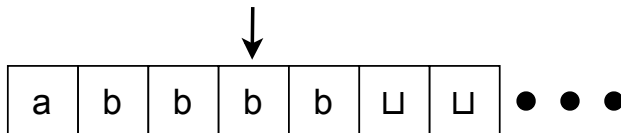
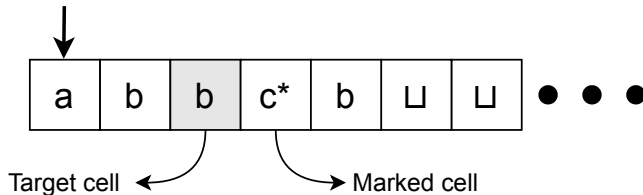


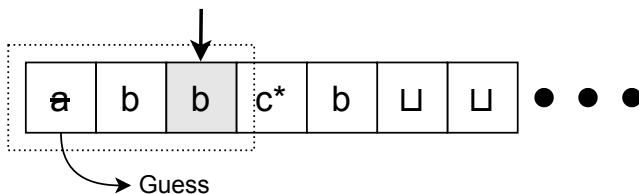
Initial state



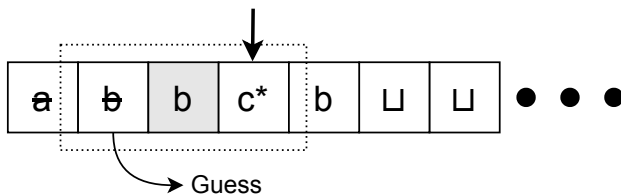
Mark current cell and reset



Guess that current cell is target cell's left neighbour, and check if it is true



Repeatedly guess and check until target cell's left neighbour is found



Clear all marked and crossed cell, and move to the target cell

