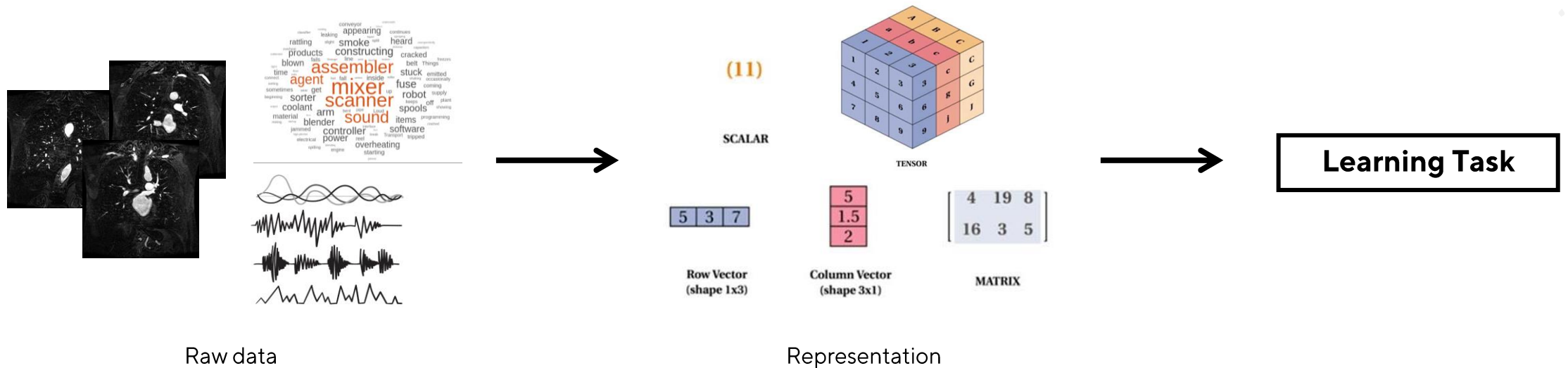


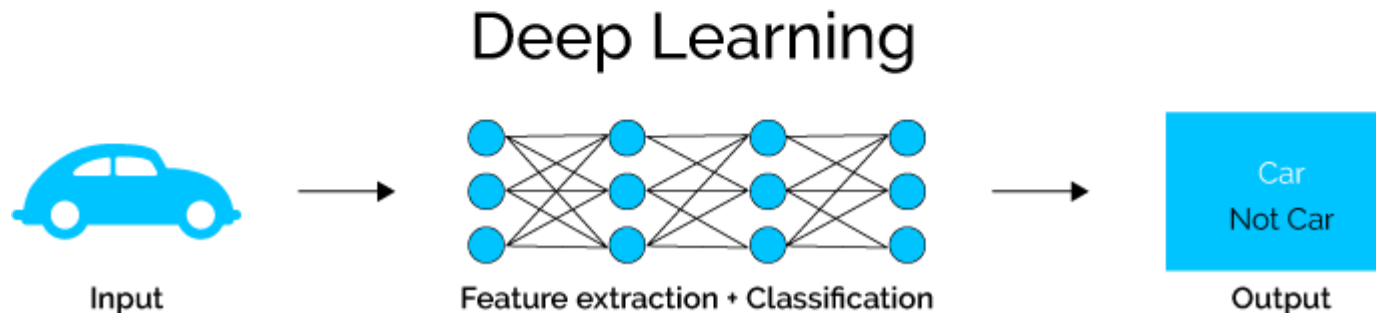
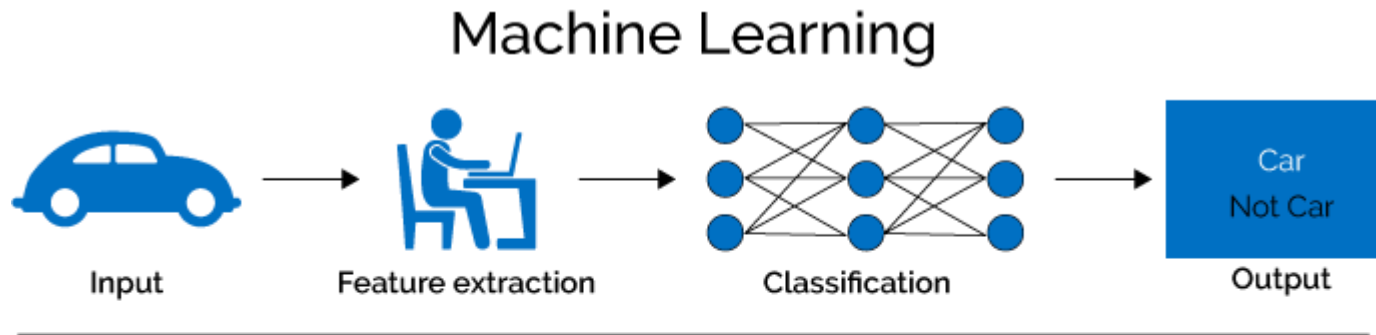
Introduction to Deep learning

- Deep Learning is a subset of machine learning
 - It uses multi-layered neural networks to model and understand **complex patterns** in data.



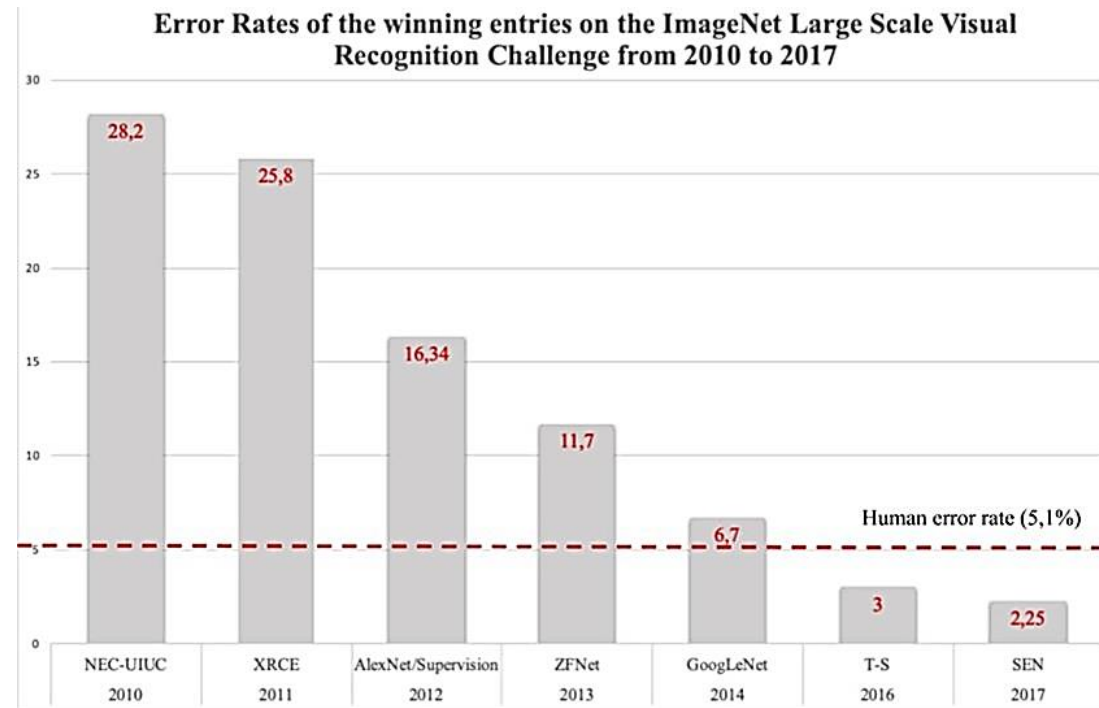
Deep learning vs Traditional Machine learning

- Feature engineering had a key role in **ML**
 - Hand-crafted features (e.g., word co-occurrence, term frequency)

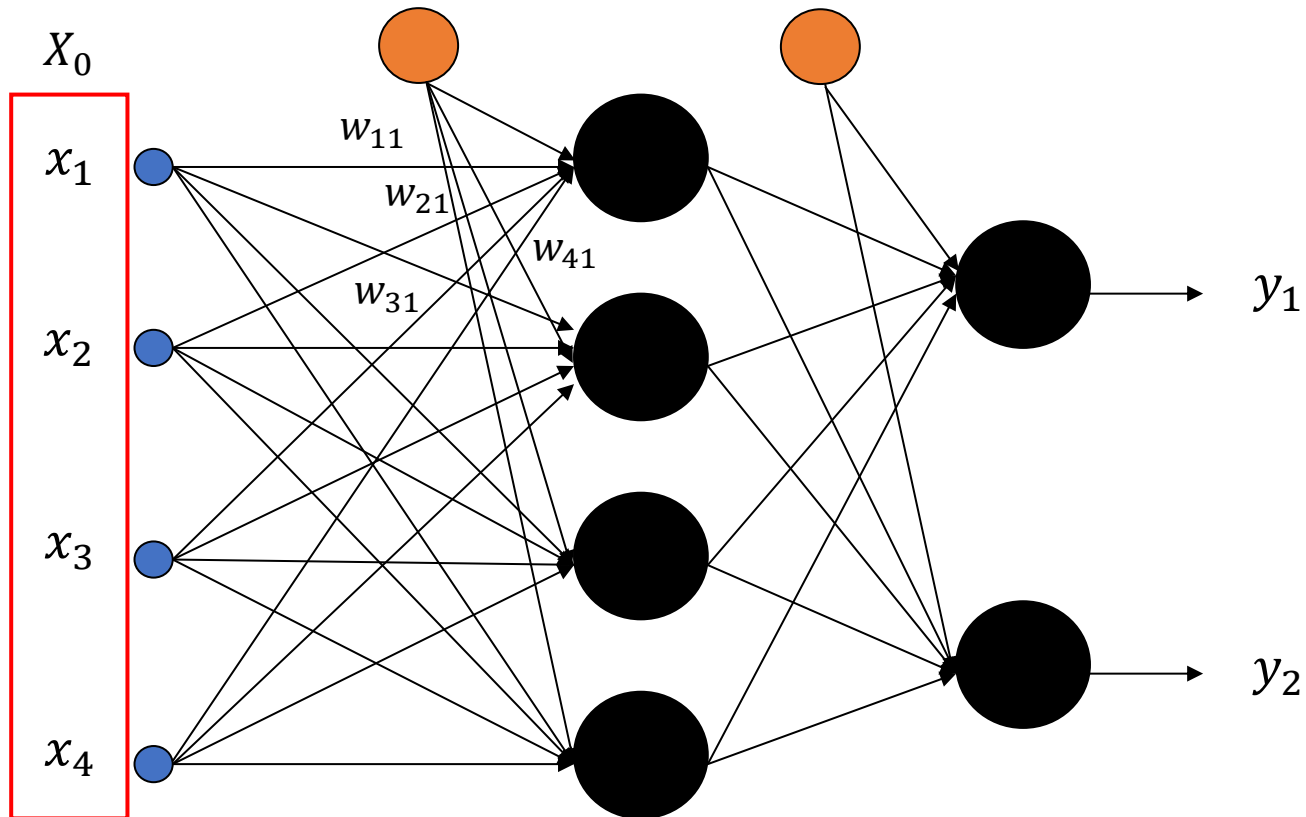


Data driven features

- Deep neural network (DNN) as **feature/representation learner**



A Simple Neural Network (NN)



$$W_1 = \begin{bmatrix} w_{11} & \dots & w_{41} \\ \vdots & \ddots & \vdots \\ w_{14} & \dots & w_{44} \end{bmatrix} \quad W_2 \rightarrow (4, 2)$$

W_i

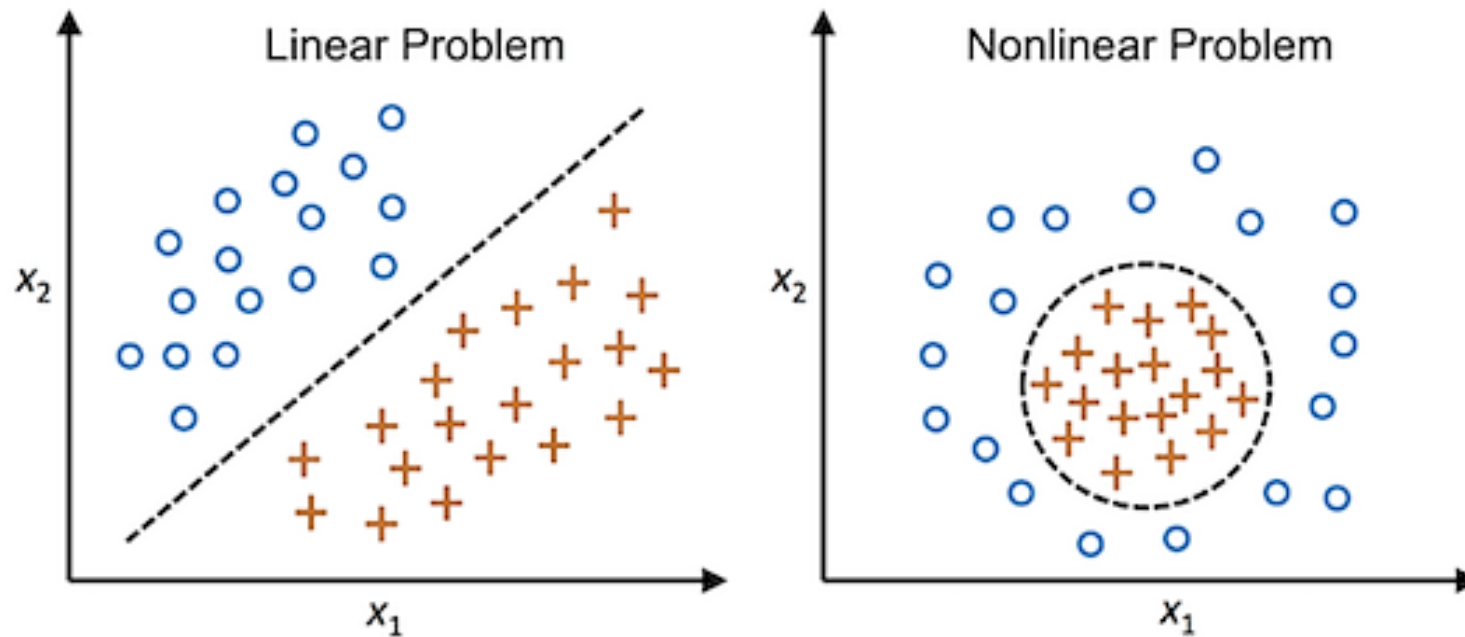
$$Y = f \left(\sum_i w_i x_i + b_i \right)$$

Activation function

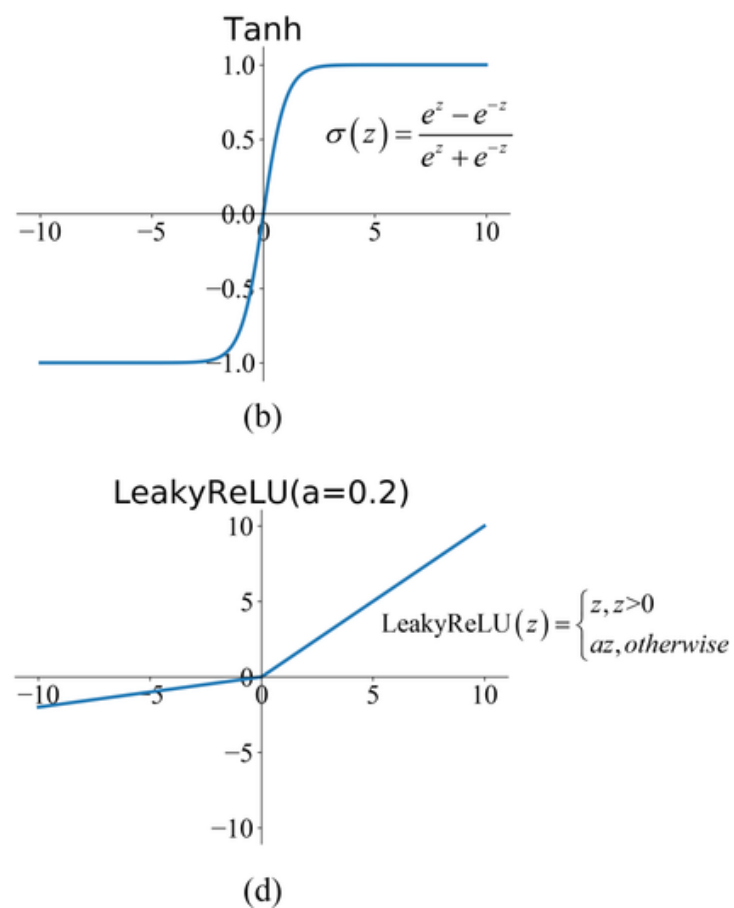
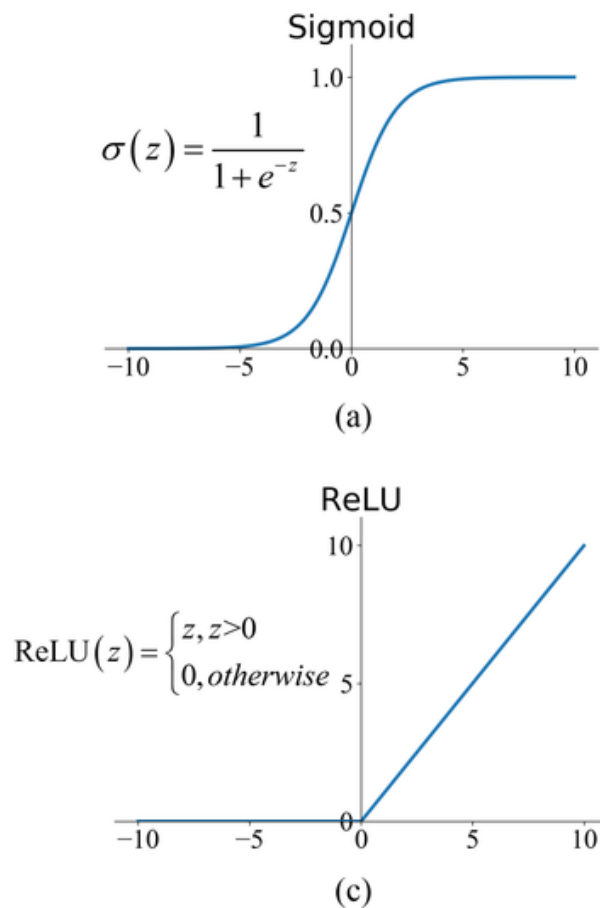
Why Activation functions?

Why Activation functions?

- They introduce **non-linearity** into the network!



Activation functions

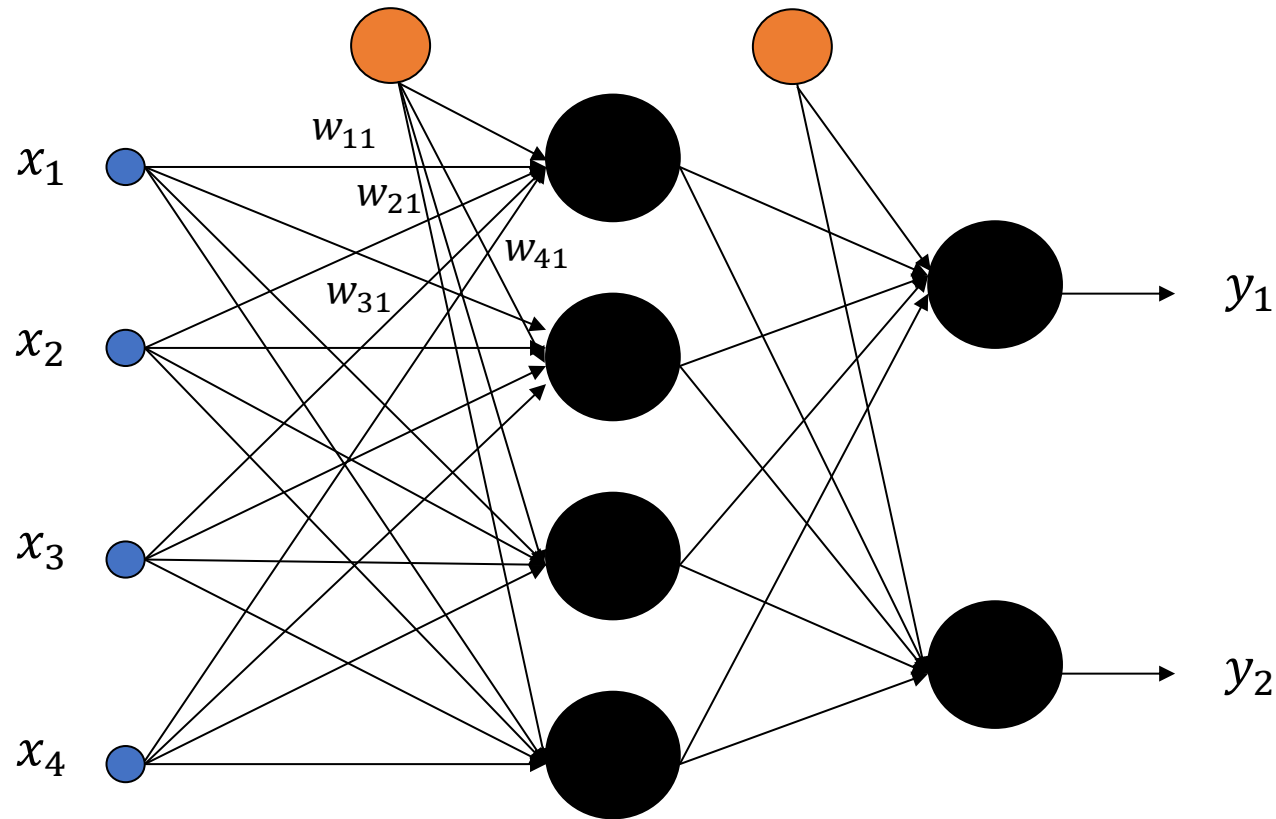


Which one to use?

- **Relu & LeakyRelu** are most used activation functions.
- **Dying Relu problem!**
- **LeakyRelu is better!**

$$\max(ax, x)$$

A Simple Neural Network (NN)



$$W_1 = \begin{bmatrix} w_{11} & \dots & w_{41} \\ \vdots & \ddots & \vdots \\ w_{14} & \dots & w_{44} \end{bmatrix}$$

$$W_2 \rightarrow (4, 2)$$

$$Y = f\left(\sum_i W_i X_i + b_i\right)$$

$$L(\mathbf{w}, \mathbf{b}) = \frac{1}{2} \sum_i (\underbrace{Y(\mathbf{X}, \mathbf{w}, \mathbf{b})}_{\text{Predicted label}} - \underbrace{Y'}_{\text{True label}})^2$$

Error = Loss value

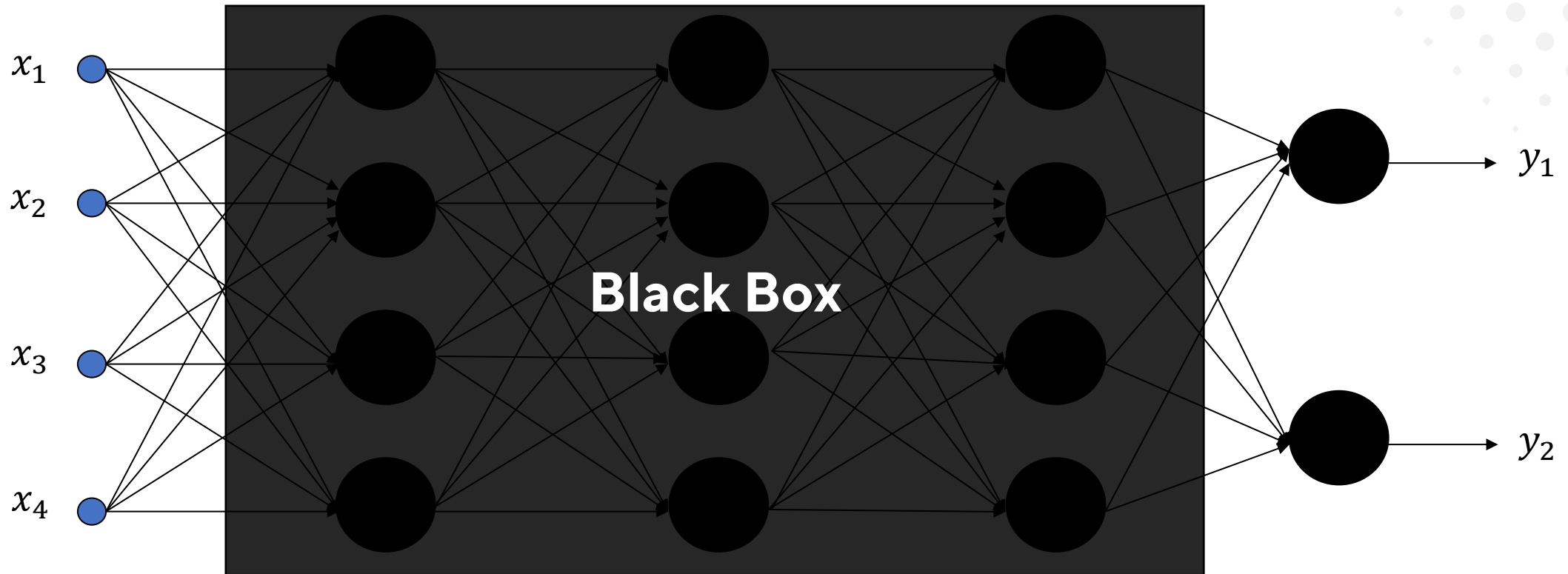


Using optimizers

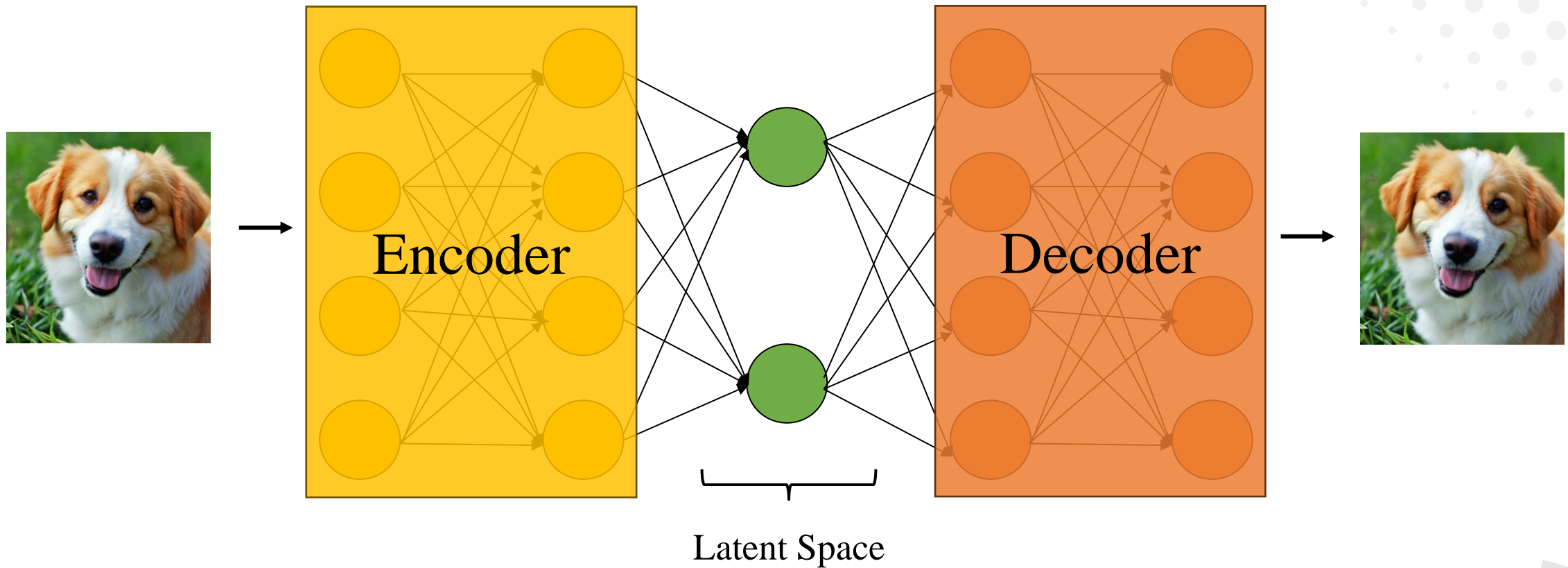
NN Optimizers

- Optimizers adjust weights of NN to minimize the loss during training
 - ✓ **Adam** (Adaptive Moment Estimation)
 - ✓ **SGD** (Stochastic Gradient Descent)
- Selection depends on **model complexity, dataset size, and convergence behavior.**

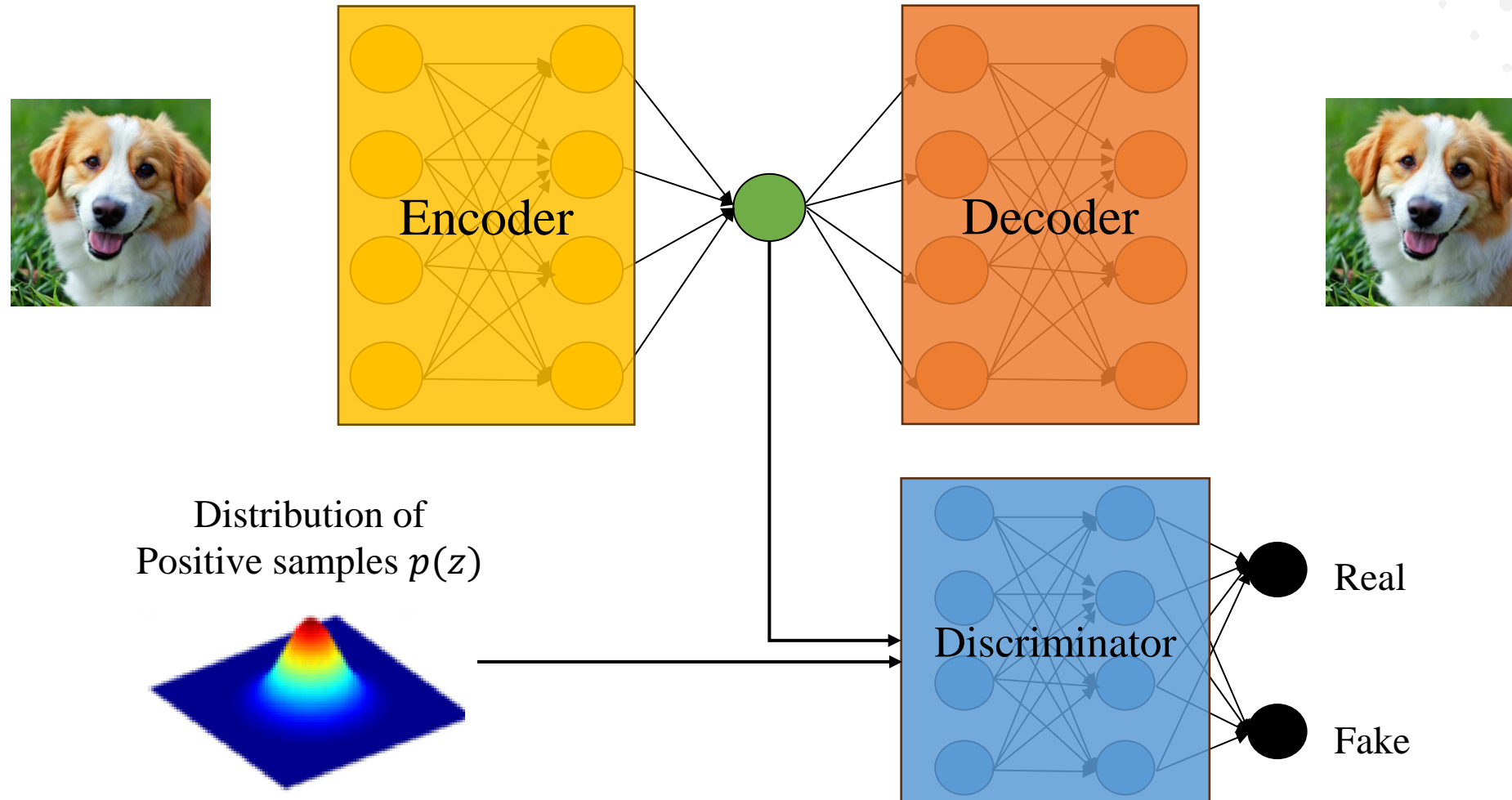
Deep Neural Network (DNN)



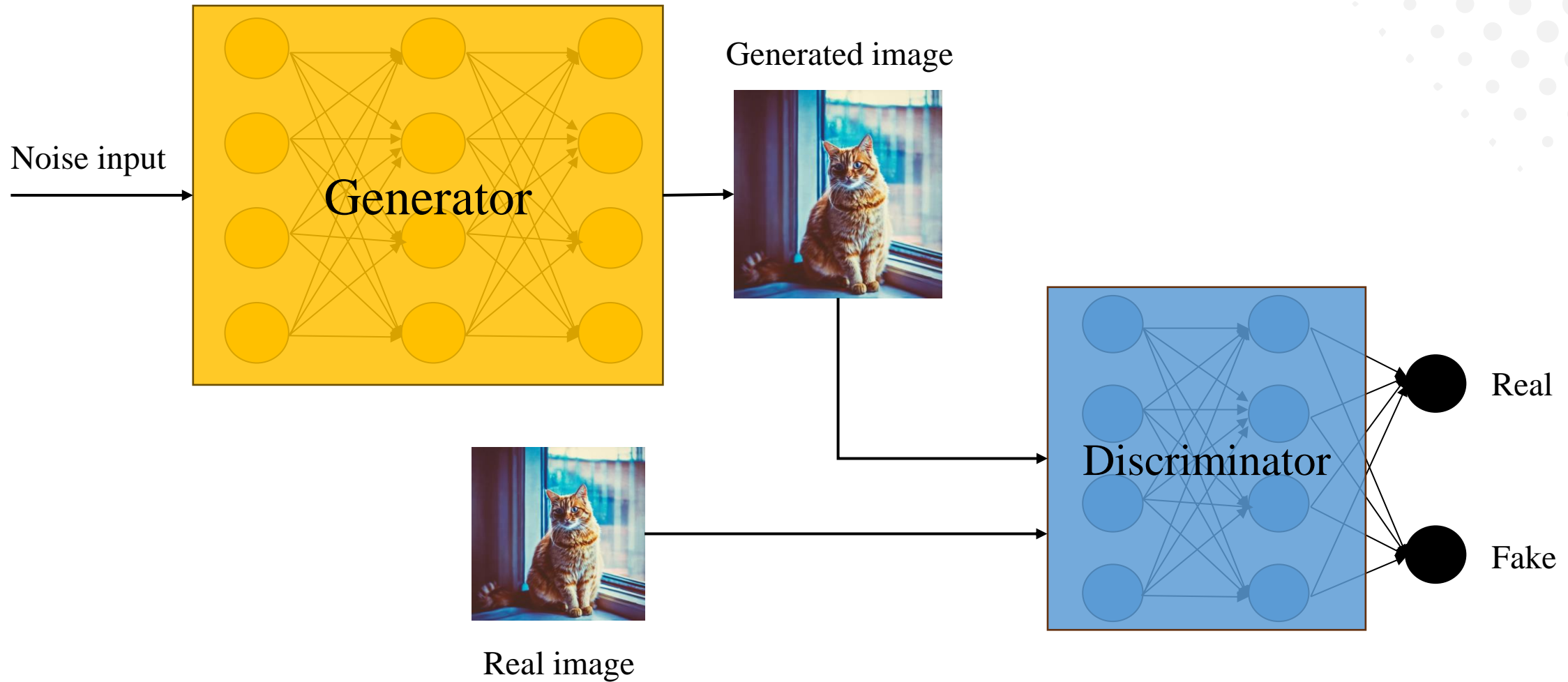
Autoencoders (AE)



Adversarial Autoencoders (AAE)



Generative adversarial networks (GANs)



Convolution in Image Processing

- **Convolution:** Transforming an image by applying a kernel over each pixel and its local neighbors across the entire image.
- **Live examples:** <https://setosa.io/ev/image-kernels/>

7	2	3	3	8
4	5	3	8	4
3	3	2	8	4
2	8	7	2	7
5	4	4	5	4

*

1	0	-1
1	0	-1
1	0	-1

=

6		

$$\begin{aligned} &7 \times 1 + 4 \times 1 + 3 \times 1 + \\ &2 \times 0 + 5 \times 0 + 3 \times 0 + \\ &3 \times -1 + 3 \times -1 + 2 \times -1 \\ &= 6 \end{aligned}$$

Convolutional Neural Networks (CNNs)

- Convolution filters as feature extractors!
- <https://poloclub.github.io/cnn-explainer/>



Convolution
Relu



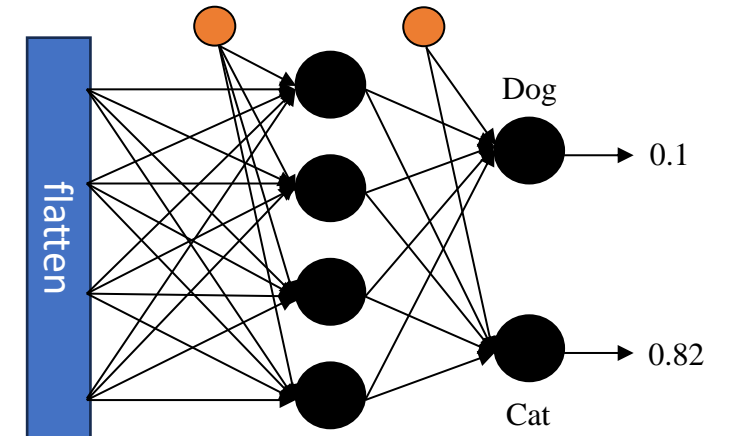
Max Pooling



Convolution
Relu

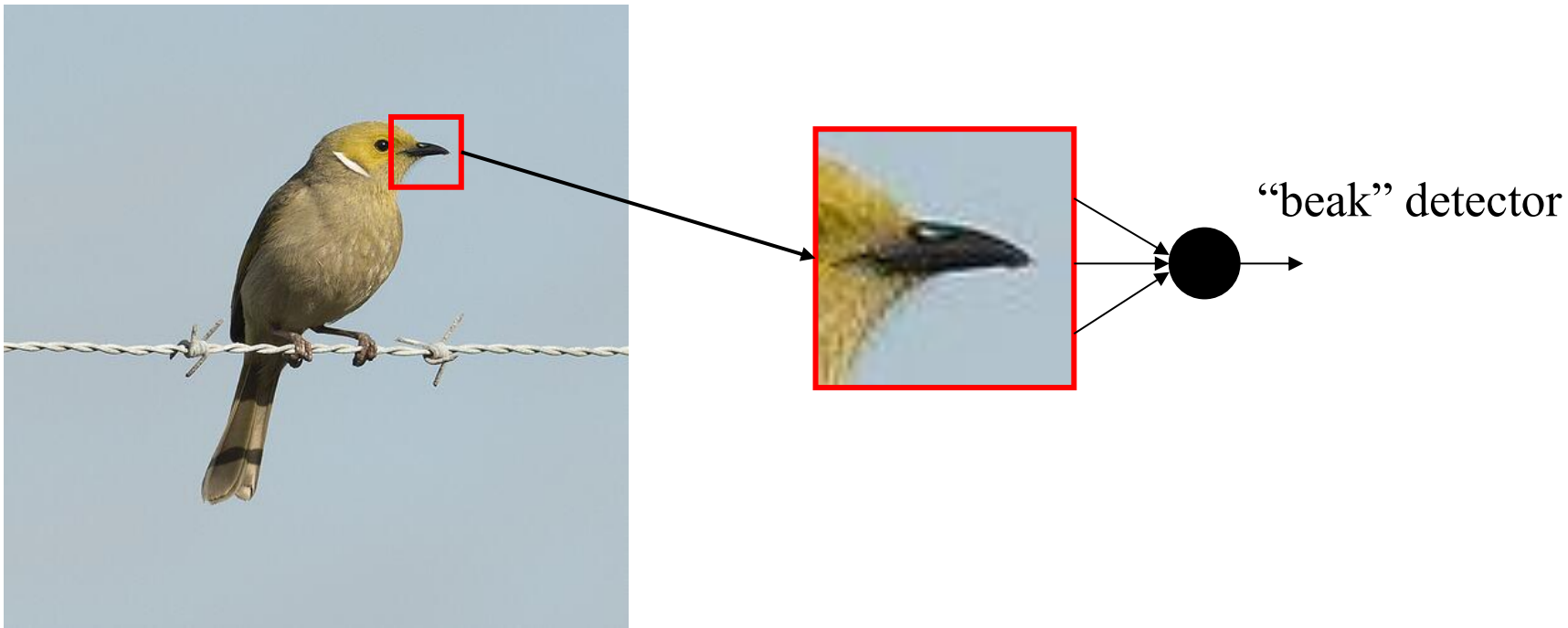


Max Pooling



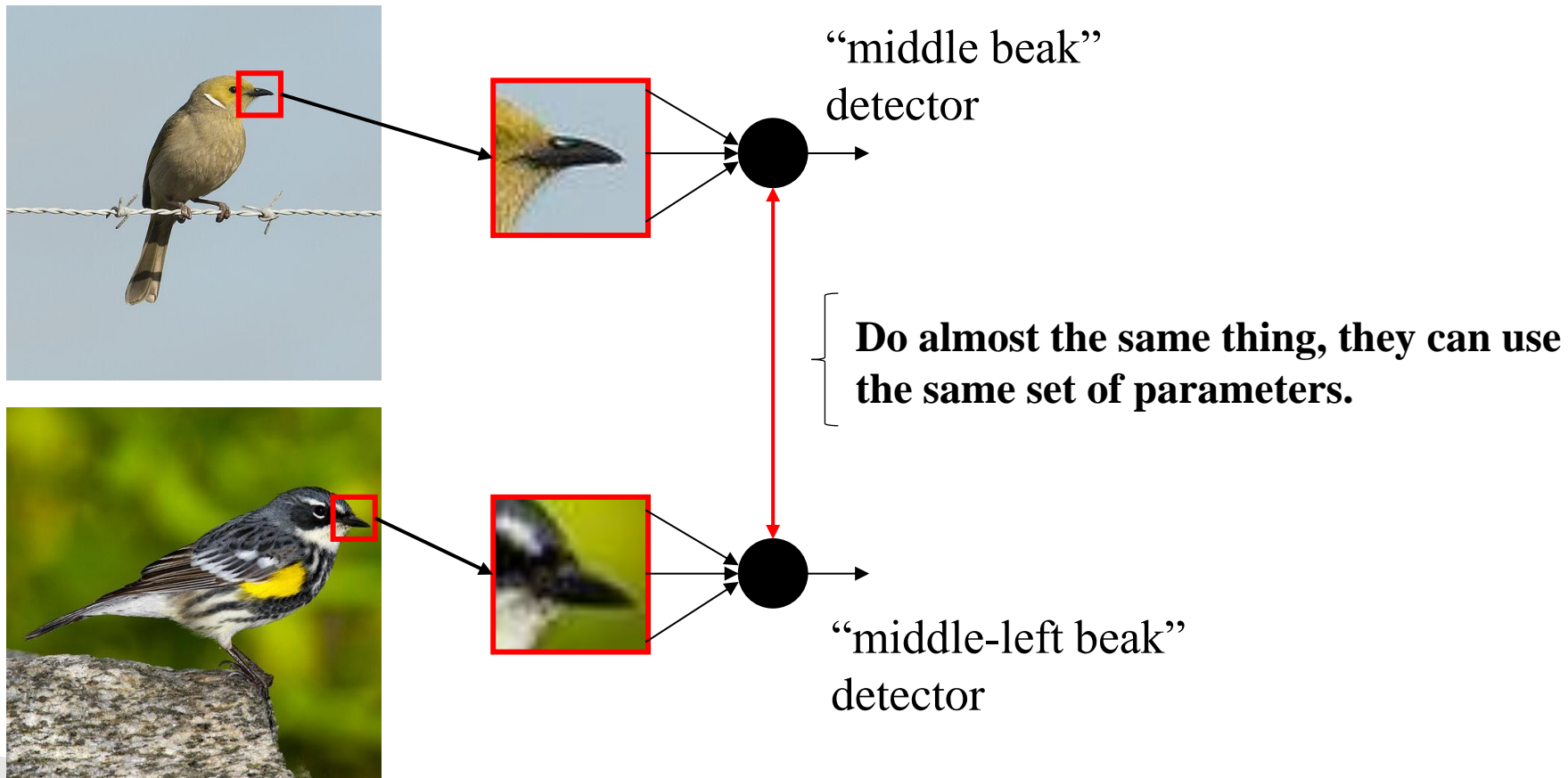
Why CNN for Image?

- Some patterns are much smaller than the whole image
 - ✓ **A neuron does not have to see the whole image to discover the pattern.**



Why CNN for Image?

- The same patterns appear in different regions.



Why CNN for Image?

- **Subsampling** the pixels will not change the object

bird



Subsampling



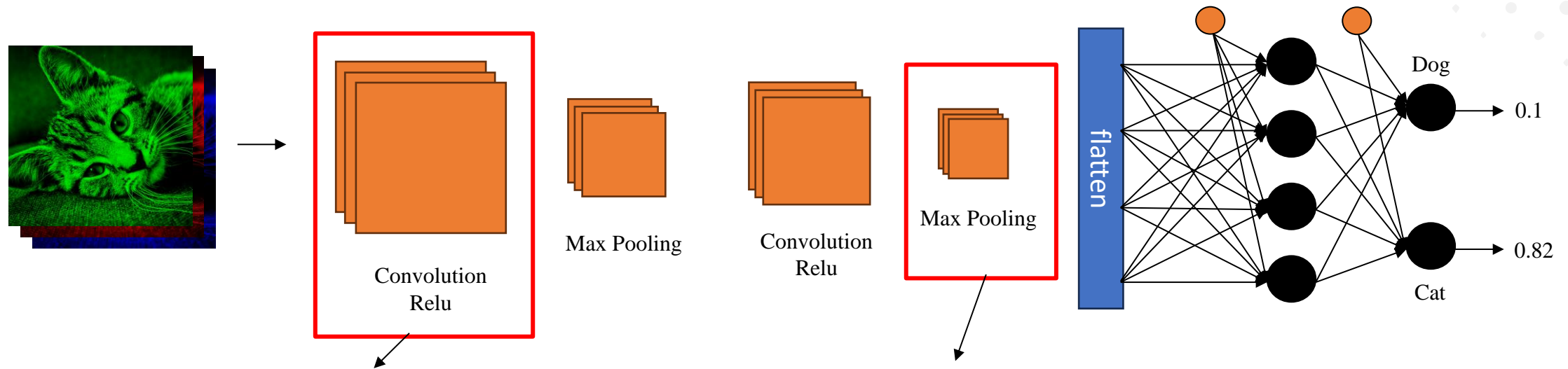
bird



- We can subsample the pixels to make image smaller
- Less parameters for the network to process the image

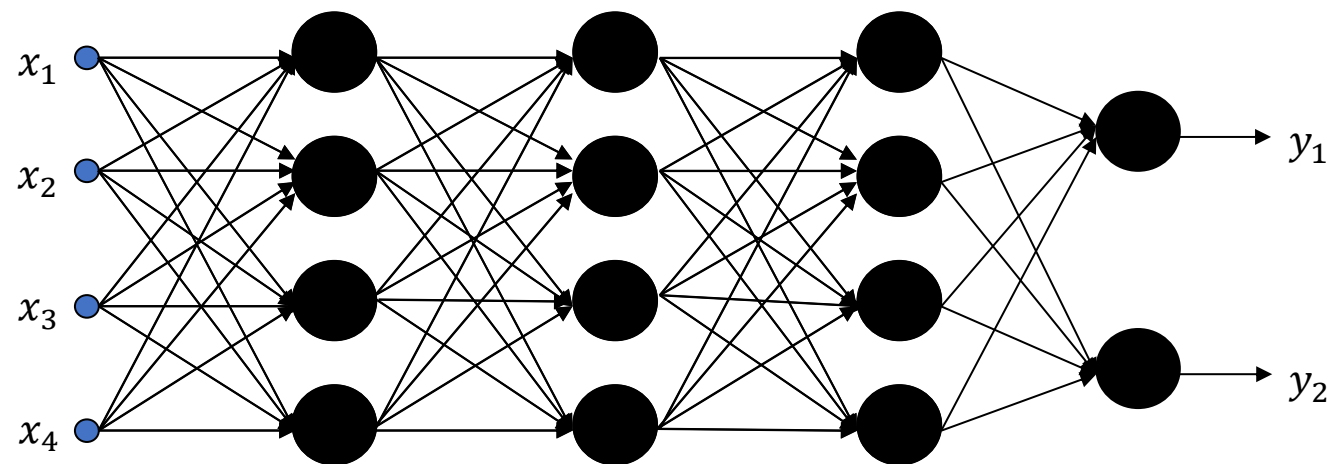
Convolutional Neural Networks (CNNs)

- Convolution filters as feature extractors!



- Some patterns are much smaller than the whole image
- The same patterns appear in different regions.
- Subsampling the pixels will not change the object

Transfer Learning



Training a huge model on a large dataset for a very long time!

