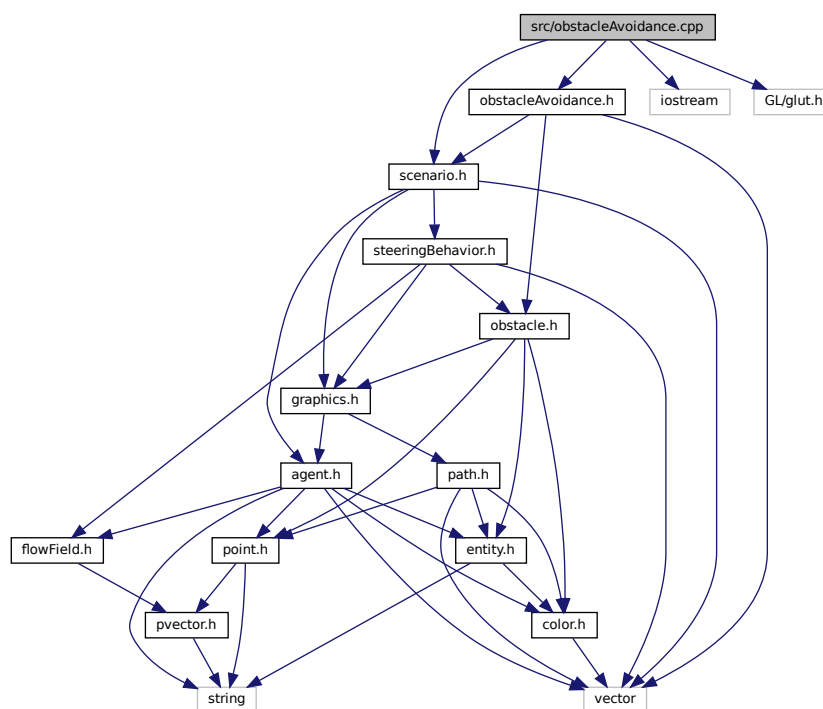
[obstacleAvoidance](#) class implementation

```
#include "scenario.h"
#include "obstacleAvoidance.h"
#include <iostream>
```



```
#include <GL/glut.h>
```

Include dependency graph for obstacleAvoidance.cpp:



### 7.35.1 Detailed Description

[obstacleAvoidance](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

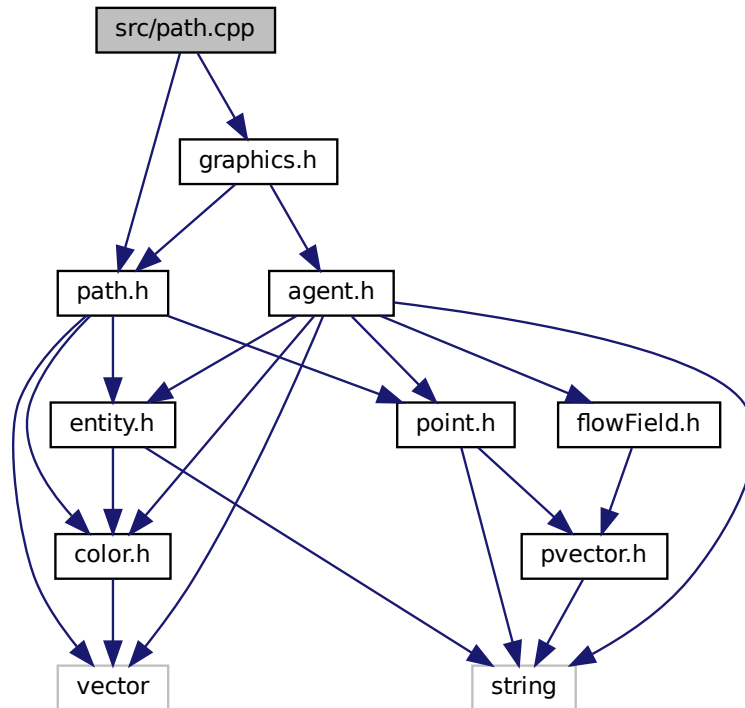
Date

15.05.2021

## 7.36 src/path.cpp File Reference

[path](#) class implementation

```
#include "path.h"
#include "graphics.h"
Include dependency graph for path.cpp:
```



### 7.36.1 Detailed Description

path class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

12.05.2021

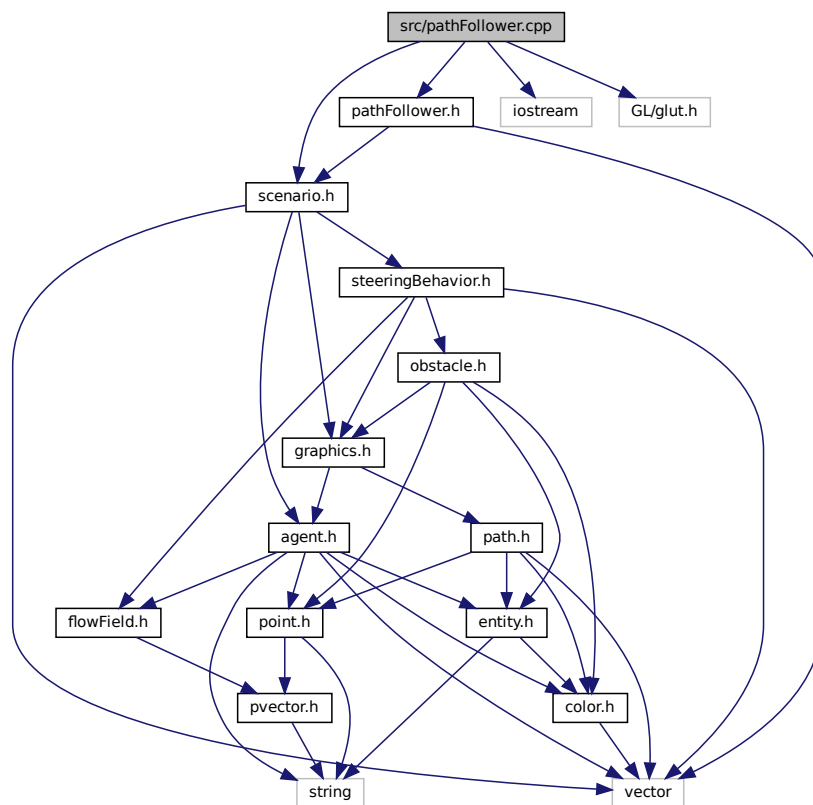
## 7.37 src/pathFollower.cpp File Reference

`pathFollower` class implementation

```
#include "scenario.h"
#include "pathFollower.h"
#include <iostream>
```

```
#include <GL/glut.h>
```

Include dependency graph for pathFollower.cpp:



### 7.37.1 Detailed Description

[pathFollower](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

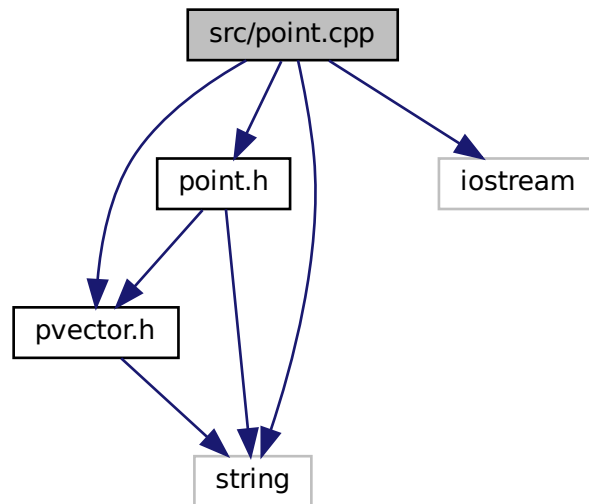
## 7.38 src/point.cpp File Reference

point class implementation file

```
#include "point.h"
#include "pvector.h"
#include <string>
```

```
#include <iostream>
```

Include dependency graph for point.cpp:



### 7.38.1 Detailed Description

point class implementation file

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

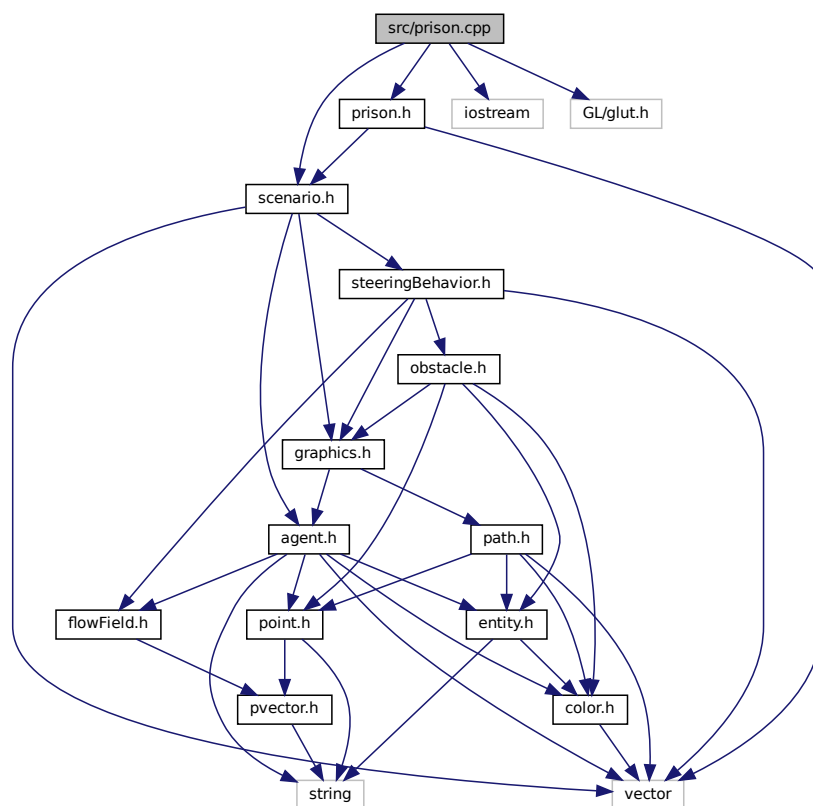
## 7.39 src/prison.cpp File Reference

prison class implementation

```
#include "scenario.h"
#include "prison.h"
#include <iostream>
```

```
#include <GL/glut.h>
```

Include dependency graph for prison.cpp:



## Macros

- #define [WALL](#) 30
- #define [DISTANCE](#) 2

### 7.39.1 Detailed Description

prison class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

### 7.39.2 Macro Definition Documentation



### 7.40.1 Detailed Description

prison class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

## 7.41 src/pvector.cpp File Reference

pvector class implementation

```
#include "pvector.h"
```

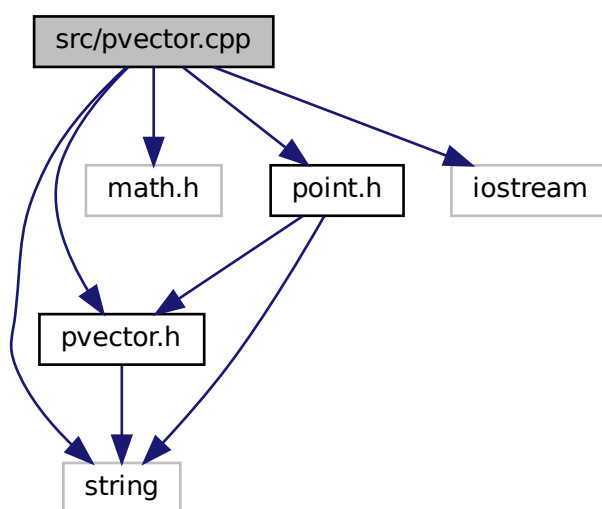
```
#include "math.h"
```

```
#include "point.h"
```

```
#include <iostream>
```

```
#include <string>
```

Include dependency graph for pvector.cpp:



### 7.41.1 Detailed Description

pvector class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

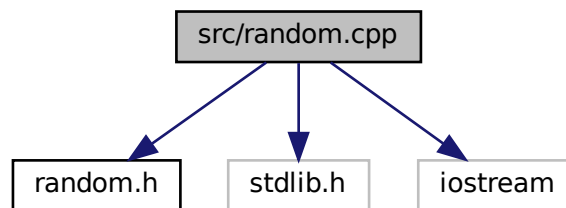
Date

15.05.2021

## 7.42 src/random.cpp File Reference

utility class for random operations

```
#include "random.h"
#include <stdlib.h>
#include <iostream>
Include dependency graph for random.cpp:
```



### 7.42.1 Detailed Description

utility class for random operations

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

## 7.43 src/scenario.cpp File Reference

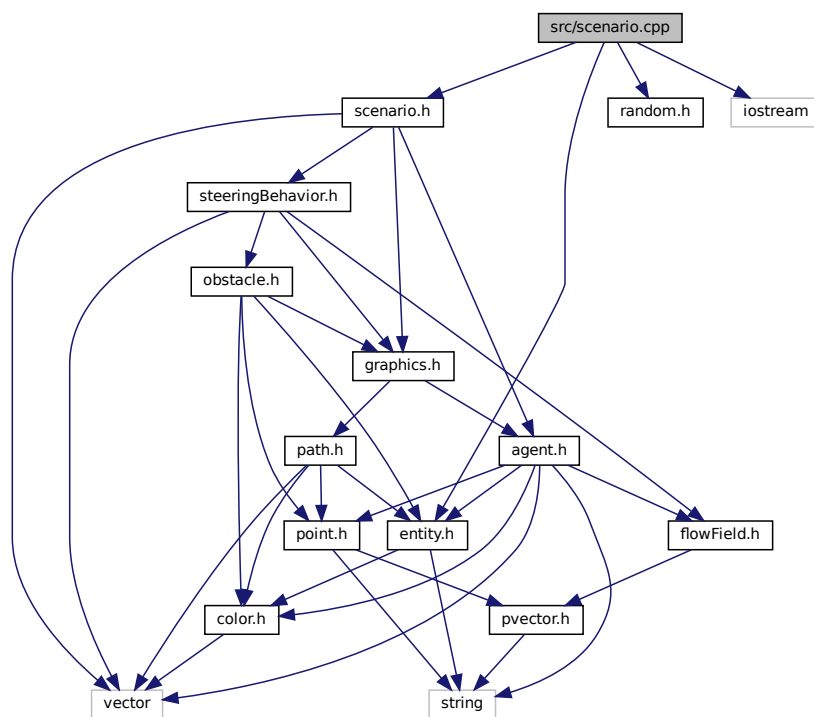
scenario base class implementation

```
#include "scenario.h"
#include "random.h"
#include "entity.h"
```



```
#include <iostream>
```

Include dependency graph for scenario.cpp:



## Macros

- `#define MAX_NUMBER_OF_AGENTS 50`

### 7.43.1 Detailed Description

scenario base class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

### 7.43.2 Macro Definition Documentation

### 7.43.2.1 MAX\_NUMBER\_OF\_AGENTS

```
#define MAX_NUMBER_OF_AGENTS 50
```

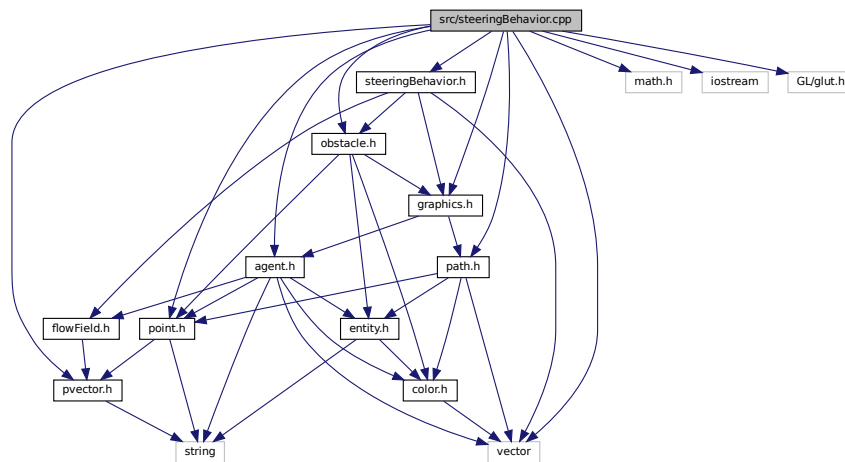
Definition at line 13 of file scenario.cpp.

## 7.44 src/steeringBehavior.cpp File Reference

implementation of autonomous steering behaviors

```
#include "steeringBehavior.h"
#include "pvector.h"
#include "agent.h"
#include "path.h"
#include "point.h"
#include <vector>
#include "graphics.h"
#include "math.h"
#include "obstacle.h"
#include <iostream>
#include <GL/glut.h>
```

Include dependency graph for steeringBehavior.cpp:



### 7.44.1 Detailed Description

implementation of autonomous steering behaviors

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

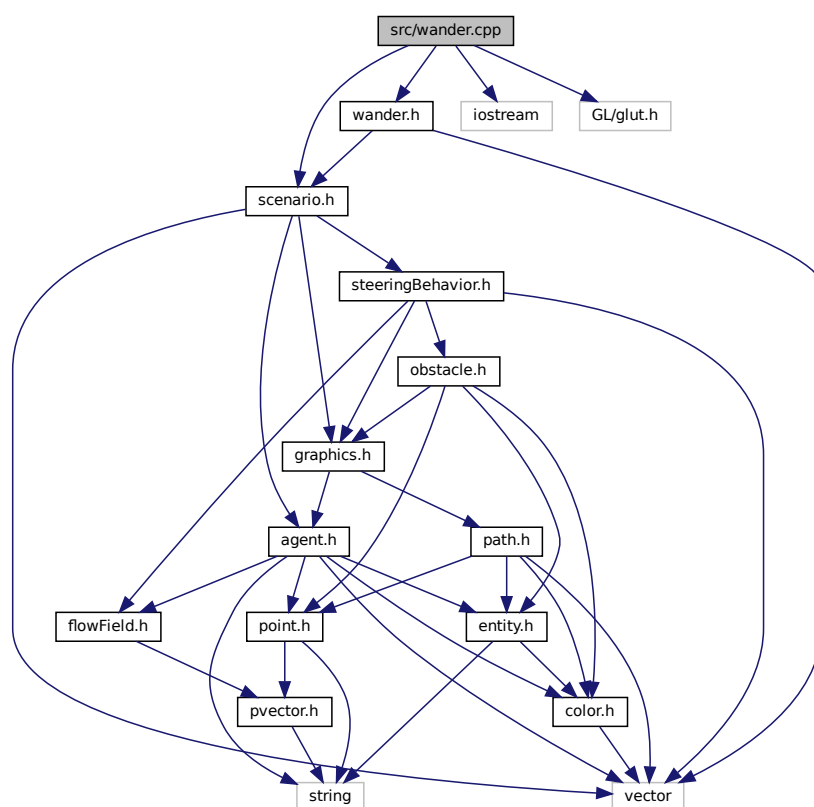
Date

15.05.2021

## 7.45 src/wander.cpp File Reference

wander class implementation

```
#include "scenario.h"
#include "wander.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for wander.cpp:
```



### 7.45.1 Detailed Description

wander class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

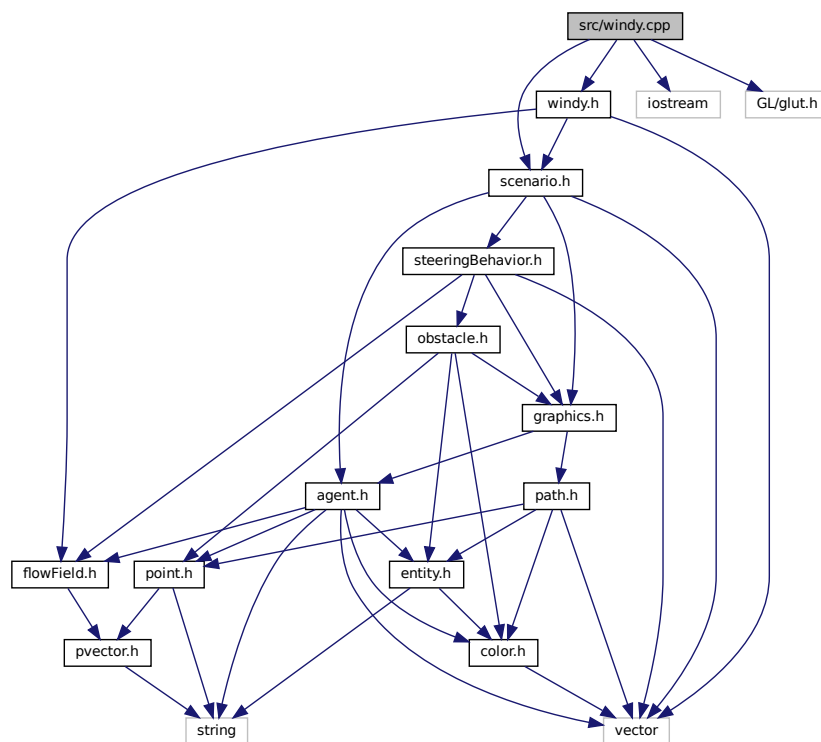
Date

15.05.2021

## 7.46 src/windy.cpp File Reference

windy class implementation

```
#include "scenario.h"
#include "windy.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for windy.cpp:
```



### 7.46.1 Detailed Description

windy class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

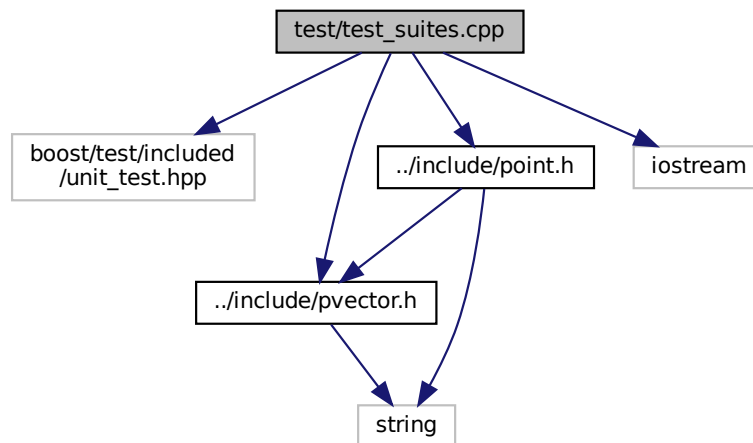
15.05.2021

## 7.47 test/test\_suites.cpp File Reference

unit test suites

```
#include <boost/test/included/unit_test.hpp>
#include "../include/pvector.h"
#include "../include/point.h"
#include <iostream>
```

Include dependency graph for test\_suites.cpp:



### Macros

- `#define BOOST_TEST_MODULE test_suites`

### Functions

- `BOOST_AUTO_TEST_CASE (s1t1)`  
*pvector magnitude test case*
- `BOOST_AUTO_TEST_CASE (s1t2)`  
*pvector mul test case*
- `BOOST_AUTO_TEST_CASE (s1t3)`  
*pvector div test case*
- `BOOST_AUTO_TEST_CASE (s1t4)`  
*pvector dotproduct test case*
- `BOOST_AUTO_TEST_CASE (s1t5)`  
*pvector angle between vectors test case*
- `BOOST_AUTO_TEST_CASE (s1t6)`  
*pvector get vector angle test case*
- `BOOST_AUTO_TEST_CASE (s1t7)`  
*pvector normalize test case*
- `BOOST_AUTO_TEST_CASE (s1t8)`

- pvector limit test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s1t9)
- pvector overloaded operators test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s2t1)
- point multiplication test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s2t2)
- point division test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s2t3)
- point overloaded operators test case*

### 7.47.1 Detailed Description

unit test suites

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### 7.47.2 Macro Definition Documentation

#### 7.47.2.1 BOOST\_TEST\_MODULE

```
#define BOOST_TEST_MODULE test_suites
```

Definition at line 8 of file test\_suites.cpp.

### 7.47.3 Function Documentation

#### 7.47.3.1 BOOST\_AUTO\_TEST\_CASE() [1/12]

```
BOOST_AUTO_TEST_CASE (
    s1t1 )
```

pvector magnitude test case

Definition at line 22 of file test\_suites.cpp.

```
23 {
24     pvector p1 = pvector(0, 4);
25     pvector p2 = pvector(3, 0);
26     pvector p3 = p1 + p2;
27     BOOST_CHECK(p3.magnitude() == 5);
28 }
```

### 7.47.3.2 BOOST\_AUTO\_TEST\_CASE() [2/12]

```
BOOST_AUTO_TEST_CASE (
    slt2 )
```

pvector mul test case

Definition at line 33 of file test\_suites.cpp.

```
34 {
35     pvector p1 = pvector(1, 1);
36     p1.mul(3);
37     pvector p2 = pvector(3, 3);
38     BOOST_CHECK(p1 == p2);
39 }
```

### 7.47.3.3 BOOST\_AUTO\_TEST\_CASE() [3/12]

```
BOOST_AUTO_TEST_CASE (
    slt3 )
```

pvector div test case

Definition at line 44 of file test\_suites.cpp.

```
45 {
46     pvector p1 = pvector(5, 5);
47     p1.div(5);
48     pvector p2 = pvector(1, 1);
49     BOOST_CHECK(p1 == p2);
50 }
```

### 7.47.3.4 BOOST\_AUTO\_TEST\_CASE() [4/12]

```
BOOST_AUTO_TEST_CASE (
    slt4 )
```

pvector dotproduct test case

Definition at line 55 of file test\_suites.cpp.

```
56 {
57     pvector p1 = pvector(1, 4);
58     pvector p2 = pvector(3, 2);
59     float dotProduct = p1.dotProduct(p2);
60     BOOST_CHECK(dotProduct == 11);
61 }
```

### 7.47.3.5 BOOST\_AUTO\_TEST\_CASE() [5/12]

```
BOOST_AUTO_TEST_CASE (
    slt5 )
```

pvector angle between vectors test case

Definition at line 66 of file test\_suites.cpp.

```
67 {
68     pvector p1 = pvector(10, 10);
69     pvector p2 = pvector(0, 10);
70     float angle = p1.angleBetween(p2);
71     BOOST_CHECK(angle == 45);
72 }
```

**7.47.3.6 BOOST\_AUTO\_TEST\_CASE()** [6/12]

```
BOOST_AUTO_TEST_CASE (
    slt6 )
```

pvector get vector angle test case

Definition at line 77 of file test\_suites.cpp.

```
78 {
79     pvector p1 = pvector(3, 4);
80     float angle = p1.getAngle();
81     BOOST_CHECK(angle < 53.2 && angle > 52.8);
82 }
```

**7.47.3.7 BOOST\_AUTO\_TEST\_CASE()** [7/12]

```
BOOST_AUTO_TEST_CASE (
    slt7 )
```

pvector normalize test case

Definition at line 87 of file test\_suites.cpp.

```
88 {
89     pvector p1 = pvector(2, 2);
90     p1.normalize();
91     float range = 0.01;
92     BOOST_CHECK_CLOSE_FRACTION(0.707, p1.x, range);
93     BOOST_CHECK_CLOSE_FRACTION(0.707, p1.y, range);
94 }
```

**7.47.3.8 BOOST\_AUTO\_TEST\_CASE()** [8/12]

```
BOOST_AUTO_TEST_CASE (
    slt8 )
```

pvector limit test case

Definition at line 99 of file test\_suites.cpp.

```
100 {
101     pvector p1 = pvector(2, 2);
102     p1.limit(3);
103     float range = 0.01;
104     BOOST_CHECK_CLOSE_FRACTION(2.12, p1.x, range);
105     BOOST_CHECK_CLOSE_FRACTION(2.12, p1.y, range);
106 }
```



**7.47.3.9 BOOST\_AUTO\_TEST\_CASE()** [9/12]

```
BOOST_AUTO_TEST_CASE (
    s1t9 )
```

pvector overloaded operators test case

Definition at line 111 of file test\_suites.cpp.

```
112 {
113     pvector p1 = pvector(1, 1);
114     p1 += pvector(1,1);
115     BOOST_CHECK(p1 == pvector(2,2));
116     p1 = pvector(1,1) + pvector(3,3);
117     BOOST_CHECK(p1 == pvector(4,4));
118     p1 = pvector(4,1) - pvector(3,3);
119     BOOST_CHECK(p1 == pvector(1,-2));
120     p1 = pvector(4,1) - point(3,3);
121     BOOST_CHECK(p1 == pvector(1,-2));
122     p1 = pvector(4,1) + point(3,3);
123     BOOST_CHECK(p1 == pvector(7,4));
124 }
```

**7.47.3.10 BOOST\_AUTO\_TEST\_CASE()** [10/12]

```
BOOST_AUTO_TEST_CASE (
    s2t1 )
```

point multiplication test case

Definition at line 133 of file test\_suites.cpp.

```
134 {
135     point p1 = point(1, 1);
136     p1.mul(3);
137     point p2 = point(3, 3);
138     BOOST_CHECK(p1 == p2);
139 }
```

**7.47.3.11 BOOST\_AUTO\_TEST\_CASE()** [11/12]

```
BOOST_AUTO_TEST_CASE (
    s2t2 )
```

point division test case

Definition at line 144 of file test\_suites.cpp.

```
145 {
146     point p1 = point(4, 4);
147     p1.div(4);
148     point p2 = point(1, 1);
149     BOOST_CHECK(p1 == p2);
150 }
```

**7.47.3.12 BOOST\_AUTO\_TEST\_CASE()** [12/12]

```
BOOST_AUTO_TEST_CASE (
    s2t3 )
```

point overloaded operators test case

Definition at line 155 of file test\_suites.cpp.

```
156 {
157     point p1 = point(1,1) + point(3,3);
158     BOOST_CHECK(p1 == point(4,4));
159     p1 = point(1,1) + pvector(3,3);
160     BOOST_CHECK(p1 == point(4,4));
161     pvector p2 = point(1,1) - point(3,3);
162     BOOST_CHECK(p2 == pvector(-2,-2));
163 }
```



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