MICROCONTROLLERS

Chapter 2

What is Computer ?

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References:

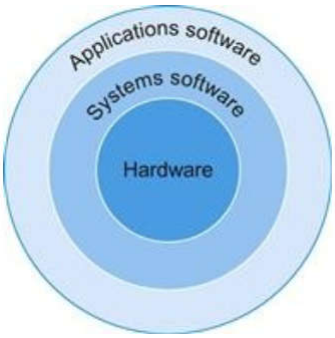
- Computer System Architecture - M.Morris Mano - 3rd edition – Prentice Hall
- Computer Organization & Design: The Hardware/Software Interface - David A. Patterson, John L. Hennessy – 5th edition – Morgan Kaufmann

What is Computer ?

The digital computer is a digital system that performs various computational tasks. The word *digital* implies that the information in the computer is represented by variables that take a limited number of discrete values. These values are processed internally by components that can maintain a limited number of discrete states.

A computer system is sometimes subdivided into two functional entities: hardware and software. The hardware of the computer consists of all the electronic components and electromechanical devices that comprise the physical entity of the device. Computer software consists of the instructions and data that the computer manipulates to perform various data-processing tasks. A sequence of instructions for the computer is called a *program*. The data that are manipulated by the program constitute the *data base*.

What is Computer ? (Cont.)



System Software

There are many types of systems software, but two types of systems software are central to every computer system today: an operating system and a compiler. An **operating system** interfaces between a user's program and the hardware and provides a variety of services and supervisory functions. Among the most important functions are:

- Handling basic input and output operations
- Allocating storage and memory
- Providing for protected sharing of the computer among multiple applications using it simultaneously.

Compilers perform another vital function: the translation of a program written in a high-level language, such as C, C++, Java, or Visual Basic into instructions that the hardware can execute.

But How it's works?

To actually speak to electronic hardware, you need to send electrical signals. The easiest signals for computers to understand are *on* and *off*, and so the computer alphabet is just two letters. Just as the 26 letters of the English alphabet do not limit how much can be written, the two letters of the computer alphabet do not limit what computers can do. The two symbols for these two letters are the numbers 0 and 1, and we commonly think of the computer language as numbers in base 2, or *binary numbers*. We refer to each "letter" as a **binary digit** or **bit**. Computers are slaves to our commands, which are called **instructions**. Instructions, which are just collections of bits that the computer understands and obeys, can be thought of as numbers. For example, the bits

```
1000110010100000
```

Assembler

The first programmers communicated to computers in binary numbers, but this was so tedious that they quickly invented new notations that were closer to the way humans think. At first, these notations were translated to binary by hand, but this process was still tiresome. Using the computer to help program the computer, the pioneers invented programs to translate from symbolic notation to binary. The first of these programs was named an **assembler**. This program translates a symbolic version of an instruction into the binary version. For example, the programmer would write

```
add A,B
```

and the assembler would translate this notation into

```
1000110010100000
```

This instruction tells the computer to add the two numbers `A` and `B`. The name coined for this symbolic language, still used today, is **assembly language**. In contrast, the binary language that the machine understands is the **machine language**.

High Level Languages

Although a tremendous improvement, assembly language is still far from the notations a scientist might like to use to simulate fluid flow or that an accountant might use to balance the books. Assembly language requires the programmer to write one line for every instruction that the computer will follow, forcing the programmer to think like the computer.

The recognition that a program could be written to translate a more powerful language into computer instructions was one of the great breakthroughs in the early days of computing. Programmers today owe their productivity—and their sanity—to the creation of **high-level programming languages** and compilers that translate programs in such languages into instructions. Figure 1.4 shows the relationships among these programs and languages, which are more examples of the power of **abstraction**.

High Level Languages (Cont.)

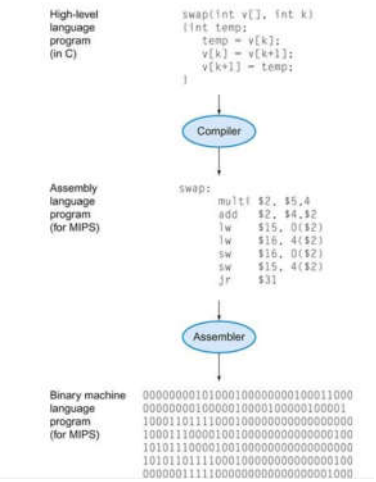


FIGURE 1.4 C program compiled into assembly language and then assembled into binary machine language.
Although the translation from high-level language to binary machine language is shown in two steps, some compilers cut out the middleman and produce binary machine language directly. These languages and this program are examined in more detail in

Input / Output

Two key components of computers are **input devices**, such as the microphone, and **output devices**, such as the speaker. As the names suggest, input feeds the computer, and output is the result of computation sent to the user. Some devices, such as wireless networks, provide both input and output to the computer.

input device
A mechanism through which the computer is fed information, such as a microphone.

output device
A mechanism that conveys the result of a computation to a user, such as a display, or to another computer.

Big Picture

The BIG Picture

The five classic components of a computer are input, output, memory, datapath, and control, with the last two sometimes combined and called the processor. Figure 1.5 shows the standard organization of a computer. This organization is independent of hardware technology: you can place every piece of every computer, past and present, into one of these five categories. To help you keep all this in perspective, the five components of a computer are shown on the front page of each of the following chapters, with the portion of interest to that chapter highlighted.

Big Picture (Cont.)

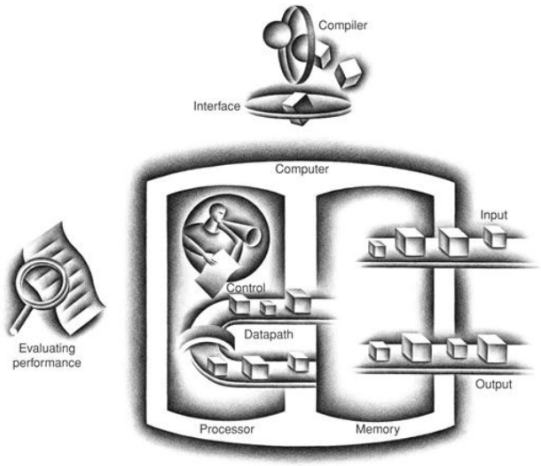


FIGURE 1.5 The organization of a computer, showing the five classic components. The processor gets instructions and data from memory. Input writes data to memory, and output reads data from memory. Control sends the signals that determine the operations of the datapath, memory, input, and output.

Look Inside

FIGURE 1.7 Components of the Apple iPad 2 A1395. The metal back of the iPad (with the reversed Apple logo in the middle) is in the center. At the top is the capacitive multitouch screen and LCD display. To the far right is the 3.8 V, 25 watt-hour, polymer battery, which consists of three Li-ion cell cases and offers 10 hours of battery life. To the far left is the metal frame that attaches the LCD to the back of the iPad. The small components surrounding the metal back in the center are what we think of as the computer; they are often L-shaped to fit compactly inside the case next to the battery. Figure 1.8 shows a close-up of the L-shaped board to the lower left of the metal case, which is the logic printed circuit board that contains the processor and the memory. The tiny rectangle below the logic board contains a chip that provides wireless communication: Wi-Fi, Bluetooth, and FM tuner: it fits into a small slot in the lower left corner of the logic board. Near the upper left corner of the case is another L-shaped component, which is a front-facing camera assembly that includes the camera, headphone jack, and microphone. Near the right upper corner of the case is the board containing the volume control and silent/screen rotation lock button along with a gyroscope and accelerometer. These last two chips combine to allow the iPad to recognize 6-axis motion. The tiny rectangle next to it is the rear-facing camera. Near the bottom right of the case is the L-shaped speaker assembly. The cable at the bottom is the connector between the logic board and the camera/volume control board. The board between the cable and the speaker assembly is the controller for the capacitive touchscreen. (Courtesy iFixit, www.ifixit.com)

Look Inside (Cont.)

FIGURE 1.8 The logic board of Apple iPad 2 in Figure 1.7. The photo highlights five integrated circuits. The large integrated circuit in the middle is the Apple A5 chip, which contains a dual ARM processor cores that run at 1 GHz as well as 512 MB of main memory inside the package. Figure 1.9 shows a photograph of the processor chip inside the A5 package. The similar sized chip to the left is the 32 GB flash memory chip for nonvolatile storage. There is an empty space between the two chips where a second flash chip can be installed to double storage capacity of the iPad. The chips to the right of the A5 include power controller and I/O controller chips. (Courtesy iFixit, www.ifixit.com)

CPU

The small rectangles in Figure 1.8 contain the devices that drive our advancing technology, called **integrated circuits** and nicknamed **chips**. The A5 package seen in the middle of in Figure 1.8 contains two ARM processors that operate with a clock rate of 1 GHz. The *processor* is the active part of the computer, following the instructions of a program to the letter. It adds numbers, tests numbers, signals I/O devices to activate, and so on. Occasionally, people call the processor the **CPU**, for the more bureaucratic-sounding **central processor unit**.

integrated circuit
Also called a **chip**. A device combining dozens to millions of transistors.

central processor unit (CPU)
Also called processor. The active part of the computer, which contains the datapath and control and which adds numbers, tests numbers, signals I/O devices to activate, and so on.

Inside Microprocessor

Descending even lower into the hardware, Figure 1.9 reveals details of a microprocessor. The processor logically comprises two main components: datapath and control, the respective brawn and brain of the processor. The **datapath** performs the arithmetic operations, and **control** tells the datapath, memory, and I/O devices what to do according to the wishes of the instructions of the program. Chapter 4 explains the datapath and control for a higher-performance design.

datapath
The component of the processor that performs arithmetic operations

control
The component of the processor that commands the datapath, memory, and I/O devices according to the instructions of the program.

Inside Microprocessor (Cont.)

FIGURE 1.9 The processor integrated circuit inside the A5 package. The size of chip is 12.1 by 10.1 mm, and it was manufactured originally in a 45-nm process (see Section 1.5). It has two identical ARM processors or cores in the middle left of the chip and a PowerVR graphical processor unit (GPU) with four datapaths in the upper left quadrant. To the left and bottom side of the ARM cores are interfaces to main memory (DRAM). (Courtesy Chipworks, www.chipworks.com)

Memory

The A5 package in Figure 1.8 also includes two memory chips, each with 2 gibibits of capacity, thereby supplying 512 MiB. The **memory** is where the programs are kept when they are running; it also contains the data needed by the running programs. The memory is built from DRAM chips. *DRAM* stands for **dynamic random access memory**. Multiple DRAMs are used together to contain the instructions and data of a program. In contrast to sequential access memories, such as magnetic tapes, the *RAM* portion of the term DRAM means that memory accesses take basically the same amount of time no matter what portion of the memory is read.

Memory (Cont.)

memory
The storage area in which programs are kept when they are running and that contains the data needed by the running programs.

dynamic random access memory (DRAM)
Memory built as an integrated circuit; it provides random access to any location. Access times are 50 nanoseconds and cost per gigabyte in 2012 was $5 to $10.

Memory (Cont.)

Descending into the depths of any component of the hardware reveals insights into the computer. Inside the processor is another type of memory—cache memory. **Cache memory** consists of a small, fast memory that acts as a buffer for the DRAM memory. (The nontechnical definition of *cache* is a safe place for hiding things.) Cache is built using a different memory technology, **static random access memory (SRAM)**. SRAM is faster but less dense, and hence more expensive, than DRAM (see Chapter 5). SRAM and DRAM are two layers of the **memory hierarchy**.

Memory (Cont.)

cache memory
A small, fast memory that acts as a buffer for a slower, larger memory.

static random access memory (SRAM)
Also memory built as an integrated circuit, but faster and less dense than DRAM.

Computer Architecture

As mentioned above, one of the great ideas to improve design is abstraction. One of the most important **abstractions** is the interface between the hardware and the lowest-level software. Because of its importance, it is given a special name: the **instruction set architecture**, or simply **architecture**, of a computer. The instruction set architecture includes anything programmers need to know to make a binary machine language program work correctly, including instructions, I/O devices, and so on. Typically, the operating system will encapsulate the details of doing I/O, allocating memory, and other low-level system functions so that application programmers do not need to worry about such details. The combination of the basic instruction set and the operating system interface provided for application programmers is called the **application binary interface (ABI)**.

(Cont.) Computer Architecture

instruction set architecture

Also called **architecture**. An abstract interface between the hardware and the lowest-level software that encompasses all the information necessary to write a machine language program that will run correctly, including instructions, registers, memory access, I/O, and so on.

application binary interface (ABI)

The user portion of the instruction set plus the operating system interfaces used by application programmers. It defines a standard for binary portability across computers.

Computer Functions

An instruction set architecture allows computer designers to talk about functions independently from the hardware that performs them. For example, we can talk about the functions of a digital clock (keeping time, displaying the time, setting the alarm) independently from the clock hardware (quartz crystal, LED displays, plastic buttons). Computer designers distinguish architecture from an **implementation** of an architecture along the same lines: an implementation is hardware that obeys the architecture abstraction. These ideas bring us to another Big Picture.

Computer Functions (Cont.)

implementation
Hardware that obeys the architecture abstraction.

The BIG Picture
Both hardware and software consist of hierarchical layers using abstraction, with each lower layer hiding details from the level above. One key interface between the levels of abstraction is the *instruction set architecture*—the interface between the hardware and low-level software. This abstract interface enables many *implementations* of varying cost and performance to run identical software.

A Safe Place for Data !

Thus far, we have seen how to input data, compute using the data, and display data. If we were to lose power to the computer, however, everything would be lost because the memory inside the computer is **volatile**—that is, when it loses power, it forgets. In contrast, a DVD disk doesn't forget the movie when you turn off the power to the DVD player, and is thus a **nonvolatile memory** technology.

volatile memory
Storage, such as DRAM, that retains data only if it is receiving power.

nonvolatile memory
A form of memory that retains data even in the absence of a power source and that is used to store programs between runs. A DVD disk is nonvolatile.

Memory Models

To distinguish between the volatile memory used to hold data and programs while they are running and this nonvolatile memory used to store data and programs between runs, the term **main memory** or **primary memory** is used for the former, and **secondary memory** for the latter. Secondary memory forms the next lower layer of the **memory hierarchy**. DRAMs have dominated main memory since 1975, but **magnetic disks** dominated secondary memory starting even earlier. Because of their size and form factor, personal Mobile Devices use **flash memory**, a nonvolatile semiconductor memory, instead of disks. Figure 1.8 shows the chip containing the flash memory of the iPad 2. While slower than DRAM, it is much cheaper than DRAM in addition to being nonvolatile. Although costing more per bit than disks, it is smaller, it comes in much smaller capacities, it is more rugged, and it is more power efficient than disks. Hence, flash memory is the standard secondary memory for PMDs. Alas, unlike disks and DRAM, flash memory bits wear out after 100,000 to 1,000,000 writes. Thus, file systems must keep track of the number of writes and have a strategy to avoid wearing out storage, such as by moving popular data. Chapter 5 describes disks and flash memory in more detail.

Memory Models (Cont.)

main memory

Also called **primary memory**. Memory used to hold programs while they are running; typically consists of DRAM in today's computers.

secondary memory

Nonvolatile memory used to store programs and data between runs; typically consists of flash memory in PMDs and magnetic disks in servers.

Communication with Other Computers

We've explained how we can input, compute, display, and save data, but there is still one missing item found in today's computers: computer networks. Just as the processor shown in Figure 1.5 is connected to memory and I/O devices, networks interconnect whole computers, allowing computer users to extend the power of computing by including communication. Networks have become so popular that they are the backbone of current computer systems; a new personal mobile device or server without a network interface would be ridiculed. Networked computers have several major advantages:

- *Communication*: Information is exchanged between computers at high speeds.
- *Resource sharing*: Rather than each computer having its own I/O devices, computers on the network can share I/O devices.
- *Nonlocal access*: By connecting computers over long distances, users need not be near the computer they are using.

Communication with Other Computers (Cont.)

Networks vary in length and performance, with the cost of communication increasing according to both the speed of communication and the distance that information travels. Perhaps the most popular type of network is *Ethernet*. It can be up to a kilometer long and transfer at up to 40 gigabits per second. Its length and speed make Ethernet useful to connect computers on the same floor of a building; hence, it is an example of what is generically called a **local area network**. Local area networks are interconnected with switches that can also provide routing services and security. **Wide area networks** cross continents and are the backbone of the Internet, which supports the web. They are typically based on optical fibers and are leased from telecommunication companies.

Technology of Making CPU and Memories

Processors and memory have improved at an incredible rate, because computer designers have long embraced the latest in electronic technology to try to win the race to design a better computer. Figure 1.10 shows the technologies that have been used over time, with an estimate of the relative performance per unit cost for each technology. Since this technology shapes what computers will be able to do and how quickly they will evolve, we believe all computer professionals should be familiar with the basics of integrated circuits.

Technology of Making CPU and Memories (Cont.)

Year	Technology used in computers	Relative performance/unit cost
1951	Vacuum tube	1
1965	Transistor	35
1975	Integrated circuit	900
1995	Very large-scale integrated circuit	2,400,000
2013	Ultra large-scale integrated circuit	6,200,000,000

FIGURE 1.10 Relative performance per unit cost of technologies used in computers over time. Source: Computer Museum, Boston, with 2013 extrapolated by the authors. See Section 1.12.

Technology of Making CPU and Memories (Cont.)

A **transistor** is simply an on/off switch controlled by electricity. The *integrated circuit* (IC) combined dozens to hundreds of transistors into a single chip. When Gordon Moore predicted the continuous doubling of resources, he was predicting the growth rate of the number of transistors per chip. To describe the tremendous increase in the number of transistors from hundreds to millions, the adjective *very large scale* is added to the term, creating the abbreviation *VLSI*, for **very large-scale integrated circuit**.

Technology of Making CPU and Memories (Cont.)

This rate of increasing integration has been remarkably stable. Figure 1.11 shows the growth in DRAM capacity since 1977. For 35 years, the industry has consistently quadrupled capacity every 3 years, resulting in an increase in excess of 16,000 times!

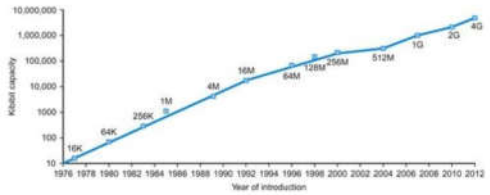


FIGURE 1.11 Growth of capacity per DRAM chip over time.
The *y*-axis is measured in kibibits (2^{10} bits). The DRAM industry quadrupled capacity almost every three years, a 60% increase per year, for 20 years. In recent years, the rate has slowed down and is somewhat closer to doubling every two years to three years.

Making an IC

To understand how manufacture integrated circuits, we start at the beginning. The manufacture of a chip begins with **silicon**, a substance found in sand. Because silicon does not conduct electricity well, it is called a **semiconductor**. With a special chemical process, it is possible to add materials to silicon that allow tiny areas to transform into one of three devices:

- Excellent conductors of electricity (using either microscopic copper or aluminum wire)
- Excellent insulators from electricity (like plastic sheathing or glass)
- Areas that can conduct or insulate under special conditions (as a switch)

Making an IC (Cont.)

Transistors fall in the last category. A VLSI circuit, then, is just billions of combinations of conductors, insulators, and switches manufactured in a single small package.

The manufacturing process for integrated circuits is critical to the cost of the chips and hence important to computer designers. Figure 1.12 shows that process. The process starts with a **silicon crystal ingot**, which looks like a giant sausage. Today, ingots are 8–12 inches in diameter and about 12–24 inches long. An ingot is finely sliced into **wafers** no more than 0.1 inches thick. These wafers then go through a series of processing steps, during which patterns of chemicals are placed on each wafer, creating the transistors, conductors, and insulators discussed earlier. Today's integrated circuits contain only one layer of transistors but may have from two to eight levels of metal conductor, separated by layers of insulators.

Making an IC (Cont.)

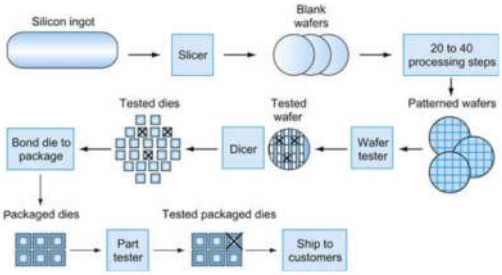


FIGURE 1.12 The chip manufacturing process.
After being sliced from the silicon ingot, blank wafers are put through 20 to 40 steps to create patterned wafers (see Figure 1.13). These patterned wafers are then tested with a wafer tester, and a map of the good parts is made. Then, the wafers are diced into dies (see Figure 1.9). In this figure, one wafer produced 20 dies, of which 17 passed testing. (X means the die is bad.) The yield of good dies in this case was 17/20, or 85%. These good dies are then bonded into packages and tested one more time before shipping the packaged parts to customers. One bad packaged part was found in this final test.

Making an IC (Cont.)

A single microscopic flaw in the wafer itself or in one of the dozens of patterning steps can result in that area of the wafer failing. These **defects**, as they are called, make it virtually impossible to manufacture a perfect wafer. The simplest way to cope with imperfection is to place many independent components on a single wafer. The patterned wafer is then chopped up, or *diced*, into these components, called **dies** and more informally known as **chips**. Figure 1.13 shows a photograph of a wafer containing microprocessors before they have been diced; earlier, Figure 1.9 shows an individual microprocessor die.

Making an IC (Cont.)

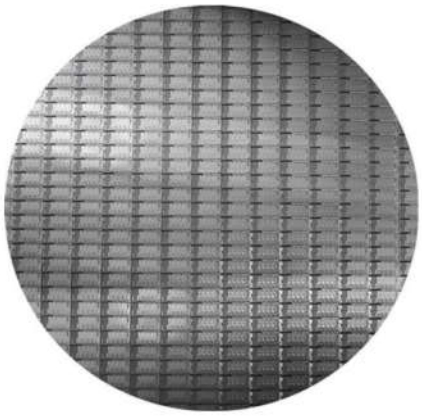


FIGURE 1.13 A 12-inch (300 mm) wafer of Intel Core i7 (Courtesy Intel). The number of dies on this 300 mm (12 inch) wafer at 100% yield is 280, each 20.7 by 10.5 mm. The several dozen partially rounded chips at the boundaries of the wafer are useless; they are included because it's easier to create the masks used to pattern the silicon. This die uses a 32-nanometer technology, which means that the smallest features are approximately 32 nm in size, although they are typically somewhat smaller than the actual feature size, which refers to the size of the transistors as "drawn" versus the final manufactured size.

Making an IC (Cont.)

Dicing enables you to discard only those dies that were unlucky enough to contain the flaws, rather than the whole wafer. This concept is quantified by the **yield** of a process, which is defined as the percentage of good dies from the total number of dies on the wafer.

The cost of an integrated circuit rises quickly as the die size increases, due both to the lower yield and the smaller number of dies that fit on a wafer. To reduce the cost, using the next generation process shrinks a large die as it uses smaller sizes for both transistors and wires. This improves the yield and the die count per wafer. A 32-nanometer (nm) process was typical in 2012, which means essentially that the smallest feature size on the die is 32 nm.

Once you've found good dies, they are connected to the input/output pins of a package, using a process called *bonding*. These packaged parts are tested a final time, since mistakes can occur in packaging, and then they are shipped to customers.

Introduction to Performance

Assessing the performance of computers can be quite challenging. The scale and intricacy of modern software systems, together with the wide range of performance improvement techniques employed by hardware designers, have made performance assessment much more difficult.

When trying to choose among different computers, performance is an important attribute. Accurately measuring and comparing different computers is critical to purchasers and therefore to designers. The people selling computers know this as well. Often, salespeople would like you to see their computer in the best possible light, whether or not this light accurately reflects the needs of the purchaser's application. Hence, understanding how best to measure performance and the limitations of performance measurements is important in selecting a computer.

The rest of this section describes different ways in which performance can be determined; then, we describe the metrics for measuring performance from the viewpoint of both a computer user and a designer. We also look at how these metrics are related and present the classical processor performance equation, which we will use throughout the text.

Introduction to Performance (Cont.)

When we say one computer has better performance than another, what do we mean? Although this question might seem simple, an analogy with passenger airplanes shows how subtle the question of performance can be. Figure 1.14 lists some typical passenger airplanes, together with their cruising speed, range, and capacity. If we wanted to know which of the planes in this table had the best performance, we would first need to define performance. For example, considering different measures of performance, we see that the plane with the highest cruising speed was the Concorde (retired from service in 2003), the plane with the longest range is the DC-8, and the plane with the largest capacity is the 747.

Airplane	Passenger capacity	Cruising range (miles)	Cruising speed (m.p.h.)	Passenger throughput (passengers × m.p.h.)
Boeing 777	375	4630	610	228,750
Boeing 747	470	4150	610	286,700
BAC/Sud Concorde	132	4000	1350	178,200
Douglas DC-8-50	146	8720	544	79,424

FIGURE 1.14 The capacity, range, and speed for a number of commercial airplanes. The last column shows the rate at which the airplane transports passengers, which is the capacity times the cruising speed (ignoring range and takeoff and landing times).

Speed

If you were running a program on two different desktop computers, you'd say that the faster one is the desktop computer that gets the job done first. If you were running a datacenter that had several servers running jobs submitted by many users, you'd say that the faster computer was the one that completed the most jobs during a day. As an individual computer user, you are interested in reducing **response time**—the time between the start and completion of a task—also referred to as **execution time**. Datacenter managers are often interested in increasing **throughput** or **bandwidth**—the total amount of work done in a given time. Hence, in most cases, we will need different performance metrics as well as different sets of applications to benchmark personal mobile devices, which are more focused on response time, versus servers, which are more focused on throughput.

Speed (Cont.)

response time

Also called **execution time**. The total time required for the computer to complete a task, including disk accesses, memory accesses, I/O activities, operating system overhead, CPU execution time, and so on.

throughput

Also called **bandwidth**. Another measure of performance, it is the number of tasks completed per unit time.

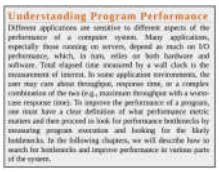
Measuring Performance

Time is the measure of computer performance: the computer that performs the same amount of work in the least time is the fastest. Program *execution time* is measured in seconds per program. However, time can be defined in different ways, depending on what we count. The most straightforward definition of time is called *wall clock time*, *response time*, or *elapsed time*. These terms mean the total time to complete a task, including disk accesses, memory accesses, input/output (I/O) activities, operating system overhead—everything.

Measuring Performance (Cont.)

Computers are often shared, however, and a processor may work on several programs simultaneously. In such cases, the system may try to optimize throughput rather than attempt to minimize the elapsed time for one program. Hence, we often want to distinguish between the elapsed time and the time over which the processor is working on our behalf. **CPU execution time** or simply **CPU time**, which recognizes this distinction, is the time the CPU spends computing for this task and does not include time spent waiting for I/O or running other programs. (Remember, though, that the response time experienced by the user will be the elapsed time of the program, not the CPU time.) CPU time can be further divided into the CPU time spent in the program, called **user CPU time**, and the CPU time spent in the operating system performing tasks on behalf of the program, called **system CPU time**. Differentiating between system and user CPU time is difficult to do accurately, because it is often hard to assign responsibility for operating system activities to one user program rather than another and because of the functionality differences among operating systems.

Program Performance (Cont.)



Understanding Program Performance

Different applications are sensitive to different aspects of the performance of a computer system. Many applications, especially those running on servers, depend as much on I/O performance, which, in turn, relies on both hardware and software. Total elapsed time measured by a wall clock is the measurement of interest. In some application environments, the user may care about throughput, response time, or a complex combination of the two (e.g., maximum throughput with a worst-case response time). To improve the performance of a program, one must have a clear definition of what performance metric matters and then proceed to look for performance bottlenecks by measuring program execution and looking for the likely bottlenecks. In the following chapters, we will describe how to search for bottlenecks and improve performance in various parts of the system.

Clock

Although as computer users we care about time, when we examine the details of a computer it's convenient to think about performance in other metrics. In particular, computer designers may want to think about a computer by using a measure that relates to how fast the hardware can perform basic functions. Almost all computers are constructed using a clock that determines when events take place in the hardware. These discrete time intervals are called **clock cycles** (or **ticks**, **clock ticks**, **clock periods**, **clocks**, **cycles**). Designers refer to the length of a **clock period** both as the time for a complete *clock cycle* (e.g., 250 picoseconds, or 250 ps) and as the *clock rate* (e.g., 4 gigahertz, or 4 GHz), which is the inverse of the clock period.

Execution Time

Users and designers often examine performance using different metrics. If we could relate these different metrics, we could determine the effect of a design change on the performance as experienced by the user. Since we are confining ourselves to CPU performance at this point, the bottom-line performance measure is CPU execution time. A simple formula relates the most basic metrics (clock cycles and clock cycle time) to CPU time:

$$\text{CPU execution time for a program} = \text{CPU clock cycles for a program} \times \text{Clock cycle time}$$

Basic Components of Performance

Components of performance	Units of measure
CPU execution time for a program	Seconds for the program
Instruction count	Instructions executed for the program
Clock cycles per instruction (CPI)	Average number of clock cycles per instruction
Clock cycle time	Seconds per clock cycle

FIGURE 1.15 The basic components of performance and how each is measured.