

## Autonomous Steering Agents

Generated by Doxygen 1.8.17



<b>1 Intent</b>	<b>1</b>
1.1 Dependencies	1
1.2 Used Libraries and Tools	1
1.3 Resources	1
1.4 Links	1
<b>2 Todo List</b>	<b>3</b>
<b>3 Hierarchical Index</b>	<b>5</b>
3.1 Class Hierarchy	5
<b>4 Class Index</b>	<b>7</b>
4.1 Class List	7
<b>5 File Index</b>	<b>9</b>
5.1 File List	9
<b>6 Class Documentation</b>	<b>13</b>
6.1 agent Class Reference	13
6.1.1 Detailed Description	14
6.1.2 Constructor & Destructor Documentation	14
6.1.2.1 agent() [1/2]	14
6.1.2.2 agent() [2/2]	14
6.1.2.3 ~agent()	15
6.1.3 Member Function Documentation	15
6.1.3.1 draw()	15
6.1.3.2 getMass()	16
6.1.3.3 getName()	16
6.1.3.4 getTarget()	16
6.1.3.5 getVelocity()	16
6.1.3.6 setFeatures()	16
6.1.3.7 setMass()	17
6.1.3.8 setName()	17
6.1.3.9 setTarget()	18
6.1.3.10 setVelocity()	18
6.1.3.11 updatePosition()	18
6.1.4 Member Data Documentation	19
6.1.4.1 acceleration	19
6.1.4.2 arrive	19
6.1.4.3 desiredVelocity	19
6.1.4.4 force	20
6.1.4.5 id	20
6.1.4.6 maxForce	20
6.1.4.7 maxSpeed	20

6.1.4.8 position	20
6.1.4.9 r	21
6.1.4.10 steering	21
6.1.4.11 targetPoint	21
6.2 color Class Reference	21
6.2.1 Detailed Description	22
6.2.2 Constructor & Destructor Documentation	22
6.2.2.1 color() [1/2]	22
6.2.2.2 color() [2/2]	22
6.2.3 Member Function Documentation	23
6.2.3.1 getColor()	23
6.2.4 Member Data Documentation	23
6.2.4.1 B	23
6.2.4.2 G	24
6.2.4.3 R	24
6.3 entity Class Reference	24
6.3.1 Detailed Description	25
6.3.2 Constructor & Destructor Documentation	25
6.3.2.1 entity()	25
6.3.3 Member Function Documentation	25
6.3.3.1 draw()	25
6.3.3.2 getColor()	25
6.3.3.3 getId()	26
6.3.3.4 getName()	26
6.3.3.5 setColor()	26
6.3.3.6 setId()	26
6.3.3.7 setName()	27
6.4 evade Class Reference	27
6.4.1 Detailed Description	27
6.4.2 Constructor & Destructor Documentation	28
6.4.2.1 evade()	28
6.4.3 Member Function Documentation	28
6.4.3.1 loop()	28
6.5 flee Class Reference	28
6.5.1 Detailed Description	29
6.5.2 Constructor & Destructor Documentation	29
6.5.2.1 flee()	29
6.5.3 Member Function Documentation	29
6.5.3.1 loop()	29
6.6 flock Class Reference	30
6.6.1 Detailed Description	30
6.6.2 Constructor & Destructor Documentation	30

6.6.2.1 flock()	30
6.6.3 Member Function Documentation	30
6.6.3.1 loop()	31
6.7 flowField Class Reference	31
6.7.1 Detailed Description	31
6.7.2 Constructor & Destructor Documentation	31
6.7.2.1 flowField() [1/2]	32
6.7.2.2 flowField() [2/2]	32
6.7.3 Member Function Documentation	32
6.7.3.1 getField()	32
6.8 graphics Class Reference	33
6.8.1 Detailed Description	34
6.8.2 Member Function Documentation	34
6.8.2.1 drawAgent()	34
6.8.2.2 drawCircle()	35
6.8.2.3 drawLine()	35
6.8.2.4 drawPath()	36
6.8.2.5 drawPoint()	36
6.8.2.6 drawText()	36
6.8.2.7 forceInScreen()	37
6.8.2.8 getMousePosition()	37
6.8.2.9 handleKeypress()	38
6.8.2.10 handleResize()	38
6.8.2.11 initGraphics()	38
6.8.2.12 mouseButton()	40
6.8.2.13 mouseMove()	40
6.8.2.14 refreshScene()	41
6.8.2.15 timerEvent()	41
6.8.3 Member Data Documentation	41
6.8.3.1 target_x	42
6.8.3.2 target_y	42
6.9 leaderFollower Class Reference	42
6.9.1 Detailed Description	43
6.9.2 Constructor & Destructor Documentation	43
6.9.2.1 leaderFollower()	43
6.9.3 Member Function Documentation	43
6.9.3.1 loop()	43
6.9.4 Member Data Documentation	44
6.9.4.1 leaderAngle	44
6.9.4.2 leaderPosition	45
6.9.4.3 leaderVelocity	45
6.10 mouseFollower Class Reference	45

6.10.1 Detailed Description	45
6.10.2 Constructor & Destructor Documentation	45
6.10.2.1 mouseFollower()	46
6.10.3 Member Function Documentation	46
6.10.3.1 loop()	46
6.11 obstacle Class Reference	46
6.11.1 Detailed Description	47
6.11.2 Constructor & Destructor Documentation	47
6.11.2.1 obstacle() [1/2]	47
6.11.2.2 obstacle() [2/2]	47
6.11.3 Member Function Documentation	48
6.11.3.1 draw()	48
6.11.3.2 getCenter()	48
6.11.3.3 getRadius()	49
6.11.3.4 setCenter()	49
6.11.3.5 setRadius()	49
6.12 obstacleAvoidance Class Reference	49
6.12.1 Detailed Description	50
6.12.2 Constructor & Destructor Documentation	50
6.12.2.1 obstacleAvoidance()	50
6.12.3 Member Function Documentation	50
6.12.3.1 createObstacle()	50
6.12.3.2 loop()	51
6.12.4 Member Data Documentation	51
6.12.4.1 obstacles	51
6.13 path Class Reference	52
6.13.1 Detailed Description	52
6.13.2 Constructor & Destructor Documentation	52
6.13.2.1 path() [1/2]	52
6.13.2.2 path() [2/2]	52
6.13.3 Member Function Documentation	53
6.13.3.1 addPoint()	53
6.13.3.2 draw()	53
6.13.3.3 getPathWidth()	54
6.13.3.4 setPathWidth()	54
6.13.4 Member Data Documentation	54
6.13.4.1 points	54
6.14 pathFollower Class Reference	54
6.14.1 Detailed Description	55
6.14.2 Constructor & Destructor Documentation	55
6.14.2.1 pathFollower()	55
6.14.3 Member Function Documentation	55

6.14.3.1 createPath()	55
6.14.3.2 loop()	56
6.14.4 Member Data Documentation	56
6.14.4.1 myPath	56
6.15 point Class Reference	57
6.15.1 Detailed Description	57
6.15.2 Constructor & Destructor Documentation	57
6.15.2.1 point() [1/2]	58
6.15.2.2 point() [2/2]	58
6.15.3 Member Function Documentation	58
6.15.3.1 difference()	58
6.15.3.2 div()	59
6.15.3.3 getNormalPoint()	59
6.15.3.4 mul()	60
6.15.3.5 operator+() [1/2]	60
6.15.3.6 operator+() [2/2]	61
6.15.3.7 operator-()	61
6.15.3.8 operator==()	61
6.15.3.9 print()	62
6.15.3.10 rotate()	62
6.15.3.11 rotateByAngleAboutPoint()	63
6.15.4 Member Data Documentation	63
6.15.4.1 x	63
6.15.4.2 y	63
6.16 prison Class Reference	64
6.16.1 Detailed Description	64
6.16.2 Constructor & Destructor Documentation	64
6.16.2.1 prison()	64
6.16.3 Member Function Documentation	64
6.16.3.1 loop()	65
6.17 pursuit Class Reference	65
6.17.1 Detailed Description	65
6.17.2 Constructor & Destructor Documentation	66
6.17.2.1 pursuit()	66
6.17.3 Member Function Documentation	66
6.17.3.1 loop()	66
6.18 pvector Class Reference	66
6.18.1 Detailed Description	67
6.18.2 Constructor & Destructor Documentation	68
6.18.2.1 pvector() [1/2]	68
6.18.2.2 pvector() [2/2]	68
6.18.3 Member Function Documentation	68

6.18.3.1 add()	69
6.18.3.2 angleBetween()	70
6.18.3.3 div()	70
6.18.3.4 dotProduct()	71
6.18.3.5 getAngle()	71
6.18.3.6 limit()	71
6.18.3.7 magnitude()	72
6.18.3.8 mul()	72
6.18.3.9 normalize()	72
6.18.3.10 operator+() [1/2]	73
6.18.3.11 operator+() [2/2]	73
6.18.3.12 operator+=()	74
6.18.3.13 operator-() [1/2]	74
6.18.3.14 operator-() [2/2]	75
6.18.3.15 operator==()	75
6.18.3.16 print()	76
6.18.4 Member Data Documentation	76
6.18.4.1 x	76
6.18.4.2 y	76
6.19 random Class Reference	76
6.19.1 Detailed Description	77
6.19.2 Member Function Documentation	77
6.19.2.1 createRandomArray()	77
6.20 scenario Class Reference	77
6.20.1 Detailed Description	78
6.20.2 Constructor & Destructor Documentation	78
6.20.2.1 scenario()	79
6.20.3 Member Function Documentation	79
6.20.3.1 createRandomAgents()	79
6.20.3.2 createStaticAgents()	79
6.20.3.3 createTroop()	80
6.20.3.4 initGL()	81
6.20.3.5 refresh()	81
6.20.4 Member Data Documentation	81
6.20.4.1 agents	81
6.20.4.2 behavior	82
6.20.4.3 callback	82
6.20.4.4 name	82
6.20.4.5 view	82
6.21 steeringBehavior Class Reference	83
6.21.1 Detailed Description	83
6.21.2 Member Function Documentation	83



6.21.2.1 align()	83
6.21.2.2 avoid()	84
6.21.2.3 cohesion()	85
6.21.2.4 evade()	85
6.21.2.5 flee()	86
6.21.2.6 inFlowField()	87
6.21.2.7 pursuit()	87
6.21.2.8 seek()	88
6.21.2.9 separation()	89
6.21.2.10 stayInArea()	89
6.21.2.11 stayInPath()	90
6.21.2.12 wander()	91
6.22 wander Class Reference	91
6.22.1 Detailed Description	92
6.22.2 Constructor & Destructor Documentation	92
6.22.2.1 wander()	92
6.22.3 Member Function Documentation	92
6.22.3.1 loop()	92
6.23 windy Class Reference	93
6.23.1 Detailed Description	93
6.23.2 Constructor & Destructor Documentation	93
6.23.2.1 windy()	93
6.23.3 Member Function Documentation	94
6.23.3.1 loop()	94
6.23.4 Member Data Documentation	94
6.23.4.1 flow	94
<b>7 File Documentation</b>	<b>95</b>
7.1 /home/user/Desktop/mmm/autonomousSteeringAgents/agent.d File Reference	96
7.2 /home/user/Desktop/mmm/autonomousSteeringAgents/color.d File Reference	96
7.3 uml/activity_diagram/todo.txt File Reference	96
7.4 uml/state_diagram/todo.txt File Reference	96
7.5 uml/use_case_diagram/todo.txt File Reference	96
7.6 /home/user/Desktop/mmm/autonomousSteeringAgents/entity.d File Reference	96
7.7 /home/user/Desktop/mmm/autonomousSteeringAgents/evade.d File Reference	96
7.8 /home/user/Desktop/mmm/autonomousSteeringAgents/flee.d File Reference	96
7.9 /home/user/Desktop/mmm/autonomousSteeringAgents/flock.d File Reference	96
7.10 /home/user/Desktop/mmm/autonomousSteeringAgents/flowField.d File Reference	96
7.11 /home/user/Desktop/mmm/autonomousSteeringAgents/graphics.d File Reference	96
7.12 /home/user/Desktop/mmm/autonomousSteeringAgents/include/agent.h File Reference	96
7.12.1 Detailed Description	97
7.13 /home/user/Desktop/mmm/autonomousSteeringAgents/include/color.h File Reference	98

7.13.1 Detailed Description	99
7.13.2 Macro Definition Documentation	99
7.13.2.1 BLACK	99
7.13.2.2 BLUE	99
7.13.2.3 CYAN	99
7.13.2.4 GREEN	99
7.13.2.5 MAGENDA	100
7.13.2.6 RED	100
7.13.2.7 WHITE	100
7.13.2.8 YELLOW	100
7.14 /home/user/Desktop/mmm/autonomousSteeringAgents/include/entity.h File Reference	100
7.15 /home/user/Desktop/mmm/autonomousSteeringAgents/include/evade.h File Reference	101
7.15.1 Detailed Description	102
7.16 /home/user/Desktop/mmm/autonomousSteeringAgents/include/flee.h File Reference	102
7.16.1 Detailed Description	103
7.17 /home/user/Desktop/mmm/autonomousSteeringAgents/include/flock.h File Reference	104
7.17.1 Detailed Description	105
7.18 /home/user/Desktop/mmm/autonomousSteeringAgents/include/flowField.h File Reference	105
7.18.1 Detailed Description	106
7.18.2 Macro Definition Documentation	107
7.18.2.1 FIELD_HEIGHT	107
7.18.2.2 FIELD_WIDTH	107
7.18.2.3 GRAVITY	107
7.18.2.4 WIND_WEST	107
7.19 /home/user/Desktop/mmm/autonomousSteeringAgents/include/graphics.h File Reference	108
7.19.1 Detailed Description	109
7.19.2 Macro Definition Documentation	109
7.19.2.1 ESC	109
7.19.2.2 HEIGHT	109
7.19.2.3 PI	109
7.19.2.4 WIDTH	109
7.20 /home/user/Desktop/mmm/autonomousSteeringAgents/include/leaderFollower.h File Reference	110
7.20.1 Detailed Description	111
7.21 /home/user/Desktop/mmm/autonomousSteeringAgents/include/mouseFollower.h File Reference	111
7.21.1 Detailed Description	112
7.22 /home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacle.h File Reference	112
7.22.1 Detailed Description	113
7.23 /home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacleAvoidance.h File Reference	114
7.23.1 Detailed Description	115
7.24 /home/user/Desktop/mmm/autonomousSteeringAgents/include/path.h File Reference	115
7.24.1 Detailed Description	116
7.25 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pathFollower.h File Reference	116

7.25.1 Detailed Description . . . . .	117
7.26 /home/user/Desktop/mmm/autonomousSteeringAgents/include/point.h File Reference . . . . .	118
7.26.1 Detailed Description . . . . .	119
7.27 /home/user/Desktop/mmm/autonomousSteeringAgents/include/prison.h File Reference . . . . .	119
7.27.1 Detailed Description . . . . .	120
7.28 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pursuit.h File Reference . . . . .	120
7.28.1 Detailed Description . . . . .	121
7.29 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pvector.h File Reference . . . . .	122
7.29.1 Detailed Description . . . . .	123
7.29.2 Macro Definition Documentation . . . . .	123
7.29.2.1 PI . . . . .	123
7.30 /home/user/Desktop/mmm/autonomousSteeringAgents/include/random.h File Reference . . . . .	123
7.30.1 Detailed Description . . . . .	124
7.31 /home/user/Desktop/mmm/autonomousSteeringAgents/include/scenario.h File Reference . . . . .	124
7.31.1 Detailed Description . . . . .	125
7.31.2 Enumeration Type Documentation . . . . .	125
7.31.2.1 types . . . . .	125
7.32 /home/user/Desktop/mmm/autonomousSteeringAgents/include/steeringBehavior.h File Reference . . . . .	125
7.32.1 Detailed Description . . . . .	127
7.32.2 Macro Definition Documentation . . . . .	127
7.32.2.1 AVOID_OBSTACLE . . . . .	127
7.32.2.2 CIRCLE_DISTANCE . . . . .	127
7.32.2.3 CIRCLE_RADIUS . . . . .	127
7.32.2.4 EVADE . . . . .	127
7.32.2.5 FLEE . . . . .	128
7.32.2.6 FLOCK . . . . .	128
7.32.2.7 FOLLOW_MOUSE . . . . .	128
7.32.2.8 IN_FLOW_FIELD . . . . .	128
7.32.2.9 LEADER_FOLLOWER . . . . .	128
7.32.2.10 PURSUIT . . . . .	128
7.32.2.11 STAY_IN_FIELD . . . . .	129
7.32.2.12 STAY_IN_PATH . . . . .	129
7.32.2.13 WANDER . . . . .	129
7.33 /home/user/Desktop/mmm/autonomousSteeringAgents/include/wander.h File Reference . . . . .	129
7.33.1 Detailed Description . . . . .	130
7.34 /home/user/Desktop/mmm/autonomousSteeringAgents/include/windy.h File Reference . . . . .	131
7.34.1 Detailed Description . . . . .	132
7.35 /home/user/Desktop/mmm/autonomousSteeringAgents/leaderFollower.d File Reference . . . . .	132
7.36 /home/user/Desktop/mmm/autonomousSteeringAgents/main.cpp File Reference . . . . .	132
7.36.1 Detailed Description . . . . .	133
7.36.2 Function Documentation . . . . .	133
7.36.2.1 main() . . . . .	134

7.36.2.2 menu()	134
7.36.3 Variable Documentation	135
7.36.3.1 mode	135
7.37 /home/user/Desktop/mmm/autonomousSteeringAgents/main.d File Reference	137
7.38 /home/user/Desktop/mmm/autonomousSteeringAgents/mouseFollower.d File Reference	137
7.39 /home/user/Desktop/mmm/autonomousSteeringAgents/obstacle.d File Reference	137
7.40 /home/user/Desktop/mmm/autonomousSteeringAgents/obstacleAvoidance.d File Reference	137
7.41 /home/user/Desktop/mmm/autonomousSteeringAgents/path.d File Reference	137
7.42 /home/user/Desktop/mmm/autonomousSteeringAgents/pathFollower.d File Reference	137
7.43 /home/user/Desktop/mmm/autonomousSteeringAgents/point.d File Reference	137
7.44 /home/user/Desktop/mmm/autonomousSteeringAgents/prison.d File Reference	137
7.45 /home/user/Desktop/mmm/autonomousSteeringAgents/pursuit.d File Reference	137
7.46 /home/user/Desktop/mmm/autonomousSteeringAgents/pvector.d File Reference	137
7.47 /home/user/Desktop/mmm/autonomousSteeringAgents/random.d File Reference	137
7.48 /home/user/Desktop/mmm/autonomousSteeringAgents/README.md File Reference	137
7.49 /home/user/Desktop/mmm/autonomousSteeringAgents/scenario.d File Reference	137
7.50 /home/user/Desktop/mmm/autonomousSteeringAgents/src/agent.cpp File Reference	137
7.50.1 Detailed Description	138
7.51 /home/user/Desktop/mmm/autonomousSteeringAgents/src/color.cpp File Reference	138
7.51.1 Detailed Description	139
7.52 /home/user/Desktop/mmm/autonomousSteeringAgents/src/entity.cpp File Reference	139
7.52.1 Detailed Description	140
7.53 /home/user/Desktop/mmm/autonomousSteeringAgents/src/evade.cpp File Reference	140
7.53.1 Detailed Description	141
7.54 /home/user/Desktop/mmm/autonomousSteeringAgents/src/flee.cpp File Reference	141
7.54.1 Detailed Description	142
7.55 /home/user/Desktop/mmm/autonomousSteeringAgents/src/flock.cpp File Reference	142
7.55.1 Detailed Description	143
7.56 /home/user/Desktop/mmm/autonomousSteeringAgents/src/flowField.cpp File Reference	143
7.56.1 Detailed Description	144
7.57 /home/user/Desktop/mmm/autonomousSteeringAgents/src/graphics.cpp File Reference	144
7.57.1 Detailed Description	145
7.58 /home/user/Desktop/mmm/autonomousSteeringAgents/src/leaderFollower.cpp File Reference	145
7.58.1 Detailed Description	146
7.58.2 Variable Documentation	146
7.58.2.1 mainTarget	147
7.59 /home/user/Desktop/mmm/autonomousSteeringAgents/src/mouseFollower.cpp File Reference	147
7.59.1 Detailed Description	148
7.60 /home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacle.cpp File Reference	148
7.60.1 Detailed Description	149
7.61 /home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacleAvoidance.cpp File Reference	149
7.61.1 Detailed Description	150

7.62 /home/user/Desktop/mmm/autonomousSteeringAgents/src/path.cpp File Reference . . . . .	150
7.62.1 Detailed Description . . . . .	151
7.63 /home/user/Desktop/mmm/autonomousSteeringAgents/src/pathFollower.cpp File Reference . . . . .	151
7.63.1 Detailed Description . . . . .	152
7.64 /home/user/Desktop/mmm/autonomousSteeringAgents/src/point.cpp File Reference . . . . .	152
7.64.1 Detailed Description . . . . .	153
7.65 /home/user/Desktop/mmm/autonomousSteeringAgents/src/prison.cpp File Reference . . . . .	153
7.65.1 Detailed Description . . . . .	154
7.65.2 Macro Definition Documentation . . . . .	154
7.65.2.1 DISTANCE . . . . .	154
7.65.2.2 WALL . . . . .	154
7.66 /home/user/Desktop/mmm/autonomousSteeringAgents/src/pursuit.cpp File Reference . . . . .	155
7.66.1 Detailed Description . . . . .	155
7.67 /home/user/Desktop/mmm/autonomousSteeringAgents/src/pvector.cpp File Reference . . . . .	156
7.67.1 Detailed Description . . . . .	156
7.68 /home/user/Desktop/mmm/autonomousSteeringAgents/src/random.cpp File Reference . . . . .	157
7.68.1 Detailed Description . . . . .	157
7.69 /home/user/Desktop/mmm/autonomousSteeringAgents/src/scenario.cpp File Reference . . . . .	157
7.69.1 Detailed Description . . . . .	158
7.69.2 Macro Definition Documentation . . . . .	158
7.69.2.1 MAX_NUMBER_OF_AGENTS . . . . .	158
7.70 /home/user/Desktop/mmm/autonomousSteeringAgents/src/steeringBehavior.cpp File Reference . . . . .	159
7.70.1 Detailed Description . . . . .	159
7.71 /home/user/Desktop/mmm/autonomousSteeringAgents/src/wander.cpp File Reference . . . . .	160
7.71.1 Detailed Description . . . . .	160
7.72 /home/user/Desktop/mmm/autonomousSteeringAgents/src/windy.cpp File Reference . . . . .	161
7.72.1 Detailed Description . . . . .	161
7.73 /home/user/Desktop/mmm/autonomousSteeringAgents/steeringBehavior.d File Reference . . . . .	162
7.74 /home/user/Desktop/mmm/autonomousSteeringAgents/test/unit_test/test_suites.cpp File Reference . . . . .	162
7.74.1 Detailed Description . . . . .	163
7.74.2 Macro Definition Documentation . . . . .	163
7.74.2.1 BOOST_TEST_MODULE . . . . .	163
7.74.3 Function Documentation . . . . .	163
7.74.3.1 BOOST_AUTO_TEST_CASE() [1/12] . . . . .	163
7.74.3.2 BOOST_AUTO_TEST_CASE() [2/12] . . . . .	164
7.74.3.3 BOOST_AUTO_TEST_CASE() [3/12] . . . . .	164
7.74.3.4 BOOST_AUTO_TEST_CASE() [4/12] . . . . .	164
7.74.3.5 BOOST_AUTO_TEST_CASE() [5/12] . . . . .	164
7.74.3.6 BOOST_AUTO_TEST_CASE() [6/12] . . . . .	165
7.74.3.7 BOOST_AUTO_TEST_CASE() [7/12] . . . . .	165
7.74.3.8 BOOST_AUTO_TEST_CASE() [8/12] . . . . .	165
7.74.3.9 BOOST_AUTO_TEST_CASE() [9/12] . . . . .	166

7.74.3.10 BOOST_AUTO_TEST_CASE() [10/12]	166
7.74.3.11 BOOST_AUTO_TEST_CASE() [11/12]	166
7.74.3.12 BOOST_AUTO_TEST_CASE() [12/12]	167
7.75 /home/user/Desktop/mmm/autonomousSteeringAgents/wander.d File Reference	167
7.76 /home/user/Desktop/mmm/autonomousSteeringAgents/windy.d File Reference	167
<b>Index</b>	<b>169</b>

# Chapter 1

## Intent

Implementing smart agents using Craig Reynolds's autonomous steering behaviors

### 1.1 Dependencies

```
$sudo apt-get install libglu1-mesa-dev freeglut3-dev mesa-common-dev
```

```
$sudo apt-get install libboost-all-dev
```

### 1.2 Used Libraries and Tools

UML : plantuml documentation : doxygen Graphics : openGL static analysis : cppcheck unit test : boost/test

### 1.3 Resources

Dan Schiffmann : Nature of Code

Fernando Bevilacqua : Understanding Steering Behaviors

### 1.4 Links

<https://videotutorialsrock.com/index.php>

<https://www.opengl.org/resources/libraries/glut/spec3/node1.html>

<https://learnopengl.com/Getting-started/Coordinate-Systems>





## Chapter 2

# Todo List

Member `wander::wander ()`

business logic will be changed



## Chapter 3

# Hierarchical Index

### 3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

color . . . . .	21
entity . . . . .	24
agent . . . . .	13
obstacle . . . . .	46
path . . . . .	52
flowField . . . . .	31
graphics . . . . .	33
point . . . . .	57
pvector . . . . .	66
random . . . . .	76
scenario . . . . .	77
evade . . . . .	27
flee . . . . .	28
flock . . . . .	30
leaderFollower . . . . .	42
mouseFollower . . . . .	45
obstacleAvoidance . . . . .	49
pathFollower . . . . .	54
prison . . . . .	64
pursuit . . . . .	65
wander . . . . .	91
windy . . . . .	93
steeringBehavior . . . . .	83



## Chapter 4

# Class Index

### 4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

agent	13
color	21
entity	24
evade	27
flee	28
flock	30
flowField	31
graphics	33
leaderFollower	42
mouseFollower	45
obstacle	46
obstacleAvoidance	49
path	52
pathFollower	54
point	57
prison	64
pursuit	65
pvector	66
random	76
scenario	77
steeringBehavior	83
wander	91
windy	93



## Chapter 5

# File Index

### 5.1 File List

Here is a list of all files with brief descriptions:

/home/user/Desktop/mmm/autonomousSteeringAgents/agent.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/color.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/entity.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/evade.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/flee.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/flock.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/flowField.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/graphics.d . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/leaderFollower.d . . . . .	132
/home/user/Desktop/mmm/autonomousSteeringAgents/main.cpp . . . . .	
Client code . . . . .	132
/home/user/Desktop/mmm/autonomousSteeringAgents/main.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/mouseFollower.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/obstacle.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/obstacleAvoidance.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/path.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/pathFollower.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/point.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/prison.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/pursuit.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/pvector.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/random.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/scenario.d . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/steeringBehavior.d . . . . .	162
/home/user/Desktop/mmm/autonomousSteeringAgents/wander.d . . . . .	167
/home/user/Desktop/mmm/autonomousSteeringAgents/windy.d . . . . .	167
/home/user/Desktop/mmm/autonomousSteeringAgents/include/agent.h . . . . .	
Agent class defines all agent specifications . . . . .	96
/home/user/Desktop/mmm/autonomousSteeringAgents/include/color.h . . . . .	
Color class used for agent, path, wall etc. color . . . . .	98
/home/user/Desktop/mmm/autonomousSteeringAgents/include/entity.h . . . . .	100
/home/user/Desktop/mmm/autonomousSteeringAgents/include/evade.h . . . . .	
Evade class inherited from scenario class . . . . .	101
/home/user/Desktop/mmm/autonomousSteeringAgents/include/flee.h . . . . .	
Agents flee from mouse scenario . . . . .	102

/home/user/Desktop/mmm/autonomousSteeringAgents/include/flock.h	
Flocking agents scenario . . . . .	104
/home/user/Desktop/mmm/autonomousSteeringAgents/include/flowField.h	
FlowField class, screen can be filled with a force for each pixel . . . . .	105
/home/user/Desktop/mmm/autonomousSteeringAgents/include/graphics.h	
Graphics class, drives openGL . . . . .	108
/home/user/Desktop/mmm/autonomousSteeringAgents/include/leaderFollower.h	
Agents follow leader scenario . . . . .	110
/home/user/Desktop/mmm/autonomousSteeringAgents/include/mouseFollower.h	
Agents follow mouse scenario . . . . .	111
/home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacle.h	
Circular obstacles for agent avoidance behaviors . . . . .	112
/home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacleAvoidance.h	
Agents avoid from obstacles scenario . . . . .	114
/home/user/Desktop/mmm/autonomousSteeringAgents/include/path.h	
Path class used for path following steering behaviors . . . . .	115
/home/user/Desktop/mmm/autonomousSteeringAgents/include/pathFollower.h	
Path following scenario . . . . .	116
/home/user/Desktop/mmm/autonomousSteeringAgents/include/point.h	
Point class used for point operations . . . . .	118
/home/user/Desktop/mmm/autonomousSteeringAgents/include/prison.h	
Agents cant escape from field scenario . . . . .	119
/home/user/Desktop/mmm/autonomousSteeringAgents/include/pursuit.h	
One agent pursue other one scenario . . . . .	120
/home/user/Desktop/mmm/autonomousSteeringAgents/include/pvector.h	
Pvector class used for 2D vector operations . . . . .	122
/home/user/Desktop/mmm/autonomousSteeringAgents/include/random.h	
Utility class for random operations . . . . .	123
/home/user/Desktop/mmm/autonomousSteeringAgents/include/scenario.h	
Base class for all scenarios . . . . .	124
/home/user/Desktop/mmm/autonomousSteeringAgents/include/steeringBehavior.h	
Functions for autonomous steering behaviors . . . . .	125
/home/user/Desktop/mmm/autonomousSteeringAgents/include/wander.h	
Random wandering agents scenario . . . . .	129
/home/user/Desktop/mmm/autonomousSteeringAgents/include/windy.h	
Windy air scenario . . . . .	131
/home/user/Desktop/mmm/autonomousSteeringAgents/src/agent.cpp	
Implementation of the agent class . . . . .	137
/home/user/Desktop/mmm/autonomousSteeringAgents/src/color.cpp	
Color class implementation . . . . .	138
/home/user/Desktop/mmm/autonomousSteeringAgents/src/entity.cpp	
Entity class implementation . . . . .	139
/home/user/Desktop/mmm/autonomousSteeringAgents/src/evade.cpp	
Evade class implementation . . . . .	140
/home/user/Desktop/mmm/autonomousSteeringAgents/src/flee.cpp	
Flee class implementation . . . . .	141
/home/user/Desktop/mmm/autonomousSteeringAgents/src/flock.cpp	
Flock class implementation . . . . .	142
/home/user/Desktop/mmm/autonomousSteeringAgents/src/flowField.cpp	
FlowField class implementation . . . . .	143
/home/user/Desktop/mmm/autonomousSteeringAgents/src/graphics.cpp	
Graphics class implementation . . . . .	144
/home/user/Desktop/mmm/autonomousSteeringAgents/src/leaderFollower.cpp	
LeaderFollower class implementation . . . . .	145
/home/user/Desktop/mmm/autonomousSteeringAgents/src/mouseFollower.cpp	
MouseFollower class implementation . . . . .	147
/home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacle.cpp	
Obstacle class implementation . . . . .	148



/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">obstacleAvoidance.cpp</a>	
ObstacleAvoidance class implementation . . . . .	149
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">path.cpp</a>	
Path class implementation . . . . .	150
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">pathFollower.cpp</a>	
PathFollower class implementation . . . . .	151
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">point.cpp</a>	
Point class implementation file . . . . .	152
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">prison.cpp</a>	
Prison class implementation . . . . .	153
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">pursuit.cpp</a>	
Prison class implementation . . . . .	155
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">pvector.cpp</a>	
Pvector class implementation . . . . .	156
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">random.cpp</a>	
Utility class for random operations . . . . .	157
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">scenario.cpp</a>	
Scenario base class implementation . . . . .	157
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">steeringBehavior.cpp</a>	
Implementation of autonomous steering behaviors . . . . .	159
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">wander.cpp</a>	
Wander class implementation . . . . .	160
/home/user/Desktop/mmm/autonomousSteeringAgents/src/ <a href="#">windy.cpp</a>	
Windy class implementation . . . . .	161
/home/user/Desktop/mmm/autonomousSteeringAgents/test/unit_test/ <a href="#">test_suites.cpp</a>	
Unit test suites . . . . .	162



## Chapter 6

# Class Documentation

### 6.1 agent Class Reference

```
#include <agent.h>
```

#### Public Member Functions

- `agent ()`  
*default constructor.*
- `agent (float x, float y)`  
*constructor.*
- `~agent ()`  
*destructor*
- `void updatePosition (bool arrive)`  
*position update calculations*
- `void setFeatures (float s, float f, float r, float m)`  
*initialize the agent attributes*
- `string getName ()`  
*name attribute getter*
- `void setName (string n)`  
*name attribute setter*
- `float getMass ()`  
*mass attribute getter*
- `void setMass (float m)`  
*mass attribute setter*
- `void draw (graphics view) override`  
*agent drawing*
- `pvector getVelocity ()`  
*velocity attribute getter*
- `void setVelocity (pvector v)`  
*velocity attribute setter*
- `point getTarget ()`  
*target attribute getter*
- `void setTarget (point t)`  
*target attribute setter*

## Public Attributes

- float [maxSpeed](#)  
*maximum speed of the agent*
- [point position](#)  
*position of the agent*
- float [maxForce](#)  
*maximum force of the agent*
- [pvector steering](#)  
*steering force of the apply*
- [pvector force](#)  
*force to apply to the agent*
- [pvector acceleration](#)  
*acceleration of the agent*
- [pvector desiredVelocity](#)  
*desired velocity of the agent*
- float [r](#)  
*radius for arrive behavior*
- int [id](#)  
*id of the agent*
- bool [arrive](#) = false  
*has arriving behavior or not*
- [point targetPoint](#)

### 6.1.1 Detailed Description

Definition at line 21 of file agent.h.

### 6.1.2 Constructor & Destructor Documentation

#### 6.1.2.1 [agent\(\)](#) [1/2]

```
agent::agent ( )
```

default constructor.

See also

[agent\(float x, float y\)](#)

Definition at line 16 of file agent.cpp.

```
17 {
18
19 }
```

#### 6.1.2.2 [agent\(\)](#) [2/2]

```
agent::agent (
    float x,
    float y )
```

constructor.

## Parameters

<i>x</i>	position x of the agent
<i>y</i>	position y of the agent

## See also

[agent\(\)](#)

Definition at line 37 of file agent.cpp.

```

38 {
39     position      = point(x, y);
40     velocity      = pvector(0.6, 0.0);
41     acceleration  = pvector(0.0, 0.0);
42     steering      = pvector(0.0, 0.0);
43     desiredVelocity = pvector(0.0, 0.0);
44     force         = pvector(0.0, 0.0);
45     targetPoint   = point(0.0, 0.0);
46     setColor(RED);
47 }
```

## 6.1.2.3 ~agent()

```
agent::~agent ( )
```

destructor

Definition at line 96 of file agent.cpp.

```

97 {
98
99 }
```

## 6.1.3 Member Function Documentation

## 6.1.3.1 draw()

```
void agent::draw (
    graphics view ) [override], [virtual]
```

agent drawing

## Parameters

<i>view</i>	graphics to draw
-------------	------------------

Implements [entity](#).

Definition at line 101 of file agent.cpp.

```
101         {
102     this->updatePosition(this->arrive);
103     view.drawAgent(*this);
104 }
```

#### 6.1.3.2 getMass()

```
float agent::getMass ( )
```

mass attribute getter

Definition at line 29 of file agent.cpp.

```
29     {
30     return mass;
31 }
```

#### 6.1.3.3 getName()

```
string agent::getName ( )
```

name attribute getter

Definition at line 21 of file agent.cpp.

```
21     {
22     return name;
23 }
```

#### 6.1.3.4 getTarget()

```
point agent::getTarget ( )
```

target attribute getter

Definition at line 57 of file agent.cpp.

```
57     {
58     return targetPoint;
59 }
```

#### 6.1.3.5 getVelocity()

```
pvector agent::getVelocity ( )
```

velocity attribute getter

Definition at line 49 of file agent.cpp.

```
49     {
50     return velocity;
51 }
```

#### 6.1.3.6 setFeatures()

```
void agent::setFeatures (
    float s,
    float f,
    float r,
    float m )
```

initialize the agent attributes

**Parameters**

<i>s</i>	maximum velocity
<i>f</i>	maximum force
<i>r</i>	radius for arriving behavior
<i>m</i>	mass

Definition at line 88 of file agent.cpp.

```
89 {  
90     this->maxSpeed = s;  
91     this->maxForce = f;  
92     this->r = r;  
93     this->mass = m;  
94 }
```

**6.1.3.7 setMass()**

```
void agent::setMass (  
    float m )
```

mass attribute setter

**Parameters**

<i>m</i>	set value
----------	-----------

Definition at line 33 of file agent.cpp.

```
33     {  
34         mass = m;  
35     }
```

**6.1.3.8 setName()**

```
void agent::setName (  
    string n )
```

name attribute setter

**Parameters**

<i>n</i>	set value
----------	-----------

Definition at line 25 of file agent.cpp.

```
25     {  
26         name = n;  
27     }
```

### 6.1.3.9 setTarget()

```
void agent::setTarget (
    point t )
```

target attribute setter

#### Parameters

<i>t</i>	set value
----------	-----------

Definition at line 61 of file agent.cpp.

```
61     {
62         targetPoint = t;
63     }
```

### 6.1.3.10 setVelocity()

```
void agent::setVelocity (
    pvector v )
```

velocity attribute setter

#### Parameters

<i>v</i>	set value
----------	-----------

Definition at line 53 of file agent.cpp.

```
53     {
54         velocity = v;
55     }
```

### 6.1.3.11 updatePosition()

```
void agent::updatePosition (
    bool arrive )
```

position update calculations

#### Parameters

<i>arrive</i>	has arriving behavior or not
---------------	------------------------------

Definition at line 66 of file agent.cpp.

```
67 {
68     force.limit(maxForce);
69     acceleration = force;
70     velocity += acceleration;
71 }
```



```
72     //arriving behavior implementation
73     if(arrive == true){
74         pvector diff = targetPoint - position;
75         if(diff.magnitude() > r)
76             velocity.limit(maxSpeed);
77         else
78             velocity.limit(maxSpeed * diff.magnitude() / r);
79     }
80     else{
81         velocity.limit(maxSpeed);
82     }
83
84     position = position + velocity;
85     force = pvector(0,0);
86 }
```

## 6.1.4 Member Data Documentation

### 6.1.4.1 acceleration

`pvector agent::acceleration`

acceleration of the agent

Definition at line 135 of file agent.h.

### 6.1.4.2 arrive

`bool agent::arrive = false`

has arriving behavior or not

Definition at line 155 of file agent.h.

### 6.1.4.3 desiredVelocity

`pvector agent::desiredVelocity`

desired velocity of the agent

Definition at line 140 of file agent.h.

#### 6.1.4.4 force

```
pvector agent::force
```

force to apply to the agent

Definition at line 130 of file agent.h.

#### 6.1.4.5 id

```
int agent::id
```

id of the agent

Definition at line 150 of file agent.h.

#### 6.1.4.6 maxForce

```
float agent::maxForce
```

maximum force of the agent

Definition at line 120 of file agent.h.

#### 6.1.4.7 maxSpeed

```
float agent::maxSpeed
```

maximum speed of the agent

Definition at line 110 of file agent.h.

#### 6.1.4.8 position

```
point agent::position
```

position of the agent

Definition at line 115 of file agent.h.

#### 6.1.4.9 r

```
float agent::r
```

radius for arrive behavior

Definition at line 145 of file agent.h.

#### 6.1.4.10 steering

```
pvector agent::steering
```

steering force of the apply

Definition at line 125 of file agent.h.

#### 6.1.4.11 targetPoint

```
point agent::targetPoint
```

Definition at line 156 of file agent.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[agent.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[agent.cpp](#)

## 6.2 color Class Reference

```
#include <color.h>
```

### Public Member Functions

- [color](#) ()  
*default constructor.*
- [color](#) (float r, float g, float b)  
*constructor.*

### Static Public Member Functions

- static [color](#) [getColor](#) (int index)  
*gets colorbar colors*

## Public Attributes

- float [R](#)  
*portion of red color*
- float [G](#)  
*portion of green color*
- float [B](#)  
*portion of blue color*

### 6.2.1 Detailed Description

Definition at line 23 of file color.h.

### 6.2.2 Constructor & Destructor Documentation

#### 6.2.2.1 `color()` [1/2]

```
color::color ( )
```

default constructor.

See also

[color\(float r, float g, float b\)](#)

Definition at line 13 of file color.cpp.

```
14 {  
15  
16 }
```

#### 6.2.2.2 `color()` [2/2]

```
color::color (  
    float r,  
    float g,  
    float b )
```

constructor.

Parameters

<i>r</i>	red (0-255)
<i>g</i>	green (0-255)
<i>b</i>	blue (0-255)

See also

[path\(\)](#)

Definition at line 18 of file color.cpp.

```
19 {
20     R = r;
21     G = g;
22     B = b;
23 }
```

## 6.2.3 Member Function Documentation

### 6.2.3.1 getColor()

```
color color::getColor (
    int index ) [static]
```

gets colorbar colors

Parameters

<i>index</i>	color id
--------------	----------

Definition at line 25 of file color.cpp.

```
25 {
26     switch (index)
27     {
28         case 0: return WHITE; break;
29         case 1: return BLUE; break;
30         case 2: return RED; break;
31         case 3: return YELLOW; break;
32         case 4: return GREEN; break;
33         case 5: return BLACK; break;
34         case 6: return CYAN; break;
35         case 7: return MAGENDA; break;
36     }
37     return RED;
38 }
39 }
```

## 6.2.4 Member Data Documentation

### 6.2.4.1 B

```
float color::B
```

portion of blue color

Definition at line 53 of file color.h.

#### 6.2.4.2 G

```
float color::G
```

portion of green color

Definition at line 48 of file color.h.

#### 6.2.4.3 R

```
float color::R
```

portion of red color

Definition at line 43 of file color.h.

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/color.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/color.cpp](#)

## 6.3 entity Class Reference

```
#include <entity.h>
```

### Public Member Functions

- [entity](#) ()  
*default constructor.*
- string [getName](#) ()  
*getter of the name*
- void [setName](#) (string name)  
*name attribute setter*
- int [getId](#) ()  
*getter of the id attribute*
- void [setId](#) (int id)  
*id attribute setter*
- virtual void [draw](#) ([graphics](#) view)=0  
*overriden by child classes*
- [color](#) [getColor](#) ()  
*getter of the color attribute*
- void [setColor](#) ([color](#) color)  
*getter of the color attribute*

### 6.3.1 Detailed Description

Definition at line 10 of file entity.h.

### 6.3.2 Constructor & Destructor Documentation

#### 6.3.2.1 entity()

```
entity::entity ( )
```

default constructor.

Definition at line 10 of file entity.cpp.

```
10     {  
11         entityColor = RED;  
12     }
```

### 6.3.3 Member Function Documentation

#### 6.3.3.1 draw()

```
virtual void entity::draw (  
    graphics view ) [pure virtual]
```

overridden by child classes

##### Parameters

<i>view</i>	graphics
-------------	----------

Implemented in [agent](#), [obstacle](#), and [path](#).

#### 6.3.3.2 getColor()

```
color entity::getColor ( )
```

getter of the color attribute

Definition at line 15 of file entity.cpp.

```
16 {  
17     return entityColor;  
18 }
```

#### 6.3.3.3 getId()

```
int entity::getId ( )
```

getter of the id attribute

Definition at line 32 of file entity.cpp.

```
32 {  
33     return id;  
34 }
```

#### 6.3.3.4 getName()

```
string entity::getName ( )
```

getter of the name

Definition at line 24 of file entity.cpp.

```
24 {  
25     return name;  
26 }
```

#### 6.3.3.5 setColor()

```
void entity::setColor (  
    color color )
```

getter of the color attribute

Definition at line 20 of file entity.cpp.

```
20 {  
21     entityColor = color;  
22 }
```

#### 6.3.3.6 setId()

```
void entity::setId (  
    int id )
```

id attribute setter

##### Parameters

<i>id</i>	setter
-----------	--------

Definition at line 36 of file entity.cpp.

```
36 {  
37     this->id = id;
```



```
38 }
```

### 6.3.3.7 setName()

```
void entity::setName (
    string name )
```

name attribute setter

#### Parameters

<i>name</i>	setter
-------------	--------

Definition at line 28 of file entity.cpp.

```
28 {
29     this->name = name;
30 }
```

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/entity.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/entity.cpp](#)

## 6.4 evade Class Reference

```
#include <evade.h>
```

### Public Member Functions

- [evade](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*loop function of evading scenario*

### Additional Inherited Members

#### 6.4.1 Detailed Description

Definition at line 15 of file evade.h.

## 6.4.2 Constructor & Destructor Documentation

### 6.4.2.1 evade()

evade::evade ( )

default constructor.

Definition at line 31 of file evade.cpp.

```
32 {
33     name = "evading";
34     createStaticAgents("gazelle", "lion");
35     callback = reinterpret_cast <void(*) ()> ( (void *)(&loop) );
36 }
```

## 6.4.3 Member Function Documentation

### 6.4.3.1 loop()

void evade::loop ( ) [static]

loop function of evading scenario

#### Note

opengl callback forces that function to be static

Definition at line 15 of file evade.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         if((*it).getName() == "lion"){
19             (*it).setTarget(view.getMousePosition());
20             (*it).force = behavior.seek(*it);
21             (*it).arrive = true;
22         }
23         else{//gazelle
24             (*it).force = behavior.evade(agents, *it, view, "lion");
25         }
26     }
27     refresh();
28 }
29 }
```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[evade.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[evade.cpp](#)

## 6.5 flee Class Reference

```
#include <flee.h>
```

## Public Member Functions

- [flee](#) ()  
*default constructor.*

## Static Public Member Functions

- static void [loop](#) ()  
*evading scenario loop function*

## Additional Inherited Members

### 6.5.1 Detailed Description

Definition at line 14 of file [flee.h](#).

### 6.5.2 Constructor & Destructor Documentation

#### 6.5.2.1 flee()

```
flee::flee ( )
```

default constructor.

Definition at line 24 of file [flee.cpp](#).

```
25 {
26     int agentCount = 196;
27     name = "fleeing troop";
28     createTroop(agentCount);
29     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );
30 }
```

### 6.5.3 Member Function Documentation

#### 6.5.3.1 loop()

```
void flee::loop ( ) [static]
```

evading scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file [flee.cpp](#).

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         (*it).force = behavior.flee((*it), view, view.getMousePosition());
19     }
20
21     refresh();
22 }
```

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/flee.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/flee.cpp](#)

## 6.6 flock Class Reference

```
#include <flock.h>
```

### Public Member Functions

- `flock ()`  
*default constructor.*

### Static Public Member Functions

- static void `loop ()`  
*flocking scenario loop function*

### Additional Inherited Members

#### 6.6.1 Detailed Description

Definition at line 15 of file flock.h.

#### 6.6.2 Constructor & Destructor Documentation

##### 6.6.2.1 flock()

```
flock::flock ( )
```

default constructor.

Definition at line 32 of file flock.cpp.

```
33 {  
34     int agentCount = 40;  
35     float maxForce = 0.5;  
36     float maxSpeed = 0.9;  
37     name = "flocking agents";  
38  
39     createRandomAgents(agentCount, maxForce, maxSpeed);  
40     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );  
41 }
```

#### 6.6.3 Member Function Documentation

### 6.6.3.1 loop()

```
void flock::loop ( ) [static]
```

flocking scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file flock.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         view.forceInScreen((*it));
19
20         pvector sep = behavior.separation(agents, *it, 6);
21         sep.mul(1);
22         pvector ali = behavior.align(agents, *it, 20);
23         ali.mul(4);
24         pvector coh = behavior.cohesion(agents, *it, 20);
25         coh.mul(0.1);
26
27         (*it).force = sep + ali + coh;
28     }
29     refresh();
30 }
```

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/flock.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/flock.cpp](#)

## 6.7 flowField Class Reference

```
#include <flowField.h>
```

### Public Member Functions

- [flowField \(\)](#)  
*default constructor.*
- [flowField \(pvector p\)](#)  
*constructor.*
- [pvector getField \(int x, int y\)](#)  
*get force at individual pixel*

### 6.7.1 Detailed Description

Definition at line 18 of file flowField.h.

### 6.7.2 Constructor & Destructor Documentation

### 6.7.2.1 flowField() [1/2]

```
flowField::flowField ( )
```

default constructor.

See also

[flowField\(pvector p\)](#)

Definition at line 15 of file flowField.cpp.

```
16 {  
17  
18 }
```

### 6.7.2.2 flowField() [2/2]

```
flowField::flowField (  
    pvector p )
```

constructor.

Parameters

<i>p</i>	force vector
----------	--------------

See also

[flowField\(\)](#)

Definition at line 10 of file flowField.cpp.

```
11 {  
12     createFlowField(p);  
13 }
```

## 6.7.3 Member Function Documentation

### 6.7.3.1 getField()

```
pvector flowField::getField (  
    int x,  
    int y )
```

get force at individual pixel

**Parameters**

<i>x</i>	coordinate
<i>y</i>	coordinate

**Returns**

force at specified position

Definition at line 39 of file flowField.cpp.

```
40 {
41     return uniformField[x][y];
42 }
```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/flowField.h
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/flowField.cpp

## 6.8 graphics Class Reference

```
#include <graphics.h>
```

**Public Member Functions**

- void [drawAgent](#) ([agent](#) &[agent](#))  
*drawing with corresponding angle*
- void [drawLine](#) ([point](#) p1, [point](#) p2, [color](#) cl)  
*drawing line*
- void [drawPath](#) ([path](#) &[path](#))  
*draws path*
- void [drawPoint](#) ([point](#) p, [color](#) cl)  
*draws point*
- void [drawCircle](#) ([point](#) p, float radius, [color](#) color)  
*draws circle*
- void [drawText](#) (string text, [point](#) p)  
*draws text on screen*
- void [forceInScreen](#) ([agent](#) &[agent](#))  
*changes agent position so that it stays in screen*
- void [refreshScene](#) ()  
*update agent position*
- [point](#) [getMousePosition](#) ()  
*gets mouse position*
- void [initGraphics](#) (int \*argv, char \*\*argc, void(\*callback)())  
*initialization of graphics*

## Static Public Member Functions

- static void `timerEvent` (int value)  
*periodic timer event*
- static void `handleKeyPress` (unsigned char key, int x, int y)  
*key press event*
- static void `mouseButton` (int button, int state, int x, int y)  
*mouse press event*
- static void `handleResize` (int w, int h)  
*event triggered with screen resizing*
- static void `mouseMove` (int x, int y)  
*event triggered with mouse movements*

## Static Public Attributes

- static int `target_x` = `-WIDTH`  
*mouse position x*
- static int `target_y` = `HEIGHT`  
*mouse position y*

### 6.8.1 Detailed Description

Definition at line 22 of file `graphics.h`.

### 6.8.2 Member Function Documentation

#### 6.8.2.1 `drawAgent()`

```
void graphics::drawAgent (
    agent & agent )
```

drawing with corresponding angle

#### Parameters

<i>agent</i>	instance to change
--------------	--------------------

Definition at line 159 of file `graphics.cpp`.

```
160 {
161     glPushMatrix();
162     glTranslatef(agent.position.x, agent.position.y, 0.0f);
163     glRotatef(agent.getVelocity().getAngle(), 0.0f, 0.0f, 1.0f);
164     glBegin(GL_TRIANGLES);
165     glColor3f( agent.getColor().R, agent.getColor().G, agent.getColor().B);
166     glVertex3f( 1.0f, 0.0f, 0.0f);
167     glVertex3f(-1.0f, 0.5f, 0.0f);
168     glVertex3f(-1.0f, -0.5f, 0.0f);
169     glEnd();
170     glPopMatrix();
```



```
171 }
```

### 6.8.2.2 drawCircle()

```
void graphics::drawCircle (
    point p,
    float radius,
    color color )
```

draws circle

#### Parameters

<i>p</i>	center of the circle
<i>radius</i>	radius of the circle
<i>color</i>	of the circle

Definition at line 136 of file graphics.cpp.

```
137 {
138     glColor3f(color.R, color.G, color.B);
139     glBegin(GL_LINE_STRIP);
140     glLineWidth(2);
141     for (int i = 0; i <= 300; i++) {
142         float angle = 2 * PI * i / 300;
143         float x = cos(angle) * radius;
144         float y = sin(angle) * radius;
145         glVertex2d(p.x + x, p.y + y);
146     }
147     glEnd();
148 }
```

### 6.8.2.3 drawLine()

```
void graphics::drawLine (
    point p1,
    point p2,
    color cl )
```

drawing line

#### Parameters

<i>p1</i>	start point of the line
<i>p2</i>	end point of the line
<i>cl</i>	color of the line

Definition at line 126 of file graphics.cpp.

```
127 {
128     glColor3f( cl.R, cl.G, cl.B);
129     glLineWidth(2);
130     glBegin(GL_LINES);
131     glVertex2f(p1.x, p1.y);
132     glVertex2f(p2.x, p2.y);
```

```

133     glEnd();
134 }

```

#### 6.8.2.4 drawPath()

```

void graphics::drawPath (
    path & path )

```

draws path

##### Parameters

<i>path</i>	to draw
-------------	---------

Definition at line 112 of file graphics.cpp.

```

113 {
114     point p1, p2;
115     for(auto it = path.points.begin(); it < path.points.end()-1; it++){
116         p1 = point((*it).x, (*it).y - path.getPathWidth() / 2) ;
117         p2 = point((*it+1).x, (*it+1).y - path.getPathWidth() / 2);
118         drawLine(p1, p2, path.getColor());
119
120         p1 = point((*it).x, (*it).y + path.getPathWidth() / 2) ;
121         p2 = point((*it+1).x, (*it+1).y + path.getPathWidth() / 2);
122         drawLine(p1, p2, path.getColor());
123     }
124 }

```

#### 6.8.2.5 drawPoint()

```

void graphics::drawPoint (
    point p,
    color cl )

```

draws point

##### Parameters

<i>p</i>	point to draw
----------	---------------

Definition at line 150 of file graphics.cpp.

```

151 {
152     glColor3f(cl.R, cl.G, cl.B);
153     glPointSize(4.0);
154     glBegin(GL_POINTS);
155     glVertex2f(p.x, p.y);
156     glEnd();
157 }

```

#### 6.8.2.6 drawText()

```

void graphics::drawText (

```

```
    string text,
    point p )
```

draws text on screen

#### Parameters

<i>p</i>	position of the text
<i>text</i>	to display

Definition at line 21 of file graphics.cpp.

```
22 {
23     glColor3f (0.0, 0.0, 1.0);
24     glRasterPos2f(p.x, p.y);
25     for ( string::iterator it=text.begin(); it!=text.end(); ++it){
26         glutBitmapCharacter(GLUT_BITMAP_9_BY_15, *it);
27     }
28 }
```

#### 6.8.2.7 forceInScreen()

```
void graphics::forceInScreen (
    agent & agent )
```

changes agent position so that it stays in screen

#### Parameters

<i>agent</i>	instance
--------------	----------

Definition at line 61 of file graphics.cpp.

```
62 {
63     if (agent.position.x > WIDTH)
64         agent.position.x -= 2 * WIDTH;
65     if (agent.position.x < -WIDTH)
66         agent.position.x += 2 * WIDTH;
67     if (agent.position.y > HEIGHT)
68         agent.position.y -= 2 * HEIGHT;
69     if (agent.position.y < -HEIGHT)
70         agent.position.y += 2 * HEIGHT;
71 }
```

#### 6.8.2.8 getMousePosition()

```
point graphics::getMousePosition ( )
```

gets mouse position

#### Returns

mouse point

Definition at line 56 of file graphics.cpp.

```
57 {
58     return point (graphics::target_x, graphics::target_y);
59 }
```

### 6.8.2.9 handleKeypress()

```
void graphics::handleKeypress (
    unsigned char key,
    int x,
    int y ) [static]
```

key press event

#### Parameters

<i>key</i>	pressed
<i>x</i>	unused but required for OpenGL
<i>y</i>	unused but required for OpenGL

Definition at line 105 of file graphics.cpp.

```
106 {
107     if (key == ESC){
108         exit(0);
109     }
110 }
```

### 6.8.2.10 handleResize()

```
void graphics::handleResize (
    int w,
    int h ) [static]
```

event triggered with screen resizing

#### Parameters

<i>w</i>	width of the screen
<i>h</i>	height of the screen

Definition at line 81 of file graphics.cpp.

```
82 {
83     glViewport(0, 0, w, h); //Tell OpenGL how to convert from coordinates to pixel values
84     glMatrixMode(GL_PROJECTION); //Switch to setting the camera perspective
85     glLoadIdentity(); //Reset the camera
86     //Set the camera perspective
87     gluPerspective(45.0, //The camera angle
88                   (double)w / (double)h, //The width-to-height ratio
89                   1.0, //The near z clipping coordinate
90                   200.0); //The far z clipping coordinate
91 }
```

### 6.8.2.11 initGraphics()

```
void graphics::initGraphics (
    int * argv,
```

```
char ** argc,  
void(*)() callback )
```

initialization of graphics

## Parameters

<i>argv</i>	user parametersdrawc
<i>argc</i>	count of user parameters
<i>callback</i>	loop function for openGL periodic callback

Definition at line 39 of file graphics.cpp.

```

40 {
41     glutInit(argv, argc);
42     glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGB | GLUT_DEPTH);
43     glutInitWindowSize(400, 400);
44     glutCreateWindow("Autonomous Steering Agents");
45     glClearColor(0.7f, 0.7f, 0.7f, 1.0f); //set background color
46     glEnable(GL_DEPTH_TEST);
47     glutDisplayFunc(*callback);
48     glutMouseFunc(graphics::mouseButton);
49     glutPassiveMotionFunc(graphics::mouseMove);
50     glutKeyboardFunc(graphics::handleKeypress);
51     glutReshapeFunc(graphics::handleResize);
52     glutTimerFunc(20, graphics::timerEvent, 0);
53     glutMainLoop();
54 }
```

### 6.8.2.12 mouseButton()

```

void graphics::mouseButton (
    int button,
    int state,
    int x,
    int y ) [static]
```

mouse press event

## Parameters

<i>button</i>	mouse key pressed
<i>state</i>	down/up etc.
<i>x</i>	unused but required for openGL
<i>y</i>	unused but required for openGL

Definition at line 99 of file graphics.cpp.

```

100 {
101     if (button == GLUT_LEFT_BUTTON && state == GLUT_DOWN){
102     }
103 }
```

### 6.8.2.13 mouseMove()

```

void graphics::mouseMove (
    int x,
    int y ) [static]
```

event triggered with mouse movements

## Parameters

<i>x</i>	osition of the mouse
<i>y</i>	position of the mouse

Definition at line 73 of file graphics.cpp.

```

74 {
75     //TODO: mouse position to glut
76     //TODO: magic numbers
77     graphics::target_x = x / 5.88 - 34;
78     graphics::target_y = 34 - y / 5.88;
79 }
```

## 6.8.2.14 refreshScene()

```
void graphics::refreshScene ( )
```

update agent position

Definition at line 30 of file graphics.cpp.

```

31 {
32     glutSwapBuffers();
33     glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
34     glMatrixMode(GL_MODELVIEW); //Switch to the drawing perspective
35     glLoadIdentity(); //Reset the drawing perspective
36     glTranslatef(0.0f, 0.0f, -85.0f); //Move to the center of the triangle
37 }
```

## 6.8.2.15 timerEvent()

```
void graphics::timerEvent (
    int value ) [static]
```

periodic timer event

## Parameters

<i>value</i>	period as ms
--------------	--------------

Definition at line 93 of file graphics.cpp.

```

94 {
95     glutPostRedisplay(); //Tell GLUT that the display has changed
96     glutTimerFunc(value, timerEvent, 20);
97 }
```

## 6.8.3 Member Data Documentation

### 6.8.3.1 target\_x

```
int graphics::target_x = -WIDTH [static]
```

mouse position x

Definition at line 130 of file graphics.h.

### 6.8.3.2 target\_y

```
int graphics::target_y = HEIGHT [static]
```

mouse position y

Definition at line 135 of file graphics.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[graphics.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[graphics.cpp](#)

## 6.9 leaderFollower Class Reference

```
#include <leaderFollower.h>
```

### Public Member Functions

- [leaderFollower](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*leader following scenario loop function*

### Static Public Attributes

- static [pvector](#) [leaderVelocity](#)  
*leader velocity*
- static [point](#) [leaderPosition](#)  
*leader position*
- static float [leaderAngle](#)



## Additional Inherited Members

### 6.9.1 Detailed Description

Definition at line 14 of file leaderFollower.h.

### 6.9.2 Constructor & Destructor Documentation

#### 6.9.2.1 leaderFollower()

```
leaderFollower::leaderFollower ( )
```

default constructor.

Definition at line 72 of file leaderFollower.cpp.

```
73 {  
74     int agentCount = 10;  
75     float maxForce = 0.4;  
76     float maxSpeed = 0.6;  
77     name = "leader following";  
78  
79     //todo: refactor leader creation  
80     agent agent1 {-10.0, 0.0};  
81     agent1.id = 1;  
82     agent1.setName("leader");  
83     agent1.setColor(BLUE);  
84     agent1.setFeatures(0.8, 0.4, 5, 1);  
85     agents.push_back(agent1);  
86  
87     createRandomAgents(agentCount, maxForce, maxSpeed);  
88     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );  
89 }
```

### 6.9.3 Member Function Documentation

#### 6.9.3.1 loop()

```
void leaderFollower::loop ( ) [static]
```

leader following scenario loop function

**Note**

opengl callback forces that function to be static

Definition at line 21 of file leaderFollower.cpp.

```

22 { //todo: refactor code
23     int row = 1;
24     int index = 0;
25     int distance = 3;
26     point vTarget = mainTarget;
27
28     for(auto it = agents.begin(); it < agents.end(); it++){
29         if((*it).getName() == "leader"){
30             (*it).setTarget(view.getMousePosition());
31             (*it).force = behavior.seek(*it);
32
33             leaderVelocity = (*it).getVelocity();
34             leaderVelocity.mul(-1);
35             leaderVelocity.normalize().mul(10);
36             leaderPosition = (*it).position;
37             leaderAngle = leaderVelocity.getAngle() + 180;
38
39             mainTarget = leaderPosition + leaderVelocity;
40             view.drawText((*it).getName(), point(leaderPosition.x -3, leaderPosition.y - 3));
41         }
42         else{
43             pvector sep = behavior.separation(agents, *it, 3);
44             sep.mul(20);
45             (*it).force = sep;
46
47             //make target of the agents different and v shaped individually
48             if(index == row){
49                 row++;
50                 vTarget = point( vTarget.x - distance, mainTarget.y + distance * ( row - 1 ) );
51                 index = 0;
52             }
53             index++;
54             (*it).targetPoint = vTarget;
55             //view.drawPoint((*it).targetPoint, RED);
56             vTarget.y = vTarget.y - ( 2 * distance );
57
58             //transform other agent targets referencing first agents target considering leader angle
59             (*it).targetPoint.rotateByAngleAboutPoint(mainTarget, leaderAngle);
60
61             view.drawPoint((*it).targetPoint, BLUE);
62             (*it).force += behavior.seek(*it);
63
64             //todo: make angle of the agent same with angle of leader
65             //todo: leader changes its orientation before arriving
66         }
67         (*it).arrive = true;
68     }
69     refresh();
70 }

```

## 6.9.4 Member Data Documentation

### 6.9.4.1 leaderAngle

```
float leaderFollower::leaderAngle [static]
```

Definition at line 26 of file leaderFollower.h.

### 6.9.4.2 leaderPosition

```
point leaderFollower::leaderPosition [static]
```

leader position

Definition at line 24 of file leaderFollower.h.

### 6.9.4.3 leaderVelocity

```
pvector leaderFollower::leaderVelocity [static]
```

leader velocity

Definition at line 19 of file leaderFollower.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[leaderFollower.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[leaderFollower.cpp](#)

## 6.10 mouseFollower Class Reference

```
#include <mouseFollower.h>
```

### Public Member Functions

- [mouseFollower](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*mouse following scenario loop function*

### Additional Inherited Members

#### 6.10.1 Detailed Description

Definition at line 14 of file mouseFollower.h.

#### 6.10.2 Constructor & Destructor Documentation

### 6.10.2.1 mouseFollower()

```
mouseFollower::mouseFollower ( )
```

default constructor.

Definition at line 25 of file mouseFollower.cpp.

```
26 {  
27     int agentCount = 30;  
28     float maxForce = 0.3;  
29     float maxSpeed = 0.6;  
30     name = "mouse following";  
31     createRandomAgents(agentCount, maxForce, maxSpeed);  
32     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );  
33 }
```

## 6.10.3 Member Function Documentation

### 6.10.3.1 loop()

```
void mouseFollower::loop ( ) [static]
```

mouse following scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file mouseFollower.cpp.

```
16 {  
17     for(auto it = agents.begin(); it < agents.end(); it++){  
18         (*it).setTarget(view.getMousePosition());  
19         (*it).force = behavior.seek(*it);  
20         (*it).arrive = true;  
21     }  
22     refresh();  
23 }
```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/mouseFollower.h
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/mouseFollower.cpp

## 6.11 obstacle Class Reference

```
#include <obstacle.h>
```

## Public Member Functions

- [obstacle](#) ()  
*default constructor.*
- [obstacle](#) ([point](#) p, float r)  
*constructor*
- [point](#) [getCenter](#) ()  
*getter of the center point attribute*
- void [setCenter](#) ([point](#) p)  
*setter of the center point attribute*
- float [getRadius](#) ()  
*getter of the radius attribute*
- void [setRadius](#) (float r)  
*setter of the radius attribute*
- void [draw](#) ([graphics](#) view) override  
*overriden draw implementation*

### 6.11.1 Detailed Description

Definition at line 15 of file obstacle.h.

### 6.11.2 Constructor & Destructor Documentation

#### 6.11.2.1 [obstacle\(\)](#) [1/2]

```
obstacle::obstacle ( )
```

default constructor.

See also

[obstacle](#)([point](#) p, float r

Definition at line 16 of file obstacle.cpp.

```
17 {  
18     p = point(0,0);  
19     r = 5;  
20     setColor(RED);  
21 }
```

#### 6.11.2.2 [obstacle\(\)](#) [2/2]

```
obstacle::obstacle (  
    point p,  
    float r )
```

constructor

#### Parameters

$p$	center of the circular obstacle
$r$	radius of the obstacle

#### See also

[obstacle\(point p, float r\);](#)

Definition at line 23 of file obstacle.cpp.

```
24 {  
25     this->p = p;  
26     this->r = r;  
27     setColor(RED);  
28 }
```

### 6.11.3 Member Function Documentation

#### 6.11.3.1 draw()

```
void obstacle::draw (  
    graphics view ) [override], [virtual]
```

overriden draw implementation

Implements [entity](#).

Definition at line 30 of file obstacle.cpp.

```
30     {  
31         view.drawCircle(p, r, getColor());  
32     }
```

#### 6.11.3.2 getCenter()

```
point obstacle::getCenter ( )
```

getter of the center point attribute

Definition at line 34 of file obstacle.cpp.

```
34     {  
35         return p;  
36     }
```

### 6.11.3.3 getRadius()

```
float obstacle::getRadius ( )
```

getter of the radius attribute

Definition at line 42 of file obstacle.cpp.

```
42     {  
43         return r;  
44     }
```

### 6.11.3.4 setCenter()

```
void obstacle::setCenter (  
    point p )
```

setter of the center point attribute

Definition at line 38 of file obstacle.cpp.

```
38     {  
39         this->p = p;  
40     }
```

### 6.11.3.5 setRadius()

```
void obstacle::setRadius (  
    float r )
```

setter of the radius attribute

Definition at line 46 of file obstacle.cpp.

```
46     {  
47         this->r = r;  
48     }
```

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacle.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacle.cpp](#)

## 6.12 obstacleAvoidance Class Reference

```
#include <obstacleAvoidance.h>
```

### Public Member Functions

- [obstacleAvoidance \(\)](#)  
*default constructor.*

## Static Public Member Functions

- static void `loop` ()  
*obstacle avoidance scenario loop function*
- static void `createObstacle` (vector< `obstacle` > &`obstacles`)  
*creation of list of obstacles*

## Static Public Attributes

- static vector< `obstacle` > `obstacles`  
*list of obstacles*

## Additional Inherited Members

### 6.12.1 Detailed Description

Definition at line 15 of file `obstacleAvoidance.h`.

### 6.12.2 Constructor & Destructor Documentation

#### 6.12.2.1 `obstacleAvoidance()`

```
obstacleAvoidance::obstacleAvoidance ( )
```

default constructor.

Definition at line 43 of file `obstacleAvoidance.cpp`.

```
44 {
45     name = "avoid obstacles";
46     createStaticAgents("ag1", "ag2");
47     createObstacle(obstacles);
48     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );
49 }
```

### 6.12.3 Member Function Documentation

#### 6.12.3.1 `createObstacle()`

```
void obstacleAvoidance::createObstacle (
    vector< obstacle > & obstacles ) [static]
```

creation of list of obstacles



## Parameters

<i>obstacles</i>	list to be created
------------------	--------------------

## Note

opengl callback forces that function to be static

Definition at line 36 of file obstacleAvoidance.cpp.

```

37 {
38     obstacles.push_back(obstacle(point(0,0), 8));
39     obstacles.push_back(obstacle(point(-20,0), 3));
40     obstacles.push_back(obstacle(point(20,-10), 4));
41 }
```

## 6.12.3.2 loop()

```
void obstacleAvoidance::loop ( ) [static]
```

obstacle avoidance scenario loop function

## Note

opengl callback forces that function to be static

Definition at line 17 of file obstacleAvoidance.cpp.

```

18 {
19     for(auto it = agents.begin(); it < agents.end(); it++){
20         (*it).setTarget(view.getMousePosition());
21         pvector seek = behavior.seek(*it);
22         seek.mul(0.5);
23
24         pvector avoid = behavior.avoid(obstacles, *it);
25         (*it).force = avoid + seek;
26         (*it).arrive = true;
27     }
28
29     for(auto it = obstacles.begin(); it < obstacles.end(); it++){
30         (*it).draw(view);
31     }
32
33     refresh();
34 }
```

## 6.12.4 Member Data Documentation

## 6.12.4.1 obstacles

```
vector< obstacle > obstacleAvoidance::obstacles [static]
```

list of obstacles

## Note

opengl callback forces that function to be static

Definition at line 32 of file obstacleAvoidance.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[obstacleAvoidance.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[obstacleAvoidance.cpp](#)

## 6.13 path Class Reference

```
#include <path.h>
```

### Public Member Functions

- [path](#) ()  
*default constructor.*
- [path](#) (float width)  
*donstructor.*
- void [addPoint](#) ([point](#) p)  
*adds a new point to the path*
- void [setPathWidth](#) (int w)  
*setter of the path width*
- int [getPathWidth](#) ()  
*getter of the path width*
- void [draw](#) ([graphics](#) view)  
*overriden draw implementation*

### Public Attributes

- vector< [point](#) > [points](#)  
*list of points added to the path*

#### 6.13.1 Detailed Description

Definition at line 17 of file path.h.

#### 6.13.2 Constructor & Destructor Documentation

##### 6.13.2.1 [path\(\)](#) [1/2]

```
path::path ( )
```

default constructor.

See also

[path\(float width\)](#)

Definition at line 16 of file path.cpp.

```
17 {  
18     setColor(BLUE);  
19     width = 8;  
20 }
```

##### 6.13.2.2 [path\(\)](#) [2/2]

```
path::path (  
    float width )
```

donstructor.

## Parameters

<i>width</i>	The width of the path.
--------------	------------------------

## See also

[path\(\)](#)

Definition at line 31 of file path.cpp.

```
32 {  
33     this->width = width;  
34     setColor(BLUE);  
35 }
```

### 6.13.3 Member Function Documentation

#### 6.13.3.1 addPoint()

```
void path::addPoint (  
    point p )
```

adds a new point to the path

## Parameters

<i>point</i>	to add to the path
--------------	--------------------

Definition at line 11 of file path.cpp.

```
12 {  
13     points.push_back(p);  
14 }
```

#### 6.13.3.2 draw()

```
void path::draw (  
    graphics view ) [virtual]
```

overriden draw implementation

Implements [entity](#).

Definition at line 37 of file path.cpp.

```
37     {  
38         view.drawPath(*this);  
39     }
```

### 6.13.3.3 getPathWidth()

```
int path::getPathWidth ( )
```

getter of the path width

Definition at line 26 of file path.cpp.

```
26         {  
27     return width;  
28 }
```

### 6.13.3.4 setPathWidth()

```
void path::setPathWidth (  
    int w )
```

setter of the path width

Definition at line 22 of file path.cpp.

```
22     {  
23     width = w;  
24 }
```

## 6.13.4 Member Data Documentation

### 6.13.4.1 points

```
vector<point> path::points
```

list of points added to the path

Definition at line 41 of file path.h.

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/path.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/path.cpp](#)

## 6.14 pathFollower Class Reference

```
#include <pathFollower.h>
```

### Public Member Functions

- [pathFollower \(\)](#)  
*default constructor.*

## Static Public Member Functions

- static void `loop` ()  
*path follower scenario loop function*
- static void `createPath` (`path` &p)  
*creates path*

## Static Public Attributes

- static `path` `myPath`  
*path that will be followed*

## Additional Inherited Members

### 6.14.1 Detailed Description

Definition at line 14 of file pathFollower.h.

### 6.14.2 Constructor & Destructor Documentation

#### 6.14.2.1 pathFollower()

```
pathFollower::pathFollower ( )
```

default constructor.

Definition at line 38 of file pathFollower.cpp.

```
39 {  
40     int agentCount = 40;  
41     float maxForce = 0.2;  
42     float maxSpeed = 0.4;  
43     myPath = path(8);  
44     createPath(myPath);  
45     name = "path following";  
46     createRandomAgents(agentCount, maxForce, maxSpeed);  
47     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );  
48 }
```

### 6.14.3 Member Function Documentation

#### 6.14.3.1 createPath()

```
void pathFollower::createPath (  
    path & p ) [static]
```

creates path

## Parameters

<i>path</i>	to create
-------------	-----------

## Note

opengl callback forces that function to be static

Definition at line 30 of file pathFollower.cpp.

```
31 {
32     p.addPoint(point(-40, 5));
33     p.addPoint(point(-14, 15));
34     p.addPoint(point(10, 7));
35     p.addPoint(point(40, 12));
36 }
```

### 6.14.3.2 loop()

```
void pathFollower::loop ( ) [static]
```

path follower scenario loop function

## Note

opengl callback forces that function to be static

Definition at line 17 of file pathFollower.cpp.

```
18 {
19     for(auto it = agents.begin(); it < agents.end(); it++){
20         pvector flwpth = behavior.stayInPath(*it, myPath, view);
21         pvector sep = behavior.separation(agents, *it, 3);
22         sep.mul(5);
23         (*it).force = sep + flwpth;
24     }
25     myPath.draw(view);
26 }
27 refresh();
28 }
```

## 6.14.4 Member Data Documentation

### 6.14.4.1 myPath

```
path pathFollower::myPath [static]
```

path that will be followed

## Note

opengl callback forces that function to be static

Definition at line 38 of file pathFollower.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[pathFollower.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[pathFollower.cpp](#)

## 6.15 point Class Reference

```
#include <point.h>
```

### Public Member Functions

- `point ()`  
*default constructor*
- `point (float x, float y)`  
*constructor*
- `void div (float d)`  
*divide point*
- `void mul (float d)`  
*multiply point*
- `void print (const string &s)`  
*debug function*
- `void getNormalPoint (point predicted, point start, point end)`  
*provides normal point on a vector of a point*
- `point operator+ (pvector const &obj)`  
*overloaded + operator*
- `point operator+ (point const &obj)`  
*overloaded + operator*
- `pvector operator- (point const &obj)`  
*overloaded - operator*
- `bool operator== (point const &obj)`  
*overloaded == operator*
- `void rotate (float angle)`  
*rotate point by angle*
- `void rotateByAngleAboutPoint (point p, float angle)`  
*rotate point about another point by angle*
- `float difference (point &obj)`  
*difference measurement of points*

### Public Attributes

- `float x`  
*x position*
- `float y`  
*y position*

#### 6.15.1 Detailed Description

Definition at line 15 of file point.h.

#### 6.15.2 Constructor & Destructor Documentation

### 6.15.2.1 `point()` [1/2]

```
point::point ( )
```

default constructor

See also

[point\(float x, float y\)](#)

Definition at line 22 of file point.cpp.

```
23 {  
24     x = 0;  
25     y = 0;  
26 }
```

### 6.15.2.2 `point()` [2/2]

```
point::point (  
                float x,  
                float y )
```

constructor

Parameters

<i>x</i>	position x of the point
<i>y</i>	position y of the point

See also

[point\(\)](#)

Definition at line 16 of file point.cpp.

```
17 {  
18     this->x = x;  
19     this->y = y;  
20 }
```

## 6.15.3 Member Function Documentation

### 6.15.3.1 `difference()`

```
float point::difference (  
    point & obj )
```

difference measurement of points



## Parameters

<i>obj</i>	point to measure difference
------------	-----------------------------

## Returns

difference of two points

Definition at line 46 of file point.cpp.

```
46 {  
47     return sqrt( (x - obj.x) * (x - obj.x) + (y - obj.y) * (y - obj.y) );  
48 }
```

### 6.15.3.2 div()

```
void point::div (  
    float d )
```

divide point

## Parameters

<i>d</i>	scalar to divide position of the point
----------	--

Definition at line 65 of file point.cpp.

```
66 {  
67     x = x / d;  
68     y = y / d;  
69 }
```

### 6.15.3.3 getNormalPoint()

```
void point::getNormalPoint (  
    point predicted,  
    point start,  
    point end )
```

provides normal point on a vector of a point

## Parameters

<i>predicted</i>	point that caller require normal on the vector
<i>start</i>	point of the vector
<i>end</i>	point of the vector

Definition at line 94 of file point.cpp.

```

95 {
96     pvector a = predicted - start;
97     pvector b = end - start;
98     b.normalize();
99     float a_dot_b = a.dotProduct(b);
100    b.mul(a_dot_b);
101    point normalPoint = start + b;
102    this->x = normalPoint.x;
103    this->y = normalPoint.y;
104 }

```

#### 6.15.3.4 mul()

```

void point::mul (
    float d )

```

multiply point

##### Parameters

<i>d</i>	scalar to multiply position of the point
----------	--

Definition at line 71 of file point.cpp.

```

72 {
73     x = x * d;
74     y = y * d;
75 }

```

#### 6.15.3.5 operator+() [1/2]

```

point point::operator+ (
    point const & obj )

```

overloaded + operator

##### Parameters

<i>obj</i>	point to add
------------	--------------

##### Returns

sum

Definition at line 78 of file point.cpp.

```

79 {
80     point res;
81     res.x = x + obj.x;
82     res.y = y + obj.y;
83     return res;
84 }

```

### 6.15.3.6 operator+() [2/2]

```
point point::operator+ (
    pvector const & obj )
```

overloaded + operator

#### Parameters

<i>obj</i>	vector to add
------------	---------------

#### Returns

sum

Definition at line 50 of file point.cpp.

```
51 {
52     point res;
53     res.x = x + obj.x;
54     res.y = y + obj.y;
55     return res;
56 }
```

### 6.15.3.7 operator-()

```
pvector point::operator- (
    point const & obj )
```

overloaded - operator

#### Parameters

<i>obj</i>	point to subtract
------------	-------------------

#### Returns

difference as pvector

Definition at line 86 of file point.cpp.

```
87 {
88     pvector res;
89     res.x = x - obj.x;
90     res.y = y - obj.y;
91     return res;
92 }
```

### 6.15.3.8 operator==()

```
bool point::operator== (
    point const & obj )
```

overloaded == operator

**Parameters**

<i>obj</i>	point to compare
------------	------------------

**Returns**

comparison result

Definition at line 58 of file point.cpp.

```
59 {
60     if(x == obj.x && y == obj.y)
61         return true;
62     return false;
63 }
```

**6.15.3.9 print()**

```
void point::print (
    const string & s )
```

debug function

**Parameters**

<i>s</i>	explanation string of the log
----------	-------------------------------

Definition at line 106 of file point.cpp.

```
107 {
108     cout << " " << s << " " << x << " " << y << endl;
109 }
```

**6.15.3.10 rotate()**

```
void point::rotate (
    float angle )
```

rotate point by angle

**Parameters**

<i>angle</i>	angle to rotate
--------------	-----------------

Definition at line 38 of file point.cpp.

```
38     {
39         float currentAngle;
40         currentAngle = atan2 (this->y, this->x) * 180 / PI;
41         float r = sqrt(this->x * this->x + this->y * this->y);
42         this->x = r * cos((currentAngle + angle) * PI / 180);
43         this->y = r * sin((currentAngle + angle) * PI / 180);
```

```
44 }
```

### 6.15.3.11 rotateByAngleAboutPoint()

```
void point::rotateByAngleAboutPoint (
    point p,
    float angle )
```

rotate point about another point by angle

#### Parameters

<i>p</i>	reference point to rotate
<i>angle</i>	to rotate

Definition at line 28 of file point.cpp.

```
28                                     {
29     pvector agentTargetToMainTarget = *this - p;
30     float diff = p.difference( *this );
31     float angleAboutMainTarget = agentTargetToMainTarget.getAngle();
32
33     *this = point (diff * cos((angleAboutMainTarget + angle) * PI / 180),
34                  diff * sin((angleAboutMainTarget + angle) * PI / 180));
35     *this = p + *this;
36 }
```

## 6.15.4 Member Data Documentation

### 6.15.4.1 x

```
float point::x
```

x position

Definition at line 109 of file point.h.

### 6.15.4.2 y

```
float point::y
```

y position

Definition at line 114 of file point.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[point.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[point.cpp](#)

## 6.16 prison Class Reference

```
#include <prison.h>
```

### Public Member Functions

- [prison](#) ()  
*default constructor.*

### Static Public Member Functions

- static void [loop](#) ()  
*prisoning scenario loop function*

### Additional Inherited Members

#### 6.16.1 Detailed Description

Definition at line 15 of file prison.h.

#### 6.16.2 Constructor & Destructor Documentation

##### 6.16.2.1 prison()

```
prison::prison ( )
```

default constructor.

Definition at line 31 of file prison.cpp.

```
32 {  
33     int agentCount = 10;  
34     float maxForce = 0.7;  
35     float maxSpeed = 0.7;  
36  
37     name = "stay in prison";  
38     createRandomAgents(agentCount, maxForce, maxSpeed);  
39     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );  
40 }
```

#### 6.16.3 Member Function Documentation

### 6.16.3.1 loop()

```
void prison::loop ( ) [static]
```

prisoning scenario loop function

prison loop function

#### Note

opengl callback forces that function to be static

Definition at line 18 of file prison.cpp.

```
19 {
20     for(auto it = agents.begin(); it < agents.end(); it++){
21         view.drawLine(point(-WALL, WALL), point(WALL, WALL), BLUE);
22         view.drawLine(point(WALL, WALL), point(WALL, -WALL), BLUE);
23         view.drawLine(point(WALL, -WALL), point(-WALL, -WALL), BLUE);
24         view.drawLine(point(-WALL, WALL), point(-WALL, -WALL), BLUE);
25         (*it).force = behavior.stayInArea(*it, WALL - DISTANCE);
26         (*it).force += behavior.separation(agents, *it, 4);
27     }
28     refresh();
29 }
```

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/prison.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/prison.cpp](#)

## 6.17 pursuit Class Reference

```
#include <pursuit.h>
```

### Public Member Functions

- [pursuit\(\)](#)  
*default constructor.*

### Static Public Member Functions

- static void [loop\(\)](#)  
*pursuing scenario loop function*

### Additional Inherited Members

#### 6.17.1 Detailed Description

Definition at line 14 of file pursuit.h.

## 6.17.2 Constructor & Destructor Documentation

### 6.17.2.1 pursuit()

```
pursuit::pursuit ( )
```

default constructor.

Definition at line 31 of file pursuit.cpp.

```
32 {
33     name = "pursuit";
34     createStaticAgents("gazelle", "lion");
35     callback = reinterpret_cast <void(*) ()> ( (void *)(&loop) );
36 }
```

## 6.17.3 Member Function Documentation

### 6.17.3.1 loop()

```
void pursuit::loop ( ) [static]
```

pursuing scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file pursuit.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         if((*it).getName() == "gazelle"){
19             (*it).setTarget(view.getMousePosition());
20             (*it).force = behavior.seek(*it);
21         }
22         else{//lion
23             (*it).force = behavior.pursuit(agents, *it, view, "gazelle");
24         }
25         (*it).arrive = true;
26     }
27     refresh();
28 }
29 }
```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/pursuit.h
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/pursuit.cpp

## 6.18 pvector Class Reference

```
#include <pvector.h>
```



## Public Member Functions

- `pvector ()`  
*default constructor*
- `pvector (float x, float y)`  
*constructor*
- `float magnitude ()`  
*calculates magnitude of the vector*
- `pvector & normalize ()`  
*normalize*
- `void div (float i)`  
*vector division*
- `void mul (float i)`  
*vector multiplication*
- `void add (pvector p)`  
*addition of vectors*
- `void limit (float limit)`  
*vector limitation*
- `float getAngle ()`  
*calculates vector angle*
- `float dotProduct (pvector v)`  
*dot product of two vectors*
- `float angleBetween (pvector v)`  
*angle calculation between two vectors*
- `void print (const string &s)`  
*debug function*
- `pvector operator+= (pvector const &obj)`  
*overloaded += operator*
- `pvector operator+ (pvector const &obj)`  
*overloaded + operator*
- `pvector operator- (pvector const &obj)`  
*overloaded - operator*
- `pvector operator- (point const &obj)`  
*overloaded - operator*
- `pvector operator+ (point const &obj)`  
*overloaded + operator*
- `bool operator== (pvector const &obj)`  
*overloaded == operator*

## Public Attributes

- `float x`  
*x magnitude of the vector*
- `float y`  
*y magnitude of the vector*

### 6.18.1 Detailed Description

Definition at line 17 of file pvector.h.

## 6.18.2 Constructor & Destructor Documentation

### 6.18.2.1 `pvector()` [1/2]

```
pvector::pvector ( )
```

default constructor

See also

[pvector\(float x, float y\)](#)

Definition at line 35 of file `pvector.cpp`.

```
36 {  
37     x = 0;  
38     y = 0;  
39 }
```

### 6.18.2.2 `pvector()` [2/2]

```
pvector::pvector (  
    float x,  
    float y )
```

constructor

Parameters

<i>x</i>	magnitude of the vector
<i>y</i>	magnitude of the vector

See also

[pvector\(\)](#)

Definition at line 41 of file `pvector.cpp`.

```
42 {  
43     this->x = x;  
44     this->y = y;  
45 }
```

## 6.18.3 Member Function Documentation

### 6.18.3.1 add()

```
void pvector::add (  
    pvector p )
```

addition of vectors

### Parameters

$p$	vector to add
-----	---------------

Definition at line 59 of file pvector.cpp.

```
60 {  
61      $x = x + p.x$ ;  
62      $y = y + p.y$ ;  
63 }
```

### 6.18.3.2 angleBetween()

```
float pvector::angleBetween (  
    pvector v )
```

angle calculation between two vectors

### Parameters

$v$	vector to calculate angle
-----	---------------------------

### Returns

angle

Definition at line 23 of file pvector.cpp.

```
24 {  
25     float angle = this->dotProduct(v) / (this->magnitude() * v.magnitude());  
26     angle = acos(angle) * 180 / PI;  
27     return angle;  
28 }
```

### 6.18.3.3 div()

```
void pvector::div (  
    float i )
```

vector division

### Parameters

$i$	scalar value to divide
-----	------------------------

Definition at line 47 of file pvector.cpp.

```
48 {  
49      $x = x / i$ ;  
50      $y = y / i$ ;  
51 }
```

#### 6.18.3.4 dotProduct()

```
float pvector::dotProduct (
    pvector v )
```

dot product of two vectors

##### Parameters

<i>v</i>	vector to calculate dot product
----------	---------------------------------

##### Returns

returns scalar dot product

Definition at line 30 of file pvector.cpp.

```
31 {
32     return ((x * v.x) + (y * v.y));
33 }
```

#### 6.18.3.5 getAngle()

```
float pvector::getAngle ( )
```

calculates vector angle

##### Returns

angle

Definition at line 16 of file pvector.cpp.

```
17 {
18     float angle;
19     angle = atan2 (this->y, this->x) * 180 / PI;
20     return angle;
21 }
```

#### 6.18.3.6 limit()

```
void pvector::limit (
    float limit )
```

vector limitation

##### Parameters

<i>limit</i>	value to restrict vector magnitude
--------------	------------------------------------

Definition at line 84 of file pvector.cpp.

```
85 {  
86     this->normalize();  
87     this->mul(limit);  
88 }
```

### 6.18.3.7 magnitude()

```
float pvector::magnitude ( )
```

calculates magnitude of the vector

#### Returns

magnitude of the vector

Definition at line 65 of file pvector.cpp.

```
66 {  
67     return sqrt((this->x * this->x) + (this->y * this->y));  
68 }
```

### 6.18.3.8 mul()

```
void pvector::mul (  
                    float i )
```

vector multiplication

#### Parameters

<i>i</i>	scalar value to multiply
----------	--------------------------

Definition at line 53 of file pvector.cpp.

```
54 {  
55     x = x * i;  
56     y = y * i;  
57 }
```

### 6.18.3.9 normalize()

```
pvector & pvector::normalize ( )
```

normalize

**Returns**

normalized vector

Definition at line 70 of file pvector.cpp.

```
71 {  
72     float magnitude = this->magnitude();  
73     if(magnitude != 0){  
74         this->x = this->x / magnitude;  
75         this->y = this->y / magnitude;  
76     }  
77     else{  
78         this->x = 0;  
79         this->y = 0;  
80     }  
81     return *this;  
82 }
```

**6.18.3.10 operator+() [1/2]**

```
pvector pvector::operator+ (  
    point const & obj )
```

overloaded + operator

**Parameters**

<i>obj</i>	point to add
------------	--------------

**Returns**

sum

Definition at line 112 of file pvector.cpp.

```
113 {  
114     pvector res;  
115     res.x = x + obj.x;  
116     res.y = y + obj.y;  
117     return res;  
118 }
```

**6.18.3.11 operator+() [2/2]**

```
pvector pvector::operator+ (  
    pvector const & obj )
```

overloaded + operator

**Parameters**

<i>obj</i>	vector to add
------------	---------------

**Returns**

sum

Definition at line 90 of file pvector.cpp.

```
91 {  
92     pvector res;  
93     res.x = x + obj.x;  
94     res.y = y + obj.y;  
95     return res;  
96 }
```

**6.18.3.12 operator+=()**

```
pvector pvector::operator+= (  
    pvector const & obj )
```

overloaded += operator

**Parameters**

<i>obj</i>	vector to add
------------	---------------

**Returns**

sum

Definition at line 98 of file pvector.cpp.

```
99 {  
100     x = x + obj.x;  
101     y = y + obj.y;  
102     return *this;  
103 }
```

**6.18.3.13 operator-() [1/2]**

```
pvector pvector::operator- (  
    point const & obj )
```

overloaded - operator

**Parameters**

<i>obj</i>	point to substract
------------	--------------------

**Returns**

difference

Definition at line 120 of file pvector.cpp.



```
121 {  
122     pvector res;  
123     res.x = x - obj.x;  
124     res.y = y - obj.y;  
125     return res;  
126 }
```

#### 6.18.3.14 operator-() [2/2]

```
pvector pvector::operator- (  
    pvector const & obj )
```

overloaded - operator

##### Parameters

<i>obj</i>	vector to subtract
------------	--------------------

##### Returns

difference

Definition at line 133 of file pvector.cpp.

```
134 {  
135     pvector res;  
136     res.x = x - obj.x;  
137     res.y = y - obj.y;  
138     return res;  
139 }
```

#### 6.18.3.15 operator==( )

```
bool pvector::operator==(   
    pvector const & obj )
```

overloaded == operator

##### Parameters

<i>obj</i>	vector to check if equal
------------	--------------------------

##### Returns

comparison result

Definition at line 105 of file pvector.cpp.

```
106 {  
107     if (x == obj.x && y == obj.y)  
108         return true;  
109     return false;  
110 }
```

### 6.18.3.16 print()

```
void pvector::print (
    const string & s )
```

debug function

#### Parameters

s	identification text
---	---------------------

Definition at line 128 of file pvector.cpp.

```
129 {
130     cout << s << " " << x << " " << y << endl;
131 }
```

## 6.18.4 Member Data Documentation

### 6.18.4.1 x

```
float pvector::x
```

x magnitude of the vector

Definition at line 140 of file pvector.h.

### 6.18.4.2 y

```
float pvector::y
```

y magnitude of the vector

Definition at line 145 of file pvector.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[pvector.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[pvector.cpp](#)

## 6.19 random Class Reference

```
#include <random.h>
```

## Static Public Member Functions

- static void [createRandomArray](#) (int \*arr, int size)  
*random array generation*

### 6.19.1 Detailed Description

Definition at line 9 of file random.h.

### 6.19.2 Member Function Documentation

#### 6.19.2.1 createRandomArray()

```
void random::createRandomArray (
    int * arr,
    int size ) [static]
```

random array generation

#### Parameters

<i>arr</i>	struct that includes random values
<i>size</i>	of the array

Definition at line 14 of file random.cpp.

```
14                                     {
15     //srand(time(NULL));
16     for(int i=0; i<size; i++)
17         arr[i] = i+1;
18
19     for (int i=0; i < size; i++){
20         int r = rand() % size;
21         swap(arr[i], arr[r]);
22     }
23 }
```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[random.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[random.cpp](#)

## 6.20 scenario Class Reference

```
#include <scenario.h>
```

## Public Member Functions

- [scenario](#) ()  
*default constructor.*
- void [initGL](#) (int \*argv, char \*\*argc)  
*graphics initialization*
- void [createRandomAgents](#) (int agentCount, float mForce, float mSpeed)  
*random agent creation*
- void [createStaticAgents](#) (string s1, string s2)  
*static agent creation*
- void [createTroop](#) (int agentCount)  
*troop creation*

## Static Public Member Functions

- static void [refresh](#) ()  
*refreshes all items*

## Public Attributes

- void(\* [callback](#) )()  
*openGL screen refresh callback function, used as main loop in derived classes*

## Static Public Attributes

- static vector< [agent](#) > [agents](#)  
*structure stores agents*
- static [graphics view](#)  
*graphics instance used*
- static [steeringBehavior behavior](#)  
*behavior instance used*
- static string [name](#)  
*scenario name*

### 6.20.1 Detailed Description

Definition at line 19 of file scenario.h.

### 6.20.2 Constructor & Destructor Documentation

### 6.20.2.1 scenario()

```
scenario::scenario ( )
```

default constructor.

Definition at line 28 of file scenario.cpp.

```
29 {
30     view = graphics();
31 }
```

## 6.20.3 Member Function Documentation

### 6.20.3.1 createRandomAgents()

```
void scenario::createRandomAgents (
    int agentCount,
    float mForce,
    float mSpeed )
```

random agent creation

Parameters

<i>agentCount</i>	number of agents
<i>mForce</i>	maxForce
<i>mSpeed</i>	maxSpeed

Definition at line 45 of file scenario.cpp.

```
46 {
47     int size = MAX_NUMBER_OF_AGENTS * 2;
48     int arr[size];
49
50     srand(time(NULL));
51     random::createRandomArray(arr, size);
52
53     agent tempAgent {0, 0};
54     for(int i=0; i < count * 2; i=i+2){
55         tempAgent.setName("agent"+to_string(i)+":");
56         tempAgent.position.x = arr[i] - WIDTH;
57         tempAgent.position.y = arr[i+1] - HEIGHT;
58
59         //float f = (float) arr[i] / (float) 100.0;
60         //float s = (float) arr[i+1] / (float) 100.0;
61         //if( f > force ) f = force;
62         //if( s > speed ) s = speed;
63         //if( s > f ) s = f;
64
65         tempAgent.setColor(color::getColor((i/2) % 8));
66         tempAgent.setFeatures(speed, force, 5, 1);
67         agents.push_back(tempAgent);
68     }
69 }
```

### 6.20.3.2 createStaticAgents()

```
void scenario::createStaticAgents (
```

```

        string s1,
        string s2 )

```

static agent creation

#### Parameters

<i>s1</i>	name of the first agent
<i>s2</i>	name of the second agent

Definition at line 71 of file scenario.cpp.

```

72 {
73     agent agent1 {-10.0, 0.0};
74     agent1.id = 1;
75     agent1.setName(s1);
76     agent1.setColor(BLUE);
77     agent1.setFeatures(0.5, 0.2, 5, 1);
78     agents.push_back(agent1);
79
80     agent agent2 { 10.0, 0.0};
81     agent2.id = 2;
82     agent2.setName(s2);
83     agent2.setColor(RED);
84     agent2.setFeatures(0.4, 0.2, 5, 1);
85     agents.push_back(agent2);
86 }

```

### 6.20.3.3 createTroop()

```

void scenario::createTroop (
    int agentCount )

```

troop creation

#### Parameters

<i>number</i>	of agents in the troop
---------------	------------------------

Definition at line 88 of file scenario.cpp.

```

89 {
90     int row = 14;
91     int blanks = 5;
92     int rowStartPosition = -33;
93     agent tempAgent {0, 0};
94     pvector location {-33, 33};
95
96     for(int i=0; i < count; i++){
97         tempAgent.id = i;
98         tempAgent.setVelocity(pvector(0, 0));
99         tempAgent.position.x = location.x;
100        tempAgent.position.y = location.y;
101        tempAgent.setTarget(tempAgent.position);
102
103        if( ((i+1) % row) == 0){
104            location.y -= blanks;
105            location.x = rowStartPosition;
106        }
107        else
108            location.x += blanks;
109
110        tempAgent.setColor(color::getColor((i/2) % 8));
111        tempAgent.setFeatures(0.3, 0.3, 5, 1);
112        agents.push_back(tempAgent);
113    }
114 }

```

### 6.20.3.4 initGL()

```
void scenario::initGL (
    int * argv,
    char ** argc )
```

graphics initialization

#### Parameters

<i>argv</i>	list of user arguments
<i>argc</i>	number of user arguments

Definition at line 23 of file scenario.cpp.

```
24 {
25     view.initGraphics(argc, argv, callback);
26 }
```

### 6.20.3.5 refresh()

```
void scenario::refresh ( ) [static]
```

refreshes all items

#### Note

opengl callback forces that function to be static

Definition at line 33 of file scenario.cpp.

```
34 {
35     point textPosition = point(-34, 32.25);
36
37     for(auto it = agents.begin(); it < agents.end(); it++){
38         (*it).draw(view);
39     }
40
41     view.drawText(name, textPosition);
42     view.refreshScene();
43 }
```

## 6.20.4 Member Data Documentation

### 6.20.4.1 agents

```
vector< agent > scenario::agents [static]
```

structure stores agents

#### Note

opengl callback forces that function to be static

Definition at line 43 of file scenario.h.

#### 6.20.4.2 behavior

```
steeringBehavior scenario::behavior [static]
```

behavior instance used

##### Note

opengl callback forces that function to be static

Definition at line 55 of file scenario.h.

#### 6.20.4.3 callback

```
void(* scenario::callback) ()
```

openGL screen refresh callback function, used as main loop in derived classes

Definition at line 66 of file scenario.h.

#### 6.20.4.4 name

```
string scenario::name [static]
```

scenario name

##### Note

opengl callback forces that function to be static

Definition at line 61 of file scenario.h.

#### 6.20.4.5 view

```
graphics scenario::view [static]
```

graphics instance used

##### Note

opengl callback forces that function to be static

Definition at line 49 of file scenario.h.

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[scenario.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[scenario.cpp](#)



## 6.21 steeringBehavior Class Reference

```
#include <steeringBehavior.h>
```

### Public Member Functions

- [pvector stayInArea](#) ([agent](#) &[agent](#), int turnPoint)  
*gets reflection force*
- [pvector inFlowField](#) ([agent](#) &[agent](#), [flowField](#) &flow)  
*gets flow field force*
- [pvector stayInPath](#) ([agent](#) &[agent](#), [path](#) &[path](#), [graphics](#) view)  
*gets force to follow path*
- [pvector seek](#) ([agent](#) &[agent](#))  
*force to seek*
- [pvector separation](#) (vector< [agent](#) > agents, [agent](#) &[agent](#), float radius)  
*force to separate*
- [pvector cohesion](#) (vector< [agent](#) > boids, [agent](#) &[agent](#), float radius)  
*force to cohesion*
- [pvector align](#) (vector< [agent](#) > boids, [agent](#) &[agent](#), float radius)  
*force to align*
- [pvector wander](#) ([agent](#) &[agent](#))  
*force to wander*
- [pvector pursuit](#) (vector< [agent](#) > boids, [agent](#) &pursuer, [graphics](#) view, string name)  
*force to pursue*
- [pvector evade](#) (vector< [agent](#) > boids, [agent](#) &evader, [graphics](#) view, string name)  
*force to evade*
- [pvector flee](#) ([agent](#) &[agent](#), [graphics](#) &view, [point](#) p)  
*force to flee*
- [pvector avoid](#) (vector< [obstacle](#) > obstacles, [agent](#) &[agent](#))  
*force to avoid*

### 6.21.1 Detailed Description

Definition at line 36 of file steeringBehavior.h.

### 6.21.2 Member Function Documentation

#### 6.21.2.1 align()

```
pvector steeringBehavior::align (
    vector< agent > boids,
    agent & agent,
    float radius )
```

force to align

**Parameters**

<i>agent</i>	to be aligned
<i>boids</i>	list of all the agents
<i>radius</i>	range for agents that will be aligned

**Returns**

force to be applied

Definition at line 120 of file steeringBehavior.cpp.

```

121 {
122     pvector sum {0,0};
123     int count = 0;
124     for(auto it = boids.begin(); it < boids.end(); it++){
125         float d = (agent.position - (*it).position).magnitude();
126         if( (d > 0) && (d < radius) ){
127             sum += (*it).getVelocity();
128             count++;
129         }
130     }
131     if(count > 0){
132         sum.div(count);
133         sum.normalize().mul(agent.maxSpeed);
134         agent.steering = sum - agent.getVelocity();
135         return agent.steering;
136     }
137     return pvector(0,0);
138 }
```

**6.21.2.2 avoid()**

```

pvector steeringBehavior::avoid (
    vector< obstacle > obstacles,
    agent & agent )
```

force to avoid

**Parameters**

<i>agent</i>	agent that will avoid from obstacles
<i>obstacles</i>	list of all existing objects

**Returns**

force to be applied

Definition at line 181 of file steeringBehavior.cpp.

```

182 {
183     float dynamic_length = agent.getVelocity().magnitude() / agent.maxSpeed;
184     pvector vel = agent.getVelocity();
185     vel.normalize().mul(dynamic_length);
186     pvector ahead = vel + agent.position;
187     vel.mul(6);
188     pvector ahead2 = vel + agent.position;
189     //view.drawPoint(point(ahead.x, ahead.y));
190     //view.drawPoint(point(ahead2.x, ahead2.y));
191 }
```

```

192     for(auto it = obstacles.begin(); it < obstacles.end(); it++){
193         float dist = (ahead - (*it).getCenter()).magnitude();
194         float dist2 = (ahead2 - (*it).getCenter()).magnitude();
195         if(dist < (*it).getRadius() + 2 || dist2 < (*it).getRadius() + 2){
196             pvector avoidance = ahead - (*it).getCenter();
197             avoidance.normalize().mul(20);
198             /*a = point(avoidance.x, avoidance.y);
199             view.drawLine(agent.position, agent.position + a, color(0,1,0));*/
200             return avoidance;
201         }
202     }
203     return pvector(0,0);
204 }

```

### 6.21.2.3 cohesion()

```

pvector steeringBehavior::cohesion (
    vector< agent > boids,
    agent & agent,
    float radius )

```

force to cohesion

#### Parameters

<i>agent</i>	to go to center of other agents, with specified distance
<i>boids</i>	list of all the agents
<i>radius</i>	range for agents that will be aligned

#### Returns

force to be applied

Definition at line 140 of file steeringBehavior.cpp.

```

141 {
142     point sum {0,0};
143     int count = 0;
144     for(auto it = boids.begin(); it < boids.end(); it++){
145         float d = (agent.position - (*it).position).magnitude();
146         if( (d > 0) && (d < radius) ){
147             sum = sum + (*it).position;
148             count++;
149         }
150     }
151     if(count > 0){
152         sum.div(count);
153         agent.setTarget(sum);
154         return seek(agent);
155     }
156     return pvector(0,0);
157 }

```

### 6.21.2.4 evade()

```

pvector steeringBehavior::evade (
    vector< agent > boids,
    agent & evader,
    graphics view,
    string name )

```

force to evade

## Parameters

<i>evader</i>	agent that will escape
<i>view</i>	used for debugging
<i>boids</i>	list of all the agents
<i>name</i>	other agent to evade

## Returns

force to be applied

Definition at line 47 of file steeringBehavior.cpp.

```

48 {
49     agent target;
50     for(auto it = boids.begin(); it < boids.end(); it++){
51         if((*it).getName() == name){
52             target = *it;
53         }
54     }
55
56     point p = point(evader.position.x + 2, evader.position.y - 2);
57     view.drawText(evader.getName(), p);
58     p = point(target.position.x + 2, target.position.y - 2);
59     view.drawText(target.getName(), p);
60
61     pvector targetVel = target.getVelocity();
62     targetVel.mul(5); //TODO: magic number
63
64     point futurePos = target.position + targetVel;
65     //view.drawPoint(futurePos);
66
67     pvector dist = evader.position - futurePos;
68     dist.normalize().mul(1 / dist.magnitude());
69
70     evader.setTarget(evader.position + dist);
71     return flee(evader, view, futurePos);
72 }
```

## 6.21.2.5 flee()

```

pvector steeringBehavior::flee (
    agent & agent,
    graphics & view,
    point p )
```

force to flee

## Parameters

<i>agent</i>	agent that will flee
<i>view</i>	used for debugging
<i>p</i>	point that agent flees

## Returns

force to be applied

Definition at line 28 of file steeringBehavior.cpp.

```

29 {
30     int radius = 15;
31
32     pvector dist = agent.getTarget() - p;
33     //view.drawPoint(agent.targetPoint);
34
35     if(dist.magnitude() < radius){
36         agent.arrive = false;
37         agent.desiredVelocity = agent.position - p;
38     }
39     else{
40         agent.arrive = true;
41         agent.desiredVelocity = agent.getTarget() - agent.position;
42     }
43     agent.steering = agent.desiredVelocity - agent.getVelocity();
44     return agent.steering;
45 }

```

### 6.21.2.6 inFlowField()

```

pvector steeringBehavior::inFlowField (
    agent & agent,
    flowField & flow )

```

gets flow field force

#### Parameters

<i>agent</i>	unit to apply flow field
<i>flow</i>	field

#### Returns

force to be applied

Definition at line 236 of file steeringBehavior.cpp.

```

237 {
238     //pos_x, pos_y must be non negative integer
239     int pos_x = abs((int)agent.position.x) % WIDTH;
240     int pos_y = abs((int)agent.position.y) % HEIGHT;
241     //TODO: modification required for non uniform fields
242     return flow.getField(pos_x, pos_y);
243 }

```

### 6.21.2.7 pursuit()

```

pvector steeringBehavior::pursuit (
    vector< agent > boids,
    agent & pursuer,
    graphics view,
    string name )

```

force to pursue

**Parameters**

<i>pursuer</i>	agent that will follow specified agent
<i>view</i>	used for debugging
<i>boids</i>	list of all the agents
<i>name</i>	other agent to pursue

**Returns**

force to be applied

Definition at line 74 of file steeringBehavior.cpp.

```

75 {
76     agent target;
77     for(auto it = boids.begin(); it < boids.end(); it++){
78         if((*it).getName() == name){
79             target = *it;
80         }
81     }
82
83     point p = point(target.position.x + 2, target.position.y - 2);
84     view.drawText(target.getName(), p);
85
86     p = point(pursuer.position.x + 2, pursuer.position.y - 2);
87     view.drawText(pursuer.getName(), p);
88
89     float dist = (target.position - pursuer.position).magnitude();
90     float t = dist / target.maxSpeed;
91
92     pvector targetVel = target.getVelocity();
93     targetVel.mul(t);
94     point futurePos = target.position + targetVel;
95     pursuer.setTarget(futurePos);
96     return seek(pursuer);
97 }
```

**6.21.2.8 seek()**

```
pvector steeringBehavior::seek (
    agent & agent )
```

force to seek

**Parameters**

<i>agent</i>	that will go to specific target point
--------------	---------------------------------------

**Returns**

force to be applied

Definition at line 206 of file steeringBehavior.cpp.

```

207 {
208     agent.desiredVelocity = agent.getTarget() - agent.position;
209     agent.steering = agent.desiredVelocity - agent.getVelocity();
210     return agent.steering;
211 }
```

### 6.21.2.9 separation()

```
pvector steeringBehavior::separation (
    vector< agent > agents,
    agent & agent,
    float radius )
```

force to separate

#### Parameters

<i>agent</i>	agent that will be stayed away
<i>agents</i>	list of all the agents
<i>radius</i>	range for agents that will be aligned

#### Returns

force to be applied

Definition at line 159 of file steeringBehavior.cpp.

```
160 {
161     pvector sum = pvector(0,0);
162     int count = 0;
163     for(auto it = agents.begin(); it < agents.end(); it++){
164         float d = (agent.position - (*it).position).magnitude();
165         if( (d > 0) && (d < radius) ){
166             pvector diff = agent.position - (*it).position;
167             diff.normalize().div(d);
168             sum = sum + diff;
169             count++;
170         }
171     }
172     if(count > 0){
173         sum.div(count);
174         sum.normalize().mul(agent.maxSpeed);
175         agent.steering = sum - agent.getVelocity();
176         return agent.steering;
177     }
178     return pvector(0,0);
179 }
```

### 6.21.2.10 stayInArea()

```
pvector steeringBehavior::stayInArea (
    agent & agent,
    int turnPoint )
```

gets reflection force

#### Parameters

<i>agent</i>	unit to check
<i>turnpoint</i>	defines border to apply force

**Returns**

force to be applied

Definition at line 245 of file steeringBehavior.cpp.

```

246 {
247     if(agent.position.x >= turnPoint){
248         agent.desiredVelocity = pvector( -agent.maxSpeed, agent.getVelocity().y );
249         agent.steering = agent.desiredVelocity - agent.getVelocity();
250         agent.steering.mul(5);
251         return agent.steering;
252     }
253     else if(agent.position.x <= -turnPoint){
254         agent.desiredVelocity = pvector( agent.maxSpeed, agent.getVelocity().y );
255         agent.steering = agent.desiredVelocity - agent.getVelocity();
256         agent.steering.mul(5);
257         return agent.steering;
258     }
259     else if(agent.position.y >= turnPoint){
260         agent.desiredVelocity = pvector( agent.getVelocity().x, -agent.maxSpeed );
261         agent.steering = agent.desiredVelocity - agent.getVelocity();
262         agent.steering.mul(5);
263         return agent.steering;
264     }
265     else if(agent.position.y <= -turnPoint){
266         agent.desiredVelocity = pvector( agent.getVelocity().x, agent.maxSpeed );
267         agent.steering = agent.desiredVelocity - agent.getVelocity();
268         agent.steering.mul(5);
269         return agent.steering;
270     }
271     return pvector(0,0);
272 }
```

**6.21.2.11 stayInPath()**

```

pvector steeringBehavior::stayInPath (
    agent & agent,
    path & path,
    graphics view )
```

gets force to follow path

**Parameters**

<i>agent</i>	to follow the pathk
<i>path</i>	to follow
<i>view</i>	used for debugging

**Returns**

force to be applied

Definition at line 213 of file steeringBehavior.cpp.

```

214 {
215     float worldRecord = 1000000;
216     point normalPoint, predictedPos, start, end;
217     pvector distance;
218     for(auto it = path.points.begin(); it < path.points.end()-1; it++){
219         start = point((*it).x, (*it).y);
220         end = point((*it+1).x, (*it+1).y);
221         predictedPos = agent.position + agent.getVelocity();
222         normalPoint.getNormalPoint(predictedPos, start, end);
223         if (normalPoint.x < start.x || normalPoint.x > end.x){
224             normalPoint = end;
225         }
226     }
```



```

226     distance = predictedPos - normalPoint;
227     if (distance.magnitude() < worldRecord){
228         worldRecord = distance.magnitude();
229         agent.setTarget(end);
230     }
231     view.drawPoint(agent.getTarget(), RED);
232 }
233 return seek(agent);
234 }

```

### 6.21.2.12 wander()

```

pvector steeringBehavior::wander (
    agent & agent )

```

force to wander

#### Parameters

<i>agent</i>	agent that will wander
--------------	------------------------

#### Returns

force to be applied

Definition at line 99 of file steeringBehavior.cpp.

```

100 {
101     pvector circleCenter = agent.getVelocity();
102     circleCenter.normalize().mul(CIRCLE_DISTANCE + CIRCLE_RADIUS);
103
104     int wanderAngle = (rand() % 360);
105     pvector displacement {0, 1};
106     setAngle(displacement, wanderAngle);
107     displacement.mul(CIRCLE_RADIUS);
108
109     agent.desiredVelocity = displacement + circleCenter;
110     agent.steering = agent.desiredVelocity - agent.getVelocity();
111
112     //move it to the center when it is out of screen
113     if(agent.position.x > WIDTH || agent.position.x < -WIDTH ||
114        agent.position.y > HEIGHT || agent.position.y < -HEIGHT)
115         agent.position = point(0,0);
116
117     return agent.steering;
118 }

```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/steeringBehavior.h
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/steeringBehavior.cpp

## 6.22 wander Class Reference

```
#include <wander.h>
```

### Public Member Functions

- [wander\(\)](#)  
*default constructor*

## Static Public Member Functions

- static void [loop](#) ()  
*wander scenario loop function*

## Additional Inherited Members

### 6.22.1 Detailed Description

Definition at line 14 of file wander.h.

### 6.22.2 Constructor & Destructor Documentation

#### 6.22.2.1 wander()

wander::wander ( )

default constructor

**Todo** business logic will be changed

Definition at line 23 of file wander.cpp.

```
24 {
25     int agentCount = 30;
26     float maxForce = 0.3;
27     float maxSpeed = 0.6;
28     name = "wandering objects";
29     createRandomAgents(agentCount, maxForce, maxSpeed);
30     callback = reinterpret_cast<void(*)()> ( (void *)(&loop) );
31 }
```

### 6.22.3 Member Function Documentation

#### 6.22.3.1 loop()

void wander::loop ( ) [static]

wander scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 15 of file wander.cpp.

```
16 {
17     for(auto it = agents.begin(); it < agents.end(); it++){
18         (*it).force = behavior.wander(*it);
19     }
20     refresh();
21 }
```

The documentation for this class was generated from the following files:

- /home/user/Desktop/mmm/autonomousSteeringAgents/include/[wander.h](#)
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/[wander.cpp](#)

## 6.23 windy Class Reference

```
#include <windy.h>
```

### Public Member Functions

- `windy()`  
*default constructor.*

### Static Public Member Functions

- static void `loop()`  
*windy scenario loop function*

### Static Public Attributes

- static `flowField flow`  
*flow field used*

### Additional Inherited Members

#### 6.23.1 Detailed Description

Definition at line 15 of file windy.h.

#### 6.23.2 Constructor & Destructor Documentation

##### 6.23.2.1 windy()

```
windy::windy ( )
```

default constructor.

Definition at line 29 of file windy.cpp.

```
30 {  
31     int agentCount = 50;  
32     float maxForce = 0.3;  
33     float maxSpeed = 0.6;  
34  
35     name = "flow field";  
36     createRandomAgents(agentCount, maxForce,  
37     maxSpeed);  
38     callback = reinterpret_cast <void(*)()> ( (void *)(&loop) );  
39 }
```

## 6.23.3 Member Function Documentation

### 6.23.3.1 loop()

```
void windy::loop ( ) [static]
```

windy scenario loop function

#### Note

opengl callback forces that function to be static

Definition at line 17 of file windy.cpp.

```
18 {  
19     for(auto it = agents.begin(); it < agents.end(); it++){  
20         flow = flowField(pvector(GRAVITY));  
21         (*it).force = behavior.inFlowField(*it, flow);  
22     }  
23     flow = flowField(pvector(WIND_WEST));  
24     (*it).force += behavior.inFlowField(*it, flow);  
25 }  
26 refresh();  
27 }
```

## 6.23.4 Member Data Documentation

### 6.23.4.1 flow

```
flowField windy::flow [static]
```

flow field used

#### Note

opengl callback forces that function to be static

Definition at line 32 of file windy.h.

The documentation for this class was generated from the following files:

- [/home/user/Desktop/mmm/autonomousSteeringAgents/include/windy.h](#)
- [/home/user/Desktop/mmm/autonomousSteeringAgents/src/windy.cpp](#)

## Chapter 7

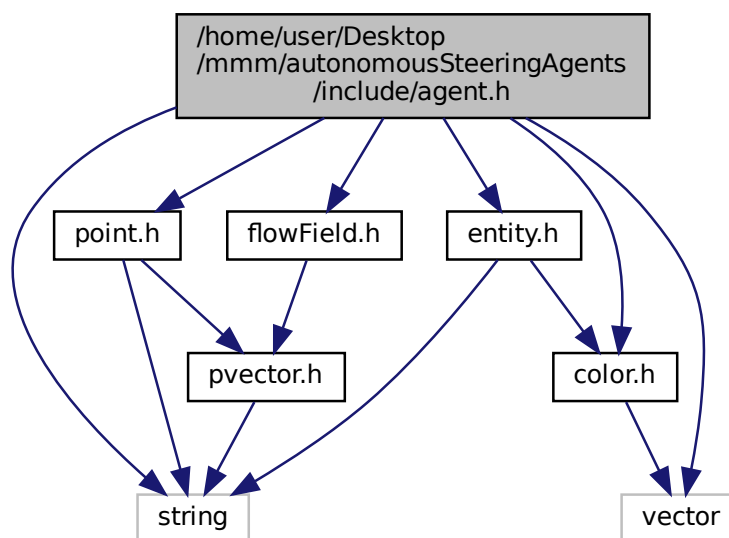
# File Documentation

- 7.1    /home/user/Desktop/mmm/autonomousSteeringAgents/agent.d File Reference**
- 7.2    /home/user/Desktop/mmm/autonomousSteeringAgents/color.d File Reference**
- 7.3    uml/activity\_diagram/todo.txt File Reference**
- 7.4    uml/state\_diagram/todo.txt File Reference**
- 7.5    uml/use\_case\_diagram/todo.txt File Reference**
- 7.6    /home/user/Desktop/mmm/autonomousSteeringAgents/entity.d File Reference**
- 7.7    /home/user/Desktop/mmm/autonomousSteeringAgents/evade.d File Reference**
- 7.8    /home/user/Desktop/mmm/autonomousSteeringAgents/flee.d File Reference**
- 7.9    /home/user/Desktop/mmm/autonomousSteeringAgents/flock.d File Reference**
- 7.10   /home/user/Desktop/mmm/autonomousSteeringAgents/flowField.d File Reference**
- 7.11   /home/user/Desktop/mmm/autonomousSteeringAgents/graphics.d File Reference**
- 7.12   /home/user/Desktop/mmm/autonomousSteeringAgents/include/agent.h File Reference**

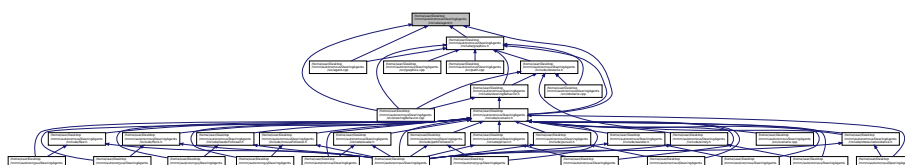
agent class defines all agent specifications

```
#include "point.h"
#include "color.h"
#include "entity.h"
#include "flowField.h"
#include <vector>
#include <string>
```

Include dependency graph for agent.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [agent](#)

### 7.12.1 Detailed Description

agent class defines all agent specifications

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

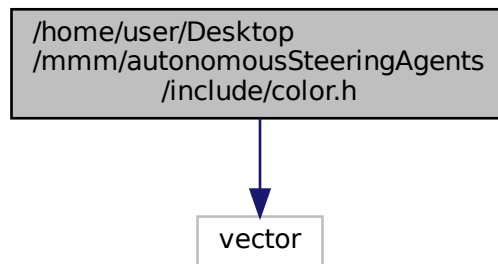
14.05.2021

## 7.13 /home/user/Desktop/mmm/autonomousSteeringAgents/include/color.h File Reference

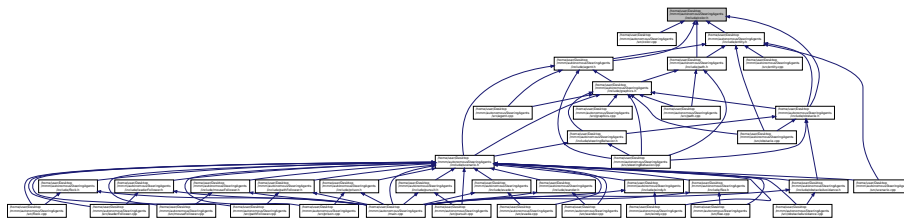
color class used for agent, path, wall etc. color

```
#include <vector>
```

Include dependency graph for color.h:



This graph shows which files directly or indirectly include this file:



### Classes

- class `color`

### Macros

- `#define BLACK color(0,0,0)`
- `#define BLUE color(0,0,1)`
- `#define GREEN color(0,1,0)`
- `#define CYAN color(0,1,1)`
- `#define RED color(1,0,0)`
- `#define YELLOW color(1,1,0)`
- `#define MAGENDA color(1,0,1)`
- `#define WHITE color(1,1,1)`



### 7.13.1 Detailed Description

color class used for agent, path, wall etc. color

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

13.05.2021

### 7.13.2 Macro Definition Documentation

#### 7.13.2.1 BLACK

```
#define BLACK color(0,0,0)
```

Definition at line 10 of file color.h.

#### 7.13.2.2 BLUE

```
#define BLUE color(0,0,1)
```

Definition at line 11 of file color.h.

#### 7.13.2.3 CYAN

```
#define CYAN color(0,1,1)
```

Definition at line 13 of file color.h.

#### 7.13.2.4 GREEN

```
#define GREEN color(0,1,0)
```

Definition at line 12 of file color.h.

#### 7.13.2.5 MAGENDA

```
#define MAGENDA color(1,0,1)
```

Definition at line 16 of file color.h.

#### 7.13.2.6 RED

```
#define RED color(1,0,0)
```

Definition at line 14 of file color.h.

#### 7.13.2.7 WHITE

```
#define WHITE color(1,1,1)
```

Definition at line 17 of file color.h.

#### 7.13.2.8 YELLOW

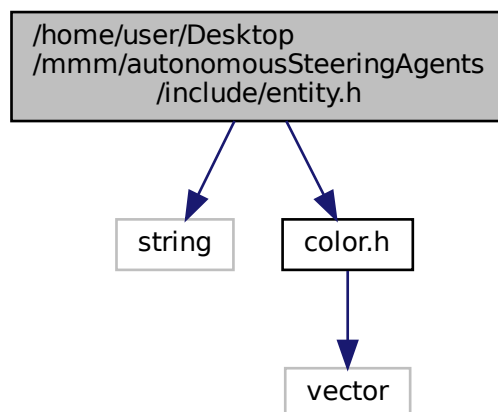
```
#define YELLOW color(1,1,0)
```

Definition at line 15 of file color.h.

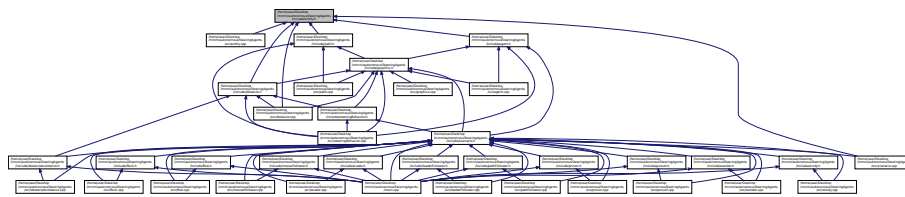
### 7.14 /home/user/Desktop/mmm/autonomousSteeringAgents/include/entity.h File Reference

```
#include <string>
#include "color.h"
```

Include dependency graph for entity.h:



This graph shows which files directly or indirectly include this file:



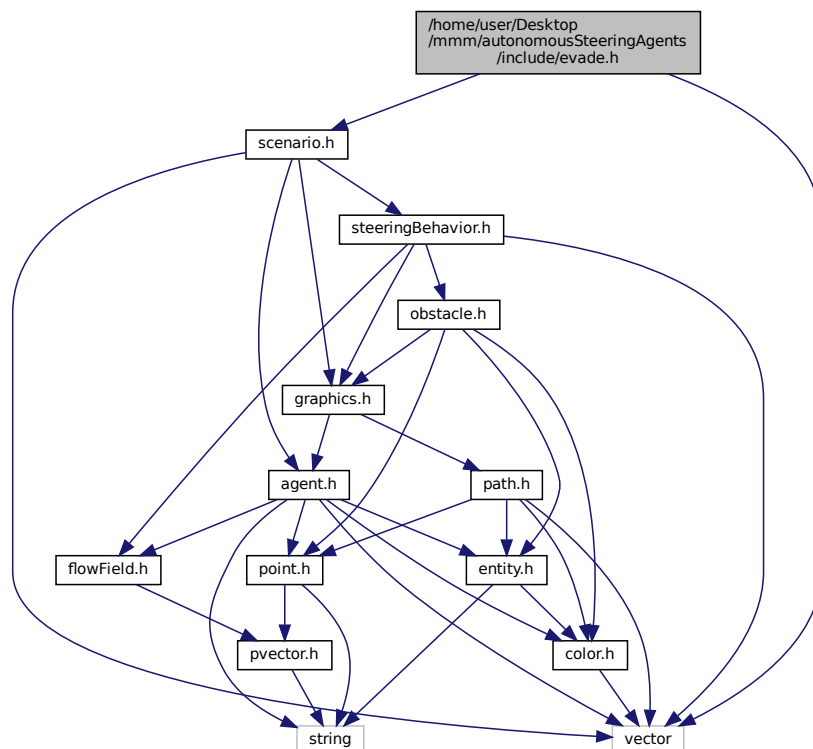
## Classes

- class [entity](#)

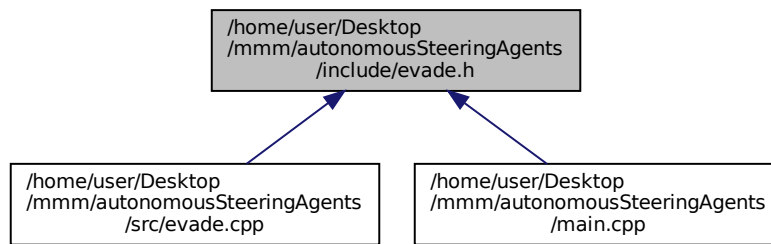
## 7.15 /home/user/Desktop/mmm/autonomousSteeringAgents/include/evade.h File Reference

evade class inherited from scenario class

```
#include "scenario.h"
#include <vector>
Include dependency graph for evade.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [evade](#)

### 7.15.1 Detailed Description

evade class inherited from scenario class

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

## 7.16 /home/user/Desktop/mmm/autonomousSteeringAgents/include/flee.h File Reference

agents flee from mouse scenario

```
#include "scenario.h"
#include <vector>
```



## Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

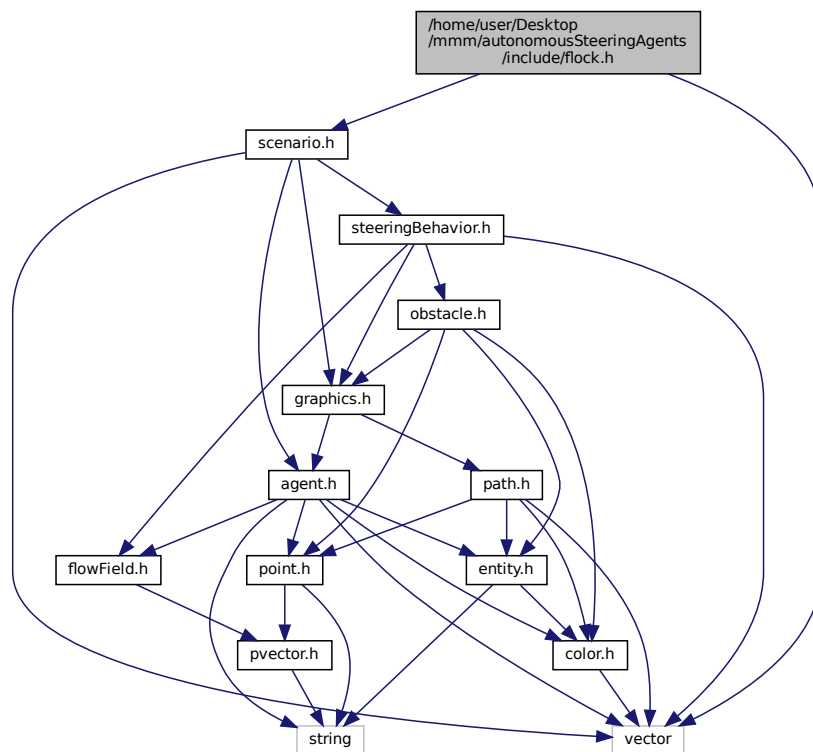
## Date

15.05.2021

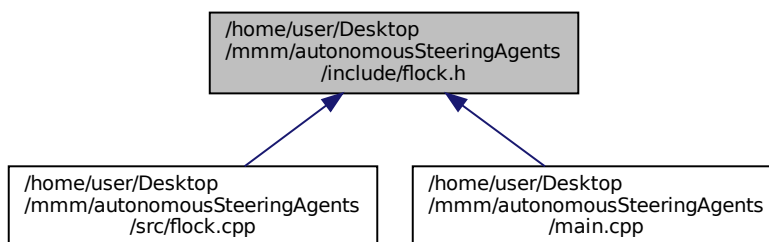
## 7.17 /home/user/Desktop/mmm/autonomousSteeringAgents/include/flock.h File Reference

flocking agents scenario

```
#include "scenario.h"
#include <vector>
Include dependency graph for flock.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [flock](#)

### 7.17.1 Detailed Description

flocking agents scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

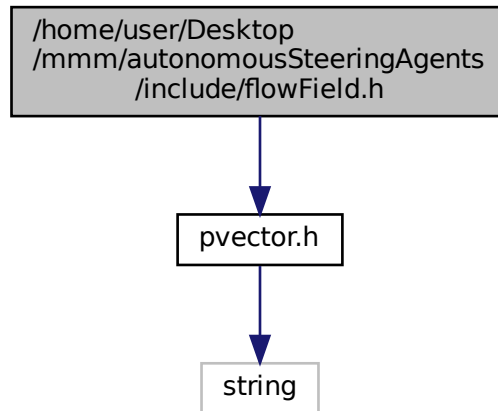
15.05.2021

## 7.18 /home/user/Desktop/mmm/autonomousSteeringAgents/include/flowField.h File Reference

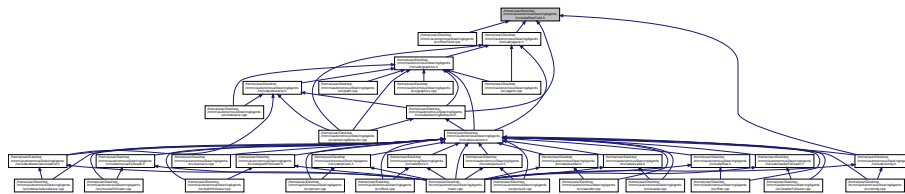
[flowField](#) class, screen can be filled with a force for each pixel

```
#include "pvector.h"
```

Include dependency graph for flowField.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [flowField](#)

## Macros

- #define [FIELD\\_WIDTH](#) 34
- #define [FIELD\\_HEIGHT](#) 34
- #define [WIND\\_WEST](#) 0.1, 0.0
- #define [GRAVITY](#) 0.0, -0.1

### 7.18.1 Detailed Description

[flowField](#) class, screen can be filled with a force for each pixel

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

13.05.2021



## 7.18.2 Macro Definition Documentation

### 7.18.2.1 FIELD\_HEIGHT

```
#define FIELD_HEIGHT 34
```

Definition at line 13 of file flowField.h.

### 7.18.2.2 FIELD\_WIDTH

```
#define FIELD_WIDTH 34
```

Definition at line 12 of file flowField.h.

### 7.18.2.3 GRAVITY

```
#define GRAVITY 0.0, -0.1
```

Definition at line 16 of file flowField.h.

### 7.18.2.4 WIND\_WEST

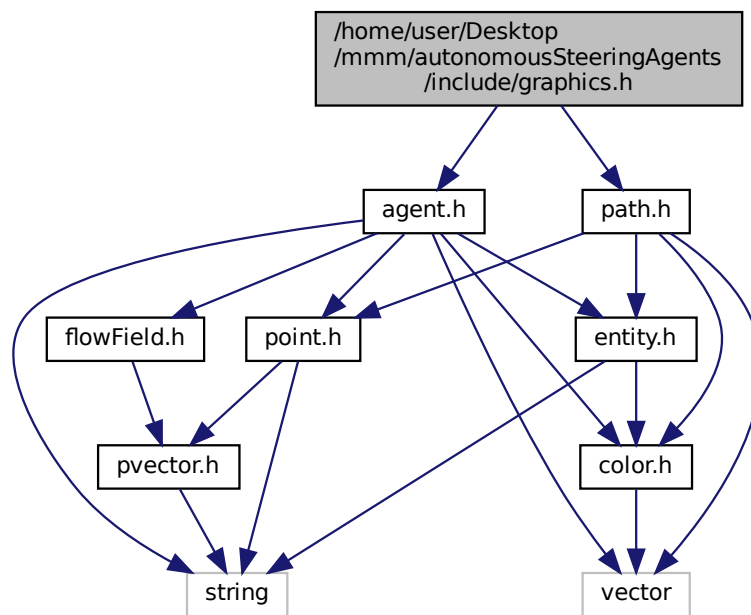
```
#define WIND_WEST 0.1, 0.0
```

Definition at line 15 of file flowField.h.

## 7.19 /home/user/Desktop/mmm/autonomousSteeringAgents/include/graphics.h File Reference

graphics class, drives openGL

```
#include "agent.h"
#include "path.h"
Include dependency graph for graphics.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

- class [graphics](#)

### Macros

- `#define WIDTH 34`
- `#define HEIGHT 34`
- `#define ESC 27`
- `#define PI 3.14159265`

### 7.19.1 Detailed Description

graphics class, drives openGL

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.19.2 Macro Definition Documentation

#### 7.19.2.1 ESC

```
#define ESC 27
```

Definition at line 16 of file graphics.h.

#### 7.19.2.2 HEIGHT

```
#define HEIGHT 34
```

Definition at line 14 of file graphics.h.

#### 7.19.2.3 PI

```
#define PI 3.14159265
```

Definition at line 17 of file graphics.h.

#### 7.19.2.4 WIDTH

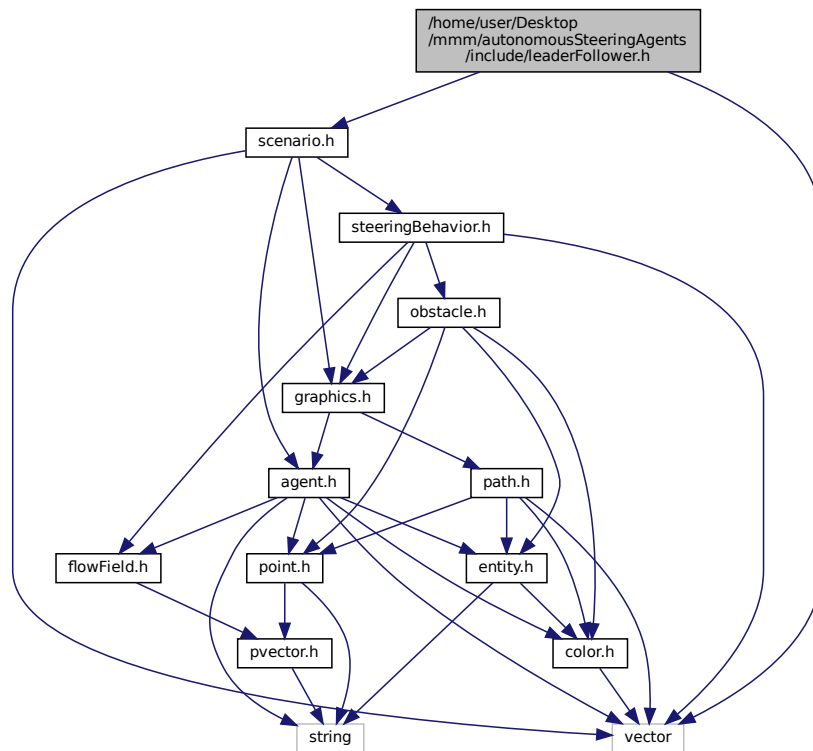
```
#define WIDTH 34
```

Definition at line 13 of file graphics.h.

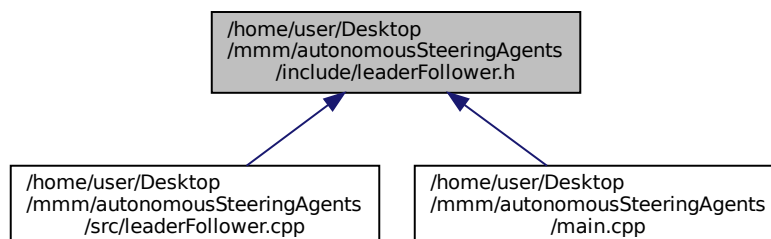
## 7.20 /home/user/Desktop/mmm/autonomousSteeringAgents/include/leaderFollower.h File Reference

agents follow leader scenario

```
#include "scenario.h"
#include <vector>
Include dependency graph for leaderFollower.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [leaderFollower](#)

### 7.20.1 Detailed Description

agents follow leader scenario

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

19.05.2021

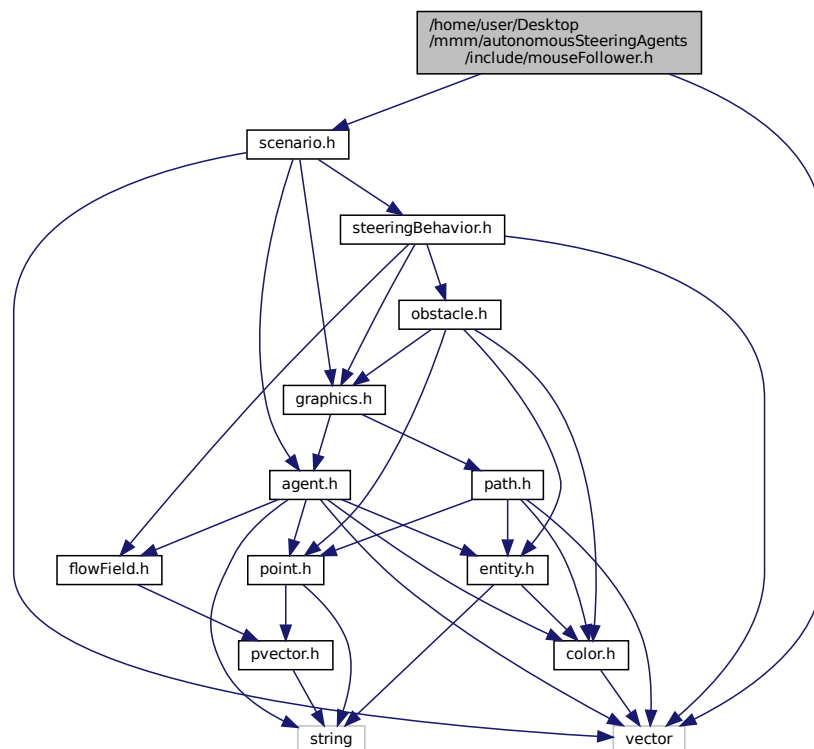
## 7.21 /home/user/Desktop/mmm/autonomousSteeringAgents/include/mouseFollower.h File Reference

agents follow mouse scenario

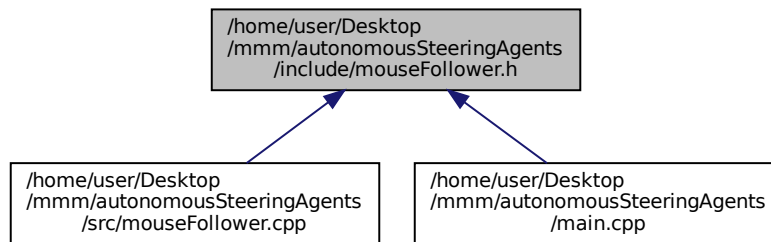
```
#include "scenario.h"
```

```
#include <vector>
```

Include dependency graph for mouseFollower.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [mouseFollower](#)

### 7.21.1 Detailed Description

agents follow mouse scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

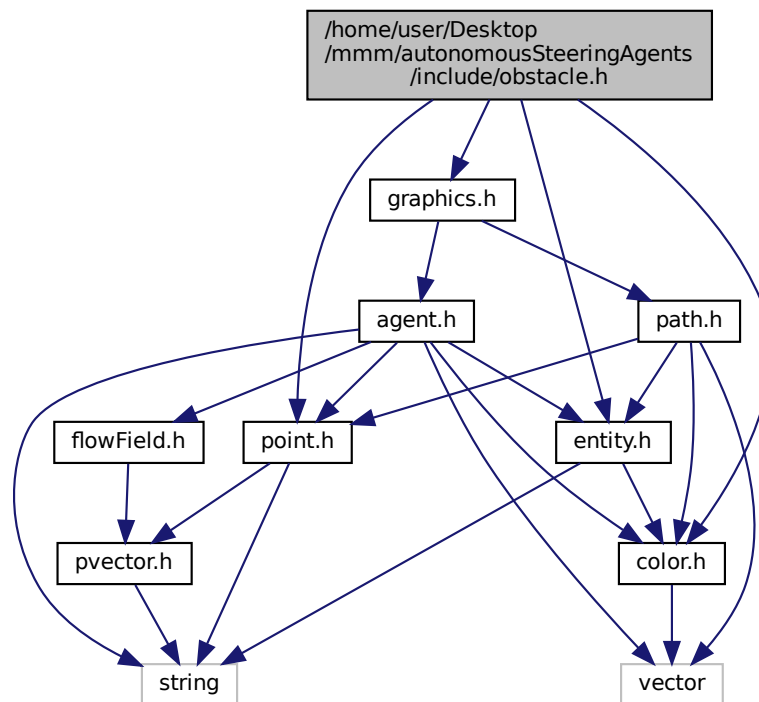
## 7.22 /home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacle.h File Reference

circular obstacles for agent avoidance behaviors

```
#include "point.h"
#include "graphics.h"
#include "color.h"
```

```
#include "entity.h"
```

Include dependency graph for obstacle.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [obstacle](#)

### 7.22.1 Detailed Description

circular obstacles for agent avoidance behaviors

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

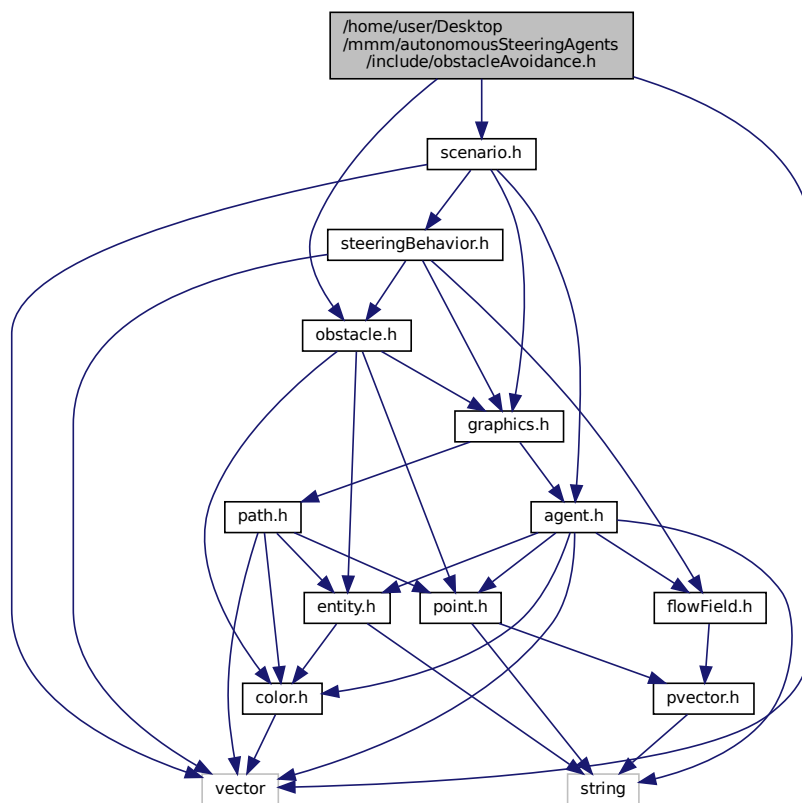
12.05.2021

## 7.23 /home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacleAvoidance.h File Reference

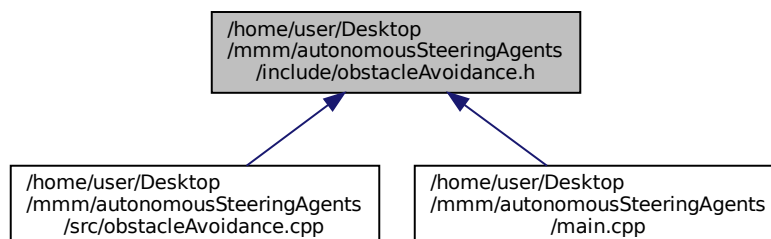
agents avoid from obstacles scenario

```
#include "scenario.h"
#include "obstacle.h"
#include <vector>
```

Include dependency graph for obstacleAvoidance.h:



This graph shows which files directly or indirectly include this file:





## Classes

- class [obstacleAvoidance](#)

### 7.23.1 Detailed Description

agents avoid from obstacles scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

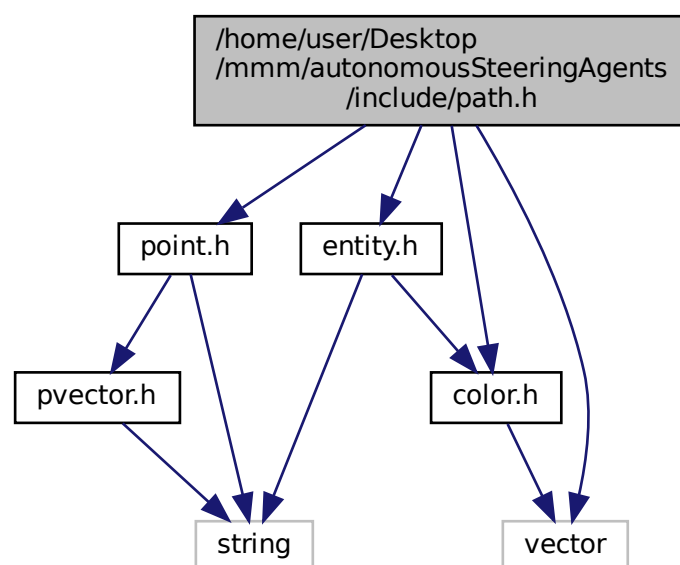
#### Date

15.05.2021

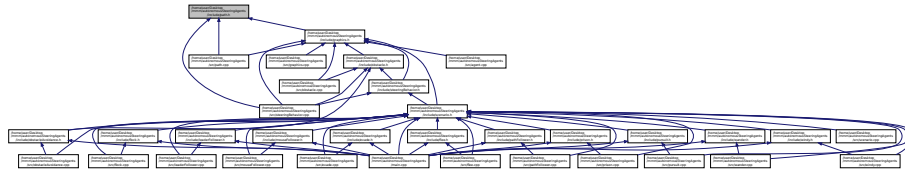
## 7.24 /home/user/Desktop/mmm/autonomousSteeringAgents/include/path.h File Reference

path class used for path following steering behaviors.

```
#include "point.h"
#include "entity.h"
#include "color.h"
#include <vector>
Include dependency graph for path.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [path](#)

### 7.24.1 Detailed Description

path class used for path following steering behaviors.

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

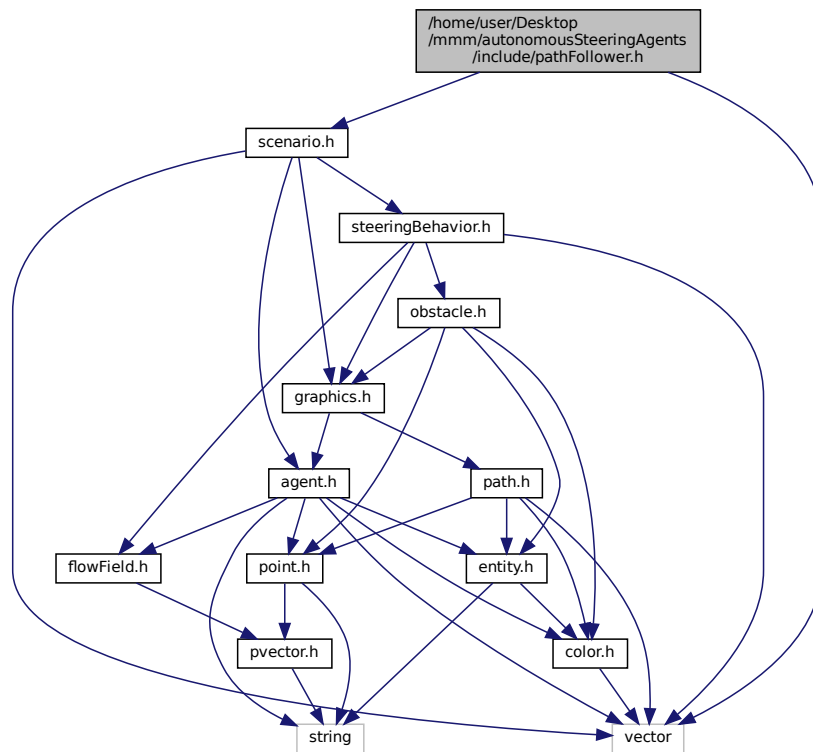
12.05.2021

## 7.25 [/home/user/Desktop/mmm/autonomousSteeringAgents/include/pathFollower.h](#) File Reference

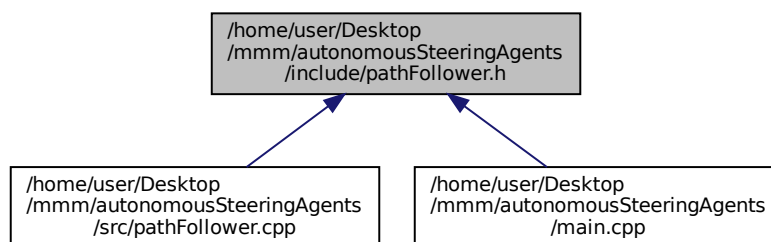
path following scenario

```
#include "scenario.h"
#include <vector>
```

Include dependency graph for pathFollower.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [pathFollower](#)

### 7.25.1 Detailed Description

path following scenario

## Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

## Date

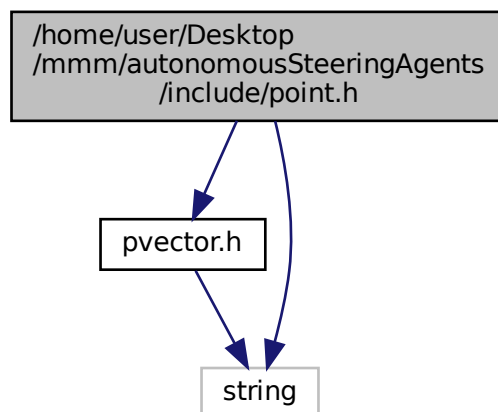
15.05.2021

## 7.26 /home/user/Desktop/mmm/autonomousSteeringAgents/include/point.h File Reference

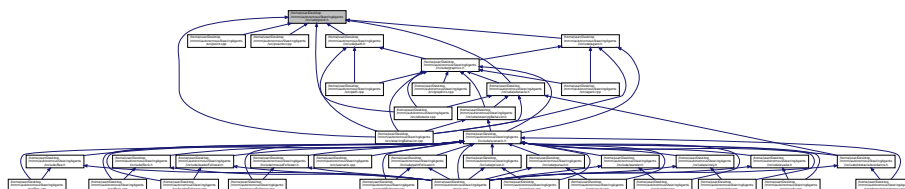
point class used for point operations

```
#include "pvector.h"
#include <string>
```

Include dependency graph for point.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [point](#)

### 7.26.1 Detailed Description

point class used for point operations

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

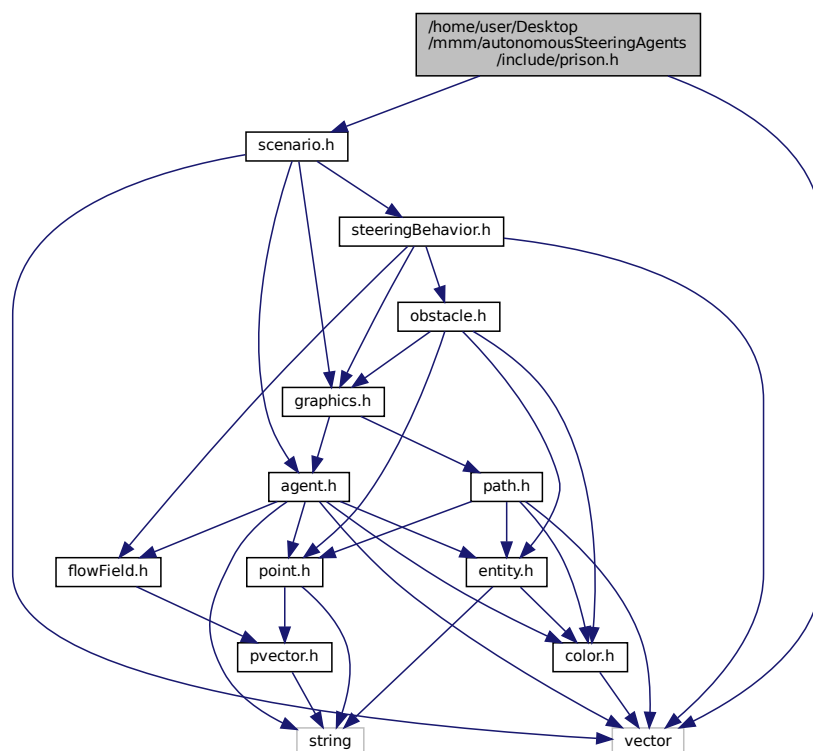
## 7.27 /home/user/Desktop/mmm/autonomousSteeringAgents/include/prison.h File Reference

agents cant escape from field scenario

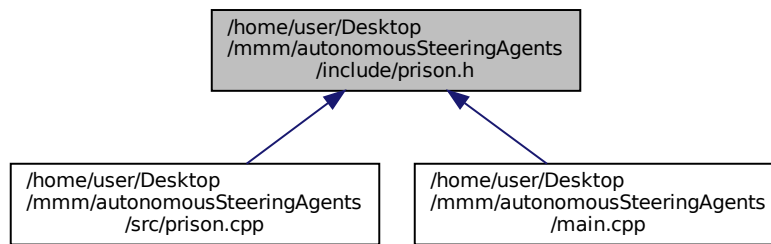
```
#include "scenario.h"
```

```
#include <vector>
```

Include dependency graph for prison.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [prison](#)

### 7.27.1 Detailed Description

agents cant escape from field scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

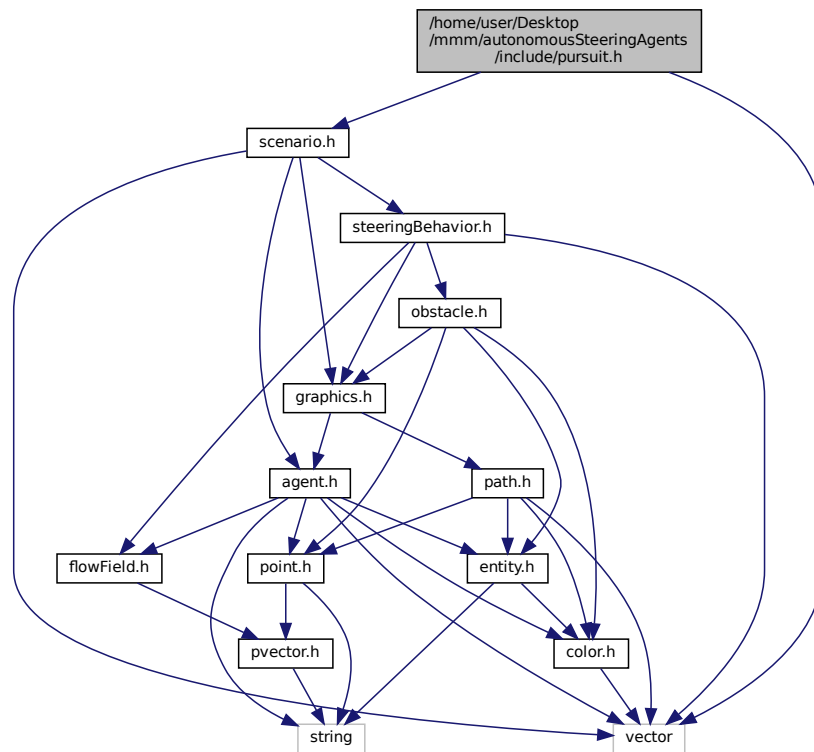
15.05.2021

## 7.28 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pursuit.h File Reference

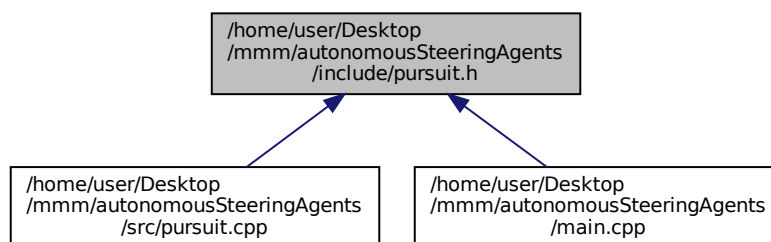
one agent pursue other one scenario

```
#include "scenario.h"
#include <vector>
```

Include dependency graph for pursuit.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [pursuit](#)

### 7.28.1 Detailed Description

one agent pursue other one scenario

## Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

## Date

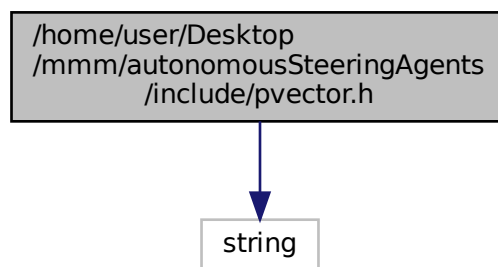
15.05.2021

## 7.29 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pvector.h File Reference

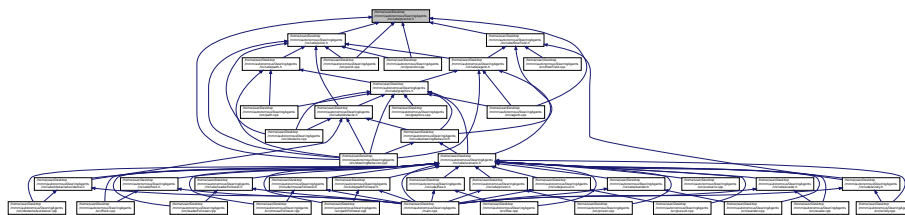
pvector class used for 2D vector operations

```
#include <string>
```

Include dependency graph for pvector.h:



This graph shows which files directly or indirectly include this file:



### Classes

- class `pvector`

### Macros

- `#define PI 3.14159265`



### 7.29.1 Detailed Description

pvector class used for 2D vector operations

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.29.2 Macro Definition Documentation

#### 7.29.2.1 PI

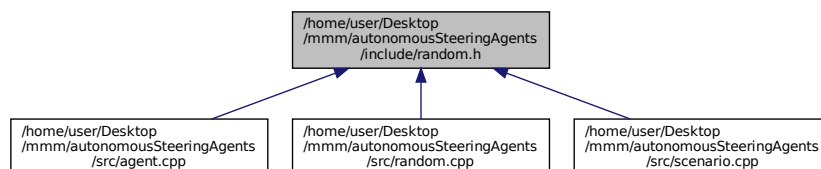
```
#define PI 3.14159265
```

Definition at line 11 of file pvector.h.

## 7.30 /home/user/Desktop/mmm/autonomousSteeringAgents/include/random.h File Reference

utility class for random operations

This graph shows which files directly or indirectly include this file:



## Classes

- class [random](#)

### 7.30.1 Detailed Description

utility class for random operations

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

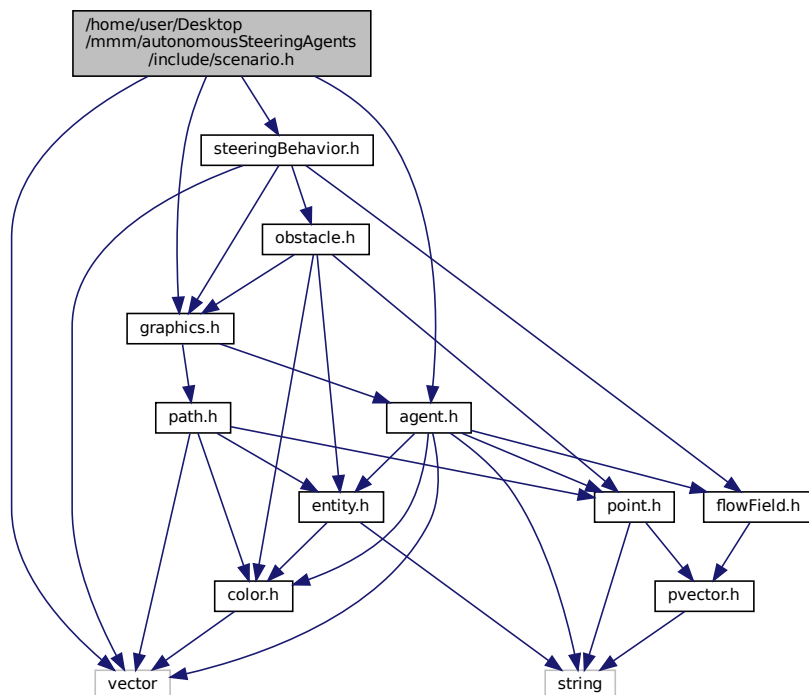
15.05.2021

## 7.31 /home/user/Desktop/mmm/autonomousSteeringAgents/include/scenario.h File Reference

base class for all scenarios

```
#include "agent.h"
#include "graphics.h"
#include "steeringBehavior.h"
#include <vector>
```

Include dependency graph for scenario.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [scenario](#)

## Enumerations

- enum [types](#) { [RANDOM](#) =0, [STATIC](#), [TROOP](#) }

### 7.31.1 Detailed Description

base class for all scenarios

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.31.2 Enumeration Type Documentation

#### 7.31.2.1 types

enum [types](#)

#### Enumerator

RANDOM	
STATIC	
TROOP	

Definition at line 17 of file scenario.h.

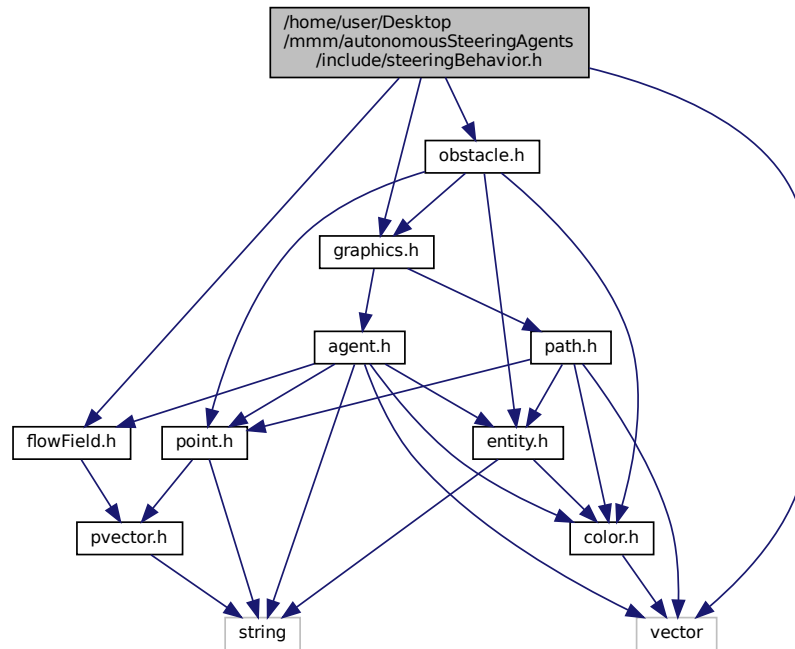
```
17 { RANDOM=0, STATIC, TROOP };
```

## 7.32 /home/user/Desktop/mmm/autonomousSteeringAgents/include/steeringBehavior.h File Reference

functions for autonomous steering behaviors

```
#include "flowField.h"
#include <vector>
```

```
#include "graphics.h"
#include "obstacle.h"
Include dependency graph for steeringBehavior.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [steeringBehavior](#)

## Macros

- `#define CIRCLE_DISTANCE 0.1`
- `#define CIRCLE_RADIUS 0.4`
- `#define FOLLOW_MOUSE 1`
- `#define STAY_IN_FIELD 2`
- `#define IN_FLOW_FIELD 3`
- `#define AVOID_OBSTACLE 4`
- `#define STAY_IN_PATH 5`
- `#define FLOCK 6`
- `#define WANDER 7`
- `#define FLEE 8`
- `#define PURSUIT 9`
- `#define EVADE 10`
- `#define LEADER_FOLLOWER 11`

### 7.32.1 Detailed Description

functions for autonomous steering behaviors

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.32.2 Macro Definition Documentation

#### 7.32.2.1 AVOID\_OBSTACLE

```
#define AVOID_OBSTACLE 4
```

Definition at line 21 of file steeringBehavior.h.

#### 7.32.2.2 CIRCLE\_DISTANCE

```
#define CIRCLE_DISTANCE 0.1
```

Definition at line 15 of file steeringBehavior.h.

#### 7.32.2.3 CIRCLE\_RADIUS

```
#define CIRCLE_RADIUS 0.4
```

Definition at line 16 of file steeringBehavior.h.

#### 7.32.2.4 EVADE

```
#define EVADE 10
```

Definition at line 27 of file steeringBehavior.h.

#### 7.32.2.5 FLEE

```
#define FLEE 8
```

Definition at line 25 of file steeringBehavior.h.

#### 7.32.2.6 FLOCK

```
#define FLOCK 6
```

Definition at line 23 of file steeringBehavior.h.

#### 7.32.2.7 FOLLOW\_MOUSE

```
#define FOLLOW_MOUSE 1
```

Definition at line 18 of file steeringBehavior.h.

#### 7.32.2.8 IN\_FLOW\_FIELD

```
#define IN_FLOW_FIELD 3
```

Definition at line 20 of file steeringBehavior.h.

#### 7.32.2.9 LEADER\_FOLLOWER

```
#define LEADER_FOLLOWER 11
```

Definition at line 28 of file steeringBehavior.h.

#### 7.32.2.10 PURSUIT

```
#define PURSUIT 9
```

Definition at line 26 of file steeringBehavior.h.

#### 7.32.2.11 STAY\_IN\_FIELD

```
#define STAY_IN_FIELD 2
```

Definition at line 19 of file steeringBehavior.h.

#### 7.32.2.12 STAY\_IN\_PATH

```
#define STAY_IN_PATH 5
```

Definition at line 22 of file steeringBehavior.h.

#### 7.32.2.13 WANDER

```
#define WANDER 7
```

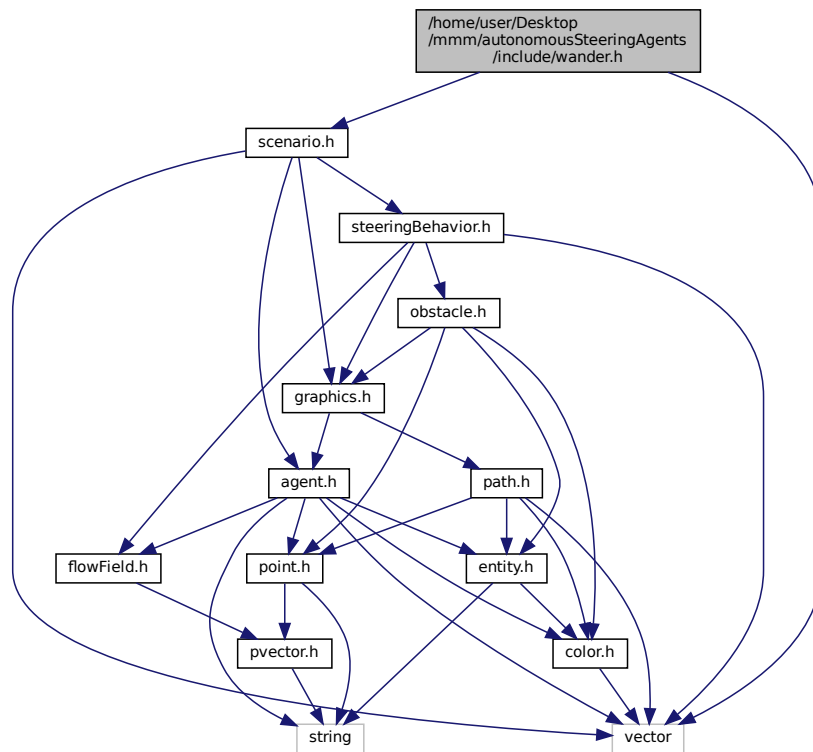
Definition at line 24 of file steeringBehavior.h.

### 7.33 /home/user/Desktop/mmm/autonomousSteeringAgents/include/wander.h File Reference

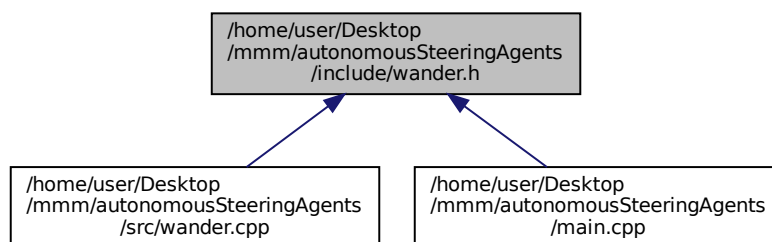
random wandering agents scenario

```
#include "scenario.h"  
#include <vector>
```

Include dependency graph for wander.h:



This graph shows which files directly or indirectly include this file:



## Classes

- class [wander](#)

### 7.33.1 Detailed Description

random wandering agents scenario



## Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

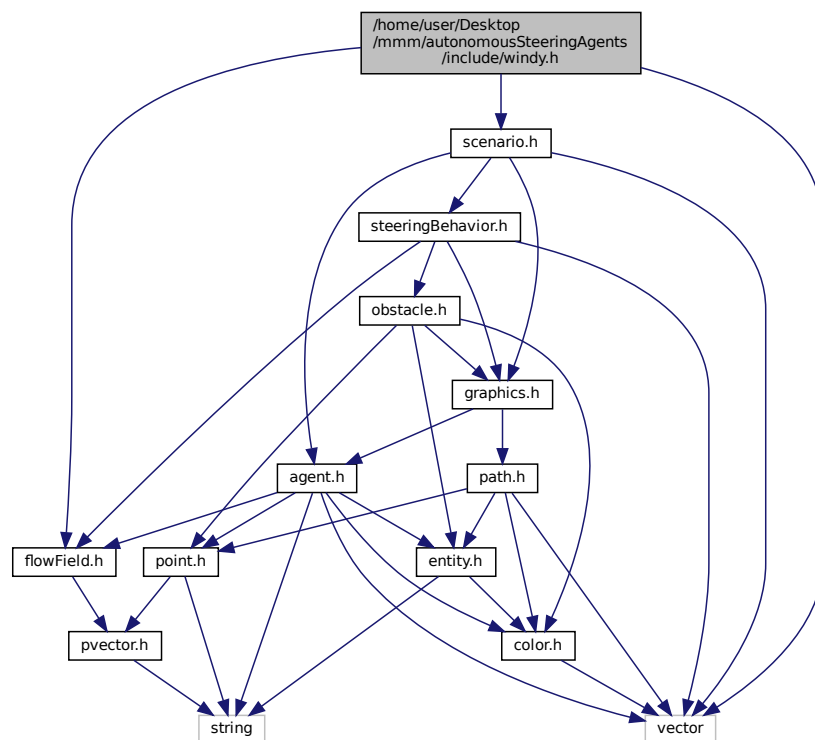
## Date

15.05.2021

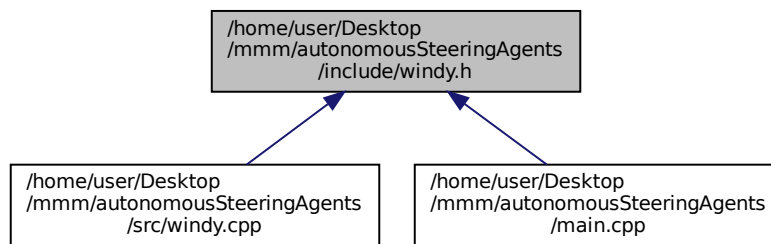
## 7.34 /home/user/Desktop/mmm/autonomousSteeringAgents/include/windy.h File Reference

windy air scenario

```
#include "scenario.h"  
#include "flowField.h"  
#include <vector>  
Include dependency graph for windy.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class [windy](#)

### 7.34.1 Detailed Description

windy air scenario

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

## 7.35 /home/user/Desktop/mmm/autonomousSteeringAgents/leaderFollower.d File Reference

## 7.36 /home/user/Desktop/mmm/autonomousSteeringAgents/main.cpp File Reference

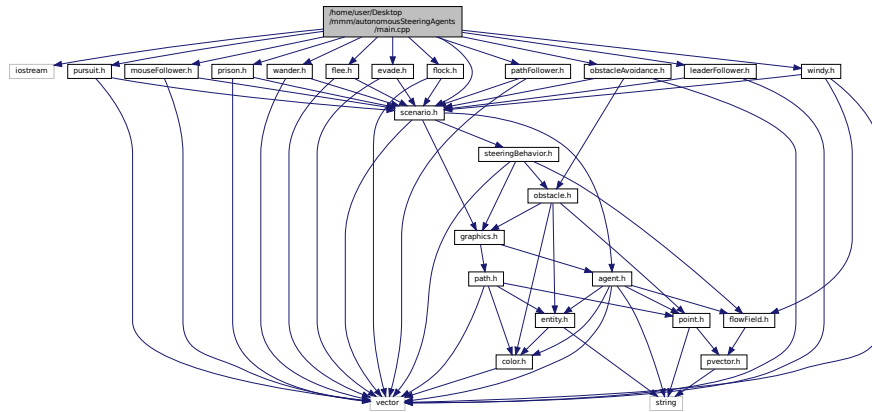
client code

```

#include <iostream>
#include "mouseFollower.h"
#include "prison.h"
#include "windy.h"
#include "wander.h"
#include "pursuit.h"
#include "flee.h"

```

```
#include "scenario.h"
#include "evade.h"
#include "flock.h"
#include "pathFollower.h"
#include "leaderFollower.h"
#include "obstacleAvoidance.h"
Include dependency graph for main.cpp:
```



## Functions

- void `menu` ()  
*displays menu*
- int `main` (int argc, char \*\*argv)  
*main routine*

## Variables

- int `mode`  
*specifies user selected scenario*

### 7.36.1 Detailed Description

client code

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

### 7.36.2 Function Documentation

### 7.36.2.1 main()

```
int main (
    int argc,
    char ** argv )
```

main routine

Definition at line 50 of file main.cpp.

```
50     {
51         menu();
52
53         scenario *sc;
54
55         if(mode == FOLLOW_MOUSE){
56             *sc = mouseFollower();
57         }
58         else if(mode == STAY_IN_FIELD){
59             *sc = prison();
60         }
61         else if(mode == IN_FLOW_FIELD){
62             *sc = windy();
63         }
64         else if(mode == WANDER){
65             *sc = wander();
66         }
67         else if(mode == PURSUIT){
68             *sc = pursuit();
69         }
70         else if(mode == FLEE){
71             *sc = flee();
72         }
73         else if(mode == EVADE){
74             *sc = evade();
75         }
76         else if(mode == FLOCK){
77             *sc = flock();
78         }
79         else if(mode == STAY_IN_PATH){
80             *sc = pathFollower();
81         }
82         else if(mode == AVOID_OBSTACLE){
83             *sc = obstacleAvoidance();
84         }
85         else if(mode == LEADER_FOLLOWER){
86             *sc = leaderFollower();
87         }
88
89         sc->initGL(&argc, argv);
90
91         return 0;
92     }
```

### 7.36.2.2 menu()

```
void menu ( )
```

displays menu

Definition at line 32 of file main.cpp.

```
32     {
33         cout << "Follow Mouse           : 1" << endl;
34         cout << "Stay in Field           : 2" << endl;
35         cout << "In Flow Field          : 3" << endl;
36         cout << "Avoid Obstacles        : 4" << endl;
37         cout << "Stay in Path           : 5" << endl;
38         cout << "FLOCK                  : 6" << endl;
39         cout << "WANDER                  : 7" << endl;
40         cout << "FLEE                   : 8" << endl;
41         cout << "PURSUIT                 : 9" << endl;
42         cout << "EVADE                  : 10" << endl;
43         cout << "Follow Leader          : 11" << endl;
44         cin >> mode;
45     }
```

### 7.36.3 Variable Documentation

#### 7.36.3.1 mode

```
int mode
```

specifies user selected scenario

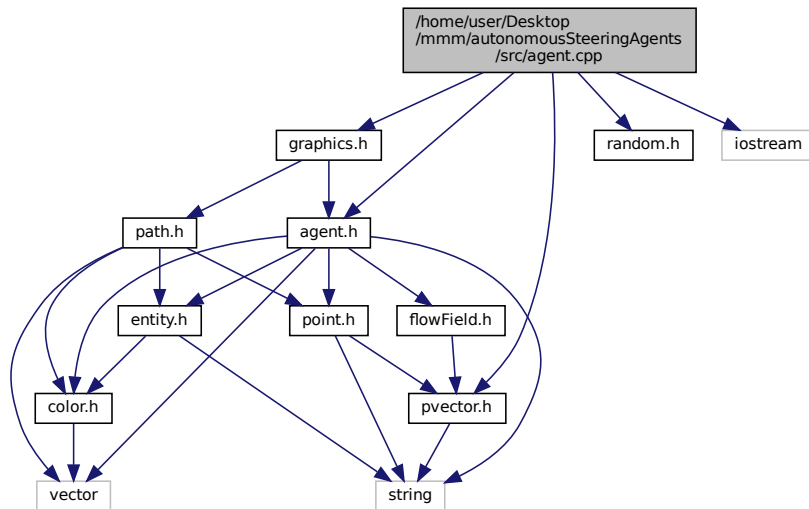
Definition at line 27 of file main.cpp.



- 7.37** /home/user/Desktop/mmm/autonomousSteeringAgents/main.d File Reference
- 7.38** /home/user/Desktop/mmm/autonomousSteeringAgents/mouse↔  
Follower.d File Reference
- 7.39** /home/user/Desktop/mmm/autonomousSteeringAgents/obstacle.d File Reference
- 7.40** /home/user/Desktop/mmm/autonomousSteeringAgents/obstacle↔  
Avoidance.d File Reference
- 7.41** /home/user/Desktop/mmm/autonomousSteeringAgents/path.d File Reference
- 7.42** /home/user/Desktop/mmm/autonomousSteeringAgents/path↔  
Follower.d File Reference
- 7.43** /home/user/Desktop/mmm/autonomousSteeringAgents/point.d File Reference
- 7.44** /home/user/Desktop/mmm/autonomousSteeringAgents/prison.d File Reference
- 7.45** /home/user/Desktop/mmm/autonomousSteeringAgents/pursuit.d File Reference
- 7.46** /home/user/Desktop/mmm/autonomousSteeringAgents/pvector.d File Reference
- 7.47** /home/user/Desktop/mmm/autonomousSteeringAgents/random.d File Reference
- 7.48** /home/user/Desktop/mmm/autonomousSteeringAgents/READ↔  
ME.md File Reference
- 7.49** /home/user/Desktop/mmm/autonomousSteeringAgents/scenario.d File Reference

- 7.50** /home/user/Desktop/mmm/autonomousSteering↔  
Agents/src/agent.cpp File

```
#include "agent.h"
#include "pvector.h"
#include "graphics.h"
#include "random.h"
#include <iostream>
Include dependency graph for agent.cpp:
```



### 7.50.1 Detailed Description

implementation of the agent class

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

14.05.2021

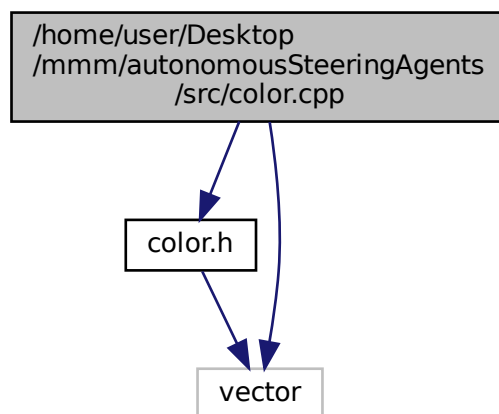
## 7.51 /home/user/Desktop/mmm/autonomousSteeringAgents/src/color.cpp File Reference

color class implementation



```
#include "color.h"
#include <vector>
```

Include dependency graph for color.cpp:



### 7.51.1 Detailed Description

color class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

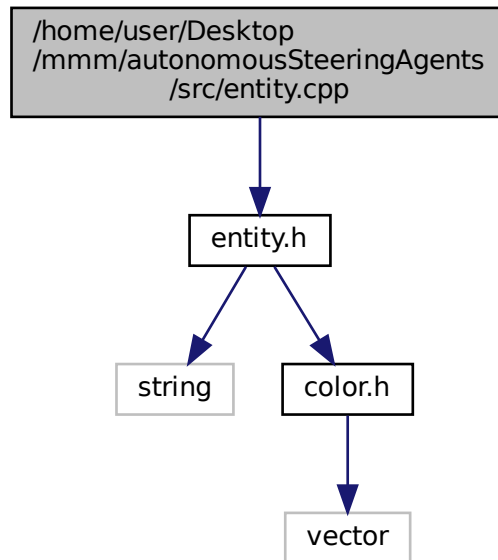
13.05.2021

## 7.52 /home/user/Desktop/mmm/autonomousSteeringAgents/src/entity.cpp File Reference

entity class implementation

```
#include "entity.h"
```

Include dependency graph for entity.cpp:



### 7.52.1 Detailed Description

entity class implementation

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

18.05.2021

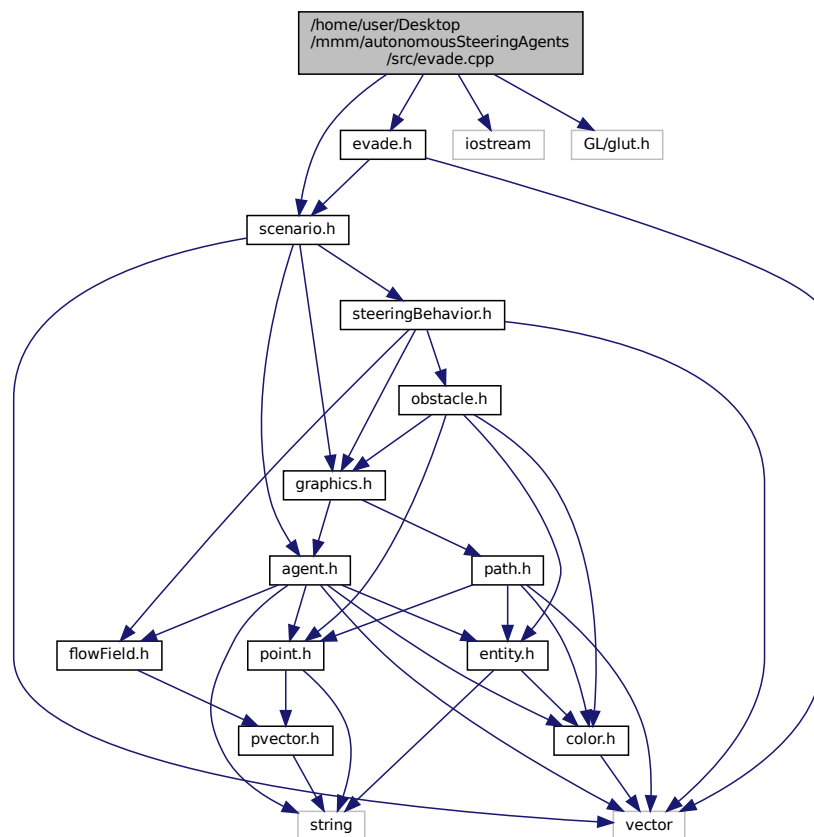
## 7.53 `/home/user/Desktop/mmm/autonomousSteeringAgents/src/evade.cpp` File Reference

evade class implementation

```
#include "scenario.h"
#include "evade.h"
#include <iostream>
```

```
#include <GL/glut.h>
```

Include dependency graph for evade.cpp:



### 7.53.1 Detailed Description

evade class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

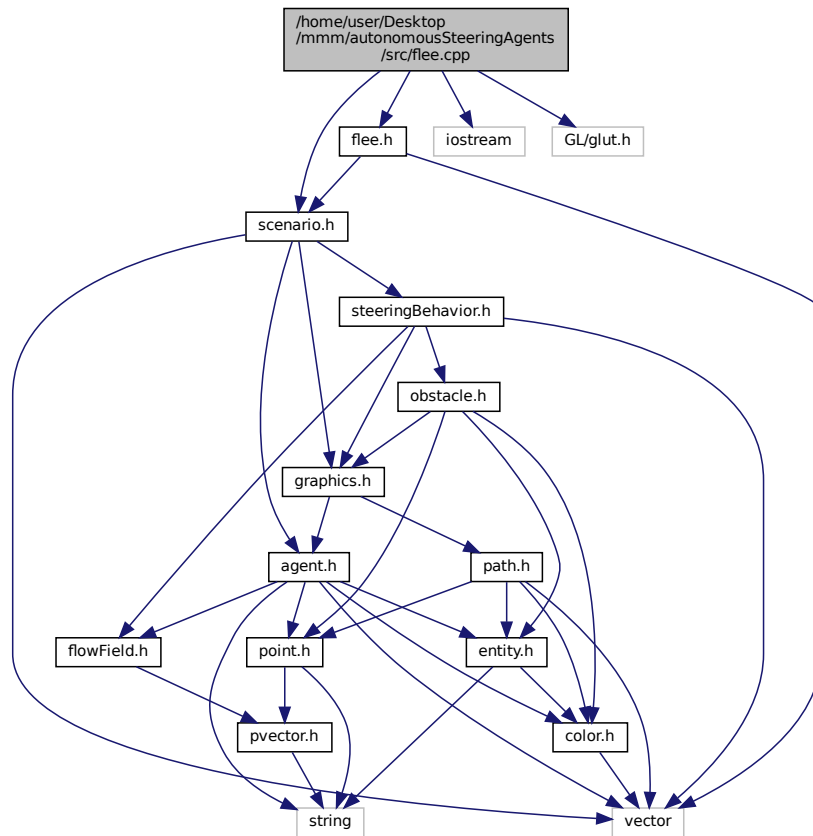
Date

15.05.2021

## 7.54 /home/user/Desktop/mmm/autonomousSteeringAgents/src/flee.cpp File Reference

flee class implementation

```
#include "scenario.h"
#include "flee.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for flee.cpp:
```



### 7.54.1 Detailed Description

flee class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

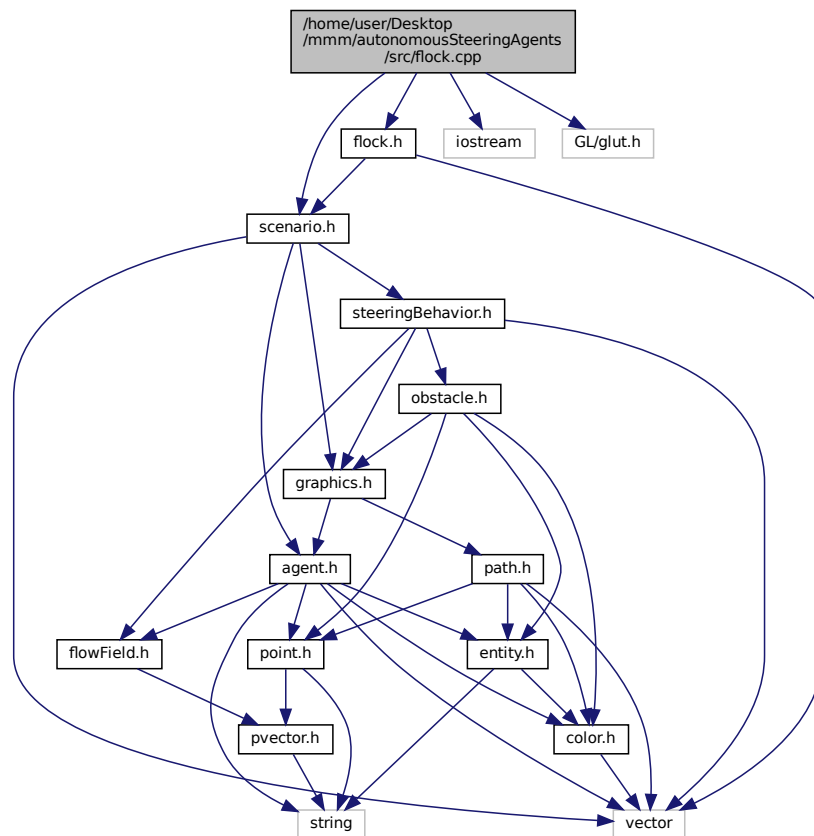
Date

15.05.2021

## 7.55 /home/user/Desktop/mmm/autonomousSteeringAgents/src/flock.cpp File Reference

flock class implementation

```
#include "scenario.h"
#include "flock.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for flock.cpp:
```



### 7.55.1 Detailed Description

flock class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

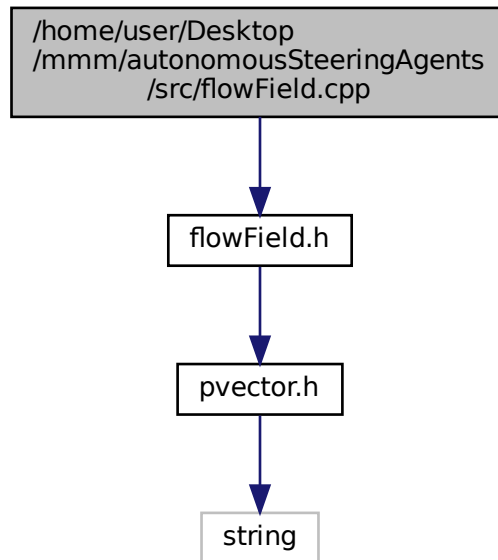
15.05.2021

## 7.56 /home/user/Desktop/mmm/autonomousSteeringAgents/src/flowField.cpp File Reference

[flowField](#) class implementation

```
#include "flowField.h"
```

Include dependency graph for flowField.cpp:



### 7.56.1 Detailed Description

`flowField` class implementation

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

13.05.2021

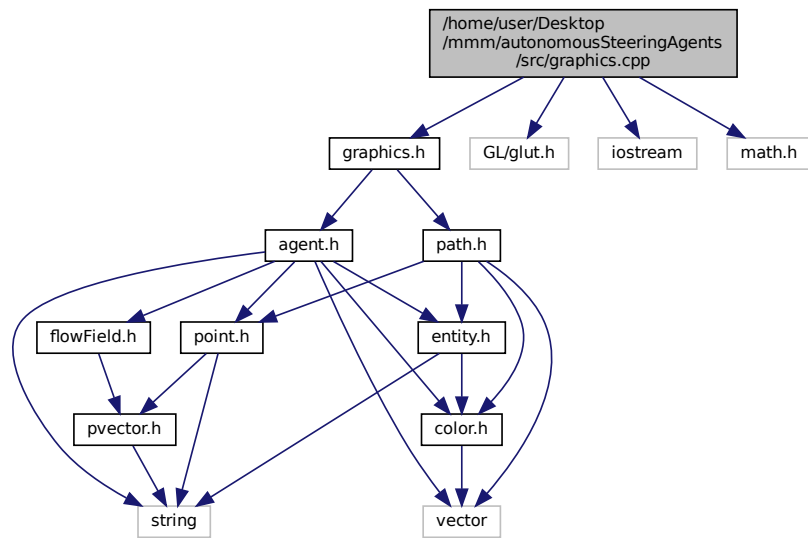
## 7.57 `/home/user/Desktop/mmm/autonomousSteeringAgents/src/graphics.cpp` File Reference

`graphics` class implementation

```
#include "graphics.h"
#include <GL/glut.h>
#include <iostream>
```

```
#include "math.h"
```

Include dependency graph for graphics.cpp:



### 7.57.1 Detailed Description

graphics class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

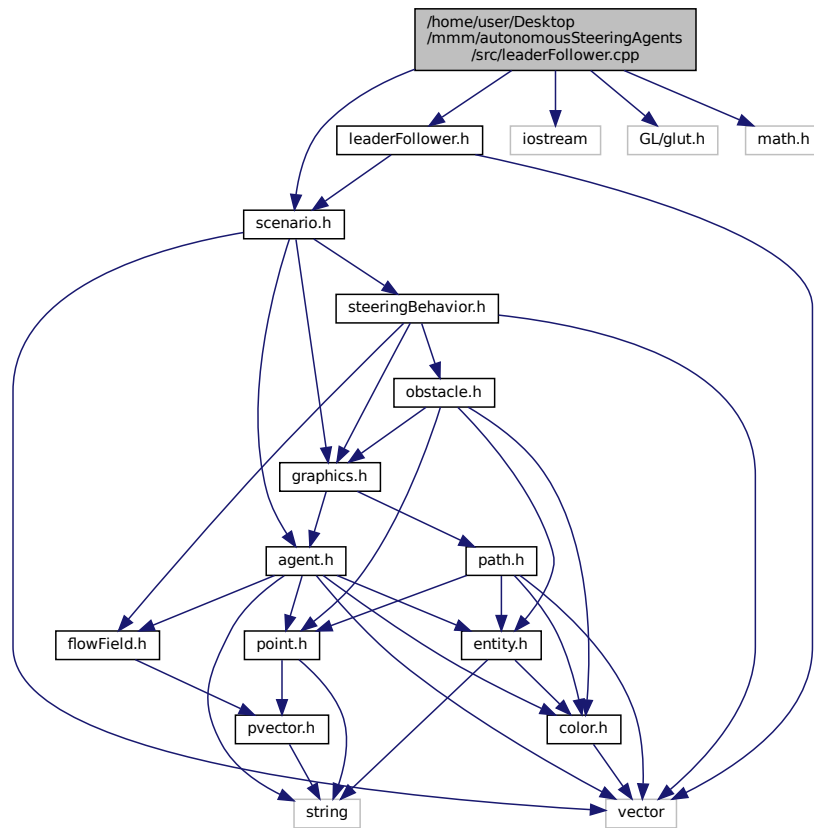
## 7.58 /home/user/Desktop/mmm/autonomousSteeringAgents/src/leaderFollower.cpp File Reference

[leaderFollower](#) class implementation

```
#include "scenario.h"
#include "leaderFollower.h"
#include <iostream>
#include <GL/glut.h>
```

```
#include "math.h"
```

Include dependency graph for leaderFollower.cpp:



## Variables

- [point mainTarget](#)

### 7.58.1 Detailed Description

[leaderFollower](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

23.05.2021

### 7.58.2 Variable Documentation



## 7.58.2.1 mainTarget

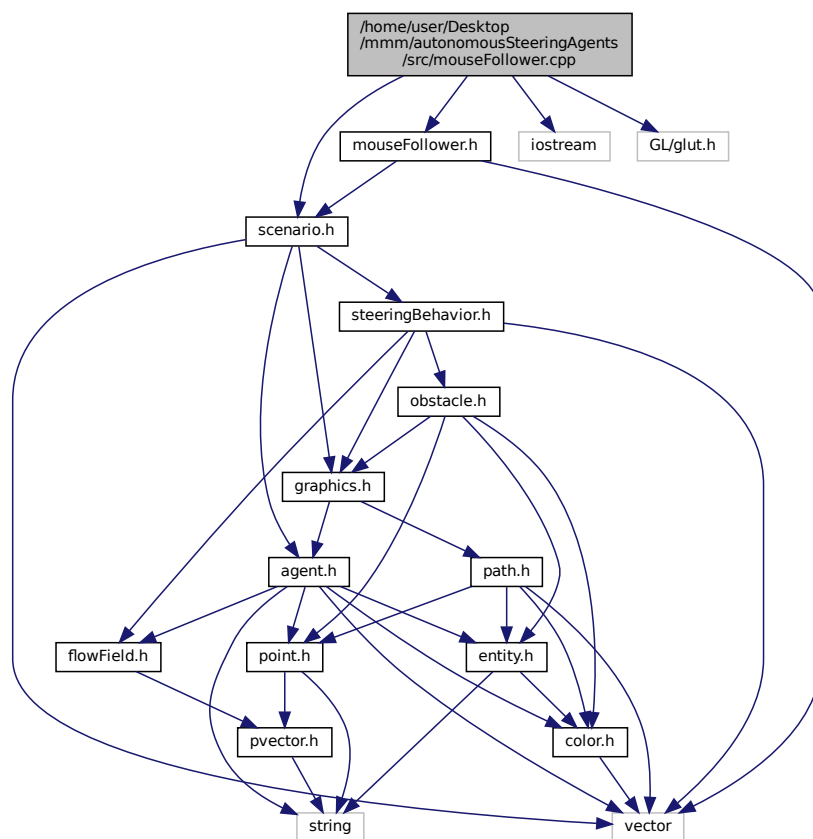
`point` mainTarget

Definition at line 19 of file leaderFollower.cpp.

## 7.59 /home/user/Desktop/mmm/autonomousSteeringAgents/src/mouseFollower.cpp File Reference

`mouseFollower` class implementation

```
#include "scenario.h"
#include "mouseFollower.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for mouseFollower.cpp:
```



### 7.59.1 Detailed Description

[mouseFollower](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

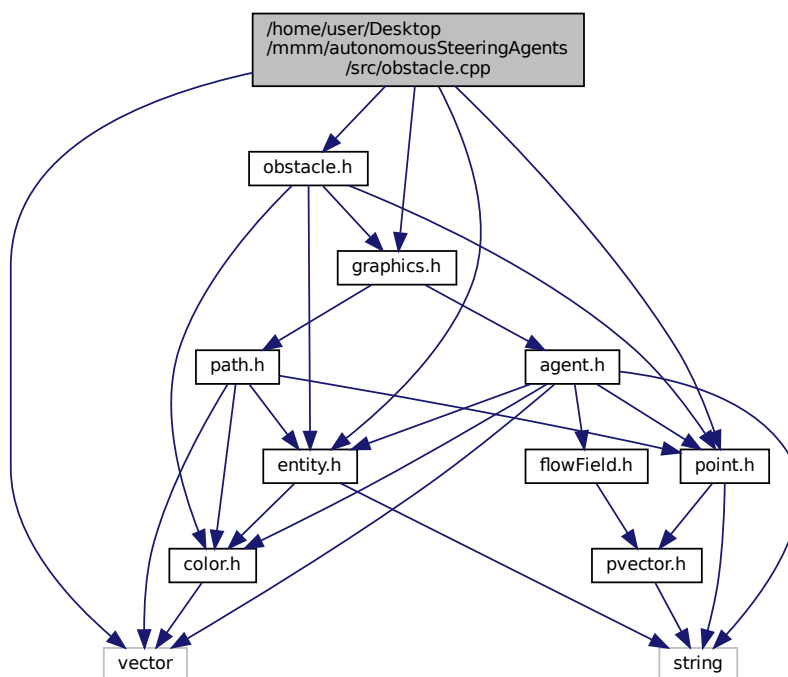
15.05.2021

## 7.60 /home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacle.cpp File Reference

obstacle class implementation

```
#include "obstacle.h"
#include "graphics.h"
#include "point.h"
#include "entity.h"
#include <vector>
```

Include dependency graph for obstacle.cpp:



### 7.60.1 Detailed Description

obstacle class implementation

Author

Mehmet Rıza Öz - [mehmetrizaaz@gmail.com](mailto:mehmetrizaaz@gmail.com)

Date

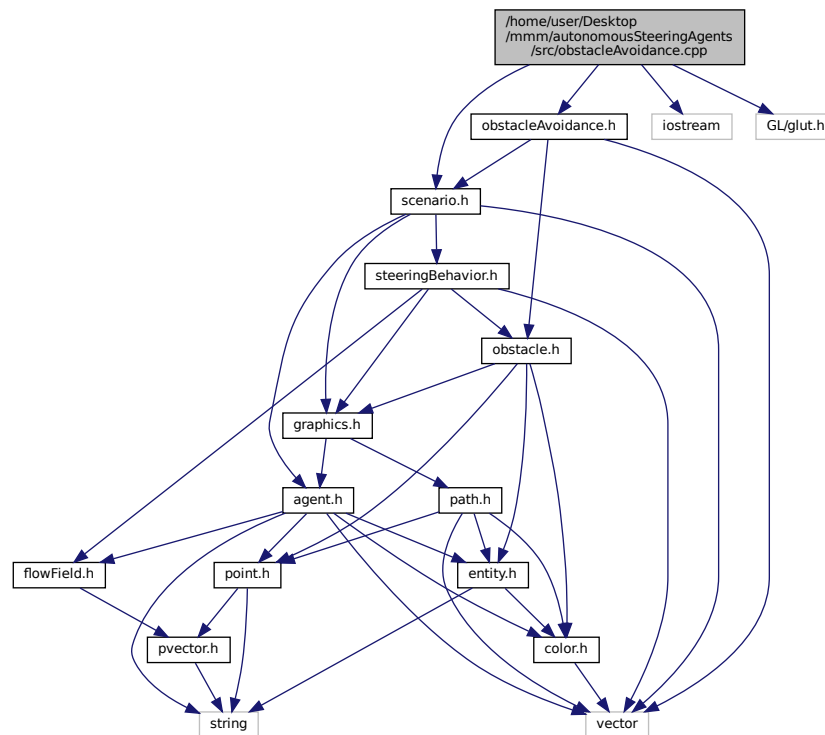
12.05.2021

## 7.61 /home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacleAvoidance.cpp File Reference

`obstacleAvoidance` class implementation

```
#include "scenario.h"
#include "obstacleAvoidance.h"
#include <iostream>
#include <GL/glut.h>
```

Include dependency graph for `obstacleAvoidance.cpp`:



### 7.61.1 Detailed Description

[obstacleAvoidance](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaaz@gmail.com](mailto:mehmetrizaaz@gmail.com)

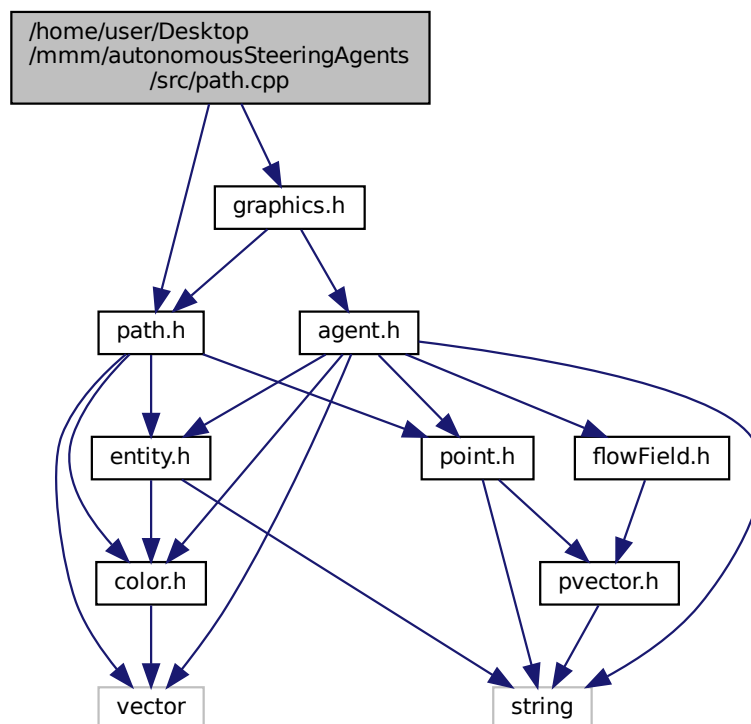
Date

15.05.2021

## 7.62 /home/user/Desktop/mmm/autonomousSteeringAgents/src/path.cpp File Reference

path class implementation

```
#include "path.h"
#include "graphics.h"
Include dependency graph for path.cpp:
```



### 7.62.1 Detailed Description

path class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

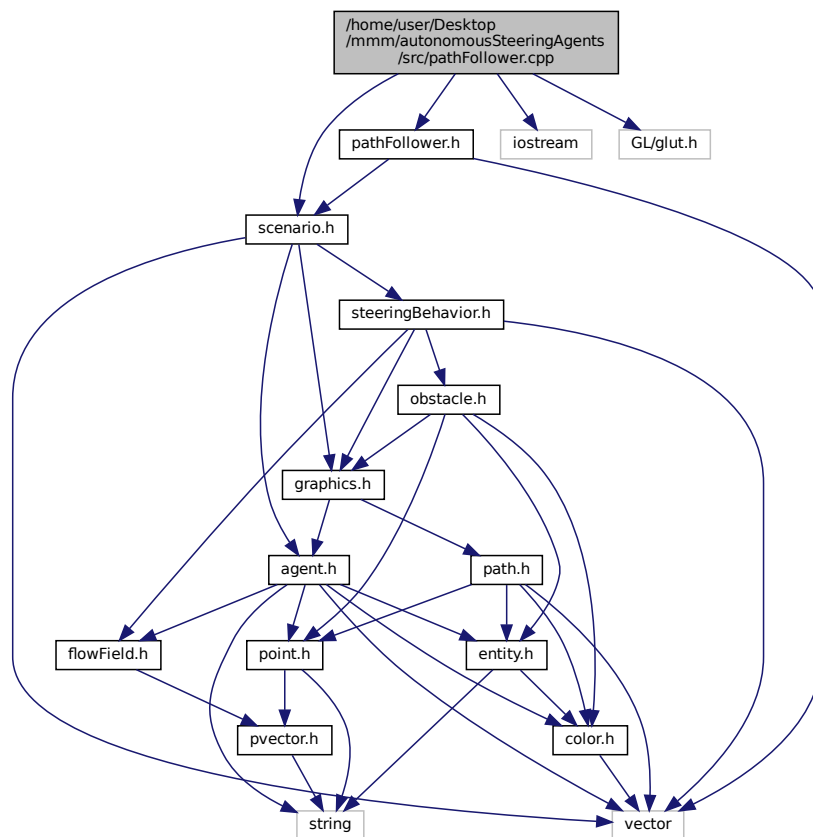
Date

12.05.2021

## 7.63 /home/user/Desktop/mmm/autonomousSteeringAgents/src/pathFollower.cpp File Reference

`pathFollower` class implementation

```
#include "scenario.h"
#include "pathFollower.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for pathFollower.cpp:
```



### 7.63.1 Detailed Description

[pathFollower](#) class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

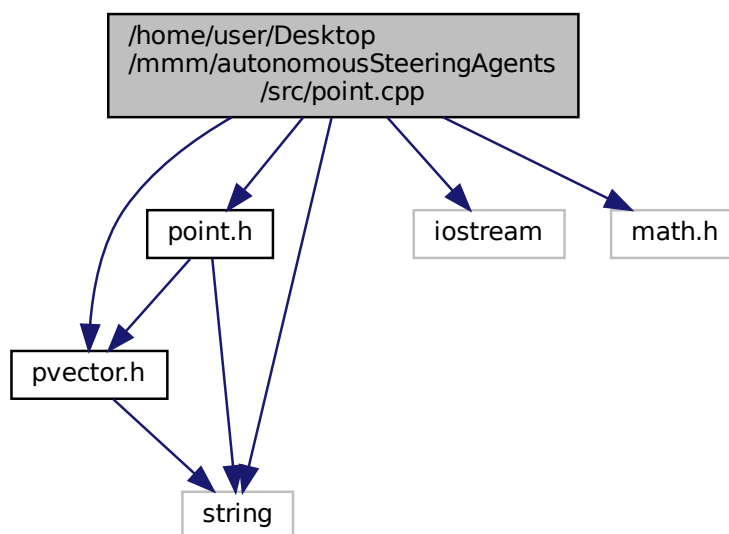
Date

15.05.2021

## 7.64 [/home/user/Desktop/mmm/autonomousSteeringAgents/src/point.cpp](#) File Reference

point class implementation file

```
#include "point.h"
#include "pvector.h"
#include <string>
#include <iostream>
#include "math.h"
Include dependency graph for point.cpp:
```



### 7.64.1 Detailed Description

point class implementation file

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

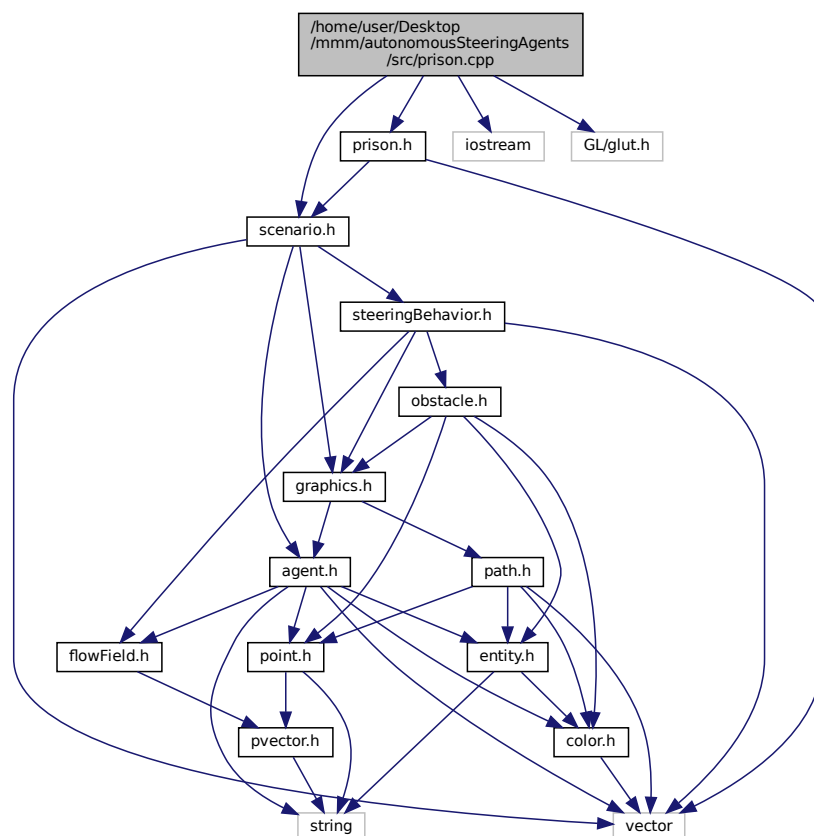
15.05.2021

## 7.65 /home/user/Desktop/mmm/autonomousSteeringAgents/src/prison.cpp File Reference

prison class implementation

```
#include "scenario.h"
#include "prison.h"
#include <iostream>
#include <GL/glut.h>
```

Include dependency graph for prison.cpp:



## Macros

- #define WALL 30
- #define DISTANCE 2

### 7.65.1 Detailed Description

prison class implementation

#### Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

#### Date

15.05.2021

### 7.65.2 Macro Definition Documentation

#### 7.65.2.1 DISTANCE

```
#define DISTANCE 2
```

Definition at line 14 of file prison.cpp.

#### 7.65.2.2 WALL

```
#define WALL 30
```

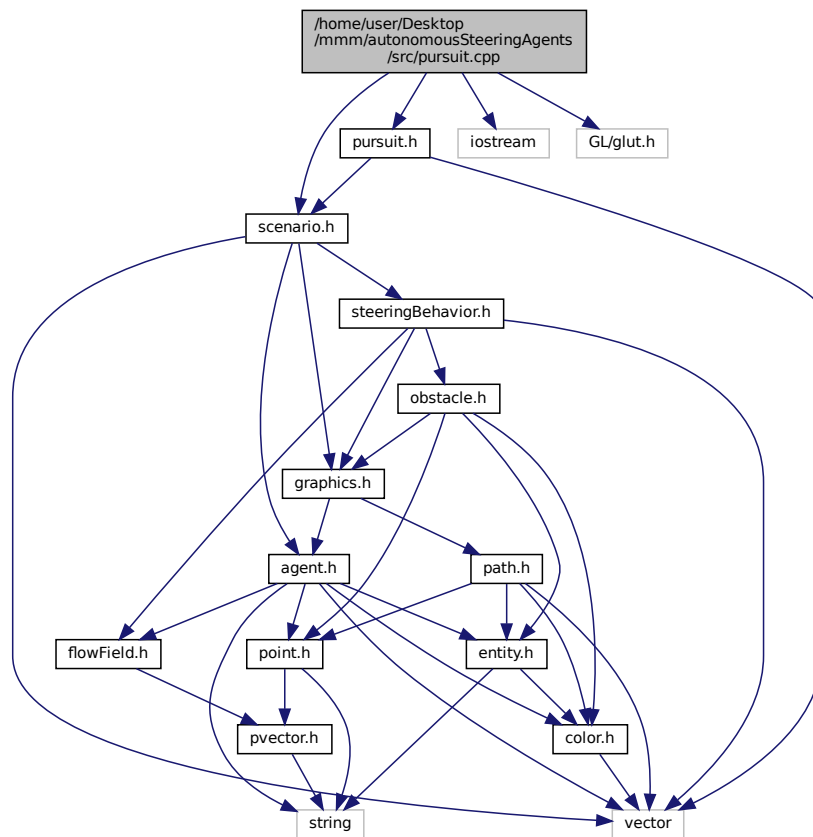
Definition at line 13 of file prison.cpp.



## 7.66 /home/user/Desktop/mmm/autonomousSteeringAgents/src/pursuit.cpp File Reference

prison class implementation

```
#include "scenario.h"
#include "pursuit.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for pursuit.cpp:
```



### 7.66.1 Detailed Description

prison class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

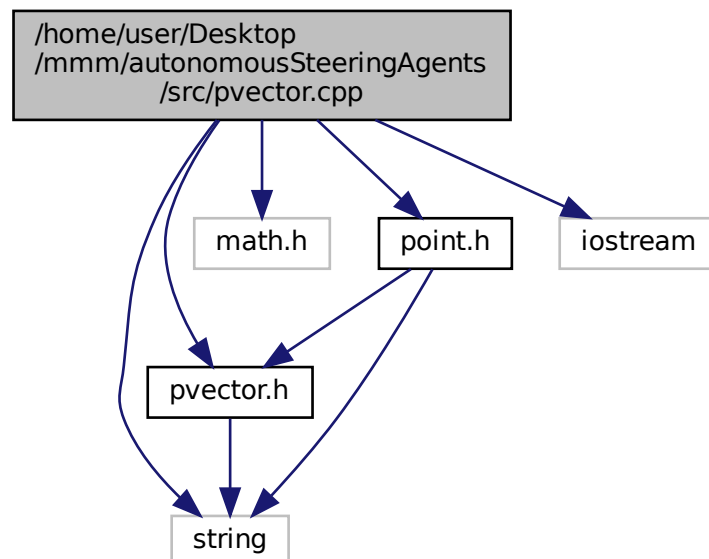
15.05.2021

## 7.67 /home/user/Desktop/mmm/autonomousSteeringAgents/src/pvector.cpp File Reference

pvector class implementation

```
#include "pvector.h"  
#include "math.h"  
#include "point.h"  
#include <iostream>  
#include <string>
```

Include dependency graph for pvector.cpp:



### 7.67.1 Detailed Description

pvector class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

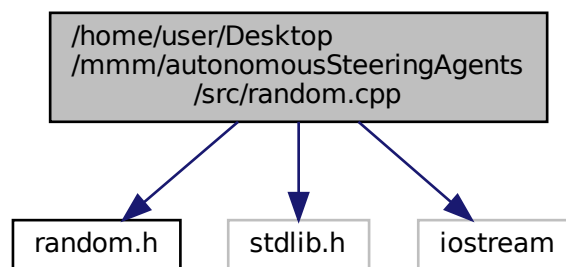
15.05.2021

## 7.68 /home/user/Desktop/mmm/autonomousSteeringAgents/src/random.cpp File Reference

utility class for random operations

```
#include "random.h"
#include <stdlib.h>
#include <iostream>
```

Include dependency graph for random.cpp:



### 7.68.1 Detailed Description

utility class for random operations

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

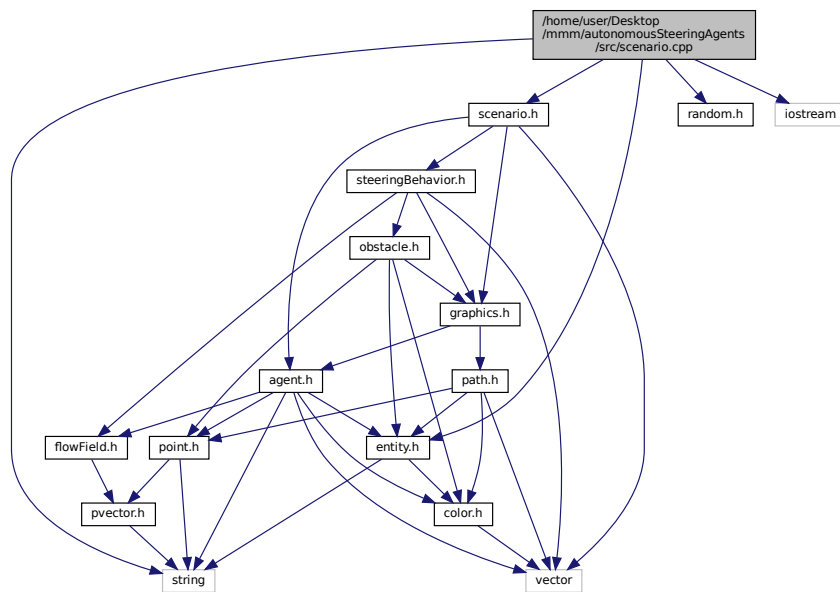
## 7.69 /home/user/Desktop/mmm/autonomousSteeringAgents/src/scenario.cpp File Reference

scenario base class implementation

```
#include "scenario.h"
#include "random.h"
#include "entity.h"
#include <iostream>
```

```
#include <string>
```

Include dependency graph for scenario.cpp:



## Macros

- #define `MAX_NUMBER_OF_AGENTS` 50

### 7.69.1 Detailed Description

scenario base class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

### 7.69.2 Macro Definition Documentation

#### 7.69.2.1 MAX\_NUMBER\_OF\_AGENTS

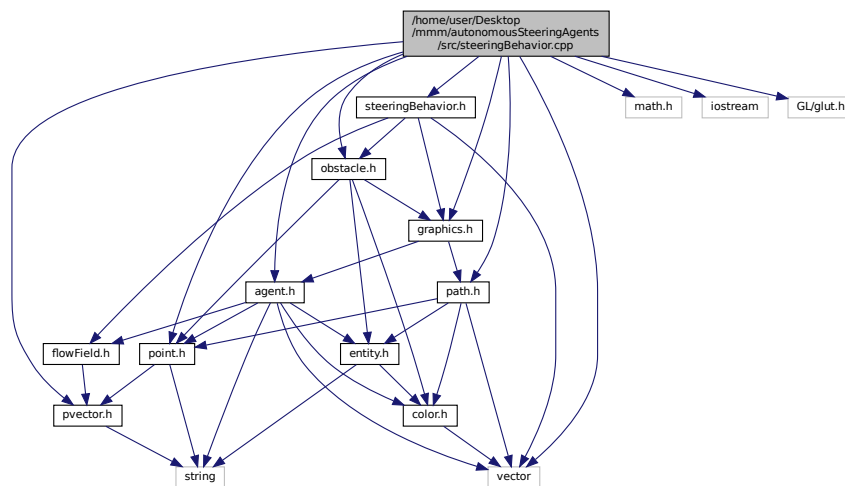
```
#define MAX_NUMBER_OF_AGENTS 50
```

Definition at line 14 of file scenario.cpp.

## 7.70 /home/user/Desktop/mmm/autonomousSteeringAgents/src/steeringBehavior.cpp File Reference

implementation of autonomous steering behaviors

```
#include "steeringBehavior.h"
#include "pvector.h"
#include "agent.h"
#include "path.h"
#include "point.h"
#include <vector>
#include "graphics.h"
#include "math.h"
#include "obstacle.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for steeringBehavior.cpp:
```



### 7.70.1 Detailed Description

implementation of autonomous steering behaviors

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

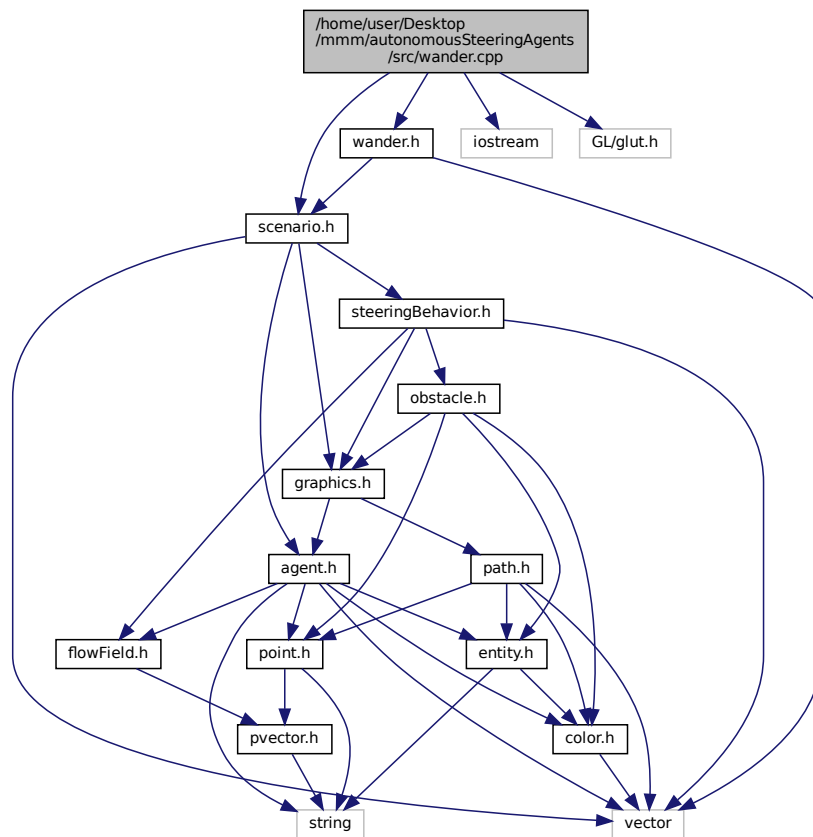
Date

15.05.2021

## 7.71 /home/user/Desktop/mmm/autonomousSteeringAgents/src/wander.cpp File Reference

wander class implementation

```
#include "scenario.h"
#include "wander.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for wander.cpp:
```



### 7.71.1 Detailed Description

wander class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

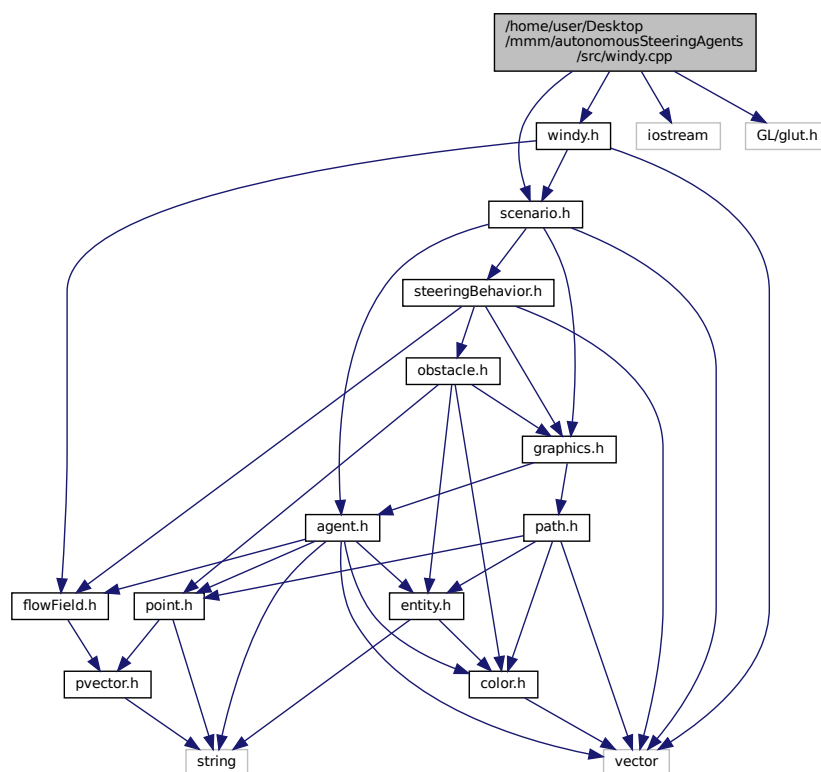
Date

15.05.2021

## 7.72 /home/user/Desktop/mmm/autonomousSteeringAgents/src/windy.cpp File Reference

windy class implementation

```
#include "scenario.h"
#include "windy.h"
#include <iostream>
#include <GL/glut.h>
Include dependency graph for windy.cpp:
```



### 7.72.1 Detailed Description

windy class implementation

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

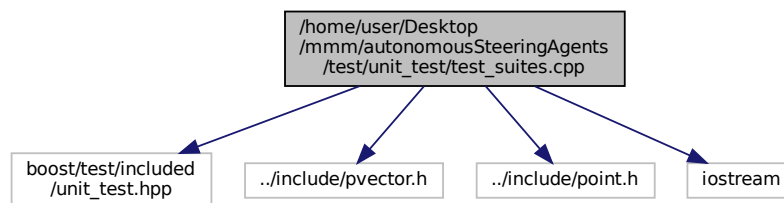
### 7.73 [/home/user/Desktop/mmm/autonomousSteeringAgents/steeringBehavior.d File Reference](#)

### 7.74 [/home/user/Desktop/mmm/autonomousSteeringAgents/test/unit\\_test/test\\_suites.cpp File Reference](#)

unit test suites

```
#include <boost/test/included/unit_test.hpp>
#include "../include/pvector.h"
#include "../include/point.h"
#include <iostream>
```

Include dependency graph for test\_suites.cpp:



## Macros

- `#define BOOST_TEST_MODULE test_suites`

## Functions

- `BOOST_AUTO_TEST_CASE (s1t1)`  
*pvector magnitude test case*
- `BOOST_AUTO_TEST_CASE (s1t2)`  
*pvector mul test case*
- `BOOST_AUTO_TEST_CASE (s1t3)`  
*pvector div test case*
- `BOOST_AUTO_TEST_CASE (s1t4)`  
*pvector dotproduct test case*
- `BOOST_AUTO_TEST_CASE (s1t5)`  
*pvector angle between vectors test case*
- `BOOST_AUTO_TEST_CASE (s1t6)`  
*pvector get vector angle test case*
- `BOOST_AUTO_TEST_CASE (s1t7)`  
*pvector normalize test case*



- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s1t8)  
*pvector limit test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s1t9)  
*pvector overloaded operators test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s2t1)  
*point multiplication test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s2t2)  
*point division test case*
- [BOOST\\_AUTO\\_TEST\\_CASE](#) (s2t3)  
*point overloaded operators test case*

### 7.74.1 Detailed Description

unit test suites

Author

Mehmet Rıza Öz - [mehmetrizaoz@gmail.com](mailto:mehmetrizaoz@gmail.com)

Date

15.05.2021

### 7.74.2 Macro Definition Documentation

#### 7.74.2.1 BOOST\_TEST\_MODULE

```
#define BOOST_TEST_MODULE test_suites
```

Definition at line 8 of file test\_suites.cpp.

### 7.74.3 Function Documentation

#### 7.74.3.1 BOOST\_AUTO\_TEST\_CASE() [1/12]

```
BOOST_AUTO_TEST_CASE (
    s1t1 )
```

pvector magnitude test case

Definition at line 22 of file test\_suites.cpp.

```
23 {
24     pvector p1 = pvector(0, 4);
25     pvector p2 = pvector(3, 0);
26     pvector p3 = p1 + p2;
27     BOOST_CHECK(p3.magnitude() == 5);
28 }
```

**7.74.3.2 BOOST\_AUTO\_TEST\_CASE()** [2/12]

```
BOOST_AUTO_TEST_CASE (
    slt2 )
```

pvector mul test case

Definition at line 33 of file test\_suites.cpp.

```
34 {
35     pvector p1 = pvector(1, 1);
36     p1.mul(3);
37     pvector p2 = pvector(3, 3);
38     BOOST_CHECK(p1 == p2);
39 }
```

**7.74.3.3 BOOST\_AUTO\_TEST\_CASE()** [3/12]

```
BOOST_AUTO_TEST_CASE (
    slt3 )
```

pvector div test case

Definition at line 44 of file test\_suites.cpp.

```
45 {
46     pvector p1 = pvector(5, 5);
47     p1.div(5);
48     pvector p2 = pvector(1, 1);
49     BOOST_CHECK(p1 == p2);
50 }
```

**7.74.3.4 BOOST\_AUTO\_TEST\_CASE()** [4/12]

```
BOOST_AUTO_TEST_CASE (
    slt4 )
```

pvector dotproduct test case

Definition at line 55 of file test\_suites.cpp.

```
56 {
57     pvector p1 = pvector(1, 4);
58     pvector p2 = pvector(3, 2);
59     float dotProduct = p1.dotProduct(p2);
60     BOOST_CHECK(dotProduct == 11);
61 }
```

**7.74.3.5 BOOST\_AUTO\_TEST\_CASE()** [5/12]

```
BOOST_AUTO_TEST_CASE (
    slt5 )
```

pvector angle between vectors test case

Definition at line 66 of file test\_suites.cpp.

```
67 {
68     pvector p1 = pvector(10, 10);
69     pvector p2 = pvector(0, 10);
70     float angle = p1.angleBetween(p2);
71     BOOST_CHECK(angle == 45);
72 }
```

**7.74.3.6 BOOST\_AUTO\_TEST\_CASE()** [6/12]

```
BOOST_AUTO_TEST_CASE (
    slt6 )
```

pvector get vector angle test case

Definition at line 77 of file test\_suites.cpp.

```
78 {
79     pvector p1 = pvector(3, 4);
80     float angle = p1.getAngle();
81     BOOST_CHECK(angle < 53.2 && angle > 52.8);
82 }
```

**7.74.3.7 BOOST\_AUTO\_TEST\_CASE()** [7/12]

```
BOOST_AUTO_TEST_CASE (
    slt7 )
```

pvector normalize test case

Definition at line 87 of file test\_suites.cpp.

```
88 {
89     pvector p1 = pvector(2, 2);
90     p1.normalize();
91     float range = 0.01;
92     BOOST_CHECK_CLOSE_FRACTION(0.707, p1.x, range);
93     BOOST_CHECK_CLOSE_FRACTION(0.707, p1.y, range);
94 }
```

**7.74.3.8 BOOST\_AUTO\_TEST\_CASE()** [8/12]

```
BOOST_AUTO_TEST_CASE (
    slt8 )
```

pvector limit test case

Definition at line 99 of file test\_suites.cpp.

```
100 {
101     pvector p1 = pvector(2, 2);
102     p1.limit(3);
103     float range = 0.01;
104     BOOST_CHECK_CLOSE_FRACTION(2.12, p1.x, range);
105     BOOST_CHECK_CLOSE_FRACTION(2.12, p1.y, range);
106 }
```

**7.74.3.9 BOOST\_AUTO\_TEST\_CASE()** [9/12]

```
BOOST_AUTO_TEST_CASE (
    s1t9 )
```

pvector overloaded operators test case

Definition at line 111 of file test\_suites.cpp.

```
112 {
113     pvector p1 = pvector(1, 1);
114     p1 += pvector(1, 1);
115     BOOST_CHECK(p1 == pvector(2, 2));
116     p1 = pvector(1, 1) + pvector(3, 3);
117     BOOST_CHECK(p1 == pvector(4, 4));
118     p1 = pvector(4, 1) - pvector(3, 3);
119     BOOST_CHECK(p1 == pvector(1, -2));
120     p1 = pvector(4, 1) - point(3, 3);
121     BOOST_CHECK(p1 == pvector(1, -2));
122     p1 = pvector(4, 1) + point(3, 3);
123     BOOST_CHECK(p1 == pvector(7, 4));
124 }
```

**7.74.3.10 BOOST\_AUTO\_TEST\_CASE()** [10/12]

```
BOOST_AUTO_TEST_CASE (
    s2t1 )
```

point multiplication test case

Definition at line 133 of file test\_suites.cpp.

```
134 {
135     point p1 = point(1, 1);
136     p1.mul(3);
137     point p2 = point(3, 3);
138     BOOST_CHECK(p1 == p2);
139 }
```

**7.74.3.11 BOOST\_AUTO\_TEST\_CASE()** [11/12]

```
BOOST_AUTO_TEST_CASE (
    s2t2 )
```

point division test case

Definition at line 144 of file test\_suites.cpp.

```
145 {
146     point p1 = point(4, 4);
147     p1.div(4);
148     point p2 = point(1, 1);
149     BOOST_CHECK(p1 == p2);
150 }
```

### 7.74.3.12 BOOST\_AUTO\_TEST\_CASE() [12/12]

```
BOOST_AUTO_TEST_CASE (
    s2t3 )
```

point overloaded operators test case

Definition at line 155 of file test\_suites.cpp.

```
156 {
157     point p1 = point(1,1) + point(3,3);
158     BOOST_CHECK(p1 == point(4,4));
159     p1 = point(1,1) + pvector(3,3);
160     BOOST_CHECK(p1 == point(4,4));
161     pvector p2 = point(1,1) - point(3,3);
162     BOOST_CHECK(p2 == pvector(-2,-2));
163 }
```

## 7.75 /home/user/Desktop/mmm/autonomousSteeringAgents/wander.d File Reference

## 7.76 /home/user/Desktop/mmm/autonomousSteeringAgents/windy.d File Reference



# Index

/home/user/Desktop/mmm/autonomousSteeringAgents/README.md, 19  
137 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pursuit.h,  
/home/user/Desktop/mmm/autonomousSteeringAgents/agent.d, 120  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/include/pvector.h,  
/home/user/Desktop/mmm/autonomousSteeringAgents/color.d, 122  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/include/random.h,  
/home/user/Desktop/mmm/autonomousSteeringAgents/entity.d, 123  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/include/scenario.h,  
/home/user/Desktop/mmm/autonomousSteeringAgents/evade.d, 124  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/include/steeringBe  
/home/user/Desktop/mmm/autonomousSteeringAgents/flee.d, 125  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/include/wander.h,  
/home/user/Desktop/mmm/autonomousSteeringAgents/flock.d, 129  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/include/windy.h,  
/home/user/Desktop/mmm/autonomousSteeringAgents/flowField.d, 131  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/leaderFollower.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/graphics.d, 132  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/main.cpp,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/agent.h, 132  
96 /home/user/Desktop/mmm/autonomousSteeringAgents/main.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/color.h, 137  
98 /home/user/Desktop/mmm/autonomousSteeringAgents/mouseFollower.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/entity.h, 137  
100 /home/user/Desktop/mmm/autonomousSteeringAgents/obstacle.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/evade.h, 137  
101 /home/user/Desktop/mmm/autonomousSteeringAgents/obstacleAvoidance  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/flee.h, 137  
102 /home/user/Desktop/mmm/autonomousSteeringAgents/path.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/flock.h, 137  
104 /home/user/Desktop/mmm/autonomousSteeringAgents/pathFollower.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/flowField.h, 137  
105 /home/user/Desktop/mmm/autonomousSteeringAgents/point.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/graph.h, 137  
108 /home/user/Desktop/mmm/autonomousSteeringAgents/prison.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/leaderFollower.h, 137  
110 /home/user/Desktop/mmm/autonomousSteeringAgents/pursuit.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/mouseFollower.h, 137  
111 /home/user/Desktop/mmm/autonomousSteeringAgents/pvector.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacle.h, 137  
112 /home/user/Desktop/mmm/autonomousSteeringAgents/random.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/obstacleAvoidance.h, 137  
114 /home/user/Desktop/mmm/autonomousSteeringAgents/scenario.d,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/path.h, 137  
115 /home/user/Desktop/mmm/autonomousSteeringAgents/src/agent.cpp,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/pathFollower.h, 137  
116 /home/user/Desktop/mmm/autonomousSteeringAgents/src/color.cpp,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/point.h, 138  
118 /home/user/Desktop/mmm/autonomousSteeringAgents/src/entity.cpp,  
/home/user/Desktop/mmm/autonomousSteeringAgents/include/prison.h, 139

- /home/user/Desktop/mmm/autonomousSteeringAgents/src/evade.cpp, 19
- 140
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/flee.cpp, 19
- 141
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/flock.cpp, 15
- 142
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/flowField.cpp, 16
- 143
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/graph.cpp, 16
- 144
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/leaderFollower.cpp, 20
- 145
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/mouse.cpp, 20
- 147
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacle.cpp, 16
- 148
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/obstacleAvoidance.cpp, 17
- 149
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/path.cpp, 17
- 150
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/pathFollowing.cpp, 18
- 151
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/point.cpp, 18
- 152
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/prisoner.cpp, 81
- 153
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/pursuing.cpp, 83
- 155
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/pvector.cpp, 70
- 156
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/random.cpp, 19
- 157
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/scenario.cpp, 84
- 157
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/steeringBehavior.h, 127
- 159
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/wander.cpp, 23
- 160
- /home/user/Desktop/mmm/autonomousSteeringAgents/src/wander.cpp, 81
- 161
- /home/user/Desktop/mmm/autonomousSteeringAgents/steeringBehavior.d, 99
- 162
- /home/user/Desktop/mmm/autonomousSteeringAgents/test/BLUE\_test/test\_suites.cpp, 99
- 162
- /home/user/Desktop/mmm/autonomousSteeringAgents/wander.cpp, 163–166
- 167
- /home/user/Desktop/mmm/autonomousSteeringAgents/wireframe.cpp, 163
- 167
- ~agent
- agent, 15
- acceleration
- agent, 19
- add
- pvector, 68
- addPoint
- path, 53
- agent, 13
- ~agent, 15
- callback
- scenario, 82
- CIRCLE\_DISTANCE
- steeringBehavior.h, 127
- CIRCLE\_RADIUS
- steeringBehavior.h, 127
- cohesion
- steeringBehavior, 85
- color, 21
- B, 23



- color, 22
- G, 23
- getColor, 23
- R, 24
- color.h
  - BLACK, 99
  - BLUE, 99
  - CYAN, 99
  - GREEN, 99
  - MAGENDA, 99
  - RED, 100
  - WHITE, 100
  - YELLOW, 100
- createObstacle
  - obstacleAvoidance, 50
- createPath
  - pathFollower, 55
- createRandomAgents
  - scenario, 79
- createRandomArray
  - random, 77
- createStaticAgents
  - scenario, 79
- createTroop
  - scenario, 80
- CYAN
  - color.h, 99
- desiredVelocity
  - agent, 19
- difference
  - point, 58
- DISTANCE
  - prison.cpp, 154
- div
  - point, 59
  - pvector, 70
- dotProduct
  - pvector, 70
- draw
  - agent, 15
  - entity, 25
  - obstacle, 48
  - path, 53
- drawAgent
  - graphics, 34
- drawCircle
  - graphics, 35
- drawLine
  - graphics, 35
- drawPath
  - graphics, 36
- drawPoint
  - graphics, 36
- drawText
  - graphics, 36
- entity, 24
  - draw, 25
  - entity, 25
  - getColor, 25
  - getId, 25
  - getName, 26
  - setColor, 26
  - setId, 26
  - setName, 27
- ESC
  - graphics.h, 109
- EVADE
  - steeringBehavior.h, 127
- evade, 27
  - evade, 28
  - loop, 28
  - steeringBehavior, 85
- FIELD\_HEIGHT
  - flowField.h, 107
- FIELD\_WIDTH
  - flowField.h, 107
- FLEE
  - steeringBehavior.h, 127
- flee, 28
  - flee, 29
  - loop, 29
  - steeringBehavior, 86
- FLOCK
  - steeringBehavior.h, 128
- flock, 30
  - flock, 30
  - loop, 30
- flow
  - windy, 94
- flowField, 31
  - flowField, 31, 32
  - getField, 32
- flowField.h
  - FIELD\_HEIGHT, 107
  - FIELD\_WIDTH, 107
  - GRAVITY, 107
  - WIND\_WEST, 107
- FOLLOW\_MOUSE
  - steeringBehavior.h, 128
- force
  - agent, 19
- forceInScreen
  - graphics, 37
- G
  - color, 23
- getAngle
  - pvector, 71
- getCenter
  - obstacle, 48
- getColor
  - color, 23
  - entity, 25
- getField
  - flowField, 32

- getId
  - entity, 25
- getMass
  - agent, 16
- getMousePosition
  - graphics, 37
- getName
  - agent, 16
  - entity, 26
- getNormalPoint
  - point, 59
- getPathWidth
  - path, 53
- getRadius
  - obstacle, 48
- getTarget
  - agent, 16
- getVelocity
  - agent, 16
- graphics, 33
  - drawAgent, 34
  - drawCircle, 35
  - drawLine, 35
  - drawPath, 36
  - drawPoint, 36
  - drawText, 36
  - forceInScreen, 37
  - getMousePosition, 37
  - handleKeyPress, 37
  - handleResize, 38
  - initGraphics, 38
  - mouseButton, 40
  - mouseMove, 40
  - refreshScene, 41
  - target\_x, 41
  - target\_y, 42
  - timerEvent, 41
- graphics.h
  - ESC, 109
  - HEIGHT, 109
  - PI, 109
  - WIDTH, 109
- GRAVITY
  - flowField.h, 107
- GREEN
  - color.h, 99
- handleKeyPress
  - graphics, 37
- handleResize
  - graphics, 38
- HEIGHT
  - graphics.h, 109
- id
  - agent, 20
- IN\_FLOW\_FIELD
  - steeringBehavior.h, 128
- inFlowField
  - steeringBehavior, 87
- initGL
  - scenario, 81
- initGraphics
  - graphics, 38
- LEADER\_FOLLOWER
  - steeringBehavior.h, 128
- leaderAngle
  - leaderFollower, 44
- leaderFollower, 42
  - leaderAngle, 44
  - leaderFollower, 43
  - leaderPosition, 44
  - leaderVelocity, 45
  - loop, 43
- leaderFollower.cpp
  - mainTarget, 146
- leaderPosition
  - leaderFollower, 44
- leaderVelocity
  - leaderFollower, 45
- limit
  - pvector, 71
- loop
  - evade, 28
  - flee, 29
  - flock, 30
  - leaderFollower, 43
  - mouseFollower, 46
  - obstacleAvoidance, 51
  - pathFollower, 56
  - prison, 64
  - pursuit, 66
  - wander, 92
  - windy, 94
- MAGENDA
  - color.h, 99
- magnitude
  - pvector, 72
- main
  - main.cpp, 133
- main.cpp
  - main, 133
  - menu, 134
  - mode, 135
- mainTarget
  - leaderFollower.cpp, 146
- MAX\_NUMBER\_OF\_AGENTS
  - scenario.cpp, 158
- maxForce
  - agent, 20
- maxSpeed
  - agent, 20
- menu
  - main.cpp, 134
- mode
  - main.cpp, 135

- mouseButton
  - graphics, 40
- mouseFollower, 45
  - loop, 46
  - mouseFollower, 45
- mouseMove
  - graphics, 40
- mul
  - point, 60
  - pvector, 72
- myPath
  - pathFollower, 56
- name
  - scenario, 82
- normalize
  - pvector, 72
- obstacle, 46
  - draw, 48
  - getCenter, 48
  - getRadius, 48
  - obstacle, 47
  - setCenter, 49
  - setRadius, 49
- obstacleAvoidance, 49
  - createObstacle, 50
  - loop, 51
  - obstacleAvoidance, 50
  - obstacles, 51
- obstacles
  - obstacleAvoidance, 51
- operator+
  - point, 60
  - pvector, 73
- operator+=
  - pvector, 74
- operator-
  - point, 61
  - pvector, 74, 75
- operator==
  - point, 61
  - pvector, 75
- path, 52
  - addPoint, 53
  - draw, 53
  - getPathWidth, 53
  - path, 52
  - points, 54
  - setPathWidth, 54
- pathFollower, 54
  - createPath, 55
  - loop, 56
  - myPath, 56
  - pathFollower, 55
- PI
  - graphics.h, 109
  - pvector.h, 123
- point, 57
  - difference, 58
  - div, 59
  - getNormalPoint, 59
  - mul, 60
  - operator+, 60
  - operator-, 61
  - operator==, 61
  - point, 57, 58
  - print, 62
  - rotate, 62
  - rotateByAngleAboutPoint, 63
  - x, 63
  - y, 63
- points
  - path, 54
- position
  - agent, 20
- print
  - point, 62
  - pvector, 75
- prison, 64
  - loop, 64
  - prison, 64
- prison.cpp
  - DISTANCE, 154
  - WALL, 154
- PURSUIT
  - steeringBehavior.h, 128
- pursuit, 65
  - loop, 66
  - pursuit, 66
  - steeringBehavior, 87
- pvector, 66
  - add, 68
  - angleBetween, 70
  - div, 70
  - dotProduct, 70
  - getAngle, 71
  - limit, 71
  - magnitude, 72
  - mul, 72
  - normalize, 72
  - operator+, 73
  - operator+=, 74
  - operator-, 74, 75
  - operator==, 75
  - print, 75
  - pvector, 68
  - x, 76
  - y, 76
- pvector.h
  - PI, 123
- R
  - color, 24
- r
  - agent, 20
- RANDOM

- scenario.h, 125
- random, 76
  - createRandomArray, 77
- RED
  - color.h, 100
- refresh
  - scenario, 81
- refreshScene
  - graphics, 41
- rotate
  - point, 62
- rotateByAngleAboutPoint
  - point, 63
- scenario, 77
  - agents, 81
  - behavior, 81
  - callback, 82
  - createRandomAgents, 79
  - createStaticAgents, 79
  - createTroop, 80
  - initGL, 81
  - name, 82
  - refresh, 81
  - scenario, 78
  - view, 82
- scenario.cpp
  - MAX\_NUMBER\_OF\_AGENTS, 158
- scenario.h
  - RANDOM, 125
  - STATIC, 125
  - TROOP, 125
  - types, 125
- seek
  - steeringBehavior, 88
- separation
  - steeringBehavior, 88
- setCenter
  - obstacle, 49
- setColor
  - entity, 26
- setFeatures
  - agent, 16
- setId
  - entity, 26
- setMass
  - agent, 17
- setName
  - agent, 17
  - entity, 27
- setPathWidth
  - path, 54
- setRadius
  - obstacle, 49
- setTarget
  - agent, 17
- setVelocity
  - agent, 18
- STATIC
  - scenario.h, 125
- STAY\_IN\_FIELD
  - steeringBehavior.h, 128
- STAY\_IN\_PATH
  - steeringBehavior.h, 129
- stayInArea
  - steeringBehavior, 89
- stayInPath
  - steeringBehavior, 90
- steering
  - agent, 21
- steeringBehavior, 83
  - align, 83
  - avoid, 84
  - cohesion, 85
  - evade, 85
  - flee, 86
  - inFlowField, 87
  - pursuit, 87
  - seek, 88
  - separation, 88
  - stayInArea, 89
  - stayInPath, 90
  - wander, 91
- steeringBehavior.h
  - AVOID\_OBSTACLE, 127
  - CIRCLE\_DISTANCE, 127
  - CIRCLE\_RADIUS, 127
  - EVADE, 127
  - FLEE, 127
  - FLOCK, 128
  - FOLLOW\_MOUSE, 128
  - IN\_FLOW\_FIELD, 128
  - LEADER\_FOLLOWER, 128
  - PURSUIT, 128
  - STAY\_IN\_FIELD, 128
  - STAY\_IN\_PATH, 129
  - WANDER, 129
- target\_x
  - graphics, 41
- target\_y
  - graphics, 42
- targetPoint
  - agent, 21
- test\_suites.cpp
  - BOOST\_AUTO\_TEST\_CASE, 163–166
  - BOOST\_TEST\_MODULE, 163
- timerEvent
  - graphics, 41
- TROOP
  - scenario.h, 125
- types
  - scenario.h, 125
- uml/activity\_diagram/todo.txt, 96
- uml/state\_diagram/todo.txt, 96
- uml/use\_case\_diagram/todo.txt, 96
- updatePosition

- agent, [18](#)
- view
  - scenario, [82](#)
- WALL
  - prison.cpp, [154](#)
- WANDER
  - steeringBehavior.h, [129](#)
- wander, [91](#)
  - loop, [92](#)
  - steeringBehavior, [91](#)
  - wander, [92](#)
- WHITE
  - color.h, [100](#)
- WIDTH
  - graphics.h, [109](#)
- WIND\_WEST
  - flowField.h, [107](#)
- windy, [93](#)
  - flow, [94](#)
  - loop, [94](#)
  - windy, [93](#)
- x
  - point, [63](#)
  - pvector, [76](#)
- y
  - point, [63](#)
  - pvector, [76](#)
- YELLOW
  - color.h, [100](#)