**Problem 7.21.** Let G represent an undirected graph. Also let

 $SPATH = \{ \langle G, a, b, k \rangle \mid G \text{ contains a simple path of length at most } k \text{ from } a \text{ to } b \},$ 

and

 $LPATH = \{ \langle G, a, b, k \rangle \mid G \text{ contains a simple path of length at least } k \text{ from } a \text{ to } b \}.$ 

**Part a.** Show that  $SPATH \in P$ .

*Proof.* We show that  $SPATH \in P$  by presenting a polynomial time algorithm that decides SPATH. A polynomial time algorithm M for SPATH operates as follows.

M = "On input  $\langle G, a, b, k \rangle$ :

- 1. Unmark all nodes.
- 2. Assign each node a value of  $\infty$ .
- 3. Mark a, and set it's value 0.
- 4. Let integer d = 0.
- 5. Repeat until no additional nodes are marked:
- 6. Let d = d + 1.
- 7. Scan all edges of G. If an edge (u, v) exists between a marked node u and an unmarked node v, then mark v and set value of v to d.
- 8. If b is marked and value of b is at most k, then Accept. Otherwise reject."

Now we analyze this algorithm to show that it runs in polynomial time. Obviously, stages 1 to 4 and stage 8 are executed only once. Stage 7 runs at most m times because each time except the last it marks an additional node in G, where m is the number of nodes in G. Stage 6 also runs at most m times. Thus, the total number of stages used is at most 1+1+m+m, giving a polynomial in the size of G.

Stages 1 to 4 along with stages 6 and 8 are easily implemented in polynomial time on any reasonable deterministic model. Stage 7 involves a scan of the input and a test of whether certain nodes are marked and an update of node values, which also is easily implemented in polynomial time. Hence M is a polynomial time algorithm for SPATH.

## **Part b.** Show that *LPATH* is NP-complete.

*Proof.* First, we need to show that  $LPATH \in P$ , which is easy as certificate is the path. Next, to show that all problems in NP are polynomial time reducible to LPATH, we show  $3SAT \leq_p LPATH$ . We show how to construct an integer k and an undirected graph G with two nodes, s and t, where a simple path of length at least k exists between s and t, iff  $\phi$  is satisfiable. Let  $\phi$  be any Boolean formula in 3CNF containing m clauses:

$$\phi = (a_1 \vee b_1 \vee c_1) \wedge (a_2 \vee b_2 \vee c_2) \wedge \cdots \wedge (a_m \vee b_m \vee c_m).$$

where each a, b and c is a literal  $x_i$  or  $\overline{x_i}$ , and  $x_1, x_2 \cdots x_n$  are the n variables of  $\phi$ . Now we show how to convert  $\phi$  to G. The graph contains nodes for literals, and each node's label is the same as the literal that it represents.

- 1. Repeat for each literal  $l = a_1, b_1, c_1$  of the first clause  $C_1$  in  $\phi$ .
- 2. Add a node for literal l.
- 3. Repeat for each subsequent clause  $C_2, C_3, \dots, C_m$ :
- 4. Add nodes for the three literal  $a_i$ ,  $b_i$  and  $c_i$  in clause  $C_i$ .
- 5. If i = 2, then add an edge between node l and any non-conflicting nodes added in step 3.
- 6. If i > 2, then add an edge between  $a_{i-1}$  and any node added in step 3 that does not conlict with  $a_{i-1}$  and all the nodes reachable from  $a_{i-1}$ . Repeat this step for nodes  $b_{i-1}$  and  $c_{i-1}$ .
- 7. Add node s. Add edges between node s and nodes  $a_1$ ,  $b_1$  and  $c_1$ .
- 8. Add node t. Add edges between node t and all nodes for literals  $a_m$ ,  $b_m$  and  $c_m$ .
- 9. k = m + 1.

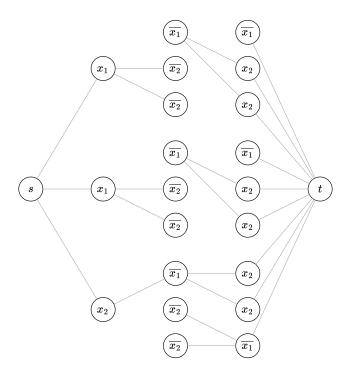
Now we analyze this algorithm to show that it runs in polynomial time. Obviously, stages 7, 8 and 9 are executed only once. Stage 2 runs 3 times. Stages 4, 5 and 6 execute at most m times. Thus, the total number of stages used is at most 1+1+1+3+m+m+m, giving a polynomial in the size of  $\phi$ . All stages are easily implemented in polynomial time on any reasonable deterministic model.

Now we demonstrate why this construction works. We show that graph G has a simple path of length at least k from s to t, iff  $\phi$  is satisfiable.

Suppose that  $\phi$  has a satisfying assignment. In that satisfying assignment, at least one literal is true in every clause. In graph G, there is an edge between node s and nodes of literals  $a_1$ ,  $b_1$  and  $c_1$  of first cluase. One of these literal is true, say  $c_1$  is true. Node  $c_1$  would have an edge with at least one of the nodes  $a_2$ ,  $b_2$  and  $c_2$  of second clause as one of these literals must be true, which means that they cannot all be  $\overline{c_1}$ . Therefore, there is at least one literal among  $a_2$ ,  $b_2$  and  $c_2$  that does not conlict with  $c_1$ , say  $b_2$ , and node  $c_1$  has an edge to node  $b_2$ . Similarly, node  $b_2$ 

would have an edge to at least one of the nodes for literals of next clause and so on. Nodes for literals  $a_m$ ,  $b_m$  and  $c_m$  have an edge to node t, so there is a path of length at least m+1 in G from s to t.

Suppose that G has a path of length at least k from s to t. No two nodes on this path conflict each other. Therefore, intermediate nodes  $n_1, n_2, \dots, n_{k-1}$  on the path  $(s, n_1, n_2, \dots, n_{k-1}, t)$  give a satisfying assignment for  $\phi$ .



Graph G with k=4 for  $\phi=(x_1\vee x_1\vee x_2)\ \wedge (\overline{x_1}\vee \overline{x_2}\vee \overline{x_2})\ \wedge (\overline{x_1}\vee x_2\vee x_2).$