

$$e) P(X_2 | X_1, \dots, X_{t-1}) = \sum_{i=1}^2 P(X_t, S_t=i | X_1, \dots, X_{t-1}) = \sum_i \underbrace{P(X_t | S_t=i)}_{\text{Gaussian mixture with } n \text{ components}} \underbrace{P(S_t=i | X_1, \dots, X_{t-1})}_{\text{Gaussian mixture with } n \text{ components}}$$

$$f) P(X_t) = \sum_{i=1}^2 \underbrace{P(X_t | S_t=i)}_{\text{Gaussian mixture with } n \text{ components}} \underbrace{P(S_t=i)}_{\text{Gaussian mixture with } n \text{ components}}$$

$$g) P(X_1 | S_1, \dots, S_t) P(X_2 | S_1, \dots, S_t, X_1) \dots P(X_t | S_1, \dots, S_t, X_1, \dots, X_{t-1}) = \prod_{i=1}^t P(X_i | S_i)$$

d-separation

multivariate Gaussian with (t-dim).

$$\mu = \begin{bmatrix} \mu_{s_1} \\ \mu_{s_2} \\ \vdots \\ \mu_{s_t} \end{bmatrix} \quad \text{and} \quad \Sigma = \begin{bmatrix} \sigma_{s_1}^2 & & & 0 \\ & \sigma_{s_2}^2 & & \\ & & \ddots & \\ 0 & & & \sigma_{s_t}^2 \end{bmatrix}$$

can be derived by multiplying all univariate Gaussian $P(X_i | S_i)$ is

$$\frac{P(X_1, X_2, \dots, X_t, S_1, S_2, \dots)}{P(S_1, S_2, \dots) \underbrace{P(S_1, S_2, \dots)}_{\text{the case that will be symmetric}} \underbrace{P(S_1, S_2, \dots)}_{\text{the case that will be symmetric}}}$$

$$= P(X_1 | S_1) P(X_2 | S_2) \dots \rightarrow \text{2D Gaussian with } \mu = \begin{bmatrix} \mu_{s_1} \\ \mu_{s_2} \end{bmatrix} \quad \text{and} \quad \Sigma = \begin{bmatrix} \sigma_{s_1}^2 & 0 \\ 0 & \sigma_{s_2}^2 \end{bmatrix}$$

① $\ell_{i,t}^* = \max_{S_1, \dots, S_{t-1}} \log P(a_1, a_2, \dots, a_t | S_1, \dots, S_{t-1}, S_t = i)$

$\ell_{j,t+1}^* = \max_i (\ell_{i,t}^* + \log a_{ij}) + \log b_j(a_{t+1})$

Base case: $\ell_{i,1}^* = \log P(a_1, S_1 = i) = \log (S_1 = i) + \log P(a_1 | S_1 = i) = \log \pi_i + \log b_i(a_1)$

At each time step ℓ_t^* is an $n \times 1$ vector ($n=26$); $t=1, \dots, 152000$

Save $\ell_t^* = \begin{bmatrix} \ell_{1,t}^* \\ \ell_{2,t}^* \\ \vdots \\ \ell_{26,t}^* \end{bmatrix}$ for $t=1, \dots, T$ in $L = \begin{bmatrix} \ell_1^* & \ell_2^* & \dots & \ell_T^* \end{bmatrix}$ ($n \times T$ matrix)

Also, save $\mathbb{F}_{t+1}(j) = \arg \max_i (\ell_{i,t}^* + \log a_{ij})$

$\mathbb{F}_t = \begin{bmatrix} \mathbb{F}_t(1) \\ \vdots \\ \mathbb{F}_t(26) \end{bmatrix}$ ($n \times 1$ vector) $\rightarrow \mathbb{F} = \begin{bmatrix} \mathbb{F}_1 & \mathbb{F}_2 & \dots & \mathbb{F}_T \end{bmatrix}$ ($n \times (T-1)$ matrix)

Now backtracking:
 $S_T^* = \arg \max_i \ell_{i,T}^*$

$S_t^* = \mathbb{F}_{t+1}(S_{t+1}^*) \rightarrow$ Square found \rightarrow

the next page

Lastly, substitute captions and decode the actual sentence.

② $P(X_t | S_{t-1}) = \sum_{i=1}^n P(X_t, S_t = i | S_{t-1}) = \sum_i P(X_t | S_t = i, S_{t-1}) P(S_t = i | S_{t-1})$

$= \sum_i \underbrace{P(X_t | S_t = i)}_{\text{Gaussian}} \underbrace{P(S_t = i | S_{t-1})}_{\text{number}} \rightarrow$ Gaussian mixture with n components

d) $\sum_{(S_1, \dots, S_t)} P(X_1, \dots, X_t, S_1 = s_1, \dots, S_t = s_t) = \sum P(X_1, \dots, X_t | S_1 = s_1, \dots, S_t = s_t) P(S_1 = s_1, \dots, S_t = s_t)$

\downarrow Gaussian mixture $\rightarrow \prod_{i=1}^t P(X_i | S_i)$ number

Gaussian mixture with n components

$$\textcircled{2} P(S_{t+1}=j, S_{t+2}=1, S_t=i, \vec{0})$$

$$= \sum_{S_{t+1}} P(S_{t+2}=1, S_{t+1}=j, S_t=i, \vec{0})$$

$$P(a_1, a_2, \dots, a_t, S_t=1) P(a_{t+1}, \dots, a_T | S_t=1)$$

$$\sum_{S_{t+1}} P(S_{t+1}=j, a_t, \dots, a_{t-1}) P(S_t=i | S_{t+1}=j) P(S_{t+2}=1 | S_{t+1}=j) P(a_t | S_t=i) P(a_{t+1} | S_{t+1}=j) P(a_{t+2} | S_{t+2}=1).$$

$$P(a_{t+3}, \dots, a_T | S_{t+2}=1)$$

Bit

$$\sum_{S_{t+1}} \alpha_{j(t-1)} \alpha_{ji} a_i(a_{t+1}) a_j(a_{t+2}) b_j(a_{t+1}) b_i(a_{t+2}) P(a_{t+2})$$

for a particular observation sequence S_0, a_2, \dots, a_T

Bit

This expression assumes stationary joint distribution

$$\textcircled{3} a) q_{jt} = P(S_t=j | a_1, \dots, a_t) = \frac{P(S_t=j, a_1, \dots, a_t)}{P(a_1, \dots, a_t)} \quad (\text{Product rule})$$

$$\sum_i P(S_t=j, S_{t-1}=i, a_1, \dots, a_t)$$

(Sum Rule)

$$\sum_{i,j} P(S_t=j, S_{t-1}=i, a_1, \dots, a_t)$$

$$\sum_i P(S_{t-1}=i, a_1, \dots, a_{t-1}) P(S_t=j | S_{t-1}=i) P(a_t | S_t=j)$$

(Product Rule Conditional Independence)

$$\sum_{i,j} P(S_{t-1}=i, a_1, \dots, a_{t-1}) P(S_t=j | S_{t-1}=i) P(a_t | S_t=j)$$

$$P(a_t | S_t=j) \sum_i P(S_t=j | S_{t-1}=i) P(S_{t-1}=i, a_1, \dots, a_{t-1})$$

$P(a_{t+1}) P(a_1, \dots, a_{t-1})$ independent of i, j (cancel)

$$\sum_{i,j} P(a_t | S_t=j) P(S_t=j | S_{t-1}=i) P(S_{t-1}=i, a_1, \dots, a_{t-1}) \sum_{i,j} b_j(a_t) \alpha_{ij} q_{i(t-1)}$$

$$b) P(x_t | y_1, \dots, y_t) = \frac{P(x_t, y_1, \dots, y_t)}{P(y_1, \dots, y_t)} = \frac{\int P(x_t, x_{t-1}, y_1, \dots, y_t) dx_{t-1}}{\int \int P(x_t, x_{t-1}, y_1, \dots, y_t) dx_{t-1} dy_t}$$

$$\int P(x_{t-1}, y_1, \dots, y_{t-1}) P(x_t | x_{t-1}) P(y_t | x_t) dx_{t-1}$$

$$\int \int P(x_{t-1}, y_1, \dots, y_{t-1}) P(x_t | x_{t-1}) P(y_t | x_t) dx_{t-1} dy_t = \int P(y_t | x_t) \int P(x_{t-1}, y_1, \dots, y_{t-1}) P(x_t | x_{t-1}) dx_{t-1}$$

independent of y_t (they cancel)

⑤

In the calculations above, the joint distribution $P(x_1, x_{1-1}, y_1, \dots, y_T)$ is marginalised once in the numerator and twice in the denominator for an arbitrary distribution, the resultant distributions may not be easy to solve. However, if the RVs are Gaussian, then we know this marginalisation will also be Gaussian and this makes the computation tractable...

$$\textcircled{5} a) P(y_1|x) = \frac{P(x|y_1)P(y_1)}{P(y_0)P(y_1) + P(y_1)P(y_1)}$$

$$= \frac{\sigma_1 (2\pi)^{-d/2} |\Sigma_1|^{-1/2} \exp\left(-\frac{1}{2}(x-\mu_1)^T \Sigma_1^{-1}(x-\mu_1)\right)}{\sigma_1 (2\pi)^{-d/2} |\Sigma_1|^{-1/2} \exp\left(-\frac{1}{2}(x-\mu_1)^T \Sigma_1^{-1}(x-\mu_1)\right) + \underbrace{\sigma_0 (2\pi)^{-d/2} |\Sigma_0|^{-1/2}}_{(1/\sigma_1)} \exp\left(-\frac{1}{2}(x-\mu_0)^T \Sigma_1^{-1}(x-\mu_0)\right)}$$

$$b) \Sigma_0 = \Sigma_1 = \Sigma$$

$$\sigma_1 (2\pi)^{-d/2} |\Sigma|^{-1/2} \exp\left(-\frac{1}{2}(x-\mu_1)^T \Sigma^{-1}(x-\mu_1)\right)$$

$$+ \sigma_0 (2\pi)^{-d/2} |\Sigma|^{-1/2} \exp\left(-\frac{1}{2}(x-\mu_1)^T \Sigma^{-1}(x-\mu_1)\right) + \sigma_0 \exp\left(-\frac{1}{2}(x-\mu_0)^T \Sigma^{-1}(x-\mu_0)\right)$$

$$= \frac{1 + \frac{\sigma_0}{\sigma_1} \exp\left(-\frac{1}{2}\left(x^T \Sigma^{-1} x - \mu_0^T \Sigma^{-1} x - x^T \Sigma^{-1} \mu_0 + \mu_0^T \Sigma^{-1} \mu_0 - x^T \Sigma^{-1} x + \mu_1^T \Sigma^{-1} x + x^T \Sigma^{-1} \mu_1 - \underbrace{\mu_1^T \Sigma^{-1} \mu_1}_{\text{scalar}}\right)\right)}{1 + \frac{\sigma_0}{\sigma_1} \exp\left(-\frac{1}{2}\left(2(\mu_1-\mu_0)^T \Sigma^{-1} x + \mu_0^T \Sigma^{-1} \mu_0 - \mu_1^T \Sigma^{-1} \mu_1\right)\right)}$$

$$= \frac{1 + \frac{\sigma_0}{\sigma_1} \exp\left(-\frac{1}{2}\left(2(\mu_1-\mu_0)^T \Sigma^{-1} x + \mu_0^T \Sigma^{-1} \mu_0 - \mu_1^T \Sigma^{-1} \mu_1\right)\right)}{1}$$

$$= \frac{1 + \exp\left(-\underbrace{\left[(\mu_1-\mu_0)^T \Sigma^{-1} x + \frac{1}{2} \mu_0^T \Sigma^{-1} \mu_0 - \frac{1}{2} \mu_1^T \Sigma^{-1} \mu_1\right]}_b - \ln\left(\frac{\sigma_0}{\sigma_1}\right)\right)}{1}$$

$$\text{where } w = \Sigma^{-1}(\mu_1-\mu_0), \quad b = \frac{1}{2} \mu_0^T \Sigma^{-1} \mu_0 - \frac{1}{2} \mu_1^T \Sigma^{-1} \mu_1 - \ln\left(\frac{\sigma_0}{\sigma_1}\right)$$

⑥